# VIET NAM GENERAL CONFEDERATION OF LABOR TON DUC THANG UNIVERSITY FACULTY OF INFORMATION TECHNOLOGY



LÂM GIA BỘI – 520H0519

# FINAL REPORT MACHINE LEARNING

HÒ CHÍ MINH CITY, 2023

# VIET NAM GENERAL CONFEDERATION OF LABOR TON DUC THANG UNIVERSITY FACULTY OF INFORMATION TECHNOLOGY



LÂM GIA BỘI – 520H0519

# FINAL REPORT MACHINE LEARNING

Instructor:

TS. LÊ ANH CƯỜNG

HÒ CHÍ MINH CITY, 2023

## **ACKNOWLEDGEMENTS**

I would like to say sincere thanks to Mr. Lê Anh Cường for his dedicated guidance and contribution to the completion of this report. Your enthusiasm and heart have been an enormous motivation of encouragement, assisting me in understanding the subject and developing the necessary skills. I want to thank you for all that you've done to help me develop. I hope you will continue to share your enthusiasm and knowledge with future generations of practitioners.

Hồ Chí Minh city, 20 December 2023

Author

(Signature)

#### WORK COMPLETED AT TON DUC THANG UNIVERSITY

I hereby declare that this research project is my own work, conducted under the scientific guidance of TS. Lê Anh Cường. The research contents and results presented in this project are truthful and have not been published in any form before. The data presented in the tables, serving for analysis, comments, and evaluations, were collected by the author from various sources as explicitly indicated in the reference section.

Furthermore, the project also incorporates some comments, evaluations, as well as data from other authors and different organizing entities, all of which are properly cited and referenced.

If any form of academic dishonesty is identified, I take full responsibility for the content of our project. Ton Duc Thang University is not associated with any copyright violations or infringements that may occur during the execution of this project (if any)."

Ho Chi Minh city, 20 December 2023

Author

(Signature)

# **WEB SOCKET**

# **SUMMARY**

This report will provide an overview of the information we have studied and learned about optimizer model in training learning models. This includes:

- 1. What is optimizer in training learning models?
- 2. Overview and study about this method?
- 3. Comparison between these methods.
- 4. Application of these methods
- 5. Continual Learning
- 6. Test Production

# TABLE OF CONTENT

LIST OF IMAGES	V
LIST OF TABLES	vi
LIST OF ABBREVIATIONS	vii
PART 1: THEORY	1
1.1 What is the optimizer in training learning models	1
1.2 Overview and study	2
1.2.1 Gradient Descent	2
1.2.2 Stochastic Gradient Descent	2
1.2.3 Momentum	3
1.2.4 Adam	4
1.2.5 Adaptive Gradient Algorithm	4
1.2.6 Root means square propagation	5
1.3 Comparision between these methods	6
1.4 Applications	7
1.5 Continual Learning	8
1.6 Test production	11
DEFEDENCES	12

# LIST OF IMAGES

Image 1.1.1: Difference between large learning and small learning rate	
Image 1.2.1: Formula of Gradient Descent	2
Image 1.2.2: Formula of Stochastic Gradient Descent	3
Image 1.2.3: Formula of momentum	3
Image 1.2.4: Formula of Adam	4
Image 1.2.5: Formula of Adaptive Gradient Algorithm	5
Image 1.2.6: Formula of Root means square propagation	5

# LIST OF TABLES

Table 1.3.1: Advantages and Disadvantages of these methods .	6
Table 1.5.1: Pros and Cons of Continual Learning	10

# LIST OF ABBREVIATIONS

GD Gradient Descent

SGD Stochastic Gradient Descent

Adagrad Adaptive Gradient Algorithm

RMSprop Root means square propagation

NLP Natural Language Processing

CNNs Convolutional Neural Network

## **CHAPTER 1: THEORY**

### 1.1 What is the optimizer in training learning models?

- In machine learning model training, optimization is an important part of updating the weight of the model so that the model achieves the best performance on the training data. Optimizers assist in minimizing the loss function. Different optimizers offer different strategies for this process. There are some common methods which are used for optimizing the data:
  - o Gradient Descent
  - Stochastic Gradient Descent
  - Momentum
  - o Adam
  - Adagrad
  - Root means square propagation.
- Learning rates play an important role in optimizing. For example, when the learning rate is very high, we never reach the true minimum. On the other hand, if the learning rate is too small, we can find the closer minimum point, but in reality, the global minimum is down here, which leads the model to end up at a false minimum.

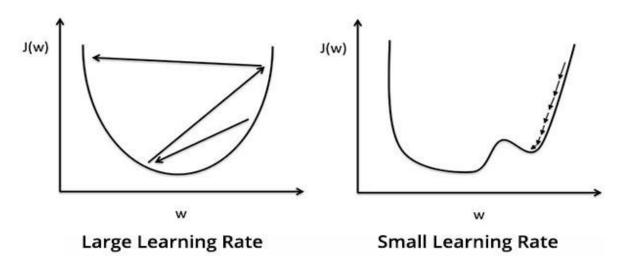


Figure 1.1.1 Difference between large learning rate and small learning rate

## 1.2 Overview and study

#### 1.2.1 Gradient Descent

- **Definition:** Gradient Descent is an optimization algorithm used to minimize a cost function iteratively. It calculates the gradient (partial derivative) of the cost function with respect to the model parameters and adjusts the parameters in the opposite direction of the gradient to reduce the cost.
- Formula:

$$\theta^{new} = \theta^{old} - \alpha \nabla_{\theta} J(\theta)$$
 
$$\alpha = \text{step size or learning rate}$$

Figure 1.2.1 Formula of Gradient Descent

#### While:

 $\theta$ : Parameters of the model.

 $J(\theta)$ : The cost function (or loss function) that we want to minimize.

a: Learning rate.

#### 1.2.2 Stochastic Gradient Descent

Definition: Stochastic Gradient Descent is a variant of gradient descent where
the model parameters are updated after each training example. Unlike batch
gradient descent, which processes the entire dataset for each parameter update,
SGD is faster but introduces more noise due to its reliance on individual data
points.

#### • Formula:

$$heta^{new} = heta^{old} - lpha 
abla_{ heta} J( heta)$$
  $lpha$  = step size or learning rate

Figure 1.2.2 Formula of Stochastic Gradient Descent

#### While:

 $\theta$ : Parameters of the model.

 $J(\theta)$ : The cost function (or loss function) that we want to minimize.

a: Learning rate.

#### 1.2.3 Momentum

- Definition: Momentum is an optimization technique that enhances gradient
  descent by adding a momentum term. It helps accelerate the convergence by
  considering the past gradients and smoothing out the updates. This helps to
  overcome oscillations and converge faster, especially in the presence of noisy
  or sparse gradients.
- Formula:

$$V_{t=\gamma}V_{t-1}+\eta\nabla J(W_{t})$$
 $W_{t=\omega_{t-1}-v_{t}}$ 

Figure 1.2.3 Formula of momentum

#### While:

 $W_t$  represents the parameters of the model.

 $\alpha$  is the learning rate.

 $\beta$  is the momentum parameter (a hyperparameter typically set between 0 and 1). v is the velocity vector that accumulates the gradients over time.

 $\nabla J(W_t)$  is the gradient of the cost function with respect to the parameters.

#### 1.2.4 Adam

- **Definition:** Adam is an adaptive optimization algorithm that combines ideas from both momentum and RMSprop. It maintains moving averages of the gradients and squared gradients for each parameter. The algorithm adapts the learning rates for each parameter based on their past gradients and squared gradients, providing robust performance across different types of data and architectures.
- Formula:

$$\mathbf{g}_{n} \leftarrow \nabla f(\boldsymbol{\theta}_{n-1}) 
\mathbf{m}_{n} \leftarrow (\beta_{1}/(1-\beta_{1}^{n})) \mathbf{m}_{n-1} + ((1-\beta_{1})/(1-\beta_{1}^{n})) \mathbf{g}_{n} 
\mathbf{v}_{n} \leftarrow (\beta_{2}/(1-\beta_{2}^{n})) \mathbf{v}_{n-1} + ((1-\beta_{2})/(1-\beta_{2}^{n})) \mathbf{g}_{n} \odot \mathbf{g}_{n} 
\boldsymbol{\theta}_{n} \leftarrow \boldsymbol{\theta}_{n-1} - a \mathbf{m}_{n}/(\sqrt{\mathbf{v}_{n}} + \epsilon),$$

Figure 1.2.4 Formula of Adam

### **1.2.5 Adagrad**

• **Definition:** Adagrad is an optimization algorithm that adapts the learning rates for each parameter based on the historical gradient information. It individually scales the learning rates for each parameter, giving larger updates to parameters with smaller gradients and vice versa. While this can be beneficial for sparsely occurring features, it may lead to overly aggressive updates and a diminishing learning rate over time.

• Formula:

$$\theta_{t+1} = \theta_t - \frac{\eta}{\sqrt{G_t + \epsilon}} \odot g_t$$

Figure 1.2.5 Formula of Adagrad

While:

n is a constant.

 $g_t$  is the gradient at time t.

 $\epsilon$  is an error avoidance coefficient (used to avoid division by zero).

G is a diagonal matrix where each element on the diagonal is the square of the partial derivative of the parameter vector at time t.

#### 1.2.6 Root means square propagation

- Definition: RMSprop is an optimization algorithm that addresses the
  diminishing learning rate problem of Adagrad. It uses a moving average of
  squared gradients to normalize the learning rates. This helps to prevent the
  learning rates from becoming too small, allowing the algorithm to converge
  faster, especially in non-convex optimization problems.
- Formula:

$$E[g^2]_t = 0.9E[g^2]_{t-1} + 0.1g_t^2$$
  $heta_{t+1} = heta_t - rac{\eta}{\sqrt{E[g^2]_t + \epsilon}}g_t$ 

Figure 1.2.6 Formula of RMSprop

# 1.3 Comparison between these method

Table 1.3.1 Advantages and Disadvantages of these methods

Algorithms	Advantages	Disadvantages
GD	- Simple and easy to implement.	<ul><li>Computationally expensive for large datasets</li><li>May get stuck in local minima.</li></ul>
SGD	<ul><li>- Faster convergence for large datasets</li><li>- Less memory requirements.</li></ul>	-High variance in parameter updates, leading to noisy convergence May oscillate.
Momentum	<ul> <li>- Accelerates</li> <li>convergence, especially</li> <li>in the presence of</li> <li>oscillations.</li> <li>- Helps overcome saddle</li> <li>points.</li> </ul>	<ul><li>Requires tuning of the momentum parameter</li><li>May overshoot the minimum.</li></ul>
Adam	<ul> <li>Combines benefits of momentum and RMSprop.</li> <li>Adaptive learning rates for each parameter</li> <li>Robust performance.</li> </ul>	<ul><li>Requires tuning of hyperparameters</li><li>Computational complexity.</li></ul>

Adagrad	<ul><li>Adaptive learning rates</li><li>for each parameter</li><li>Effective for sparse</li><li>data.</li></ul>	<ul> <li>Cumulative sum of squared gradients may lead to diminishing learning rates.</li> <li>May not perform well on non-convex problems.</li> </ul>
RMSprop	<ul><li>Addresses diminishing</li><li>learning rates in Adagrad.</li><li>Adaptively scales</li><li>learning rates for each</li><li>parameter.</li></ul>	<ul><li>Requires tuning of hyperparameters.</li><li>May not perform well with high-dimensional parameter spaces.</li></ul>

# 1.4 Application

## • Machine Learning and Deep Learning:

**Application:** Training neural networks for image recognition, natural language processing, and other machine learning tasks.

**Optimization Method:** Adam, SGD, RMSprop, and their variants are commonly used to optimize the parameters of deep learning models.

#### • Natural Language Processing (NLP):

**Application:** Language translation, sentiment analysis, and chatbots.

**Optimization Method:** Adam and SGD are often employed to optimize models in NLP applications.

#### • Computer Vision:

**Application:** Object detection, facial recognition, and image segmentation.

**Optimization Method:** Adam and SGD are frequently used for optimizing convolutional neural networks (CNNs) in computer vision tasks.

#### • Recommendation Systems:

**Application:** Personalized content recommendations in platforms like Netflix and Amazon.

**Optimization Method:** SGD and variants are used to optimize collaborative filtering models in recommendation systems.

### • Financial Modeling:

**Application:** Predictive modeling for stock prices, risk assessment, and algorithmic trading.

**Optimization Method:** Various optimization algorithms, including Gradient Descent, are used to optimize financial models.

#### • Healthcare:

**Application:** Disease prediction, medical image analysis, and drug discovery.

**Optimization Method**: Gradient Descent and its variants (e.g., Adam, RMSprop): Used in training machine learning models for disease prediction, medical image analysis, and drug discovery.

#### • Operations Research:

**Application:** Supply chain optimization, logistics planning, and resource allocation.

**Optimization Method:** Gradient Descent and variants are applied to optimize objective functions in operations research problems.

#### 1.5 Continual Learning

• **Definition**: In computer science, incremental learning is a method of machine learning in which input data is continuously used to extend the existing model's knowledge i.e. to further train the model. It represents a dynamic

technique of supervised learning and unsupervised learning that can be applied when training data becomes available gradually over time or its size is out of system memory limits. Algorithms that can facilitate incremental learning are known as incremental machine learning algorithms.

#### • How it works?

Continual Learning is an approach in machine learning that enables models to learn from a continuous stream of data or tasks, sequentially over time. It addresses scenarios where new information arrives, and the model needs to adapt without forgetting previously learned knowledge.

#### **Sequential Learning:**

Continual learning involves learning tasks or concepts sequentially, one after another, rather than in a batch setting. This is particularly relevant in dynamic environments where new data becomes available over time.

#### **Retaining Knowledge:**

Models trained through continual learning should be able to retain knowledge learned from previous tasks while adapting to new information. This is crucial to prevent catastrophic forgetting, where the model forgets previously learned patterns when exposed to new data.

#### **Adaptability:**

Continual learning models need to adapt to changing data distributions and be flexible enough to incorporate knowledge from new tasks without significantly degrading performance on previous tasks.

#### **Resource Efficiency:**

In real-world scenarios, resources such as memory and computation are often limited. Continual learning models aim to efficiently use these resources while accommodating new knowledge.

#### **Transfer Learning:**

Transfer learning plays a significant role in continual learning. Knowledge gained from solving one task can be beneficial for solving related tasks, promoting knowledge transfer and reuse.

#### **Task Boundaries:**

Identifying task boundaries is crucial in continual learning to manage transitions between tasks. The model needs to recognize when a new task is introduced and adjust its parameters accordingly.

#### • Pros and Cons

Table 1.5.1 Pros and Cons of Continual Learning

Pros	Cons
Adaptability	Catastrophic Forgetting
- Continual Learning models	There is a risk of catastrophic
can adapt to changing data	forgetting, where the model may
distributions and evolving	lose knowledge from earlier tasks
tasks	when learning new ones.
Resource Efficiency	Task Interference
Models can efficiently use	Interference between tasks can
resources by updating	occur, where learning a new task
parameters selectively,	affects the performance on
avoiding the need for	previous tasks.
retraining on the entire dataset.	
Long-Term Knowledge	<b>Increased Complexity</b>
Retention	Implementing continual learning
Models can retain knowledge	systems can be more complex
from earlier tasks, preventing	

degradation of performance on	compared to traditional static	
previously learned tasks.	learning.	
Flexibility	Hyperparameter Tuning	
Well-designed continual	Tuning hyperparameters for	
learning systems are flexible	continual learning models can be	
and capable of handling a	challenging and requires careful	
variety of tasks over time.	consideration.	
* Application: Robotics, Autonomous Vehicles, Natural		
Language Processing, Computer Vision, Healthcare,		
Financial Modeling		

### 1.6 Test production

Test production is a crucial part of the machine learning solution-building process. It is often conducted after the model has been trained to evaluate the model's performance on new data not used during training.

#### **How it Works?**

#### **Model Quality:**

Test production helps assess the quality and performance of the model on real-world data, providing information about the overall capabilities of the model.

#### **Error Detection and Improvement:**

If the model does not perform accurately on new data, test production helps detect errors and provides an opportunity to improve the model.

#### **Biased Data and Adjustment Management:**

Test production can help identify issues related to biased or non-representational data and manage the process of model adjustment.

# **Continuous Testing:**

Continuous testing can be deployed to ensure that the model maintains high performance after each update or when new data is introduced.

# **Performance Management:**

Test production provides insights into the model's performance in a production environment, helping manage performance and respond quickly to changes.

# **REFERENCES**

#### Vietnamese:

- 1. https://viblo.asia/p/optimizer-hieu-sau-ve-cac-thuat-toan-toi-uu-gdsgdadam-Qbq5QQ9E5D8
- 2. https://machinelearningcoban.com/2017/01/12/gradientdescent/
- 3. https://ndquy.github.io/posts/gradient-descent-2/

## **English**

- 1. TDTU Slides
- 2. https://www.youtube.com/watch?v=nra0Tt3a-Oc&t=98s
- 3. https://www.youtube.com/watch?v=vjaq03IYgSk