# Lichao Shen

# red-pencil.github.io/homepage lichao.shen@hotmail.com

# INTEREST

#### **Human-Computer Interaction**

Virtual Reality • Mixed Reality Computer Graphics Ubiquitous Computing Machine Learning

#### **Human Augmentation**

Cognitive Science Neuroscience Robotics

#### Interaction Design

User Experience • User Interface Media Design Industrial Design

# SKILLS

#### Programming

C • C#(Unity) • JavaScript • Python Ruby • Arduino • HTML T<sub>E</sub>X • Git • UNIX

#### Engineering

Technical Drawing
Mechanical Machining
(SolidWorks • Pro/Engineer • AutoCAD)

#### Design

Pencil & Marker Sketch Gouache Painting • Prototyping (Photoshop • Illustrator • Premiere 3Ds Max • Rhinoceros • Grasshopper KeyShot • V-Ray • Unity)

# LANGUAGES

Chinese (Native) English (Academic) Japanese (Elementary)

# LINKS

#### Detailed Résumé

red-pencil.github.io/cv

#### Design Portfolio

issuu.com/lichaoshen

#### Project Video

youtube.com

# **EDUCATION**

#### KEIO UNIVERSITY | TOKYO, JAPAN

2015 - 2018

#### MASTER OF MEDIA DESIGN

Human-Computer Interaction, Media Design

#### PRATT INSTITUTE | NEW YORK, US

2017

### ROYAL COLLEGE OF ART & IMPERIAL COLLEGE | LONDON, UK

2016

# BEIHANG UNIVERSITY | BEIJING, CHINA

2010 - 2014

#### **BACHELOR OF ENGINEERING**

Industrial Design, Mechanical Engineering

# **EXPERIENCE**

# CYBER LIVING LAB | TOKYO, JAPAN

2015 - 2018

#### STUDENT RESEARCHER

- Conducted research under the Embodied Media Project, in fields of haptic sensation, virtual reality, human augmentation, telepresence, etc.
- Developed experiments, prototypes and applications for the projects.

# LENOVO RESEARCH | BEIJING, CHINA

2013 - 2014

#### **USER EXPERIENCE DESIGN INTERN**

- Researched into user's behavior towards a variety of consumer electronics.
- Developed the preliminary design of the next generation smart devices.

# RESEARCH

#### LIMITLESS OCULUS I MASTER THESIS

Visual Expansion by Animal-Inspired Visuomotor Modification

#### UNCONSTRAINED NECK | CONFERENCE BEST DEMO AWARD

Omnidirectional Observation from an Extra Robotic Neck

#### AMBIENT | CONFERENCE DEMO

Facial Thermal Feedback in Remotely Operated Applications

#### **EYE-IN-HAND**

"Snail Sight", Autonomous Monocular Vision, Observe Dual Scenes Simultaneously

#### **BUG VIEW**

"Being a Spider", Telexistence from Human to a Spider Robot

# **PUBLICATIONS**

- [1] M. Y. Saraiji, R. Peiris, L. Shen, K. Minamizawa, and S. Tachi. Ambient: Facial thermal feedback in remotely operated applications. CHI '18, 2018.
- [2] L. Shen, M. Y. Saraiji, K. Kunze, and K. Minamizawa. Unconstrained neck: Omnidirectional observation from an extra robotic neck. In *Proceedings of the 9th Augmented Human International Conference*, AH '18, pages 38:1–38:2, New York, NY, USA, 2018. ACM.