

Participatory Layout Design-Fabrication with Native Forms of Natural Materials



Figure 1: Left: an overview of the workflow: 1.fix branches on plates. 2.scan the plates and upload the model. 3.play the game with scanned branches. 4. fabricate joineries by a CNC router. Right top: branch layouts partially designed by participants in a workshop. Right bottom: the fabricated 2D screen fence (2m x 0.9m).

Abstract

Diverse natural materials such as stones and woods have been used as architectural elements, preserving their native forms since primitive shelters, however, the use of them in modern buildings is limited due to their irregular properties. In this paper, we take the diversity as playful inputs for design task, and present our game-based design-fabrication platform for customized architectural elements. Taking tree branches as a material with native forms, our online game *BranchConnect* enables users to design 2D networks of branches and fabricate it by a CNC router. The game considers fabrication constraints such as limitations with ordinal 3-axis CNC routers. Each connection has a customized unique joinery adapted to native forms of branches. The scoring system of the game guides users to design structurally sound solutions with given branches. Together with low-cost mobile scanning devices, users with diverse contexts can contribute to design and fabrication process not only as a game user, but also from collecting branches around their physical environments and uploading them to our online platform. For validating our process, we conducted a workshop with end-users (children and their parents). They collected branches in a nearby forest and contributed to design/fabricate a 2D fence with our system.

Keywords: radiosity, global illumination, constant time

Concepts: •Computing methodologies → Image manipulation; Computational photography;

Permission to make digital or hard copies of part or all of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for third-party components of this work must be honored. For all other uses, contact the owner/author(s). © 2016 Copyright held by the owner/author(s).

SIGGRAPH 2016 Posters, July 24-28, 2016, Anaheim, CA

ISBN: 978-1-4503-ABCD-E/16/07

DOI: <http://doi.acm.org/10.1145/9999997.9999999>

1 Introduction

Modern buildings are characterized by its uniformity; built upon the same principle of construction system, consisting of standardized building component and its assembly process. The standardized construction system is favored because of its efficiency in design and production. Each component satisfies specified structural performance, thus an assembled structure can be analyzed systematically. On the other hand, excessive standardization converged buildings into similar materials and details, resulting in the detached design from built environment. Reacting on the issue, designers and architects actively use local materials not only as inspirational sources, but also as a catalyst of their design to the local context [Oliver 1997].

Since primitive shelters and huts, traditional construction has used locally found natural materials directly as they are found. Such a direct use can not compete with highly standardized materials and construction system, however, the uniqueness of native forms is a valuable quality which is lacking in standardized materials. As the material is locally obtained, building and living get much closer, thus people using a facility can easily commit design and fabrication, fostering the sense of belonging to the community []. **TODO: citation** Locally obtained materials can easily connect design and the context of built environment in this way, but their irregular properties limit the use of them in modern buildings. Traditionally, craftsman has taken care irregular natural materials varying their native forms and dynamically design the global design by considering individual material properties [Pye 1968]. Such a task is difficult to be automated and these skills are developed through years of training, thus the use of native forms typically costs more than standardized construction system.

This paper aims to make the above-mentioned qualities of materials with native forms more accessible by digital technologies. We use locally obtained branch as a material with native forms, which can be found almost everywhere not only in country-side but also in urban environment such as parks and along streets. Public service

takes care of these branches: annual pruning, storing, and chipping or burning with some costs. The size of branches (from 5 -30 cm in diameter) is too small for furniture or other structural applications. It is a challenge for digital design and fabrication to utilize the diverse branches in meaningful ways. High-precision but low-cost scanning devices and personal digital fabrication machines make it possible to analyze and control natural materials with diverse native forms.

The key technical difficulty with materials with natives forms is design. Optimization is a straightforward approach: minimize an energy function which integrates structural and fabrication costs. This approach, however, is limited to particular design scenario with specific materials. Furthermore, the concept of optimum solution is well suited to goals such as efficiency or low-cost, but these goals are not the qualities materials with natives forms can compete with standardized construction systems. Instead, we take humans in our scan-design-fabricate workflow not only to solve the design problem, but also to provide an opportunity for people to participate in the workflow. Traditionally, in case of constructing public and symbolic buildings, such as church, people in a community took initiatives from fund raising to design, or even in construction process [].

TODO: citation

In this paper, we report our case study to design and fabricate an architectural element out of irregularly shaped branches, using our humans-in-the-loop system. We developed an online platform where users can post branches found at hand, and design with them through the game *BranchConnect*. The game system itself helps users to design valid branch layouts and enable them to fabricate customized joineries to connect them together without screws and adhesives. The design of our joinery extends the traditional orthogonal lap-joints to various angles within a range, freeing the diverse forms of woods from orthogonal connections. Physically collected branches are digitally scanned and stored in a cloud database *BranchCollect*, and offline application *Branch Importer* analyzes forms of branches and upload to the database. The simple visual feedback and scoring system of the game guide users to valid solutions, which are further inspected by an offline application *G-Code Generator* for CNC milling process. The game system and developed import/export applications are currently limited to branches, however, the principle of human-in-the-loop for design is applicable for other kinds of materials with diverse irregular forms. We hope our method sheds lights on materials such as waste from demolition of buildings for various design applications.

Our contributions are summarized as follows.

- a workflow enabling to take natural materials with native forms as design components stored in cloud database.
- a participatory design-fabrication method with an online game-based platform.
- an algorithm to generate customized non-orthogonal joineries able to be fabricated by ordinal CNC routers.

2 Related Work

3D printers and CNC routers made digital fabrication more accessible, and pre-fabricated customized parts are often used in buildings nowadays [Knaack et al. 2012]. According to the theory by Pye [1968], these parts are processed from highly standardized material, thus its digital fabrication process is “workmanship with certainty”; a batch process of reading G-Code and strict execution of the code. On the other hand, as “workmanship with risks” with digital technologies, interactive fabrication enables machines to pick up uncertain happenings and react on it [Willis et al. 2011]. Mueller and

her colleagues developed interactive laser cutting, taking user inputs and recognizing placed objects in a fabrication scene [Mueller et al. 2012]. While their system interprets objects as simple platonic geometry, our work takes the native forms of branches. Crowd-sourced Fabrication project took advantage of humans-in-the-loop in their fabrication system [Lafreniere et al. 2016]. On the other hand, our work puts emphasis on crowd-sourced design as a socially networked fabrication. As a crowdsourced design system, Jerry et. al., developed a platform for light users to design trees and plants [Talton et al. 2009]. Our work also developed online collaborative design platform but directly linked to the real-world.

There are few works that take natural materials with native forms as design components. Schindler and his colleagues used digitally scanned wood branches and used them for furniture and interior design elements [Schindler et al. 2014]. Monier and colleagues virtually generated irregularly shaped branch-like components and explored designs of large scale structure [Monier et al. 2013]. Using larger shaped forked tree trunks, *Wood Barn* project designed and fabricated custom joineries to construct a truss-like structure[Mairs 2016]. *Smart Scrap* project digitally measured lime stone leftover slates from a quarry and digitally generated assembly pattern of slates [Greenberg et al. 2010].

In industry, recognition of irregularly shaped objects is essential for waste management. *ZenRobotics* developed a system that sorts construction and demolition waste by picking objects on a conveyor belt using robotic hands [Lukka et al. 2014]. For factory automation purpose, there is a system that recognizes irregularly shaped objects and sort them into a container [Sujan et al. 2000]. Getting out from factories, autonomous robotics in construction site is a hot topic among roboticists [Feng et al. 2014]. *In-situ Fabricator* is a system which could be installed in construction site and co-operated with human workers [Dörfler et al. 2016]. Once robot is autonomously localize itself in such an environment, it can build foundational structure for further construction [Napp and Nagpal 2014]. Using locally found objects on-site, such a system can be much simpler.

While these projects demonstrated the capability of digital fabrication processes to handle irregularly shaped materials, design process is still dependent on a designer or architect who has experiences with materials or has access to special software.

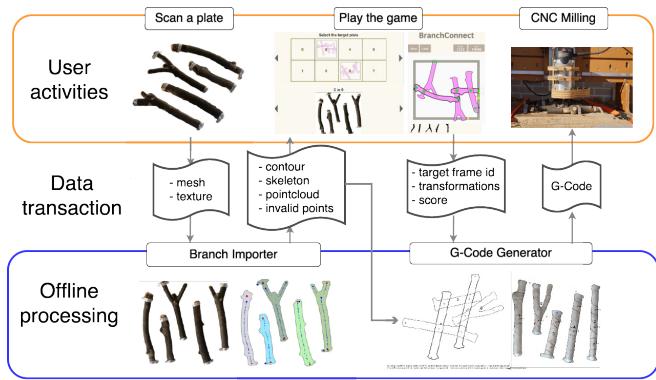
Cimerman discussed architectural design practices that took computer-mediated participatory design [Cimerman 2000]. He mentioned three motivations of digital participatory design:

- Including stakeholders in creation of one's environment.
- Experimenting diverse design tastes from multiple point of views.
- Solving complex design tasks with full of diverse solutions.

Opening database of available local materials, people with various backgrounds can involve in design process, which could lower the cost of design fee with natural materials with native forms. For example, *Nano-Doc* took gamification approach to search valid nanoparticle designs against tumors out of infinite design space [Hauert et al.]. *DrawAFriend* has developed an online game to collect big-data for drawing applications which assist humans with auto-stroke assistance [Limpaecher et al. 2013]. While these works developed games for collecting valuable data for solving medical or engineering problems, our game is served as a collaborative design platform, aiming to solve the socio-cultural issues in modern buildings: 1.generic design and 2.detached context.

183 3 Workflow

184 As illustrated in the left of Figure 1, our workflow starts from physically collecting branches. The collected branches are uploaded to cloud database by *Branch Importer*, and served to online game-based design application *BranchConnect*. The game is working on browsers and accessible from laptop computers and mobile devices. 185 186 187 188 189 190 191 192 193 194 195 196 As in the right of 1, users can explore a global design with multiple branch layouts. Once the global design is fixed, designed layouts are further inspected by *G-Code Generator*, which generates customized joineries for CNC milling. After finishing the milling process, users physically assemble branches and complete the fabrication process. The pipeline of the workflow is illustrated in the Figure 2. In this section, we describe three steps in the pipeline: Digital Model Acquisition, the Game System, and Fabrication.



225 226 227 228 229 230 231 **Figure 2:** A pipeline from model acquisition to fabrication.

197 3.1 Digital Model Acquisition

198 Our system takes textured mesh model or point cloud with colored 199 vertices. As complete mesh model provides more robust result with 200 3D shapes of branches, we describe our process based on mesh 201 model as an input.

202 There are various methods and software available for scanning 3D 203 models. As for hardware setup, we describe in the Section 4. Taking 204 mesh model with colored texture, our *Branch Importer*, integrates 205 necessary functions such as object detection, skeleton extraction, 206 branch type classification, and fixture location detection.

207 After segmenting branches from a plate by height threshold, each 208 branch is detected using *findContour* in OpenCV¹. The obtained 209 2D contours are used for extracting skeletons and clustering point 210 cloud in the mesh model. Contours are triangulated and skeleton 211 points are extracted from middle points on edges of triangles. These 212 middle points are compared with binary top view image of the mesh 213 model (contours are filled with different colors and the background 214 is white). If the point is inside of a contour, the middle point is 215 counted in skeleton points. Metal fixture locations are also filtered 216 out due as they have bright reflections on original images, however, 217 we also double check with simple mouse-clicks to ensure these 218 invalid points. After extracting valid middle points, connectivity of 219 skeletons is analyzed by angle of three adjacent skeleton points. If 220 the angle stays within a threshold bound, a point is counted in a sub- 221 branch, otherwise, new sub-branch is created. Evaluating the num- 222 ber of sub-branches, the branch is morphologically classified. Most 223 branches are categorized in three shapes: *I*, *V*, and *Y* shapes. *I* 224 shape has a straight continuous polyline, *V* has an inflection point, 225 and *Y* has a splitting point. The acquired information is stored in a 226 cloud database.

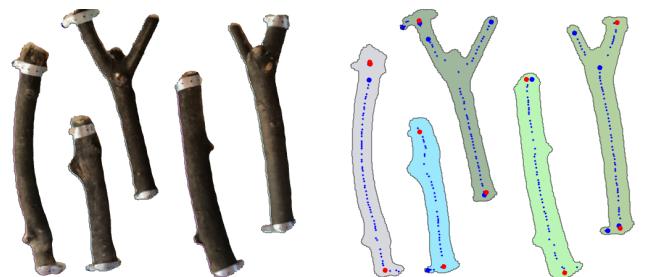


Figure 3: An overview of *Branch Importer*. Left: a top ortho-view image of textured mesh model. Right: Extracted skeletons (blue dots). The beginning of skeletons is shown bigger dots. Red dots are invalid points.

3.2 BranchConnect: The Game

The game objective is to collect valid compositions of branches which structurally sounding and possible to fabricate with ordinal 3 axis CNC milling machines. The workflow of the game is illustrated in Figure 4

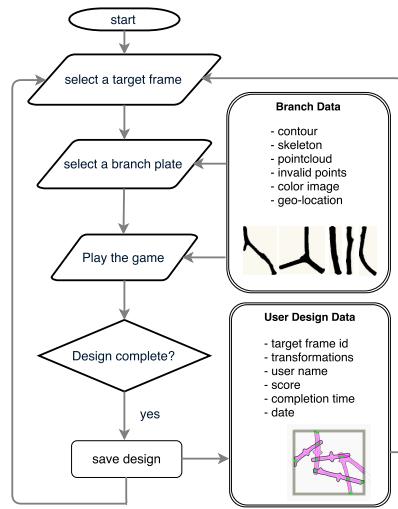


Figure 4: The workflow of *BranchConnect*. Branch data and user design data are stored on cloud database.

232 Firstly a user selects a frame indicating multiple target points to be 233 connected, and then selects a set of branches fixed on a plate (The 234 left in Figure 5). After selecting the target frame and the set of 235 branches, the user is guided to the game interface, consisting of the 236 frame with the target points, and the set of available branches (The 237 right in Figure 5). The user picks a branch from the available set 238 on the bottom, and then places it in an arbitrary 2D pose through 239 basic manipulations such as move, rotate, and mirror. The number 240 of available branches differs depending on plates. With the feasible 241 diameter of branches (over 2cm) and the plate size (50cm x 50cm), 242 the number of available branches is most likely up to six. Within 243 the limited number of branches, the user bridges all the target points 244 by connecting all the used branches in one group. The game is 245 completed when all the target points are connected by branches. For 246 higher score, the user can modify the design after the completion.

¹Open Source Computer Vision Library. See <http://opencv.org/>

247 After completing the modification, the design is submitted and sent
 248 to *G-Code Generator*.

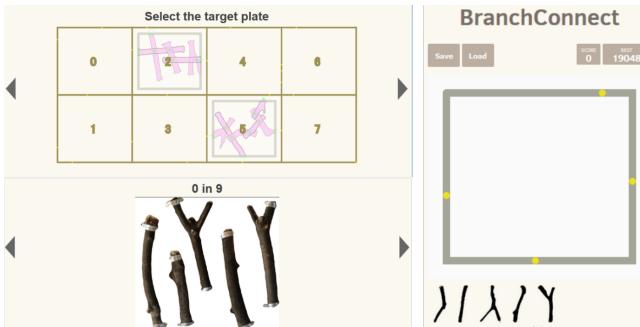


Figure 5: Left: the selection interface for target frames (top) and branch panels (bottom). Right: the start interface of the game.

Joint Condition

272 Joint is the essential entity not only in the game but also the entire
 273 project including the fabrication process. The closest skeleton point
 274 pair is obtained We accept crossing joints only because they are
 275 structurally stable, relatively simple to fabricate, and creates diverse
 276 designs. To ensure the structural performance, we set a connection
 277 angle within a range from 45 to 135 degrees. Joints close to metal
 278 fixtures are also counted as invalid. Valid and invalid joints are
 279 displayed with green and red respectively. The color-code feedback
 280 is also given when target points on a frame is connected with a
 281 branch. Figure 7 illustrates valid and invalid joint conditions.

282 To describe the process, we let \mathcal{B} denotes a set of all the available
 283 branches, and each branch as $b_i \in \mathcal{B}$. While the process checks
 284 joint condition through all the branches \mathcal{B} , each detected joint is
 285 stored in each branch b_i , categorized in different conditions such
 286 as valid and invalid joints denoted as $\mathcal{J}_{\text{valid},i}$, $\mathcal{J}_{\text{invalid},i}$ respectively,
 287 together with the paired branch id $b_{\text{paired},j,i}$. When a branch is con-
 288 nected to one of target point $t_j \in \mathcal{T}$, the t_j is stored in p_i as $t_{j,i}$.
 289 **TODO:** notaion should be improved!

System Overview

250 There are many collision detection libraries available, however, our
 251 game needs to detect intersected branch pairs, thus surface contact
 252 detection is overkill for our application. Also most branches come
 253 with free-form concave shapes, thus further geometric preparation
 254 such as convex decomposition is necessary for using these libraries.
 255 For fast and robust intersection detection, our system extensively
 256 uses skeletons of branches. Hubbard and Philip developed colli-
 257 sion detection by representing object with hierarchical 3D spheres
 258 aligned on skeletons [Hubbard 1996]. Our system takes similar ap-
 259 proach but more limited in 2D and intersection detection only. In
 260 broader phase, simplified skeletons are used to find the pair of clos-
 261 est skeleton points between two branches. After finding the pair,
 262 skeletons with higher resolutions are used.

263 A joint is created when an intersecting pair is detected, and the
 264 pair forms a group. The group is used for evaluating connections
 265 between target points. The game is completed once all the target
 266 points are connected by a group of branches. The conditions of
 267 joint and group are indicated with simple color-code. Once the user
 268 finishes positioning, score is updated with weighted sum of param-
 269 eters. Together with the color-code, the score update guides the user
 270 to form a valid design. An overview is illustrated in Figure 6.

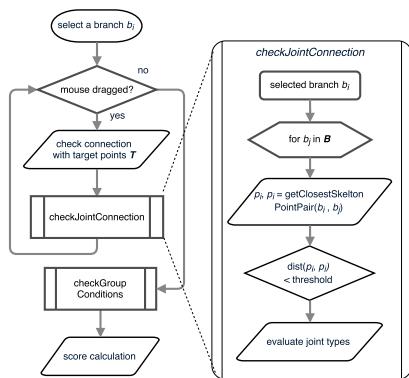


Figure 6: Left: an overview of the game system. Right: joint condi-
 tion checking process.

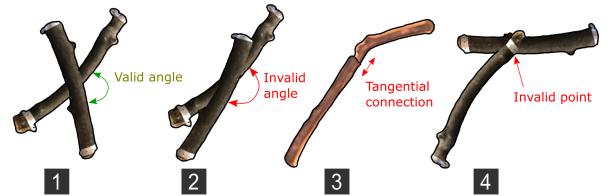


Figure 7: Joint conditions. 1.valid joint. 2.invalid for violating the
 angle. 3.invalid tangential connection. 4.invalid for connecting on
 a fixture point.

Group Condition

291 After checking joint conditions of all the pairs of branches, the sys-
 292 tem checks the number of groups as well as connectivity with the
 293 target points on a frame. If a group is not connected to any target
 294 point nor other groups, the group is islanded and structurally in-
 295 valid. While a user is positioning a branch by dragging or rotating,
 296 groups are continuously calculated and indicated by simple color
 297 (Figure 8).

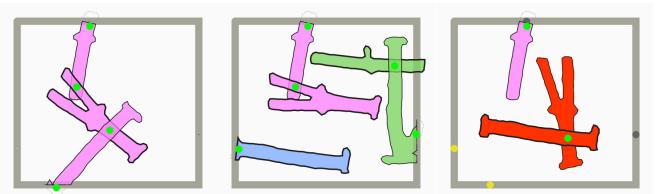


Figure 8: Left: valid group with two target points connected. Mid-
 298 dle: valid but three groups. Right: invalid due to the island situ-
 299 ation.

300 After all the joint conditions are checked, we evaluate group con-
 301 ditions. Through checking the all the branches \mathcal{B} , the first group
 302 g_0 is created and stores b_0 . The other paired branch $b_{\text{paired},i}$ is used
 303 to trace the connection with other compared to the traced through
 304 the stored paired branch in each valid joint j_i . in all groups \mathcal{G} . The
 game is completed when the number of \mathcal{G} is one, and all the target
 points are connected with the group.

Algorithm 1 Group Condition Update Algorithm

```

1: function UPDATEGROUPS( $\mathcal{B}$ )
2:   Reset all the groups  $\mathcal{G}$ 
3:   Create new group  $g_1$ 
4:    $g_1$  add  $b_1$ 
5:   if  $b_1$  has connected target point  $t_1$  then
6:      $g_1$  set  $t_1$ 
7:    $\mathcal{G}$  add  $g_1$ 
8:   for each branch  $b_i$  in  $\mathcal{B}$  do
9:      $GroupConnection \leftarrow false$ 
10:    for each group  $g_j$  in  $\mathcal{G}$  do
11:      for each branch  $b_j$  in  $g_j$  do
12:        if  $b_{\text{paired},i} \in \mathcal{P}_j$  has  $b_j$  then
13:           $g_j$  add  $b_i$ 
14:           $GroupConnection \leftarrow true$ 
15:          if ( $b_i$  has  $t_i$ ) and ( $g_j$  has  $t_j$ ) then
16:            Set  $g_j$  as Bridged
17:            if  $g_j$  has no  $t_j$  then
18:              Set  $g_j$  as Islanded
19:              break
20:          if  $GroupConnection$  is false then
21:            create new group  $g_{new}$ 
22:             $g_{new}$  add  $b_i$ 
23:             $\mathcal{G}$  add  $g_{new}$ 

```

Score Calculation

We denote the numbers of valid and invalid joints on each branch $b_i \in \mathcal{B}$ as $N(\text{valid}_i)$, $N(\text{invalid}_i)$ respectively, the number of groups as $N(\mathcal{G})$, the number of islanded groups as $N(g_{\text{islanded}} \in \mathcal{G})$, the number of bridged target points as $N(t_{\text{bridged},i}) \in \mathcal{T}$. The score is weighted sum of these joint and group conditions (see Eq 1).

TODO: notaion should be improved!

$$\begin{aligned}
Score = & w_1 \sum_{i=1}^{N(\mathcal{B})} N(\text{valid}_i) + w_2 \sum_{i=1}^{N(\mathcal{B})} N(\text{invalid}_i) \\
& + w_3 \sum_{j=1}^{N(\mathcal{G})} g_{\text{islanded}} + w_4 \sum_{j=1}^{N(\mathcal{T})} t_{\text{bridged}}
\end{aligned} \tag{1}$$

s.t. $w_j \geq 0 \forall j \in 1, \dots, 4$

3.3 Fabrication

After a design is selected for fabrication, the validity of the design is further inspected with a high-resolution model. The *G-Code Generator* was developed for fine-tuning the design by checking real-time feedback of updated joineries on branches with scanned orientations (see Figure 9).

Some fabrication factors such as mirror and invalid points are already considered by *Branch Importer* and the game system of *BranchConnect*. In this section, we describe the process of joinery generation. Each joinery geometry is different but has same topology: two plane surfaces on the sides of branches and one plane top surface. The geometry creates rigid connection with the irregularly shaped sections of branches. Similar to the joint searching process with skeletons, the *G-Code Generator* searches a set of four closest points from high-resolution contours, expecting that every intersected contour has four curves. After finding the four closest points, it trims two curves from each contour of branch. (two from intersecting branch and two from intersected branch) at each joint.

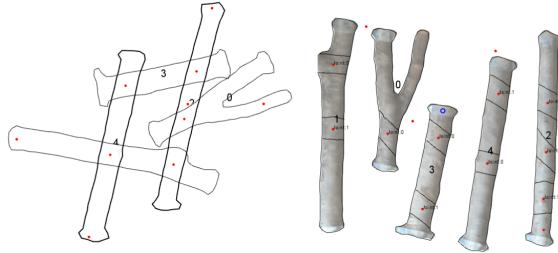


Figure 9: Interface of *G-Code Generator*. Users can tweak the design on the left side and immediately see the updated joints and milling paths on the right. **TODO:** can this image be integrated with the other one?

330 The trimmed contours are transformed to the original scanned orientation
331 and used for generating milling paths. Two curves from an intersected branch are used for side cuts milling paths, which
332 are inwardly offset paths of the original branch contours. **TODO:**
333 **need to brush up!** The center cuts are paths that are plaining the top
334 surface of the joint. **TODO:** describe the cutting height calculation!
335

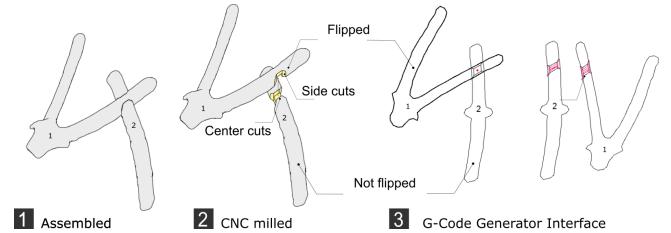


Figure 10: An example of intersected pair: 1. an assembled pair of branches. 2. branches after the center and side cuts are milled 3. left: a composition defined by a user right: the original orientations of branches with generated milling paths with red color.

336 Users can change fabrication parameters such as offset ratio for the
337 side cuts, milling bit diameter, overlapping ratio for defining the
338 center cut depth, feed-rate, moving height and so forth. After con-
339 firming the fabrication settings and milling paths, it generates G-
340 Code.

4 Case Study

342 A design and fabrication workshop was organized to examine the
343 validity of our system with a specific design target and a location.
344 We selected a public community house where people in the com-
345 munity share the space and regularly use the facility and participants
346 were selected among them. Participants are four children aged 10
347 and under (4, 7, 9, and 10 years old) and two parents (Figure 11).
348 We specifically selected children with the age range as non-experts
349 without experiences in computational design or digital fabrication,
350 also for observing the clarity and attractiveness of the game.

351 The goal for the participants is to contribute to an ongoing design
352 and fabrication process of screen wall (2m by 0.9m) consisting of
353 8 rectangles. Six frames were already designed and built, thus the
354 rest two frames were prioritized for them to design and fabricate in
355 this workshop.

356 Participants are asked to follow the entire process from collecting
357 and fixing the branches on a plate, scanning the plate, complete
358 designs by playing the game, and assembly after the CNC milling.

359 Participants were informed about the goal of the workshop, and
 360 each process was introduced by experienced tutors.



Figure 11: An overview of the workshop. 1.the overview of the space. 2.collect branches. 3.cut 4.attach on a plate 5.scan 6.play the game 7.CNC milling.

399 can change the currently displayed design by clicking within each
 400 frame and choose either starting their design from scratch, or select
 401 the design and improve it.

402 After selecting a target frame, the user goes to branch selection
 403 page, displaying 15 plates when the workshop was held. In this
 404 page, they see the plates made by themselves on the page, as well
 405 as their names on the plate. The user can select the same plate
 406 for designing other target frames. By clicking a displayed branch
 407 plate, the user is navigated to the game interface. After completing
 408 to bridge all the target points, the design is automatically uploaded
 409 to the database, but the user can continue to design. Tutors and par-
 410 ticipants select design solution for each target frame, and an ex-
 411 perienced tutor operates *G-Code Generator* as well as the CNC router.
 412 Participants were asked to assemble branches after joineries were
 413 milled.

361 4.1 Setup

362 System and Hardware Setup

363 We used two iPad minis with iSense scanners attached for scan-
 364 ning branches, and a 3 axis CNC milling router with a 6 mm di-
 365 ameter milling bit. We used a laptop PC (Lenovo w240 with intel
 366 core i7) for running *Branch Importer* and *G-Code generator*, as
 367 well as operating the milling machine. The scan area of iSense is
 368 500mm x 500mm, and the milling machine's stroke along z-axis
 369 is 70mm, which provide geometric constraints for available branch
 370 sizes. *BranchConnect* was hosted at *Heroku* cloud server ², and we
 371 used *MongoDB*³ as a cloud database.

372 Preparation of Branches

373 The participants were asked to collect branches with 2 - 10 cm in
 374 diameter. The lower bound of the diameter is for milling process
 375 would not destroy them, and the upper bound is for the limit
 376 of z-stroke of the CNC router. The collected branches are cut
 377 in arbitrary lengths, not longer than 500 mm due to the limit of
 378 scanning area.

379 As our game system and fabrication process take 3D branch shapes
 380 as 2D contours with height map, these constraints work positive for
 381 the system automatically filtering out branches with large 3D twists.
 382 We ask participants to scan with iPad + iSense and prepare feasible
 383 mesh model by themselves. After obtaining mesh models, tutors
 384 import models from iPads to a laptop and upload them to database
 385 by *Branch Importer*.

387 User Experiences with the System

388 After models were uploaded to the server, users can see that their
 389 plates are added in the selectable branch plates with their names
 390 and locations. Users can access to the start page by PC and mo-
 391 bile devices. We prepare both options and let participants choose a
 392 device.

393 A user is firstly directed to a start page and asked to submit a user
 394 name. Secondly, the user is navigated to target frame selection
 395 page, and asked to pick one out of eight frames. Each frame has dif-
 396 ferent target points. The interface also shows the completed branch
 397 organizations within each target frame. If there are multiple de-
 398 signs, three designs with highest scores are displayed. The user

414 4.2 Results

415 The entire workshop took 4.6 hours to complete the whole process,
 416 including introduction, moving, and pauses. Table 4.2 shows dura-
 417 tions of each task.

Task	Duration (hour)	Fraction (%)
Introduction	0.3	6.5
Collecting branches	0.6	13.0
Preparing plates	0.8	17.4
Preparing models	0.3	6.5
Uploading models	0.2	4.3
Designing by the game	0.5	10.8
Inspecting models	0.2	4.3
CNC milling	0.5	10.8
Assembling	0.2	4.3
Miscellaneous	1.0	21.7
In total	4.6	100

419 Collecting Branches

420 The diameter and length constraints for available branches worked
 421 as guidelines for participants rather than restricting finding and cut-
 422 ting arbitrary branches. After cutting branches in certain lengths,
 423 participants fixed branches on plates by thin metal plates with screw
 424 holes. It was straightforward for them to firmly fix branches so that
 425 they are not moved during milling process. These fixture points are
 426 counted as invalid points in the game where joinery points can not
 427 be generated. The participants built two plates with three and five
 428 branches fixed on each plate.

429 Model Acquisition

430 iSense 3D scanners come with an intuitive software for scanning
 431 and modifying models. After we gave an instruction, most of par-
 432 ticipants practiced several scans and successfully scanned models
 433 without any problem.

434 Each scanning and re-touching took 2-3 minutes, and 30 seconds
 435 for generating data by *Branch Importer*. Including the prepared
 436 panels previously, we scanned 15 plates in total, 75 branches, and
 437 35.3m of total length including sub-branches. **TODO: check the**
 438 **length again!** We got 40 I shaped branches, 19 V shaped branches,
 439 and 16 Y shaped branches. The result is shown in Figure 12.

440 Design with the Game

441 Most participants used iPads for navigating pages and playing the
 442 game. All the participants understood the goal immediately, how-

²Heroku is a platform as a service (PaaS) that enables developers to build, run, and operate applications entirely in the cloud. <https://www.heroku.com/>

³MongoDB is a free and open-source cross-platform document-oriented database program. <https://www.mongodb.com/>

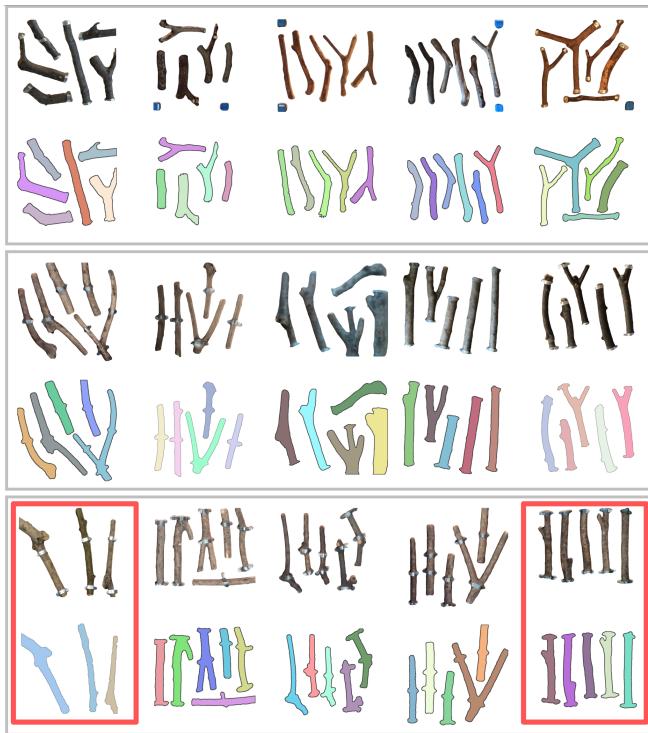


Figure 12: An overview of all the 15 scanned plates for the workshop. Top raw of each set shows ortho-top views of scanned mesh models, and the bottom raw is the recognized branches assigned random colors. The red-lined rectangles indicate the plates built by participants in the workshop.

469
470
471
472
473
474
475
476
477
478
479
480
481
482
483
484
485
486
487
488
489
490
491
492
493
494
495
496
497
The main problem was the accuracy of acquired contours. We observed most of scanned models had occluded regions between plates and branches, which create interpolated faces during solidifying process, resulting in outwardly offsetted contours. **TODO: check offsetted correct english** After milling was finished and when branches were assembled, six pairs of branches were loosely connected because the calculated contours were 2-3mm eroded than the actual sizes. We avoided this problem by trimming branches from 2-5 mm higher than the plate surface. After this operation, the rest of connections were tightly connected.

We also observed that many milling paths were 5-10 mm off from the center of planned joints. Multiple reasons could be considered as reasons such as,

- deformation of mechanical parts of the CNC router
- not dense resolution of acquired contours of branches
- misaligned orientation of the plate compared to the scanned model

To avoid the misalignments, we modified the *G-Code Generator* so that an operator can freely adjust the absolute origin of the generated milling paths. The origin was usually set with around the center of the plate. After this modification, the misalignment from joint center was reduced with 5 mm off at the maximum misalignment. Branches could absorb 3-5 mm misaligned joint positions due to the elasticity of the wooden materials. The misaligned joint positions worked as post-tensions, solidifying the structure. We assume that this is only applicable when an applied bending moment and cut surface at a joint is orthogonal or not too much off from orthogonal. **TODO: this sentence**

4.3 Summary

498
499
500
501
502
503
504
The objective of the workshop was to observe the validity of our system for non-expert users. We could see that participants aged 10 and under were capable of following the workflow. Participants were encouraged to contribute to the ongoing design with the online platform, and successfully provided designs from available branch plates.

505
506
507
508
509
510
511
We had several requests from participants regarding the game interface but also related to the workshop organization. Several participants requested to allow multiple branch plates for designing a frame, or even remove the target frame and let them freely design with branches. Also a participant who gave up with iPad operations requested additional buttons for mobile touch interface to keep an active branch selected.

512
513
514
515
516
A noteworthy fact was that one participant with four years old failed to complete the game, but insisted on accepting his design to be fabricated by the CNC router. We took these requests as their commitment to the entire workflow, as we observed that all the participants insisted on continuing the fabrication process.

5 Conclusion

Summary

519
520
521
522
523
524
525
In this paper, we presented a workflow to design and fabricate with branches which are not large enough for producing standardized building components. Our workflow was validated with case-study with lower-aged participants without design and fabrication experiences. Our online platform to store geometries of scanned branches and compositions of branches was reachable by people with various backgrounds. Our light-weight branch joint detection algorithm

443 ever, they had difficulties with mobile touch interface, such as rotation and flipping operation by gestures.

445 One participant switched to play by a PC for more precise control
446 due to the problem. All the participants chose to develop their own
447 designs from the scratch, although they had instruction about the
448 "continue existing designs".

449 Although there is no time limit in the game system, we set 30 minutes
450 for playing the game, and 8 solutions were given by participants.
451 xxx frames were completed per participants and xxx participants
452 completed the whole eight target frames. The average score is
453 xxx, and average playing duration was xxx to complete each target
454 frame.

Overall Design Consensus **TODO: this section might be removed**

457 As the target frame selection page can display designs not only
458 from one user but also from all the others at once, we could get
459 an overview of design options. The designs are displayed as score
460 descending order but limited numbers, we could find feasible solu-
461 tions with mostly all the target points were bridged. As participants
462 were excited by seeing their branches and designs, we took some
463 of their solutions and their plates for the fabrication although their
464 solutions did not satisfied completion of the game.

Fabrication

466 We did not have major problems for converting designs to G-Code
467 milling paths as we encountered major issues regarding the fabrica-
468 tion before the workshop, which are reported in this section.

526 was also validated by running on the browser game, contributed to
 527 the accessibility of the presented workflow. Together with the ac-
 528 cessibility, the intuitive interface was simple enough for non-expert
 529 users. We successfully built a network of branches with rigid joints
 530 generated by our joinery milling path generator. Each of joints has
 531 customized lapped-joint geometry, which is challenging to design
 532 and fabricate.

533 Limitations and Future Work

534 Our system is limited to handle 3D shaped branches as 2D with
 535 height information only used for segmentation and G-Code genera-
 536 tion. Our workflow requires branches to be fixed on a plate, which
 537 takes the longest duration in the workflow except for moving and
 538 pause in between tasks. Despite of successfully fabricated non-
 539 orthogonal joineries, we did not complete the attaching branches to
 540 target frames, as we prioritized to validate branch-branch joineries.

541 Our design workflow fully relies on human's ability for obtaining
 542 design solutions. As the problem of limited number of branches
 543 and fixed target points to be connected, the system could assist hu-
 544 mans to reach to structurally sounding solutions with less efforts.
 545 Collected data from game could be further analyzed for extracting
 546 meaningful data for the development of assisting algorithm. Our
 547 joint and group detection, and milling path algorithms are not ap-
 548 plicable to other purposes at this moment. It is valuable to com-
 549 pare the performance of our joint and group detection system to
 550 other collision detection library. In our workflow, the pipeline is
 551 not seamlessly connected: experienced operators need to take care
 552 of retouching mesh model, Branch Importer, and G-Code generator,
 553 and operating a CNC router.

554 Acknowledgements

555 We appreciate the public house for hosting the CNC router and pro-
 556 viding participants for the user study. We thank to the film editor,
 557 Shin Yamane for shooting our video clips. We also thank to the
 558 developer of an online game 2048, Gabriele Cirulli and his contrib-
 559 utors, for sharing source code in Github community.

560 References

- 561 BOGUE, R. 2013. 3d printing: the dawn of a new era in manufac-
 562 turing? *Assembly Automation* 33, 4, 307–311.
- 563 CIMERMAN, B. 2000. Participatory design in architecture: can
 564 computers help? In *PDC*, 40–48.
- 565 DÖRFLER, K., SANDY, T., GIFTTHALER, M., GRAMAZIO, F.,
 566 KOHLER, M., AND BUCHLI, J. 2016. Mobile robotic brick-
 567 work. In *Robotic Fabrication in Architecture, Art and Design*
 568 2016. Springer, 204–217.
- 569 FENG, C., XIAO, Y., WILLETT, A., MCGEE, W., AND KA-
 570 MAT, V. 2014. Towards autonomous robotic in-situ assembly
 571 on unstructured construction sites using monocular vision. In
 572 *Proceedings of the 31th International Symposium on Automation*
 573 *and Robotics in Construction*, 163–170.
- 574 GREENBERG, B., HITTNER, G., AND PERRY, K., 2010. Smart
 575 scrap. Accessed: 2016-09-30.
- 576 HAUERT, S., LO, J. H., NACHUM, O., WARREN, A. D., AND
 577 BHATIA, S. N. Crowdsourcing swarm control of nanobots for
 578 cancer applications.
- 579 HUBBARD, P. M. 1996. Approximating polyhedra with spheres
 580 for time-critical collision detection. *ACM Trans. Graph.* 15, 3
 581 (July), 179–210.
- 582 KHOSHNEVIS, B. 2004. Automated construction by contour craft-
 583 ingrelated robotics and information technologies. *Automation in*
 584 *construction* 13, 1, 5–19.
- 585 KNAACK, U., CHUNG-KLATTE, S., AND HASSELBACH, R. 2012.
 586 *Prefabricated systems: Principles of construction*. Walter de
 587 Gruyter.
- 588 LAFRENIERE, B., GROSSMAN, T., ANDERSON, F., MATEJKA,
 589 J., KERRICK, H., NAGY, D., VASEY, L., ATHERTON, E.,
 590 BEIRNE, N., COELHO, M. H., ET AL. 2016. Crowdsourced
 591 fabrication. In *Proceedings of the 29th Annual Symposium on*
 592 *User Interface Software and Technology*, ACM, 15–28.
- 593 LENNON, M. 2005. Recycling construction and demolition wastes.
- 594 LIMPAECHER, A., FELTMAN, N., TREUILLE, A., AND COHEN,
 595 M. 2013. Real-time drawing assistance through crowdsourcing.
 596 *ACM Transactions on Graphics (TOG)* 32, 4, 54.
- 597 LUKKA, T. J., TOSSAVAINEN, T., KUJALA, J. V., AND RAIKO, T.
 598 2014. Zenrobotics recycler–robotic sorting using machine learn-
 599 ing. In *Proceedings of the International Conference on Sensor-
 600 Based Sorting (SBS)*.
- 601 MAIRS, J., 2016. Aa design and make students use a robotic arm
 602 to build a woodland barn. Accessed: 2016-09-30.
- 603 MONIER, V., BIGNON, J. C., AND DUCHANOIS, G. 2013. Use of
 604 irregular wood components to design non-standard structures. In
 605 *Advanced Materials Research*, vol. 671, Trans Tech Publ, 2337–
 606 2343.
- 607 MUELLER, S., LOPES, P., AND BAUDISCH, P. 2012. Interac-
 608 tive construction: interactive fabrication of functional mechani-
 609 cal devices. In *Proceedings of the 25th annual ACM symposium*
 610 *on User interface software and technology*, ACM, New York,
 611 NY, USA, UIST '12, 599–606.
- 612 NAPP, N., AND NAGPAL, R. 2014. Distributed amorphous ramp
 613 construction in unstructured environments. *Robotica* 32, 02,
 614 279–290.
- 615 NIELSEN, S. A., AND DANCU, A. 2015. Fusing design and con-
 616 struction as speculative articulations for the built environment.
- 617 OLIVER, P. 1997. *Encyclopedia of vernacular architecture of the*
 618 *world*. Cambridge University Press.
- 619 PYE, D. 1968. *The nature and art of workmanship*. Cambridge
 620 UP.
- 621 SCHINDLER, C., TAMKE, M., TABATABAI, A., BEREUTER, M.,
 622 AND YOSHIDA, H. 2014. Processing branches: Reactivating
 623 the performativity of natural wooden form with contemporary
 624 information technology. *International Journal of Architectural*
 625 *Computing* 12, 2, 101–115.
- 626 SEIKE, K. 1977. The art of japanese joinery.
- 627 SUJAN, V., DUBOWSKY, S., OHKAMI, Y., ET AL. 2000. Design
 628 and implementation of a robot assisted crucible charging system.
 629 In *Robotics and Automation, 2000. Proceedings. ICRA'00. IEEE*
 630 *International Conference on*, vol. 2, IEEE, 1969–1975.
- 631 TALTON, J. O., GIBSON, D., YANG, L., HANRAHAN, P., AND
 632 KOLTUN, V. 2009. Exploratory modeling with collaborative
 633 design spaces. *ACM Transactions on Graphics-TOG* 28, 5, 167.

634 WESTON, R. 2003. *Materials, form and architecture*. Yale Uni-
635 versity Press.

636 WILLIS, K. D., XU, C., WU, K.-J., LEVIN, G., AND GROSS,
637 M. D. 2011. Interactive fabrication: new interfaces for digital
638 fabrication. In *Proceedings of the fifth international conference*
639 *on Tangible, embedded, and embodied interaction*, ACM, 69–72.