## **Tutorial 8**

19. Using the Routh-Hurwitz criterion, tell how many closed-loop poles of the system shown in Figure P6.5 lie in the left half-plane, in the right half-plane, and on the  $j\omega$ -axis. [Section: 6.3]

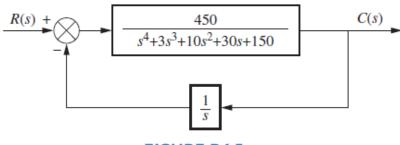


FIGURE P6.5

**33.** Given the unity feedback system of Figure P6.3 with

$$G(s) = \frac{K(s+4)}{s(s+1.2)(s+2)}$$

find the following: [Section: 6.4]

- **a.** The range of *K* that keeps the system stable
- **b.** The value of *K* that makes the system oscillate
- **c.** The frequency of oscillation when *K* is set to the value that makes the system oscillate
- 52. The following system in state space represents the forward path of a unity feedback system. Use the Routh-Hurwitz criterion to determine if the closed-loop system is stable. [Section: 6.5]

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 2 \\ -5 & -4 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} u$$
$$y = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} \mathbf{x}$$