

ELG 3155 Introduction to Control Systems Winter 2023

Final EXAMINATION (2.5 hours)

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Date: 2023-07-13

This is a closed book exam

Answer all questions

The problems are not ordered by difficulty

C'est un examen à livres fermés

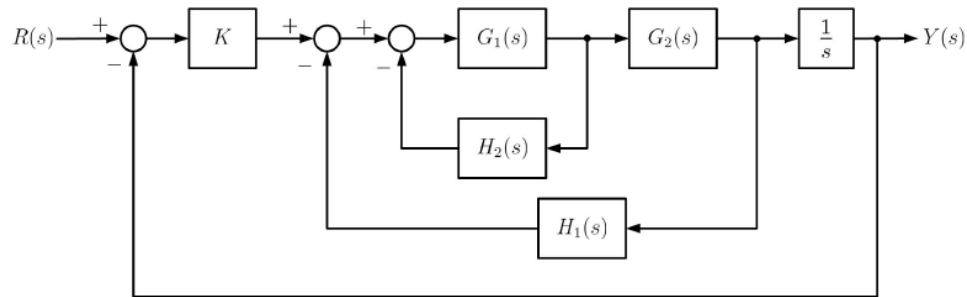
Répondre à toutes les questions

Les problèmes ne sont pas classés par difficulté

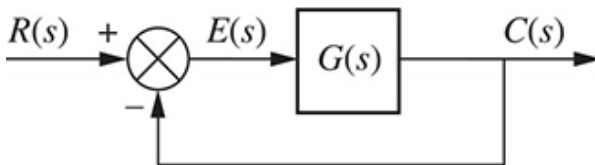
Question (weight)	Q1 (18)	Q2 (21)	Q3 (21)	Q4 (25)	Q5 (15)	Total (100)
Mark/Point						

Helpful formula	
$s_{1,2} = \sigma_d \pm j\omega_d = -\xi\omega_n \pm j\omega_n\sqrt{1-\xi^2}$, $G(s) = \frac{\omega_n^2}{s^2+2\xi\omega_n s+\omega_n^2}$	
$f(\infty) = \lim_{s \rightarrow 0} sF(s)$, $e(\infty) = \lim_{s \rightarrow 0} \frac{sR(s)}{1+G(s)}$	
$\sigma_a = \frac{\sum p_i - \sum z_i}{\#p - \#z}$	$\theta_a = \frac{(2k+1)\pi}{\#p - \#z}$ $KG(s)H(s) = 1 \angle (2k+1)180^\circ$
$Z_c(s) = \frac{1}{cs}$, $Z_L(s) = Ls$, $Z_R(s) = R$	

Problem 1: (18 points) Block-Diagram Reduction. Find the transfer function $Y(s)/R(s)$.



Problem 2. (21 points) For the unity feedback system shown below

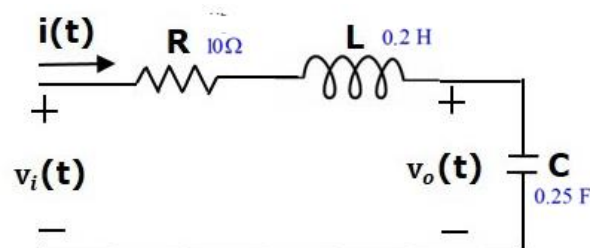


$$G(s) = \frac{450(s + 7)(s - 8)(s + 15)}{s(s + 38)(s^2 + 2s + 28)}$$

find the steady-state errors for the following test inputs:

- a. $15u(t)$; b. $3tu(t)$; c. $4t^2u(t)$

Problem 3: (21 points) In the given electrical network, the input is the dc-voltage (V_i) and the output voltage is V_o .

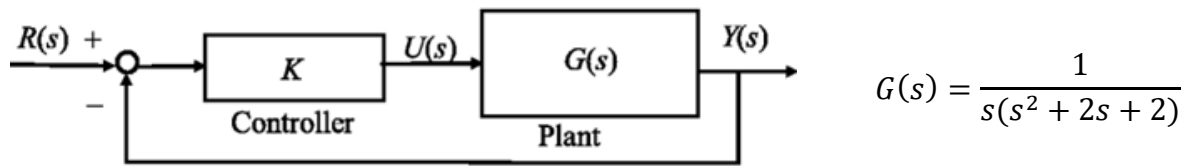


- Find the transfer function V_o/V_i
- Is the system underdamped or overdamped?
- Assuming $x_1 = i_L$ and $x_2 = v_c$, write the state equation in the following form,

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

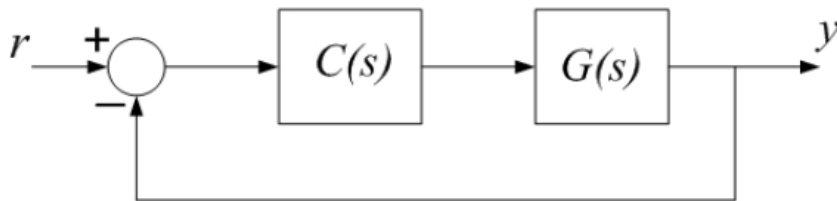
Problem 4: (25 points) A unity feedback control system is shown in this block diagram.



Make a rough sketch of root locus plot by determining the following.

- Centroid, number and angle of asymptotes.
- Angle of departure of root loci from the poles.
- Points of intersection with $j\omega$

Problem 5: (15 points) Consider the following LTI system:



where $C(s) = \frac{K}{s+4}$ and $G(s) = \frac{3s+3}{s^2-2s-3}$

Determine for what values of K the system is stable and unstable.