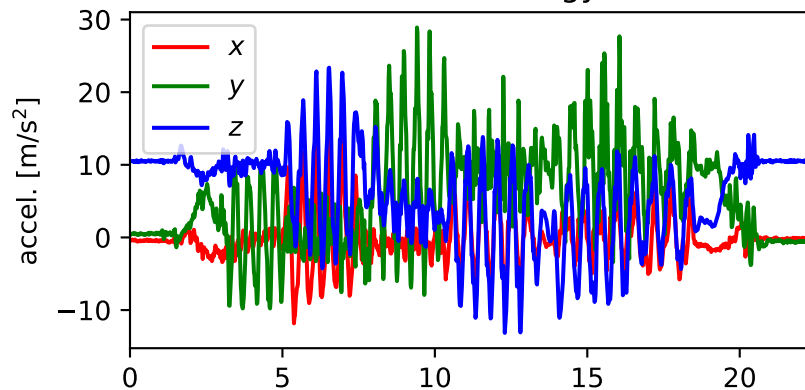


imu0 accel. and gyro.



imu1 accel. and gyro.

