

Automatic Image Colorization

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Team #8
EEE 511 Final Project



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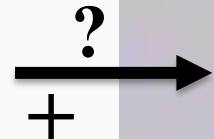
Introduction

Challenge

Specific objects can take on many different valid and “good” colors



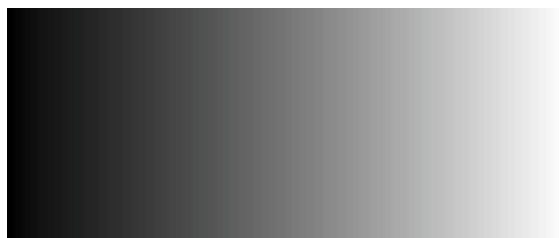
Luminance, L



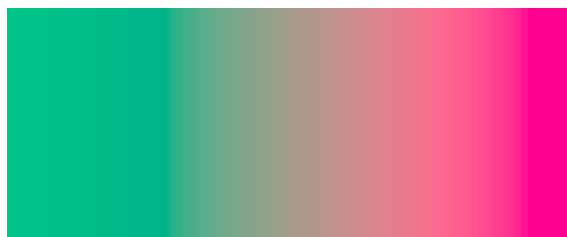
GB)

“L-ab” Color space

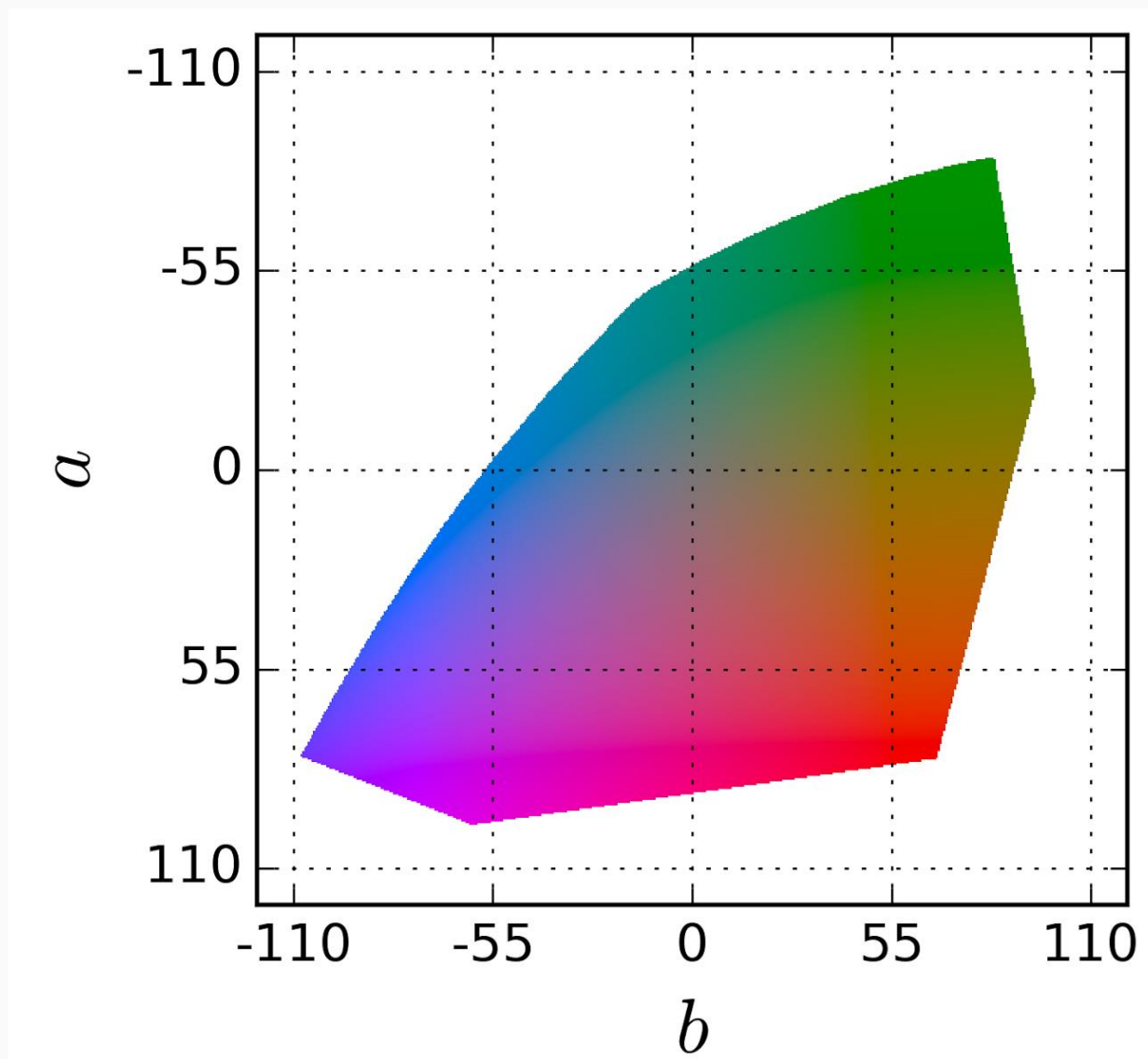
L channel



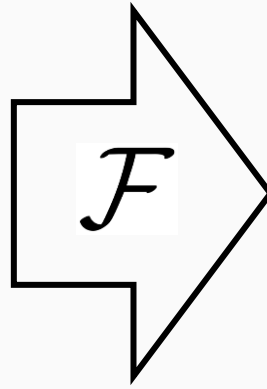
a channel



b channel



Problem Description

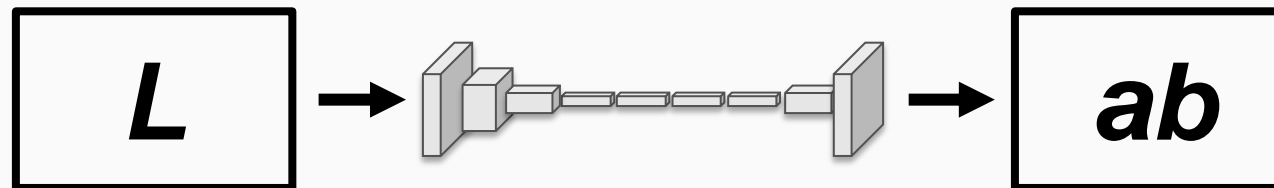


Grayscale image: L channel

$$\mathbf{X} \in \mathbb{R}^{H \times W \times 1}$$

Color information: ab channels

$$\hat{\mathbf{Y}} \in \mathbb{R}^{H \times W \times 2}$$

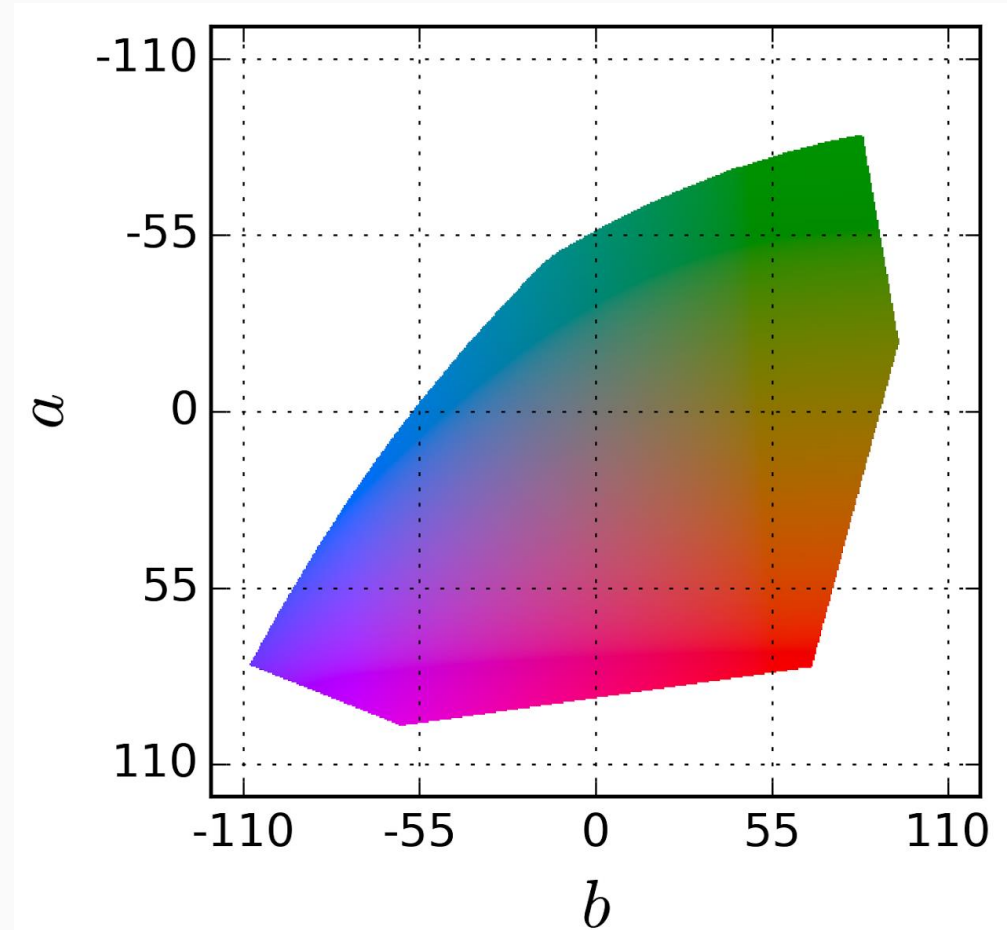


Loss Function

- Learning a mapping function \mathcal{F} which predicts $\hat{\mathbf{Y}}$
- Loss Function:

$$L_2(\hat{\mathbf{Y}}, \mathbf{Y}) = \frac{1}{2} \sum_{h,w} \|\mathbf{Y}_{h,w} - \hat{\mathbf{Y}}_{h,w}\|_2^2$$

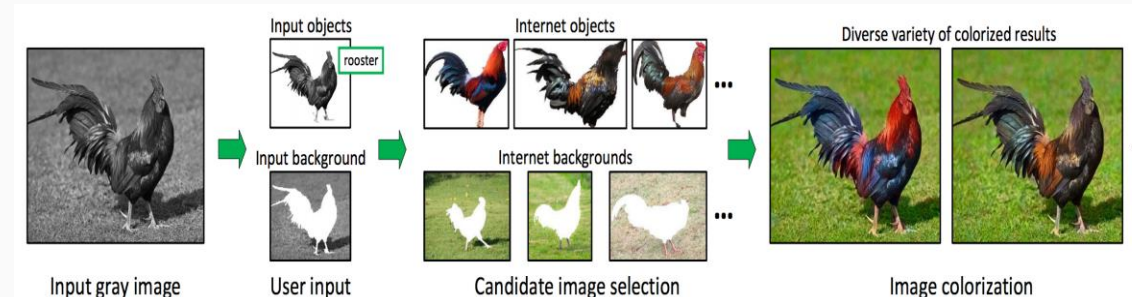
$$\hat{\mathbf{Y}} \in \mathbb{R}^{H \times W \times 2}$$



Methods

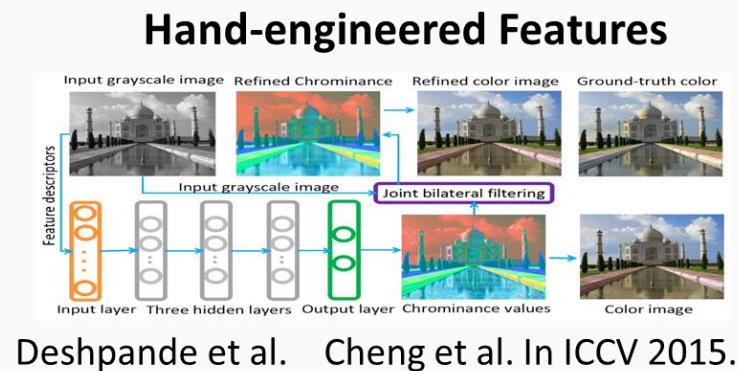
Non-
parametric

Hertzmann et al. In SIGGRAPH, 2001.
Welsh et al. In TOG, 2002.
Irony et al. In Eurographics, 2005.
Liu et al. In TOG, 2008.
Chia et al. In ACM 2011.
Gupta et al. In ACM, 2012.

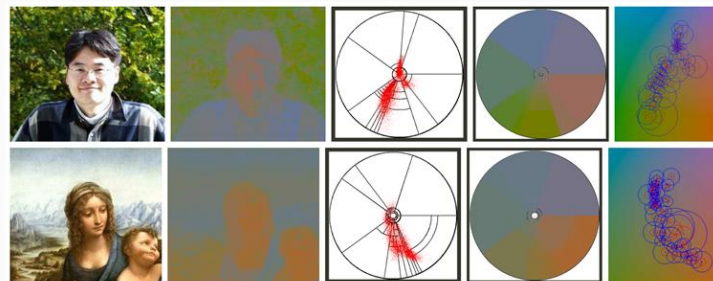


Parametric

L2 Regression

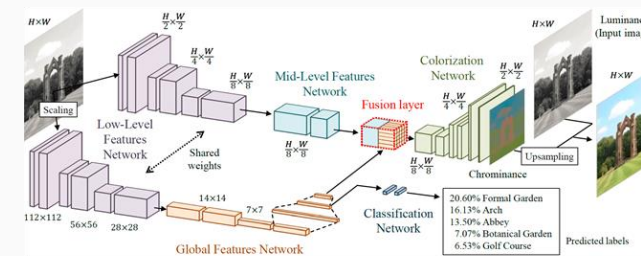


Classification

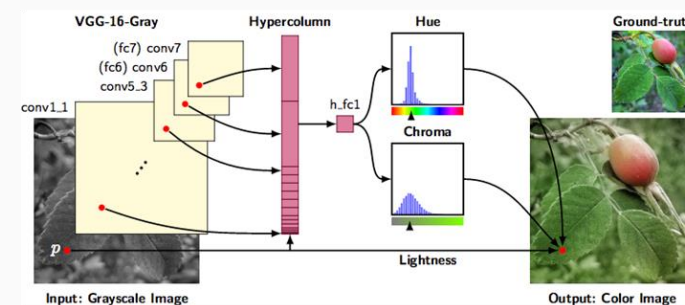


Charpiat et al. In ECCV 2008.

Deep Networks



Dahl, Jan 2016. Iizuka et al. In SIGGRAPH, 2016.



Larsson et al. In ECCV 2016.

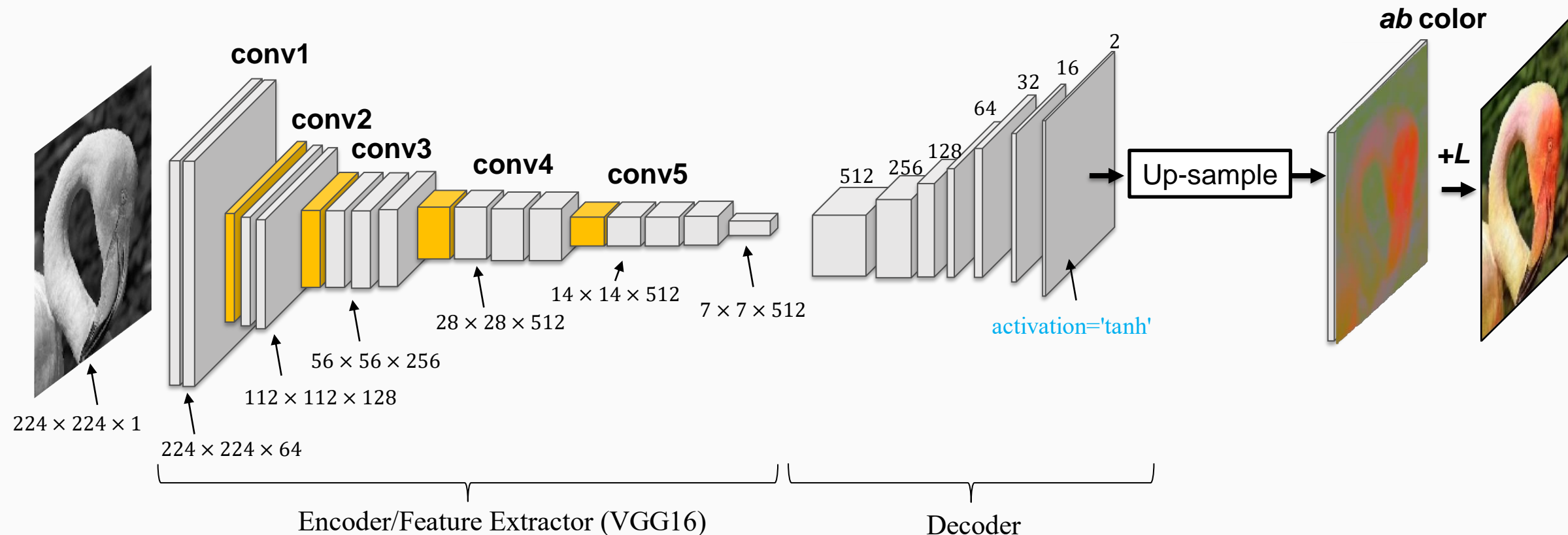
Framework/Model Summary

Data Preprocessing
`lab = rgb2lab(image)`
`L = lab[:, :, 0]`

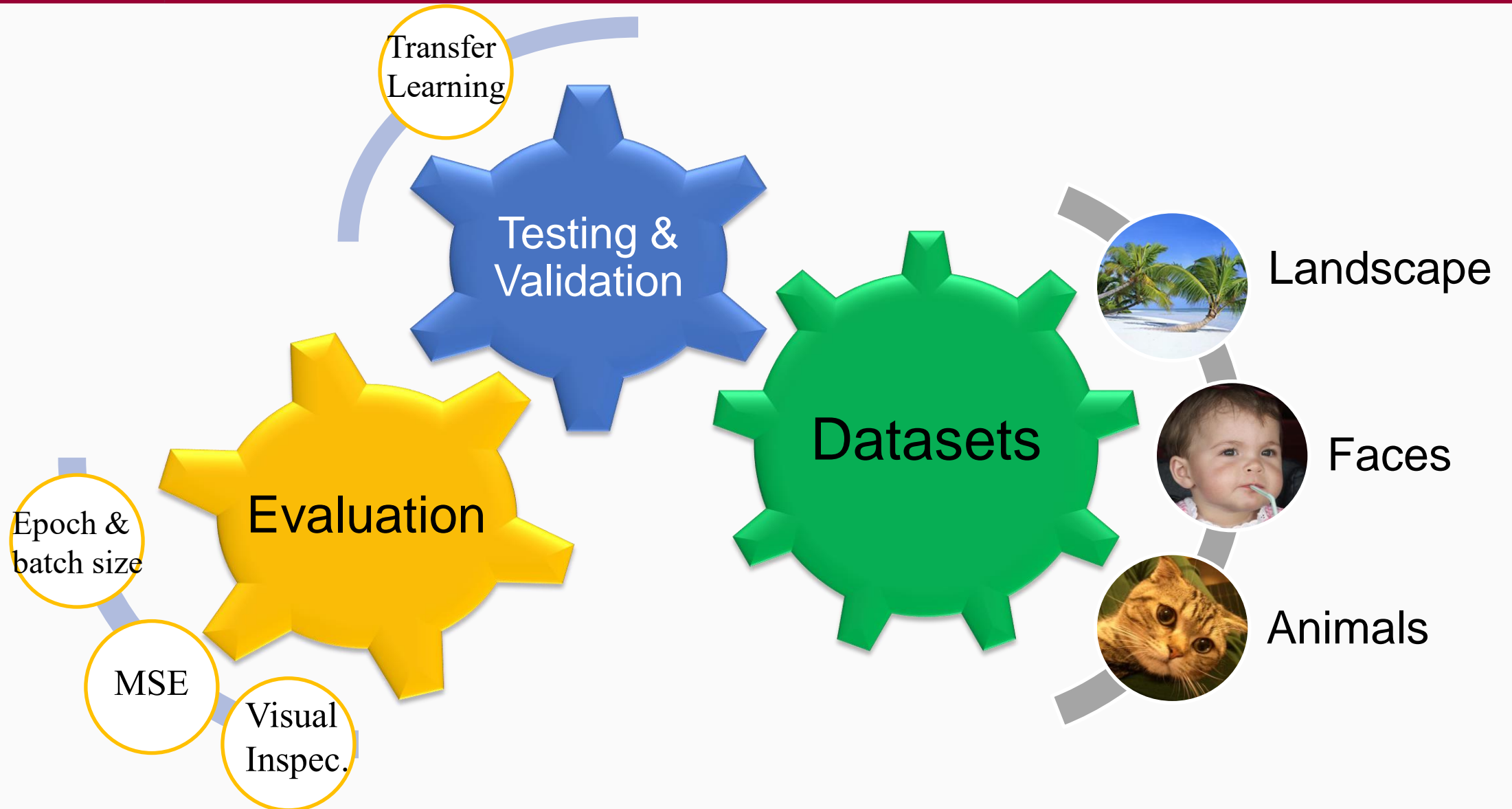
Feature Extraction
`keras.applications.vgg16.VGG16()`
`vggpred = newmodel.predict(L)`

Selecting *ab* based on Feature learned
`tf.keras.layers.Conv2D`
`ab = model.predict(vggpred)`

Up-scaling and combining all channels
`temp = np.zeros((224, 224, 3))`
`temp[:, :, 0] = L`
`temp[:, :, 1:] = ab`
`out = lab2rgb(temp)`



Evaluation



Results and Discussion

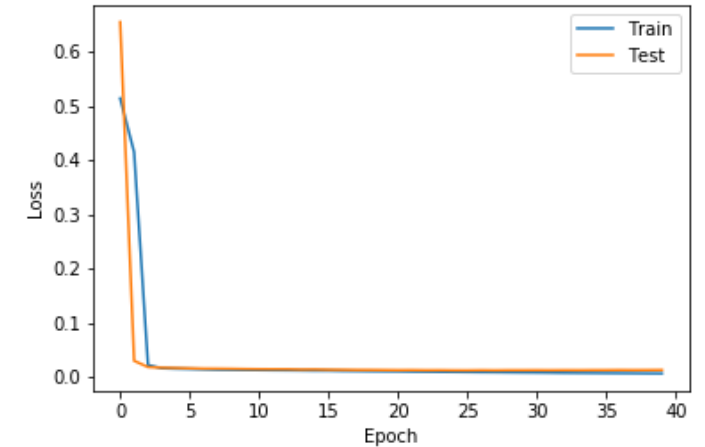


Grayscale

Ground Truth

Output Image

- Image Quality reduction
 - Down sampling
 - Dimensionality reduction
- Training set of **Landscape** images (924 images)



MSE loss during each epoch with
10% validation test set

Results and Discussion Cont.

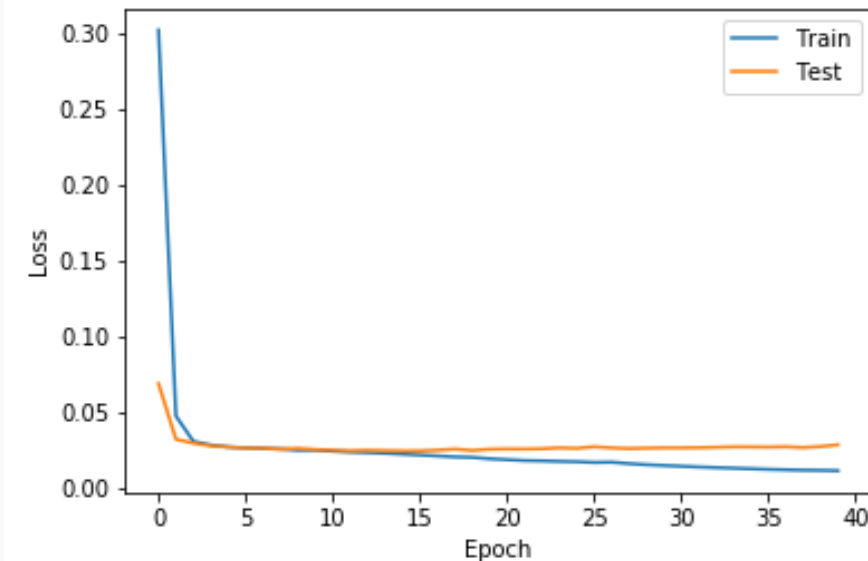


Input

Ground Truth

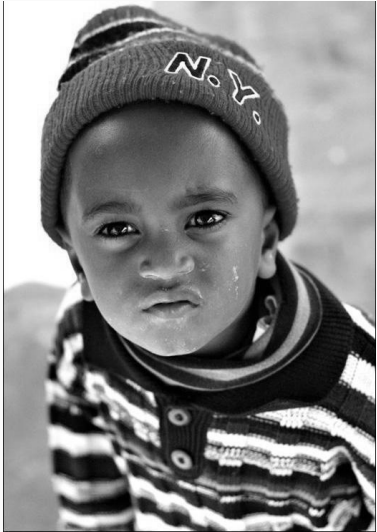
Output Image

- Image Quality reduction
 - Down sampling
 - Dimensionality reduction
- Training set of **Animal** images (539 images)



MSE loss during each epoch with
10% validation test set

Results and Discussion Cont.

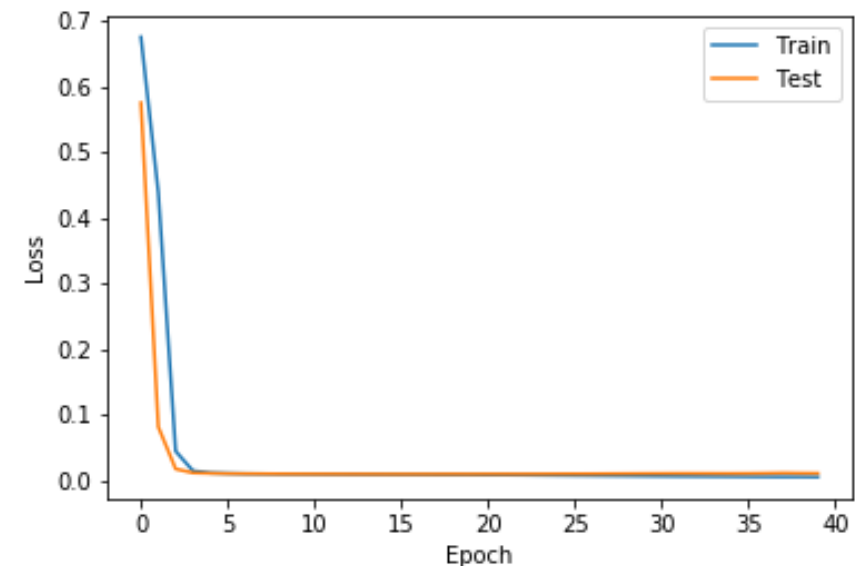


Input

Ground Truth

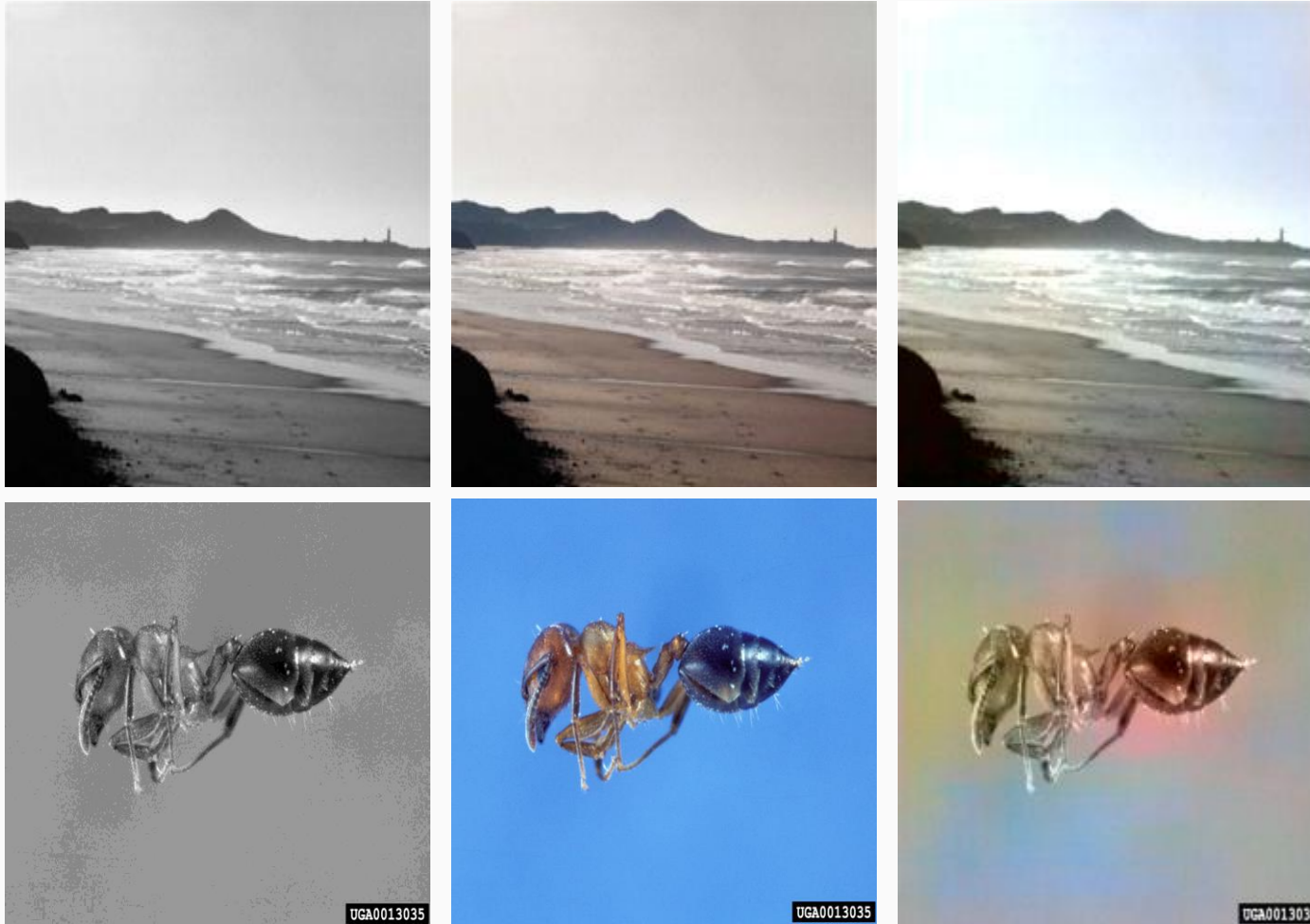
Output Image

- Image Quality reduction
 - Down sampling
 - Dimensionality reduction
- Training set of **Faces** images (996 images)



MSE loss during each epoch with
10% validation test set

Results and Discussion Cont.

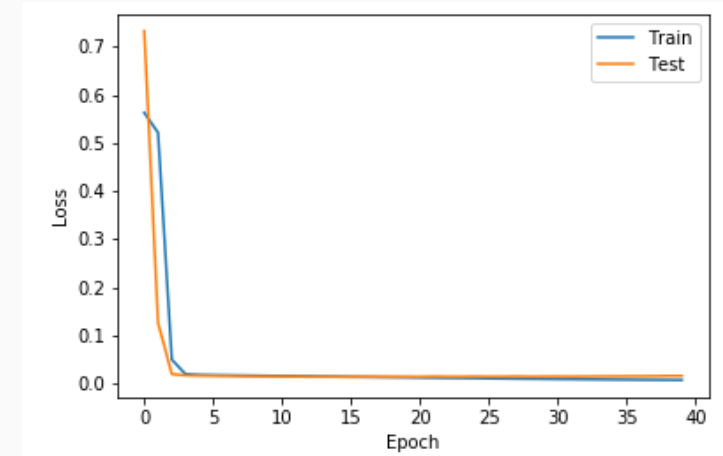


Input

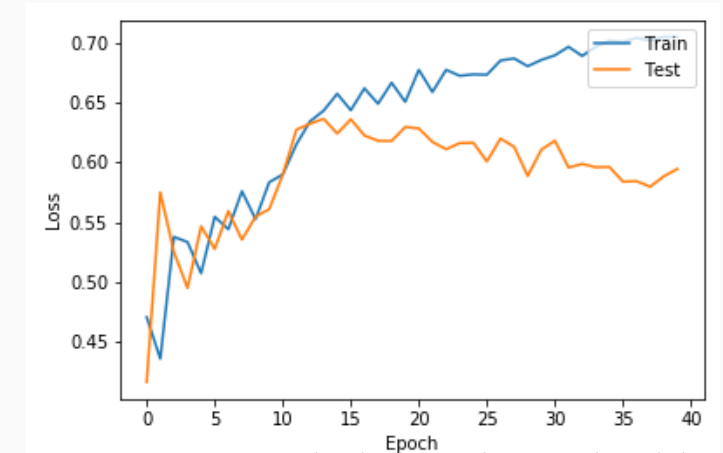
Ground Truth

Output Image

- Training set of **All** images (2500 images)



MSE loss during each epoch with 10% validation test set



Accuracy during each epoch with 10% validation test set

Limitations and Challenges

- The main limitation is the test set given
 - Larger and more diverse set → better feature extractor → better results in determining *ab* spaces
 - Model can learn “too” well (overfit) data set
 - Skin tone foreground color on background objects (e.g., sky, blue background)
- VGG16 pretrained on RGB images
- Two color channel (Lab) estimation lowers performance overhead but reduces vibrancy of output
- Longer training time does not necessary corresponds to better results
 - Accuracy drops under validation set
- Quality and performance
 - Inverse relationship trade-off

Conclusions and Recommendations

- Image colorization using CNN with auto encoder
- Trained using Keras with TensorFlow backend
- Different test cases and conditions are evaluated
 - Animal
 - Faces
 - Landscapes
- Evaluation based on subjective user inspection and MSE and accuracy quantification
- Only maximum of 2500 images were used
 - Typically, need around 50K images for reasonable colorization
 - Model underperformed in some images given as input
 - More testing and training
 - Using custom encoder with training instead of VGG16 feature extractor

Thank you

Questions and Suggestions!