

Delta Rule

Dataset: $\begin{bmatrix} x_1 & x_2 & x_3 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ $\begin{bmatrix} b \\ w_0 \\ 2 \end{bmatrix}$ $\begin{bmatrix} \text{wheel} \\ 0 \\ 1 \end{bmatrix}$ unit step func

weight $\begin{bmatrix} w_1 & w_2 & w_3 \\ -2 & 2 & 1 \end{bmatrix}$

2nd sample

$$= b_0 w_0 + x_1 w_1 + x_2 w_2 + x_3 w_3$$

$$= 1(2) + 1(-2) + 0(2) + 1(1)$$

$$= 2 - 2 + 0 + 1$$

$$= 3$$

$$\hat{y}_1 = \text{act}(3) = 1$$

$$\alpha = 0.2$$

$y_i - \hat{y}_i$	$(y_i - \hat{y}_i) \cdot b$	$(y_i - \hat{y}_i) \cdot x_1$	$(y_i - \hat{y}_i) \cdot x_2$	$(y_i - \hat{y}_i) \cdot x_3$
$0 - 1 = -1$	$1 \times (-1) = -1$	$-1 \times 1 = -1$	$0 \times -1 = 0$	$-1 \times 1 = -1$
$1 - 1 = 0$	$1 \times 0 = 0$	$0 \times 0 = 0$	$0 \times 0 = 0$	$0 \times 0 = 0$
$\Sigma = -1$	$\Sigma = -1$	$\Sigma = -1$	$\Sigma = 0$	$\Sigma = -1$

$$w_{0_{\text{new}}} = w_0 + \Sigma \alpha (y_i - \hat{y}_i) \cdot b = 2 + 0.2(-1) = 1.8$$

$$w_{1_{\text{new}}} = w_1 + \Sigma \alpha (y_i - \hat{y}_i) \cdot x_1 = -2 + 0.2(-1) = -2.2$$

$$w_{2_{\text{new}}} = w_2 + \Sigma \alpha (y_i - \hat{y}_i) \cdot x_2 = 2 + 0.2(0) = 2$$

$$w_{3_{\text{new}}} = w_3 + \Sigma \alpha (y_i - \hat{y}_i) \cdot x_3 = 1 + 0.2(-1) = 0.8$$

$$\begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} 1.8 \\ -2.2 \\ 2 \\ 0.8 \end{bmatrix}$$

Delta Rule: $\alpha \cdot \sum (y - \hat{y}) \cdot f'(act) \cdot x_1$

Suppose no act function.

$$(y - \hat{y}) \cdot x_1$$

cost function: $\frac{1}{2} (y - \hat{y})^2$

$$\frac{dc}{dw_0} = \frac{d \left(\frac{1}{2} (y - \hat{y})^2 \right)}{dw_0}$$

now, $\hat{y} = w_0 b + w_1 x_1 + \dots$
so \hat{y} has many more
variables and not only w_0

\Rightarrow Therefore we will take
its Partial derivative.

\Rightarrow Your cost is not directly dependent
on w_0 .

Cost depends on \hat{y}
 \hat{y} depends on w_0] This is called
Chain Rule

Therefore: $\frac{dc}{dw_0} = \frac{dc}{d\hat{y}} \cdot \frac{d\hat{y}}{dw_0}$

Let's take the first term:

$$\frac{dc}{d\hat{y}} = \frac{2 \cdot \frac{1}{2} (y - \hat{y})^2}{2 (\hat{y})} \Rightarrow \text{since } \hat{y} \text{ has many variables}$$

hence taking its partial derivative.

$$= \frac{1}{2} \cdot 2 (y - \hat{y})^{2-1} \left(\frac{dy}{d\hat{y}} - \frac{d\hat{y}}{d\hat{y}} \right)$$

$$(y - \hat{y}) (0 - 1)$$

$$(y - \hat{y}) (-1)$$

$$= -(y - \hat{y})$$

Therefore: $\frac{dc}{dw_0} = \frac{dc}{dy} \cdot \frac{dy}{dw_0}$

lets take the first term

$$\frac{dc}{dy} = \frac{\partial \frac{1}{2} (y - \hat{y})^2}{\partial (\hat{y})} \Rightarrow \text{since } \hat{y} \text{ has many variables}$$

hence taking its partial derivative.

$$= \frac{1}{2} \cdot 2 (y - \hat{y})^{2-1} \left(\frac{dy}{dy} - \frac{d\hat{y}}{d\hat{y}} \right)$$

$$(y - \hat{y}) (0 - 1)$$

$$(y - \hat{y}) (-1)$$

$$= -(y - \hat{y})$$

So, $\frac{dc}{dy} = -(y - \hat{y})$

$$\hat{y} = w_0 b + w_1 x_1 + \dots$$

Now lets see, $\frac{dy}{dw_0} = \frac{\partial (w_0 b + w_1 x_1 + \dots)}{\partial w_0}$

$$= \frac{\partial (w_0 b)}{\partial w_0} + \frac{\partial w_1 x_1}{\partial w_0}$$

$$= 1 \cdot b + 0$$

$$= b$$

since bias is always 1

$$\Rightarrow -(y - \hat{y}) \cdot b$$

for weight update the equation is:

$$w_0 = \alpha \cdot \frac{dc}{dw_0}$$

$$w_0 = -(y - \hat{y}) \cdot x_i$$

$$w_0 = -(y - \hat{y}) \cdot x_i$$