

GNG1106

Fundamentals of Engineering Computation

Instructor: **Hitham Jleed**



University of Ottawa

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Outline

- 1 Plotting (not in C)
- 2 Designing a Function (Prototype)
- 3 Numerical Method I: Root Finding

Plotting

- C does not have built-in plotting functions.
- There are various third-party libraries developed in C for plotting mathematical functions. But these libraries are usually developed for specific OS, and can hardly be used across different OS's.
- In real-world work place, one rarely plots using C. Rather we use other more convenient tools.
- In this course, whenever you are asked to plot, you can use any third-party tool to plot, for example, here is an online plotting tool:
`http://gnuplot.respawned.com/`
- To plot, you can prepare you data (as a collection of (x, y) coordinates) in an ASCII file (or simply print to the console, if you are not asked explicitly to create the file), and load/paste the data in your choice of plotting software.

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Designing a Function (Prototype)

Suppose that in the `main` function or any other function, we need to call a function `foo` with input `X` to obtain some information, say `Y`, about `X`. To do this, there are two ways:

- 1 Make `foo` return `Y`.
- 2 Create a variable in the calling function (e.g. `main`), that serves as a “receiver” for `Y`; pass the address of the receiver into the function (i.e., via pass by reference). In `foo`, compute the value `Y` and save it to the receiver through its address.

- A limitation of the first approach is that that Y can only be a single variable (since a function can only return one variable). When Y includes multiple variables, if they can be “naturally bundled”, one can create a structure including these variables as the members of one structure-typed variable.
- It is also possible to combine the two approaches, making some components of Y returned from `foo` and sending other components of Y via pass by reference.

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- In engineering, we are often interested in solving equations in the form of

$$f(x) = 0.$$

where f is an arbitrary function.

- Via computer programming, usually we can very rapidly evaluate the function (i.e., compute the value of $f(x)$ for any x).
- Can we leverage this fact to solve equation $f(x) = 0$?
- We now consider the case where $f(x)$ is a **polynomial** in x , namely, $f(x)$ in the form of

$$f(x) = c_0 + c_1x + c_2x^2 + \dots + c^nx^n$$

- The method we will develop apply in general to other kinds of functions $f(x)$.

- In polynomial $f(x) = c_0 + c_1x + c_2x^2 + \dots + c_nx^n$, the highest power (n) of x is called the **degree** of the polynomial.
- Solutions to polynomial equation $f(x) = 0$ is called the **roots** or **zeros** of polynomial $f(x)$.
- It is known that a polynomial with degree n has maximally n real roots.
 - $x + 3$ has one root, -3 .
 - $x^2 - 1$ has two real roots, ± 1 .
 - $x^2 + 1$ has no real roots.
 - $x^2 - 2x + 1 = (x - 1)^2$ has two repeated roots, $+1$ and $+1$.

- **Problem Statement:**

Given a polynomial $c_0 + c_1x + c_2x^2 + \dots + c_nx^n$ and an interval (a, b) , find all real roots of the polynomial in the interval.

- **I/O Description:**

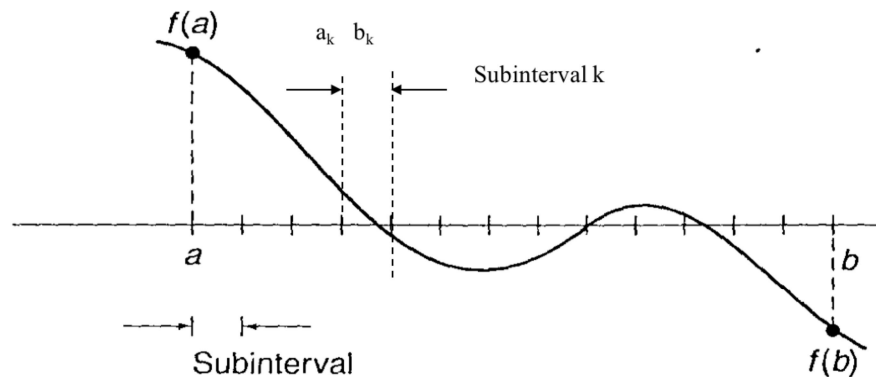
- Input:

- coefficients c_0, c_2, \dots, c_n ,
 - two end points of the interval, a and b

- Output:

- the roots of polynomial $c_0 + c_1x + c_2x^2 + \dots + c_nx^n$ in (a, b)

Root Finding by Incremental Search



- Divide the interval (a, b) to many tiny subintervals.
- For each sub-interval, say (a_k, b_k) , test if $f(a_k)$ and $f(b_k)$ take opposite signs, or, if $f(a_k) \cdot f(b_k) < 0$.
 - If yes, there is a root in (a_k, b_k) ; we then use the mid-point of the sub-interval, $\frac{a_k + b_k}{2}$, as the approximation of the root.
 - When the interval is sufficiently small, the approximation is very accurate.

Caution

- What if at one end of a sub-interval (a_k, b_k) , the function has value 0? For example $f(a_k) = 0$, then we would have missed a_k as the root.
 - We should also check if $f(a_k)$ is zero.
 - It is sufficient to only check the left end of the sub-interval, since the right end is the left end of the next sub-interval.
- But in programming, we never check if two floating-point (say, `double` typed) values are exactly equal, since even when they meant to be exactly equal, they usually aren't, due to finite precision in the representation of floating-point numbers.
- In practice, checking two floating-type values, say x and y are equal is implemented as checking if `fabs(x-y) < ALMOST_ZERO`, where `ALMOST_ZERO` is an extremely small positive number.

```
#include <stdio.h>
#include <math.h>
#define ALMOST_ZERO 1e-20
#define SUBINTERVAL_SIZE 0.0001

double evalPoly(int polyDegree, double *polyCoeffs, double x)
{
    double result=0;
    int i;
    for (i=0; i<=polyDegree; i++)
        result = result + polyCoeffs[i]*pow(x, i);
    return result;
}
```

```

int findARootInSubInterval(int polyDegree, double *polyCoeffs, double leftEnd,
double rightEnd, double *ptrFoundRoot)
{
    double leftVal, rightVal;
    int found=0;
    leftVal=evalPoly(polyDegree, polyCoeffs, leftEnd);
    rightVal=evalPoly(polyDegree, polyCoeffs, rightEnd);
    if (fabs(leftVal)<ALMOST_ZERO)
    {
        *ptrFoundRoot = leftEnd;
        found=1;
    }
    else
    {
        if (leftVal*rightVal<0)
        {
            *ptrFoundRoot = 0.5*(leftEnd+rightEnd);
            found=1;
        }
    }
    return found;
}

```

```

int findAllRootsByIncSearch(int polyDegree, double *polyCoeffs, double xStart,
double xEnd, double *ptrAllRootsFound)
{
    int numOfRootsFound=0;
    double left, right;
    int rootFound;
    left=xStart;
    while (left<xEnd)
    {
        right=left+SUBINTERVAL_SIZE;
        rootFound=0;
        rootFound=findARootInSubInterval(polyDegree, polyCoeffs, left, right,
            &ptrAllRootsFound[numOfRootsFound]);
        if (rootFound)
            numOfRootsFound++;
        left=right;
    }
    return numOfRootsFound;
}

```

Potential Issues with Incremental Search

- No roots may be found when the range of search does not include any root.
- Found roots are not accurate if sub-interval size is not sufficiently small.
 - Incremental search can be slow if we demand very high accuracy.
- Incremental search may fail on repeated roots, since in this case $f(a_k) \cdot f(b_k)$ is positive.
- When `ALMOST_ZERO` is not sufficiently small and the sub-interval size is too small, a root might be identified as several roots. This usually only happens when the polynomial coefficients have too small amplitudes so that its curve intersects with the x axis at a tiny angle. A fix for this is to scale up all coefficients of the polynomial.

Bisection Root Finding

- Suppose that for a given interval (a, b) we know there is **exactly one root** and we have observe $f(a)f(b) < 0$. In this case, we can use bisection search to find the root.
- Algorithm:
 - Keep cutting the interval into two halves, and identify the half that contains the root. When the interval is small enough, take its mid-point as the root.
 - Also caution the case where the root falls on an endpoint of the interval.

In-Class Exercise: