

Participatory Design and Fabrication Platform with Non-standard Materials



Figure 1: Left: an overview of the workflow: 1. fix branches on plates. 2. scan the plates and upload the model. 3. play the game with scanned branches. 4. fabricate joineries. Right top: compositions designed by participants in a workshop. Right bottom: the outcome as an interior screen (2m x 0.9m).

Abstract

Diverse natural materials such as stones and woods have been used as architectural elements preserving their native forms since primitive shelters, however, the use of them in modern buildings is limited due to the irregular properties. In this paper, we take the diversity as playful inputs for design task, and present our participatory game-based design-fabrication platform for customized architectural elements. Taking tree branches as case study of materials with native forms, our online game *BranchConnect* enables users to design 2D networks of branches and realize the design. As the generated design is realizable with ordinal 3-axis CNC milling machines, each connection has a customized unique joinery adapted to the native branch shapes. The scoring system of the game guides users to design structurally sound solutions with given branches. Together with low-cost mobile scanning devices, users with diverse contexts can contribute to design and fabrication process not only as a game user, but also from collecting branches around their physical environments and uploading them to our online platform. For validating our process, we conducted a workshop with end-users (children and their parents). They collected branches in a nearby forest and contributed to design/fabricate a 2D fence with our system.

Keywords: radiosity, global illumination, constant time

Concepts: •Computing methodologies → Image manipulation; Computational photography;

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1 Introduction

Modern buildings are characterized by its uniformity; built upon the same principle of construction system, consisting of standardized building component and its assembly process. The standardized construction system is favored because of its efficiency in design and production. Each component satisfies specified structural performance, enabling to integrate them and calculate the performance of the overall structure. On the other hand, excessive standardization converged buildings into similar materials and details, resulting in the detached design from built environment. Reacting on the issue, designers and architects actively use local materials not only as inspirational sources, but also as a catalyst of their design to the local context [Oliver 1997].

Since primitive shelters and huts, traditional construction has used locally found natural resources. Direct use of these materials can not compete with highly standardized materials and construction system, however, the uniqueness from their native shapes is a valuable quality which is lacking in standard materials. As the material is found locally, building and living get much closer, thus people using a facility can easily commit design and fabrication, fostering the sense of belonging to the community []. **TODO: citation** Locally found material easily connects design and the context of built environment in this way, but their irregular properties limit the use of them in modern buildings. Traditionally, craftsman has taken care irregular natural materials varying their native shapes and dynamically design the global design by considering individual material properties [Pye 1968]. Such a task is difficult to be automated and these skills are developed through years of training, thus typically the use of native shapes costs more than standardized construction system.

This paper aims to make the above-mentioned qualities of materials with native shapes more accessible by digital technologies. We use locally found branches as materials with native shapes, which can be found almost everywhere not only in country-side but also in urban environment such as parks and along streets. Public service

takes care of these branches: annual pruning, storing, and chipping or burning with some costs. The size of branches (from 5 -30 cm in diameter) is too small for furniture or other structural applications. It is a challenge for digital design and fabrication to utilize the diverse branches in meaningful ways. High-precision but low-cost scanning devices and personal digital fabrication machines make it possible to analyze and control natural materials with diverse native shapes.

The key technical difficulty with materials with natives shapes is design. Optimization is a straightforward approach: minimize an energy function which integrates structural and fabrication costs. This approach, however, is limited to particular design scenario with specific materials. Furthermore, the concept of optimum solution is well suited to goals such as efficiency or low-cost, but these goals are not the qualities materials with natives shapes can compete with standardized construction systems. Instead, we take humans in our scan-design-fabricate workflow not only to solve the design problem, but also to provide an opportunity for people to participate in the workflow. Traditionally, in case of constructing public and symbolic buildings, such as church, people in a community took initiatives from fund raising to design, or even in construction process [].

TODO: citation

In this paper, we report our case study to design and fabricate an architectural element out of irregularly shaped branches, using our humans-in-the-loop system. We developed an online platform where users can post branches found at hand, and design with them through the game *BranchConnect*. The game system itself helps users to design valid branch compositions and enable them to fabricate customized joineries to connect them together without screws and adhesives. The design of our joinery extends the traditional orthogonal lap-joints to various angles within a range, freeing the diverse shapes of woods from orthogonal connections. Physically collected branches are digitally scanned and stored in a cloud database *BranchCollect*, and offline application *Branch Importer* analyzes shapes of branches and upload to the database. The simple visual feedback and scoring system of the game guide users to valid solutions, which are further inspected by an offline application *G-Code Generator* for CNC milling process. The game system and developed import/export applications are currently limited to branches, however, the principle of human-in-the-loop for design is applicable for other kinds of materials with diverse irregular shapes. We hope our method sheds lights on materials such as waste from demolition of buildings for various design applications.

Our contributions are summarized as follows.

- a workflow enabling to take natural materials with native shapes as design components.
- online platform to collect irregularly shaped materials and serving them to an online game as a design driver.
- fast and robust intersection detection algorithm for fabricating customized non-orthogonal joineries.

2 Related Work

3D printers and CNC routers made digital fabrication more accessible, and pre-fabricated customized parts are often used in buildings nowadays [Knaack et al. 2012]. According to Pye, these parts are processed from highly standardized material, thus its digital fabrication process is “workmanship with certainty”; a batch process of reading G-Code and strict execution of the code. On the other hand, as “workmanship with risks” with digital technologies, interactive fabrication enables machines to pick up uncertain happenings and react on it [Willis et al. 2011]. Mueller developed interactive laser

cutting, taking user inputs and recognizing placed objects in a fabrication scene [Mueller et al. 2012]. While their system interprets objects as simple platonic geometry, our work takes the branches with diverse shapes. While Crowdsourced fabrication project took advantage of humans-in-the-loop in their fabrication system [Lafreniere et al. 2016], our work puts emphasis on crowd-sourced design. As a crowd-sourced design system, Jerry et. al., developed a platform for light users to design trees and plants [Talton et al. 2009]. Our design process is not parametric modeling, also directly linked to physical world. **TODO: ill-logic**

There are few works that take natural materials with native shapes as design components. Schindler and his colleagues used digitally scanned wood branches and used them for furniture and interior design elements [Schindler et al. 2014]. Monier and colleagues virtually generated irregularly shaped branch-like components and explored designs of large scale structure [Monier et al. 2013]. Using larger shaped forked tree trunks, *Wood Barn* project designed and fabricated custom joineries to construct a truss-like structure[Mairs 2016]. *Smart Scrap* project digitally measured lime stone leftover slates from a quarry and digitally generated assembly pattern of slates [Greenberg et al. 2010].

In industry, recognition of irregularly shaped objects is essential for waste management. *ZenRobotics* developed a system that sorts construction and demolition waste by picking objects on a conveyor belt using robotic hands [Lukka et al. 2014]. For factory automation purpose, there is a system that recognizes irregularly shaped objects and sort them into a container [Sujan et al. 2000]. Getting out from factories, autonomous robotics in construction site is a hot topic among roboticists [Feng et al. 2014]. *In-situ Fabricator* is a system which could be installed in construction site and co-operated with human workers [Dörfler et al. 2016]. Once robot is autonomously localize itself in such an environment, it can build foundational structure for further construction [Napp and Nagpal 2014]. Using locally found objects on-site, such a system can be much simpler.

While these projects demonstrated the capability of digital fabrication processes to handle irregularly shaped materials, design process is still dependent on a designer or architect who has experiences with materials or has access to special software.

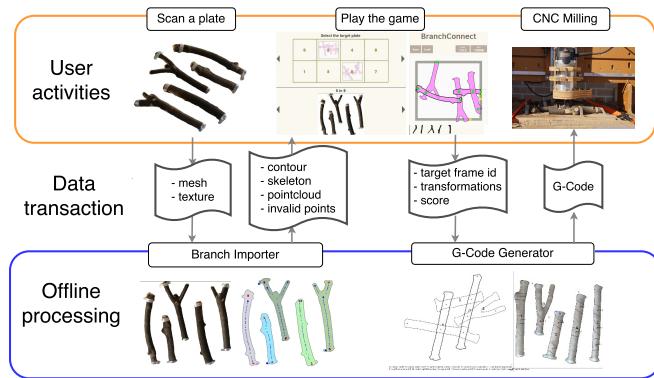
Cimerman discussed architectural design practices that took computer-mediated participatory design [Cimerman 2000]. He mentioned three motivations of digital participatory design:

- Including stakeholders in creation of one's environment.
- Experimenting diverse design tastes from multiple point of views.
- Solving complex design tasks with full of diverse solutions.

Opening database of available local materials, people with various backgrounds can involve in design process, which could lower the cost of design fee with natural materials with native shapes. For example, *Nano-Doc* took gamification approach to search valid nanoparticle designs against tumors out of infinite design space [Hauert et al.]. *DrawAFriend* has developed an online game to collect big-data for drawing applications which assist humans with auto-stroke assistance [Limpaecher et al. 2013]. While these works developed games which are collecting data for solving medical or engineering problems, our game intends to provide a participatory design platform as a solution for social and cultural problems context-aware architectural design with locally found natural materials. **TODO: ambiguous!**

183 3 Workflow

184 In this section, we shortly walk through the pipeline in our workflow
 185 and describe three steps: Digital Model Acquisition, the Game
 186 System, and Fabrication. Our system takes textured mesh model or
 187 point cloud with colored vertices. As complete mesh model pro-
 188 vides more robust result with 3D shapes of branches, we describe
 189 our process based on mesh model as input (see Figure 2).



190 **Figure 2:** A pipeline from model acquisition to fabrication.

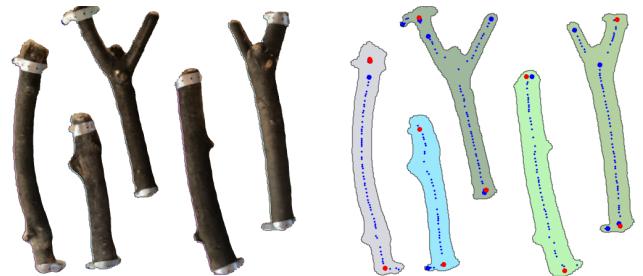
3.1 Digital Model Acquisition

191 There are various methods and software available for scanning 3D
 192 models and detecting objects. As for the scanning, we describe
 193 in the Experiment. Taking mesh model with colored texture, our
 194 *Branch Importer*, integrates necessary functions such as object de-
 195 tection, skeleton extraction, branch type classification, and fixture
 196 location detection.

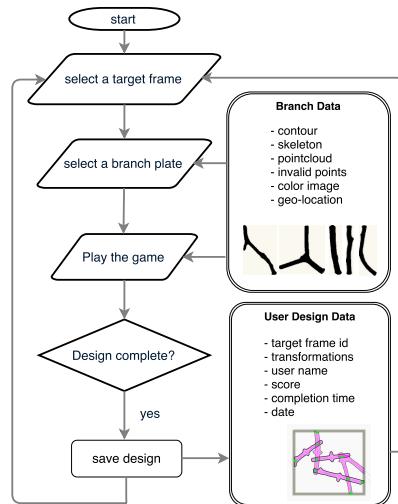
197 After segmenting branches from a plate by height threshold, each
 198 branch is detected using *findContour* in OpenCV ¹. The obtained
 199 2D contours are used for extracting skeletons and clustering point
 200 cloud in the mesh model. Contours are triangulated and skeleton
 201 points are extracted from middle points on edges of triangles. These
 202 middle points are compared with binary top view image of the mesh
 203 model (contours are filled with different colors and the background
 204 is white). If the point is inside of a contour, the middle point is
 205 counted in skeleton points. Metal fixture locations are also filtered
 206 out due as they have bright reflections on original images, however,
 207 we also double check with simple mouse-clicks to ensure these in-
 208 valid points. After extracting valid middle points, connectivity of
 209 skeletons is analyzed by angle of three adjacent skeleton points. If
 210 the angle stays within a threshold bound, a point is counted in a sub-
 211 branch, otherwise, new sub-branch is created. Evaluating the num-
 212 ber of sub-branches, the branch is morphologically classified. Most
 213 branches are categorized in three shapes: *I*, *V*, and *Y* shapes. *I*
 214 shape has a straight continuous polyline, *V* has an inflection point,
 215 and *Y* has a splitting point. The acquired information is stored in a
 216 cloud database.

3.2 BranchConnect: The Game

217 The game objective is to collect valid compositions of branches
 218 which structurally sounding and possible to fabricate with ordinal
 219 3 axis CNC milling machines. The workflow of the game is illus-
 220 trated in Figure 4



221 **Figure 3:** An overview of *Branch Importer*. Left: a top ortho-view
 222 image of textured mesh model. Right: Extracted skeletons (blue
 223 dots). The beginning of skeletons is shown bigger dots. Red
 224 dots are invalid points.



225 **Figure 4:** The workflow of *BranchConnect*. Branch data and user
 226 data are stored on cloud database.

227 Firstly a user selects a frame indicating multiple target points to be
 228 connected, and then selects a set of branches fixed on a plate (The
 229 left in Figure 5). After selecting the target frame and the set of
 230 branches, the user is guided to the game interface, consisting of the
 231 frame with the target points, and the set of available branches (The
 232 right in Figure 5). The user picks a branch from the available set
 233 on the bottom, and then places it in an arbitrary 2D pose through
 234 basic manipulations such as move, rotate, and mirror. The number
 235 of available branches differs depending on plates. With the feasible
 236 diameter of branches (over 2cm) and the plate size (50cm x 50cm),
 237 the number of available branches is most likely up to six. Within
 238 the limited number of branches, the user bridges all the target points
 239 by connecting all the used branches in one group. The game is
 240 completed when all the target points are connected by branches. For
 241 higher score, the user can modify the design after the completion.
 242 After completing the modification, the design is submitted and sent
 243 to *G-Code Generator*.

¹Open Source Computer Vision Library. See <http://opencv.org/>

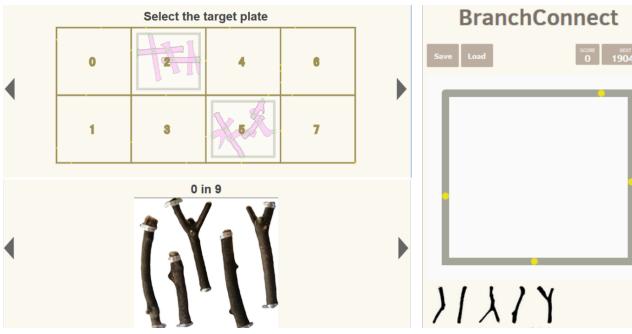


Figure 5: Left: the selection interface for target frames (top) and branch panels (bottom). Right: the start interface of the game.

designs. To ensure the structural performance, we set a connection angle within a range from 45 to 135 degrees. Joints close to metal fixtures are also counted as invalid. Valid and invalid joints are displayed with green and red respectively. The color-code feedback is also given when target points on a frame is connected with a branch. Figure 7 illustrates valid and invalid joint conditions.

To describe the process, we let \mathcal{B} denotes a set of all the available branches, and each branch as $b_i \in \mathcal{B}$. While the process checks joint condition through all the branches \mathcal{B} , each detected joint is stored in each branch b_i , categorized in different conditions such as valid and invalid joints denoted as $\mathcal{J}_{\text{valid},i}$, $\mathcal{J}_{\text{invalid},i}$ respectively, together with the paired branch id $b_{\text{paired},j,i}$. When a branch is connected to one of target point $t_j \in \mathcal{T}$, the t_j is stored in p_i as $t_{j,i}$. **TODO: notaion should be improved!**

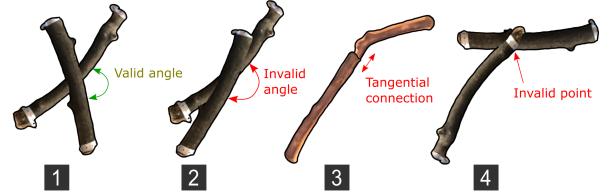


Figure 7: Joint conditions. 1.valid joint. 2.invalid for violating the angle. 3.invalid tangential connection. 4.invalid for connecting on a fixture point.

Group Condition

After checking joint conditions of all the pairs of branches, the system checks the number of groups as well as connectivity with the target points on a frame. If a group is not connected to any target point nor other groups, the group is islanded and structurally invalid. While a user is positioning a branch by dragging or rotating, groups are continuously calculated and indicated by simple color (Figure 8).

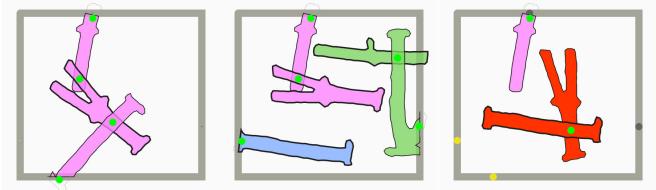


Figure 8: Left: valid group with two target points connected. Middle: valid but three groups. Right: invalid due to the island situation.

After all the joint conditions are checked, we evaluate group conditions. Through checking the all the branches \mathcal{B} , the first group g_0 is created and stores b_0 . The other paired branch $b_{\text{paired},i}$ is used to trace the connection with other compared to the traced through the stored paired branch in each valid joint j_i . in all groups \mathcal{G} . The game is completed when the number of \mathcal{G} is one, and all the target points are connected with the group.

Score Calculation

We denote the numbers of valid and invalid joints on each branch $b_i \in \mathcal{B}$ as $N(\text{valid}_i)$, $N(\text{invalid}_i)$ respectively, the number of groups as $N(\mathcal{G})$, the number of islanded groups as $N(g_{\text{islanded}} \in \mathcal{G})$,

System Overview

There are many collision detection libraries available, however, our game needs to detect intersected branch pairs, thus surface contact detection is overkill for our application. Also most branches come with free-form concave shapes, thus further geometric preparation such as convex decomposition is necessary for using these libraries. For fast and robust intersection detection, our system extensively uses skeletons of branches. Hubbard and Philip developed collision detection by representing object with hierarchical 3D spheres aligned on skeletons [Hubbard 1996]. Our system takes similar approach but more limited in 2D and intersection detection only. In broader phase, simplified skeletons are used to find the pair of closest skeleton points between two branches. After finding the pair, skeletons with higher resolutions are used.

A joint is created when an intersecting pair is detected, and the pair forms a group. The group is used for evaluating connections between target points. The game is completed once all the target points are connected by a group of branches. The conditions of joint and group are indicated with simple color-code. Once the user finishes positioning, score is updated with weighted sum of parameters. Together with the color-code, the score update guides the user to form a valid design. An overview is illustrated in Figure 6.

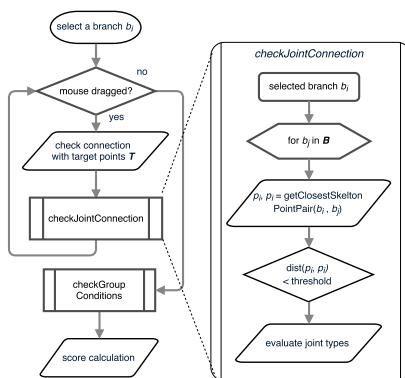


Figure 6: Left: an overview of the game system. Right: joint condition checking process.

Joint Condition

Joint is the essential entity not only in the game but also the entire project including the fabrication process. The closest skeleton point pair is obtained We accept crossing joints only because they are structurally stable, relatively simple to fabricate, and creates diverse

Algorithm 1 Group Condition Update Algorithm

```

1: function UPDATEGROUPS( $\mathcal{B}$ )
2:   Reset all the groups  $\mathcal{G}$ 
3:   Create new group  $g_1$ 
4:    $g_1$  add  $b_1$ 
5:   if  $b_1$  has connected target point  $t_1$  then
6:      $g_1$  set  $t_1$ 
7:    $\mathcal{G}$  add  $g_1$ 
8:   for each branch  $b_i$  in  $\mathcal{B}$  do
9:      $GroupConnection \leftarrow false$ 
10:    for each group  $g_j$  in  $\mathcal{G}$  do
11:      for each branch  $b_j$  in  $g_j$  do
12:        if  $b_{paired,i} \in \mathcal{P}_j$  has  $b_j$  then
13:           $g_j$  add  $b_i$ 
14:           $GroupConnection \leftarrow true$ 
15:          if ( $b_i$  has  $t_i$ ) and ( $g_j$  has  $t_j$ ) then
16:            Set  $g_j$  as Bridged
17:          if  $g_j$  has no  $t_j$  then
18:            Set  $g_j$  as Islanded
19:          break
20:        if  $GroupConnection$  is false then
21:          create new group  $g_{new}$ 
22:           $g_{new}$  add  $b_i$ 
23:           $\mathcal{G}$  add  $g_{new}$ 

```

Some fabrication factors such as mirror and invalid points are already considered by *Branch Importer* and the game system of *BranchConnect*. In this section, we describe the process of joinery generation. Each joinery geometry is different but has same topology: two plane surfaces on the sides of branches and one plane top surface. The geometry creates rigid connection with the irregularly shaped sections of branches. Similar to the joint searching process with skeletons, the *G-Code Generator* searches a set of four closest points from high-resolution contours, expecting that every intersected contour has four curves. After finding the four closest points, it trims two curves from each contour of branch. (two from intersecting branch and two from intersected branch) at each joint. The trimmed contours are transformed to the original scanned orientation and used for generating milling paths. Two curves from an intersected branch are used for side cuts milling paths, which are inwardly offset paths of the original branch contours. **TODO: need to brush up!** The center cuts are paths that are plaining the top surface of the joint. **TODO: describe the cutting height calculation!**

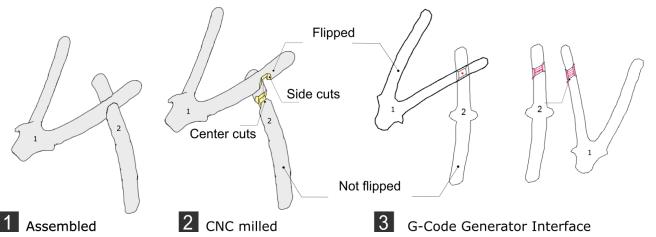


Figure 10: An example of intersected pair: 1. an assembled pair of branches. 2. branches after the center and side cuts are milled 3. left: a composition defined by a user right: the original orientations of branches with generated milling paths with red color.

the number of bridged target points as $N(t_{bridged,i}) \in \mathcal{T}$). The score is weighted sum of these joint and group conditions (see Eq 1).

Users can change fabrication parameters such as offset ratio for the side cuts, milling bit diameter, overlapping ratio for defining the center cut depth, feed-rate, moving height and so forth. After confirming the fabrication settings and milling paths, it generates G-Code.

TODO: notaion should be improved!

$$\begin{aligned}
Score = & w_1 \sum_1^{N(\mathcal{B})} N(valid_i) + w_2 \sum_1^{N(\mathcal{B})} N(invalid_i) \\
& + w_3 \sum_1^{N(\mathcal{G})} g_{islanded} + w_4 \sum_1^{N(\mathcal{T})} t_{bridged}
\end{aligned} \tag{1}$$

s.t. $w_j \geq 0 \forall j \in 1, \dots, 4$

3.3 Fabrication

A design and fabrication workshop was organized to examine the validity of our system with a specific design target and a location. We selected a public community house where people in the community share the space and regularly use the facility and participants were selected among them. Participants are four children aged 10 and under (4, 7, 9, and 10 years old) and two parents (Figure 11). We specifically selected children with the age range as non-experts without experiences in computational design or digital fabrication, also for observing the clarity and attractiveness of the game.

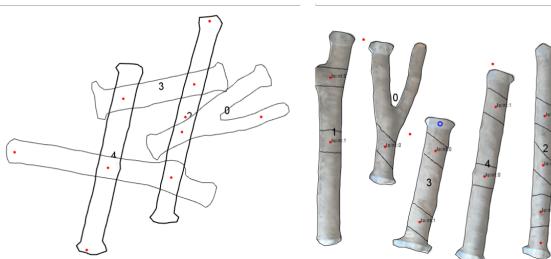


Figure 9: Interface of G-Code Generator. Users can tweak the design on the left side and immediately see the updated joints and milling paths on the right. **TODO: can this image be integrated with the other one?**

The goal for the participants is to contribute to an ongoing design and fabrication process of screen wall (2m by 0.9m) consisting of 8 rectangles. Six frames were already designed and built, thus the rest two frames were prioritized for them to design and fabricate in this workshop.

Participants are asked to follow the entire process from collecting and fixing the branches on a plate, scanning the plate, complete designs by playing the game, and assembly after the CNC milling. Participants were informed about the goal of the workshop, and each process was introduced by experienced tutors.



Figure 11: An overview of the workshop. 1.the overview of the space. 2.collect branches. 3.cut 4.attach on a plate 5.scan 6.play the game 7.CNC milling.

After selecting a target frame, the user goes to branch selection page, displaying 15 plates when the workshop was held. In this page, they see the plates made by themselves on the page, as well as their names on the plate. The user can select the same plate for designing other target frames. By clicking a displayed branch plate, the user is navigated to the game interface. After completing to bridge all the target points, the design is automatically uploaded to the database, but the user can continue to design. Tutors and participants select design solution for each target frame, and an experienced tutor operates *G-Code Generator* as well as the CNC router. Participants were asked to assemble branches after joineries were milled.

351 4.1 Setup

352 System and Hardware Setup

353 We used two iPad minis with iSense scanners attached for scanning branches, and a 3 axis CNC milling router with a 6 mm diameter milling bit. We used a laptop PC (Lenovo w240 with intel core i7) for running *Branch Importer* and *G-Code generator*, as 354 well as operating the milling machine. The scan area of iSense is 355 500mm x 500mm, and the milling machine's stroke along z-axis 356 is 70mm, which provide geometric constraints for available branch 357 sizes. *BranchConnect* was hosted at *Heroku* cloud server², and we 358 used *MongoDB*³ as a cloud database.

362 Preparation of Branches

363 The participants were asked to collect branches with 2 - 10 cm in 364 diameter. The lower bound of the diameter is for milling process 365 would not destroy them, and the upper bound is for the limit 366 of z-stroke of the CNC router. The collected branches are cut 367 in arbitrary lengths, not longer than 500 mm due to the limit of 368 scanning area.

370 As our game system and fabrication process take 3D branch shapes 371 as 2D contours with height map, these constraints work positive for 372 the system automatically filtering out branches with large 3D twists. 373 We ask participants to scan with iPad + iSense and prepare feasible 374 mesh model by themselves. After obtaining mesh models, tutors 375 import models from iPads to a laptop and upload them to database 376 by *Branch Importer*.

377 User Experiences with the System

378 After models were uploaded to the server, users can see that their 379 plates are added in the selectable branch plates with their names 380 and locations. Users can access to the start page by PC and mobile 381 devices. We prepare both options and let participants choose a 382 device.

383 A user is firstly directed to a start page and asked to submit a user 384 name. Secondly, the user is navigated to target frame selection 385 page, and asked to pick one out of eight frames. Each frame has different 386 target points. The interface also shows the completed branch 387 organizations within each target frame. If there are multiple designs, 388 three designs with highest scores are displayed. The user 389 can change the currently displayed design by clicking within each 390 frame and choose either starting their design from scratch, or select 391 the design and improve it.

²Heroku is a platform as a service (PaaS) that enables developers to build, run, and operate applications entirely in the cloud. <https://www.heroku.com/>

³MongoDB is a free and open-source cross-platform document-oriented database program. <https://www.mongodb.com/>

404 4.2 Results

405 The entire workshop took 4.6 hours to complete the whole process, 406 including introduction, moving, and pauses. Table 4.2 shows durations 407 of each task.

Task	Duration (hour)	Fraction (%)
Introduction	0.3	6.5
Collecting branches	0.6	13.0
Preparing plates	0.8	17.4
Preparing models	0.3	6.5
Uploading models	0.2	4.3
Designing by the game	0.5	10.8
Inspecting models	0.2	4.3
CNC milling	0.5	10.8
Assembling	0.2	4.3
Miscellaneous	1.0	21.7
In total	4.6	100

409 Collecting Branches

410 The diameter and length constraints for available branches worked 411 as guidelines for participants rather than restricting finding and cutting 412 arbitrary branches. After cutting branches in certain lengths, 413 participants fixed branches on plates by thin metal plates with screw 414 holes. It was straightforward for them to firmly fix branches so that 415 they are not moved during milling process. These fixture points are 416 counted as invalid points in the game where joinery points can not 417 be generated. The participants built two plates with three and five 418 branches fixed on each plate.

419 Model Acquisition

iSense 3D scanners come with an intuitive software for scanning and modifying models. After we gave an instruction, most of participants practiced several scans and successfully scanned models without any problem.

420 Each scanning and re-touching took 2-3 minutes, and 30 seconds 421 for generating data by *Branch Importer*. Including the prepared 422 panels previously, we scanned 15 plates in total, 75 branches, and 423 35.3m of total length including sub-branches. **TODO: check the 424 length again!** We got 40 I shaped branches, 19 V shaped branches, 425 and 16 Y shaped branches. The result is shown in Figure 12.

430 Design with the Game

431 Most participants used iPads for navigating pages and playing the 432 game. All the participants understood the goal immediately, how- 433 ever, they had difficulties with mobile touch interface, such as rota- 434 tion and flipping operation by gestures.

435 One participant switched to play by a PC for more precise control 436 due to the problem. All the participants chose to develop their own

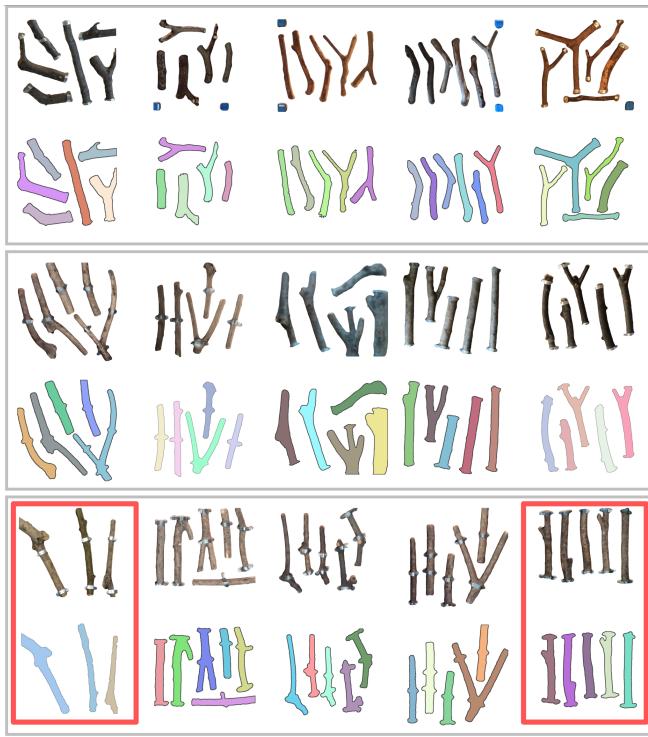


Figure 12: An overview of all the 15 scanned plates for the workshop. Top raw of each set shows ortho-top views of scanned mesh models, and the bottom raw is the recognized branches assigned random colors. The red-lined rectangles indicate the plates built by participants in the workshop.

463 **TODO: check offsetted correct english** After milling was finished
 464 and when branches were assembled, six pairs of branches were
 465 loosely connected because the calculated contours were 2-3mm
 466 eroded than the actual sizes. We avoided this problem by trimming
 467 branches from 2-5 mm higher than the plate surface. After this
 468 operation, the rest of connections were tightly connected.
 469

470 We also observed that many milling paths were 5-10 mm off from
 471 the center of planned joints. Multiple reasons could be considered
 472 as reasons such as,

- 473 • deformation of mechanical parts of the CNC router
- 474 • not dense resolution of acquired contours of branches
- 475 • misaligned orientation of the plate compared to the scanned
 476 model

477 To avoid the misalignments, we modified the *G-Code Generator*
 478 so that an operator can freely adjust the absolute origin of the gen-
 479 erated milling paths. The origin was usually set with around the
 480 center of the plate. After this modification, the misalignment from
 481 joint center was reduced with 5 mm off at the maximum misalign-
 482 ment. Branches could absorb 3-5 mm misaligned joint positions
 483 due to the elasticity of the wooden materials. The misaligned joint
 484 positions worked as post-tensions, solidifying the structure. We as-
 485 sume that this is only applicable when an applied bending moment
 486 and cut surface at a joint is orthogonal or not too much off from
 487 orthogonal. **TODO: this sentence**

488 4.3 Summary

489 The objective of the workshop was to observe the validity of our
 490 system for non-expert users. We could see that participants aged
 491 10 and under were capable of following the workflow. Participants
 492 were encouraged to contribute to the ongoing design with the online
 493 platform, and successfully provided designs from available branch
 494 plates.

495 We had several requests from participants regarding the game in-
 496 terface but also related to the workshop organization. Several par-
 497 ticipants requested to allow multiple branch plates for designing a
 498 frame, or even remove the target frame and let them freely design
 499 with branches. Also a participant who gave up with iPad operations
 500 requested additional buttons for mobile touch interface to keep an
 501 active branch selected.

502 A noteworthy fact was that one participant with four years old failed
 503 to complete the game, but insisted on accepting his design to be fab-
 504 ricated by the CNC router. We took these requests as their commit-
 505 ment to the entire workflow, as we observed that all the participants
 506 insisted on continuing the fabrication process.

507 5 Conclusion

508 Summary

509 In this paper, we presented a workflow to design and fabricate with
 510 branches which are not large enough for producing standardized
 511 building components. Our workflow was validated with case-study
 512 with lower-aged participants without design and fabrication expe-
 513riences. Our online platform to store geometries of scanned branches
 514 and compositions of branches was reachable by people with var-
 515 ious backgrounds. Our light-weight branch joint detection algorithm
 516 was also validated by running on the browser game, contributed to
 517 the accessibility of the presented workflow. Together with the ac-
 518 cessibility, the intuitive interface was simple enough for non-expert
 519 users. We successfully built a network of branches with rigid joints

437 designs from the scratch, although they had instruction about the
 438 "continue existing designs".

439 Although there is no time limit in the game system, we set 30 min-
 440 utes for playing the game, and 8 solutions were given by partici-
 441 pants. xxx frames were completed per participants and xxx partici-
 442 pants completed the whole eight target frames. The average score is
 443 xxx, and average playing duration was xxx to complete each target
 444 frame.

445 Overall Design Consensus **TODO: this section might be re-** 446 **removed**

447 As the target frame selection page can display designs not only
 448 from one user but also from all the others at once, we could get
 449 an overview of design options. The designs are displayed as score
 450 descending order but limited numbers, we could find feasible solu-
 451 tions with mostly all the target points were bridged. As participants
 452 were excited by seeing their branches and designs, we took some
 453 of their solutions and their plates for the fabrication although their
 454 solutions did not satisfied completion of the game.

455 Fabrication

456 We did not have major problems for converting designs to G-Code
 457 milling paths as we encountered major issues regarding the fabrica-
 458 tion before the workshop, which are reported in this section.

459 The main problem was the accuracy of acquired contours. We
 460 observed most of scanned models had occluded regions between
 461 plates and branches, which create interpolated faces during
 462 solidifying process, resulting in outwardly offsetted contours.

generated by our joinery milling path generator. Each of joints has customized lapped-joint geometry, which is challenging to design and fabricate.

Limitations and Future Work

Our system is limited to handle 3D shaped branches as 2D with height information only used for segmentation and G-Code generation. Our workflow requires branches to be fixed on a plate, which takes the longest duration in the workflow except for moving and pause in between tasks. Despite of successfully fabricated non-orthogonal joineries, we did not complete the attaching branches to target frames, as we prioritized to validate branch-branch joineries.

Our design workflow fully relies on human's ability for obtaining design solutions. As the problem of limited number of branches and fixed target points to be connected, the system could assist humans to reach to structurally sounding solutions with less efforts. Collected data from game could be further analyzed for extracting meaningful data for the development of assisting algorithm. Our joint and group detection, and milling path algorithms are not applicable to other purposes at this moment. It is valuable to compare the performance of our joint and group detection system to other collision detection library. In our workflow, the pipeline is not seamlessly connected: experienced operators need to take care of retouching mesh model, Branch Importer, and G-Code generator, and operating a CNC router.

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