Homework 2

1 K Nearest Neighbors

1.1 Problem Statement

(20 points) k-nearest neighbors. Complete the k-nearest neighbors Jupyter notebook. The goal of this workbook is to give you experience with the CIFAR-10 dataset, training and evaluating a simple classifier, and k-fold cross validation. In the Jupyter notebook, we'll be using the CIFAR-10 dataset. Acquire this dataset by running:

```
wget http://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
tar -xzvf cifar-10-python.tar.gz
rm cifar-10-python.tar.gz
```

1.2 Jupyter Results

knn

January 26, 2021

0.1 This is the k-nearest neighbors workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement k-nearest neighbors.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and code in the jupyter notebook to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with the data, training and evaluating a simple classifier, k-fold cross validation, and as a Python refresher.

0.2 Import the appropriate libraries

[131]:
```
import numpy as np # for doing most of our calculations
import matplotlib.pyplot as plt# for plotting
from cs231n.data_utils import load_CIFAR10 # function to load the CIFAR-10␣
 ↪dataset.

# Load matplotlib images inline
%matplotlib inline

# These are important for reloading any code you write in external .py files.
# see http://stackoverflow.com/questions/1907993/
 ↪autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

```
The autoreload extension is already loaded. To reload it, use:
  %reload_ext autoreload
```

[132]:
```
# Set the path to the CIFAR-10 data
cifar10_dir = 'cifar-10-batches-py' # You need to update this line
X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
```

```python
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Training data shape:  (50000, 32, 32, 3)
Training labels shape:  (50000,)
Test data shape:  (10000, 32, 32, 3)
Test labels shape:  (10000,)
```

[133]:

```python
# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse',␣
 ↪'ship', 'truck']
num_classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples_per_class, num_classes, plt_idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()
```

[134]:
```
# Subsample the data for more efficient code execution in this exercise
num_training = 5000
mask = list(range(num_training))
X_train = X_train[mask]
y_train = y_train[mask]

num_test = 500
mask = list(range(num_test))
X_test = X_test[mask]
y_test = y_test[mask]

# Reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
print(X_train.shape, X_test.shape)
```

```
(5000, 3072) (500, 3072)
```

1 K-nearest neighbors

In the following cells, you will build a KNN classifier and choose hyperparameters via k-fold cross-validation.

[135]:
```
# Import the KNN class

from nndl import KNN
```

[136]:
```
# Declare an instance of the knn class.
knn = KNN()

# Train the classifier.
#   We have implemented the training of the KNN classifier.
#   Look at the train function in the KNN class to see what this does.
knn.train(X=X_train, y=y_train)
```

1.1 Questions

(1) Describe what is going on in the function knn.train().

(2) What are the pros and cons of this training step?

1.2 Answers

(1) knn.train() just saves all the training data and labels from the training set CIFAR

(2) The pros are the it is simple and fast (O(1)). On the other hand, it is memory intensive because all the training data must be stored and it scales with the amount of training examples.

1.3 KNN prediction

In the following sections, you will implement the functions to calculate the distances of test points to training points, and from this information, predict the class of the KNN.

[137]:
```
# Implement the function compute_distances() in the KNN class.
# Do not worry about the input 'norm' for now; use the default definition of␣
 ↪the norm
#   in the code, which is the 2-norm.
# You should only have to fill out the clearly marked sections.

import time
time_start =time.time()

dists_L2 = knn.compute_distances(X=X_test)

print('Time to run code: {}'.format(time.time()-time_start))
print('Frobenius norm of L2 distances: {}'.format(np.linalg.norm(dists_L2,␣
 ↪'fro')))
```

```
Time to run code: 26.693132877349854
Frobenius norm of L2 distances: 7906696.077040902
```

Really slow code Note: This probably took a while. This is because we use two for loops. We could increase the speed via vectorization, removing the for loops.

If you implemented this correctly, evaluating np.linalg.norm(dists_L2, 'fro') should return: ~7906696

1.3.1 KNN vectorization

The above code took far too long to run. If we wanted to optimize hyperparameters, it would be time-expensive. Thus, we will speed up the code by vectorizing it, removing the for loops.

[138]:
```
# Implement the function compute_L2_distances_vectorized() in the KNN class.
# In this function, you ought to achieve the same L2 distance but WITHOUT any␣
 ↪for loops.
# Note, this is SPECIFIC for the L2 norm.

time_start =time.time()
dists_L2_vectorized = knn.compute_L2_distances_vectorized(X=X_test)
print('Time to run code: {}'.format(time.time()-time_start))
print('Difference in L2 distances between your KNN implementations (should be␣
 ↪0): {}'.format(np.linalg.norm(dists_L2 - dists_L2_vectorized, 'fro')))
```

```
Time to run code: 0.14873099327087402
Difference in L2 distances between your KNN implementations (should be 0): 0.0
```

Speedup Depending on your computer speed, you should see a 10-100x speed up from vectorization. On our computer, the vectorized form took 0.36 seconds while the naive implementation took 38.3 seconds.

1.3.2 Implementing the prediction

Now that we have functions to calculate the distances from a test point to given training points, we now implement the function that will predict the test point labels.

[139]:
```
# Implement the function predict_labels in the KNN class.
# Calculate the training error (num_incorrect / total_samples)
# from running knn.predict_labels with k=1

error = 1

# ================================================================ #
# YOUR CODE HERE:
#   Calculate the error rate by calling predict_labels on the test
#   data with k = 1.  Store the error rate in the variable error.
# ================================================================ #
y_pred = knn.predict_labels(dists_L2_vectorized,1)
num_incorrect = np.count_nonzero((y_pred-y_test))
error = num_incorrect/len(y_test)
# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #

print(error)
```

```
0.726
```

If you implemented this correctly, the error should be: 0.726.

This means that the k-nearest neighbors classifier is right 27.4% of the time, which is not great, considering that chance levels are 10%.

2 Optimizing KNN hyperparameters

In this section, we'll take the KNN classifier that you have constructed and perform cross-validation to choose a best value of k, as well as a best choice of norm.

2.0.1 Create training and validation folds

First, we will create the training and validation folds for use in k-fold cross validation.

[140]:
```
# Create the dataset folds for cross-valdiation.
num_folds = 5

X_train_folds = []
y_train_folds =  []
```

```
# ================================================================ #
# YOUR CODE HERE:
#   Split the training data into num_folds (i.e., 5) folds.
#   X_train_folds is a list, where X_train_folds[i] contains the
#      data points in fold i.
#   y_train_folds is also a list, where y_train_folds[i] contains
#      the corresponding labels for the data in X_train_folds[i]
# ================================================================ #

X_train_folds = np.array_split(X_train, num_folds)
# print(X_train_folds[0].shape)
y_train_folds = np.array_split(y_train, num_folds)
# print(y_train_folds[0].shape)

# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
```

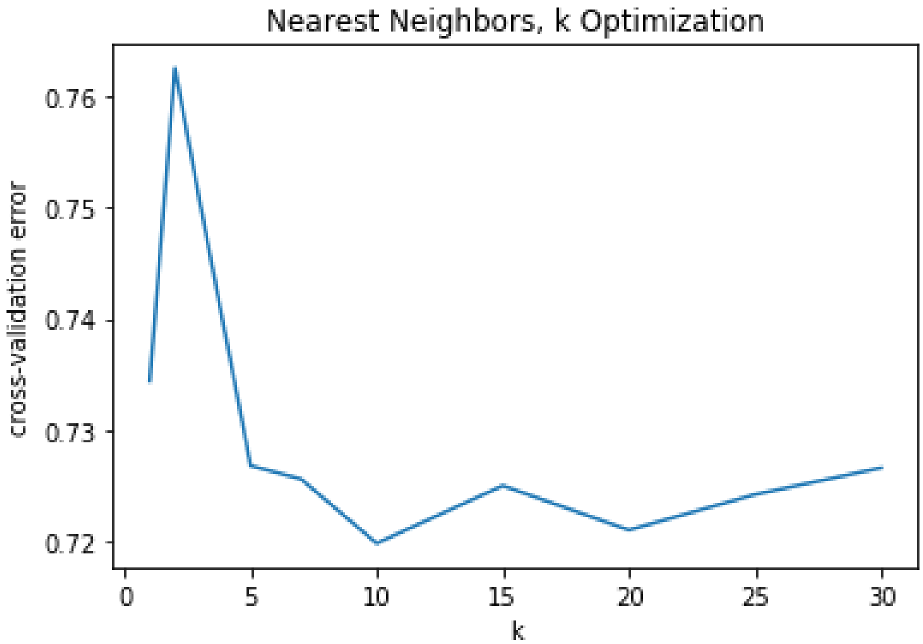
2.0.2 Optimizing the number of nearest neighbors hyperparameter.

In this section, we select different numbers of nearest neighbors and assess which one has the lowest k-fold cross validation error.

[141]:
```
time_start =time.time()

ks = [1, 2, 3, 5, 7, 10, 15, 20, 25, 30]

# ================================================================ #
# YOUR CODE HERE:
#   Calculate the cross-validation error for each k in ks, testing
#   the trained model on each of the 5 folds.  Average these errors
#   together and make a plot of k vs. cross-validation error. Since
#   we are assuming L2 distance here, please use the vectorized code!
#   Otherwise, you might be waiting a long time.
# ================================================================ #

# preallocations
num_k = len(ks)
xerror = np.zeros(num_folds)
av_error = np.zeros(num_k)

# iterating through all the k values
for k in np.arange(num_k):
    # iterating through all the folds
    for i in np.arange(num_folds):
        # choosing the fold for validation
        X_val_fold = X_train_folds[i]
```

```
        y_val_fold = y_train_folds[i]

        # preallocations
        X_train_sfold = []
        y_train_sfold = []

        # assigning the rest of the folds to be used for training
        for l in np.arange(num_folds):
            if l != i:
                X_train_sfold.extend(X_train_folds[l])
                y_train_sfold.extend(y_train_folds[l])

        # converting list to array
        X_train_sfold = np.array(X_train_sfold)
        y_train_sfold = np.array(y_train_sfold)
        # print(np.shape(X_train_sfold))

        knn.train(X=X_train_sfold, y=y_train_sfold)
        dists_fold = knn.compute_L2_distances_vectorized(X=X_val_fold)

        y_pred = knn.predict_labels(dists_fold,ks[k])
        num_incorrect = np.count_nonzero((y_pred-y_val_fold))
        xerror[i] = num_incorrect/len(y_val_fold)

    av_error[k] = 1/num_folds*np.sum(xerror)

min_id = np.argmin(av_error)
plt.plot(ks,av_error)
plt.title('Nearest Neighbors, k Optimization')
plt.xlabel('k')
plt.ylabel('cross-validation error')
print('Optimum k value = %d, with error = %f' %(ks[min_id],av_error[min_id]))

# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #

print('Computation time: %.2f'%(time.time()-time_start))
```

```
Optimum k value = 10, with error = 0.719800
Computation time: 19.98
```



2.1 Questions:

(1) What value of k is best amongst the tested k's?

(2) What is the cross-validation error for this value of k?

2.2 Answers:

(1) k=10 is the best amongst the tested k values.

(2) The cross-validation error for this value is 0.71980.

2.2.1 Optimizing the norm

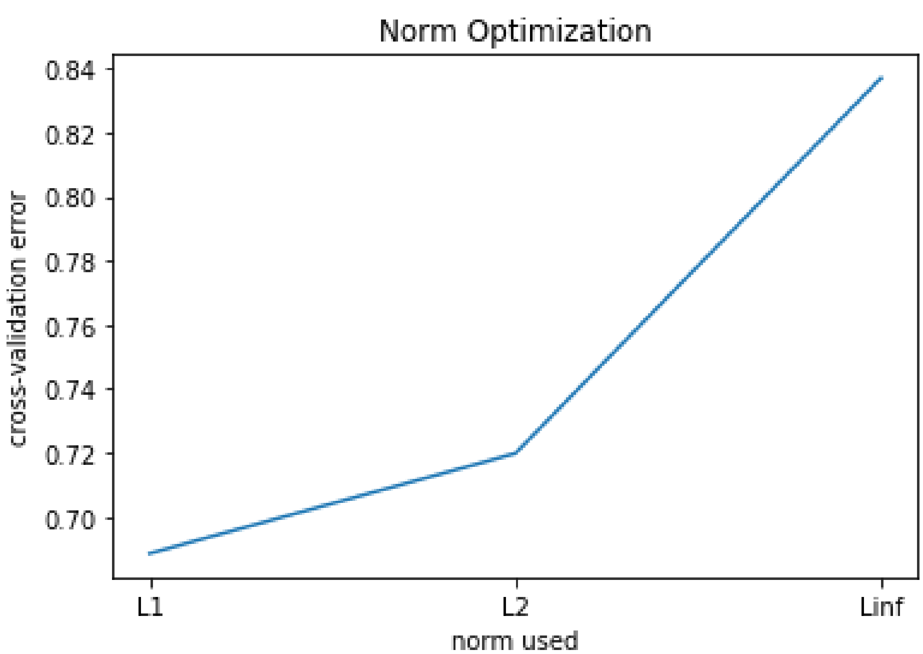
Next, we test three different norms (the 1, 2, and infinity norms) and see which distance metric results in the best cross-validation performance.

[145]:
```
time_start =time.time()

L1_norm = lambda x: np.linalg.norm(x, ord=1)
L2_norm = lambda x: np.linalg.norm(x, ord=2)
Linf_norm = lambda x: np.linalg.norm(x, ord= np.inf)
norms = [L1_norm, L2_norm, Linf_norm]

# ================================================================ #
```

```
# YOUR CODE HERE:
#   Calculate the cross-validation error for each norm in norms, testing
#   the trained model on each of the 5 folds.  Average these errors
#   together and make a plot of the norm used vs the cross-validation error
#   Use the best cross-validation k from the previous part.
#
#   Feel free to use the compute_distances function.  We're testing just
#   three norms, but be advised that this could still take some time.
#   You're welcome to write a vectorized form of the L1- and Linf- norms
#   to speed this up, but it is not necessary.
# ================================================================ #

# preallocations
num_norm = len(norms)
xerror = np.zeros(num_folds)
av_error = np.zeros(num_norm)
# k = 10
k_opt = ks[min_id]
# print(k_opt)

# iterating through all the k values
for k in np.arange(num_norm):
    # iterating through all the folds
    for i in np.arange(num_folds):
        #knn = KNN()

        # choosing the fold for validation
        X_val_fold = X_train_folds[i]
        y_val_fold = y_train_folds[i]

        # preallocations
        X_train_sfold = []
        y_train_sfold = []

        # assigning the rest of the folds to be used for training
        for l in np.arange(num_folds):
            if l != i:
                X_train_sfold.extend(X_train_folds[l])
                y_train_sfold.extend(y_train_folds[l])

        # converting list to array
        X_train_sfold = np.array(X_train_sfold)
        y_train_sfold = np.array(y_train_sfold)
        # print(np.shape(X_train_sfold))

        knn.train(X=X_train_sfold, y=y_train_sfold)
        dists_fold = knn.compute_distances(X = X_val_fold, norm=norms[k])
```

```
        y_pred = knn.predict_labels(dists_fold,k_opt)
        num_incorrect = np.count_nonzero((y_pred-y_val_fold))
        xerror[i] = num_incorrect/len(y_val_fold)

    av_error[k] = 1/num_folds*np.sum(xerror)

norm_name = ["L1","L2","Linf"]

plt.plot(norm_name,av_error)
plt.title('Norm Optimization')
plt.xlabel('norm used')
plt.ylabel('cross-validation error')



# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
print('Computation time: %.2f'%(time.time()-time_start))
```

```
10
Computation time: 555.03
```



2.3 Questions:

(1) What norm has the best cross-validation error?

(2) What is the cross-validation error for your given norm and k?

2.4 Answers:

(1) The best cross-validation error is of the L1 norm

(2) The cross validation error for the L1 norm and k=10 is equal to 0.6886

3 Evaluating the model on the testing dataset.

Now, given the optimal k and norm you found in earlier parts, evaluate the testing error of the k-nearest neighbors model.

[148]:
```
error = 1

# ================================================================ #
# YOUR CODE HERE:
#   Evaluate the testing error of the k-nearest neighbors classifier
#   for your optimal hyperparameters found by 5-fold cross-validation.
# ================================================================ #

knn.train(X=X_train, y=y_train)

norm_opt = norms[1]
dists_L1= knn.compute_distances(X = X_test, norm = norm_opt)
y_pred = knn.predict_labels(dists_L1,k_opt)
num_incorrect = np.count_nonzero((y_pred-y_test))
error = num_incorrect/len(y_test)

# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #

print('Error rate achieved: {}'.format(error))
```

```
Error rate achieved: 0.718
```

3.1 Question:

How much did your error improve by cross-validation over naively choosing $k = 1$ and using the L2-norm?

3.2 Answer:

It improved from 0.726 to 0.718 which is about a 1% improvement

1.3 knn.py

```
import numpy as np
import pdb

"""
This code was based off of code from cs231n at Stanford University, and ...
    modified for ECE C147/C247 at UCLA.
"""

class KNN(object):

  def __init__(self):
    pass

  def train(self, X, y):
    """
    Inputs:
    - X is a numpy array of size (num_examples, D)
    - y is a numpy array of size (num_examples, )
    """
    self.X_train = X
    self.y_train = y

  def compute_distances(self, X, norm=None):
    """
    Compute the distance between each test point in X and each training ...
        point
    in self.X_train.

    Inputs:
    - X: A numpy array of shape (num_test, D) containing test data.
```

```
    - norm: the function with which the norm is taken.

    Returns:
    - dists: A numpy array of shape (num_test, num_train) where ...
       dists[i, j]
      is the Euclidean distance between the ith test point and the jth ...
         training
      point.
    """
    if norm is None:
      norm = lambda x: np.sqrt(np.sum(x**2))
      #norm = 2

    num_test = X.shape[0]
    num_train = self.X_train.shape[0]
    dists = np.zeros((num_test, num_train))
    for i in np.arange(num_test):

      for j in np.arange(num_train):
        # ...
           ================================================================ ...
           #
        # YOUR CODE HERE:
        #   Compute the distance between the ith test point and the jth
        #   training point using norm(), and store the result in ...
           dists[i, j].
        # ...
           ================================================================ ...
           #
        dists[i,j] = norm(X[i]-self.X_train[j])

        # ...
           ================================================================ ...
```

```
            # ...
                =================================================================== ...
                #
        # END YOUR CODE HERE
        # ...
            =================================================================== ...
            #

    return dists

  def compute_L2_distances_vectorized(self, X):
    """
    Compute the distance between each test point in X and each training ...
        point
    in self.X_train WITHOUT using any for loops.

    Inputs:
    - X: A numpy array of shape (num_test, D) containing test data.

    Returns:
    - dists: A numpy array of shape (num_test, num_train) where ...
        dists[i, j]
      is the Euclidean distance between the ith test point and the jth ...
          training
      point.
    """
    num_test = X.shape[0]
    num_train = self.X_train.shape[0]
    dists = np.zeros((num_test, num_train))

    # ================================================================ #
    # YOUR CODE HERE:
    #   Compute the L2 distance between the ith test point and the jth
    #   training point and store the result in dists[i, j].  You may
    #   NOT use a for loop (or list comprehension).  You may only use
```

```
    #   numpy operations.
    #
    #   HINT: use broadcasting.  If you have a shape (N,1) array and
    #   a shape (M,) array, adding them together produces a shape (N, M)
    #   array.
    # ================================================================ #

    # euclidean norm = sqrt((xi-yj)^2) -> sqrt(xi^2+yj^2-2*xiyj)
    # shape sizes
    # (500,1)+(5000,) - 2* (500,5000)
    # note axis 1 sums along rows
    dists = np.sqrt(np.sum(X**2,axis = ...
        1,keepdims=True)+np.sum(self.X_train**2,axis=1)-2*np.dot(X,self.X_train.T))

    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return dists


  def predict_labels(self, dists, k=1):
    """
    Given a matrix of distances between test points and training points,
    predict a label for each test point.

    Inputs:
    - dists: A numpy array of shape (num_test, num_train) where ...
        dists[i, j]
      gives the distance betwen the ith test point and the jth training ...
          point.

    Returns:
```

```
    - y: A numpy array of shape (num_test,) containing predicted labels ...
        for the
      test data, where y[i] is the predicted label for the test point X[i].
    """
    num_test = dists.shape[0]
    y_pred = np.zeros(num_test)
    for i in np.arange(num_test):
      # A list of length k storing the labels of the k nearest ...
          neighbors to
      # the ith test point.
      closest_y = []
      # ...
          ================================================================ ...
          #
      # YOUR CODE HERE:
      #   Use the distances to calculate and then store the labels of
      #   the k-nearest neighbors to the ith test point.  The function
      #   numpy.argsort may be useful.
      #
      #   After doing this, find the most common label of the k-nearest
      #   neighbors.  Store the predicted label of the ith training example
      #   as y_pred[i].  Break ties by choosing the smaller label.
      # ...
          ================================================================ ...
          #

      sortedIdxs = np.argsort(dists[i])
      closest_y = self.y_train[sortedIdxs[:k]]
      y_pred[i] = np.argmax(np.bincount(closest_y))

      # ...
          ================================================================ ...
          #
```

```
        # END YOUR CODE HERE
        # ...
            ============================================================ ...
            #

    return y_pred
```

2 Support Vector Machine

2.1 Problem Statement

(40 points) Support vector machine. Complete the SVM Jupyter notebook. Print out the entire workbook and related code sections in svm.py, then submit them as a pdf to gradescope.

2.2 Jupyter Results

svm

January 26, 2021

0.1 This is the svm workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement a linear support vector machine.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and includes code to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with training an SVM classifier via gradient descent.

0.2 Importing libraries and data setup

[1]:
```
import numpy as np # for doing most of our calculations
import matplotlib.pyplot as plt# for plotting
from cs231n.data_utils import load_CIFAR10 # function to load the CIFAR-10␣
 ↪dataset.
import pdb

# Load matplotlib images inline
%matplotlib inline

# These are important for reloading any code you write in external .py files.
# see http://stackoverflow.com/questions/1907993/
 ↪autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

[511]:
```
# Set the path to the CIFAR-10 data
cifar10_dir = 'cifar-10-batches-py' # You need to update this line
X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Training data shape:  (50000, 32, 32, 3)
Training labels shape:  (50000,)
Test data shape:  (10000, 32, 32, 3)
Test labels shape:  (10000,)
```

[512]:
```
# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse',␣
↪'ship', 'truck']
num_classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples_per_class, num_classes, plt_idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()
```

[513]:
```
# Split the data into train, val, and test sets. In addition we will
# create a small development set as a subset of the training data;
# we can use this for development so our code runs faster.
num_training = 49000
num_validation = 1000
num_test = 1000
num_dev = 500

# Our validation set will be num_validation points from the original
# training set.
mask = range(num_training, num_training + num_validation)
X_val = X_train[mask]
y_val = y_train[mask]

# Our training set will be the first num_train points from the original
# training set.
mask = range(num_training)
X_train = X_train[mask]
y_train = y_train[mask]

# We will also make a development set, which is a small subset of
# the training set.
mask = np.random.choice(num_training, num_dev, replace=False)
X_dev = X_train[mask]
y_dev = y_train[mask]

# We use the first num_test points of the original test set as our
# test set.
mask = range(num_test)
X_test = X_test[mask]
y_test = y_test[mask]

print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
print('Dev data shape: ', X_dev.shape)
print('Dev labels shape: ', y_dev.shape)
```

```
Train data shape:  (49000, 32, 32, 3)
Train labels shape:  (49000,)
Validation data shape:  (1000, 32, 32, 3)
Validation labels shape:  (1000,)
Test data shape:  (1000, 32, 32, 3)
Test labels shape:  (1000,)
Dev data shape:  (500, 32, 32, 3)
```

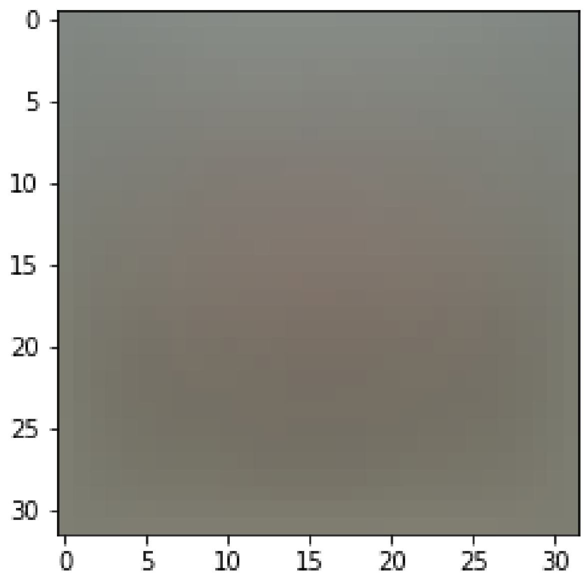
```
Dev labels shape:  (500,)
```

[514]:
```
# Preprocessing: reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_val = np.reshape(X_val, (X_val.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))

# As a sanity check, print out the shapes of the data
print('Training data shape: ', X_train.shape)
print('Validation data shape: ', X_val.shape)
print('Test data shape: ', X_test.shape)
print('dev data shape: ', X_dev.shape)
```

```
Training data shape:  (49000, 3072)
Validation data shape:  (1000, 3072)
Test data shape:  (1000, 3072)
dev data shape:  (500, 3072)
```

[515]:
```
# Preprocessing: subtract the mean image
# first: compute the image mean based on the training data
mean_image = np.mean(X_train, axis=0)
print(mean_image[:10]) # print a few of the elements
plt.figure(figsize=(4,4))
plt.imshow(mean_image.reshape((32,32,3)).astype('uint8')) # visualize the mean␣
↪image
plt.show()
```

```
[130.64189796 135.98173469 132.47391837 130.05569388 135.34804082
 131.75402041 130.96055102 136.14328571 132.47636735 131.48467347]
```



[516]:
```
# second: subtract the mean image from train and test data
X_train -= mean_image
X_val -= mean_image
X_test -= mean_image
X_dev -= mean_image
```

[517]:
```
# third: append the bias dimension of ones (i.e. bias trick) so that our SVM
# only has to worry about optimizing a single weight matrix W.
X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

print(X_train.shape, X_val.shape, X_test.shape, X_dev.shape)
```

```
(49000, 3073) (1000, 3073) (1000, 3073) (500, 3073)
```

0.3 Question:

(1) For the SVM, we perform mean-subtraction on the data. However, for the KNN notebook, we did not. Why?

0.4 Answer:

(1) For SVM mean-subtraction is performed because we want to "center" the data while in KNN we measure distances between points in order to distinguish classes so mean-subtraction would not do anything.

0.5 Training an SVM

The following cells will take you through building an SVM. You will implement its loss function, then subsequently train it with gradient descent. Finally, you will choose the learning rate of gradient descent to optimize its classification performance.

[518]:
```
from nndl.svm import SVM
```

[519]:
```
# Declare an instance of the SVM class.
# Weights are initialized to a random value.
# Note, to keep people's initial solutions consistent, we are going to use a␣
↪random seed.

np.random.seed(1)

num_classes = len(np.unique(y_train))
num_features = X_train.shape[1]

svm = SVM(dims=[num_classes, num_features])
```

SVM loss

[520]:
```
## Implement the loss function for in the SVM class(nndl/svm.py), svm.loss()

loss = svm.loss(X_train, y_train)
print('The training set loss is {}.'.format(loss))

# If you implemented the loss correctly, it should be 15569.98
```

```
The training set loss is 15569.977915410187.
```

[ ]:
```
```

SVM gradient

[521]:
```
## Calculate the gradient of the SVM class.
# For convenience, we'll write one function that computes the loss
#   and gradient together. Please modify svm.loss_and_grad(X, y).
# You may copy and paste your loss code from svm.loss() here, and then
#   use the appropriate intermediate values to calculate the gradient.

loss, grad = svm.loss_and_grad(X_dev,y_dev)

# Compare your gradient to a numerical gradient check.
# You should see relative gradient errors on the order of 1e-07 or less if you␣
↪implemented the gradient correctly.
svm.grad_check_sparse(X_dev, y_dev, grad)
```

```
numerical: -3.681664 analytic: -3.681663, relative error: 2.542594e-08
numerical: 4.343144 analytic: 4.343143, relative error: 1.075819e-07
numerical: -3.260883 analytic: -3.260883, relative error: 9.346886e-09
```

```
numerical: 18.110456 analytic: 18.110456, relative error: 4.575248e-09
numerical: 10.624520 analytic: 10.624521, relative error: 2.793705e-08
numerical: 5.241199 analytic: 5.241198, relative error: 3.918448e-08
numerical: 5.384190 analytic: 5.384190, relative error: 5.281280e-08
numerical: -3.250758 analytic: -3.250758, relative error: 2.035146e-09
numerical: -6.618687 analytic: -6.618686, relative error: 3.693142e-08
numerical: -17.852199 analytic: -17.852198, relative error: 5.444536e-09
```

0.6 A vectorized version of SVM

To speed things up, we will vectorize the loss and gradient calculations. This will be helpful for stochastic gradient descent.

[522]:
```
import time
```

[523]:
```
## Implement svm.fast_loss_and_grad which calculates the loss and gradient
#    WITHOUT using any for loops.

# Standard loss and gradient
tic = time.time()
loss, grad = svm.loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Normal loss / grad_norm: {} / {} computed in {}s'.format(loss, np.linalg.
 ↪norm(grad, 'fro'), toc - tic))

tic = time.time()
loss_vectorized, grad_vectorized = svm.fast_loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Vectorized loss / grad: {} / {} computed in {}s'.format(loss_vectorized,␣
 ↪np.linalg.norm(grad_vectorized, 'fro'), toc - tic))

# The losses should match but your vectorized implementation should be much␣
 ↪faster.
print('difference in loss / grad: {} / {}'.format(loss - loss_vectorized, np.
 ↪linalg.norm(grad - grad_vectorized)))

# You should notice a speedup with the same output, i.e., differences on the␣
 ↪order of 1e-12
```

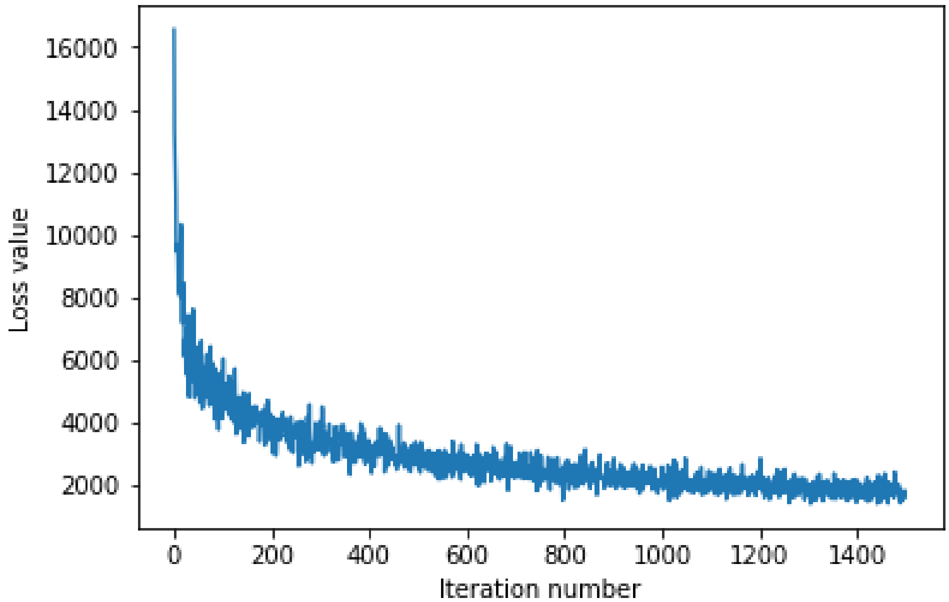
```
Normal loss / grad_norm: 15816.57339070797 / 2205.1819144473743 computed in
0.10318613052368164s
Vectorized loss / grad: 15816.573390707988 / 2205.1819144473743 computed in
0.0050106048583984375s
difference in loss / grad: -1.8189894035458565e-11 / 2.6413939701336207e-12
```

0.7 Stochastic gradient descent

We now implement stochastic gradient descent. This uses the same principles of gradient descent we discussed in class, however, it calculates the gradient by only using examples from a subset of the training set (so each gradient calculation is faster).

[524]:
```
# Implement svm.train() by filling in the code to extract a batch of data
# and perform the gradient step.

tic = time.time()
loss_hist = svm.train(X_train, y_train, learning_rate=5e-4,
                      num_iters=1500, verbose=True)
toc = time.time()
print('That took {}s'.format(toc - tic))

plt.plot(loss_hist)
plt.xlabel('Iteration number')
plt.ylabel('Loss value')
plt.show()
```

```
iteration 0 / 1500: loss 16557.38000190916
iteration 100 / 1500: loss 4701.089451272714
iteration 200 / 1500: loss 4017.333137942788
iteration 300 / 1500: loss 3681.9226471953625
iteration 400 / 1500: loss 2732.6164373988995
iteration 500 / 1500: loss 2786.6378424645045
iteration 600 / 1500: loss 2837.035784278268
iteration 700 / 1500: loss 2206.234868739933
iteration 800 / 1500: loss 2269.038824116981
iteration 900 / 1500: loss 2543.23781538592
iteration 1000 / 1500: loss 2566.6921357268257
iteration 1100 / 1500: loss 2182.0689059051633
iteration 1200 / 1500: loss 1861.1182244250447
iteration 1300 / 1500: loss 1982.9013858528256
iteration 1400 / 1500: loss 1927.5204158582117
That took 4.7113938331604s
```



0.7.1 Evaluate the performance of the trained SVM on the validation data.

[525]:
```
## Implement svm.predict() and use it to compute the training and testing error.

y_train_pred = svm.predict(X_train)
print('training accuracy: {}'.format(np.mean(np.equal(y_train,y_train_pred), )))
y_val_pred = svm.predict(X_val)
print('validation accuracy: {}'.format(np.mean(np.equal(y_val, y_val_pred)), ))
```

```
training accuracy: 0.28530612244897957
validation accuracy: 0.3
```

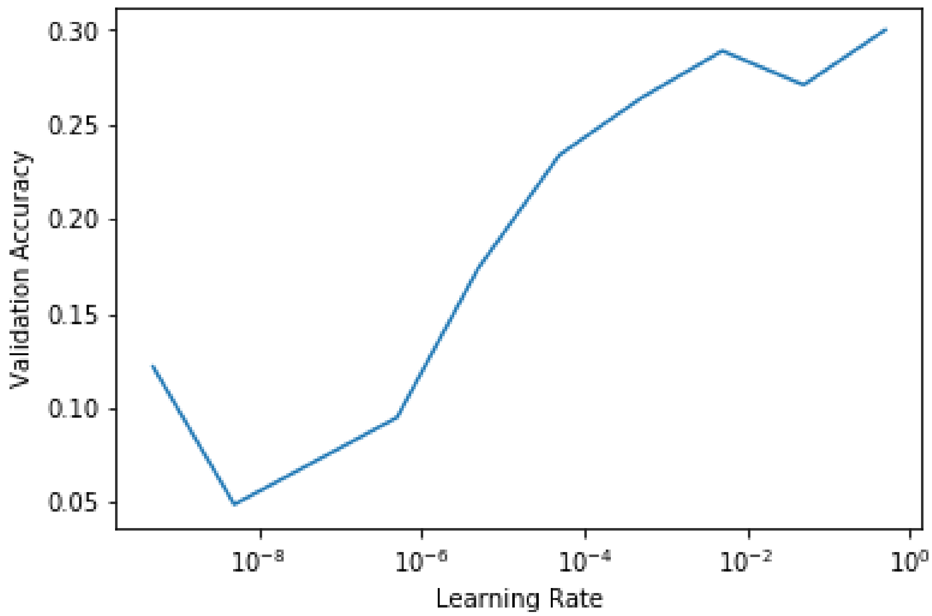
0.8 Optimize the SVM

Note, to make things faster and simpler, we won't do k-fold cross-validation, but will only optimize the hyperparameters on the validation dataset (X_val, y_val).

[526]:
```
# ================================================================ #
# YOUR CODE HERE:
#   Train the SVM with different learning rates and evaluate on the
#     validation data.
#   Report:
#     - The best learning rate of the ones you tested.
#     - The best VALIDATION accuracy corresponding to the best VALIDATION error.
#
```

```
#   Select the SVM that achieved the best validation error and report
#     its error rate on the test set.
#   Note: You do not need to modify SVM class for this section
# ================================================================ #
epsilon = 5*np.logspace(-10,-1,num = 10)
val_acc = np.zeros_like(epsilon)

ep_opt = 0
val_opt = 0

for i in np.arange(len(epsilon)):

    svm.train(X_train, y_train, learning_rate=epsilon[i],num_iters=1500,␣
↪verbose=False)
    y_val_pred = svm.predict(X_val)
    val_acc[i] = np.mean(np.equal(y_val, y_val_pred))

    if val_acc[i]> val_opt:
        val_opt = val_acc[i]
        ep_opt = epsilon[i]


print('Optimal epsilon = %4.3e with validation accuracy %4.3f'␣
↪%(ep_opt,val_opt))
plt.semilogx(epsilon,val_acc)
plt.xlabel('Learning Rate')
plt.ylabel('Validation Accuracy')
plt.show()

svm.train(X_train, y_train, learning_rate=ep_opt,num_iters=1500, verbose=False)
y_test_pred = svm.predict(X_test)
test_err = 1-np.mean(np.equal(y_test, y_test_pred))
print('Optimal epsilon = %4.3e with test error %4.3f' %(ep_opt,test_err))
# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
```

```
Optimal epsilon = 5.000e-01 with validation accuracy 0.300
```




```
Optimal epsilon = 5.000e-01 with test error 0.741
```

[ ]:

2.3 svm.py

```
import numpy as np
import pdb

"""
This code was based off of code from cs231n at Stanford University, and ...
    modified for ECE C147/C247 at UCLA.
"""
class SVM(object):

  def __init__(self, dims=[10, 3073]):
    self.init_weights(dims=dims)

  def init_weights(self, dims):
    """
    Initializes the weight matrix of the SVM.  Note that it has shape ...
        (C, D)
    where C is the number of classes and D is the feature size.
    """
    self.W = np.random.normal(size=dims)

  def loss(self, X, y):
    """
    Calculates the SVM loss.

    Inputs have dimension D, there are C classes, and we operate on ...
        minibatches
    of N examples.

    Inputs:
    - X: A numpy array of shape (N, D) containing a minibatch of data.
```

```
    - y: A numpy array of shape (N,) containing training labels; y[i] = ...
       c means
      that X[i] has label c, where 0 ≤ c < C.

    Returns a tuple of:
    - loss as single float
    """

    # compute the loss and the gradient
    num_classes = self.W.shape[0]
    num_train = X.shape[0]
    loss = 0.0

    for i in np.arange(num_train):
    # ================================================================ #
    # YOUR CODE HERE:
      #   Calculate the normalized SVM loss, and store it as 'loss'.
    #   (That is, calculate the sum of the losses of all the training
    #   set margins, and then normalize the loss by the number of
      #   training examples.)
    # ================================================================ #
      a = self.W.dot(X[i].T) #(C,1)

      for j in np.arange(num_classes):
        if j != y[i]:
          hinge = np.maximum(0,1+a[j]-a[y[i]])
          loss += hinge
    loss = 1/num_train*(loss)

    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

```

```
    return loss

  def loss_and_grad(self, X, y):
    """
    Same as self.loss(X, y), except that it also returns the gradient.

    Output: grad -- a matrix of the same dimensions as W containing
        the gradient of the loss with respect to W.
    """

    # compute the loss and the gradient
    num_classes = self.W.shape[0]
    num_train = X.shape[0]
    loss = 0.0
    grad = np.zeros_like(self.W)

    for i in np.arange(num_train):
    # ================================================================ #
    # YOUR CODE HERE:
      #   Calculate the SVM loss and the gradient.  Store the gradient in
    #   the variable grad.
    # ================================================================ #
      a = self.W.dot(X[i].T) #(C,1)

      for j in np.arange(num_classes):
        zj = 1+a[j]-a[y[i]]

        #defining indicator function
        if zj > 0:
          ind = 1
        else:
          ind = 0

```

```
        if j != y[i]:
          hinge = np.maximum(0,zj)
          loss += hinge
          grad[j] += ind*X[i] #(1,D)
          grad[y[i]] -= ind*X[i]

    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    loss /= num_train
    grad /= num_train

    return loss, grad

  def grad_check_sparse(self, X, y, your_grad, num_checks=10, h=1e-5):
    """
    sample a few random elements and only return numerical
    in these dimensions.
    """

    for i in np.arange(num_checks):
      ix = tuple([np.random.randint(m) for m in self.W.shape])

      oldval = self.W[ix]
      self.W[ix] = oldval + h # increment by h
      fxph = self.loss(X, y)
      self.W[ix] = oldval - h # decrement by h
      fxmh = self.loss(X,y) # evaluate f(x - h)
      self.W[ix] = oldval # reset

      grad_numerical = (fxph - fxmh) / (2 * h)
      grad_analytic = your_grad[ix]
```

```
        rel_error = abs(grad_numerical - grad_analytic) / ...
            (abs(grad_numerical) + abs(grad_analytic))
        print('numerical: %f analytic: %f, relative error: %e' % ...
            (grad_numerical, grad_analytic, rel_error))

    def fast_loss_and_grad(self, X, y):
      """
      A vectorized implementation of loss_and_grad. It shares the same
      inputs and ouptuts as loss_and_grad.
      """
      loss = 0.0
      grad = np.zeros(self.W.shape) # initialize the gradient as zero

      # ================================================================ #
      # YOUR CODE HERE:
        #   Calculate the SVM loss WITHOUT any for loops.
      # ================================================================ #
      # preallocations
      a = X.dot(self.W.T) #size (N,C)
      num_train = a.shape[0]
      # num_class = a.shape[1]

      a_ind = [np.arange(num_train),y]
      hinge = np.maximum(np.zeros_like(a),np.ones_like(a)+(a.T-a[a_ind]).T)

      # for j = yi hingeloss = 0
      hinge[a_ind] = 0
      loss = np.sum(hinge)
      loss = 1/num_train*(loss)

      # ================================================================ #
      # END YOUR CODE HERE
      # ================================================================ #
```

```



    # ================================================================ #
    # YOUR CODE HERE:
    #   Calculate the SVM grad WITHOUT any for loops.
    # ================================================================ #
    # defining indicator function
    ind = hinge #(N,C)
    ind[ind>0] = 1

    # summing through all the training samples
    sumyi = np.sum(ind, axis =1)
    # changing j = yi indices to -sum of j!=i
    ind[a_ind] = -sumyi.T
    grad = ind.T.dot(X) # (C,D)
    grad = 1/num_train*(grad)

    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return loss, grad

  def train(self, X, y, learning_rate=1e-3, num_iters=100,
            batch_size=200, verbose=False):
    """
    Train this linear classifier using stochastic gradient descent.

    Inputs:
    - X: A numpy array of shape (N, D) containing training data; there ...
       are N
      training samples each of dimension D.
```

```
    - y: A numpy array of shape (N,) containing training labels; y[i] = c
      means that X[i] has label 0 ≤ c < C for C classes.
    - learning_rate: (float) learning rate for optimization.
    - num_iters: (integer) number of steps to take when optimizing
    - batch_size: (integer) number of training examples to use at each ...
        step.
    - verbose: (boolean) If true, print progress during optimization.

    Outputs:
    A list containing the value of the loss function at each training ...
        iteration.
    """
    num_train, dim = X.shape
    num_classes = np.max(y) + 1 # assume y takes values 0...K-1 where K ...
        is number of classes

    self.init_weights(dims=[np.max(y) + 1, X.shape[1]]) # initializes ...
        the weights of self.W

    # Run stochastic gradient descent to optimize W
    loss_history = []

    for it in np.arange(num_iters):
      X_batch = None
      y_batch = None

      # ...
          ================================================================= ...
          #
      # YOUR CODE HERE:
      #   Sample batch_size elements from the training data for use in
      #   gradient descent.  After sampling,
      #     - X_batch should have shape: (dim, batch_size)
```

```
        #     - y_batch should have shape: (batch_size,)
        #   The indices should be randomly generated to reduce correlations
        #   in the dataset.  Use np.random.choice.  It's okay to sample ...
           with
        #   replacement.
      # ...
          ================================================================ ...
          #
      index = np.random.choice(num_train,batch_size)
      X_batch = X[index]
      y_batch = y[index]
      # ...
          ================================================================ ...
          #
      # END YOUR CODE HERE
      # ...
          ================================================================ ...
          #

      # evaluate loss and gradient
      loss, grad = self.fast_loss_and_grad(X_batch, y_batch)
      loss_history.append(loss)

      # ...
          ================================================================ ...
          #
      # YOUR CODE HERE:
      #   Update the parameters, self.W, with a gradient step
      # ...
          ================================================================ ...
          #
      self.W = self.W - learning_rate*grad
```

```
        # ...
            ================================================================= ...
            #
      # END YOUR CODE HERE
      # ...
          ================================================================= ...
          #

      if verbose and it % 100 == 0:
        print('iteration {} / {}: loss {}'.format(it, num_iters, loss))

    return loss_history

  def predict(self, X):
    """
    Inputs:
    - X: N x D array of training data. Each row is a D-dimensional point.

    Returns:
    - y_pred: Predicted labels for the data in X. y_pred is a 1-dimensional
      array of length N, and each element is an integer giving the ...
          predicted
      class.
    """
    y_pred = np.zeros(X.shape[1])


    # ================================================================= #
    # YOUR CODE HERE:
    #   Predict the labels given the training data with the parameter ...
          self.W.
    # ================================================================= #
    y_pred = np.argmax(X.dot(self.W.T),axis=1)
```

```
    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return y_pred
```

3 Softmax

3.1 Problem Statement

(40 points) Softmax classifier. Complete the Softmax Jupyter notebook. Print out the entire workbook and related code sections in softmax.py, then submit them as a pdf to gradescope.

3.2 Jupyter Results

softmax

January 26, 2021

0.1 This is the softmax workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement a softmax classifier.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and code in the jupyer notebook to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with training a softmax classifier.

[1]:
```
import random
import numpy as np
from cs231n.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

%matplotlib inline
%load_ext autoreload
%autoreload 2
```

[48]:
```
def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000,␣
↪num_dev=500):
    """
    Load the CIFAR-10 dataset from disk and perform preprocessing to prepare
    it for the linear classifier. These are the same steps as we used for the
    SVM, but condensed to a single function.
    """
    # Load the raw CIFAR-10 data
    cifar10_dir = 'cifar-10-batches-py' # You need to update this line
    X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

    # subsample the data
    mask = list(range(num_training, num_training + num_validation))
    X_val = X_train[mask]
    y_val = y_train[mask]
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]
```

```
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]
    mask = np.random.choice(num_training, num_dev, replace=False)
    X_dev = X_train[mask]
    y_dev = y_train[mask]

    # Preprocessing: reshape the image data into rows
    X_train = np.reshape(X_train, (X_train.shape[0], -1))
    X_val = np.reshape(X_val, (X_val.shape[0], -1))
    X_test = np.reshape(X_test, (X_test.shape[0], -1))
    X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))

    # Normalize the data: subtract the mean image
    mean_image = np.mean(X_train, axis = 0)
    X_train -= mean_image
    X_val -= mean_image
    X_test -= mean_image
    X_dev -= mean_image

    # add bias dimension and transform into columns
    X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
    X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
    X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
    X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

    return X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev


# Invoke the above function to get our data.
X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev =␣
↪get_CIFAR10_data()
print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
print('dev data shape: ', X_dev.shape)
print('dev labels shape: ', y_dev.shape)
```

```
Train data shape:  (49000, 3073)
Train labels shape:  (49000,)
Validation data shape:  (1000, 3073)
Validation labels shape:  (1000,)
Test data shape:  (1000, 3073)
Test labels shape:  (1000,)
dev data shape:  (500, 3073)
```

```
dev labels shape:  (500,)
```

0.2 Training a softmax classifier.

The following cells will take you through building a softmax classifier. You will implement its loss function, then subsequently train it with gradient descent. Finally, you will choose the learning rate of gradient descent to optimize its classification performance.

[49]:
```
from nndl import Softmax
```

[50]:
```
# Declare an instance of the Softmax class.
# Weights are initialized to a random value.
# Note, to keep people's first solutions consistent, we are going to use a␣
↪random seed.

np.random.seed(1)

num_classes = len(np.unique(y_train))
num_features = X_train.shape[1]

softmax = Softmax(dims=[num_classes, num_features])
```

Softmax loss

[51]:
```
## Implement the loss function of the softmax using a for loop over
#  the number of examples

loss = softmax.loss(X_train, y_train)
```

[52]:
```
print(loss)
```

```
2.3277607028048966
```

0.3 Question:

You'll notice the loss returned by the softmax is about 2.3 (if implemented correctly). Why does this make sense?

0.4 Answer:

-log(softmax(x)) = 2.3 which means softmax(x) ~ 0.10. This makes sense because there are ten classes meaning equal probability it could be one of the classes.

Softmax gradient

[53]:
```
## Calculate the gradient of the softmax loss in the Softmax class.
# For convenience, we'll write one function that computes the loss
#   and gradient together, softmax.loss_and_grad(X, y)
# You may copy and paste your loss code from softmax.loss() here, and then
#   use the appropriate intermediate values to calculate the gradient.
```

```
loss, grad = softmax.loss_and_grad(X_dev,y_dev)

# Compare your gradient to a gradient check we wrote.
# You should see relative gradient errors on the order of 1e-07 or less if you␣
↪implemented the gradient correctly.
softmax.grad_check_sparse(X_dev, y_dev, grad)
```

```
numerical: 0.037523 analytic: 0.037523, relative error: 3.387207e-07
numerical: 1.437461 analytic: 1.437461, relative error: 2.819630e-08
numerical: -0.726794 analytic: -0.726794, relative error: 9.528998e-09
numerical: 1.543500 analytic: 1.543500, relative error: 1.314298e-08
numerical: -0.511871 analytic: -0.511871, relative error: 1.320853e-07
numerical: 1.243152 analytic: 1.243152, relative error: 1.538739e-08
numerical: -0.451246 analytic: -0.451246, relative error: 1.064016e-07
numerical: -1.734786 analytic: -1.734786, relative error: 9.860642e-09
numerical: 0.414030 analytic: 0.414030, relative error: 6.750906e-09
numerical: -1.058630 analytic: -1.058630, relative error: 2.340584e-08
```

0.5 A vectorized version of Softmax

To speed things up, we will vectorize the loss and gradient calculations. This will be helpful for stochastic gradient descent.

[54]:
```
import time
```

[55]:
```
## Implement softmax.fast_loss_and_grad which calculates the loss and gradient
#    WITHOUT using any for loops.

# Standard loss and gradient
tic = time.time()
loss, grad = softmax.loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Normal loss / grad_norm: {} / {} computed in {}s'.format(loss, np.linalg.
↪norm(grad, 'fro'), toc - tic))

tic = time.time()
loss_vectorized, grad_vectorized = softmax.fast_loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Vectorized loss / grad: {} / {} computed in {}s'.format(loss_vectorized,␣
↪np.linalg.norm(grad_vectorized, 'fro'), toc - tic))

# The losses should match but your vectorized implementation should be much␣
↪faster.
print('difference in loss / grad: {} /{} '.format(loss - loss_vectorized, np.
↪linalg.norm(grad - grad_vectorized)))

# You should notice a speedup with the same output.
```

```
Normal loss / grad_norm: 2.3613109117810556 / 321.6294577431447 computed in
0.08613395690917969s
Vectorized loss / grad: 2.3613109117810542 / 321.62945774314477 computed in
0.004011392593383789s
difference in loss / grad: 1.3322676295501878e-15 /2.272637193003094e-13
```

0.6 Stochastic gradient descent

We now implement stochastic gradient descent. This uses the same principles of gradient descent we discussed in class, however, it calculates the gradient by only using examples from a subset of the training set (so each gradient calculation is faster).

0.7 Question:

How should the softmax gradient descent training step differ from the svm training step, if at all?

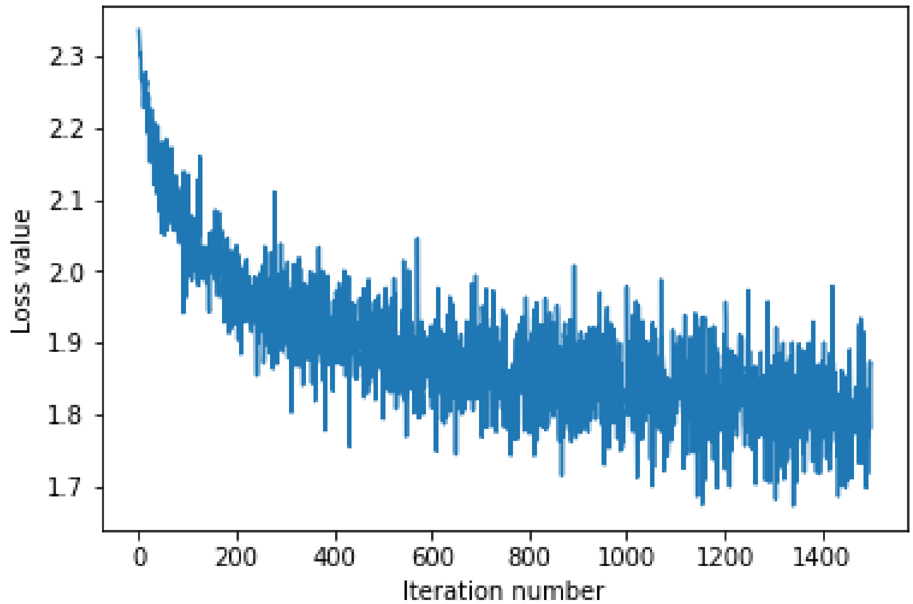
0.8 Answer:

The training step does not differ between the two methods besides the fact they have different loss functions

[56]:
```python
# Implement softmax.train() by filling in the code to extract a batch of data
# and perform the gradient step.
import time


tic = time.time()
loss_hist = softmax.train(X_train, y_train, learning_rate=1e-7,
                      num_iters=1500, verbose=True)
toc = time.time()
print('That took {}s'.format(toc - tic))

plt.plot(loss_hist)
plt.xlabel('Iteration number')
plt.ylabel('Loss value')
plt.show()
```

```
iteration 0 / 1500: loss 2.3365926606637544
iteration 100 / 1500: loss 2.0557222613850827
iteration 200 / 1500: loss 2.035774512066282
iteration 300 / 1500: loss 1.9813348165609888
iteration 400 / 1500: loss 1.9583142443981612
iteration 500 / 1500: loss 1.8622653073541355
iteration 600 / 1500: loss 1.8532611454359385
iteration 700 / 1500: loss 1.835306222372583
iteration 800 / 1500: loss 1.829389246882764
iteration 900 / 1500: loss 1.8992158530357484
iteration 1000 / 1500: loss 1.97835035402523
iteration 1100 / 1500: loss 1.8470797913532633
```

```
iteration 1200 / 1500: loss 1.8411450268664085
iteration 1300 / 1500: loss 1.7910402495792102
iteration 1400 / 1500: loss 1.870580302938226
That took 4.511507749557495s
```



0.8.1 Evaluate the performance of the trained softmax classifier on the validation data.

[57]:
```
## Implement softmax.predict() and use it to compute the training and testing␣
↪error.

y_train_pred = softmax.predict(X_train)
print('training accuracy: {}'.format(np.mean(np.equal(y_train,y_train_pred), )))
y_val_pred = softmax.predict(X_val)
print('validation accuracy: {}'.format(np.mean(np.equal(y_val, y_val_pred)), ))
```

```
training accuracy: 0.3811428571428571
validation accuracy: 0.398
```

0.9 Optimize the softmax classifier

You may copy and paste your optimization code from the SVM here.

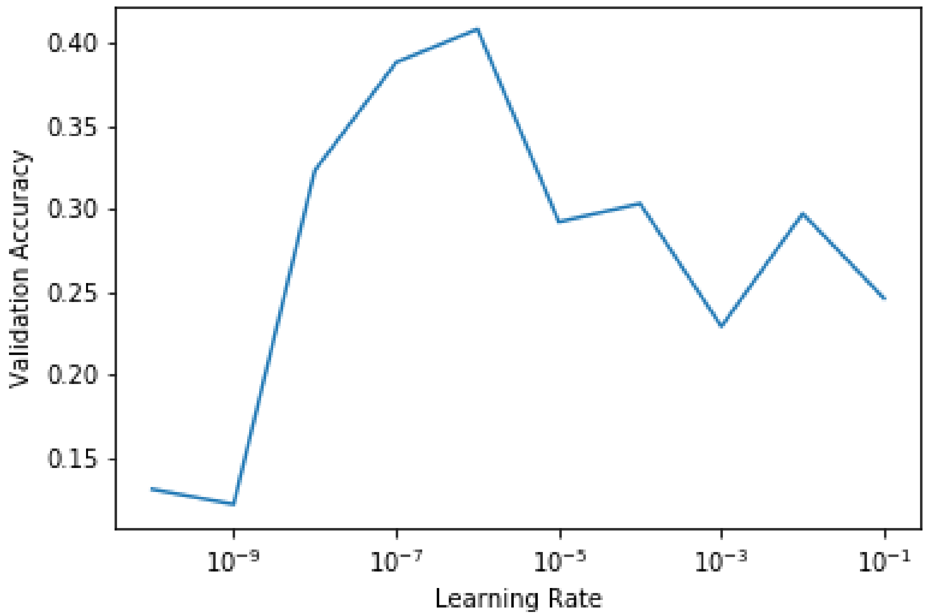
[58]:
```
np.finfo(float).eps
```

[58]: 2.220446049250313e-16

[59]:
```
# ================================================================ #
# YOUR CODE HERE:
#   Train the Softmax classifier with different learning rates and
#     evaluate on the validation data.
#   Report:
#     - The best learning rate of the ones you tested.
#     - The best validation accuracy corresponding to the best validation error.
#
#   Select the SVM that achieved the best validation error and report
#     its error rate on the test set.
# ================================================================ #
epsilon = np.logspace(-10,-1, num=10)
val_acc = np.zeros_like(epsilon)

ep_opt = 0
val_opt = 0

for i in np.arange(len(epsilon)):

    softmax.train(X_train, y_train, learning_rate=epsilon[i],num_iters=1500,␣
 ↪verbose=False)
    y_val_pred = softmax.predict(X_val)
    val_acc[i] = np.mean(np.equal(y_val, y_val_pred))

    if val_acc[i]> val_opt:
        val_opt = val_acc[i]
        ep_opt = epsilon[i]


print('Optimal epsilon = %4.3e with validation accuracy %4.3f'␣
 ↪%(ep_opt,val_opt))
plt.semilogx(epsilon,val_acc)
plt.xlabel('Learning Rate')
plt.ylabel('Validation Accuracy')
plt.show()

softmax.train(X_train, y_train, learning_rate=ep_opt,num_iters=1500,␣
 ↪verbose=False)
y_test_pred = softmax.predict(X_test)
test_err = 1- np.mean(np.equal(y_test, y_test_pred))
print('Optimal epsilon = %4.3e with test error %4.3f' %(ep_opt,test_err))


# ================================================================ #
# END YOUR CODE HERE
```

```
# ================================================================ #
```

Optimal epsilon = 1.000e-06 with validation accuracy 0.408



Optimal epsilon = 1.000e-06 with test error 0.598

[ ]:

3.3 softmax.py

```
import numpy as np

class Softmax(object):

  def __init__(self, dims=[10, 3073]):
    self.init_weights(dims=dims)

  def init_weights(self, dims):
    """
    Initializes the weight matrix of the Softmax classifier.
    Note that it has shape (C, D) where C is the number of
    classes and D is the feature size.
    """
    self.W = np.random.normal(size=dims) * 0.0001

  def loss(self, X, y):
    """
    Calculates the softmax loss.

    Inputs have dimension D, there are C classes, and we operate on ...
        minibatches
    of N examples.

    Inputs:
    - X: A numpy array of shape (N, D) containing a minibatch of data.
    - y: A numpy array of shape (N,) containing training labels; y[i] = ...
        c means
      that X[i] has label c, where 0 ≤ c < C.

    Returns a tuple of:
```

```
    - loss as single float
    """

    # Initialize the loss to zero.
    loss = 0.0

    # ================================================================ #
    # YOUR CODE HERE:
      #   Calculate the normalized softmax loss.  Store it as the ...
          variable loss.
    #   (That is, calculate the sum of the losses of all the training
    #   set margins, and then normalize the loss by the number of
      # training examples.)
    # ================================================================ #

    a = self.W.dot(X.T) #size (C,N)
    num_sample = a.shape[1]
    sumL = 0

    # iterating through all the training samples (columns of a)
    for i in np.arange(num_sample):
      # to avoid overflow, normalize softmax func by logk = -maxai(x) ...
          (maximum value in the column)
      logk= -np.amax(a[:,i])

      # y[i] is the class that the training image belongs to
      # want to extract the score for the first x(i) for class y[i]
      smax = np.exp(a[y[i],i]+logk)/np.sum(np.exp(a[:,i]+logk))
      L_i = -np.log(smax)

      sumL = sumL + L_i
    loss = 1/num_sample*(sumL)

```

```
    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return loss

  def loss_and_grad(self, X, y):
    """
    Same as self.loss(X, y), except that it also returns the gradient.

    Output: grad -- a matrix of the same dimensions as W containing
        the gradient of the loss with respect to W.
    """

    # Initialize the loss and gradient to zero.
    loss = 0.0
    grad = np.zeros_like(self.W)

    # ================================================================ #
    # YOUR CODE HERE:
    #   Calculate the softmax loss and the gradient. Store the gradient
    #   as the variable grad.
    # ================================================================ #

    # calculating loss
    a = self.W.dot(X.T) #size (C,N)
    num_sample = a.shape[1]
    num_class = a.shape[0]

    # iterating through all the training samples (columns of a)
    for i in np.arange(num_sample):
      # avoiding overflow
      logk= -np.amax(a[:,i])
```

```
      a[:,i] += logk

      # iterating through classes
      for j in np.arange(num_class):
        smax = np.exp(a[j,i])/np.sum(np.exp(a[:,i]))
        if y[i] == j:
          # want to take grad of g = -log(smax)
          # dg/dsmax = -1/smax
          # dsmax/da = smax(1-smax)
          # da/dw = x
          # grad[j,:] += -1/smax*smax*(1-smax)*X[i,:]
          grad[j,:] += (smax-1)*X[i,:]

        else:
          # dg/dsmax = -1/smax
          # dsmax/da = -smax(smax)
          # da/dw = x
          # grad[j,:] += -1/smax*(-smax*smax)*X[i,:]
          grad[j,:] += smax*X[i,:]

    loss = self.loss(X,y)

    # calculating gradient
    # (C,D)
    grad = grad/num_sample

    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return loss, grad

  def grad_check_sparse(self, X, y, your_grad, num_checks=10, h=1e-5):
```

```
    """
    sample a few random elements and only return numerical
    in these dimensions.
    """

    for i in np.arange(num_checks):
      ix = tuple([np.random.randint(m) for m in self.W.shape])

      oldval = self.W[ix]
      self.W[ix] = oldval + h # increment by h
      fxph = self.loss(X, y)
      self.W[ix] = oldval - h # decrement by h
      fxmh = self.loss(X,y) # evaluate f(x - h)
      self.W[ix] = oldval # reset

      grad_numerical = (fxph - fxmh) / (2 * h)
      grad_analytic = your_grad[ix]
      rel_error = abs(grad_numerical - grad_analytic) / ...
          (abs(grad_numerical) + abs(grad_analytic))
      print('numerical: %f analytic: %f, relative error: %e' % ...
          (grad_numerical, grad_analytic, rel_error))

  def fast_loss_and_grad(self, X, y):
    """
    A vectorized implementation of loss_and_grad. It shares the same
    inputs and ouptuts as loss_and_grad.
    """
    loss = 0.0
    grad = np.zeros(self.W.shape) # initialize the gradient as zero

    # ================================================================ #
    # YOUR CODE HERE:
      #   Calculate the softmax loss and gradient WITHOUT any for loops.
```

```
    # ================================================================= #

    a = X.dot(self.W.T) #size (N,C)
    num_sample = a.shape[0]

    #  normalize by max in each class
    logk= -np.amax(a, axis =1, keepdims = True)
    # creating logk vector into matrix of repeated column value
    a = a + np.tile(logk,(1,a.shape[1]))

    # defining softmax function
    smax = np.exp(a)/np.sum(np.exp(a), axis =1, keepdims = True)
    # y is a list of classes that x belongs to [1 c 3 ... c], want to ...
        select all the samples of xi that correspond to yi
    a_ind = [np.arange(num_sample),y]
    loss = np.sum(-np.log(smax[a_ind]))
    loss = 1/num_sample*loss

    # creating indicator function
    ind = np.zeros_like(smax)
    ind[a_ind] = 1

    # recall for smax yi equal to j dg/df*df/dz = (smax-1) otherwise ...
        just smax
    dgdz = smax - ind
    grad = dgdz.T.dot(X)
    grad = 1/num_sample*grad
    # ================================================================= #
    # END YOUR CODE HERE
    # ================================================================= #

    return loss, grad

```

```
  def train(self, X, y, learning_rate=1e-3, num_iters=100,
            batch_size=200, verbose=False):
    """
    Train this linear classifier using stochastic gradient descent.

    Inputs:
    - X: A numpy array of shape (N, D) containing training data; there ...
        are N
      training samples each of dimension D.
    - y: A numpy array of shape (N,) containing training labels; y[i] = c
      means that X[i] has label 0 ≤ c < C for C classes.
    - learning_rate: (float) learning rate for optimization.
    - num_iters: (integer) number of steps to take when optimizing
    - batch_size: (integer) number of training examples to use at each ...
        step.
    - verbose: (boolean) If true, print progress during optimization.

    Outputs:
    A list containing the value of the loss function at each training ...
        iteration.
    """
    num_train, dim = X.shape
    num_classes = np.max(y) + 1 # assume y takes values 0...K-1 where K ...
        is number of classes

    self.init_weights(dims=[np.max(y) + 1, X.shape[1]]) # initializes ...
        the weights of self.W

    # Run stochastic gradient descent to optimize W
    loss_history = []

    for it in np.arange(num_iters):
      X_batch = None
```

```
        y_batch = None

        # ...
            =============================================================== ...
            #
        # YOUR CODE HERE:
        #   Sample batch_size elements from the training data for use in
        #   gradient descent.  After sampling,
        #     - X_batch should have shape: (dim, batch_size)
        #     - y_batch should have shape: (batch_size,)
        #   The indices should be randomly generated to reduce correlations
        #   in the dataset.  Use np.random.choice.  It's okay to sample with
        #   replacement.
        # ...
            =============================================================== ...
            #
        N = X.shape[0]
        index = np.random.choice(N,batch_size)
        X_batch = X[index]
        y_batch = y[index]
        # ...
            =============================================================== ...
            #
        # END YOUR CODE HERE
        # ...
            =============================================================== ...
            #

        # evaluate loss and gradient
        loss, grad = self.fast_loss_and_grad(X_batch, y_batch)
        loss_history.append(loss)

```

```
      # ...
        ================================================================= ...
        #
      # YOUR CODE HERE:
      #   Update the parameters, self.W, with a gradient step
      # ...
        ================================================================= ...
        #
      self.W = self.W - learning_rate*grad

        # ...
          ================================================================= ...
          #
      # END YOUR CODE HERE
      # ...
        ================================================================= ...
        #

      if verbose and it % 100 == 0:
        print('iteration {} / {}: loss {}'.format(it, num_iters, loss))

    return loss_history

  def predict(self, X):
    """
    Inputs:
    - X: N x D array of training data. Each row is a D-dimensional point.

    Returns:
    - y_pred: Predicted labels for the data in X. y_pred is a 1-dimensional
      array of length N, and each element is an integer giving the ...
        predicted
      class.
```

```
    """
    y_pred = np.zeros(X.shape[1])
    # ================================================================ #
    # YOUR CODE HERE:
    #   Predict the labels given the training data.
    # ================================================================ #
    # find maximum score out of all the classes and return index
    y_pred = np.argmax(X.dot(self.W.T),axis=1)
    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return y_pred
```