

Attention

HE Jiayou

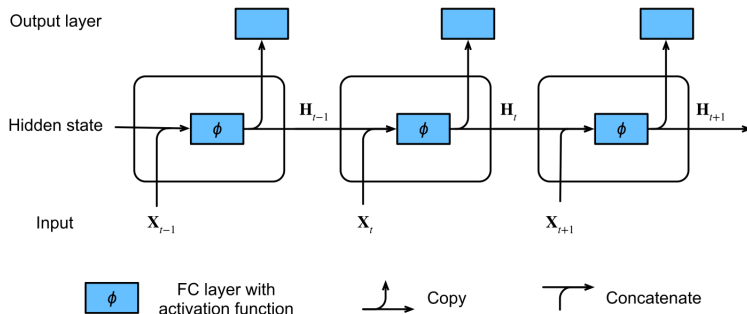
July 7, 2022

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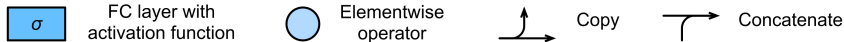
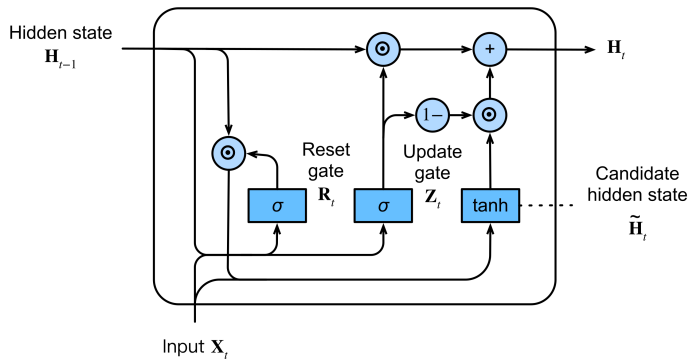
$$H_t = \phi(X_t W_{xh} + H_{t-1} W_{hh} + b_h)$$

$$O_t = H_t W_{hq} + b_q$$

$$X_t \in \mathbb{R}^{n \times d} \quad H_t \in \mathbb{R}^{n \times h}$$

$$O_t \in \mathbb{R}^{n \times q} \quad b_h \in \mathbb{R}^{1 \times h}$$

GRU Gated Recurrent Unit



GRU Gated Recurrent Unit

GRU supports gating of the hidden state.

- Reset gates help capture short-term dependencies in sequences.
- Update gates help capture long-term dependencies in sequences.

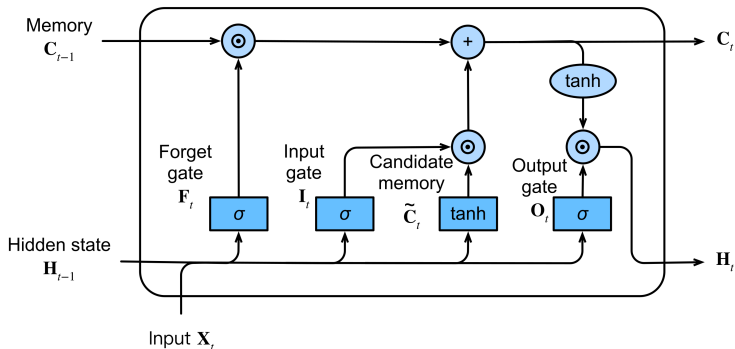
$$R_t = \sigma(X_t W_{xr} + H_{t-1} W_{hr} + b_r)$$

$$Z_t = \sigma(X_t W_{xz} + H_{t-1} W_{hz} + b_z)$$

$$\tilde{H}_t = \tanh(X_t W_{xh} + (R_t \odot H_{t-1}) W_{hh} + b_h)$$

$$H_t = Z_t \odot H_{t-1} + (1 - Z_t) \odot \tilde{H}_t$$

LSTM



FC layer with
activation function



Elementwise
operator



Copy



Concatenate

The idea is similar to GRU.

$$I_t = \sigma(X_t W_{xi} + H_{t-1} W_{hi} + b_i)$$

$$F_t = \sigma(X_t W_{xf} + H_{t-1} W_{hf} + b_f)$$

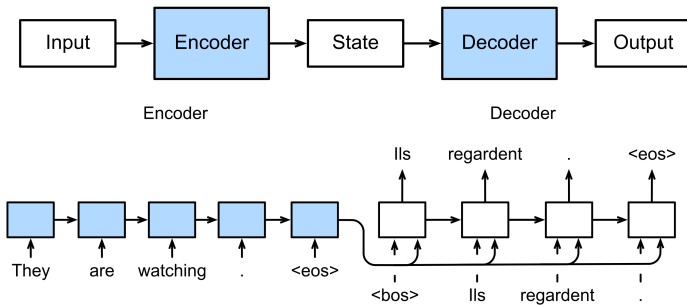
$$O_t = \sigma(X_t W_{xo} + H_{t-1} W_{ho} + b_o)$$

$$\tilde{C}_t = \tanh(X_t W_{xc} + H_{t-1} W_{hc} + b_c)$$

$$C_t = F_t \odot C_{t-1} + I_t \odot \tilde{C}_t$$

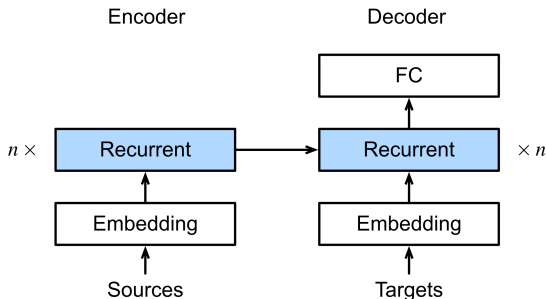
$$H_t = O_t \odot \tanh(C_t)$$

Encoder-Decoder



Encoder-Decoder

- Encoder: $H_t = f(X_t, H_{t-1})$, $C = g(H_1, \dots, H_t)$
- Decoder: to get $P(Y_t | Y_1, \dots, Y_{t-1}, C)$, $H_t = g(Y_{t-1}, C, H_{t-1})$.



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Attention Prompt

A simple regression Problem: $f \in \{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$.

- Average Pooling:

$$f(x) = \frac{1}{n} \sum_{i=1}^n y_i$$

- Attention Pooling:

$$f(x) = \sum_{i=1}^n \alpha(x, x_i) y_i$$

We call x a *query* and (x_i, y_i) a *key-value* pair.
 α is the attention weight, which is the target.²

²Aston Zhang et al. "Dive into Deep Learning". In: *CoRR* abs/2106.11342 (2021). arXiv: 2106.11342. URL: <https://arxiv.org/abs/2106.11342>.

- Nonparametric:

$$\alpha(x, x_i) = \frac{K(x - x_i)}{\sum_j K(x - x_j)}$$

$$K(u) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{u^2}{2}\right)$$

- parametric: learnable *Attention Scoring Function*

Outline

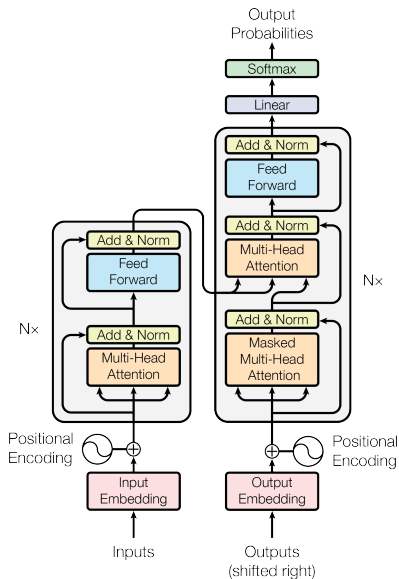
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- Relys entirely on multi-head self-attention
- Encoder-Decoder architecture
- Positional encoding

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³Ashish Vaswani et al. "Attention Is All You Need". In: *CoRR* abs/1706.03762 (2017). arXiv: 1706.03762. URL: <http://arxiv.org/abs/1706.03762>.

Architecture



Encoder:

$N = 6$ layers

Multi-head self-attention +
feed forward

Decoder:

Masked Multi-head
self-attention
Multi-head attention

Others:

Positional Encoding
Layer-normalization

Scoring Function

Scaled Dot-Product Attention

$$\text{Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right) V$$

$$Q \in \mathbb{R}^{n \times d_k} \quad K \in \mathbb{R}^{m \times d_k} \quad V \in \mathbb{R}^{m \times d_v}$$

Multi-Head Attention

It is beneficial to linearly project Q, K, V to d_k, d_k, d_v dimensions h times.

$$\text{Multihead}(Q, K, V) = \text{Concat}(\text{head}_1, \dots, \text{head}_n) W^O$$

where $\text{head}_i = \text{Attention}(QW_i^Q, KW_i^K, VW_i^V)$

Self-attention:

$$\{f(x_i), 1 \leq i \leq n\}$$

where $f \in \{(x_i, x_i)\}$

Positional Encoding

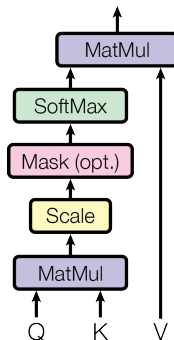
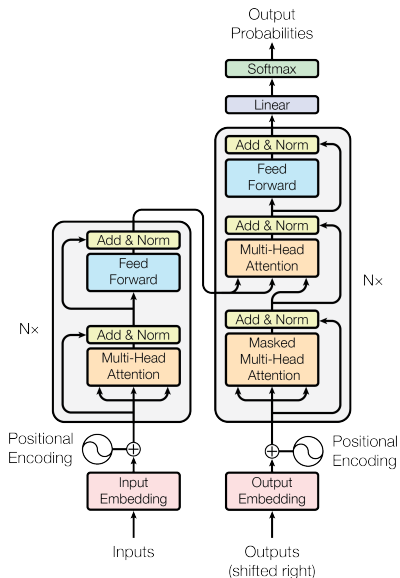
For $P \in \mathbb{R}^{n \times d}$:

$$p_{pos,2i} = \sin\left(\frac{i}{10000^{2i/d}}\right)$$
$$p_{pos,2i+1} = \cos\left(\frac{i}{10000^{2i/d}}\right)$$

n length of sequence; d length of encoding.

Give each position-embedding pair a *unique* value.

Recap



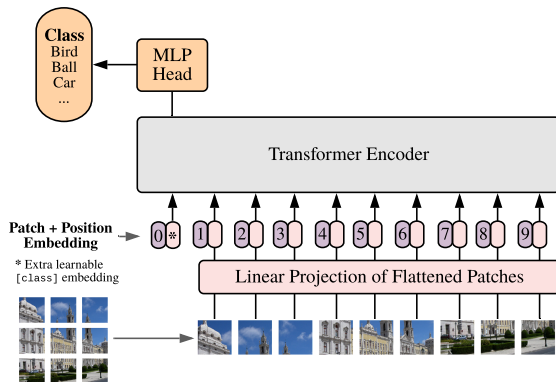
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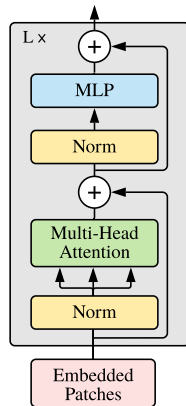
VIT Vision Transformer

Split images into fixed-size patches

Vision Transformer (ViT)



Transformer Encoder



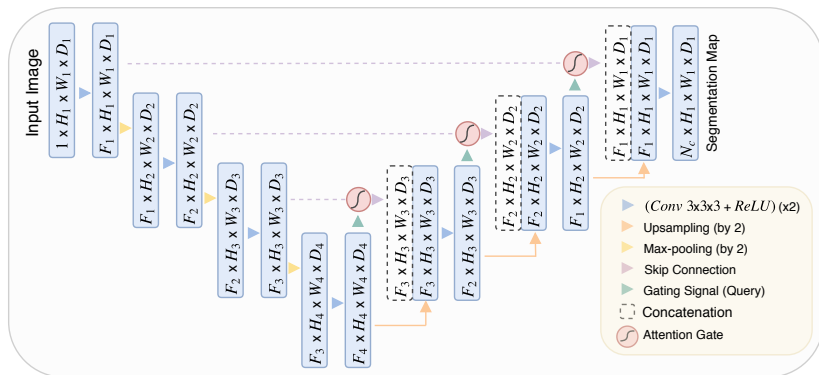
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⁴Alexey Dosovitskiy et al. "An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale". In: *CoRR* abs/2010.11929 (2020). arXiv: 2010.11929. URL: <https://arxiv.org/abs/2010.11929>

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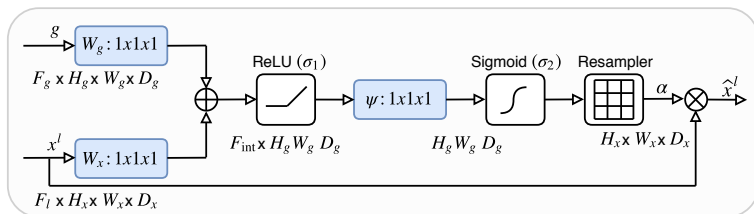
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Attention UNet



Concat(Attention, upsample)

Attention Unet



Using *query* g from a coarser scale. Resampler Trilinear interpolation is applied.⁵

⁵Ozan Oktay et al. "Attention U-Net: Learning Where to Look for the Pancreas". In: *CoRR* abs/1804.03999 (2018). arXiv: 1804.03999. URL: <http://arxiv.org/abs/1804.03999>.

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Inductive Bias

Component	Entities	Relations	Rel. inductive bias	Invariance
Fully connected	Units	All-to-all	Weak	-
Convolutional	Grid elements	Local	Locality	Spatial translation
Recurrent	Timesteps	Sequential	Sequentiality	Time translation
Graph network	Nodes	Edges	Arbitrary	Node, edge permutations

Peter W. Battaglia et al. “Relational inductive biases, deep learning, and graph networks”. In: *CoRR* abs/1806.01261 (2018). arXiv: 1806.01261. URL: <http://arxiv.org/abs/1806.01261>

- [1] Peter W. Battaglia et al. “Relational inductive biases, deep learning, and graph networks”. In: *CoRR* abs/1806.01261 (2018). arXiv: 1806.01261. URL: <http://arxiv.org/abs/1806.01261>.
- [2] Alexey Dosovitskiy et al. “An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale”. In: *CoRR* abs/2010.11929 (2020). arXiv: 2010.11929. URL: <https://arxiv.org/abs/2010.11929>.
- [3] Ozan Oktay et al. “Attention U-Net: Learning Where to Look for the Pancreas”. In: *CoRR* abs/1804.03999 (2018). arXiv: 1804.03999. URL: <http://arxiv.org/abs/1804.03999>.
- [4] Ashish Vaswani et al. “Attention Is All You Need”. In: *CoRR* abs/1706.03762 (2017). arXiv: 1706.03762. URL: <http://arxiv.org/abs/1706.03762>.
- [5] Aston Zhang et al. “Dive into Deep Learning”. In: *CoRR* abs/2106.11342 (2021). arXiv: 2106.11342. URL: <https://arxiv.org/abs/2106.11342>.