## **Diabetic Retinopathy Detection Using Python**

Importing Nessesary libraries and modules from the local python environment

```
In [2]: from scipy import misc
        from PIL import Image
        from skimage import exposure
        from sklearn import svm
        import scipy
        from math import sqrt,pi
        from numpy import exp
        from matplotlib import pyplot as plt
        import numpy as np
        import glob
        import matplotlib.pyplot as pltss
        import cv2
        from matplotlib import cm
        import pandas as pd
        from math import pi, sqrt
        import pywt
```

## **Pre-processing**

Loading Images and converting them to grey-Scale followed by adaptive hstogram equilisation the final image matrix is stored in 1-D format to a new 2-D array

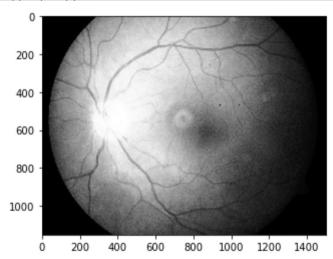
```
In [103]: #img_rows=img_cols=200
                                        immatrix=[]
                                        im_unpre = []
                                        \#image\_path = Image.open('C:\Users\Rohan\Desktop\Diabetic\_Retinopathy\diaretdb1\_v\_1\_1\diaretdb1\_v\_1\_1\resources\images\ddb1\_fundus
                                        #image = misc.imread(image path)
                                        for i in range(1,90):
                                                       img_pt = r'C:\Users\Rohan\Desktop\Diabetic_Retinopathy\diaretdb1_v_1_1\diaretdb1_v_1_1\resources\images\db1_fundusimages\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\images\im
                                                                      img_pt = img_pt + "00" + str(i) + ".png"
                                                       else:
                                                                      img_pt = img_pt + "0" + str(i)+ ".png"
                                                       img = cv2.imread(img_pt)
                                                       #im_unpre.append(np.array(img).flatten())
                                                       img_gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
                                                       equ = cv2.equalizeHist(img_gray)
                                                       immatrix.append(np.array(equ).flatten())
                                                       #res = np.hstack((img_gray,equ))
```

```
In [4]: Out[4]: (1728000,)
```

Visualising a random image after the above steps the array contains 90 images

The shape of the image is determined from np.shape(equ) and those values are 1152,1500

```
In [111]: np.shape(immatrix)
    np.shape(equ)
    plt.imshow(immatrix[78].reshape((1152,1500)),cmap='gray')
```



Performing Discrete-Wavelet transform on the 2-D array available

the Haar wavelet is a sequence of rescaled "square-shaped" functions which together form a wavelet family or basis. Wavelet analysis is similar to Fourier analysis in that it allows a target function over an interval to be represented in terms of an orthonormal basis. The Haar sequence is now recognised as the first known wavelet basis and extensively used as a teaching example.

```
In [6]: imm_dwt = []
```

```
for equ in immatrix:
    equ = equ.reshape((1152,1500))
    coeffs = pywt.dwt2(equ, 'haar')
    equ2 = pywt.idwt2(coeffs, 'haar')
    imm_dwt.append(np.array(equ2).flatten())
```

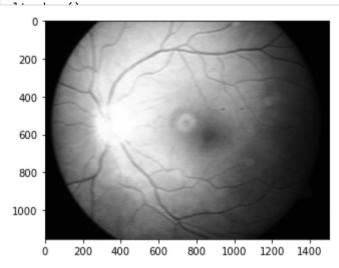
Visualising a random image

```
In [7]: np.shape(imm_dwt)
np.shape(equ2)
plt.imshow(imm_dwt[78].reshape((1152,1500)),cmap='gray')
```

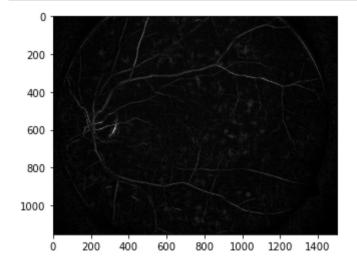
```
200 -
400 -
600 -
800 -
1000 -
0 200 400 600 800 1000 1200 1400
```

```
In [27]: def _filter_kernel_mf_fdog(L, sigma, t = 3, mf = True):
             dim_y = int(L)
             dim_x = 2 * int(t * sigma)
             arr = np.zeros((dim_y, dim_x), 'f')
             ctr_x = dim_x / 2
             ctr_y = int(dim_y / 2.)
             # an un-natural way to set elements of the array
             # to their x coordinate.
             # x's are actually columns, so the first dimension of the iterator is used
             it = np.nditer(arr, flags=['multi_index'])
             while not it.finished:
                 arr[it.multi_index] = it.multi_index[1] - ctr_x
                 it.iternext()
             two_sigma_sq = 2 * sigma * sigma
             sqrt_w_pi_sigma = 1. / (sqrt(2 * pi) * sigma)
             if not mf:
                 sqrt_w_pi_sigma = sqrt_w_pi_sigma / sigma ** 2
             #@vectorize(['float32(float32)'], target='cpu')
             def k_fun(x):
                 return sqrt_w_pi_sigma * exp(-x * x / two_sigma_sq)
             #@vectorize(['float32(float32)'], target='cpu')
             def k_fun_derivative(x):
                 return -x * sqrt_w_pi_sigma * exp(-x * x / two_sigma_sq)
                 kernel = k_fun(arr)
                 kernel = kernel - kernel.mean()
             else:
                 kernel = k_fun_derivative(arr)
             # return the "convolution" kernel for filter2D
             return cv2.flip(kernel, -1)
         def show_images(images,titles=None, scale=1.3):
              """Display a list of images"""
             n_ims = len(images)
             if titles is None: titles = ['(%d)' % i for i in range(1,n_ims + 1)]
             fig = plt.figure()
             n = 1
             for image,title in zip(images,titles):
                 a = fig.add subplot(1,n ims,n) # Make subplot
                 if image.ndim == 2: # Is image grayscale?
                     plt.imshow(image, cmap = cm.Greys_r)
                 else:
                     plt.imshow(cv2.cvtColor(image, cv2.COLOR_RGB2BGR))
                 a.set_title(title)
                 plt.axis("off")
                 n += 1
             fig.set_size_inches(np.array(fig.get_size_inches(), dtype=np.float) * n_ims / scale)
             plt.show()
         def gaussian_matched_filter_kernel(L, sigma, t = 3):
             K = \frac{1}{(sqrt(2 * pi) * sigma)} * exp(-x^2/2sigma^2), |y| <= L/2, |x| < s * t
             return _filter_kernel_mf_fdog(L, sigma, t, True)
         #Creating a matched filter bank using the kernel generated from the above functions
         def createMatchedFilterBank(K, n = 12):
```

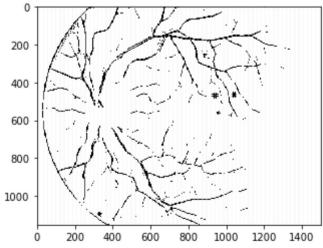
```
rotate = 180 / n
   center = (K.shape[1] / 2, K.shape[0] / 2)
   cur_rot = 0
   kernels = [K]
   for i in range(1, n):
        cur_rot += rotate
        r_mat = cv2.getRotationMatrix2D(center, cur_rot, 1)
        k = cv2.warpAffine(K, r_mat, (K.shape[1], K.shape[0]))
        kernels.append(k)
   return kernels
#Given a filter bank, apply them and record maximum response
def applyFilters(im, kernels):
   images = np.array([cv2.filter2D(im, -1, k) for k in kernels])
   return np.max(images, 0)
gf = gaussian_matched_filter_kernel(20, 5)
bank_gf = createMatchedFilterBank(gf, 4)
imm_gauss = []
for equ2 in imm_dwt:
   equ2 = equ2.reshape((1152,1500))
   equ3 = applyFilters(equ2,bank_gf)
   imm_gauss.append(np.array(equ3).flatten())
```



```
In [8]: def createMatchedFilterBank():
            filters = []
            ksize = 31
            for theta in np.arange(0, np.pi, np.pi / 16):
                kern = cv2.getGaborKernel((ksize, ksize), 6, theta,12, 0.37, 0, ktype=cv2.CV_32F)
                kern /= 1.5*kern.sum()
                filters.append(kern)
            return filters
        def applyFilters(im, kernels):
            images = np.array([cv2.filter2D(im, -1, k) for k in kernels])
            return np.max(images, 0)
        bank_gf = createMatchedFilterBank()
        #equx=equ3
        #equ3 = applyFilters(equ2,bank_gf)
        imm_gauss2 = []
        for equ2 in imm dwt:
            equ2 = equ2.reshape((1152,1500))
            equ3 = applyFilters(equ2,bank_gf)
            imm_gauss2.append(np.array(equ3).flatten())
```



```
In [128]: # the array ranges from 0 - 89
          np.shape(imm_gauss2)
          plt.imshow(imm_gauss2[1].reshape((1152,1500)),cmap='gray')
              0 -
            200
            400
            600
            800
           1000
                        400
                              600
                                   800 1000 1200 1400
 In [38]: e_ = equ3
          np.shape(e_)
          e_=e_.reshape((-1,3))
 Out[38]: (576000, 3)
          Performing K-means Clusttering with PP centers(non random) neighbours on the final image
  In [ ]: | img = equ3
          Z = img.reshape((-1,3))
          # convert to np.float32
          Z = np.float32(Z)
          k=cv2.KMEANS_PP_CENTERS
          # define criteria, number of clusters(K) and apply kmeans()
          criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 10, 1.0)
          ret,label,center=cv2.kmeans(Z,K,None,criteria,10,k)
          # Now convert back into uint8, and make original image
          center = np.uint8(center)
          res = center[label.flatten()]
 In [10]: |imm_kmean = []
          for equ3 in imm_gauss2:
              img = equ3.reshape((1152,1500))
              Z = img.reshape((-1,3))
              # convert to np.float32
              Z = np.float32(Z)
              k=cv2.KMEANS_PP_CENTERS
              # define criteria, number of clusters(K) and apply kmeans()
              criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 10, 1.0)
              ret,label,center=cv2.kmeans(Z,K,None,criteria,10,k)
              # Now convert back into uint8, and make original image
              center = np.uint8(center)
              res = center[label.flatten()]
              res2 = res.reshape((img.shape))
              imm_kmean.append(np.array(res2).flatten())
In [113]: # the array ranges from 0 - 89
          np.shape(imm_kmean)
          plt.imshow(imm_kmean[78].reshape((1152,1500)),cmap="gray")
```



## **Model training**

Importing SVc(same as SVM) from sklearn library

```
In [42]: from sklearn.svm import SVC
In [64]:
        These corresponding Images are marked as non-effected in the data-set
In [65]: WEAT WEAT WEAT WEAT
        SVM with Radial Basis Function (RBF)
        Linear SVM classifies the data by putting a hyper plane between the two classes. In the case of rbf SVM the plane would be in infinite dimension
Out[66]: SVC(C=1.0, cache_size=200, class_weight=None, coef0=0.0,
          decision_function_shape=None, degree=3, gamma='auto', kernel='rbf',
          max_iter=-1, probability=False, random_state=None, shrinking=True,
          tol=0.001, verbose=False)
In [72]:
In [1]:
In [3]:
In [87]:
Out[87]: array([ 0., 2., 3., 8., 9., 10., 12., 13., 19., 21., 23.,
               24., 25., 26., 27., 28., 34., 35., 37., 41., 52., 54.,
               56., 63., 69., 78., 83., 85.])
In [92]:
        k =[int(x) for x in k]
In [93]:
Out[93]: [0,
         2,
         3,
         8,
         9,
         10,
         12,
         13,
         19,
         21,
         23,
         24,
         25,
         26,
         27,
         28,
         34,
         35,
         37,
         41,
         52,
         54,
         56,
         63,
         69,
         78,
         83,
         85]
In [98]: |imm_train = []
        y_{train} = []
        k.append(5)
        k.append(7)
        for i in k:
           imm_train.append(imm_kmean[i])
           y_train.append(Y[i])
In [99]:
Out[99]:
```

```
[1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
          1.0,
In [100]:
Out[100]: SVC(C=1.0, cache_size=200, class_weight=None, coef0=0.0,
           decision_function_shape=None, degree=3, gamma='auto', kernel='rbf',
           max_iter=-1, probability=False, random_state=None, shrinking=True,
           tol=0.001, verbose=False)
In [101]:
In [102]:
Out[102]: 0.9662921348314607
         The final accuracy received on predicting over the remaining dataset is
         96.62%
In [114]: from sklearn.neighbors import KNeighborsClassifier
In [115]: neigh = KNeighborsClassifier(n_neighbors=3)
Out[116]: KNeighborsClassifier(algorithm='auto', leaf_size=30, metric='minkowski',
                   metric_params=None, n_jobs=1, n_neighbors=3, p=2,
                   weights='uniform')
In [117]: y_pred2=neigh.predict(imm_kmean)
In [119]:
Out[119]: 0.9438202247191011
```

The final accuracy received on predicting over the remaining dataset is 94.38% using KNN algo