

TEMPEST sniffing monitor

KAIR neural network to denoise image

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Electromagnetic emanations

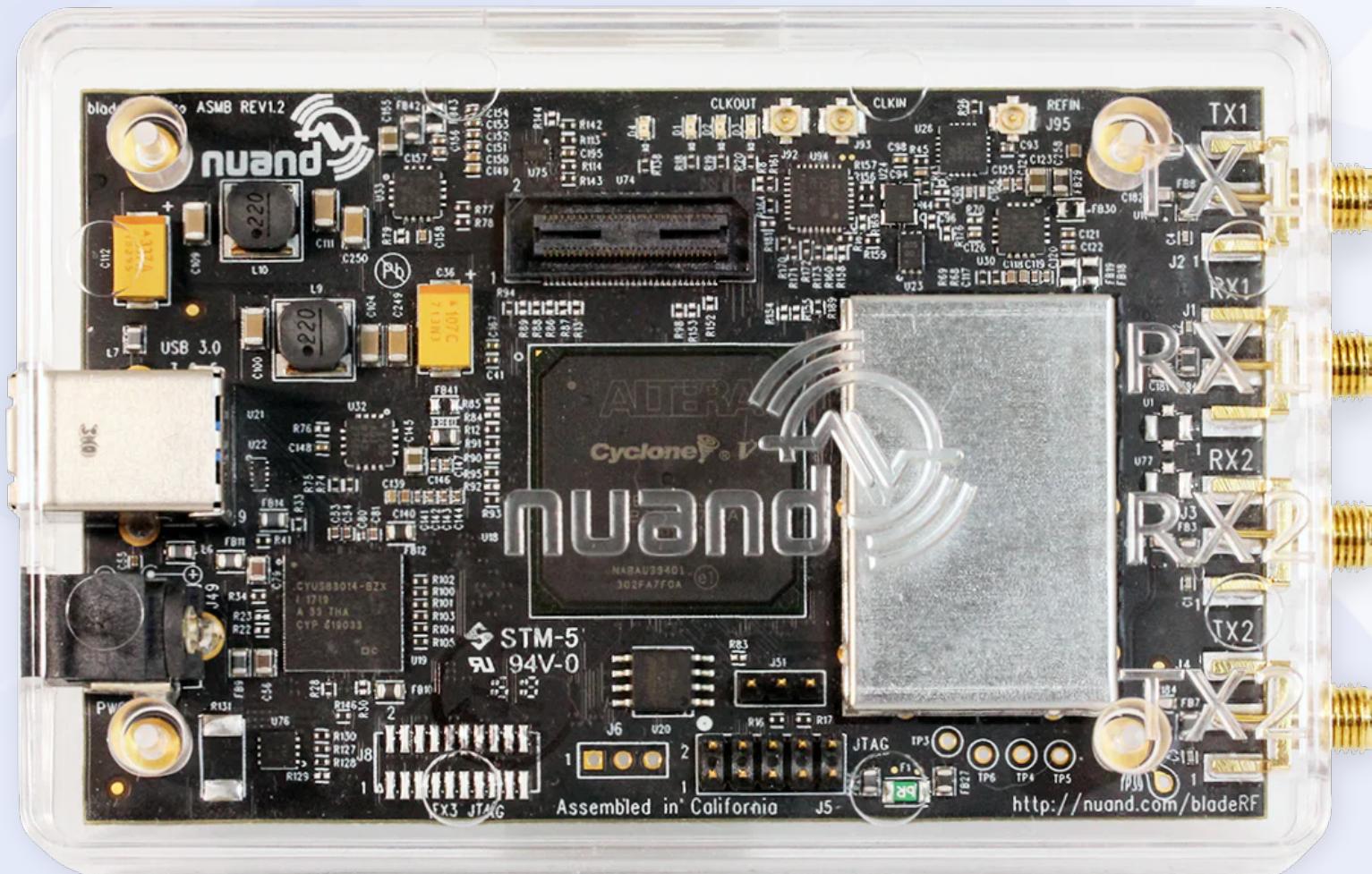
- all time-varying voltage and current interfaces emit electromagnetic waves
 - chips, cables, all PCB traces act as transmitter antennas
 - signal can be -50 dBm or lower (less than 0.01 μ W), even -130 dBm workable
 - current off-the-shelf SDRs can capture it, generally have $>=90$ dB dynamic range
 - e.g. BladeRF, USRP B210, H-field probe

NESTOR - Vietnam war, ~1969

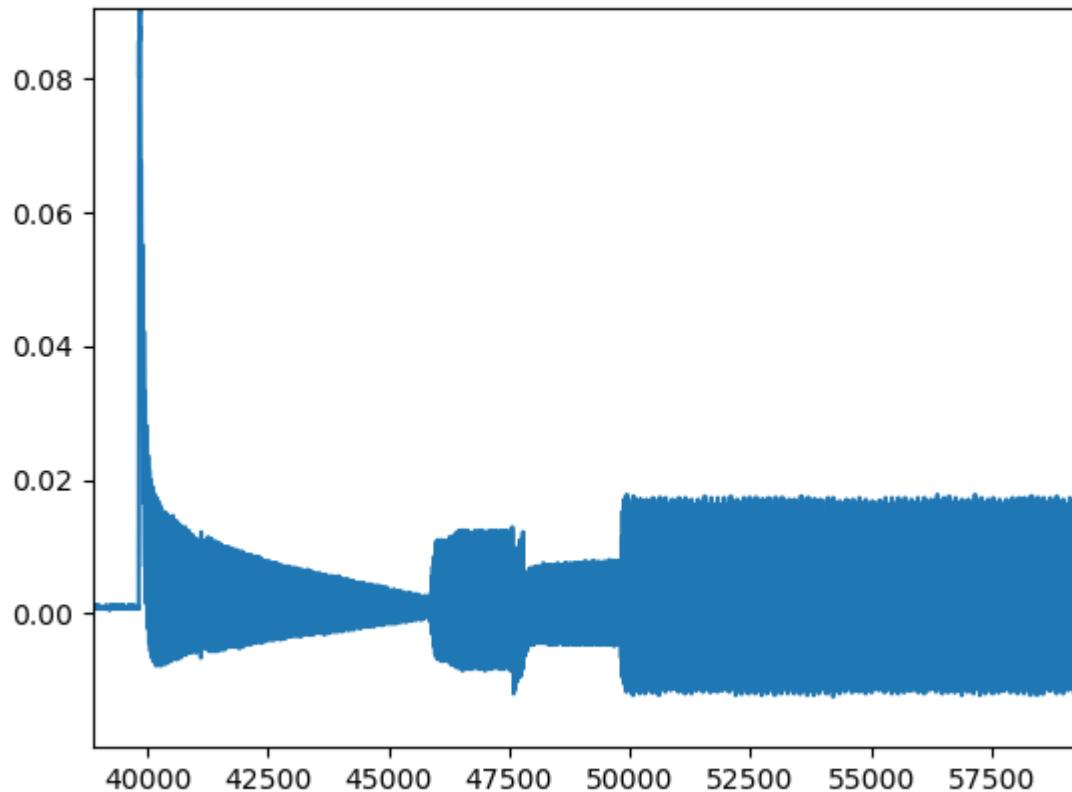


Had to be opened in the heat & humidity in Vietnam thus leaked plaintext voice in FM

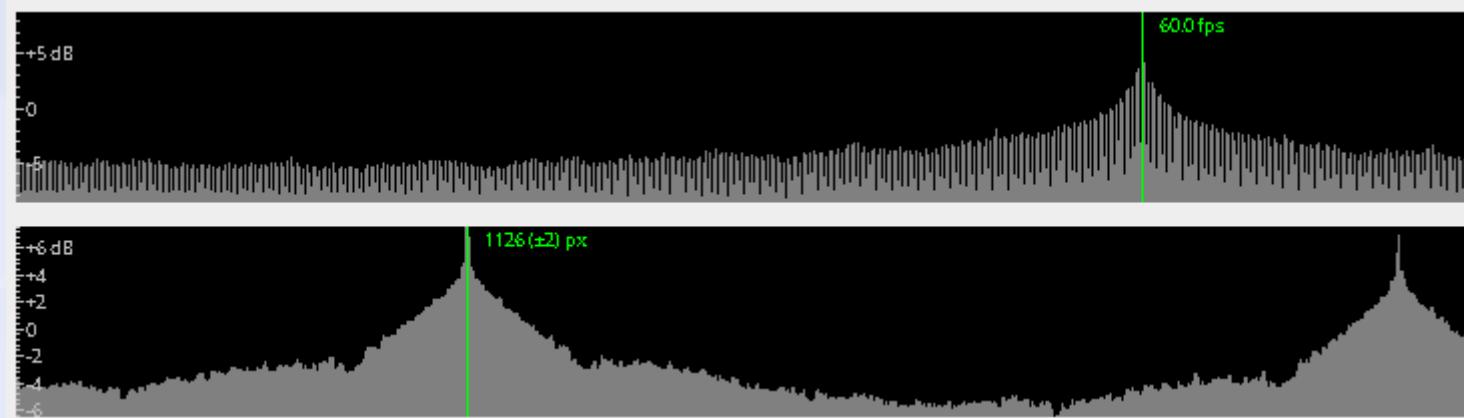
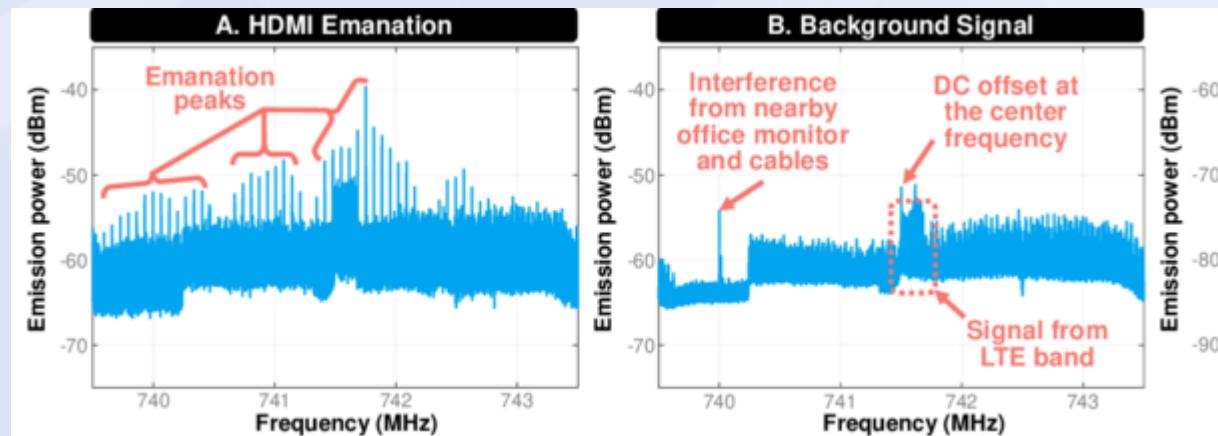
SDR used – bladeRF 2.0 xA4



Sample EM trace of ARM chip



HDMI emanation & interference

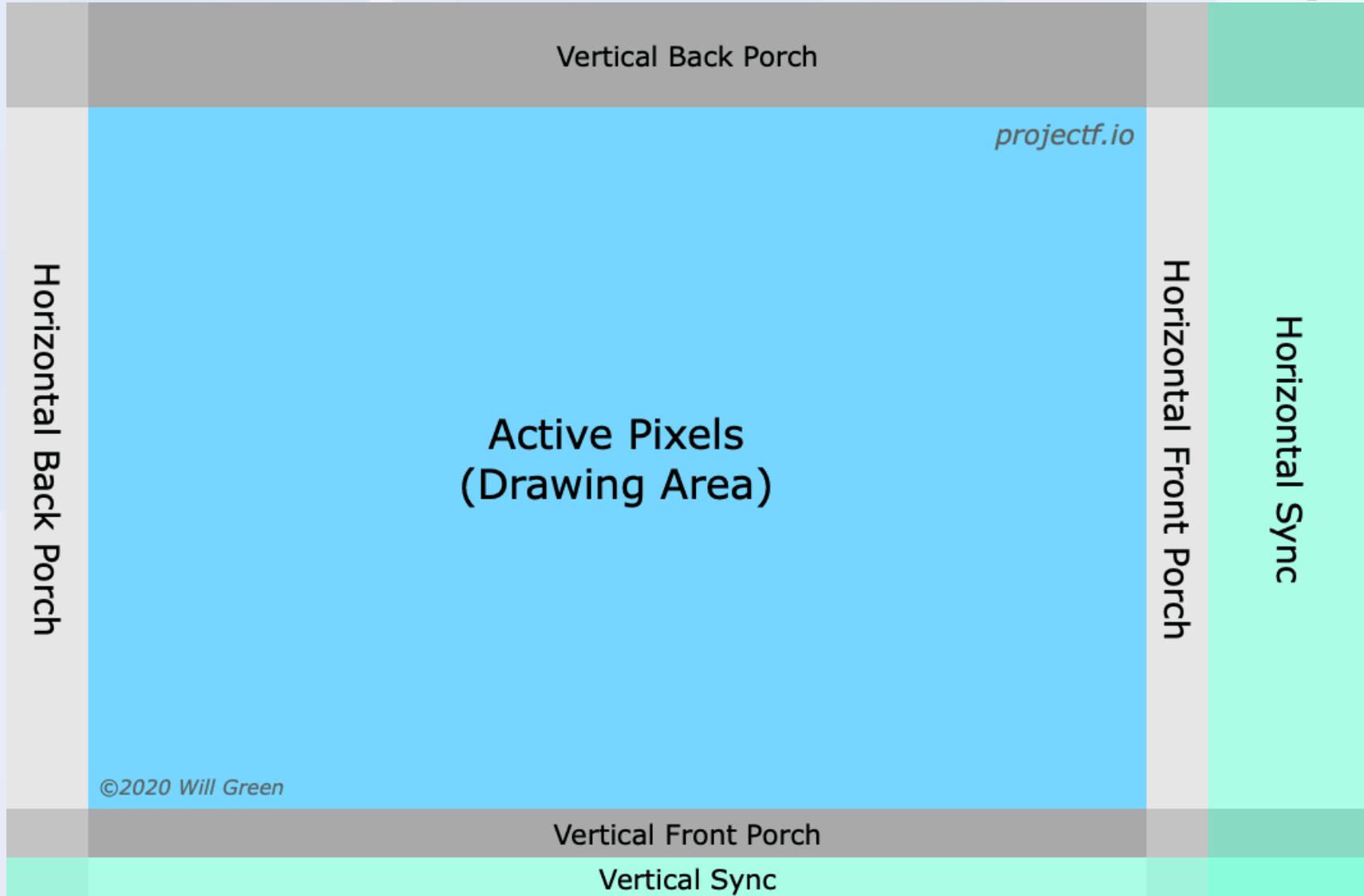


Why around 740 MHz? 742.5 is 5th harmonic frequency of 148.5 MHz pixel clock of one of 1920x1980, most commonly used videomodes.

VGA/HDMI/DisplayPort/USB-C

- VGA is trivial to sniff, analog
- HDMI & LVDS (LVDS is used in notebooks) have differential signalling, but still sniffeable
- DisplayPort is differential signalling, but with some PRNG to not make it so easy, can be partially filtered out, but with loss
- USB-C is network that encapsulates DisplayPort – hard to catch pixelclock

Front/back porch/pixelclock (1)



Front/back porch/pixelclock (2)

Resolution alone does not give horizontal/vertical or pixelclock timings, depends on display and other things

1920x1080 (0xa8) 148.500MHz +HSync +VSync			
h: width 1920 start 2008 end 2052 total 2200 skew	0	clock 67.50KHz	
v: height 1080 start 1084 end 1089 total 1125		clock 60.00Hz	
1920x1080 (0xa9) 148.500MHz +HSync +VSync			
h: width 1920 start 2448 end 2492 total 2640 skew	0	clock 56.25KHz	
v: height 1080 start 1084 end 1089 total 1125		clock 50.00Hz	
1920x1080 (0xaa) 148.352MHz +HSync +VSync			
h: width 1920 start 2008 end 2052 total 2200 skew	0	clock 67.43KHz	
v: height 1080 start 1084 end 1089 total 1125		clock 59.94Hz	
1920x1080i (0xab) 74.250MHz +HSync +VSync Interlace			
h: width 1920 start 2008 end 2052 total 2200 skew	0	clock 33.75KHz	
v: height 1080 start 1084 end 1094 total 1125		clock 60.00Hz	
1920x1080i (0xac) 74.250MHz +HSync +VSync Interlace			
h: width 1920 start 2448 end 2492 total 2640 skew	0	clock 28.12KHz	
v: height 1080 start 1084 end 1094 total 1125		clock 50.00Hz	
1920x1080 (0xad) 74.250MHz +HSync +VSync			
h: width 1920 start 2558 end 2602 total 2750 skew	0	clock 27.00KHz	
v: height 1080 start 1084 end 1089 total 1125		clock 24.00Hz	
1920x1080i (0xae) 74.176MHz +HSync +VSync Interlace			
h: width 1920 start 2008 end 2052 total 2200 skew	0	clock 33.72KHz	
v: height 1080 start 1084 end 1094 total 1125		clock 59.94Hz	
1920x1080 (0xaf) 74.176MHz +HSync +VSync			
h: width 1920 start 2558 end 2602 total 2750 skew	0	clock 26.97KHz	
v: height 1080 start 1084 end 1089 total 1125		clock 23.98Hz	

Front/back porch/pixelclock (3)

- pixelclock in MHz gives you timing for whole image, all these values neeed to be correct
- horizontal and vertical pixels are needed to make sense of the signal
- I found 5th harmonic frequency of pixelclock works best for me
 - e.g. pixelclock of 148.5 MHz has 3rd harmonic 445.5 MHz and 5th 742.5 MHz

Antennas, filters & amplifiers

- better antennas and filters result in better images, i.e. better specify what is sniffed
- used omnidirectional antennas, also log-periodic (log-periodic is better)



log-periodic antenna
(stock depleted now!)



3-band LTE omnidirectional antennas
Taoglas has 82-page datasheet, best datasheet

other
3-band
LTE for
sniffing
LTE data,
not much
monitors
(omni,
noisy)

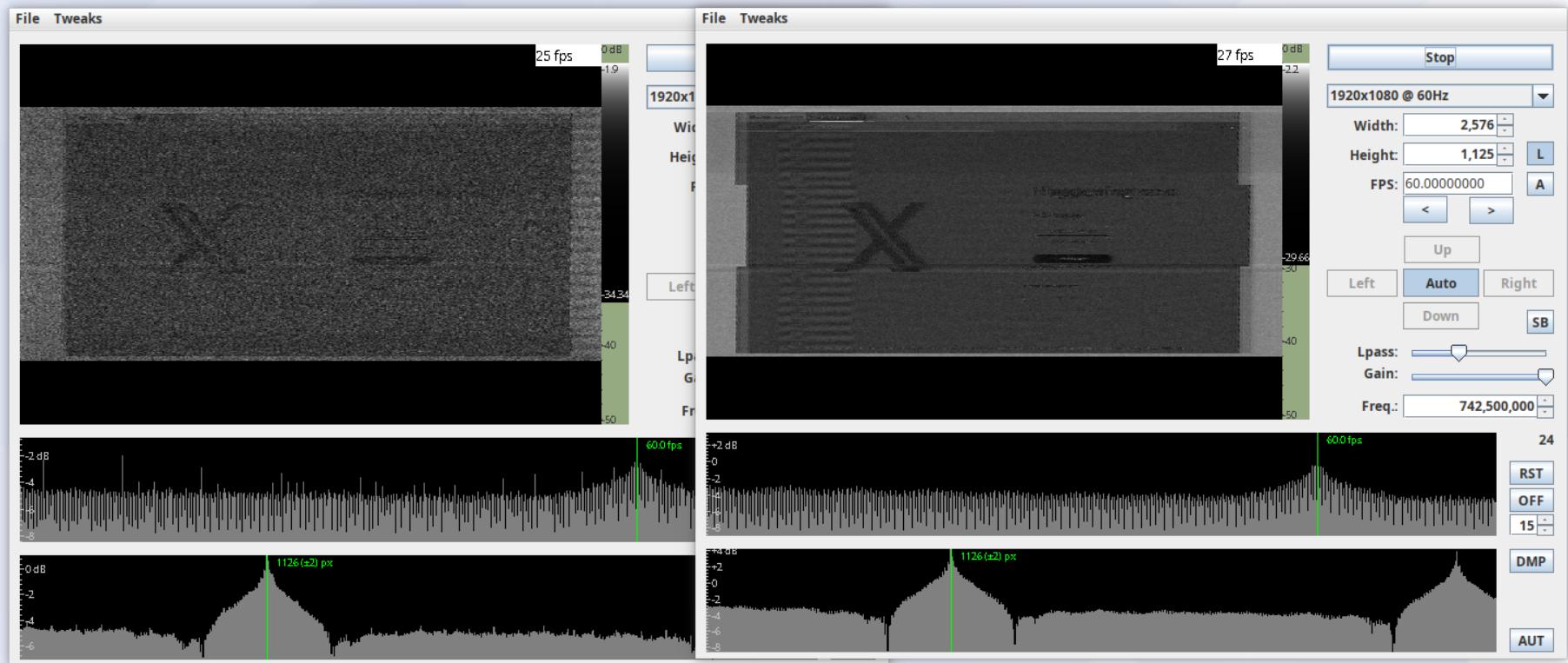


Used cheap TV log-periodic

- it's tuned to 75Ω impedance
- rest of SDR is tuned to 50Ω impedance
- impedance mismatch causes VSWR 1.5:1
but still better than omni 3band Taoglas
- less noisy (50Ω tuned w/SMA costs more)
- avoid signal filter
- could be lot better
- 800 CZK w/F-SMA



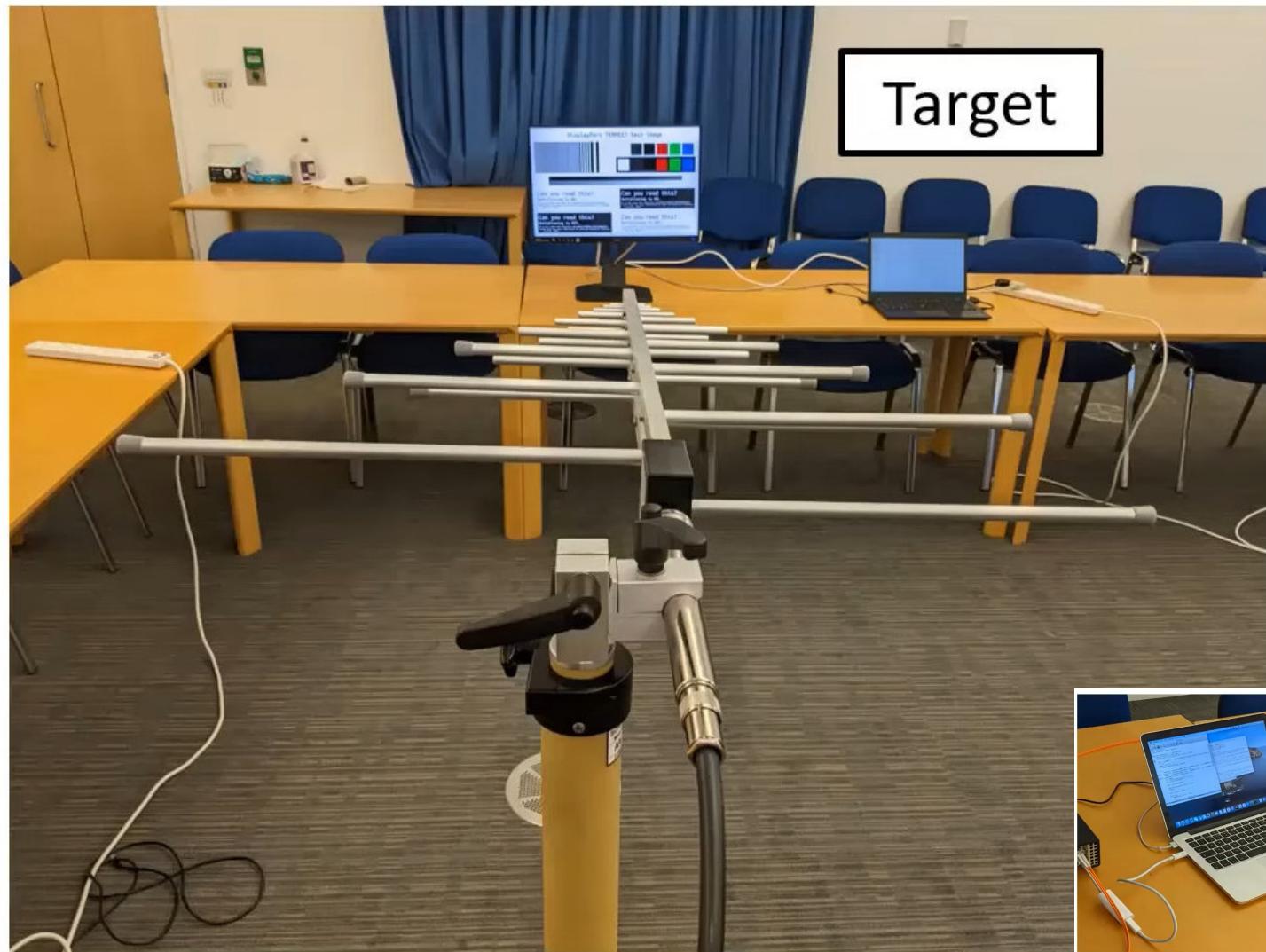
Bad day omni vs log-periodic



Bad placement for omni, omni antenna picks up more noise from every direction cca

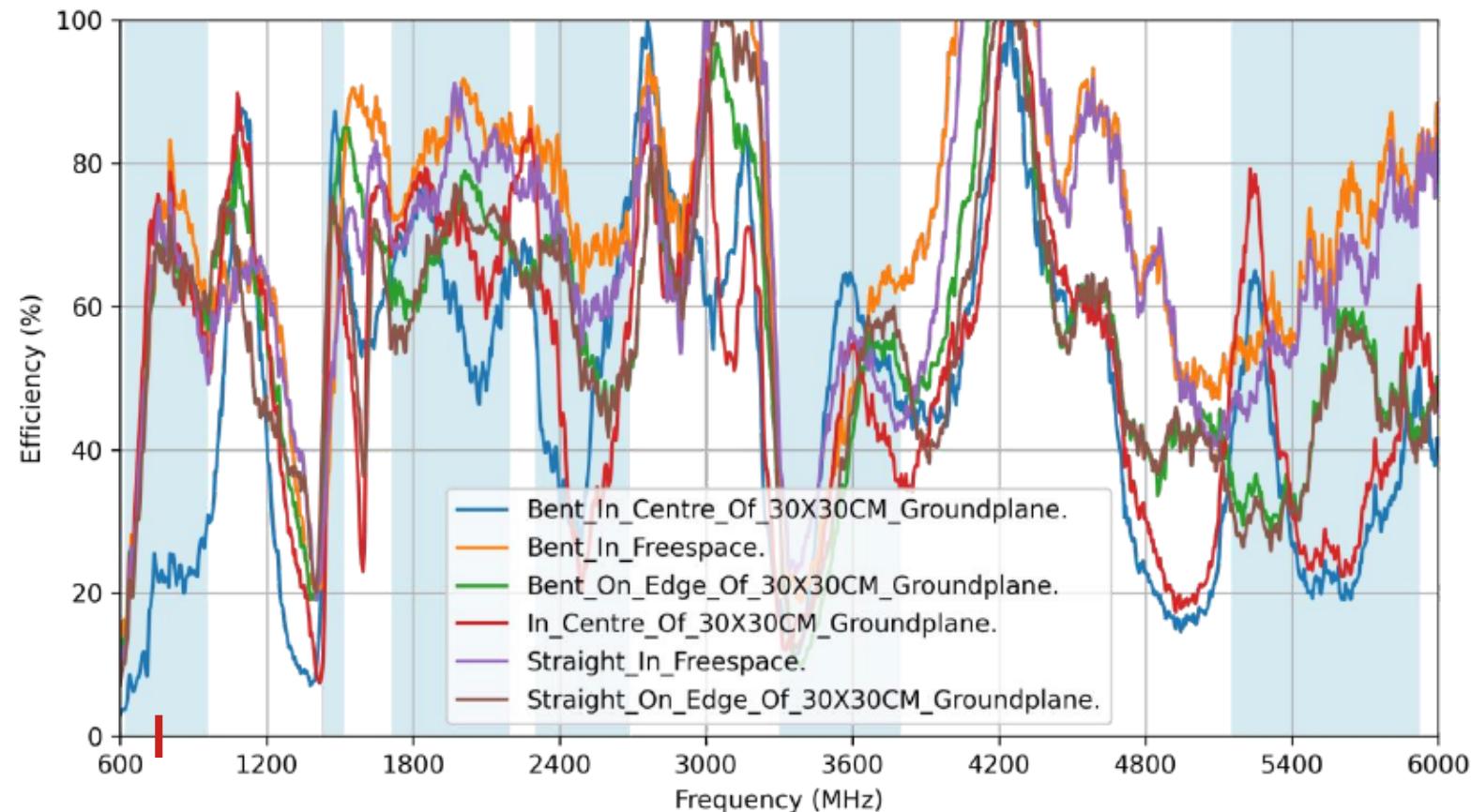
Impedance-mismatched log-periodic does better than I expected

More serious setup



Short about antennas (1)

3.2 Efficiency



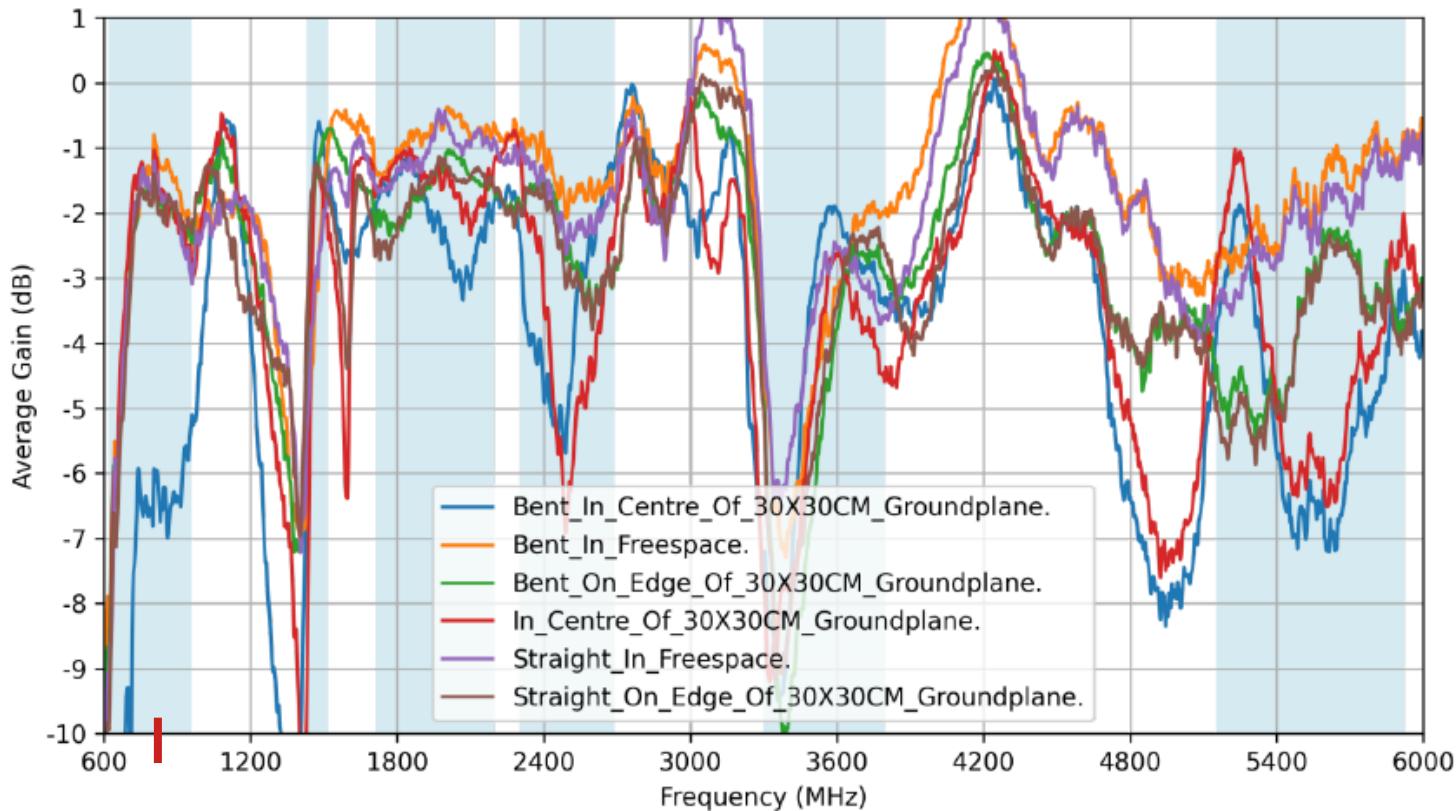
Efficiency and gain are correlated, based on directivity

We will be interested in those 742.5 MHz

This is Taoglas omidirectional TG.30.8113

Short about antennas (2)

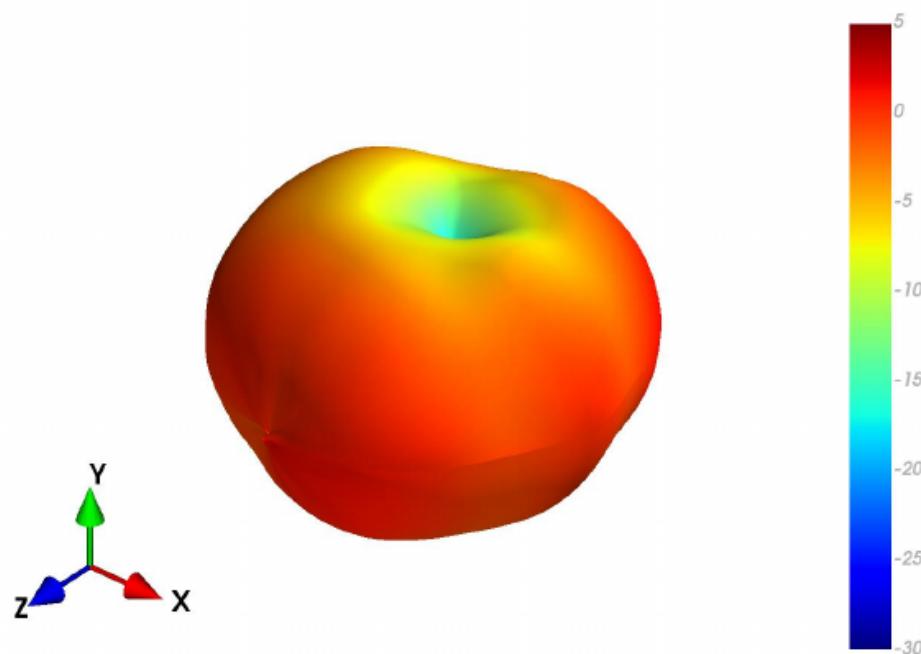
3.3 Average Gain



Taoglas Omnidirectional TG.30.8113
No other antenna had this good datasheet

Antenna radiation patterns (1)

4.9 Bent in Free space -Patterns at 750 MHz

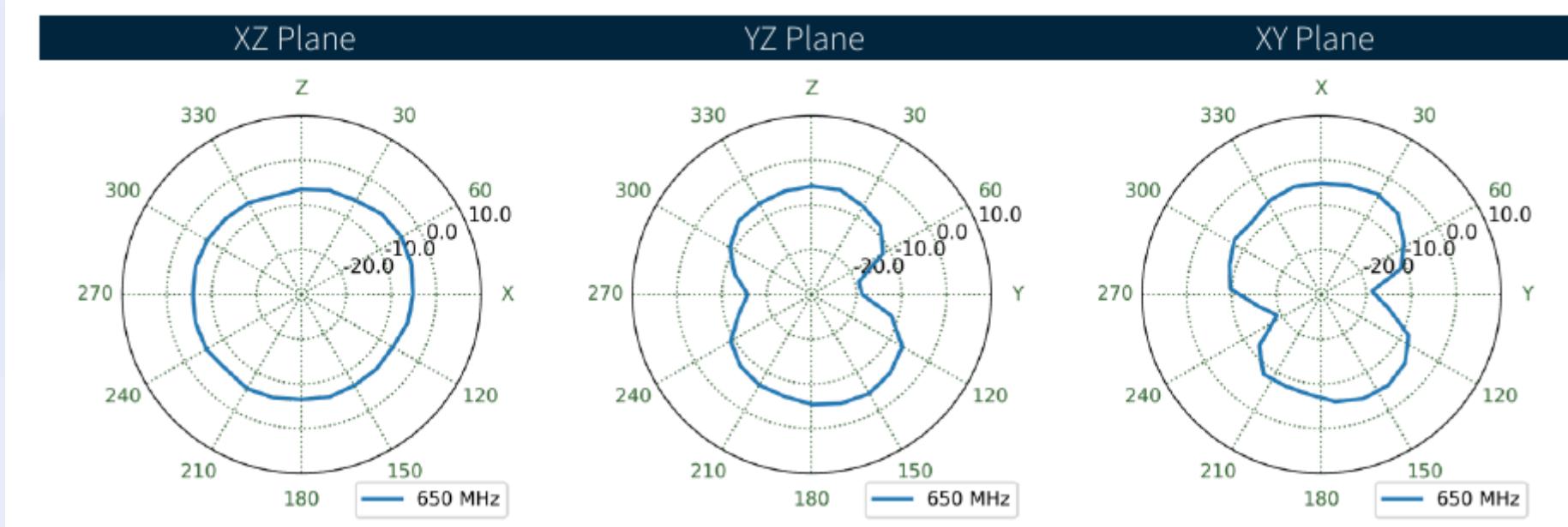


XZ Plane

YZ Plane

XY Plane

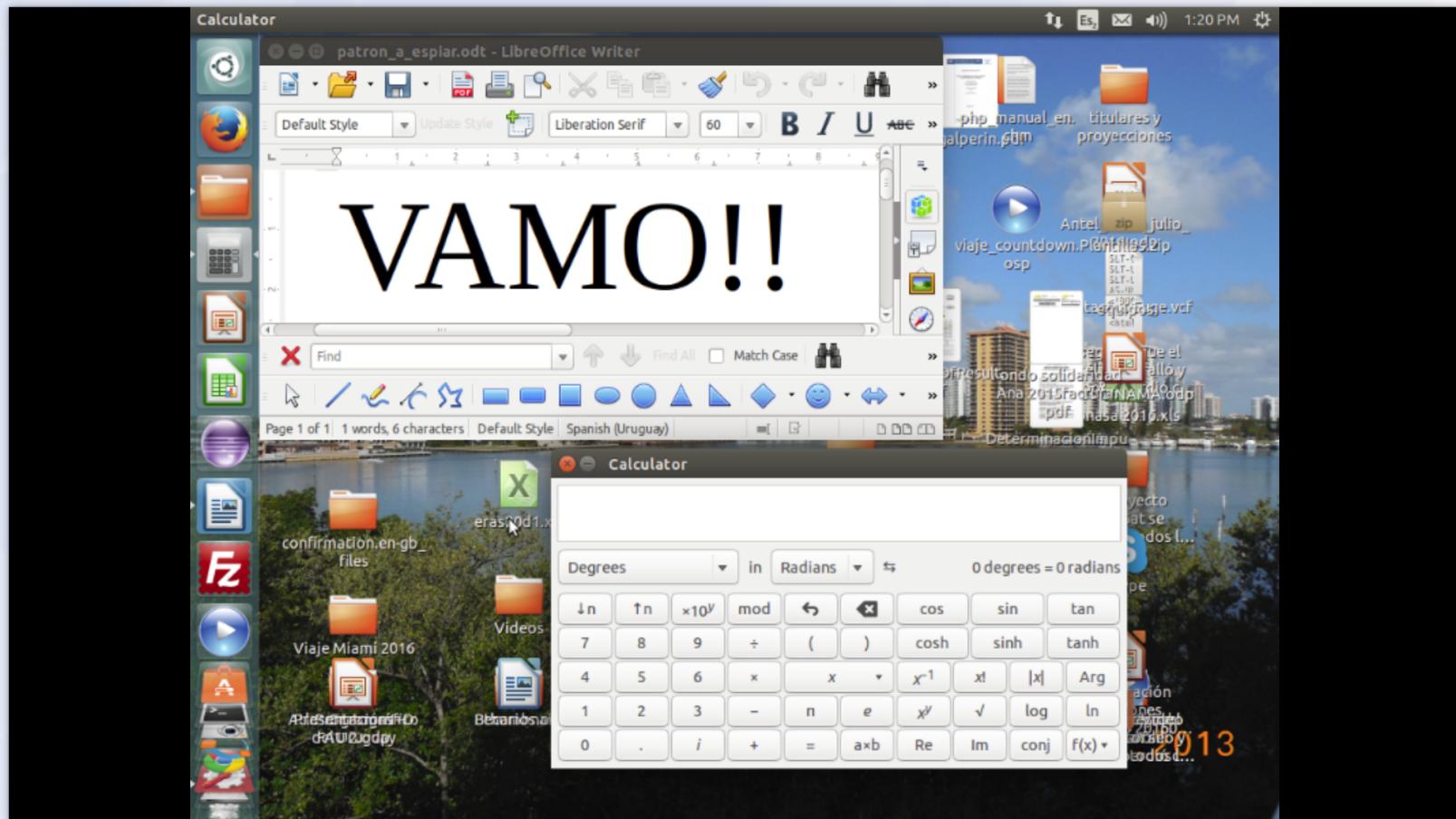
Antenna radiation patterns (2)



Software stacks

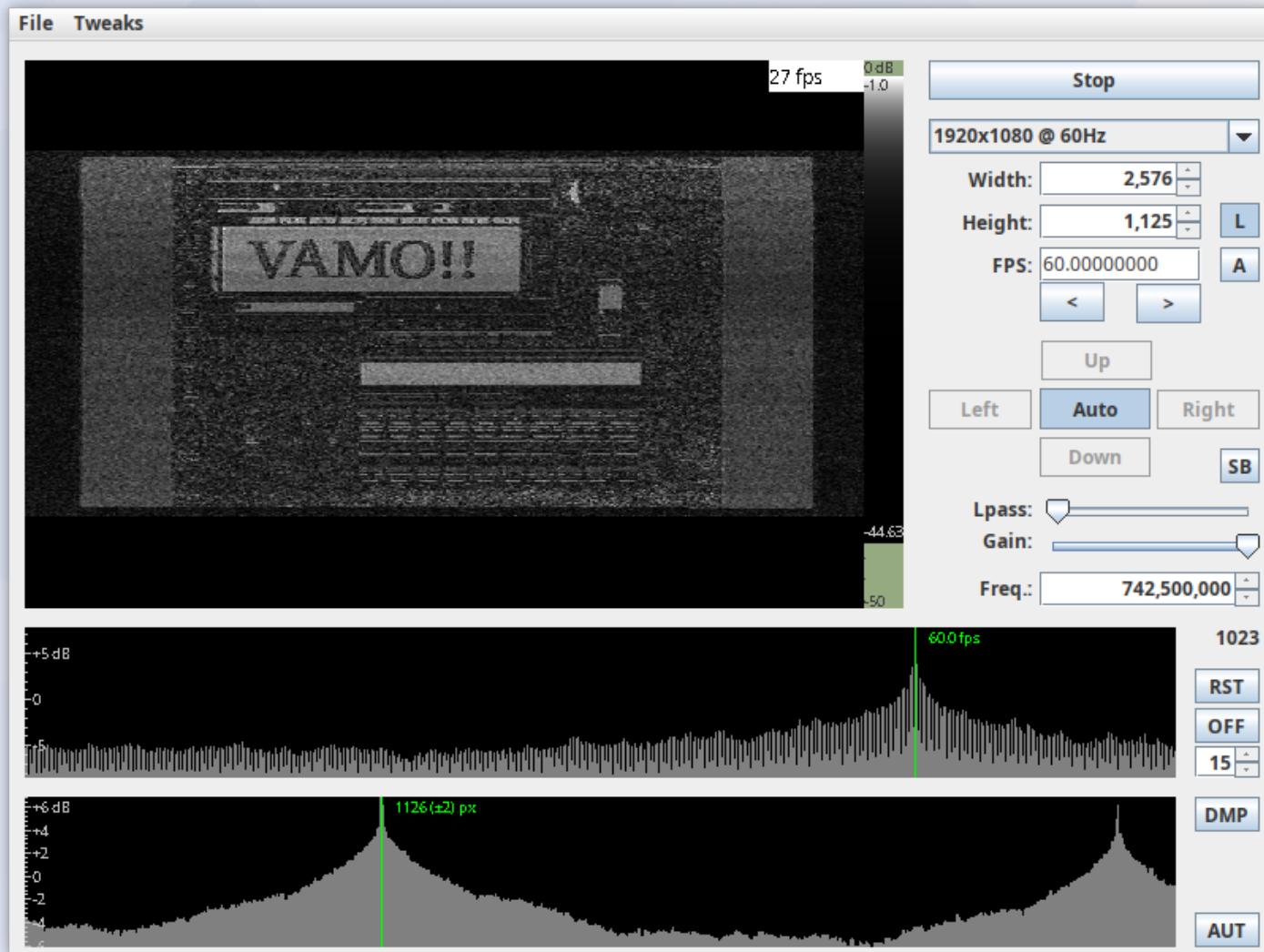
- kinda all
 - Java + native libs
 - C++
 - python + C/C++ native libs
 - multiprocessing
 - gnuradio (terrible design)

First results, monitor original

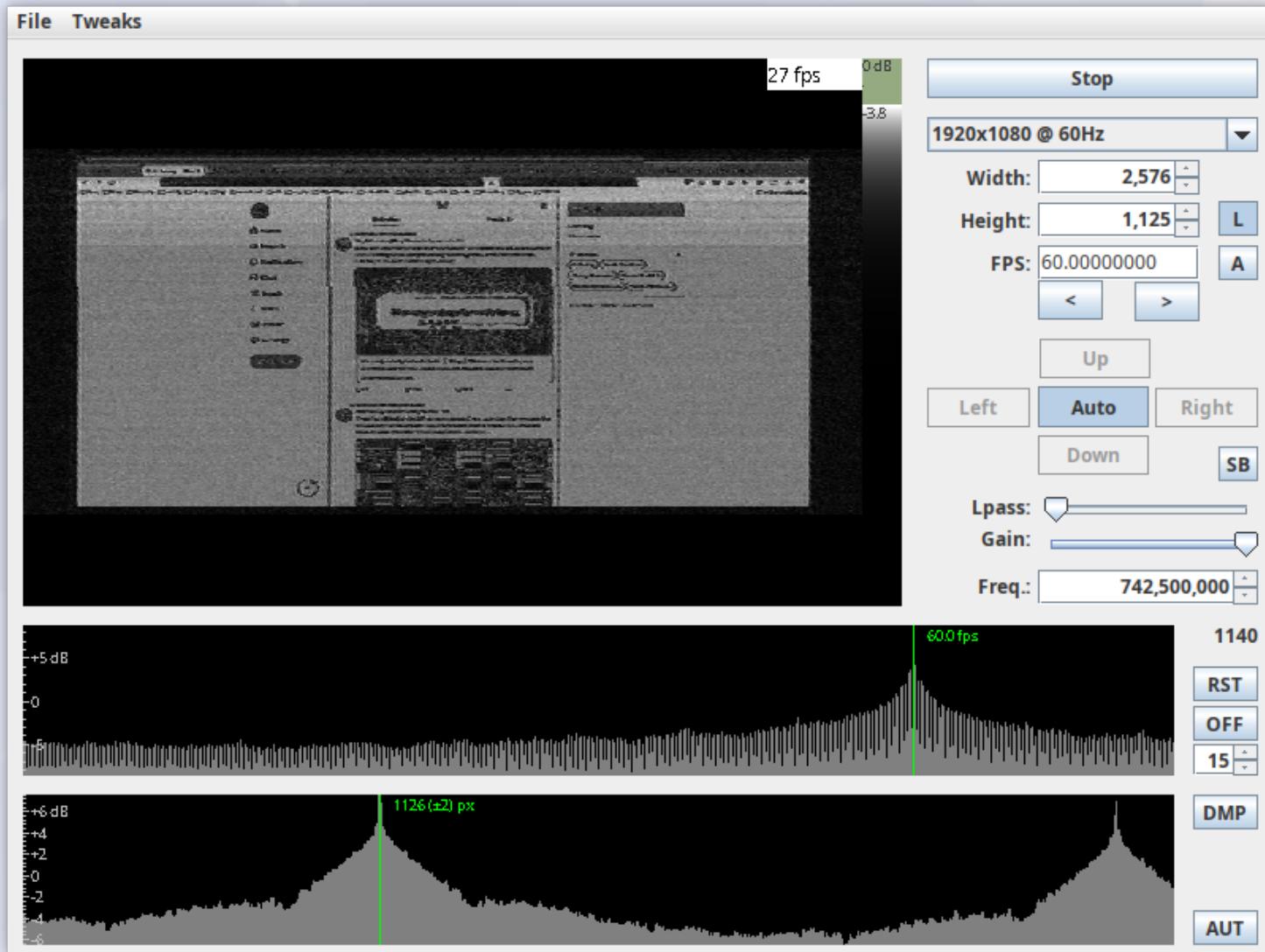


made a mistake to enlarge image via interpolation, thus losing edges
(losing edges \Leftrightarrow losing high frequencies, Fourier/cosine transform)

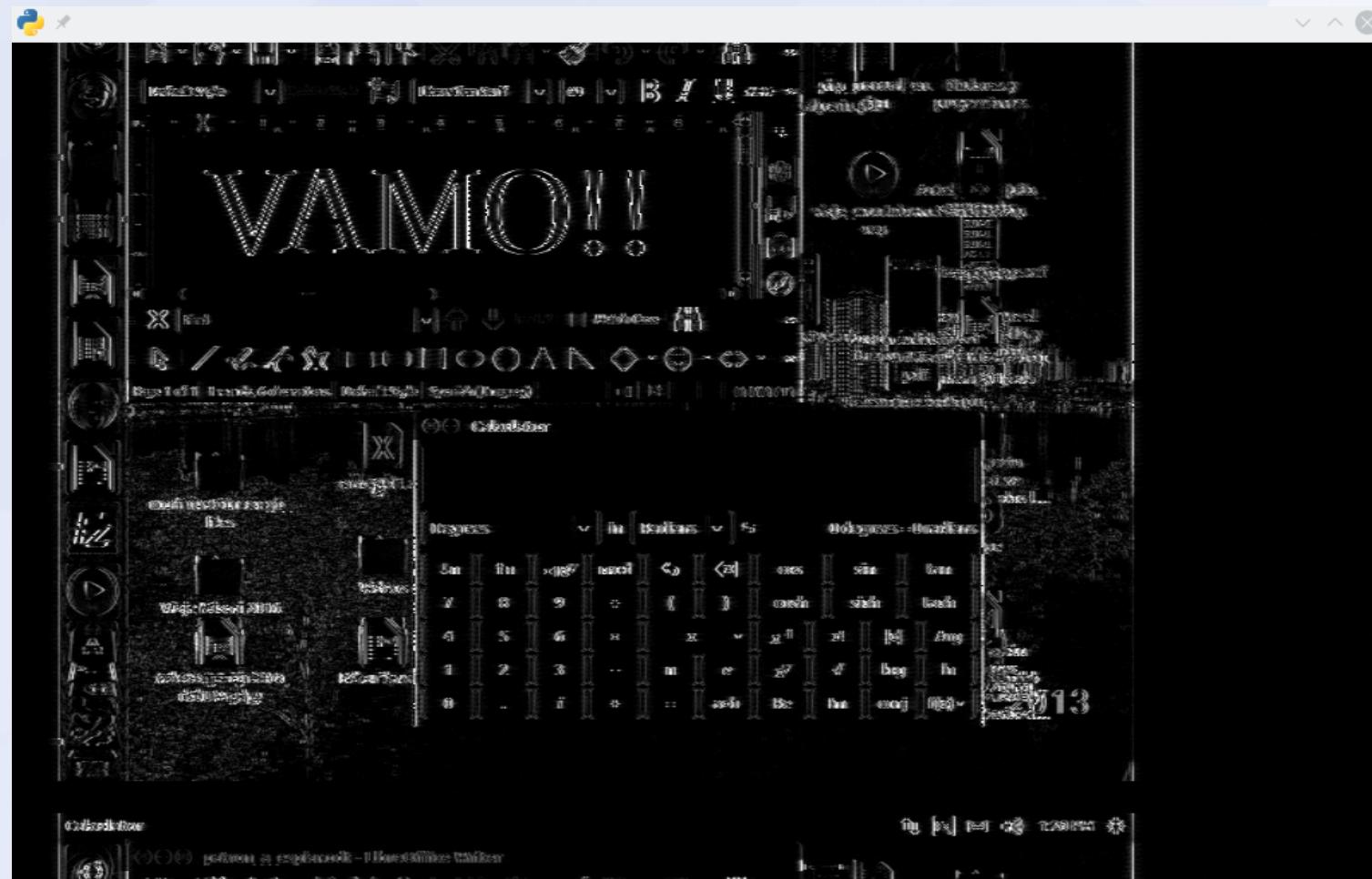
First results, TEMPEST image



High-contrast sharp image



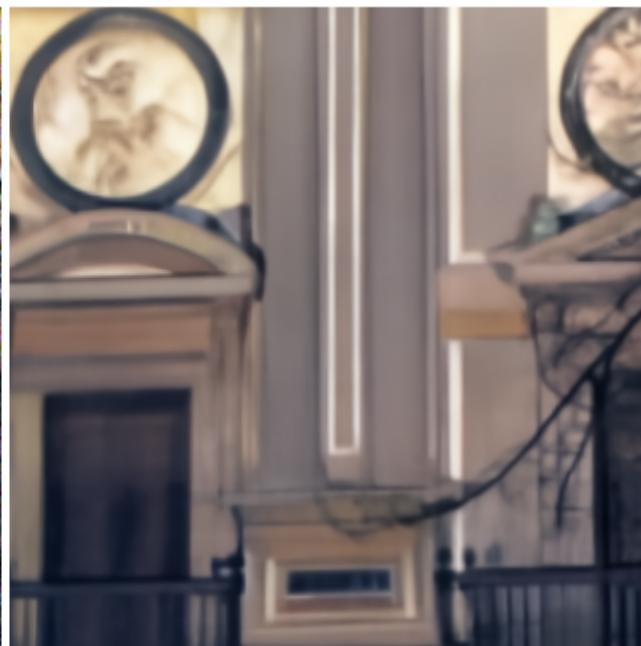
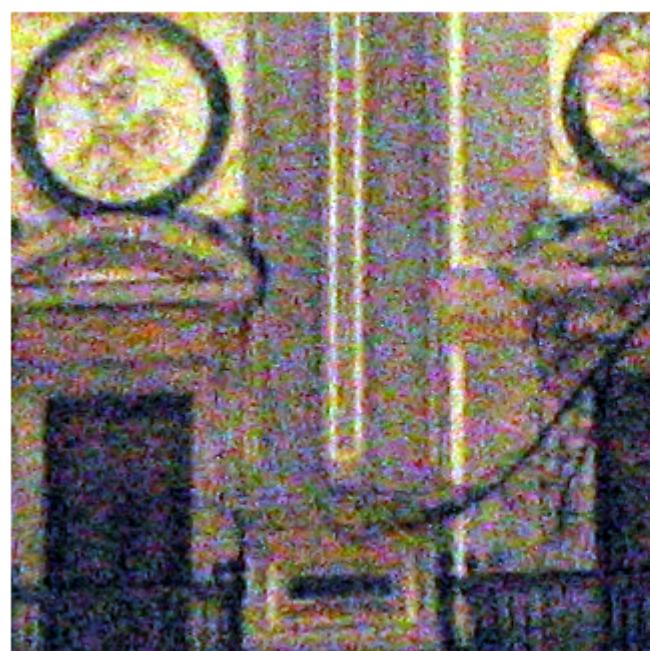
Best you can hope with just SDR



What next?

- enhance image somehow
- there is KAIR image restoration library you can use to train on some images
- training on web pages, PDFs and text is generally useful for attacker, as he wants to see some secret documents

KAIR denoising



Sniffed image before KAIR

pseudo coordinates (θ_1, θ_2) are calculated and determined solely from the K Gaussian kernels with learnable means and covariances. Finally, \mathcal{L} , X , and y_{obj} are fed into Graph Classification Neural Network (GCN) defined by Figure 2. The output of our Spatial-aware Graph Reasoning Module is concatenated to the f to improve both classification and localization.

center of node b in first system. Naturally, the relative positions of each region (node) in the image can be represented in the pseudo-coordinates system. In this paper, we use a polar function $a(x, y) = (d, \theta)$ which returns a 2-d vector that calculates the distance and the angle of two vectors $[x_a, y_a], [x_b, y_b]$ of the region proposals a and b , e.g.,

$$d = \sqrt{(x_a - x_b)^2 + (y_a - y_b)^2} \text{ and } \theta = \arctan \left(\frac{y_a - y_b}{x_a - x_b} \right).$$

Then we tend to incorporate our spatial-aware graph reasoning by defining a patch operator to describe the influence and propagation of each neighbouring node in the graph. Similar to MoNet [38], we define the patch operator by a set of K Gaussian kernels of learnable means and covariances. Finally, given the regional segments from $y_{\text{obj}} \in X$ and the graph structure $G = \langle N, E \rangle$, the patch operator at each layer k for node i is given by:

$$t_i^k(j) = \sum_{j \in \text{Neighbours}(i)} w_k(\text{vec}_i, j) y_j, \quad (6)$$

where $\text{Neighbours}(i)$ denotes the neighborhood of node i and vec_i is the i th Gaussian kernel.

The weights $\mathbf{W}_{\text{source}}$ of the linear regression and classification layer can be transformed to the target dataset by $\mathbf{W}_{\text{target}} = \Gamma \mathbf{W}_{\text{source}}$, where $\Gamma \in \mathbb{R}^{C_{\text{target}} \times C_{\text{source}}}$. The Γ is a transform matrix which can be obtained by calculating the cosine distance between the category name word embeddings [2, 16]. Experiments of transferring from multiple datasets can be found in Section 4.3. Our SORN shows great transfer capability which can be used to shorten the testing schedule.

4. Experiments

4.1. Datasets and Evaluation

We first conduct experiments on large-scale object detection benchmarks with a large number of classes: Visual Genome (VG) [15] and ADB [30]. Note that these two datasets have long-tail distributions. The task is to localize an object and classify it, which is different from the experiments with given ground truth locations in Chen et al. [6]. For VG, we use the synsets [40] instead of the raw names of the categories due to inconsistent label annotations, following [21, 14, 21]. We consider two set of target classes: 1000 most frequent classes and 3600 most frequent classes of VG_{syn} and VG_{raw}. We split the remaining 92960 images with objects in these class sets into 87960 and 5,000 for training and testing, following [21]. For ADB dataset, we use 30197 images for training and 1,000 images for

After KAIR restoration

(note the artifacts)

pxendo coordinates $u(i, j)$ are calculated and determinne $w_k(\cdot)$ from the K Gaussian kernels with learnable means and covariances. Finally, E , X , and $w_k(\cdot)$ are feed into Graph Convolutional Neural Networks(GCN) detined by Equation (2). The output of our Spatial-aware Graph Reasoning Module is concatenated to the f to improve both classification and localivation.

nated of node b in that system. Naturally, the relative positions of each region (node) in the image can be recognized as the pseudo-coordinate system. In this paper, we use a polar function $\pi(a, b) = (d, \theta)$ which returns a 2-d vector that calculates the distance and the angle of two centers $(c_a, y_a, [c_b, y_b])$ of the region proposals a and b , e.g.

$$d = \sqrt{(c_a - c_b)^2 + (y_a - y_b)^2} \text{ and } \theta = \arctan\left(\frac{y_b - y_a}{c_b - c_a}\right).$$

Then we need to formulate our spatial-aware graph reasoning by defining a patch operator to describe the influence and propagation of each neighboring node in the graph. Similar to MoNet [38], we detine the patch operator by a set of K Gaussian kernels of learnable means and covariances. Formally, given the regional semantic input $x_s \in \mathbf{X}$ and the graph structure $G = \langle N, E \rangle$, the patch operator at each kernel k for node i is given by:

$$\tilde{x}'_k(i) = \sum_{j \in \text{Neighbour}(i)} w_k(u(i, j)) x_j e_{ij}, \quad (2)$$

where $\text{Neighbour}(i)$ denotes the neighborhood of node i and $w_k(\cdot)$ is the k th Gaussian kernek

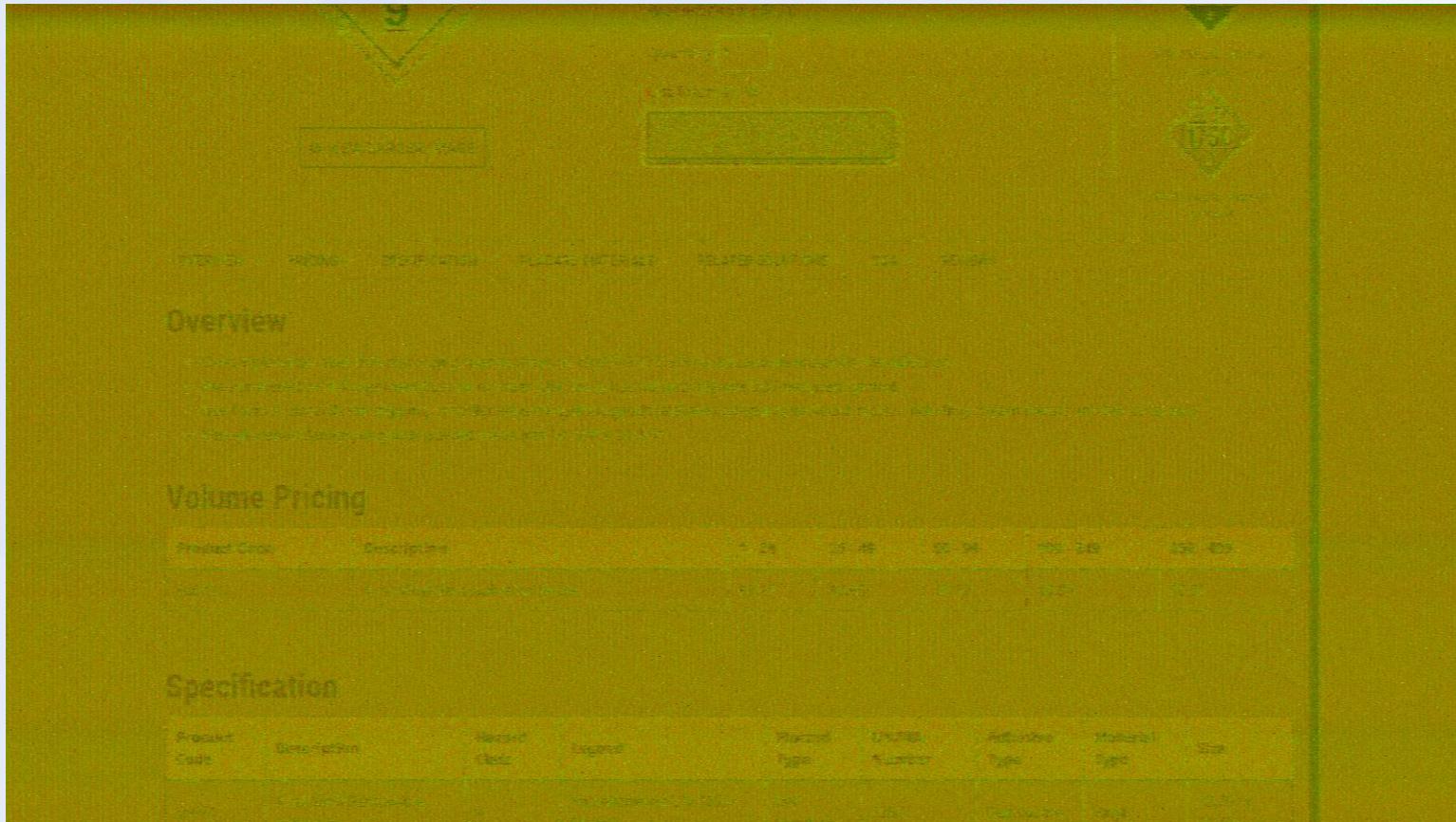
The weights $\mathbf{W}_{\text{bbox}}^*$ of the bbox regression and classification layer can be transformed to the target dataset by $\mathbf{W}_{\text{target}} = \Gamma \mathbf{W}_{\text{source}}$, where $\Gamma \in \mathbb{R}^{C_{\text{target}} \times C_{\text{source}}}$. The Γ is a transform matrix which can be obtained by calculating the cosine distance between the category name word embedding [2, 16]. Experiments of transferring from multiple datasets the can be found in Section 4.5. Our SGRN shows great transfer capability which can be used to shorten the training schedule.

4. Experiments

4.1. Datasets and Evaluation.

We first conduct experiments on large-scale object detection benchmarks with a large number of classes: Visual Genome (VG) [25] and ADE [62]. Note that these two datasets have long-tail distributions. The task is to localize an object and classify it, which is different from the experiments with given ground truth locations in Chen et al. [6]. For VG, we use the synsets [46] instead of the raw names of the categories due to inconsistent label annotations, following [21, 6, 23]. We consider two set of target classes: 1000 most frequent classes and 3000 most frequent classes: VO_{1000} and VG_{3000} . We split the remaining 92960 images with objects on these class sets into 87960 and 5,000 for training and testing, following [23]. For ADE dataset, we use 20,197 images for training and 1,000 images for

Training KAIR, SDR snapshot



Training KAIR+deep tempest

- PITA to make it work
 - permanently pinched conda package versions (aaaaaaaaaaaaah workaround)
 - build does not work (aaaaaaaaah)
 - ... UHD driver for radio lags for gnuradio
 - crashes from time to time (gr-tempest)
 - need to take care to not overtrain it
 - placement of signal must be aligned

What could you add next

- OCR via Tesseract to get better text recognition

Training KAIR is tricky

- you need a model for every videomode pixelclock/hsize/vsize
 - when you see all the variables, it's too many resulting in many models to make
- cable measured matters
- not sure if it's reasonable to extrapolate data trained from one cable to another, rather not easily

Training – how?

- preparing training data sound easy
- but you need to make at least a script that changes monitor image, then takes 5 SDR samples per source image, deal with synthetic, ground-truths, simulations and real data
- avoid „overtraining“
- „write a script“ sounds way easier than it is to collect data for a model

Thanks

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