Quiz 3

Started: Jan 25 at 9:02pm

Quiz Instructions

Question 1 1 pts

Which of these is true with respect to effect of control on system dynamics? Check all that apply.

- $oxed{\Box}$ Good control u_k leads to small state x_k with small effort u_k .
- System behavior is completely determined by the state $m{x_k}$ and control input $m{u_k}$ at each step.
- Good control $oldsymbol{u_k}$ leads to large state $oldsymbol{x_k}$ with small effort $oldsymbol{u_k}$.
- System behavior is completely determined only by the initial state x_0 and control input u_k at each step.

Question 2 1 pts

Which of the following is the correct representation of finite and infinite horizon problem? $l\left(x_k,u_k\right)$ is the running cost function which penalizes nonzero state and input, N is the number of steps for finite horizon problem, $g\left(x_k\right)$ is the cost at state x_k , J_N is the total cost for finite horizon and J_∞ is the total cost for infinite horizon.

$$\int J_N = g\left(x_N
ight) + \sum_{k=0}^{N-1} l\left(x_k, u_k
ight), \ J_\infty = g\left(x_0
ight) + \sum_{k=1}^\infty l\left(x_k, u_k
ight)$$

$$J_N = \sum_{k=0}^N l\left(x_k, u_k
ight), \ J_\infty = g\left(x_0
ight) + \sum_{k=1}^\infty l\left(x_k, u_k
ight)$$

$$\bigcirc J_N = g\left(x_N
ight) + \sum_{k=0}^{N-1} l\left(x_k, u_k
ight), \ J_\infty = \sum_{k=0}^\infty l\left(x_k, u_k
ight)$$

$$\bigcirc J_N = \sum_{k=0}^N l\left(x_k, u_k
ight), \ J_\infty = \sum_{k=0}^\infty l\left(x_k, u_k
ight)$$

Question 3 1 pts

1 of 4 1/25/18, 9:02 PM

Which of these is tru	ue with respect to Dynamic Programming? Check all that apply.
Dynamic Progra	mming is an iterative way to solve sequential optimization problem.
Dynamic program	mming is a single step way to solve sequential optimization problem.
We use forward	induction to find the optimal control strategy.
We use backwar	rd induction to find optimal control strategy.

Question 4	1 pts
Control policy is a function that maps information set to action set.	
O True	
O False	

Quiz saved at 9:02pm

SUBMIT QUIZ

2 of 4 1/25/18, 9:02 PM

3 of 4 1/25/18, 9:02 PM

4 of 4