

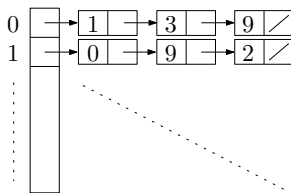
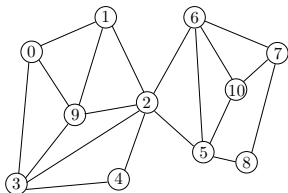
Breadth-First Search

Version of October 11, 2014



Representations of Graphs: Adjacency List

- V : set of vertices, E : set of edges. (We will sometimes also simultaneously use V to denote the number of vertices, and E to denote the number of edges.)
- **Adjacency list representation:** $O(V + E)$ storage
 $Adj[u]$ — linked list of all v such that $(u, v) \in E$.
 - $Adj[0] = \{1, 3, 9\}$; $Adj[1] = \{0, 9, 2\}$; ...
- Can retrieve all the neighbors of u in $O(\text{degree}(u))$ time.



Representations of Graphs: Adjacency Matrix

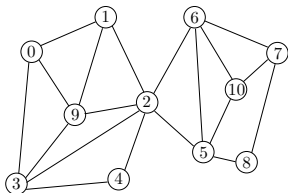
- Adjacency matrix representation: $O(V^2)$ storage

$A = [a_{ij}]$, $a_{ij} = 1$ if $(v_i, v_j) \in E$;

$a_{ij} = 0$ if $(v_i, v_j) \notin E$.

For undirected graph, adjacency matrix is always **symmetric**.

- Can check if u and v are connected in $O(1)$ time.



	0	1	2	3	4	5	6	7	8	9	10
0	0	1	0	1	0	0	0	0	0	1	0
1	1	0	1	0	0	0	0	0	0	1	0
2	0	1	0	1	1	1	1	0	0	1	0
3	1	0	1	0	1	0	0	0	0	1	0
4	0	0	1	1	0	0	0	0	0	0	0
5	0	0	1	0	0	0	1	0	1	0	1
6	0	0	1	0	0	1	0	1	0	0	1
7	0	0	0	0	0	0	1	0	1	0	1
8	0	0	0	0	0	1	0	1	0	0	0
9	1	1	1	1	0	0	0	0	0	0	0
10	0	0	0	0	0	1	1	1	0	0	0

The Breadth-First Search (BFS) Algorithm

What does Breadth-First Search (BFS) do?

- Traverse all vertices in graph, and thereby
- Reveal properties of the graph.

Three arrays are used to keep information gathered during traversal

- ① $color[u]$: the **color** of each vertex visited
 - WHITE: **undiscovered**
 - GRAY: **discovered** but not finished processing
 - BLACK: **finished** processing
- ② $pred[u]$: the **predecessor** pointer
 - pointing back to the vertex from which u was discovered
- ③ $d[u]$: the **distance** from the source to vertex u

BFS(G)

```
// Initialize
foreach  $u$  in  $V$  do
    color[u] = WHITE; // undiscovered
    pred[u] = NULL; // no predecessor
end
time = 0;
foreach  $u$  in  $V$  do
    // start a new tree
    if color[u] = WHITE then
        | BFSVisit(u);
    end
end
```

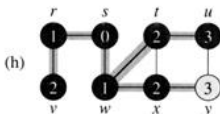
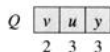
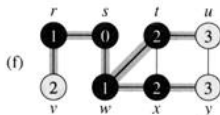
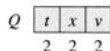
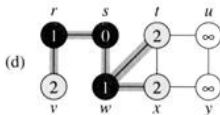
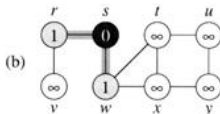
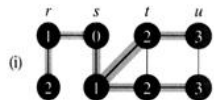
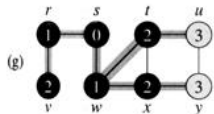
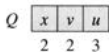
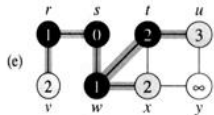
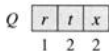
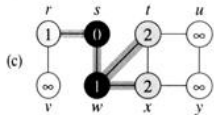
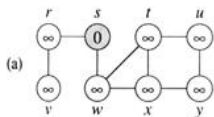
BFSVisit(s)

```
color[s] = GRAY; pred[s] = NULL; d[s] = 0;
Q =  $\emptyset$ ; Enqueue(Q,s);
while  $Q \neq \emptyset$  do
    u = Dequeue(Q);
    foreach  $v \in Adj[u]$  do
        if  $color[v] = \text{WHITE}$  then
            color[v] = GRAY;
            d[v] = d[u]+1 ;
            pred[v] = u;
            Enqueue(Q,v);
        end
    end
    color[u] = BLACK;
end
```

Question

Which graph representation shall we use?

BFS Example



The BFS Algorithm

The outputs of BFS:

- 1 Distance array: $d[v]$
- 2 Predecessor array $pred[v]$

The BFS Forest:

- Use $pred[v]$ to define a graph $F = (V, E_f)$ as follows:

$$E_f = \{(pred[v], v) | v \in V, pred[v] \neq \text{NULL}\}$$

- This graph has no cycles (why?), and is therefore a **forest**, i.e. a collection of trees. We call it a **BFS Forest**.
- In each tree, $d[v]$ gives the shortest distance to the initial vertex of the tree.
- Following $pred[v]$ gives a shortest path to the initial vertex of the tree.

Running Time of BFS

On each vertex u , we spend time $T_u = O(1 + \text{degree}(u))$

The total running time is

$$\sum_{u \in V} T_u \leq \sum_{u \in V} (O(1 + \text{degree}(u))) = O(V + E)$$

Hence, the running of BFS on a graph with V vertices and E edges is $O(V + E)$

Applications:

- ① Shortest paths in a graph
 - What if the graph is weighted?
- ② Finding connected components