Chapter 3

Introduction to Digital Image Analysis

1

Introduction

- ➤Image Analysis:
- ✓ Manipulation of image data to determine exactly what information is required to develop a computer imaging system
- ✓ Data reduction process
- √Part of a larger process
- ✓ Iterative in nature
- ✓ Answers application specific questions

➤ System Model:

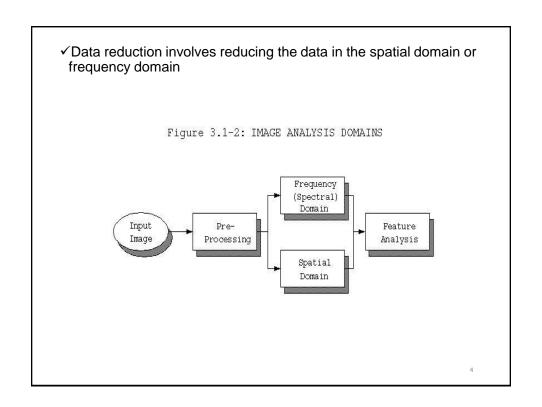
✓ Image analysis can be broken into three primary stages as:

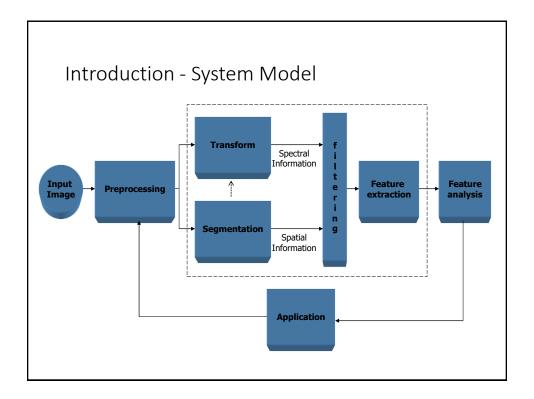
• Preprocessing

• Data Reduction

• Feature Analysis

Figure 3.1-1: IMAGE ANALYSIS





Preprocessing

- √To make data reduction and analysis task easier
- ✓ Consist of following operations:
- · Noise and artifact removal
- Extracting Region of Interest (ROI)
- Performing mathematical operations
- Enhancement of specific image features
- Data reduction in resolution and brightness



Image with border



Image with border removed



Shape information required



Image with object shape

7

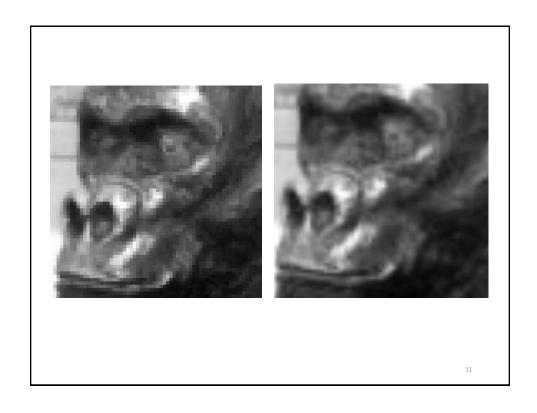
≻Region of Interest Image Geometry

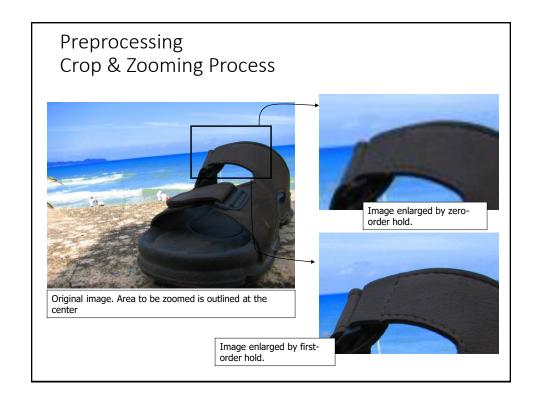
- √To investigate more closely a specific area of an image
- √ Consists of following operations:
- Crop
- Zoom
 - Enlarge
- Shrink
- Translate
- Rotate

- *Crop*: Selecting a portion of an image, a sub-image, and cutting it away from the rest of the image, for example "border removal"
- Zoom:
- Enlarging a section of an image, to improve visual analysis of detailed objects
- Can be done by zero hold order (repeating previous pixel values) or first order hold (linear interpolation of adjacent pixels)

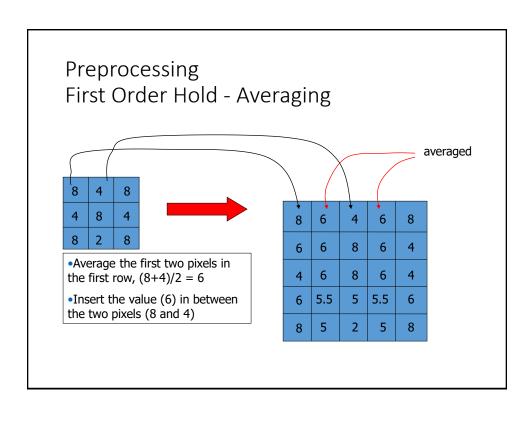
- Zero order hold: Can also be performed by convolution in the following way:
 - a. Extend the image by adding rows and columns of zeroes between existing rows and columns
- b. Perform convolution by using the following convolution mask

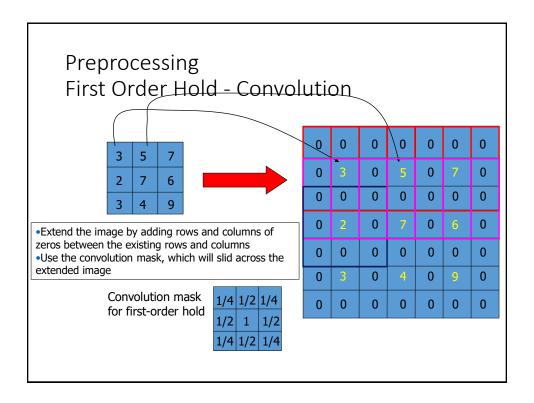
 $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

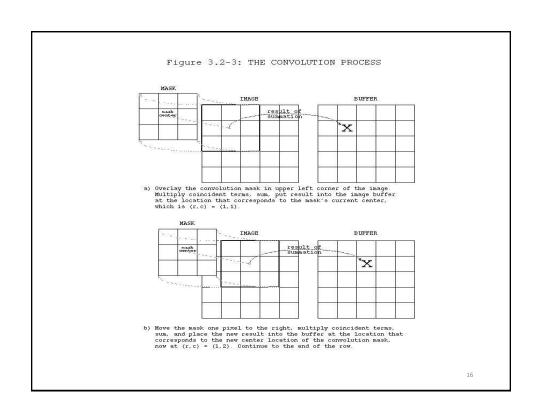


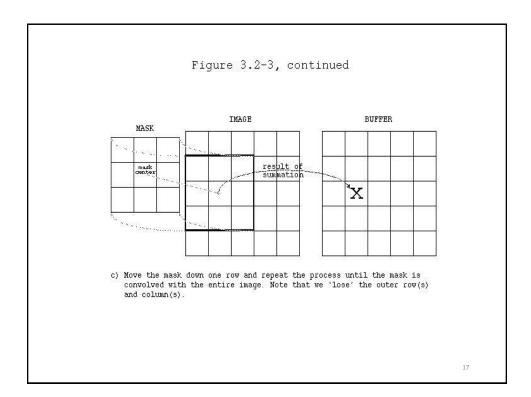


- ❖First order hold:
 - Can be performed in two ways:
 - 1. Averaging
 - 2. Convolution
 - 1. Averaging: Allows to enlarge an N*N sized image to a size of (2N-1) * (2N-1), and can be repeated









√The convolution equation is given by

whe
$$\sum_{w=-\infty}^{+\infty}\sum_{y=-\infty}^{+\infty}I(r-x,c-y)M(x,y)$$
 M (: ,r,c) is the image

- Why use the convolution method as opposed to the basic averaging of neighbors method?
- √ Many imaging systems provide the convolution capability in hardware
- ✓ In general, hardware is faster than software

1

Linear interpolation method

- ✓ Enlarges an image other than a factor of (2N-1)
- ✓ Finds a line that connects two values in brightness space, and hence sampling it faster to get more samples, thus increasing the resolution