Assignment 4 - Jesús Rabanal Álvarez

March 18, 2024

```
[1]: import numpy as np
  import matplotlib.pyplot as plt
  import pandas as pd
  from sklearn.preprocessing import StandardScaler
  import warnings
  warnings.filterwarnings("ignore")
```

EXERCISE 1

1. Implementation of PCA.

```
[2]: class PCA:
         def __init__(self, n_components):
             self.n\_components = n\_components
             self.components = None
             self.variance = None
             self.mean = None
             self.cumulative_variance = None
         def fit(self, X):
             #we prepare the data by standardizing it
             self.mean = np.mean(X, axis=0)
             X = X - self.mean
             #we create the covariance matrix which is need for the eigenvalue decomp
             cov_matrix = np.cov(X.T)
             eigenvalues, eigenvectors = np.linalg.eig(cov_matrix)
             #take the principal components
             eigenvectors = eigenvectors.T
             idxs = np.argsort(eigenvalues)[::-1]
             self.components = eigenvectors[idxs][:self.n_components]
             #calculate the variance from each component
             self.variance = eigenvalues[idxs][:self.n_components] / np.
      →sum(eigenvalues)
```

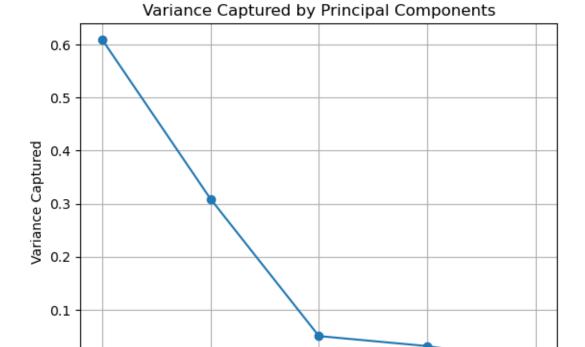
```
#calculate the cumulative variance
self.cumulative_variance = np.cumsum(self.variance)

def transform(self, X):
    #dot product the data and the principal components
    X = X - self.mean
    return np.dot(X, self.components.T), self.variance, self.
cumulative_variance
```

The class PCA includes two functions, firstly the .fit() which intakes the data in matrix form, it standardises the data, then it creates a matrix with the covariance which is later used to crate the eigenvalues and eigenvectors. Finally, we obtain the eigenvectors, sort them and obtain the principal components from them. Additionally, we calculate the variance from each component. The second function .transform() intakes the data and projects the principal components onto our data using the dot product, in addition the variance is returned here.

```
data using the dot product, in addition the variance is returned here.
[3]: occu_train = np.loadtxt('OccupancyTrain.csv', delimiter=',')
     occu_test = np.loadtxt('OccupancyTest.csv', delimiter=',')
[4]: X_occu_train = occu_train[:,:-1]
     y_occu_train = occu_train[:,-1]
     X_occu_test = occu_test[:,:-1]
     y_occu_test = occu_test[:,-1]
[5]: weed train = np.loadtxt('IDSWeedCropTrain.csv', delimiter=',')
     weed_test = np.loadtxt('IDSWeedCropTest.csv', delimiter=',')
[6]: X_weed_train = weed_train[:,:-1]
     y_weed_train = weed_train[:,-1]
     X_weed_test = weed_test[:,:-1]
     y_weed_test = weed_test[:,-1]
[7]: #we normalize the data as asked before applying pca
     scaler = StandardScaler()
     X_occu_train_scaled = scaler.fit_transform(X_occu_train)
     #instantiate pca and fit
     pca = PCA(n_components=X_occu_train_scaled.shape[1])
     pca.fit(X_occu_train_scaled)
     #transform data and obtain variance
     X occu train transformed, variance trained, cumvar trained = pca.
      stransform(X_occu_train_scaled)
     #Plot
     plt.plot(range(1, len(variance_trained) + 1), variance_trained, marker='o', __
      →linestyle='-')
```

```
plt.xlabel('Principal Component Index')
plt.ylabel('Variance Captured')
plt.title('Variance Captured by Principal Components')
plt.xticks(range(1, len(variance_trained) + 1))
plt.grid(True)
plt.show()
```



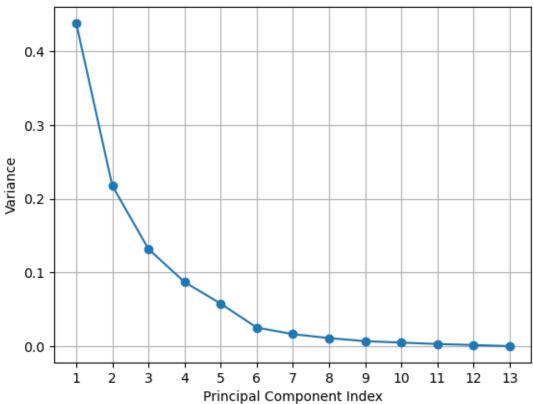
Principal Component Index

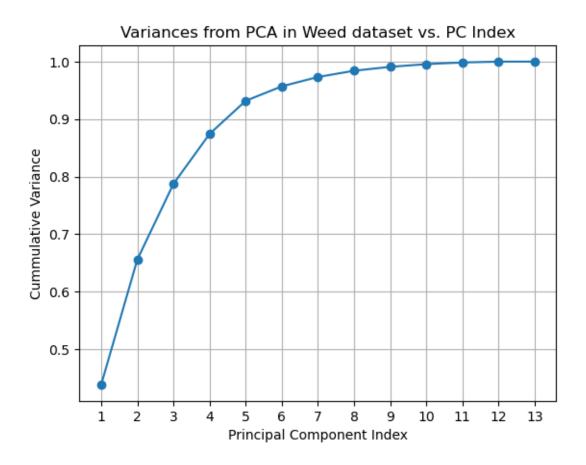
2

0.0

1

Variances from PCA in Weed dataset vs. PC Index



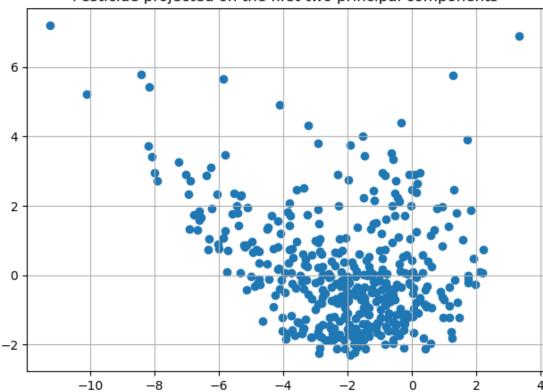


Number of principal components needed to capture 90% of the variance: 5 Number of principal components needed to capture 95% of the variance: 6

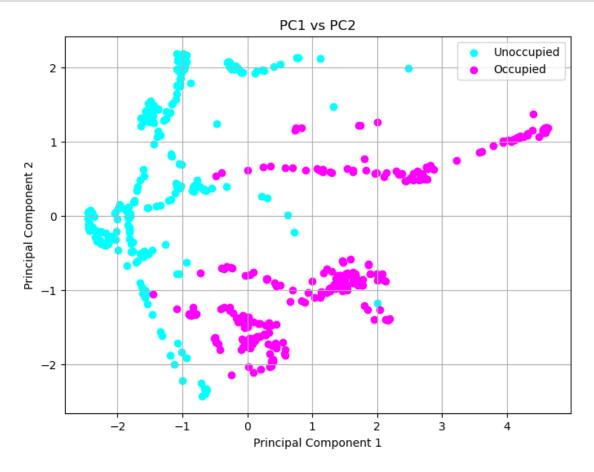
EXERCISE 2

```
plt.title('Pesticide projected on the first two principal components')
plt.tight_layout()
plt.grid(True)
plt.show()
```





As my class PCA allows for the selection of the number of components, I just setted it up for 2 components, then fitted the model with the scaled data from the weed dataset. Then after that I used a scatterplot project the Pesticide/weed training dataset onto the first 2 principal components



EXERCISE 3

Both steps like centering and normalization are common methods used in data science. They are meant to standardize the features and bring them to comparable scales which is obviously if not required at least recommendable for PCA.

To answer the question of whether applying centering and normalization will make a difference. It all depends on the data distribution and scale. In this case we have dataset with data in very different scales.

CENTERING:

- Centering involves substracting the mean of each feature from the data, shifting the data points so the mean is at the origin. Without this measure, the principal components might be biased towards directions that capture the mean instead of the variance.

NORMALIZATION:

- Normalization scales each feature to have unit variance. This is done to ensure that features with larger vairances will not dominate the PCA process, if not done the principal components will obviously be biased due to the unscaled larger variances.

In conclusion I believe that in the current case we are working on, both Centering and Normalization are very much required because as the exercise clarifies the scales of the data are not comparable. If not centered and normalized it will definitely affect the results. Together, centering and normalizing will help in obtaining a more accurate and interpretable principal components that capture the underlying structure of the data. To sum up, we can say that these preprocessing steps are crucial before performing PCA and they ensure that the results are not biased by scalability or distribution of features, allowing for more meaningful and interpretable principal components.

EXERCISE 4

```
\lceil 13 \rceil: def f(x):
          return np.exp(-x/2) + 10*x**2
      def fprime(x):
          return 20*x - (np.exp(-x/2))/2
      def gradient_descent(learning_rate, max_iter=10000, x0=1):
          xk = x0
          iter = 0
          xs = [x0]
          while max_iter > iter and np.absolute(fprime(xk)) > 10e-10:
              gradient = fprime(xk)
              xk = xk - (gradient * learning rate)
              iter += 1
              xs.append(xk)
          return {'x':xk, 'iters':iter, 'xs':xs}
      learning_rates = [0.1, 0.01, 0.001, 0.0001]
      colors = ['red', 'green', 'orange']
      for learning rate in learning rates:
          res = gradient_descent(learning_rate)
          plt.figure(figsize=(8,6))
          plt.plot(np.linspace(-3,3), f(np.linspace(-3,3)), label='f(x)')
```

```
print('Learning rate: ' + str(learning_rate) + ', ITERS: ' +
str(res['iters']) + ', Minimum: ' + str(res['x']))

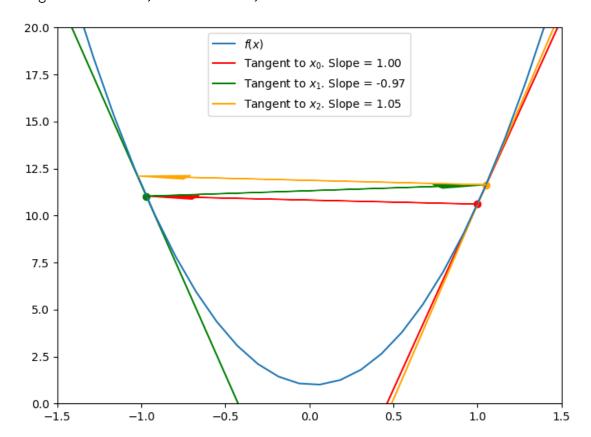
for i, x in enumerate(res['xs'][:3]):
    linspace = np.linspace(-100, 100)
    plt.plot(linspace, fprime(x)*(linspace - x) + f(x), label=f'Tangent tou
sx_'+str(i)+f'$. Slope = {x:.2f}', color=colors[i], zorder=1)
    plt.scatter(x, f(x), color=colors[i], zorder=1)

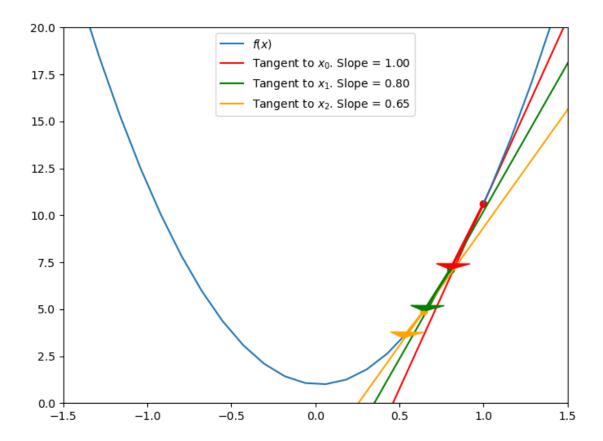
for i, x in enumerate(res['xs'][:3]):
    plt.arrow(x, f(x), res['xs'][i+1] - x, f(res['xs'][i+1]) - f(x),
swidth=0.01, length_includes_head=True, zorder=2, head_width=0.2,
scolor=colors[i])
    plt.legend()

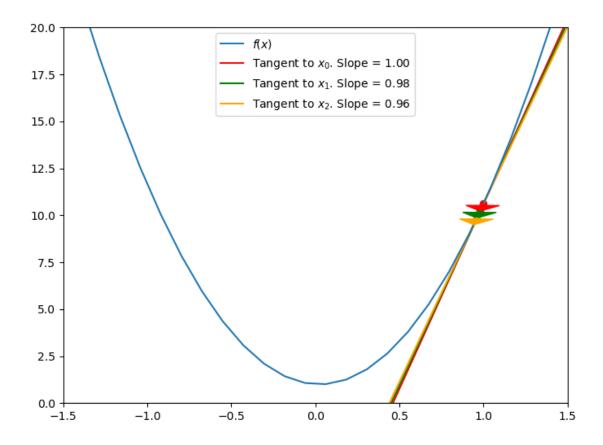
plt.xlim((-1.5, 1.5))
    plt.ylim((0, 20))
```

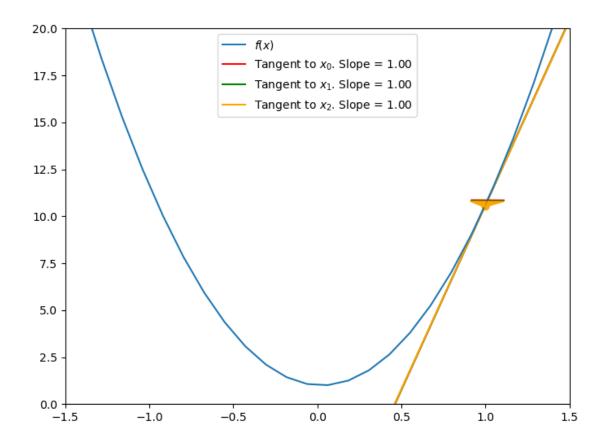
Learning rate: 0.1, ITERS: 69, Minimum: nan

Learning rate: 0.01, ITERS: 105, Minimum: 0.024693232312567183 Learning rate: 0.001, ITERS: 1160, Minimum: 0.024693232313839686 Learning rate: 0.0001, ITERS: 10000, Minimum: 0.024693233808097063





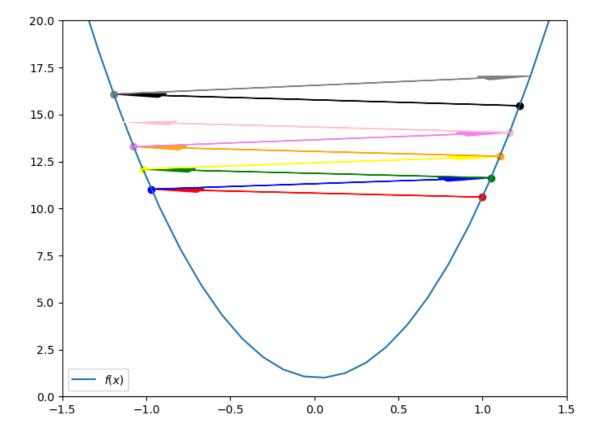


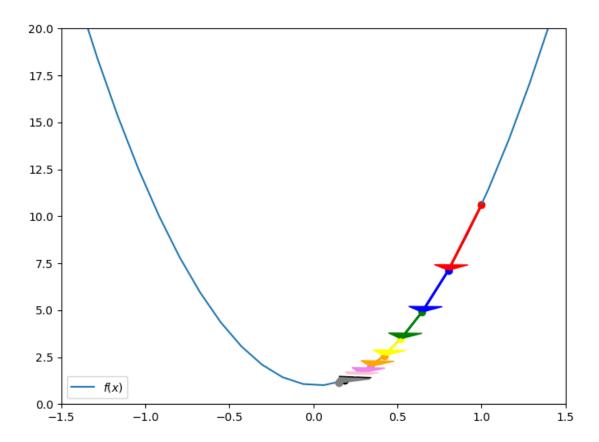


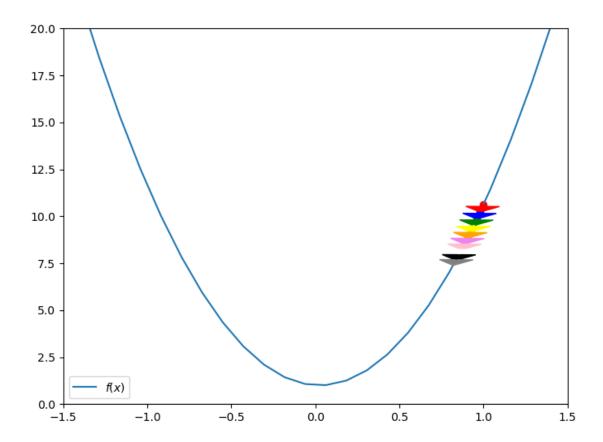
As we can see in the plots above, in between the four learning rates the one that significantly approximates to the convergeance is 0.01, the first one (with a lr = 0.1) has a erratic behaviour and instead of converging it diverges going towards infinity as it can be seen by the value 'nan' in the print statement above the plots, the second one presents a promising descent in the function with a learning rate of 0.01 and a slope in the third iteration of 0.65 nearing the perfect 0 that we are looking for, the third and fourth learning rates present clear diminishing returns as the step gets smaller and smaller, as it can be observed in the last two plots.

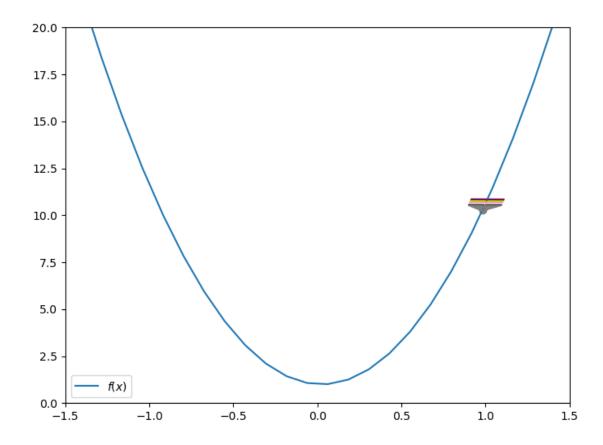
```
plt.arrow(x, f(x), res['xs'][i+1] - x, f(res['xs'][i+1]) - f(x),
width=0.01, length_includes_head=True, zorder=2, head_width=0.2,
color=colors[i])
plt.legend()

plt.xlim((-1.5, 1.5))
plt.ylim((0, 20))
```









As we were thinking, the addition of more steps helps to further consolidate our conclusions in the paragraph before. The learning rate 0.01 approximates to the threshold of 10^{-10} in the least number of iterations (105) compared to the others. Therefore we can say that the preferable learning rate for the gradient descent of this function is 0.01.

EXERCISE 5

```
print('Value for '+name+': '+str(value))
```

```
Value for w0 (intercept): -6.39653177883233e-14, Value for w1 (relative humidity): -0.009387889127335883

Value for w1: -0.3601066690378464

Value for w2: 0.414081699613497

Value for w3: 0.5449262989086808
```

In this exercise we used the implementaion by scikit-learn. The parameters w0 & w1 are printed above, and it can be seen as how the relative humidity plays a relatively lesser role when using it alone as a feature to predict temperature. As for the wi values when using the three features, an increase in the relative humidity is correlated with a decrease in the temperature, an increase in light is correlated with an increase in temperature and finally an increase in CO2 is also correlated with an increase in the temperature. To sum up we can see how the model with three features fitted is much better at prediciting temperature based on the features than the model with only one feature (relative humidity).

EXERCISE 6

```
RMSE for model with 1 feature (Relative Humidity): 0.9999559327979065 RMSE for model with 3 features: 0.5871098459314781
```

RMSE reports back what we concluded in the exercise before. When the model is fitted with three features it is greater at predicting data with a much lesser root mean squared error, although not perfect but comparatively better.

REFERENCES

- GitHub Copilot v1.174.0 was used as assistance while developing the code for this assignment.