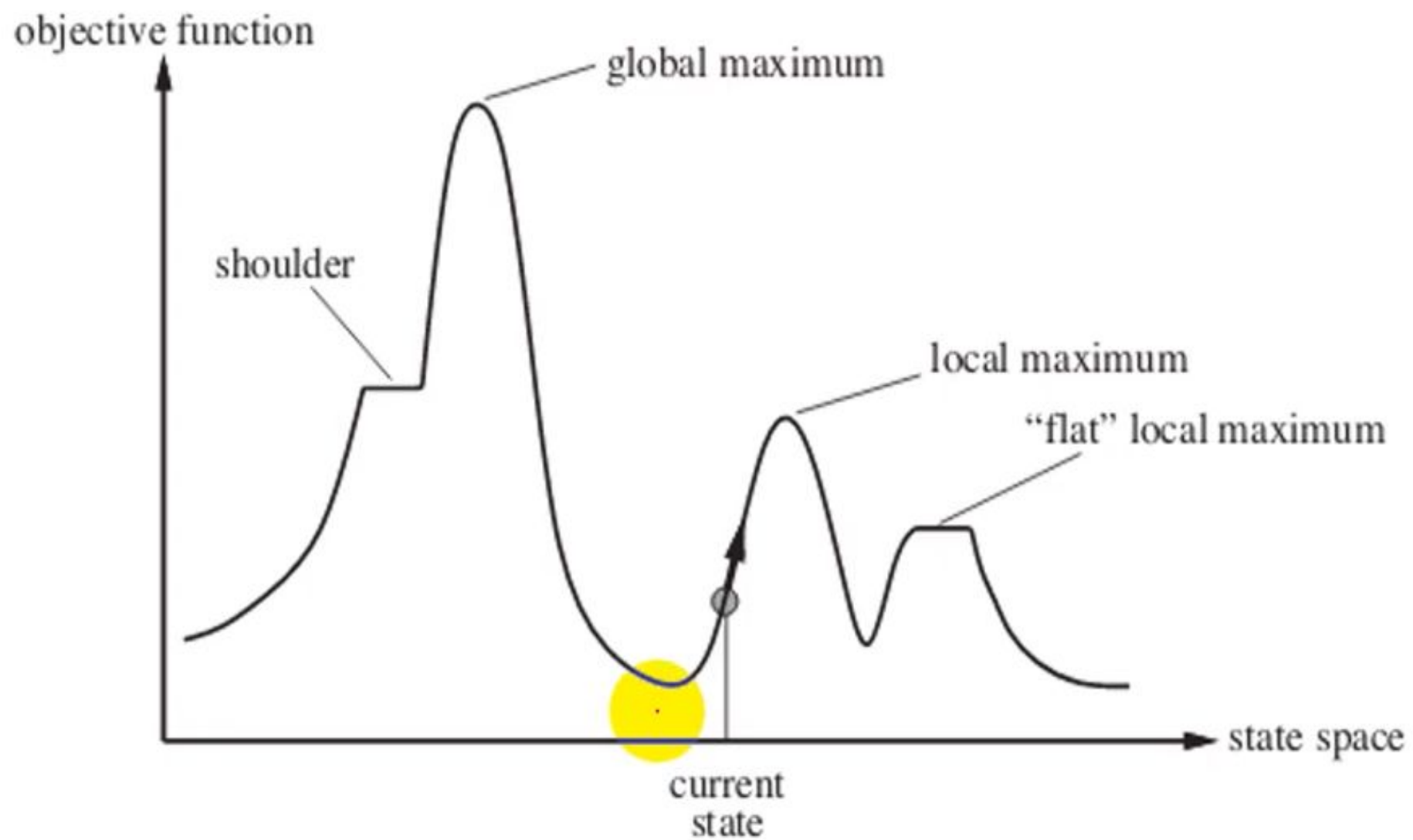




Artificial Intelligence

HILL CLIMBING

Hill Climbing



Hill Climbing Problems

- ▶ HLocal maxima = no uphill step
- ▶ Algorithms on previous slide fail (not complete)
- ▶ Allow "random restart" which is complete, but might take a very long time
- ▶ Plateau = all steps equal (flat or shoulder)
- ▶ Must move to equal state to make progress, but no indication of the correct direction
- ▶ Ridge = narrow path of maxima, but might have to go down to go up

Hill Climbing

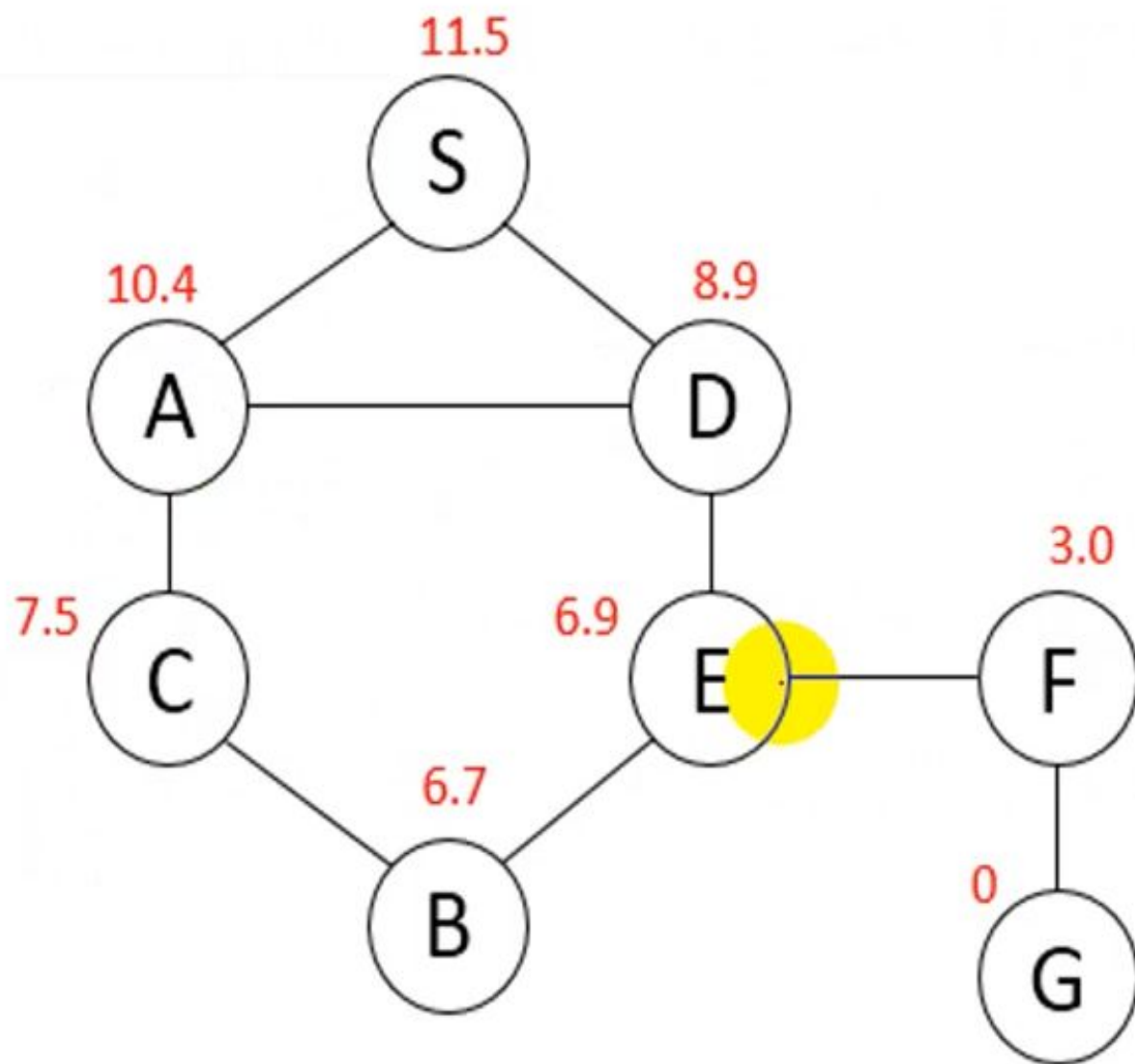
Hill-climbing (or gradient ascent/descent)

“Like climbing Everest in thick fog with amnesia”

```
function HILL-CLIMBING(problem) returns a state that is a local maximum
  inputs: problem, a problem
  local variables: current, a node
                  neighbor, a node

  current ← MAKE-NODE(INITIAL-STATE[problem])
  loop do
    neighbor ← a highest-valued successor of current
    if VALUE[neighbor] ≤ VALUE[current] then return STATE[current]
    current ← neighbor
  end
```

Hill Climbing Example:



"Like climbing Everest in thick fog with amnesia"

function HILL-CLIMBING(*problem*) **returns** a state that is a local maximum

inputs: *problem*, a problem

local variables: *current*, a node

neighbor, a node

current \leftarrow MAKE-NODE(INITIAL-STATE[*problem*])

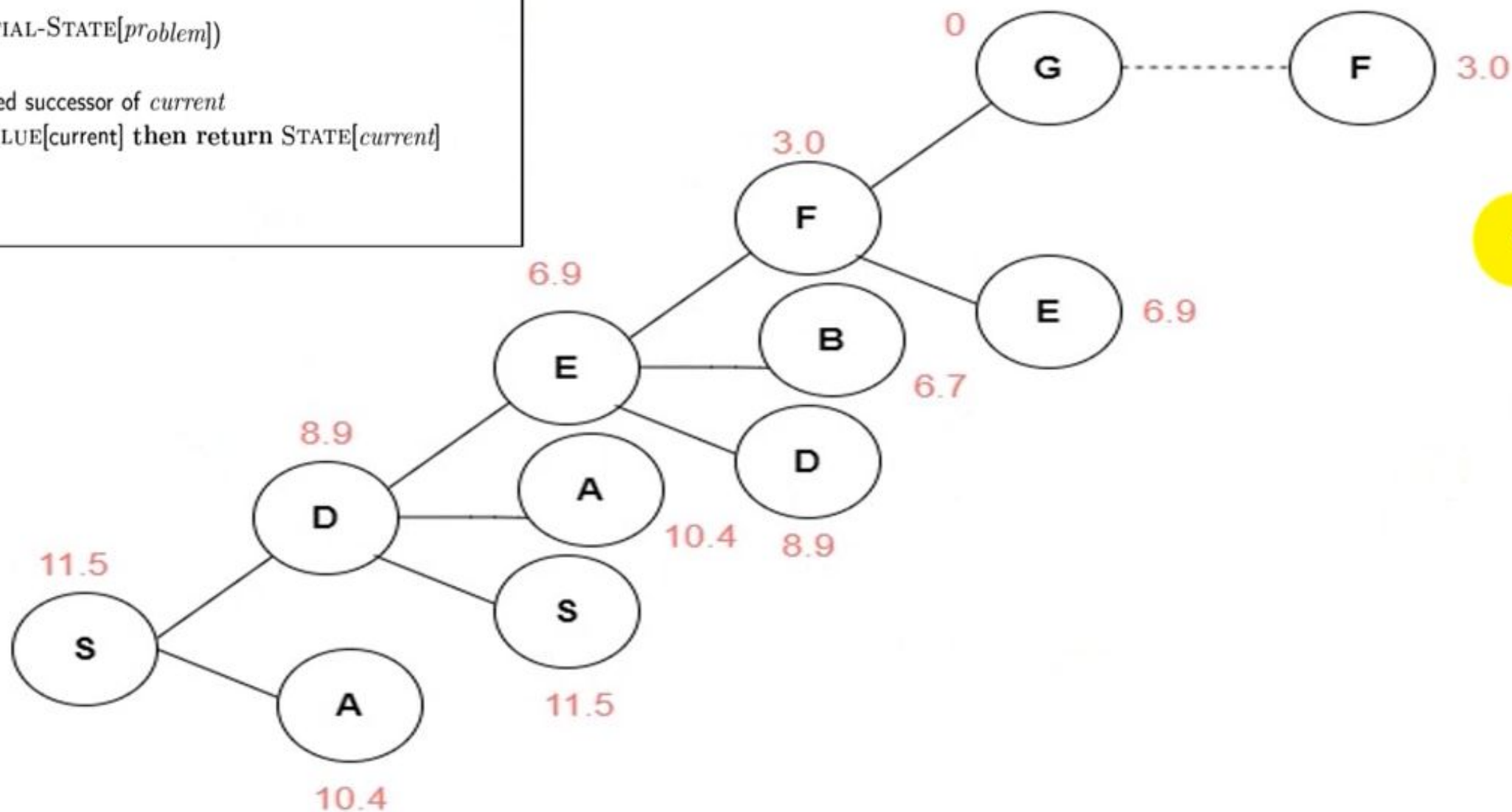
loop do

neighbor \leftarrow a highest-valued successor of *current*

if VALUE[*neighbor*] < VALUE[*current*] **then return** STATE[*current*]

current \leftarrow *neighbor*

end



Hill Climbing Example:

