

Determinants (Part-1) #L1.4

- Every sq. matrix A has an associated no., called its determinant.
 $\Rightarrow \det(A)$ or $|A|$

- Solving system of linear eqⁿ

- Finding inverse of matrix

- calculus and more

- If $A = [a]$, a 1×1 matrix, then $\boxed{\det(A) = a}$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\boxed{\det(A) = ad - bc}$$

ex, $A = \begin{bmatrix} 2 & 3 \\ 6 & 10 \end{bmatrix}$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\boxed{\det(A) = a_{11} \times \det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \times \det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}}$$

Solve during Revision $\rightarrow A = \begin{bmatrix} 2 & 4 & 1 \\ 3 & 8 & 7 \\ 5 & 6 & 9 \end{bmatrix}$
(Ans) = 70

- det of I $I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ $\det(I_2) = 1 - 0 = 1$

$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ $\det(I_3) = 1$

- $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ $B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$ $AB = \begin{bmatrix} ae+bg & af+bh \\ ce+dg & cf+dh \end{bmatrix}$

$\det(AB) = [(1)(4)] - [(2)(3)]$

$\boxed{\det(AB) = \det(A)\det(B)}$ \rightarrow do the proof during revision.

- Inverse of matrix

$(AA^{-1}) = I = A^{-1}A$

$\boxed{\det(A^{-1}) = \frac{1}{\det(A)}}$

- $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ $\bar{A} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$ } By switching 2 rows

$\boxed{\det(\bar{A}) = -\det(A)}$

$\bar{\bar{A}} = \begin{bmatrix} b & a \\ d & c \end{bmatrix}$ $\boxed{\det(\bar{\bar{A}}) = -\det(\bar{A})}$
by switching 2 columns.

- Adding multiples of a row to another row

$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ $\bar{A} = \begin{bmatrix} a+tc & b+td \\ c & d \end{bmatrix}$

$\boxed{\det(\bar{A}) = \det(A)}$

- Scalar multiplication of a row by a constant

$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ $\bar{A} = \begin{bmatrix} ta & tb \\ c & d \end{bmatrix}$

$\boxed{\det(\bar{A}) = t \det(A)}$