

COMP170

Discrete Mathematical Tools for Computer Science

Lecture 14 *Version 5 Last updated, Nov 17 2005*

Discrete Math for Computer Science
K. Bogart, C. Stein and R.L. Drysdale
Section 5.1, pp. 213-221

Introduction to Probability

- Why Study Probability?
- Probability Spaces and Distributions
- Complementary Probabilities
- Probability and Hashing
- The Uniform Probability Distribution

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In Computer Science we often deal with random events.

Some involve randomness imposed from the outside, e.g., networking, when requests from computers on the network enter the network at “random” time.

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Studying the performance of computer systems in the presence of these types of randomness, requires understanding randomness, which is the study of probability.

Hashing

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The records are stored in a table. each table location, called a **bucket** or **slot**, holds a list of records. We are also given a **hash function** $h(x)$. A record with key key is stored in the bucket with index $h(key)$.

Hashing

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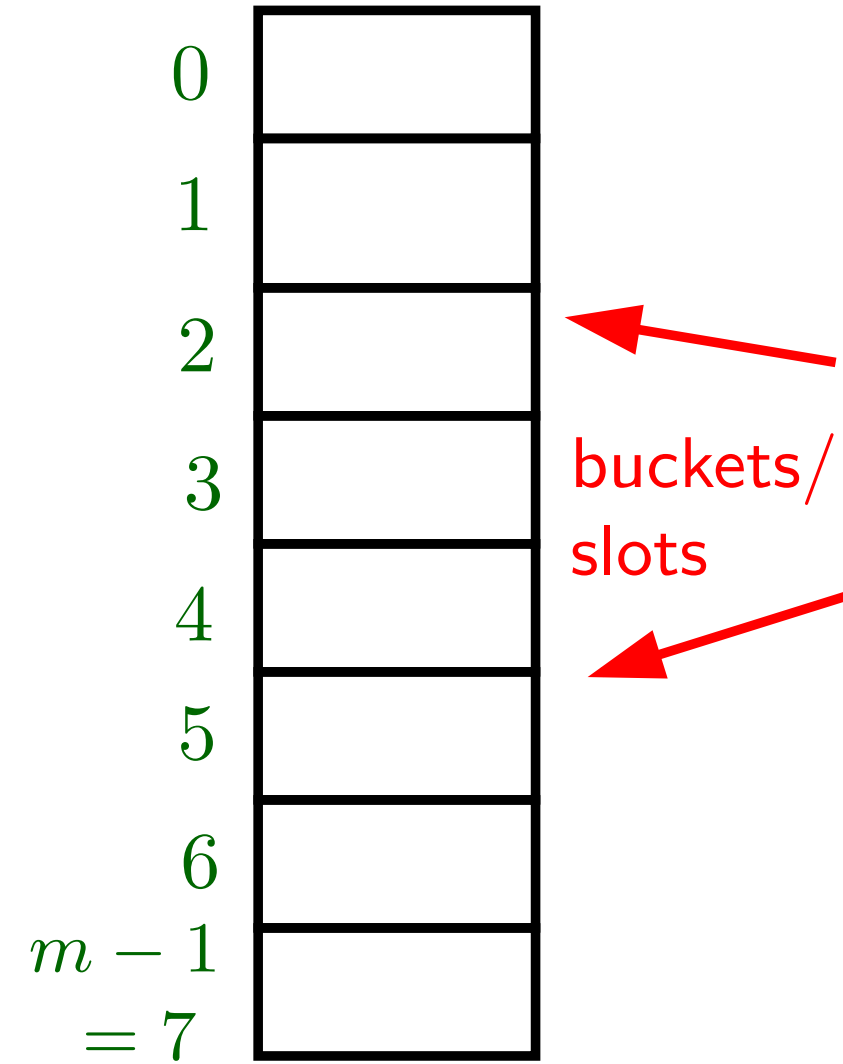
Hash Table T

0	
1	
2	
3	
4	
5	
6	
$m - 1$ $= 7$	

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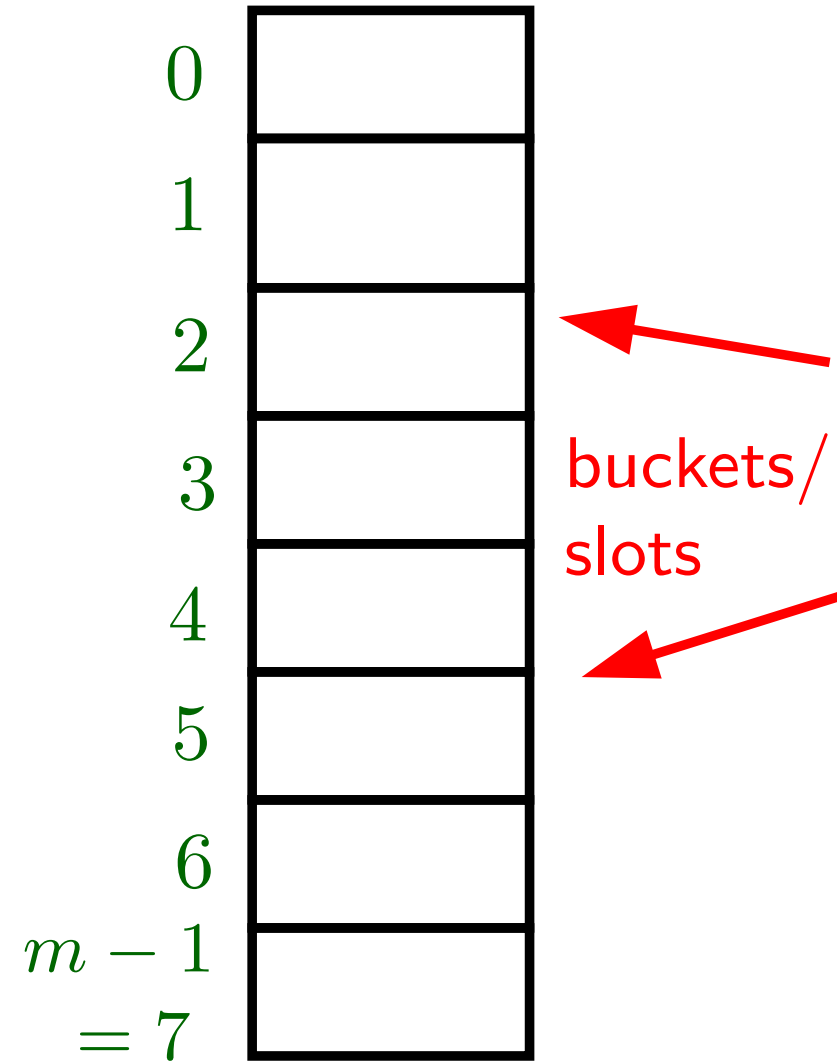
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Our Hash Function:

$$h(x) = x \bmod m$$

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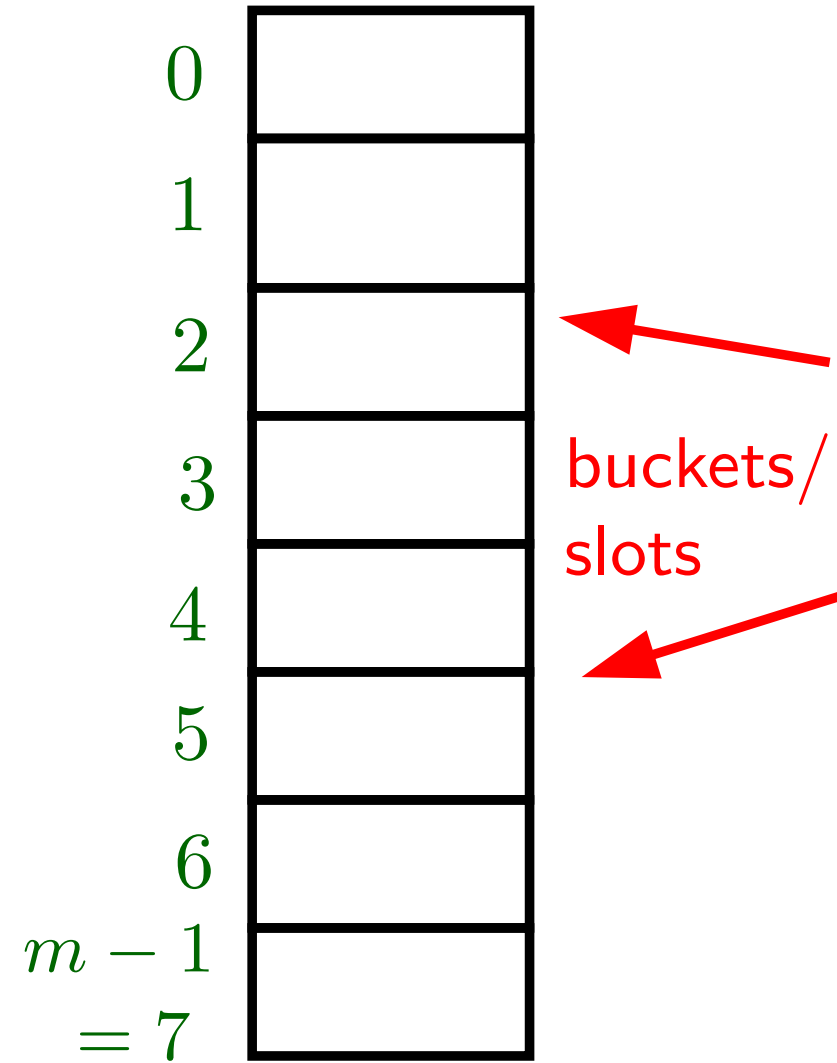
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Data (with Keys)

Hash Table T



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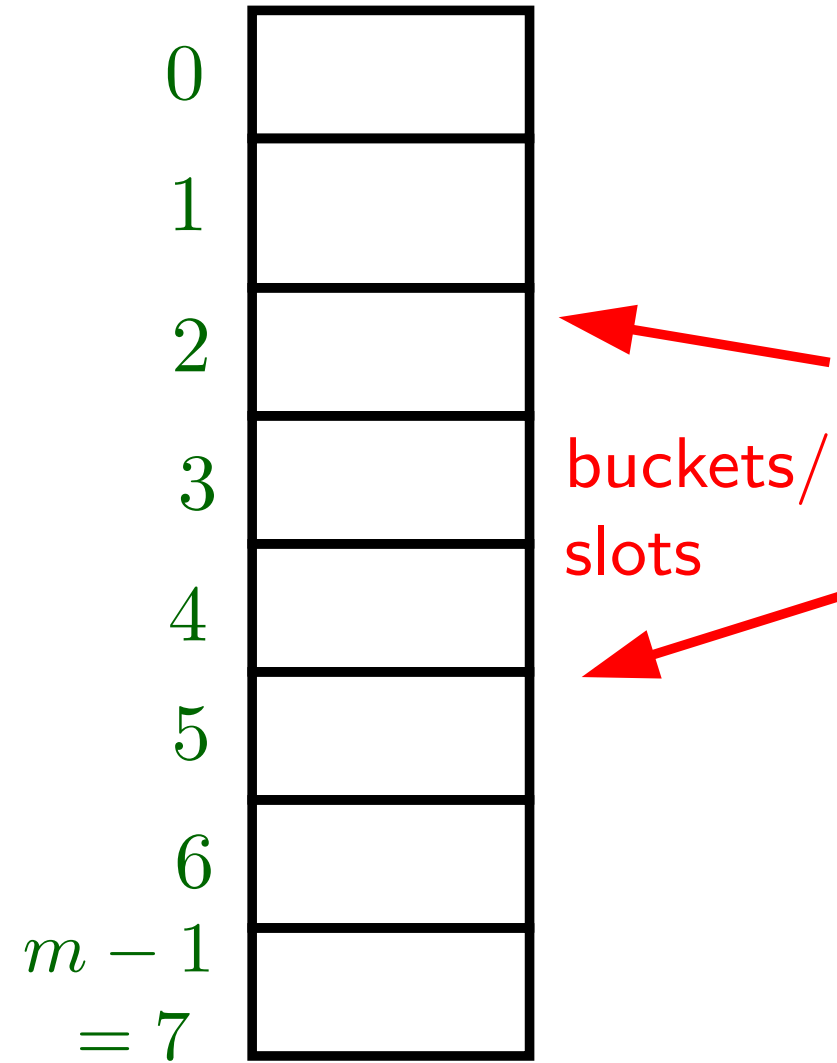
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buckets/
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buckets/
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When searching for a record you might have to look at *every* record in the appropriate bucket, so

Good hash function spreads keys evenly among buckets.

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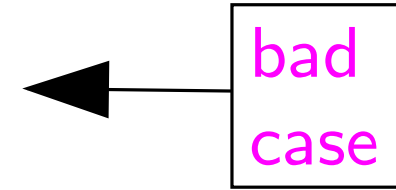
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Is it possible that all 50 keys are
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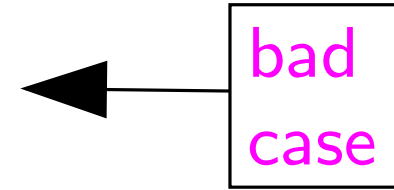
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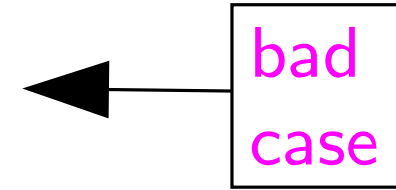
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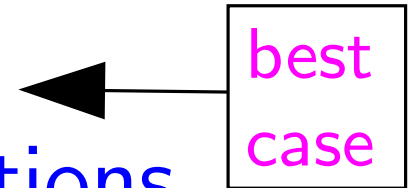
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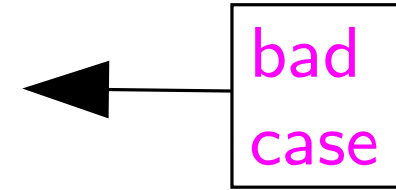


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- Actually, you also wouldn't see that all the keys hash into *different* locations.



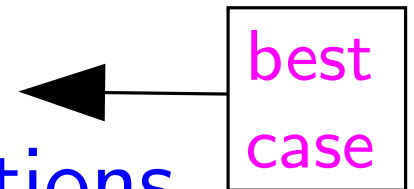
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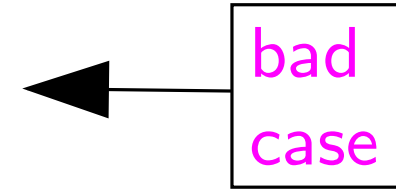
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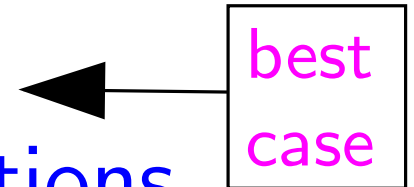
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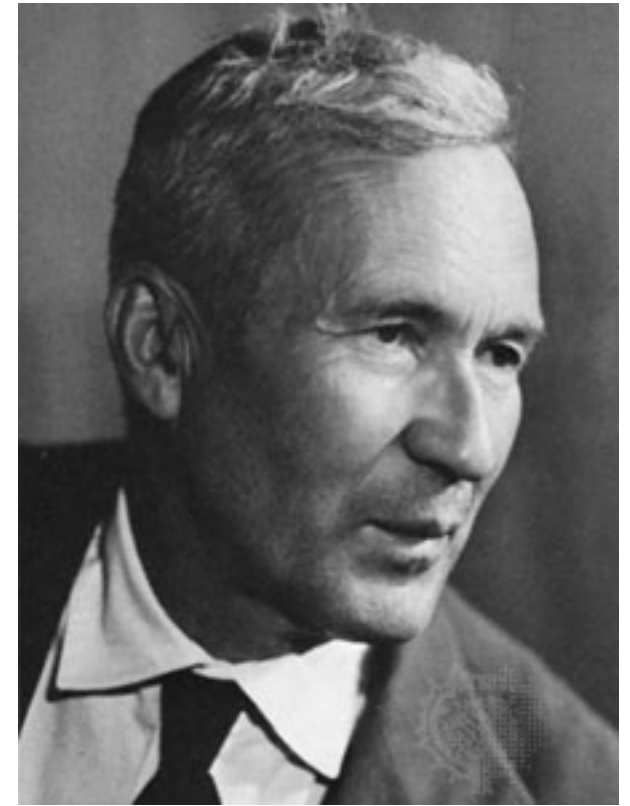
- The underlying Sample Space and Elements (Outcomes) in the sample space
- An event in the Sample Space
- The Weight of an element in the sample space Gives a Probability Distribution (Measure)

Andrei Nikolaevich Kolmogorov

Russian Mathematician

b. 1903. d. 1987

The birth of probability theory is often dated to 1654, when **Pascal** and **Fermat**, trying to solve a gambling problem, developed the fundamentals.



It wasn't until the work of Kolmogorov in 1933, though, that we had a “definition of probability that is precise enough for use in mathematics, yet comprehensive enough to be applicable to a wide range of phenomena”.

Ref. A Short History of Probability by Tom Apostol

http://www.cc.gatech.edu/classes/cs6751_97_winter/Topics/stat-meas/probHist.html

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Professor starts each class

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The sample space of all possible patterns
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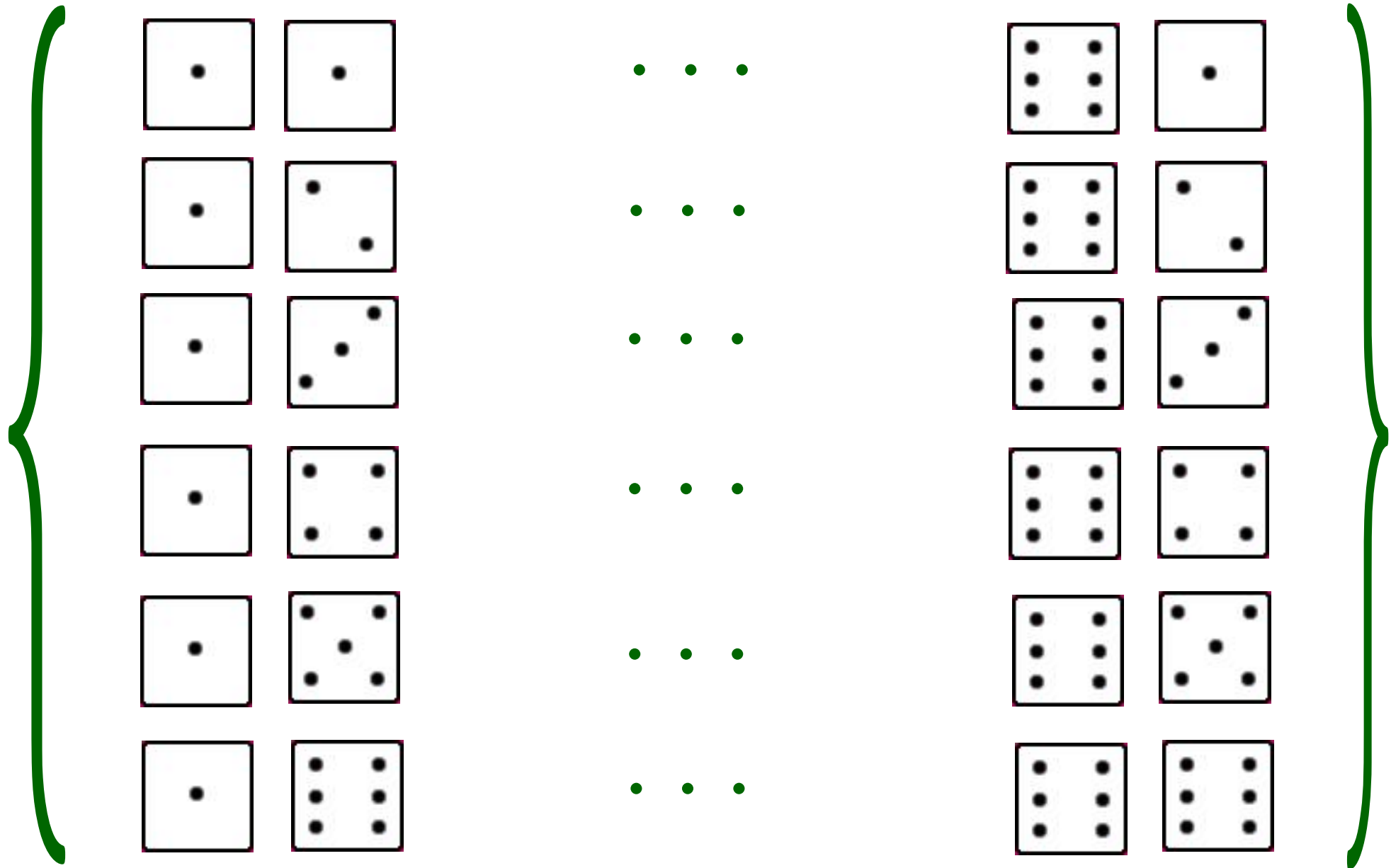
*Note: **TTT** corresponds to all answers being true, etc..*

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$\{H, TH, TTH, TTTH, TTTTH, \dots\}$

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3) Event of a Head occurring in the first 3 flips: $\{\text{H}, \text{TH}, \text{TTH}\}$.

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The **probability** $P(E)$ **of event** E is:
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$$P(E) = \sum_{x:x \in E} P(x)$$

read: “The probability of event E is the sum, over all x such that x is in E , of $P(x)$.”

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A function P satisfying these rules is called a **probability distribution** or a **probability measure**.

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The professor's three-question quiz with sample space

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$\{TTT, TTF, TFT, FTT, TFF, FTF, FFT, FFF\}$.

Suppose that each sequence of **T** and **F** is equally likely. We then want to assign each outcome the same (*uniform*) probability weight. Since the sum of the weights must add up to **1**, we assign each of the **8** outcomes a weight of $\frac{1}{8}$.

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$$\frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} = \frac{1}{2}$$

Example 1b:

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Example 1c:

Now suppose that the professor has a bias towards true answers and a **T** is more likely than a **F**. Let's assume that a **T** has a probability of $2/3$ and a **F** has a probability of $1/3$. Then, we will see later, we will get the following different weights on the *same* sample space as before

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These add up to 1, so this is a legal probability distribution

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The event of the dice adding up to 4 is: $\left\{ \begin{array}{cc} \begin{array}{|c|} \hline \cdot \\ \hline \end{array}, & \begin{array}{|c|} \hline \cdot & \cdot \\ \hline \end{array}, & \begin{array}{|c|} \hline \cdot & \cdot & \cdot \\ \hline \end{array} \\ \begin{array}{|c|} \hline \cdot & \cdot & \cdot \\ \hline \end{array}, & \begin{array}{|c|} \hline \cdot & \cdot \\ \hline \end{array}, & \begin{array}{|c|} \hline \cdot \\ \hline \end{array} \end{array} \right\}$

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There are three outcomes in this event, so its probability is

$$\frac{1}{36} + \frac{1}{36} + \frac{1}{36} = \frac{1}{12}$$

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the sample space is

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Note that this is a legal probability distribution, since

$$\sum_{i=1}^{\infty} \frac{1}{2^i} = 1$$

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- Why Study Probability?
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Note that $S = A \cup B$ (or $B = S - A$)
and that $P(A) + P(B) = 1$.

Complementary Probabilities

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- Two events E and F are **complementary** (in S) if E is the complement of F in the sample space S .

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If two events E and F are complementary, then

$$P(E) = 1 - P(F).$$

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Example:

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1	
2	
3	
4	
5	
6	
7	

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Example: 3, 12, 15, 8, 11, 5

is outcome (3, 4, 7, 0, 3, 5)

0	8
1	
2	
3	3 11
4	12
5	5
6	
7	15

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Weight function: Assuming that hash function is “random” then every n -tuple is equally likely. So, every n -tuple should have (the same) weight $1/m^n$.

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What is the probability of event A in which all three keys hash to different locations, i.e., no collisions?

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$$\Rightarrow P(A) = \frac{20 \cdot 19 \cdot 18}{20^3} = .855$$

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$$P(B) = 1 - P(A) = 1 - .855 = .145$$

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$$\Rightarrow P(A) = \frac{20^n}{20^n}$$

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Since events A and B are complementary

$$P(B) = 1 - P(A) = 1 - \frac{20^n}{20^n}$$

n	Probability of No Collisions
1	1
2	.95
3	.855
4	.72675
5	.5814
6	.43605
7	.305235
8	.19840275
9	.11904165
10	.065472908
11	.032736454
12	.014731404
13	.005892562
14	.002062397
15	.000618719
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17	.0000309359
18	.00000464039
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Probabilities that all elements of set hash to different entries of hash table of size 20 is

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$$p_{n+1} = p_n \frac{20 - n}{20} < p_n,$$

p_n decreases as n increases

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Suppose P is uniform probability measure defined on sample space S . Then for any event E ,

$$P(E) = \frac{|E|}{|S|},$$

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Note: We have implicitly used this theorem many times already

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$$\begin{aligned} 1 &= P(S) \\ &= P(x_1 \cup x_2 \cup \dots \cup x_{|S|}) \\ &= P(x_1) + P(x_2) + \dots + P(x_{|S|}) \\ &= p|S|. \end{aligned}$$

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E is a subset of S with $|E|$ elements and, therefore,

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Combining these equations gives

$$P(E) = |E|p = |E|(1/|S|) = |E|/|S|.$$

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Use Theorem 5.2

\Rightarrow probability is $4/8 = 1/2$ by Theorem 5.2.

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Sample Space: $\{0, 1, 2, 3\}$

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Sample Space:	$\{0,$	$1,$	$2,$	$3\}$
with weights	$\frac{1}{8}$	$\frac{3}{8}$	$\frac{3}{8}$	$\frac{1}{8}$

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Sample Space: $\{0, 1, 2, 3\}$
with weights $\frac{1}{8} \quad \frac{3}{8} \quad \frac{3}{8} \quad \frac{1}{8}$

Theorem 5.2 doesn't apply to this distribution. For example, let E be the event that the outcome is not positive.

Then $E = \{0\}$ but

$$P(E) = \frac{1}{8} \neq \frac{1}{4} = \frac{|E|}{|S|}$$

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1 way to get 3 H's.

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$P(2)$ should be 3 times $P(0)$

$P(3)$ should be equal $P(0)$

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which is **exactly** the non-uniform distribution
we just saw.