

General Description

The MAX3483, MAX3485, MAX3486, MAX3488, MAX3490, and MAX3491 are 3.3V, low-power transceivers for RS-485 and RS-422 communication. Each part contains one driver and one receiver. The MAX3483 and MAX3488 feature slew-rate-limited drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free data transmission at data rates up to 250kbps. The partially slew-rate-limited MAX3486 transmits up to 2.5Mbps. The MAX3485, MAX3490, and MAX3491 transmit at up to 10Mbps.

Drivers are short-circuit current limited and are protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a logic-high output if both inputs are open circuit.

The MAX3488, MAX3490, and MAX3491 feature fullduplex communication, while the MAX3483, MAX3485, and MAX3486 are designed for half-duplex communication.

Applications

Low-Power RS-485/RS-422 Transceivers **Telecommunications** Transceivers for EMI-Sensitive Applications

Industrial-Control Local Area Networks

Features

- ♦ Operate from a Single 3.3V Supply— No Charge Pump!
- ♦ Interoperable with +5V Logic
- ♦ 8ns Max Skew (MAX3485/MAX3490/MAX3491)
- **♦ Slew-Rate Limited for Errorless Data Transmission** (MAX3483/MAX3488)
- ♦ 2nA Low-Current Shutdown Mode (MAX3483/MAX3485/MAX3486/MAX3491)
- → -7V to +12V Common-Mode Input Voltage Range
- ♦ Allows up to 32 Transceivers on the Bus
- **♦ Full-Duplex and Half-Duplex Versions Available**
- **♦ Industry Standard 75176 Pinout** (MAX3483/MAX3485/MAX3486)
- Current-Limiting and Thermal Shutdown for **Driver Overload Protection**

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX3483CPA	0°C to +70°C	8 Plastic DIP
MAX3483CSA	0°C to +70°C	8 SO
MAX3483C/D	0°C to +70°C	Dice*
MAX3483EPA	-40°C to +85°C	8 Plastic DIP
MAX3483ESA	-40°C to +85°C	8 SO
MAX3485CPA	0°C to +70°C	8 Plastic DIP
MAX3485CSA	0°C to +70°C	8 SO
MAX3485C/D	0°C to +70°C	Dice*
MAX3485EPA	-40°C to +85°C	8 Plastic DIP
MAX3485ESA	-40°C to +85°C	8 SO

Ordering Information continued at end of data sheet.

Selection Table

PART NUMBER	GUARANTEED DATA RATE (Mbps)	SUPPLY VOLTAGE (V)	HALF/FULL DUPLEX	SLEW-RATE LIMITED	DRIVER/ RECEIVER ENABLE	SHUTDOWN CURRENT (nA)	PIN COUNT
MAX3483	0.25		Half	Yes	Yes	2	8
MAX3485	10		Half	No	Yes	2	8
MAX3486	2.5	3.0 to 3.6	Half	Yes	Yes	2	8
MAX3488	0.25	3.0 10 3.0	Full	Yes	No	_	8
MAX3490	10		Full	No	No	_	8
MAX3491	10		Full	No	Yes	2	14

^{*} Contact factory for for dice specifications.

ABSOLUTE MAXIMUM RATINGS

Supply Voltage (V _{CC})7V
Control Input Voltage (RE, DE)0.3V to 7V
Driver Input Voltage (DI)0.3V to 7V
Driver Output Voltage (A, B, Y, Z)7.5V to 12.5V
Receiver Input Voltage (A, B)7.5V to 12.5V
Receiver Output Voltage (RO)0.3V to (V _{CC} + 0.3V)
Continuous Power Dissipation ($T_A = +70^{\circ}C$)
8-Pin Plastic DIP (derate 9.09mW/°C above +70°C)727mW
8-Pin SO (derate 5.88mW/°C above +70°C)471mW

14-Pin Plastic DIP (derate 10mW/°C al 14-Pin SO (derate 8.33mW/°C above -	
Operating Temperature Ranges	
MAX34C	0°C to +70°C
MAX34E	40°C to +85°C
Storage Temperature Range	
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

($V_{CC} = 3.3V \pm 0.3V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25$ °C)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
		R_L = 100 Ω (RS-422), Figure	: 4	2.0			
Differential Driver Output	V _{OD}	$R_L = 54\Omega$ (RS-485), Figure 4		1.5			V
		$R_L = 60\Omega$ (RS-485), $V_{CC} = 3$	3.3V, Figure 5	1.5			1
Change in Magnitude of Driver Differential Output Voltage for Complementary Output States (Note 1)	ΔV _{OD}	R_L = 54 Ω or 100 Ω , Figure 4				0.2	V
Driver Common-Mode Output Voltage	V _{OC}	$R_L = 54\Omega$ or 100Ω , Figure 4				3	V
Change in Magnitude of Common-Mode Output Voltage (Note 1)	ΔV _{OC}	R_L = 54 Ω or 100 Ω , Figure 4				0.2	V
Input High Voltage	VIH	DE, DI, RE		2.0			V
Input Low Voltage	VIL	DE, DI, RE	DE, DI, RE			0.8	V
Logic Input Current	I _{IN1}	DE, DI, RE				±2	μΑ
Input Current (A. D.)	luca	DE = 0V,	V _{IN} = 12V			1.0	mA
Input Current (A, B)	I _{IN2}	$V_{CC} = 0V \text{ or } 3.6V$	V _{IN} = -7V			-0.8	1 IIIA
Output Leakage (Y, Z)	Io	$DE = OV, \overline{RE} = OV,$	V _{OUT} = 12V			20	μΑ
Output Leakage (1, 2)	10	$V_{CC} = 0V \text{ or } 3.6V, MAX3491$	V _{OUT} = -7V			-20] μΑ
Output Leakage (Y, Z)	Io	DE = 0V, RE = V _{CC} ,	V _{OUT} = 12V			1	μΑ
in Shutdown Mode	10	$V_{CC} = 0V \text{ or } 3.6V, MAX3491$	V _{OUT} = -7V			-1] μΑ
Receiver Differential Threshold Voltage	V _{TH}	-7V ≤ V _{CM} ≤ 12V		-0.2		0.2	V
Receiver Input Hysteresis	ΔV_{TH}	$V_{CM} = 0V$			50		mV
Receiver Output High Voltage	Voh	I _{OUT} = -1.5mA, V _{ID} = 200mV, Figure 6		V _{CC} - 0.4	1		V
Receiver Output Low Voltage	Vol	I _{OUT} = 2.5mA, V _{ID} = 200mV, Figure 6				0.4	V
Three-State (High Impedance) Output Current at Receiver	lozr	V _{CC} = 3.6V, 0V ≤ V _{OUT} ≤ V _{CC}				±1	μΑ
Receiver Input Resistance	RIN	-7V ≤ V _{CM} ≤ 12V		12			kΩ

______M/XI/V

DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = 3.3V \pm 0.3V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$ Typical values are at $T_A = +25^{\circ}C$)

PARAMETER	SYMBOL	CONDITION	IS	MIN	TYP	MAX	UNITS
Supply Current	Icc	No load,	$\frac{DE}{RE} = V_{CC},$ $RE = 0V \text{ or } V_{CC}$		1.1	2.2	mA
зирріу Сипепі	ICC	DI = 0V or V _{CC}	$\frac{DE}{RE} = 0V,$		0.95	1.9	IIIA
Supply Current in Shutdown Mode	ISHDN	DE = 0V, RE = V _{CC} , DI = V _C	C or OV		0.002	1	μΑ
Driver Short-Circuit Output	loop	V _{OUT} = -7V				-250	mA
Current	losp	$V_{OUT} = 12V$				250	
Receiver Short-Circuit Output Current	I _{OSR}	0V ≤ V _{RO} ≤ V _{CC}		±8		±60	mA

DRIVER SWITCHING CHARACTERISTICS—MAX3485, MAX3490, and MAX3491

 $(V_{CC} = 3.3V, T_A = +25^{\circ}C)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Differential Output Delay	t _{DD}	$R_L = 60\Omega$, Figure 7	1	22	35	ns
Driver Differential Output Transition Time	t _{TD}	$R_L = 60\Omega$, Figure 7	3	8	25	ns
Driver Propagation Delay, Low-to-High Level	t _{PLH}	$R_L = 27\Omega$, Figure 8	7	22	35	ns
Driver Propagation Delay, High-to-Low Level	tPHL	$R_L = 27\Omega$, Figure 8	7	22	35	ns
t _{PLH} - t _{PHL} Driver Propagation Delay Skew (Note 2)	tpDS	$R_L = 27\Omega$, Figure 8			8	ns
DRIVER OUTPUT ENABLE/DISABLE TIMES (MAX3485	/MAX3491	only)				
Driver Output Enable Time to Low Level	tpzL	$R_L = 110\Omega$, Figure 10		45	90	ns
Driver Output Enable Time to High Level	t _{PZH}	$R_L = 110\Omega$, Figure 9		45	90	ns
Driver Output Disable Time from High Level	t _{PHZ}	$R_L = 110\Omega$, Figure 9		40	80	ns
Driver Output Disable Time from Low Level	t _{PLZ}	$R_L = 110\Omega$, Figure 10		40	80	ns
Driver Output Enable Time from Shutdown to Low Level	tpsl	$R_L = 110\Omega$, Figure 10		650	900	ns
Driver Output Enable Time from Shutdown to High Level	t _{PSH}	$R_L = 110\Omega$, Figure 9		650	900	ns

DRIVER SWITCHING CHARACTERISTICS—MAX3486

 $(V_{CC} = 3.3V, T_A = +25^{\circ}C)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Differential Output Delay	t _{DD}	$R_L = 60\Omega$, Figure 7	24	48	70	ns
Driver Differential Output Transition Time	t _{TD}	$R_L = 60\Omega$, Figure 7	15	35	60	ns
Driver Propagation Delay, Low-to-High Level	t _{PLH}	$R_L = 27\Omega$, Figure 8	20	48	70	ns
Driver Propagation Delay, High-to-Low Level	tphl	$R_L = 27\Omega$, Figure 8	20	48	70	ns
tplh - tphl Driver Propagation Delay Skew (Note 2)	tpDS	$R_L = 27\Omega$, Figure 8			11	ns
Driver Output Enable Time to Low Level	tpzL	$R_L = 110\Omega$, Figure 10		55	100	ns
Driver Output Enable Time to High Level	t _{PZH}	$R_L = 110\Omega$, Figure 9		55	100	ns
Driver Output Disable Time from High Level	t _{PHZ}	$R_L = 110\Omega$, Figure 9		45	80	ns
Driver Output Disable Time from Low Level	tpLZ	$R_L = 110\Omega$, Figure 10		45	80	ns
Driver Output Enable Time from Shutdown to Low Level	t _{PSL}	$R_L = 110\Omega$, Figure 10		700	1000	ns
Driver Output Enable Time from Shutdown to High Level	tpsh	$R_L = 110\Omega$, Figure 9		700	1000	ns

DRIVER SWITCHING CHARACTERISTICS—MAX3483 and MAX3488

 $(V_{CC} = 3.3V, T_A = +25^{\circ}C)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Differential Output Delay	t _{DD}	$R_L = 60\Omega$, Figure 7	600	900	1400	ns
Driver Differential Output Transition Time	t _{TD}	$R_L = 60\Omega$, Figure 7	400	700	1200	ns
Driver Propagation Delay, Low-to-High Level	tplh	$R_L = 27\Omega$, Figure 8	700	1000	1500	ns
Driver Propagation Delay, High-to-Low Level	tphL	$R_L = 27\Omega$, Figure 8	700	1000	1500	ns
t _{PLH} - t _{PHL} Driver Propagation Delay Skew (Note 2)	tpDS	$R_L = 27\Omega$, Figure 8		100		ns
DRIVER OUTPUT ENABLE/DISABLE TIMES (MAX3483	3 only)					•
Driver Output Enable Time to Low Level	tpzL	$R_L = 110\Omega$, Figure 10		900	1300	ns
Driver Output Enable Time to High Level	t _{PZH}	R_L = 110 Ω , Figure 9		600	800	ns
Driver Output Disable Time from High Level	tphz	R_L = 110 Ω , Figure 9		50	80	ns
Driver Output Disable Time from Low Level	t _{PLZ}	$R_L = 110\Omega$, Figure 10		50	80	ns
Driver Output Enable Time from Shutdown to Low Level	tpsL	$R_L = 110\Omega$, Figure 10		1.9	2.7	μs
Driver Output Enable Time from Shutdown to High Level	tpsh	R_L = 110 Ω , Figure 9		2.2	3.0	μs

RECEIVER SWITCHING CHARACTERISTICS

 $(V_{CC} = 3.3V, T_A = +25^{\circ}C)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Time to Shutdown	tshdn	MAX3483/MAX3485/MAX3486/MAX3491 only (Note 3)	80	190	300	ns
Receiver Propagation Delay,	trplh	V _{ID} = 0V to 3.0V, C _L = 15pF, Figure 11	25	65	90	ns
Low-to-High Level	IRPLH	MAX3483/MAX3488	25	75	120	113
Receiver Propagation Delay,	topuii	V _{ID} = 0V to 3.0V, C _L = 15pF, Figure 11	25	65	90	ns
High-to-Low Level	[†] RPHL	MAX3483/MAX3488	25	75	120	113
tplh - tphl Receiver	toppe	V _{ID} = 0V to 3.0V, C _L = 15pF, Figure 11			10	ns
Propagation Delay Skew	tRPDS	MAX3483/MAX3488			20	113
Receiver Output Enable Time to Low Level	†PRZL	C _L = 15pF, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only		25	50	ns
Receiver Output Enable Time to High Level	tprzh	C _L = 15pF, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only		25	50	ns
Receiver Output Disable Time from High Level	t _{PRHZ}	C _L = 15pF, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only		25	45	ns
Receiver Output Disable Time from Low Level	†PRLZ	C _L = 15pF, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only		25	45	ns
Receiver Output Enable Time from Shutdown to Low Level	tprsl	C _L = 15pF, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only		720	1400	ns
Receiver Output Enable Time from Shutdown to High Level	tprsh	C _L = 15pF, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only		720	1400	ns

Note 1: ΔV_{OD} and ΔV_{OC} are the changes in V_{OD} and V_{OC} , respectively, when the DI input changes state.

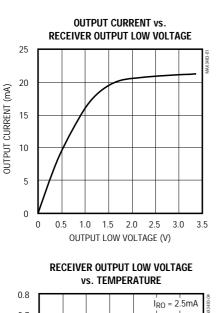
Note 2: Measured on |tplh (Y) - tphL (Y)| and |tplh (Z) - tphL (Z)|.

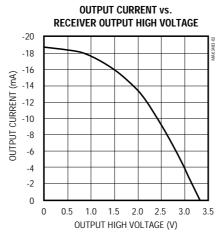
Note 3: The transceivers are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 80ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 300ns, the parts are guaranteed to have entered shutdown. See *Low-Power Shutdown Mode* section.

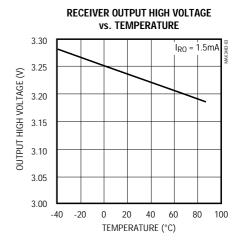
_ /VI/IXI/V

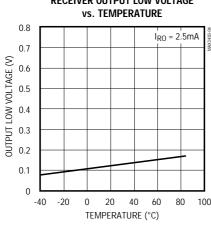
_Typical Operating Characteristics

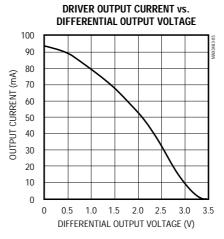
 $(V_{CC} = 3.3V, T_A = +25^{\circ}C, unless otherwise noted.)$

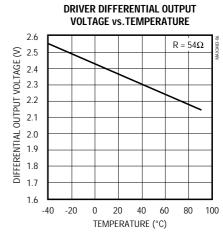


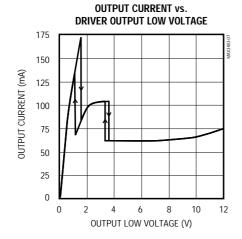


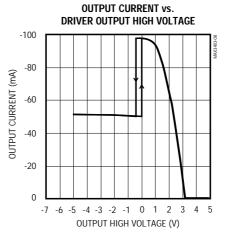




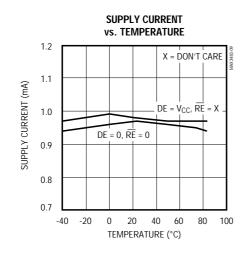


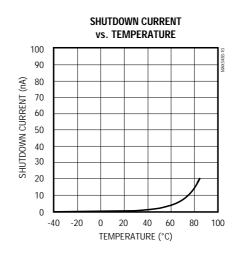






Typical Operating Characteristics (continued)





Pin Description

	PIN			
MAX3483/ MAX3485/ MAX3486	MAX3488/ MAX3490	MAX3491	NAME	FUNCTION
1	2	2	RO	Receiver Output. If $A > B$ by 200mV, RO will be high; if $A < B$ by 200mV, RO will be low.
2	_	3	RE	Receiver Output Enable. RO is enabled when \overline{RE} is low; RO is high impedance when \overline{RE} is high. If \overline{RE} is high and DE is low, the device will enter a low-power shutdown mode.
3	_	4	DE	Driver Output Enable. The driver outputs are enabled by bringing DE high. They are high impedance when DE is low. If \overline{RE} is high and DE is low, the device will enter a low-power shutdown mode. If the driver outputs are enabled, the parts function as line drivers. While they are high impedance, they function as line receivers if \overline{RE} is low.
4	3	5	DI	Driver Input. A low on DI forces output Y low and output Z high. Similarly, a high on DI forces output Y high and output Z low.
5	4	6, 7	GND	Ground
_	5	9	Υ	Noninverting Driver Output
_	6	10	Z	Inverting Driver Output
6	_	_	А	Noninverting Receiver Input and Noninverting Driver Output
_	8	12	А	Noninverting Receiver Input
7	_	_	В	Inverting Receiver Input and Inverting Driver Output
_	7	11	В	Inverting Receiver Input
8	1	13, 14	Vcc	Positive Supply: 3.0V ≤ V _{CC} ≤ 3.6V
_	_	1, 8	N.C.	No Connect—not internally connected

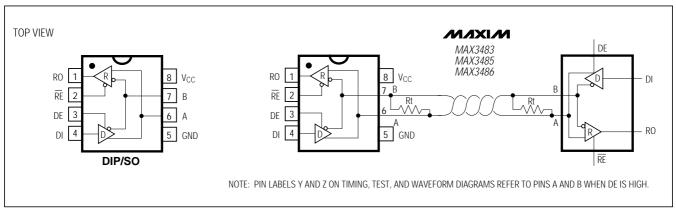


Figure 1. MAX3483/MAX3485/MAX3486 Pin Configuration and Typical Operating Circuit

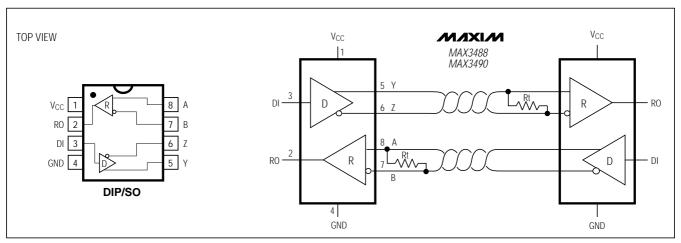


Figure 2. MAX3488/MAX3490 Pin Configuration and Typical Operating Circuit

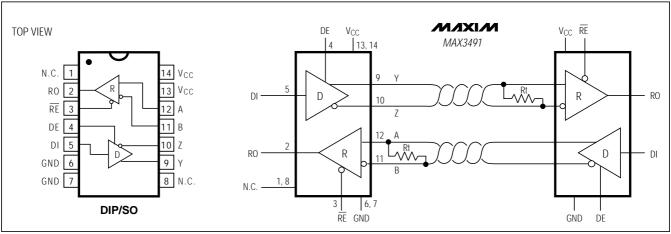


Figure 3. MAX3491 Pin Configuration and Typical Operating Circuit

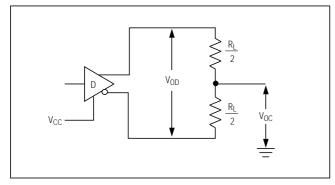


Figure 4. Driver V_{OD} and V_{OC}

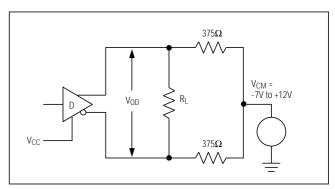


Figure 5. Driver V_{OD} with Varying Common-Mode Voltage

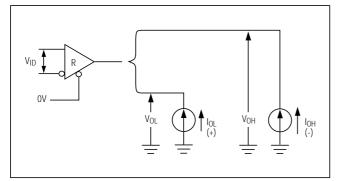


Figure 6. Receiver V_{OH} and V_{OL}

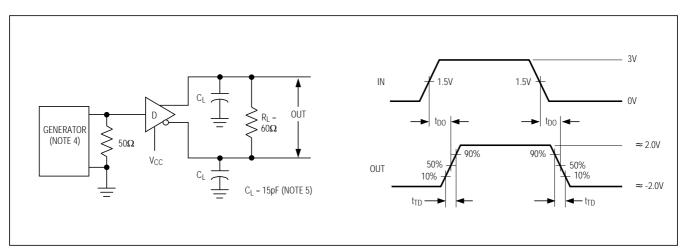


Figure 7. Driver Differential Output Delay and Transition Times

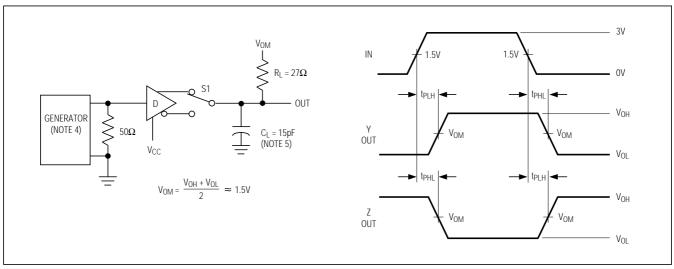


Figure 8. Driver Propagation Times

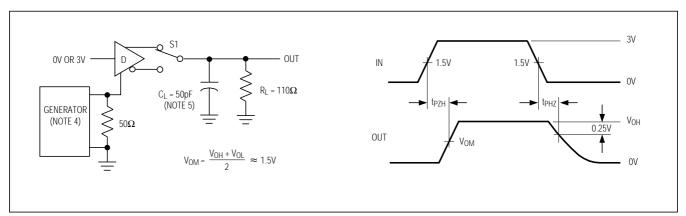


Figure 9. Driver Enable and Disable Times (t_{PZH}, t_{PSH}, t_{PHZ})

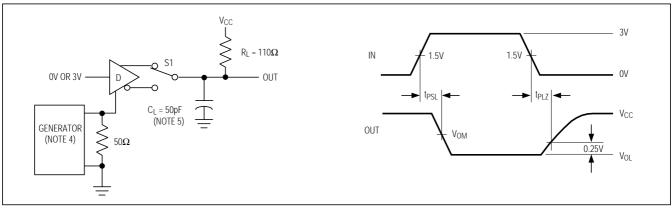


Figure 10. Driver Enable and Disable Times (t_{PZL} , t_{PSL} , t_{PLZ})

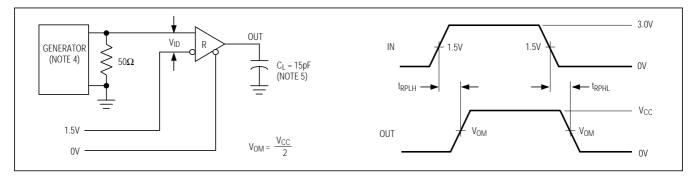


Figure 11. Receiver Propagation Delay

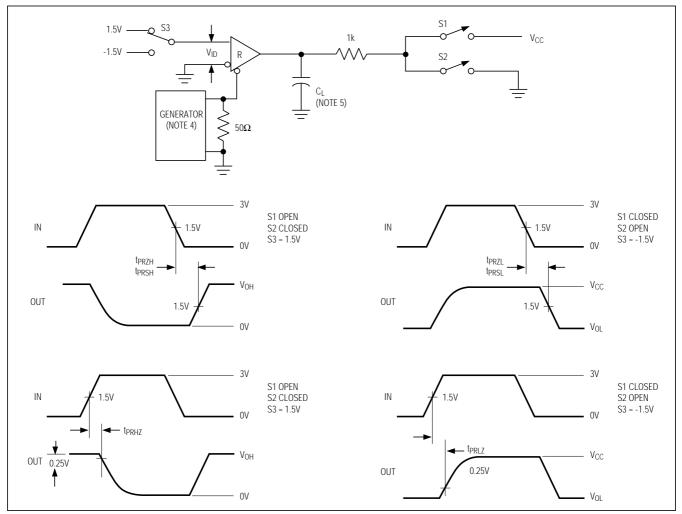


Figure 12. Receiver Enable and Disable Times

Note 4: The input pulse is supplied by a generator with the following characteristics: PRR = 250kHz, 50% duty cycle, $\frac{1}{5} \le 6.0ns$, $Z_O = 50\Omega$. Note 5: C_L includes probe and stray capacitance.

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_____Function Tables

Devices with Receiver/Driver Enable (MAX3483/MAX3485/MAX3486/MAX3491)

Table 1. Transmitting

	INPUTS	i	OUTI	PUTS	MODE
RE	DE	DI	B*	A *	WIODE
Х	1	1	0	1	Normal
Х	1	0	1	0	Normal
0	0	Χ	High-Z	High-Z	Normal
1	0	Х	High-Z	High-Z	Shutdown

^{*} B and A outputs are Z and Y, respectively, for full-duplex part (MAX3491).

X = Don't care; High-Z = High impedance

Table 2. Receiving

INPUTS			OUTPUTS	MODE	
RE	DE	A, B	RO	WIODE	
0	0*	≥+0.2V	1	Normal	
0	0*	≤-0.2V	0	Normal	
0	0*	Inputs Open	1	Normal	
1	0	Х	High-Z	Shutdown	

^{*} DE is a "don't care" (x) for the full-duplex part (MAX3491). X = Don't care; High-Z = High impedance

Devices without Receiver/Driver Enable (MAX3488/MAX3490)

Table 3. Transmitting Table 4. Receiving

INPUT	OUTI	PUTS
DI	Z	Υ
1	0	1
0	1	0

	_
INPUTS	OUTPUT
A, B	RO
≥+0.2V	1
≤-0.2V	0
Inputs Open	1

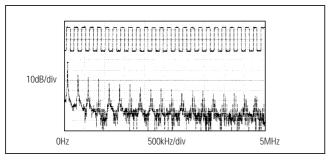


Figure 13. Driver Output Waveform and FFT Plot of MAX3485/ MAX3490/MAX3491 Transmitting a 125kHz Signal

_Applications Information

The MAX3483/MAX3485/MAX3486/MAX3488/MAX3490/MAX3491 are low-power transceivers for RS-485 and RS-422 communications. The MAX3483 and MAX3488 can transmit and receive at data rates up to 250kbps, the MAX3486 at up to 2.5Mbps, and the MAX3485/MAX3490/MAX3491 at up to 10Mbps. The MAX3488/MAX3490/MAX3491 are full-duplex transceivers, while the MAX3483/MAX3485/MAX3486 are half-duplex. Driver Enable (DE) and Receiver Enable (RE) pins are included on the MAX3483/MAX3485/MAX3486/MAX3491. When disabled, the driver and receiver outputs are high impedance.

Reduced EMI and Reflections (MAX3483/MAX3486/MAX3488)

The MAX3483/MAX3488 are slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Figure 13 shows both the driver output waveform of a MAX3485/MAX3490/MAX3491 transmitting a 125kHz signal and the Fourier analysis of that waveform. High-frequency harmonics with large amplitudes are evident. Figure 14 shows the same information, but for the slew-rate-limited MAX3483/MAX3488 transmitting the same signal. The high-frequency harmonics have much lower amplitudes, and the potential for EMI is significantly reduced.

Low-Power Shutdown Mode (MAX3483/MAX3485/MAX3486/MAX3491)

 \underline{A} low-power shutdown mode is initiated by bringing both \overline{RE} high and DE low. The devices will not shut down unless both the driver and receiver are disabled (high impedance). In shutdown, the devices typically draw only 2nA of supply current.

For these devices, the t_{PSH} and t_{PSL} enable times assume the part was in the low-power shutdown mode; the t_{PZH} and t_{PZL} enable times assume the receiver or driver was disabled, but the part was not shut down.

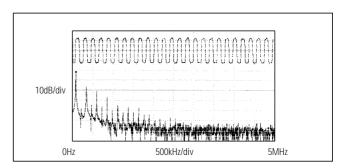


Figure 14. Driver Output Waveform and FFT Plot of MAX3483/ MAX3488 Transmitting a 125kHz Signal

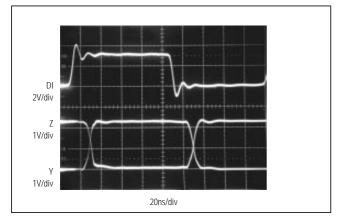


Figure 15. MAX3485/MAX3490/MAX3491 Driver Propagation Delay

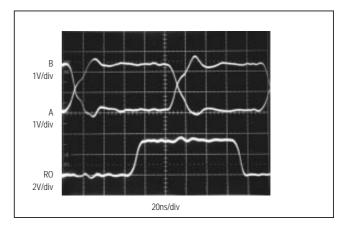


Figure 16. MAX3485/MAX3490/MAX3491 Receiver Propagation Delay Driven by External RS-485 Device

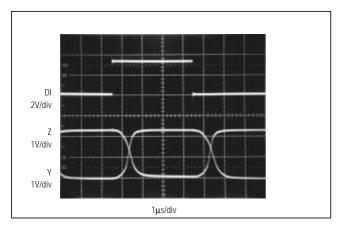


Figure 17. MAX3483/MAX3488 Driver Propagation Delay

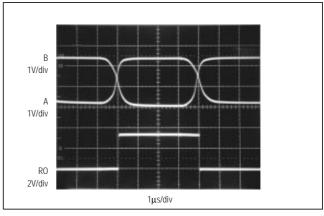


Figure 18. MAX3483/MAX3488 Receiver Propagation Delay

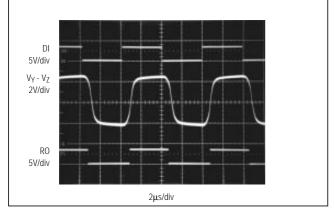


Figure 19. MAX3483/MAX3488 System Differential Voltage at 125kHz Driving 4000 ft of Cable

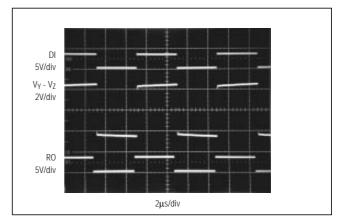


Figure 20. MAX3485/MAX3490/MAX3491 System Differential Voltage at 125kHz Driving 4000 ft of Cable

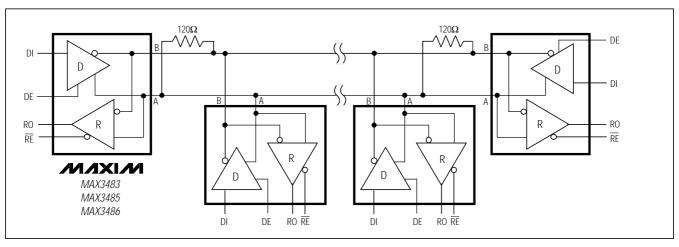


Figure 21. MAX3483/MAX3485/MAX3486 Typical RS-485 Network

Driver Output Protection

Excessive output current and power dissipation caused by faults or by bus contention are prevented by two mechanisms. A foldback current limit on the output stage provides immediate protection against short circuits over the whole common-mode voltage range (see *Typical Operating Characteristics*). In addition, a thermal shutdown circuit forces the driver outputs into a high-impedance state if the die temperature rises excessively.

Propagation Delay

Figures 15–18 show the typical propagation delays. Skew time is simply the difference between the low-to-high and high-to-low propagation delay. Small driver/receiver skew times help maintain a symmetrical mark-space ratio (50% duty cycle).

The receiver skew time, $|t_{PRLH} - t_{PRHL}|$, is under 10ns (20ns for the MAX3483/MAX3488). The driver skew times are 8ns for the MAX3485/MAX3490/MAX3491, 11ns for the MAX3486, and typically under 100ns for the MAX3483/MAX3488.

Line Length vs. Data Rate

The RS-485/RS-422 standard covers line lengths up to 4000 feet. For line lengths greater than 4000 feet, see Figure 23.

Figures 19 and 20 show the system differential voltage for parts driving 4000 feet of 26AWG twisted-pair wire at 125kHz into 120Ω loads.

Typical Applications

The MAX3483, MAX3485, MAX3486, MAX3488, MAX3490, and MAX3491 transceivers are designed for bidirectional data communications on multipoint bus transmission lines. Figures 21 and 22 show typical network applications circuits. These parts can also be used as line repeaters, with cable lengths longer than 4000 feet, as shown in Figure 23.

To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible. The slew-rate-limited MAX3483/MAX3488 and the partially slew-rate-limited MAX3486 are more tolerant of imperfect termination.

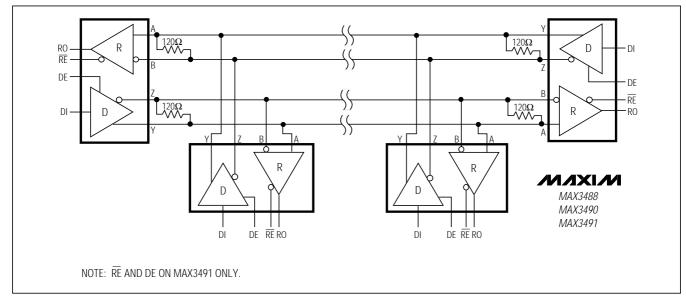


Figure 22. MAX3488/MAX3490/MAX3491 Full-Duplex RS-485 Network

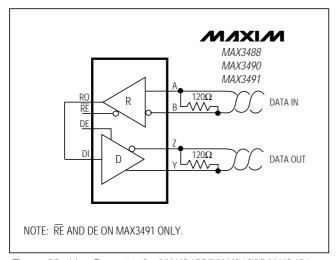


Figure 23. Line Repeater for MAX3488/MAX3490/MAX3491

_Ordering Information (continued)

PART	TEMP. RANGE	PIN-PACKAGE
MAX3486CPA	0°C to +70°C	8 Plastic DIP
MAX3486CSA	0°C to +70°C	8 SO
MAX3486C/D	0°C to +70°C	Dice*
MAX3486EPA	-40°C to +85°C	8 Plastic DIP
MAX3486ESA	-40°C to +85°C	8 SO
MAX3488CPA	0°C to +70°C	8 Plastic DIP
MAX3488CSA	0°C to +70°C	8 SO
MAX3488C/D	0°C to +70°C	Dice*
MAX3488EPA	-40°C to +85°C	8 Plastic DIP
MAX3488ESA	-40°C to +85°C	8 SO
MAX3490CPA	0°C to +70°C	8 Plastic DIP
MAX3490CSA	0°C to +70°C	8 SO
MAX3490C/D	0°C to +70°C	Dice*
MAX3490EPA	-40°C to +85°C	8 Plastic DIP
MAX3490ESA	-40°C to +85°C	8 SO
MAX3491CPD	0°C to +70°C	14 Plastic DIP
MAX3491CSD	0°C to +70°C	14 SO
MAX3491C/D	0°C to +70°C	Dice*
MAX3491EPD	-40°C to +85°C	14 Plastic DIP
MAX3491ESD	-40°C to +85°C	14 SO

^{*} Contact factory for for dice specifications.

RO

RE

DE

DI

GND

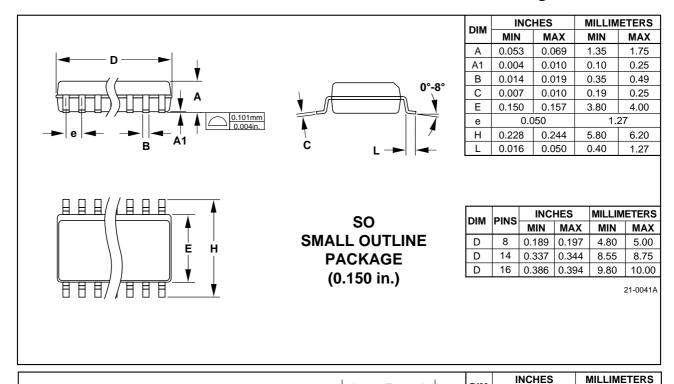
GND

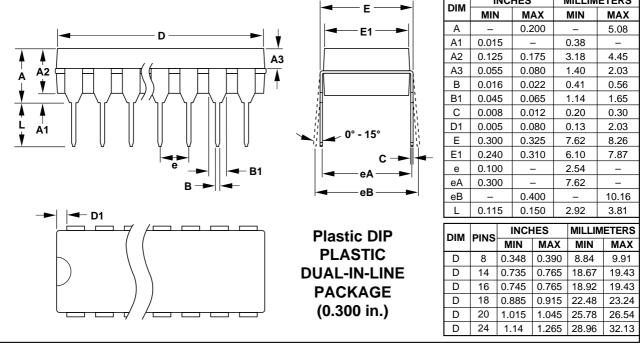
Chip Topography

TRANSISTOR COUNT: 810
SUBSTRATE CONNECTED TO GROUND

0.086" (2.18mm)

Package Information





Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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