

# Calculus 3 for Computer Science Project

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# 1 Introduction

Much of the code used within this assignment is Ruby version 1.9.x. Since it is, for most intents and purposes, a lesser known language than say, Java, we felt it necessary to explain bits of the language which might surface in the code we wrote for this project.

First and foremost, Ruby shares many similarities with, and is inspired by, Lisp, Smalltalk, and Perl (most likely in that order). It contains many of the niceties of functional programming that Lisp does, it is truly object oriented in the same way Smalltalk is, and it is a terse scripting language with powerful features like Perl is.

## 1.1 Syntax, Language Quirks, Etc.

Notations that might seem confusing unless one has a background in all three of these languages are such:

**Basic Syntax** Comments are preceded by a `#`. Strings are wrapped in either single- or double-quotes. Indentation is two spaces. Rather than using indentation-based block delimiters or curly braces, Ruby simply uses the `end` keyword.

**Blocks** Blocks are notations for anonymous functions in Ruby (like `lambda` in Lisp). They can be written a number of ways, such as:

```
# Assigning a lambda/proc to a variable, and then calling it
f = ->(x){ x + 1 }
f[2] #=> 3

# Array#map is one of several functions which takes a block as an argument
a = [1,2,3]
a.map { |i| i * i } #=> [1,4,9]

# This is the expanded form of the block, used for creating multi-line anonymous functions
a.each do |item|
  puts item
end
# would print 1, 2, and 3 on separate lines
```

**Ranges** Ranges are represented in Ruby with one of two operators, `..` or `...`. `0..10` is an inclusive range ( $[0, 10]$ ) in a more mathematical notation, whereas `0...5` is exclusive ( $[0, 5)$ ). Ranges can be iterated across.

**Method Invocation** In Ruby, method invocation has optional parens. Rather than using the form `instance.method(arg1, arg2)`, one can use the form `instance.method arg1, arg2`. In the case where an invocation doesn't have arguments, the parentheses are still optional.

**Object Oriented** Ruby, like Smalltalk, is object oriented down to the primitives of the language. This means that all things in Ruby are objects, and thus have methods that can operate on

them. This library was written to make use of this, monkey-patching functionality into the existing Matrix and Vector classes in Ruby.

**Notation** Ruby has a common nomenclature for expressing its classes and their methods. `Object#method` is the de facto standard among Rubyists, hence, that's the form we'll use here. Similarly, `#=>` is used to denote return values.

**Further Notes** Ruby's Matrix and Vector classes lack `#[]=` methods, therefore, we often convert these two datatypes to arrays and back again to perform matrix or vector arithmetic or other operations.

Hopefully, that should clear up any misconceptions or confusion before addressing the actual code at hand. That said, all three parts of this report do make use of both some standard libraries in Ruby, as well as extensions upon them.

- <http://www.ruby-doc.org/core/classes/Array.html>
- <http://www.ruby-doc.org/core/classes/Matrix.html>
- <http://www.ruby-doc.org/core/classes/Vector.html>

## 1.2 Common Code

Additionally, we wrote an abstraction layer into some of these classes via monkeypatching in order to add some common functionality:

Listing 1: Common Code for All Three Parts

```
class Vector
  private
  def sign(x)
    return 1 if x > 0
    return -1 if x < 0
    return 0
  end
end

class Matrix
  def pretty_print
    str = ""
    self.to_a.each do |row|
      row.each do |i|
        if i.to_i >= 0
          str << " "
        end
        if ("%3f" % i).to_f == i.to_i
          str << "#{i.to_i} "
        else

```

```

        str << "%.3f_" % i
    end
    end
    str << "\n"
end
puts str
end

def inf_norm
    self.to_a.map do |a|
        a.map do |ar|
            ar.abs
        end.inject(&:+)
    end.sort[0]
end

def is_lower_triangular?
    triangular(self.column_vectors)
end

def is_upper_triangular?
    triangular(self.row_vectors)
end

private
def triangular(vecs)
    for i in 0...vecs.length
        vec = vecs[i].to_a
        unless i <= 1
            return false unless vec[0...i].all? { |n| n == 0 } and vec[i..-1].all? { |n| n != 0 }
        end
    end
    return true
end
end

```

### 1.3 About This Document

This document was typeset in L<sup>A</sup>T<sub>E</sub>X. It uses the *color* and *listings* packages for the code formatting. The source code for this document is available at <http://github.com/wfarr/calc3-for-cs/report/report.tex>.

## 2 Part One

The purpose of Part One of the project is to solve the typical  $A\vec{x} = \vec{b}$  equation, with  $A$  being a Hilbert matrix. A Hilbert matrix is a square matrix whose elements follow the form

$$H_{ij} = \frac{1}{i + j - 1}$$

Here's an implementation in Ruby:

Listing 2: Hilbert Matrix Implementation

```
class Matrix
  def self.hilbert(n)
    m = Matrix.zero(n).to_a
    m = m.each_index.map{|row| m[row].each_index.map{|col| 1 / (row + col + 1)}}
    return Matrix.rows(m)
  end
end

Matrix.hilbert(4) ==> Matrix[[1/1,1/2,1/3,1/4], [1/2,1/3,1/4,1/5], [1/3,1/4,1/5,1/6],
[1/4,1/5,1/6,1/7]]
```

Often times, simplifying a single matrix  $A$  into two or more “nicer” matrices (in the case of these algorithms,  $LU$  or  $QR$ ) can make solving the equation  $A\vec{x} = \vec{b}$  easier. Such algorithms introduce the potential for error, namely because they are modified forms of the original matrix.

### 2.1 LU Decomposition

LU Decomposition uses matrix multiplication to reduce a matrix  $A$  into two matrices,  $L$  (a lower triangular matrix) and  $U$  (an upper triangular matrix).

#### 2.1.1 Explanation of the Algorithm

The algorithm for doing so is fairly simple in and of itself:

1. Starting with the first column, find the first non-zero entry below the diagonal. Let this entry be considered  $x$ . Let that column's diagonal element be  $y$ .
2. Multiply an Identity matrix, with the location of the entry  $x$  set to the value  $-\frac{x}{y}$ . This matrix is  $L_n$ .
3. The resulting matrix is the new  $A$  for the next iteration.
4. Repeat these steps until the resulting  $A$  is upper triangular. At this point,  $A$  becomes  $U$ .
5. To find  $L$ , multiply  $L_1^{-1}L_2^{-1}...L_n^{-1}$ .
6. Substitute  $A$  with  $LU$  in the equation  $A\vec{x} = \vec{b}$  and solve.

## 2.1.2 Implementation of the Algorithm

Listing 3: LU Decomposition

```
class Matrix
  def lu_decomposition
    return nil unless self.square?
    n = self.row_size
    a = self
    l_n = []
    cvs = a.column_vectors.map { |v| v.to_a }
    for k in 0...cvs.length
      for j in 0...cvs.length
        l_new = Matrix.identity(n).to_a
        if l_new[j][k] == 1 || j < k
          next
        end
        l_new[j][k] = - (cvs[k][j] / cvs[k][k])
        l_n << l_new
        a = Matrix[*l_new] * Matrix[*cvs.transpose]
        cvs = a.column_vectors.map { |v| v.to_a }
      end
    end
    l_final = l_n.map { |m| Matrix[*m].inverse }.inject(&:*)
    u_final = a
    return l_final, u_final
  end
end
```

The algorithm first begins with an essential check: the method `self.square?` determines if the matrix is a square matrix, and returns true if it is. LU Decomposition can only be done on square matrices, thus, the method returns nil when given a non-square matrix. Next, the algorithm defines *A* (written as `a` in the code because *A* would've been a Constant rather than a variable) to be the instance of `self`. To iterate across the columns efficiently, we use `Matrix#column_vectors`, which returns an array of column vectors. This array is then mapped over to convert the vectors into arrays. The end result is that `cvs` is an array of arrays representing the columns of `self`.

The actual computation lies in the nested `for` loops. For each iteration, an `l_new` matrix is created and converted to an array. If the current values of `j` and `k` are above the diagonal, then the algorithm skips to the next iteration. Next, `l_new[j][k]` is set to  $-\frac{x}{y}$ , as above in the algorithm's description. A new `a` is made as the product of `l_new` and `cvs.transpose` (the same matrix as *A*). The last step of each iteration is rebuilding `cvs` based off of the newest `a`.

Finally, *L* and *U* are assigned and returned. While `u_final` is straight-forward, `l_final` is a bit more complicated. `l_n.map { |m| Matrix[*m].inverse }` returns an array of inverted matrices from the original array of arrays (of arrays). The one bit of syntactic sugar in that line is the use of `Matrix[*m]`. In this case, `*` is acting as the glob operator, essentially inserting all the content of the array it's called on rather than simply inserting the array itself.

This is necessary because `Matrix[...]` takes a list of rows (in the form of arrays) as its argument. Finally, this new array is passed `Array#inject`, which applies a given block to all elements

of an array and returns the result. In this case, the injection is making use of a feature in Ruby 1.9 called `symbol_to_proc`, which allows for passing the method the `:*` symbol and automatically converting it into a proc/lambda. Thus, the result of the injection is to multiply all the results of the map together, in order.

### 2.1.3 Results and Analysis

The error introduced by the algorithm is effectively 0.

## 2.2 Householder Reflections

Lots of stuff about Householder Reflections.

### 2.2.1 Description of the Algorithm

Snafu.

### 2.2.2 Implementation of the Algorithm

Listing 4: QR Decomposition via Householder Reflections

```
class Matrix
  def householder
    return nil unless self.square?
    current_iteration = self
    init_dim = self.row_size
    h_list = []
    cv = current_iteration.column_vectors[0]
    h = (cv.find_householder_reflection - Matrix.identity(cv.size)).expand_to_dimensions(
      init_dim, init_dim) + Matrix.identity(init_dim)
    h_list << h
    current_iteration = h * current_iteration
    for i in 0...self.row_size
      cv = current_iteration.get_column_vector(i+1)
      break if cv.size < 2 || current_iteration.is_upper_triangular?
      h = (cv.find_householder_reflection - Matrix.identity(cv.size)).expand_to_dimensions(
        init_dim, init_dim) + Matrix.identity(init_dim)
      h_list << h
      current_iteration = h * current_iteration
    end
    q,r = h_list.inject(&:*), current_iteration
    return q,r
  end

  def expand_to_dimensions(x,y)
    curr_x, curr_y, a = self.row_size, self.column_size, self.to_a
    a.each_index do |row|
      for i in 0...(y - curr_y)
        a[row] = a[row].insert(0,0)
      end
    end
    for i in 0...(x - curr_x)
```

```

        a = a.insert(0, Array.new(y){0})
    end
    return Matrix.rows(a)
end

def get_column_vector(x)
    return Vector.elements(self.column(x)[x..-1])
end
end

class Vector
    def find_householder_reflection
        a = self.to_a
        a = a[0] if a[0].is_a?(Array)
        a[0] = a[0] + sign(a[0]) * self.r
        u = Vector[*a]
        norm_u_sqrd = u.r**2
        uut = u.covector.transpose * u.covector
        h = Matrix.identity(uut.row_size) - (uut * (2 / norm_u_sqrd))
        return h
    end
end
end

```

### 2.2.3 Results and Analysis

## 2.3 Givens Rotations

Lots of stuff about Givens Rotations.

### 2.3.1 Explanation of the Algorithm

Snafu

### 2.3.2 Implementation of the Algorithm

Listing 5: QR Decomposition via Givens Rotations

```

class Matrix
    def givens
        return nil unless self.square?
        n = self.row_size
        a = self
        g_n = []
        cvs = a.column_vectors.map { |v| v.to_a }
        for i in 0...cvs.length
            for j in 0...cvs.length
                next unless j > i
                g = Matrix.identity(n).to_a
                c = cvs[i][i] / Math.sqrt(cvs[i][i]**2 + cvs[i][j]**2)
                s = -cvs[i][j] / Math.sqrt(cvs[i][i]**2 + cvs[i][j]**2)
                g[i][i], g[j][j] = c, c
                g[j][i], g[i][j] = s, -s
                g = Matrix[*g]
            end
        end
    end
end

```



```

      g.n << g
      a = g * a
      cvs = a.column_vectors.map { |v| v.to_a }
    end
  end
  q,r = g.n.map { |m| m.t }.inject(&:*), a
  return q,r
end
end

```

### 2.3.3 Results and Analysis

## **3 Part Two**

Clusterfuck.

### **3.1 Jacobi Method**

Lots of stuff about Jacobi Method.

### **3.2 Gauss-Seidel Method**

Lots of stuff about Gauss-Seidel Method.

## **4 Part Three**

Less of a clusterfuck.

### **4.1 Leslie Matrices**

Also stuff.

### **4.2 Power Method**

Stuff galore.