

Participatory Design and Fabrication Platform with Non-standard Materials



Figure 1: Left: an overview of the workflow: 1. fix branches on plates. 2. scan the plates and upload the model. 3. play the game with scanned branches. 4. fabricate joineries. Right top: compositions designed by participants in a workshop. Right bottom: the outcome as an interior screen (2m x 0.9m).

Abstract

Diverse natural materials such as stones and woods have been used as architectural elements preserving their native forms since primitive shelters, however, the use of them in modern buildings is limited due to the irregular properties. In this paper, we take the diversity as playful inputs for design task, and present our participatory game-based design-fabrication platform for customized architectural elements. Taking tree branches as case study of materials with native forms, our online game *BranchConnect* enables users to design 2D networks of branches and realize the design. As the generated design is realizable with ordinal 3-axis CNC milling machines, each connection has a customized unique joinery adapted to the native branch shapes. The scoring system of the game guides users to design structurally sound solutions with given branches. Together with low-cost mobile scanning devices, users with diverse contexts can contribute to design and fabrication process not only as a game user, but also from collecting branches around their physical environments and uploading them to our online platform. For validating our process, we conducted a workshop with end-users (children and their parents). They collected branches in a nearby forest and contributed to design/fabricate a 2D fence with our system.

Keywords: radiosity, global illumination, constant time

Concepts: •Computing methodologies → Image manipulation; Computational photography;

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1 Introduction

Modern buildings are characterized by its uniformity; built upon the same principle of construction system, consisting of standardized building component and its assembly process. The standardized construction system is favored because of its efficiency in design and production. Each component satisfies specified structural performance, enabling to integrate them and calculate the performance of the overall structure. On the other hand, excessive standardization converged buildings into similar materials and details, resulting in the detached design from built environment. Reacting on the issue, designers and architects actively use local materials not only as inspirational sources, but also as a catalyst of their design to the local context [Oliver 1997].

Since primitive shelters and huts, traditional construction has used locally found natural resources. Direct use of these materials can not compete with highly standardized materials and construction system, however, the uniqueness from their native shapes is a valuable quality which is lacking in standard materials. As the material is found locally, building and living get much closer, thus people using a facility can easily commit design and fabrication, fostering the sense of belonging to the community []. **TODO: citation** Locally found material easily connects design and the context of built environment in this way, but their irregular properties limit the use of them in modern buildings. Traditionally craftsmanship has taken care irregular natural materials varying their native shapes and dynamically design the global design by considering individual material properties []. Such a task is difficult to automate and relying on years of training, thus typically the use of native shapes costs more than standardized construction system.

This paper aims to make the above-mentioned qualities of materials with native shapes more accessible by digital technologies. We use locally found branches as materials with native shapes, which can be found almost everywhere not only in country-side but also in urban environment such as parks and along streets. Public service takes care of these branches: annual pruning, storing, and chipping

62 or burning with some costs. The size of branches (from 5 -30 cm in
 63 diameter) is too small for furniture or other structural applications.
 64 It is a challenge for digital design and fabrication to utilize the di-
 65 verse branches in meaningful ways. High-precision but low-cost
 66 scanning devices and personal digital fabrication machines make it
 67 possible to analyze and control natural materials with diverse native
 68 shapes.

69 The key technical difficulty with non-standard materials is design.
 70 Optimization is a straightforward approach: minimize an energy
 71 function which integrates structural and fabrication costs. This ap-
 72 proach, however, is limited to particular design scenario with spe-
 73 cific materials. Furthermore, the concept of optimum solution is
 74 well suited to goals such as efficiency or low-cost, but these goals
 75 are not the qualities non-standard materials can compete with stan-
 76 dardized construction systems. Instead, we take humans in our
 77 scan-design-fabricate workflow not only to solve the design prob-
 78 lem, but also to provide an opportunity for people to participate in
 79 the workflow. Traditionally, in case of constructing public and sym-
 80 bolic buildings, such as church, people in a community took initia-
 81 tives from fund raising to design, or even in construction process [].

TODo: citation

83 In this paper, we report our case study to design and fabricate
 84 an architectural element out of irregularly shaped branches, us-
 85 ing our humans-in-the-loop system. We developed an online plat-
 86 form where users can post branches found at hand, and design with
 87 them through the game *BranchConnect*. The game system itself
 88 helps users to design valid branch compositions and enable them
 89 to fabricate customized joineries to connect them together with-
 90 out screws and adhesives. The design of our joinery extends the
 91 traditional orthogonal lap-joints to various angles within a range,
 92 freeing the diverse shapes of woods from orthogonal connections.
 93 Physically collected branches are digitally scanned and stored in a
 94 cloud database *BranchCollect*, and offline application *Branch Im-*
95 portor analyzes shapes of branches and upload to the database. The
 96 simple visual feedback and scoring system of the game guide users
 97 to valid solutions, which are further inspected by an offline applica-
 98 tion *G-Code Generator* for CNC milling process. The game system
 99 and developed import/export applications are currently limited to
 100 branches, however, the principle of human-in-the-loop for design is
 101 applicable for other kinds of materials with diverse irregular shapes.
 102 We hope our method sheds lights on materials such as waste from
 103 demolition of buildings for various design applications.

104 Our contributions are summarized as follows.

- 105 • a workflow enabling to take natural materials with native
 106 shapes as design components.
- 107 • online platform to collect irregularly shaped materials and
 108 serving them to an online game as a design driver.
- 109 • fast and robust intersection detection algorithm for fabricating
 110 customized non-orthogonal joineries.

2 Related Work

112 3D printers and CNC routers made digital fabrication more accessi-
 113 ble, and pre-fabricated customized parts are often used in buildings
 114 nowadays [Knaack et al. 2012]. These parts are processed from
 115 highly standardized material, thus its digital fabrication process is
 116 “workmanship with certainty”; a batch process of reading Gcode
 117 and strict execution of the code. On the other hand, as “workman-
 118 ship with risks” with digital technologies, interactive fabrication
 119 enables machines to pick up uncertain happenings and react on
 120 it [Willis et al. 2011]. Mueller developed interactive laser cutting,
 121 taking user inputs and recognizing placed objects in a fabrication

122 scene[Mueller et al. 2012]. While their system interprets objects as
 123 simple geometry, our work takes the diverse native branch shapes.

124 There are few works that take irregular shape of natural resources
 125 as aesthetic characteristics. Schindler and his colleagues used
 126 digitally scanned wood branches and used them for furniture
 127 and interior design elements [Schindler et al. 2013]. Monier and
 128 colleagues virtually generated irregularly shaped branch-like com-
 129 ponents and explored designs of large scale structure [Monier et al.
 130 2013]. Using larger shaped forked tree trunks, *Wood Barn* project
 131 fabricated custom joineries to construct a truss-like structure[Mairs
 132 2016]. *Smart Scrap* project digitally measured lime stone leftover
 133 slates from a quarry and digitally generated assembly pattern of
 134 slates [Greenberg et al. 2010].

135
 136 In industry, recognition of irregularly shaped objects is essential
 137 for waste management. *ZenRobotics* developed a system that
 138 sorts construction and demolition waste by picking objects on a
 139 conveyor belt using robotic hands [Lukka et al. 2014]. For factory
 140 automation purpose, there is a system that recognizes irregularly
 141 shaped objects and sort them into a container [Sujan et al. 2000].
 142 Getting out from factories, autonomous robotics in construction
 143 site is a hot topic among roboticists[Feng et al. 2014]. *In-situ*
 144 *Fabricator* is a system which could be installed in construction site
 145 and co-operated with human workers [Dörfler et al. 2016]. Once
 146 robot is autonomously localize itself in such an environment, it
 147 can build foundational structure for further construction [Napp and
 148 Nagpal 2014]. Using locally found objects on-site, such a system
 149 can be much simpler.

150
 151 While these projects demonstrated the capability of digital fabri-
 152 cation processes to handle non-standard resources, the design pro-
 153 cess is still dependent on a designer or architect who has experi-
 154 ence with non-standard materials or has access to software which
 155 can compute the structural capability. Cimerman discussed archi-
 156 tectural design practices that took computer-mediated participatory
 157 design [Cimerman 2000]. He mentioned three motivations of digi-
 158 tal participatory design:

- 159 • Including stakeholders in creation of one’s environment.
- 160 • Experimenting diverse design tastes from multiple point of
 161 views.
- 162 • Solving complex design tasks with full of diverse solutions.

163 Opening database of available local materials, multiple designers
 164 can involve in design process, which could lower the cost of design
 165 fee with non-standard materials. Even non-trained lay people
 166 might be able to provide novel designs. For example, *Nano-Doc*
 167 took gamification as an approach to solve complicated problem.
 168 Firstly, it trains players on basic rules how nano-particles swarm
 169 through cancerous cells, and let them find novel treatments for real
 170 configuration of tumor cell [Hauert et al.].

3 Workflow

172 In this section, we shortly walk through the pipeline in our work-
 173 flow and describe three steps: Digital Model Acquisition, the Game
 174 System, and Fabrication. Our system takes textured mesh model or
 175 point cloud with colored vertices. As complete mesh model pro-
 176 vides more robust result with 3D shapes of branches, we describe
 177 our process based on mesh model as input (see Figure 2).

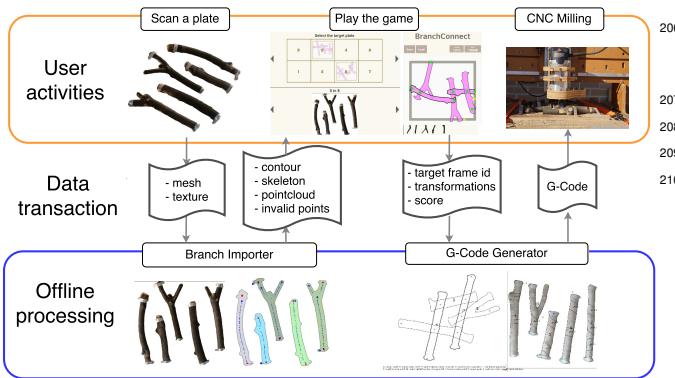


Figure 2: A pipeline from model acquisition to fabrication.

3.1 Digital Model Acquisition

There are various methods and software available for scanning 3D models and detecting objects. As for the scanning, we describe in the Experiment. Taking mesh model with colored texture, our *Branch Importer*, integrates necessary functions such as object detection, skeleton extraction, branch type classification, and fixture location detection.

After segmenting branches from a plate by height threshold, each branch is detected using *findContour* in OpenCV¹. The obtained 2D contours are used for extracting skeletons and clustering point cloud in the mesh model. Contours are triangulated and skeleton points are extracted from middle points on edges of triangles. These middle points are compared with binary top view image of the mesh model (contours are filled with different colors and the background is white). If the point is inside of a contour, the middle point is counted in skeleton points. Metal fixture locations are also filtered out due as they have bright reflections on original images, however, we also double check with simple mouse-clicks to ensure these invalid points. After extracting valid middle points, connectivity of skeletons is analyzed by angle of three adjacent skeleton points. If the angle stays within a threshold bound, a point is counted in a sub-branch, otherwise, new sub-branch is created. Evaluating the number of sub-branches, the branch is morphologically classified. Most branches are categorized in three shapes: *I*, *V*, and *Y* shapes. *I* shape has a straight continuous polyline, *V* has an inflection point, and *Y* has a splitting point. The acquired information is stored in a cloud database.

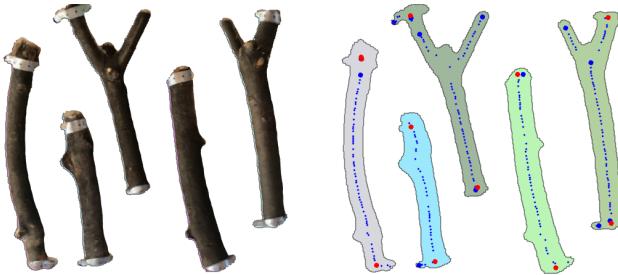


Figure 3: An overview of Branch Importer. Left: a top ortho-view image of textured mesh model. Right: Extracted skeletons (blue dots). The beginning of skeletons is shown bigger dots. Red dots are invalid points.

3.2 BranchConnect: The Game

The game objective is to collect valid compositions of branches which structurally sounding and possible to fabricate with ordinal 3 axis CNC milling machines. The workflow of the game is illustrated in Figure 4

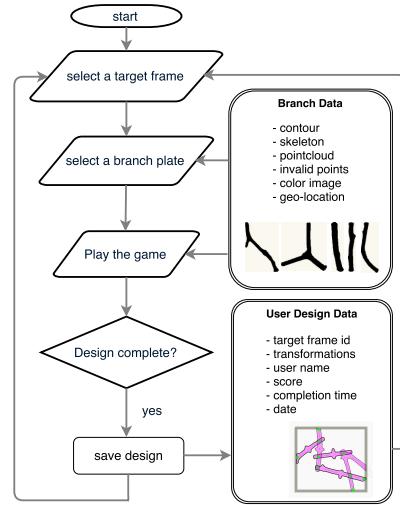


Figure 4: The workflow of BranchConnect. Branch data and user design data are stored on cloud database.

Firstly a user selects a frame indicating multiple target points to be connected, and then selects a set of branches fixed on a plate (The left in Figure 5). After selecting the target frame and the set of branches, the user is guided to the game interface, consisting of the frame with the target points, and the set of available branches (The right in Figure 5). The user picks a branch from the available set on the bottom, and then places it in an arbitrary 2D pose through basic manipulations such as move, rotate, and mirror. The number of available branches differs depending on plates. With the feasible diameter of branches (over 2cm) and the plate size (50cm x 50cm), the number of available branches is most likely up to six. Within the limited number of branches, the user bridges all the target points by connecting all the used branches in one group. The game is completed when all the target points are connected by branches. For higher score, the user can modify the design after the completion. After completing the modification, the design is submitted and sent to *G-Code Generator*.

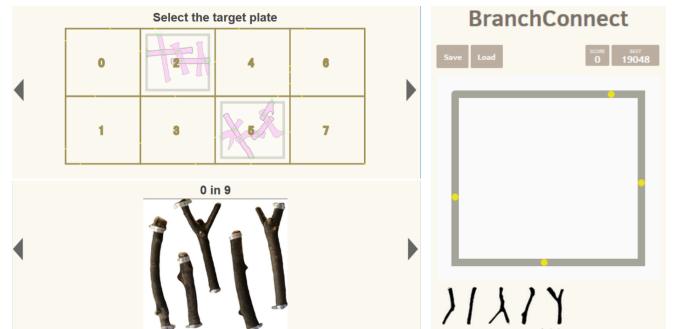


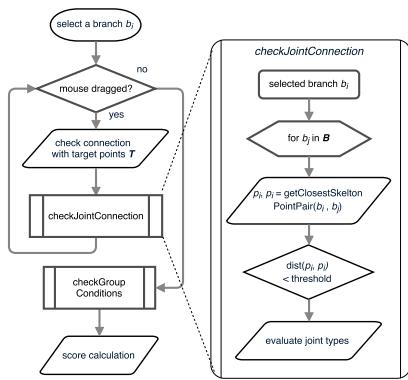
Figure 5: Left: the selection interface for target frames (top) and branch panels (bottom). Right: the start interface of the game.

¹Open Source Computer Vision Library. See <http://opencv.org/>

228 System Overview

229 There are many collision detection libraries available, however, our
 230 game needs to detect intersected branch pairs, thus surface contact
 231 detection is overkill for our application. Also most branches come
 232 with free-form concave shapes, thus further geometric preparation
 233 such as convex decomposition is necessary for using these libraries.
 234 For fast and robust intersection detection, our system extensively
 235 uses skeletons of branches. Hubbard and Philip developed colli-
 236 sion detection by representing object with hierarchical 3D spheres
 237 aligned on skeletons [Hubbard 1996]. Our system takes similar
 238 approach but more limited in 2D and intersection detection only. In
 239 broader phase, simplified skeletons are used to find the pair of clos-
 240 est skeleton points between two branches. After finding the pair,
 241 skeletons with higher resolutions are used.

242 A joint is created when an intersecting pair is detected, and the
 243 pair forms a group. The group is used for evaluating connections
 244 between target points. The game is completed once all the target
 245 points are connected by a group of branches. The conditions of
 246 joint and group are indicated with simple color-code. Once the user
 247 finishes positioning, score is updated with weighted sum of param-
 248 eters. Together with the color-code, the score update guides the user
 249 to form a valid design. An overview is illustrated in Figure 6.

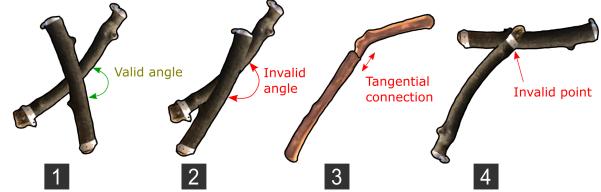


250 **Figure 6:** Left: an overview of the game system. Right: joint condi-
 251 tion checking process.

252 Joint Condition

253 Joint is the essential entity not only in the game but also the entire
 254 project including the fabrication process. The closest skeleton point
 255 pair is obtained We accept crossing joints only because they are
 256 structurally stable, relatively simple to fabricate, and creates diverse
 257 designs. To ensure the structural performance, we set a connection
 258 angle within a range from 45 to 135 degrees. Joints close to metal
 259 fixtures are also counted as invalid. Valid and invalid joints are
 260 displayed with green and red respectively. The color-code feedback
 261 is also given when target points on a frame is connected with a
 262 branch. Figure 7 illustrates valid and invalid joint conditions.

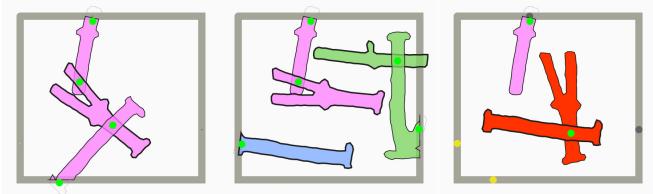
263 To describe the process, we let \mathcal{B} denotes a set of all the available
 264 branches, and each branch as $b_i \in \mathcal{B}$. While the process checks
 265 joint condition through all the branches \mathcal{B} , each detected joint is
 266 stored in each branch b_i , categorized in different conditions such
 267 as valid and invalid joints denoted as $\mathcal{J}_{valid,i}$, $\mathcal{J}_{invalid,i}$ respectively,
 268 together with the paired branch id $b_{paired,j,i}$. When a branch is con-
 269 nected to one of target point $t_j \in \mathcal{T}$, the t_j is stored in p_i as $t_{j,i}$.
 270 **TODO: notaion should be improved!**



271 **Figure 7:** Joint conditions. 1.valid joint. 2.invalid for violating the
 272 angle. 3.invalid tangential connection. 4.invalid for connecting on
 273 a fixture point.

274 Group Condition

275 After checking joint conditions of all the pairs of branches, the sys-
 276 tem checks the number of groups as well as connectivity with the
 277 target points on a frame. If a group is not connected to any target
 278 point nor other groups, the group is islanded and structurally in-
 279 valid. While a user is positioning a branch by dragging or rotating,
 280 groups are continuously calculated and indicated by simple color
 281 (Figure 8).



282 **Figure 8:** Left: valid group with two target points connected. Mid-
 283 dle: valid but three groups. Right: invalid due to the island situ-
 284 ation.

285 After all the joint conditions are checked, we evaluate group con-
 286 ditions. Through checking the all the branches \mathcal{B} , the first group
 287 g_0 is created and stores b_0 . The other paired branch $b_{paired,i}$ is used
 288 to trace the connection with other compared to the traced through
 289 the stored paired branch in each valid joint j_i . in all groups \mathcal{G} . The
 290 game is completed when the number of \mathcal{G} is one, and all the target
 291 points are connected with the group.

292 Score Calculation

293 We denote the numbers of valid and invalid joints on each branch
 294 $b_i \in \mathcal{B}$ as $N(valid_i)$, $N(invalid_i)$ respectively, the number of
 295 groups as $N(\mathcal{G})$, the number of islanded groups as $N(g_{islanded} \in \mathcal{G})$,
 296 the number of bridged target points as $N(t_{bridged,i}) \in \mathcal{T}$. The score
 297 is weighted sum of these joint and group conditions (see Eq 1).

298 **TODO: notaion should be improved!**

$$\begin{aligned}
 Score = & w_1 \sum_1^{N(\mathcal{B})} N(valid_i) + w_2 \sum_1^{N(\mathcal{B})} N(invalid_i) \\
 & + w_3 \sum_1^{N(\mathcal{G})} g_{islanded} + w_4 \sum_1^{N(\mathcal{T})} t_{bridged} \\
 \text{s.t. } & w_j \geq 0 \forall j \in 1, \dots, 4
 \end{aligned} \tag{1}$$

Algorithm 1 Group Condition Update Algorithm

```

1: function UPDATEGROUPS( $\mathcal{B}$ )
2:   Reset all the groups  $\mathcal{G}$ 
3:   Create new group  $g_1$ 
4:    $g_1$  add  $b_1$ 
5:   if  $b_1$  has connected target point  $t_1$  then
6:      $g_1$  set  $t_1$ 
7:      $\mathcal{G}$  add  $g_1$ 
8:   for each branch  $b_i$  in  $\mathcal{B}$  do
9:      $GroupConnection \leftarrow false$ 
10:    for each group  $g_j$  in  $\mathcal{G}$  do
11:      for each branch  $b_j$  in  $g_j$  do
12:        if  $b_{paired,i} \in \mathcal{P}_j$  has  $b_j$  then
13:           $g_j$  add  $b_i$ 
14:           $GroupConnection \leftarrow true$ 
15:          if ( $b_i$  has  $t_i$ ) and ( $g_j$  has  $t_j$ ) then
16:            Set  $g_j$  as Bridged
17:            if  $g_j$  has no  $t_j$  then
18:              Set  $g_j$  as Islanded
19:              break
20:          if  $GroupConnection$  is false then
21:            create new group  $g_{new}$ 
22:             $g_{new}$  add  $b_i$ 
23:             $\mathcal{G}$  add  $g_{new}$ 

```

311
312
313
314 an intersected branch are used for side cuts milling paths, which are inwardly offset paths of the original branch contours. **TODO:** need to brush up! The center cuts are paths that are plaining the top surface of the joint. **TODO:** describe the cutting height calculation!

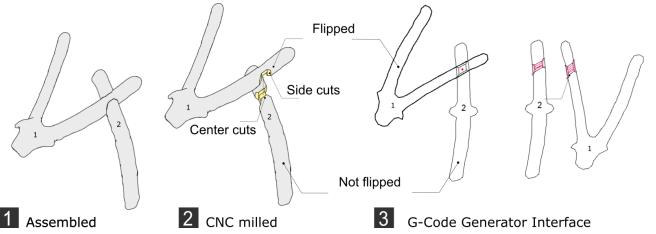


Figure 10: An example of intersected pair: 1. an assembled pair of branches. 2. branches after the center and side cuts are milled 3. left: a composition defined by a user right: the original orientations of branches with generated milling paths with red color.

315 Users can change fabrication parameters such as offset ratio for the
316 side cuts, milling bit diameter, overlapping ratio for defining the
317 center cut depth, feed-rate, moving height and so forth. After con-
318 firming the fabrication settings and milling paths, it generates G-
319 Code.

291 3.3 Fabrication

292 After a design is selected for fabrication, the validity of the de-
293 sign is further inspected with a high-resolution model. The *G-Code*
294 *Generator* was developed for fine-tuning the design by checking
295 real-time feedback of updated joineries on branches with scanned
296 orientations (see Figure 9).

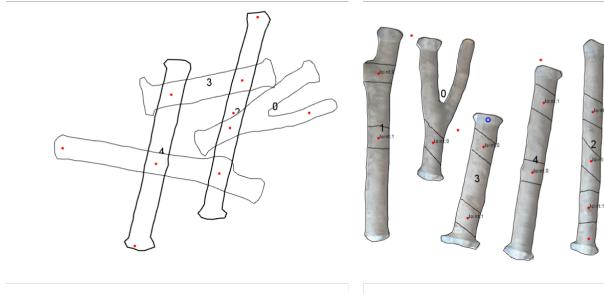


Figure 9: Interface of G-Code Generator. Users can tweak the design on the left side and immediately see the updated joints and milling paths on the right. **TODO:** can this image be integrated with the other one?

297 Some fabrication factors such as mirror and invalid points are al-
298 ready considered by *Branch Importer* and the game system of
299 *BranchConnect*. In this section, we describe the process of joinery
300 generation. Each joinery geometry is different but has same topo-
301 logy: two plane surfaces on the sides of branches and one plane top
302 surface. The geometry creates rigid connection with the irregularly
303 shaped sections of branches. Similar to the joint searching pro-
304 cess with skeletons, the *G-Code Generator* searches a set of four
305 closest points from high-resolution contours, expecting that every
306 intersected contour has four curves. After finding the four closest
307 points, it trims two curves from each contour of branch. (two from
308 intersecting branch and two from intersected branch) at each joint.
309 The trimmed contours are transformed to the original scanned orien-
310 tation and used for generating milling paths. Two curves from

320 4 Experiment

321 A design and fabrication workshop was organized to examine the
322 validity of our system with a specific design target and a location.
323 We selected a public community house where people in the com-
324 munity share the space and regularly use the facility and participants
325 were selected among them. Participants are four children aged 10
326 and under (4, 7, 9, and 10 years old) and two parents (Figure 11).
327 We specifically selected children with the age range as non-experts
328 without experiences in computational design or digital fabrication,
329 also for observing the clarity and attractiveness of the game.

330 The goal for the participants is to contribute to an ongoing design
331 and fabrication process of screen wall (2m by 0.9m) consisting of
332 8 rectangles. Six frames were already designed and built, thus the
333 rest two frames were prioritized for them to design and fabricate in
334 this workshop.

335 Participants are asked to follow the entire process from collecting
336 and fixing the branches on a plate, scanning the plate, complete
337 designs by playing the game, and assembly after the CNC milling.
338 Participants were informed about the goal of the workshop, and
339 each process was introduced by experienced tutors.



Figure 11: An overview of the workshop. 1.the overview of the space. 2.collect branches. 3.cut 4.attach on a plate 5.scan 6.play the game 7.CNC milling.

340

4.1 Setup

341

System and Hardware Setup

342 We used two iPad minis with iSense scanners attached for scanning branches, and a 3 axis CNC milling router with a 6 mm diameter
 343 milling bit. We used a laptop PC (Lenovo w240 with intel core i7) for running *Branch Importer* and *G-Code generator*, as
 344 well as operating the milling machine. The scan area of iSense is
 345 500mm x 500mm, and the milling machine's stroke along z-axis
 346 is 70mm, which provide geometric constraints for available branch
 347 sizes. *BranchConnect* was hosted at *Heroku* cloud server², and we
 348 used *MongoDB*³ as a cloud database.

351

Preparation of Branches

352 The participants were asked to collect branches with 2 - 10 cm in
 353 diameter. The lower bound of the diameter is for milling process
 354 would not destroy them, and the upper bound is for the limit of
 355 z-stroke of the CNC router. The collected branches are cut
 356 in arbitrary lengths, not longer than 500 mm due to the limit of
 357 scanning area.

358 As our game system and fabrication process take 3D branch shapes
 359 as 2D contours with height map, these constraints work positive for
 360 the system automatically filtering out branches with large 3D twists.
 361 We ask participants to scan with iPad + iSense and prepare feasible
 362 mesh model by themselves. After obtaining mesh models, tutors
 363 import models from iPads to a laptop and upload them to database
 364 by *Branch Importer*.

366

User Experiences with the System

367 After models were uploaded to the server, users can see that their
 368 plates are added in the selectable branch plates with their names
 369 and locations. Users can access to the start page by PC and mobile
 370 devices. We prepare both options and let participants choose a
 371 device.

372 A user is firstly directed to a start page and asked to submit a user
 373 name. Secondly, the user is navigated to target frame selection
 374 page, and asked to pick one out of eight frames. Each frame has dif-
 375 ferent target points. The interface also shows the completed branch
 376 organizations within each target frame. If there are multiple de-
 377 signs, three designs with highest scores are displayed. The user
 378 can change the currently displayed design by clicking within each
 379 frame and choose either starting their design from scratch, or select
 380 the design and improve it.

381 After selecting a target frame, the user goes to branch selection
 382 page, displaying 15 plates when the workshop was held. In this
 383 page, they see the plates made by themselves on the page, as well
 384 as their names on the plate. The user can select the same plate
 385 for designing other target frames. By clicking a displayed branch
 386 plate, the user is navigated to the game interface. After completing
 387 to bridge all the target points, the design is automatically uploaded
 388 to the database, but the user can continue to design. Tutors and par-
 389 ticipants select design solution for each target frame, and an expe-
 390 rienced tutor operates *G-Code Generator* as well as the CNC router.
 391 Participants were asked to assembly branches after joineries were
 392 milled.

²Heroku is a platform as a service (PaaS) that enables developers to build, run, and operate applications entirely in the cloud. <https://www.heroku.com/>

³MongoDB is a free and open-source cross-platform document-oriented database program. <https://www.mongodb.com/>

393

4.2 Results

394 The entire workshop took 4.6 hours to complete the whole process,
 395 including introduction, moving, and pauses. Table 4.2 shows dura-
 396 tions of each task.

Task	Duration (hour)	Fraction (%)
Introduction	0.3	6.5
Collecting branches	0.6	13.0
Preparing plates	0.8	17.4
Preparing models	0.3	6.5
Uploading models	0.2	4.3
Designing by the game	0.5	10.8
Inspecting models	0.2	4.3
CNC milling	0.5	10.8
Assembling	0.2	4.3
Miscellaneous	1.0	21.7
In total	4.6	100

397

Collecting Branches

398 The diameter and length constraints for available branches worked
 399 as guidelines for participants rather than restricting finding and cut-
 400 ting arbitrary branches. After cutting branches in certain lengths,
 401 participants fixed branches on plates by thin metal plates with screw
 402 holes. It was straightforward for them to firmly fix branches so that
 403 they are not moved during milling process. These fixture points are
 404 counted as invalid points in the game where joinery points can not
 405 be generated. The participants built two plates with three and five
 406 branches fixed on each plate.

408

Model Acquisition

409 iSense 3D scanners come with an intuitive software for scanning
 410 and modifying models. After we gave an instruction, most of par-
 411 ticipants practiced several scans and successfully scanned models
 412 without any problem.

413 Each scanning and re-touching took 2-3 minutes, and 30 seconds
 414 for generating data by *Branch Importer*. Including the prepared
 415 panels previously, we scanned 15 plates in total, 75 branches, and
 416 35.3m of total length including sub-branches. **TODO: check the**
 417 **length again!** We got 40 I shaped branches, 19 V shaped branches,
 418 and 16 Y shaped branches. The result is shown in Figure 12.

419

Design with the Game

420 Most participants used iPads for navigating pages and playing the
 421 game. All the participants understood the goal immediately, how-
 422 ever, they had difficulties with mobile touch interface, such as rota-
 423 tion and flipping operation by gestures.

424 One participant switched to play by a PC for more precise control
 425 due to the problem. All the participants chose to develop their own
 426 designs from the scratch, although they had instruction about the
 427 "continue existing designs".

428 Although there is no time limit in the game system, we set 30 min-
 429 utes for playing the game, and 8 solutions were given by partici-
 430 pants. xxx frames were completed per participants and xxx partici-
 431 pants completed the whole eight target frames. The average score is
 432 xxx, and average playing duration was xxx to complete each target
 433 frame.

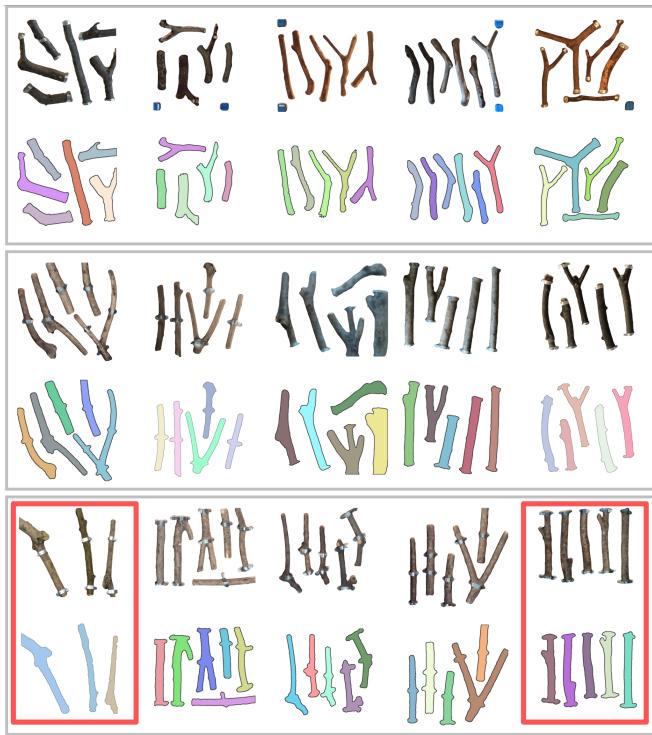


Figure 12: An overview of all the 15 scanned plates for the workshop. Top raw of each set shows ortho-top views of scanned mesh models, and the bottom raw is the recognized branches assigned random colors. The red-lined rectangles indicate the plates built by participants in the workshop.

Overall Design Consensus **TODO: this section might be removed**

As the target frame selection page can display designs not only from one user but also from all the others at once, we could get an overview of design options. The designs are displayed as score descending order but limited numbers, we could find feasible solutions with mostly all the target points were bridged. As participants were excited by seeing their branches and designs, we took some of their solutions and their plates for the fabrication although their solutions did not satisfy completion of the game.

Fabrication

We did not have major problems for converting designs to G-Code milling paths as we encountered major issues regarding the fabrication before the workshop, which are reported in this section.

The main problem was the accuracy of acquired contours. We observed most of scanned models had occluded regions between plates and branches, which create interpolated faces during solidifying process, resulting in outwardly offsetted contours. **TODO: check offsetted correct english** After milling was finished and when branches were assembled, six pairs of branches were loosely connected because the calculated contours were 2-3mm eroded than the actual sizes. We avoided this problem by trimming branches from 2-5 mm higher than the plate surface. After this operation, the rest of connections were tightly connected.

We also observed that many milling paths were 5-10 mm off from the center of planned joints. Multiple reasons could be considered

as reasons such as,

- deformation of mechanical parts of the CNC router
- not dense resolution of acquired contours of branches
- misaligned orientation of the plate compared to the scanned model

To avoid the misalignments, we modified the *G-Code Generator* so that an operator can freely adjust the absolute origin of the generated milling paths. The origin was usually set with around the center of the plate. After this modification, the misalignment from joint center was reduced with 5 mm off at the maximum misalignment. Branches could absorb 3-5 mm misaligned joint positions due to the elasticity of the wooden materials. The misaligned joint positions worked as post-tensions, solidifying the structure. We assume that this is only applicable when an applied bending moment and cut surface at a joint is orthogonal or not too much off from orthogonal. **TODO: this sentence**

4.3 Summary

The objective of the workshop was to observe the validity of our system for non-expert users. We could see that participants aged 10 and under were capable of following the workflow. Participants were encouraged to contribute to the ongoing design with the online platform, and successfully provided designs from available branch plates.

We had several requests from participants regarding the game interface but also related to the workshop organization. Several participants requested to allow multiple branch plates for designing a frame, or even remove the target frame and let them freely design with branches. Also a participant who gave up with iPad operations requested additional buttons for mobile touch interface to keep an active branch selected.

A noteworthy fact was that one participant with four years old failed to complete the game, but insisted on accepting his design to be fabricated by the CNC router. We took these requests as their commitment to the entire workflow, as we observed that all the participants insisted on continuing the fabrication process.

5 Conclusion

Summary

In this paper, we presented a workflow to design and fabricate with branches which are not large enough for producing standardized building components. Our workflow was validated with case-study with lower-aged participants without design and fabrication experiences. Our online platform to store geometries of scanned branches and compositions of branches was reachable by people with various backgrounds. Our light-weight branch joint detection algorithm was also validated by running on the browser game, contributed to the accessibility of the presented workflow. Together with the accessibility, the intuitive interface was simple enough for non-expert users. We successfully built a network of branches with rigid joints generated by our joinery milling path generator. Each of joints has customized lapped-joint geometry, which is challenging to design and fabricate.

Limitations and Future Work

Our system is limited to handle 3D shaped branches as 2D with height information only used for segmentation and G-Code generation. Our workflow requires branches to be fixed on a plate, which

- takes the longest duration in the workflow except for moving and pause in between tasks. Despite of successfully fabricated non-orthogonal joineries, we did not complete the attaching branches to target frames, as we prioritized to validate branch-branch joineries.
- Our design workflow fully relies on human's ability for obtaining design solutions. As the problem of limited number of branches and fixed target points to be connected, the system could assist humans to reach to structurally sounding solutions with less efforts. Collected data from game could be further analyzed for extracting meaningful data for the development of assisting algorithm. Our joint and group detection, and milling path algorithms are not applicable to other purposes at this moment. It is valuable to compare the performance of our joint and group detection system to other collision detection library. In our workflow, the pipeline is not seamlessly connected: experienced operators need to take care of retouching mesh model, Branch Importer, and G-Code generator, and operating a CNC router.

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