

## Lab Exercise 4

### SE2042 – Operating Systems

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**Learning Objectives:** In this lab, you will learn about Intercrosses communication with signals and pipes.

The Linux IPC (Inter-process communication) facilities provide a method for multiple processes to communicate with one another. There are several methods of IPC available to Linux C programmers:

- Pipes
- Signals
- Message queues
- Semaphore sets
- Shared memory segments
- Sockets

Pipes are known as the oldest communication mechanism under UNIX. To create a simple pipe with C, we make use of the pipe() system call. It takes a single argument, which is an array of two integers, and if successful, the array will contain two new file descriptors to be used for the pipeline. A pipe is created by calling the pipe () function in the following way.

```
int fd[2];
if (pipe(fd) < 0)
    printf("Error!\n");
```

The pipe() function is invoked. This returns two valid file descriptors in the array given as the argument. The input of the first file descriptor (fd[0]) is the output of the second file descriptor (fd[1]).

**Exercise 01:** Write the following program and execute to understand the concept of pipe.

```
#include <stdio.h>
main()
{
    int pipefd[2];
    int i;
    char s[1000];
    char *s2;

    if (pipe(pipefd) < 0)
    {
        perror("pipe");
        exit(1);
    }
```

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```

s2 = "This is the message";
write(pipefd[1], s2, strlen(s2));
i = read(pipefd[0], s, 1000);
s[i] = '\0';
printf("Read %d bytes from the pipe: '%s'\n", i, s);
}

```

**Exercise 02:** Write the following program and execute to understand the concept of pipe with parent and child processes.

```

#include <stdio.h>
#include <unistd.h>
#include <sys/types.h>
int main()
{
    int fd[2], nbytes;
    pid_t childpid;
    char string[] = "Hello, world!\n";
    char readbuffer[80];
    pipe(fd);
    if((childpid = fork()) == -1)
    {
        perror("fork");
        exit(1);
    }
    if(childpid == 0)
    {
        close(fd[0]);
        write(fd[1], string, strlen(string));
        exit(0);
    }
    else
    {
        close(fd[1]);
        nbytes = read(fd[0], readbuffer, sizeof(readbuffer));
        printf("Received string: %s", readbuffer);
    }
    return(0);
}

```

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#### Signal Handling

Signals are the means to notify a process or thread of the occurrence of an event. Signals are one of the oldest inter-process communication methods used by Unix. Signals are a way of sending simple messages to processes. Most of these messages are already defined and can be found in <linux/signal.h>. However, signals can only be processed when the process is in user mode. If a signal has been sent to a process that is in kernel mode, it is dealt with immediately on returning to user mode.

#### Exercise 03:

```
#include <stdio.h>
#include <signal.h>

void sigproc(void);
void quitproc(void);

main()
{
    signal(SIGINT, sigproc);
    signal(SIGQUIT, quitproc);
    printf(`ctrl-c disabled use ctrl. \\ to quit \n');
    for(;;) /* infinite loop */

    void sigproc()
    {
        signal(SIGINT, sigproc);
        printf(`you have pressed ctrl-c \n');
    }

    void quitproc()
    {
        printf(`ctrl- \\ pressed to quit \n');
        exit(0); /* normal exit status */
    }
}
```