

Participatory Layout Design-Fabrication with Native Forms of Natural Materials

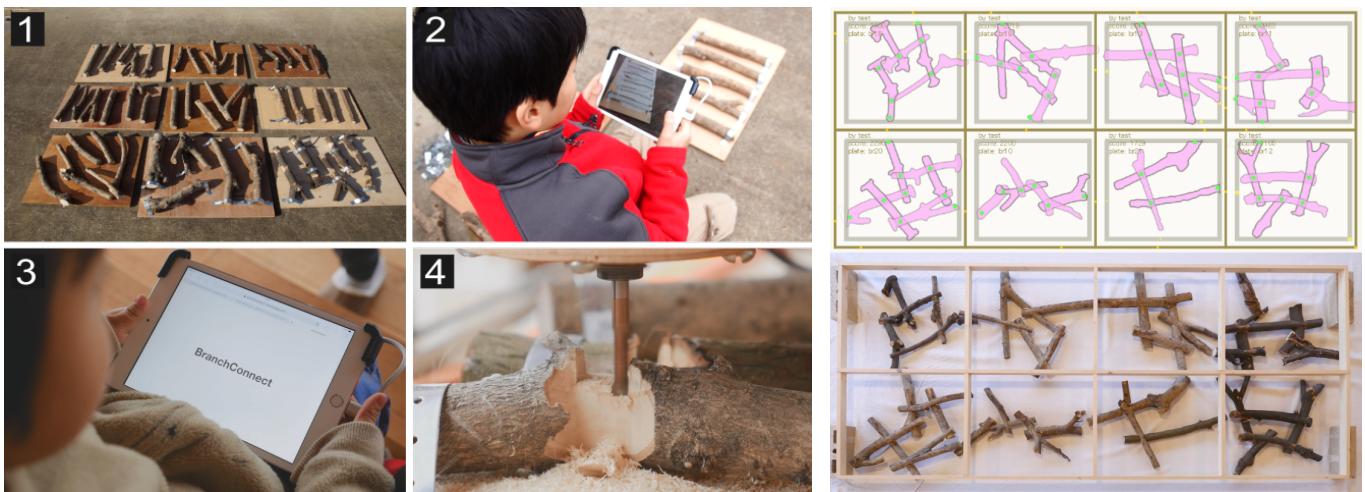


Figure 1: Left: an overview of the workflow: 1. fix branches on plates. 2. scan the plates and upload the model. 3. play the game with scanned branches. 4. fabricate joineries by a CNC router. Right top: branch layouts partially designed by participants in a workshop. Right bottom: the fabricated 2D fence (2m x 0.9m). Each pair of branches is connected with rigid lapped joinery.

Abstract

Diverse natural materials such as stones and woods have been used as architectural elements, preserving their native forms since primitive shelters, however, the use of them in modern buildings is limited due to their irregular properties. In this paper, we take the diversity as playful inputs for design task, and present our game-based design-fabrication platform for customized architectural elements. Taking tree branches as a material with native forms, our online game *BranchConnect* enables users to design 2D networks of branches and fabricate it by a CNC router. The game considers fabrication constraints such as limitations with ordinal 3-axis CNC routers. Each connection has a customized unique joinery adapted to native forms of branches. The scoring system of the game guides users to design structurally sound solutions with given branches. Together with low-cost mobile scanning devices, users with diverse contexts can contribute to design and fabrication process not only as a game user, but also from collecting branches around their physical environments and uploading them to our online platform. For validating our process, we conducted a workshop with end-users (children and their parents). They collected branches in a nearby forest and contributed to design/fabricate a 2D fence with our system.

Keywords: radiosity, global illumination, constant time

Concepts: •Computing methodologies → Image manipulation; Computational photography;

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1 Introduction

Modern buildings are characterized by its uniformity; built upon the same principle of construction system, consisting of standardized building component and its assembly process. The standardized construction system is favored because of its efficiency in design and production. Each component satisfies specified structural performance, thus the assembled resulting structure can be analyzed systematically. On the other hand, excessive standardization converged buildings into similar materials and details, resulting in the detached design from built environment. Reacting on the issue, designers and architects actively use local materials not only as inspirational sources, but also as a catalyst of their design to the local context [Oliver 1997].

Since primitive shelters and huts, traditional construction has used locally found natural materials directly as they are found [Weston 2003]. Such a direct use can not compete with highly standardized materials and construction system, however, the uniqueness of native forms is a valuable quality which is lacking in standardized materials. As the material is locally obtained, building and living get much closer, thus people using the building can easily commit design and fabrication, fostering the sense of belonging to the community []. **TODO: citation** Locally obtained materials can easily connect design and the context of built environment in this way, but their irregular properties limit the use of them in modern buildings. Traditionally, craftsman has taken care irregular natural materials varying their native forms and dynamically design the global design by considering individual material properties [Pye 1968]. Such a task is difficult to be automated and these skills are developed through years of training, thus the use of native forms typically costs more than standardized construction system.

This paper aims to make the above-mentioned qualities of materials with native forms more accessible by digital technologies. We use locally obtained branches which can be found almost everywhere not only in country-side but also in urban environment such as parks and along streets. Public service takes care of these branches: an-

62 nual pruning, storing, and chipping or burning with some costs. The
 63 size of branches (from 5 -30 cm in diameter) is too small for fur-
 64 niture or other structural applications. It is a challenge for digital
 65 design and fabrication to utilize the diverse branches in meaningful
 66 ways. High-precision but low-cost scanning devices and personal
 67 digital fabrication machines make it possible to analyze and control
 68 natural materials with diverse native forms.

69 The key technical difficulty of materials with natives forms is de-
 70 sign. Optimization is a straightforward approach: minimize an en-
 71 ergy function which integrates structural and fabrication costs. This
 72 approach, however, is limited to particular design scenario with spe-
 73 cific materials. Furthermore, the concept of optimum solution is
 74 well suited to goals such as efficiency or low-cost, but these goals
 75 are not the qualities materials with natives forms can compete with
 76 standardized construction systems. Instead, we take humans in our
 77 scan-design-fabricate workflow not only to solve the design prob-
 78 lem, but also to provide an opportunity for people to participate in
 79 the workflow. Traditionally, in case of constructing public and sym-
 80 bolic buildings, such as church, people in a community took initia-
 81 tives from fund raising to design, or even in construction process [].

TODo: citation

83 In this paper, we report our case study to design and fabricate
 84 an architectural element out of irregularly shaped branches, using
 85 our humans-in-the-loop system. We developed an online platform
 86 where users can post branches found at hand, and design with them
 87 through the game *BranchConnect*. The game system itself helps
 88 users to design valid branch layouts and enable them to fabricate
 89 customized joineries to connect them together without screws and
 90 adhesives. The design of our joinery extends the traditional or-
 91 thogonal lap-joints to various angles within a range, freeing the di-
 92 verse forms of woods from orthogonal connections. Physically col-
 93 lected branches are digitally scanned and stored in a cloud database
BranchCollect, and offline application *Branch Importer* analyzes
 95 forms of branches and upload to the database. The simple visual
 96 feedback and scoring system of the game guide users to valid solu-
 97 tions, which are further inspected by an offline application *G-Code*
 98 *Generator* for CNC milling process. The game system and devel-
 99 oped import/export applications are currently limited to branches,
 100 however, the principle of human-in-the-loop for design is applica-
 101 ble for other kinds of materials with diverse irregular forms. We
 102 hope our method sheds lights on materials such as waste from de-
 103 molition of buildings for various design applications.

104 In summary, our contributions are

- 105 • a workflow enabling to take natural materials with native
 106 forms as design components.
- 107 • an online game-based approach to participatory design-
 108 fabrication.
- 109 • an algorithm to generate customized non-orthogonal joineries
 110 which are fabricatable by a CNC router.

2 Related Work

112 3D printers and CNC routers made digital fabrication more acces-
 113 sible, and pre-fabricated customized building components are often
 114 used in buildings nowadays [Knaack et al. 2012]. According to the
 115 theory by Pye [1968], these components are processed from highly
 116 standardized material, thus its digital fabrication process is “work-
 117 manship with certainty”; a batch process of reading G-Code and
 118 strict execution of the code. On the other hand, as “workmanship
 119 with risks” in digital fabrication, interactive fabrication enables
 120 machines to pick up uncertain happenings and react on it [Willis et al.
 121 2011]. Mueller and her colleagues developed interactive laser cut-

122 ting, taking user inputs and recognizing placed objects in a fabrica-
 123 tion scene [Mueller et al. 2012]. While their system interprets ob-
 124 jects as simple platonic geometry, our work takes the native forms
 125 of branches, however, our work does not support interactivity in
 126 fabrication process. Crowdsourced Fabrication project took advan-
 127 tage of humans-in-the-loop in their fabrication system [Lafreniere
 128 et al. 2016]. On the other hand, our work puts emphasis on crowd-
 129 sourced design as a socially networked fabrication. As a crowd-
 130 sourced design system, Jerry et. al., developed a platform for light
 131 users to design trees and plants [Talton et al. 2009]. Our work also
 132 developed online collaborative design platform but directly linked
 133 to the real-world.

134 There are few works that take natural materials with native forms
 135 as design components. Schindler and his colleagues used digitally
 136 scanned wood branches and used them for furniture and interior
 137 design elements [Schindler et al. 2014]. Monier and colleagues vir-
 138 tually generated irregularly shaped branch-like components and ex-
 139 plored designs of large scale structure [Monier et al. 2013]. Using
 140 larger shaped forked tree trunks, *Wood Barn* project designed and
 141 fabricated custom joineries to construct a truss-like structure[Mairs
 142 2016]. *Smart Scrap* project digitally measured lime stone leftover
 143 slates from a quarry and digitally generated assembly pattern of
 144 slates [Greenberg et al. 2010]. In industry, recognition of irregularly
 145 shaped objects is essential for waste management. *ZenRobotics* de-
 146 veloped a system that sorts construction and demolition waste by
 147 picking objects on a conveyor belt using robotic hands [Lukka et al.
 148 2014]. For factory automation purpose, there is a system that rec-
 149ognizes irregularly shaped objects and sort them into a container
 150 [Sujan et al. 2000]. While these projects demonstrated the capa-
 151 bility of digital fabrication processes to handle irregularly shaped
 152 materials, design process with native natural materials is still de-
 153 pending on experts.

154 Cimerman discussed architectural design practices that took
 155 computer-mediated participatory (architectural) design [Cimerman
 156 2000]. He mentioned three motivations of digital participatory de-
 157 sign:

- 158 • Including stakeholders in creation of one’s environment.
- 159 • Experimenting diverse design tastes from multiple point of
 160 views.
- 161 • Solving complex design tasks with full of diverse solutions.

162 Opening database of available local materials, people with various
 163 backgrounds can involve in design process, which could lower the
 164 cost of design fee with natural materials with native forms. For ex-
 165 ample, *Nano-Doc* took gamification approach to search valid nano-
 166 particle designs against tumors out of infinite design space [Hauert
 167 et al.]. *DrawAFriend* has developed an online game to collect big-
 168 data for drawing applications which assist humans with auto-stroke
 169 assistance [Limpaecher et al. 2013]. While these works developed
 170 games for collecting valuable data for solving medical or engineer-
 171 ing problems, our game is served as a collaborative design plat-
 172 form, aiming to solve the socio-cultural issues in modern buildings:
 173 1.generic design and 2.detached context.

3 Workflow

175 As illustrated in the left of Figure 1, our workflow starts from phys-
 176 ically collecting branches. The collected branches are uploaded to
 177 cloud database by *Branch Importer*, and served to the online game-
 178 based design application *BranchConnect*. The game system uses
 179 skeletons for its joint detection process working on browsers and
 180 accessible from laptop computers and mobile devices. As in the
 181 right of 1, users can explore a global design with multiple branch

layouts. Once the global design is fixed, designed layouts are further inspected by *G-Code Generator*, which generates customized joineries for CNC milling. After finishing the milling process, users physically assemble branches and complete the fabrication process. The pipeline of the workflow is illustrated in the Figure 2. In this section, we introduce two steps in the pipeline: Digital Model Acquisition and Fabrication. As for the game system, please refer Section 4.

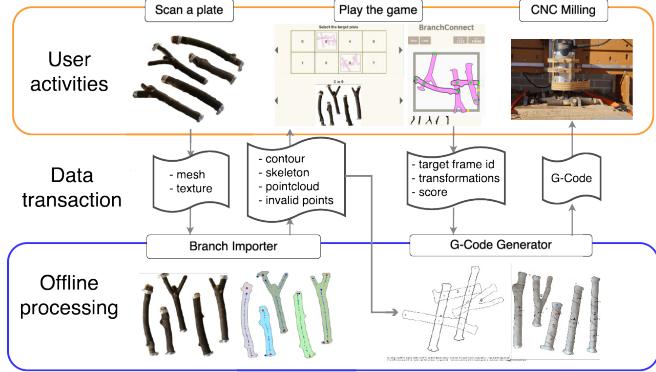


Figure 2: A pipeline from model acquisition to fabrication.

3.1 Digital Model Acquisition

Our system takes textured mesh model or point cloud with colored vertices. As complete mesh model provides more robust results with 3D shapes of branches, we describe our process based on mesh model as an input. There are various methods and software available for scanning 3D models. As for scanning setup, we describe in the Section 5. Taking mesh model with colored texture, our *Branch Importer* provides functions such as object detection, skeleton extraction, branch type classification, and fixture point setting.

The scanned result is a mesh model representing branches with a fixed plate. The system first identifies branches by applying simple height threshold, and then applies contour detection (we currently use *findContour* in OpenCV¹). The obtained 2D contours are used for extracting skeletons and clustering point cloud in the mesh model. Contours are triangulated and skeleton points are extracted from middle points on edges of triangles. These middle points are compared with top view image from OpenCV. If the point is inside of a contour, the middle point is counted as a valid point. After extracting valid middle points, the connectivity of skeletons is analyzed. In case grafting branch is detected, a new skeleton sub-branch is added. The result is shown in Figure 3. Metal fixture locations are confirmed by simple mouse-clicks and set as invalid points. The acquired information is stored in a cloud database.

3.2 Fabrication

After a design is selected for fabrication, the validity of the design is further inspected by a high-resolution model. The *G-Code Generator* displays joineries and milling paths on scanned orientations. In case joineries are invalid with the high-resolution model, a layout can be easily modified with simple mouse inputs (see Figure 4). Users can also change milling parameters such as offset ratio for the side cuts, milling bit diameter, depth of joineries, cutting speed, moving height and so forth. After confirming the fabrication settings and milling paths, it generates G-Code.

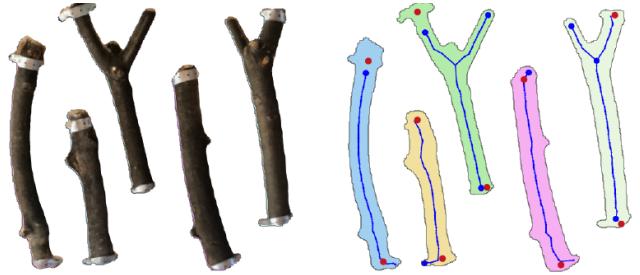


Figure 3: An interface of *Branch Importer*. Left: a top ortho-view image of textured mesh model. Right: Extracted skeletons are shown with blue dots. The beginning of skeletons is shown bigger dots, and the red dots are invalid points defined by a user.

Some fabrication factors such as invalid points due to metal fixtures and flipped (further described in Section 4.2) are already considered by *Branch Importer* and the game system respectively. In this section, we describe the process of joinery generation. Each joinery's geometry is parametrically modeled with two planar surfaces on the sides of branches (side cuts) and one planar top surface (center cuts) (see Figure 5.2). Side cuts have wedged corners for smooth assembly process. The geometry creates rigid joints with irregularly shaped sections of branches.

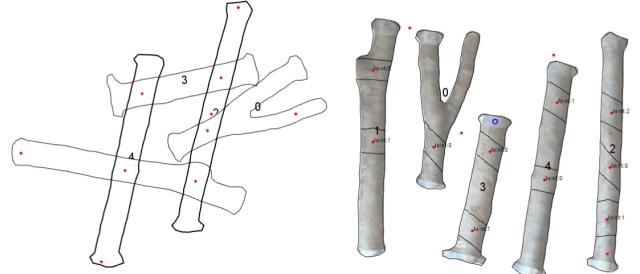


Figure 4: Interface of *G-Code Generator*. Left: a layout defined by a user. The calculated joineries are displayed. Right: an original orientation of a scanned plate with joineries.

Similar to the joint searching process with skeletons, the *G-Code Generator* searches a set of four closest points from high-resolution contours, expecting that every intersected contour has four curves. After finding the four closest points, it trims two curves from each contour of branch. (two from intersecting branch and two from intersected branch) at each joint. The trimmed contours are transformed to the original scanned orientation and used for generating milling paths. Two curves from an intersected branch are used for generating side cuts milling paths, which are inwardly offset paths of the original branch contours. Height of center cuts is half of branch diameter. The diameter as the joint is calculated with the contour. We compare this value with actual height from the stored point cloud. In case of under-cuts, the system detects different values and adjust the center cuts according to the recalculated diameter.

¹Open Source Computer Vision Library: <http://opencv.org/>

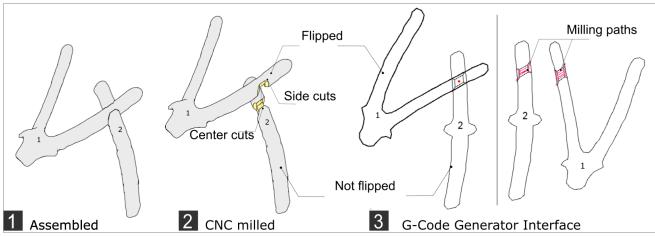


Figure 5: An example of intersected pair: 1. an assembled pair of branches. 2. branches after the center and side cuts are milled 3. left: a layout defined by a user right: the original orientations of branches with generated milling paths with red color.

4.1 System Overview

There are many collision detection libraries available, however, our game needs to detect intersected branch pairs, thus surface contact detection is overkill for our application. Also most branches come with free-form concave shapes, thus further geometric preparation such as convex decomposition is necessary for using these libraries. For fast and robust intersection detection, our system extensively uses skeletons of branches.

Hubbard and Philip developed collision detection by representing object with hierarchical 3D spheres aligned on skeletons [Hubbard 1996]. Our system takes similar approach but limited in 2D, but more focused on searching fabricatable joints. In the game, simplified skeletons are used to find the pair of closest skeleton points between two branches. When a branch is selected, it is counted as an active, and the system searches the closest skeleton point from skeletons of other branches. More precise joint calculation with higher resolution is further described in the next section.

A joint is created when an intersecting pair is detected, and the pair forms a group. The group is used for evaluating connections between target points (*Bridged*). The game is completed once all the target points are connected by a group of branches. The conditions of joint and group are indicated with simple color-code. Once the user finishes positioning, score is updated with weighted sum of parameters. Together with the color-code, the score update guides the user to form a valid design.

4.2 Joint Condition

Joint is the essential entity not only in the game but also in the fabrication process of customized lapped joineries.

Importantly, each pair of branches must have one flipped branch for fabrication constraint. We describe this further in a later section (see Section 3.2).

Figure 7 illustrates valid and invalid joint conditions.

Our joint only takes crossed pair (see Figure 7.1) because they are structurally stable, relatively simple to fabricate, and creates diverse designs. Tangential connections are counted as invalid as fabrication of tangential joinery is challenging with small branches (see Figure 7.3).

The online game is accessible by laptops and mobile touch devices, and many users can play at the same time. The objective of the game is to collect valid layouts of branches which are fabricatable with 3 axis CNC milling machines. By analyzing the connectivity of branches and target points, the game checks structural feasibility of a given layout. Similar to our game, the guidance system during furniture design inspected connectivity, durability, and stability [Umetani et al. 2012]. Unlike their work, our game puts emphasis on *fabricability*, as well as geometric *connectivity*, and does not calculate structural performance of each joint. Instead, we restrict valid layout space by limiting valid joint and conditions. We also assume that every fabricated joint works as a rigid joint, thus single connection is stable to hold a pair of branches.

Firstly a user selects a frame indicating multiple target points to be connected, and then selects a set of branches fixed on a plate (The left in Figure 6). After selecting the target frame and the set of branches, the user is guided to the game interface, consisting of the frame with the target points, and the set of available branches (The right in Figure 6). The user picks a branch from the available set on the bottom, and then places it in an arbitrary 2D pose through basic manipulations such as move, rotate, and flip. The number of available branches differs depending on plates. With the feasible diameter of branches (over 2cm) and the plate size (50cm x 50cm), the number of available branches is most likely up to six. Within the limited number of branches, the user bridges all the target points by connecting all the used branches in one group. The game is completed when all the target points are connected. For higher score, the user can modify the design after the completion, and save it to the database.

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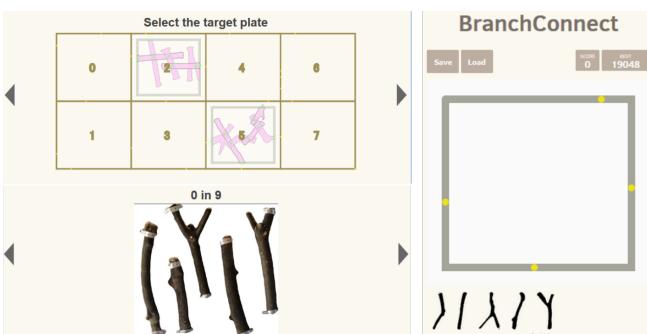


Figure 6: Left: the selection interface for target frames (top) and branch panels (bottom). Right: the start interface of the game.

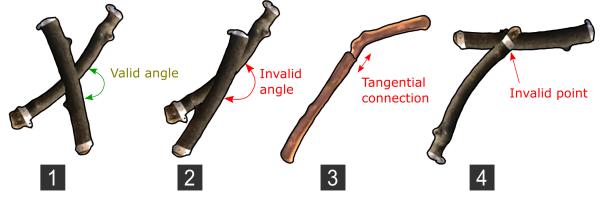


Figure 7: Joint conditions. 1.valid joint. 2.invalid for violating the angle. 3.invalid tangential connection. 4.invalid for connecting on a fixture point.

A valid joint's angle stays within a fixed range (see Figure 7.1 and 2). Joints close to metal fixtures are also counted as invalid (see Figure 7.4). Valid and invalid joints are displayed with green and red respectively.

To describe the process, we let \mathcal{B} denotes a set of all the available branches, and each branch as $b_i \in \mathcal{B}$. While the process checks joint condition through all the branches \mathcal{B} , each detected joint is

322 stored in each branch b_i , categorized in different conditions such as
 323 valid and invalid joints denoted as $j_{\text{valid},j,i} \in \mathcal{J}_{\text{valid},i}$ and $j_{\text{invalid},j,i} \in$
 324 $\mathcal{J}_{\text{invalid},i}$ respectively. When a branch b_i is connected to one of target
 325 point $t_j \in \mathcal{T}$, the t_j is stored in b_i .

326 A flowchart of the game system with joint and group conditions is
 327 illustrated in Figure 8.

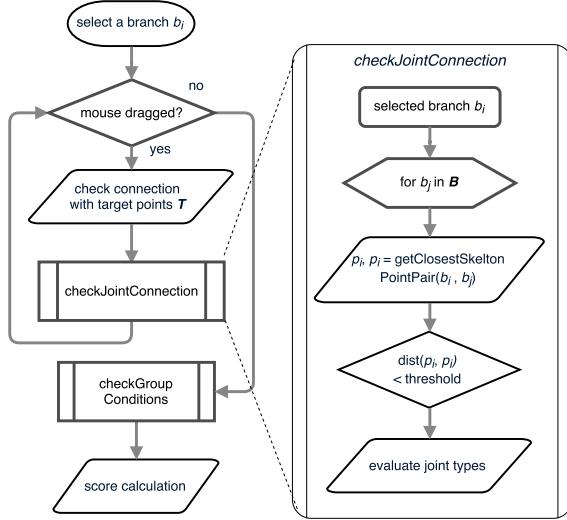


Figure 8: Left: an overview of the game system with 1. joint check and 2. group check and 3. score calculation. This process is iteratively executed while a user is exploring layout by dragging a branch. The joint check process is further illustrated in the right, and group condition check is described in Algorithm 1.

4.3 Group Condition

328 After checking joint conditions of all the pairs of branches, the sys-
 329 tem checks the number of groups as well as its connection with the
 330 target points on a frame. If a group is not connected to any target
 331 point nor other groups, the group is *Islanded* and structurally in-
 332 valid. While a user is positioning a branch by dragging or rotating,
 333 groups are continuously calculated and indicated by simple color
 334 (Figure 9).
 335

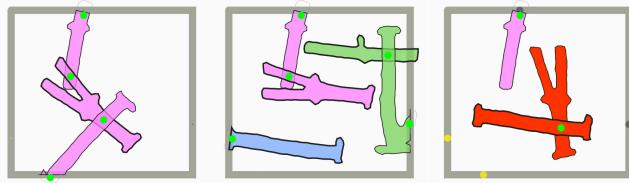


Figure 9: Left: valid group with two target points connected. Middle: valid but three groups. Right: invalid due to the Islanded situation.

336 After all the joint conditions are checked, we evaluate group con-
 337 ditions. Through checking the all the branches \mathcal{B} , the first group
 338 g_0 is created and stored as b_0 . When a branch is connected to a
 339 target point, the graphics of the point changes, and the branch and
 340 its belonging group's color also changes. When a group bridges
 341 a pair of target points, a special score is added and displayed in
 342 a pop-up square, also the graphics of target point's changes. The
 343 branch connected to the target point is trimmed at the target point,
 344 and the trimmed length is subtracted from the score. The game is

345 completed when the number of \mathcal{G} is one, and all the target points
 346 are connected with the group. The algorithm which checks group
 347 conditions is described in 1.

Algorithm 1 Group Condition Update Algorithm

```

1: function UPDATEGROUPS( $\mathcal{B}$ )
2:   Reset all the groups  $\mathcal{G}$ 
3:   Create new group  $g_0$ 
4:    $b_0$  is added to  $g_0$ 
5:   if  $b_0$  has connected target point  $t_i \in \mathcal{T}$  then
6:      $g_0$  sets  $t_i$ 
7:    $g_0$  is added to  $\mathcal{G}$ 
8:   for each branch  $b_i$  in  $\mathcal{B}$  do
9:      $GroupConnection \leftarrow false$ 
10:    for each group  $g_j$  in  $\mathcal{G}$  do
11:      for each branch  $b_j$  in  $g_j$  do
12:        if  $b_{\text{paired},i} \in \mathcal{P}_j$  has  $b_j$  then
13:           $b_i$  is added to  $g_j$ 
14:           $GroupConnection \leftarrow true$ 
15:          if ( $b_i$  has  $t_i$ ) and ( $g_j$  has  $t_j$ ) then
16:            Set  $g_j$  as Bridged
17:          if  $g_j$  has no  $t_j$  then
18:            Set  $g_j$  as Islanded
19:            break
20:        if  $GroupConnection$  is false then
21:          create new group  $g_{new}$ 
22:           $b_i$  is added to  $g_{new}$ 
23:           $g_{new}$  is added to  $\mathcal{G}$ 
  
```

4.4 Score Calculation

349 In the score calculation processes, following entities forms the
 350 score: the numbers of valid and invalid joints on each branch,
 351 the number of groups as $N(\mathcal{G})$, the number of islanded groups
 352 as $N(g_{\text{islanded}} \in \mathcal{G})$, the number of bridged target points as
 353 $N(t_{\text{bridged},i}) \in \mathcal{T}$). The trimmed lengths of branches which are
 354 connected with target points are denoted as $\text{trimmed}(t_j, b_i)$. The
 355 score is weighted sum of these joint and group conditions, denoted
 356 in Equation (1). The weights 'w1...w5' are non-negative weight
 357 coefficients pre-adjusted in advance by authors.

$$\begin{aligned}
 Score = & w_1 \sum_1^{N(\mathcal{B})} \sum_1^{N(\mathcal{J}_{\text{valid},i})} j_{\text{valid},j,i} + w_2 \sum_1^{N(\mathcal{B})} \sum_1^{N(\mathcal{J}_{\text{invalid},i})} j_{\text{invalid},j,i} \\
 & + w_3 \sum_1^{N(\mathcal{G})} g_{\text{islanded}} + w_4 \sum_1^{N(\mathcal{T})} t_{\text{bridged}} \\
 & + w_5 \sum_1^{N(\mathcal{T})} \text{trimmed}(t_j, b_i) \\
 \text{s.t. } & w_j \geq 0 \forall j \in 1, \dots, 5
 \end{aligned} \tag{1}$$

5 Case Study

359 A design and fabrication workshop was organized to examine the
 360 validity of our system with a specific design target and a location.
 361 We selected a public community house where people in the commu-
 362 nity share the space and regularly use the facility and participants
 363 were selected among them. Participants are four children aged 10
 364 and under (4, 7, 9, and 10 years old) and two parents (Figure 10).

We specifically selected children with the age range as non-experts without experiences in computational design or digital fabrication, also for observing the clarity and attractiveness of the game.

The goal for the participants is to contribute to an ongoing design and fabrication process of screen wall (2m by 0.9m) consisting of 8 rectangles. Six frames were already designed and built, thus the rest two frames were prioritized for them to design and fabricate in this workshop.

Participants are asked to follow the entire process from collecting and fixing the branches on a plate, scanning the plate, complete designs by playing the game, and assembly after the CNC milling. Participants were informed about the goal of the workshop, and each process was introduced by experienced tutors.



Figure 10: An overview of the workshop. 1.the overview of the space. 2.collect branches. 3.cut 4.attach on a plate 5.scan 6.play the game 7.CNC milling.

5.1 Setup

System and Hardware Setup

We used two iPad minis with iSense scanners attached for scanning branches, and a 3 axis CNC milling router with a 6 mm diameter milling bit. We used a laptop PC (Lenovo w240 with intel core i7) for running *Branch Importer* and *G-Code generator*, as well as operating the milling machine. The scan area of iSense is 500mm x 500mm, and the milling machine's stroke along z-axis is 70mm, which provide geometric constraints for available branch sizes. *BranchConnect* was hosted at Heroku cloud server², and we used *MongoDB*³ as a cloud database.

Preparation of Branches

The participants were asked to collect branches with 2 - 10 cm in diameter. The lower bound of the diameter is for milling process would not destroy them, and the upper bound is for the limit of z-stroke of the CNC router. The collected branches are cut in arbitrary lengths, not longer than 500 mm due to the limit of scanning area.

As our game system and fabrication process take 3D branch shapes as 2D contours with height map, these constraints work positive for the system automatically filtering out branches with large 3D twists. We ask participants to scan with iPad + iSense and prepare feasible mesh model by themselves. After obtaining mesh models, tutors import models from iPads to a laptop and upload them to database by *Branch Importer*.

²Heroku is a platform as a service (PaaS) that enables developers to build, run, and operate applications entirely in the cloud. <https://www.heroku.com/>

³MongoDB is a free and open-source cross-platform document-oriented database program. <https://www.mongodb.com/>

User Experiences with the System

After models were uploaded to the server, users can see that their plates are added in the selectable branch plates with their names and locations. Users can access to the start page by PC and mobile devices. We prepare both options and let participants choose a device.

A user is firstly directed to a start page and asked to submit a user name. Secondly, the user is navigated to target frame selection page, and asked to pick one out of eight frames. Each frame has different target points. The interface also shows the completed branch organizations within each target frame. If there are multiple designs, three designs with highest scores are displayed. The user can change the currently displayed design by clicking within each frame and choose either starting their design from scratch, or select the design and improve it.

After selecting a target frame, the user goes to branch selection page, displaying 15 plates when the workshop was held. In this page, they see the plates made by themselves on the page, as well as their names on the plate. The user can select the same plate for designing other target frames. By clicking a displayed branch plate, the user is navigated to the game interface. After completing to bridge all the target points, the design is automatically uploaded to the database, but the user can continue to design. Tutors and participants select design solution for each target frame, and an experienced tutor operates *G-Code Generator* as well as the CNC router. Participants were asked to assembly branches after joineries were milled.

5.2 Results

The entire workshop took 4.6 hours to complete the whole process, including introduction, moving, and pauses. Table 5.2 shows durations of each task.

Task	Duration (hour)	Fraction (%)
Introduction	0.3	6.5
Collecting branches	0.6	13.0
Preparing plates	0.8	17.4
Preparing models	0.3	6.5
Uploading models	0.2	4.3
Designing by the game	0.5	10.8
Inspecting models	0.2	4.3
CNC milling	0.5	10.8
Assembling	0.2	4.3
Miscellaneous	1.0	21.7
In total	4.6	100

Collecting Branches

The diameter and length constraints for available branches worked as guidelines for participants rather than restricting finding and cutting arbitrary branches. After cutting branches in certain lengths, participants fixed branches on plates by thin metal plates with screw holes. It was straightforward for them to firmly fix branches so that they are not moved during milling process. These fixture points are counted as invalid points in the game where joinery points can not be generated. The participants built two plates with three and five branches fixed on each plate.

Model Acquisition

iSense 3D scanners come with an intuitive software for scanning and modifying models. After we gave an instruction, most of participants practiced several scans and successfully scanned models

450 without any problem.

451 Each scanning and re-touching took 2-3 minutes, and 30 seconds
 452 for generating data by *Branch Importer*. Including the prepared
 453 panels previously, we scanned 15 plates in total, 75 branches, and
 454 35.3m of total length including sub-branches. **TODO: check the
 455 length again!** We got 40 *I* shaped branches, 19 *V* shaped branches,
 456 and 16 *Y* shaped branches. The result is shown in Figure 11.

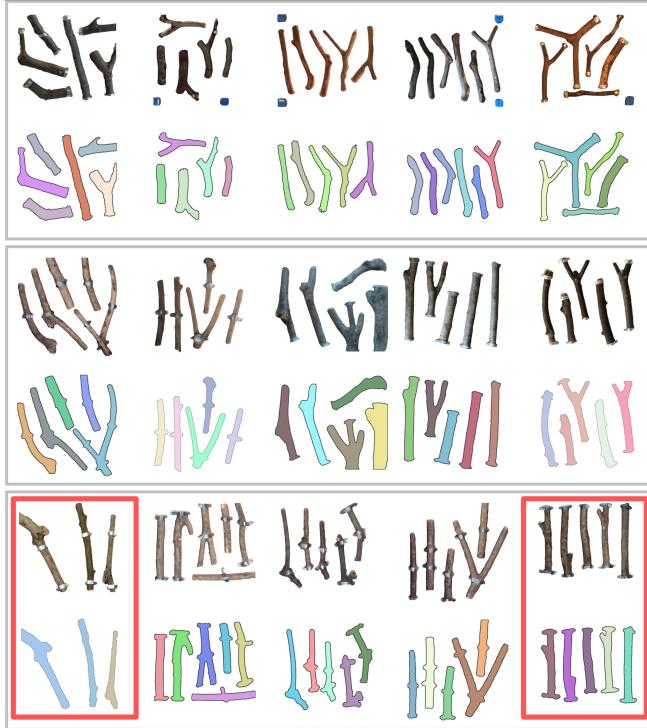


Figure 11: An overview of all the 15 scanned plates for the workshop. Top raw of each set shows ortho-top views of scanned mesh models, and the bottom raw is the recognized branches assigned random colors. The red-lined rectangles indicate the plates built by participants in the workshop.

457 Design with the Game

458 Most participants used iPads for navigating pages and playing the
 459 game. All the participants understood the goal immediately, how-
 460 ever, they had difficulties with mobile touch interface, such as rota-
 461 tion and flipping operation by gestures.

462 One participant switched to play by a PC for more precise control
 463 due to the problem. All the participants chose to develop their own
 464 designs from the scratch, although they had instruction about the
 465 "continue existing designs".

466 Although there is no time limit in the game system, we set 30 min-
 467 utes for playing the game, and 8 solutions were given by partici-
 468 pants. xxx frames were completed per participants and xxx partici-
 469 pants completed the whole eight target frames. The average score is
 470 xxx, and average playing duration was xxx to complete each target
 471 frame.

472 Overall Design Consensus **TODO: this section might be re-** **473 moved**

474 As the target frame selection page can display designs not only
 475 from one user but also from all the others at once, we could get

476 an overview of design options. The designs are displayed as score
 477 descending order but limited numbers, we could find feasible solu-
 478 tions with mostly all the target points were bridged. As participants
 479 were excited by seeing their branches and designs, we took some
 480 of their solutions and their plates for the fabrication although their
 481 solutions did not satisfied completion of the game.

482 Fabrication

483 We did not have major problems for converting designs to G-Code
 484 milling paths as we encountered major issues regarding the fabri-
 485 cation before the workshop, which are reported in this section.

486 The main problem was the accuracy of acquired contours. We
 487 observed most of scanned models had occluded regions between
 488 plates and branches, which create interpolated faces during
 489 solidifying process, resulting in outwardly offsetted contours.
TODO: check offsetted correct english After milling was finished
 490 and when branches were assembled, six pairs of branches were
 491 loosely connected because the calculated contours were 2-3mm
 492 eroded than the actual sizes. We avoided this problem by trimming
 493 branches from 2-5 mm higher than the plate surface. After this
 494 operation, the rest of connections were tightly connected.

495 We also observed that many milling paths were 5-10 mm off from
 496 the center of planned joints. Multiple reasons could be considered
 497 as reasons such as,

- 500 • deformation of mechanical parts of the CNC router
- 501 • not dense resolution of acquired contours of branches
- 502 • misaligned orientation of the plate compared to the scanned
 503 model

504 To avoid the misalignments, we modified the *G-Code Generator*
 505 so that an operator can freely adjust the absolute origin of the gen-
 506 erated milling paths. The origin was usually set with around the
 507 center of the plate. After this modification, the misalignment from
 508 joint center was reduced with 5 mm off at the maximum misalign-
 509 ment. Branches could absorb 3-5 mm misaligned joint positions
 510 due to the elasticity of the wooden materials. The misaligned joint
 511 positions worked as post-tensions, solidifying the structure. We
 512 assume that this is only applicable when an applied bending moment
 513 and cut surface at a joint is orthogonal or not too much off from
 514 orthogonal. **TODO: this sentence**

515 5.3 Summary

516 The objective of the workshop was to observe the validity of our
 517 system for non-expert users. We could see that participants aged
 518 10 and under were capable of following the workflow. Participants
 519 were encouraged to contribute to the ongoing design with the online
 520 platform, and successfully provided designs from available branch
 521 plates.

522 We had several requests from participants regarding the game in-
 523 terface but also related to the workshop organization. Several par-
 524 ticipants requested to allow multiple branch plates for designing a
 525 frame, or even remove the target frame and let them freely design
 526 with branches. Also a participant who gave up with iPad operations
 527 requested additional buttons for mobile touch interface to keep an
 528 active branch selected.

529 A noteworthy fact was that one participant with four years old failed
 530 to complete the game, but insisted on accepting his design to be fab-
 531 ricated by the CNC router. We took these requests as their commit-

532 ment to the entire workflow, as we observed that all the participants
 533 insisted on continuing the fabrication process.

534 6 Conclusion

535 Summary

536 In this paper, we presented a workflow to design and fabricate with
 537 branches which are not large enough for producing standardized
 538 building components. Our workflow was validated with case-study
 539 with lower-aged participants without design and fabrication experi-
 540 ences. Our online platform to store geometries of scanned branches
 541 and compositions of branches was reachable by people with vari-
 542 ous backgrounds. Our light-weight branch joint detection algorithm
 543 was also validated by running on the browser game, contributed to
 544 the accessibility of the presented workflow. Together with the ac-
 545 cessibility, the intuitive interface was simple enough for non-expert
 546 users. We successfully built a network of branches with rigid joints
 547 generated by our joinery milling path generator. Each of joints has
 548 customized lapped-joint geometry, which is challenging to design
 549 and fabricate.

550 Limitations and Future Work

551 Our system is limited to handle 3D shaped branches as 2D with
 552 height information only used for segmentation and G-Code genera-
 553 tion. Our workflow requires branches to be fixed on a plate, which
 554 takes the longest duration in the workflow except for moving and
 555 pause in between tasks. Despite of successfully fabricated non-
 556 orthogonal joineries, we did not complete the attaching branches to
 557 target frames, as we prioritized to validate branch-branch joineries.

558 Our design workflow fully relies on human's ability for obtaining
 559 design solutions. As the problem of limited number of branches
 560 and fixed target points to be connected, the system could assist hu-
 561 mans to reach to structurally sounding solutions with less efforts.
 562 Collected data from game could be further analyzed for extracting
 563 meaningful data for the development of assisting algorithm. Our
 564 joint and group detection, and milling path algorithms are not ap-
 565 plicable to other purposes at this moment. It is valuable to com-
 566 pare the performance of our joint and group detection system to
 567 other collision detection library. In our workflow, the pipeline is
 568 not seamlessly connected: experienced operators need to take care
 569 of retouching mesh model, Branch Importer, and G-Code generator,
 570 and operating a CNC router.

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