

All-Pairs Shortest Paths

Version of October 28, 2016



- Another example of dynamic programming
- Will see **two** different dynamic programming formulations for same problem.

Outline

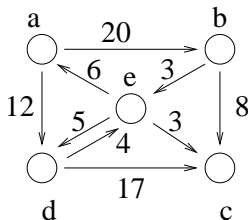
- The all-pairs shortest path problem.
- A first dynamic programming solution.
- The Floyd-Warshall algorithm
- Extracting shortest paths.

The All-Pairs Shortest Paths Problem

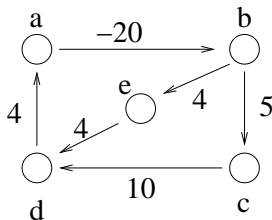
Input: weighted digraph $G = (V, E)$ with weight function $w : E \rightarrow \mathbb{R}$

Find: lengths of the shortest paths (i.e., **distance**) between **all** pairs of vertices in G .

- we assume that there are no cycles with **zero or negative cost**.



without negative cost cycle



with negative cost cycle

Solution 1: Using Dijkstra's Algorithm

- Where there are no negative cost edges.
 - Apply Dijkstra's algorithm n times, once with **each** vertex (as the source) of the shortest path tree.
 - Recall that Dijkstra algorithm runs in $\Theta(e \log n)$
 - $n = |V|$ and $e = |E|$.
 - This gives a $\Theta(ne \log n)$ time algorithm
 - If the digraph is dense, this is a $\Theta(n^3 \log n)$ algorithm.
- When negative-weight edges are present:
 - Run the Bellman-Ford algorithm from each vertex.
 - $O(n^2 e)$, which is $O(n^4)$ for dense graphs.
 - We don't learn Bellman-Ford in this class.

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Input and Output Formats

Input Format:

- To simplify the notation, we assume that $V = \{1, 2, \dots, n\}$.
- Adjacency matrix: graph is represented by an $n \times n$ matrix containing edge weights

$$w_{ij} = \begin{cases} 0 & \text{if } i = j, \\ w(i, j) & \text{if } i \neq j \text{ and } (i, j) \in E, \\ \infty & \text{if } i \neq j \text{ and } (i, j) \notin E. \end{cases}$$

Output Format: an $n \times n$ matrix $D = [d_{ij}]$ in which d_{ij} is the length of the shortest path from vertex i to j .

Step 1: Space of Subproblems

For $m = 1, 2, 3, \dots$,

- Define $d_{ij}^{(m)}$ to be the length of the **shortest path** from i to j that **contains at most m edges**.
- Let $D^{(m)}$ be the $n \times n$ matrix $[d_{ij}^{(m)}]$.

We will see (next page) that solution D satisfies $D = D^{n-1}$.

Subproblems: (Iteratively) compute $D^{(m)}$ for $m = 1, \dots, n - 1$.

Step 1: Space of Subproblems

Lemma

$D^{(n-1)} = D$, i.e.

$d_{ij}^{(n-1)} = \text{true distance from } i \text{ to } j$

Proof.

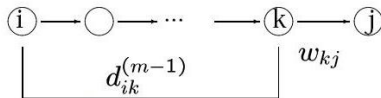
We prove that any shortest path P from i to j contains at most $n - 1$ edges.

First note that since all cycles have positive weight, a shortest path can have no cycles (if there were a cycle, we could remove it and lower the length of the path).

A path without cycles can have length at most $n - 1$ (since a longer path must contain some vertex twice, that is, contain a cycle). \square

Step 2: Building $D^{(m)}$ from $D^{(m-1)}$.

Consider a **shortest path** from i to j that contains at most m edges.



Let k be the vertex immediately before j on the shortest path (k could be i).

The sub-path from i to k must be the shortest i - k path with at most $m - 1$ edges. Then $d_{ij}^{(m)} = d_{ik}^{(m-1)} + w_{kj}$.

Since we don't know k , we try all possible choices: $1 \leq k \leq n$.

$$d_{ij}^{(m)} = \min_{1 \leq k \leq n} \left\{ d_{ik}^{(m-1)} + w_{kj} \right\}$$

Step 3: Bottom-up Computation of $D^{(n-1)}$

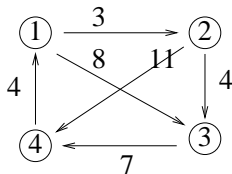
- Initialization: $D^{(1)} = [w_{ij}]$, the weight matrix.
- Iteration step: Compute $D^{(m)}$ from $D^{(m-1)}$, for $m = 2, \dots, n - 1$, using

$$d_{ij}^{(m)} = \min_{1 \leq k \leq n} \left\{ d_{ik}^{(m-1)} + w_{kj} \right\}$$

Example: Bottom-up Computation of $D^{(n-1)}$

$D^{(1)} = [w_{ij}]$ is just the weight matrix:

$$D^{(1)} = \begin{bmatrix} 0 & 3 & 8 & \infty \\ \infty & 0 & 4 & 11 \\ \infty & \infty & 0 & 7 \\ 4 & \infty & \infty & 0 \end{bmatrix}$$



$$d_{ij}^{(2)} = \min_{1 \leq k \leq 4} \{d_{ik}^{(1)} + w_{kj}\}$$

$$d_{ij}^{(3)} = \min_{1 \leq k \leq 4} \{d_{ik}^{(2)} + w_{kj}\}$$

$$D^{(2)} = \begin{bmatrix} 0 & 3 & 7 & 14 \\ 15 & 0 & 4 & 11 \\ 11 & \infty & 0 & 7 \\ 4 & 7 & 12 & 0 \end{bmatrix}$$

$$D^{(3)} = \begin{bmatrix} 0 & 3 & 7 & 14 \\ 15 & 0 & 4 & 11 \\ 11 & 14 & 0 & 7 \\ 4 & 7 & 11 & 0 \end{bmatrix}$$

$D^{(3)}$ gives the distances between **any** pair of vertices.

$$d_{ij}^{(m)} = \min_{1 \leq k \leq n} \{ d_{ik}^{(m-1)} + w_{kj} \}$$

```

for  $m = 1$  to  $n - 1$  do
  for  $i = 1$  to  $n$  do
    for  $j = 1$  to  $n$  do
       $min = \infty$ ;
      for  $k = 1$  to  $n$  do
         $new = d_{ik}^{(m-1)} + w_{kj}$ ;
        if  $new < min$  then
           $min = new$ 
        end
      end
       $d_{ij}^{(m)} = min$ ;
    end
  end
end

```

Running time $O(n^4)$, much worse than the solution using Dijkstra's algorithm.

Question

Can we improve this?

Repeated Squaring

We use the recurrence relation:

- Initialization: $D^{(1)} = [w_{ij}]$, the weight matrix.
- For $s \geq 1$ compute $D^{(2^s)}$ using

$$d_{ij}^{(2^s)} = \min_{1 \leq k \leq n} \{d_{ik}^{(2^{s-1})} + d_{kj}^{(2^{s-1})}\}$$

- From equation, can calculate $D^{(2^i)}$ from $D^{(2^{i-1})}$ in $O(n^3)$ time.
- have shown earlier that the shortest path between any two vertices contains no more than $n - 1$ edges. So

$$D^i = D^{(n-1)} \text{ for all } i \geq n.$$

We can therefore calculate all of

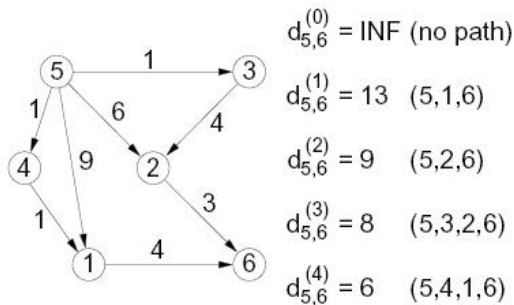
$$D^{(2)}, D^{(4)}, D^{(8)}, \dots, D^{(2^{\lceil \log_2 n \rceil})} = D^{(n-1)}$$

in $O(n^3 \log n)$ time, improving our running time.

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Step 1: Space of subproblems

- The vertices v_2, v_3, \dots, v_{l-1} are called the **intermediate vertices** of the path $p = \langle v_1, v_2, \dots, v_{l-1}, v_l \rangle$.
- For any $k=0, 1, \dots, n$, let $d_{ij}^{(k)}$ be the **length of the shortest path** from i to j such that **all** intermediate vertices on the path (**if any**) are in the set $\{1, 2, \dots, k\}$.



Step 1: Space of subproblems

- $d_{ij}^{(k)}$ is the **length of the shortest path** from i to j such that **all** intermediate vertices on the path (**if any**) are in the set $\{1, 2, \dots, k\}$.
- Let $D^{(k)}$ be the $n \times n$ matrix $[d_{ij}^{(k)}]$.
- **Subproblems:** compute $D^{(k)}$ for $k = 0, 1, \dots, n$.
- **Original Problem:** $D = D^{(n)}$, i.e. $d_{ij}^{(n)}$ is the shortest distance from i to j

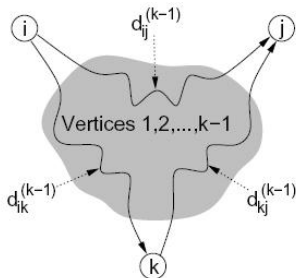
Step 2: Relating Subproblems

Observation : For a shortest path from i to j with intermediate vertices from the set $\{1, 2, \dots, k\}$, there are two possibilities:

- 1 k is not a vertex on the path: $d_{ij}^{(k)} = d_{ij}^{(k-1)}$
- 2 k is a vertex on the path.: $d_{ij}^{(k)} = d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$

(Impossible for k to appear in path twice. Why?) So:

$$d_{ij}^{(k)} = \min \left\{ d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right\}$$



Step 2: Relating Subproblems

Proof.

- Consider a **shortest path** from i to j with intermediate vertices from the set $\{1, 2, \dots, k\}$. Either it contains vertex k or it does not.
- If it does not contain vertex k , then its length must be $d_{ij}^{(k-1)}$.
- Otherwise, it contains vertex k , and we can decompose it into a subpath from i to k and a subpath from k to j .
- Each subpath can only contain intermediate vertices in $\{1, \dots, k-1\}$, and must be as short as possible. Hence they have lengths $d_{ik}^{(k-1)}$ and $d_{kj}^{(k-1)}$.
- Hence the shortest path from i to j has length $\min \left\{ d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right\}$.



Step 3: Bottom-up Computation

- Initialization: $D^{(0)} = [w_{ij}]$, the weight matrix.
- Compute $D^{(k)}$ from $D^{(k-1)}$ using

$$d_{ij}^{(k)} = \min \left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right)$$

for $k = 1, \dots, n$.

The Floyd-Warshall Algorithm: Version 1

Floyd-Warshall(w, n): $d_{ij}^{(k)} = \min \left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right)$

```
for  $i = 1$  to  $n$  do
    for  $j = 1$  to  $n$  do
        |  $d^{(0)}[i, j] = w[i, j]$ ;  $pred[i, j] = nil$ ; // initialize
    end
end
// dynamic programming
for  $k = 1$  to  $n$  do
    for  $i = 1$  to  $n$  do
        for  $j = 1$  to  $n$  do
            if  $\left( d^{(k-1)}[i, k] + d^{(k-1)}[k, j] < d^{(k-1)}[i, j] \right)$  then
                |  $d^{(k)}[i, j] = d^{(k-1)}[i, k] + d^{(k-1)}[k, j]$ ;
                |  $pred[i, j] = k$ ;
            else
                end
             $d^{(k)}[i, j] = d^{(k-1)}[i, j]$ ;
        end
    end
end
return  $d^{(n)}[1..n, 1..n]$ 
```

Comments on the Floyd-Warshall Algorithm

- The algorithm's running time is clearly $\Theta(n^3)$.
- The predecessor pointer $\text{pred}[i, j]$ can be used to extract the shortest paths (see later).

Problem: the algorithm uses $\Theta(n^3)$ space.

- It is possible to reduce this to $\Theta(n^2)$ space by keeping only one matrix instead of n .
- Algorithm is on next page. Convince yourself that it works.

The Floyd-Warshall Algorithm: Version 2

$$d_{ij}^{(k)} = \min \left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right)$$

Floyd-Warshall(*w*, *n*)

```
for i = 1 to n do
    for j = 1 to n do
        | d[i,j] = w[i,j]; pred[i,j] = nil; // initialize
    end
end
// dynamic programming
for k = 1 to n do
    for i = 1 to n do
        for j = 1 to n do
            if (d[i,k] + d[k,j] < d[i,j]) then
                | d[i,j] = d[i,k] + d[k,j];
                | pred[i,j] = k;
            end
        end
    end
end
return d[1..n, 1..n];
```

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Extracting the Shortest Paths

predecessor pointers $\text{pred}[i, j]$ can be used to extract the shortest paths.

Idea:

- Whenever we discover that the shortest path from i to j passes through an intermediate vertex k , we set $\text{pred}[i, j] = k$.
- If the shortest path does not pass through any intermediate vertex, then $\text{pred}[i, j] = \text{nil}$.
- To find the shortest path from i to j , we consult $\text{pred}[i, j]$.
 - 1 If it is nil, then the shortest path is just the edge (i, j) .
 - 2 Otherwise, we **recursively** construct the shortest path from i to $\text{pred}[i, j]$ and the shortest path from $\text{pred}[i, j]$ to j .

The Algorithm for Extracting the Shortest Paths

Path(i, j)

```
if  $pred[i, j] = nil$  then
    // single edge
    output ( $i, j$ );
else
    // compute the two parts of the path
    Path( $i, pred[i, j]$ );
    Path( $pred[i, j], j$ );
end
```

Example of Extracting the Shortest Paths

Find the shortest path from vertex 2 to vertex 3.

2..3	Path(2, 3)	$pred[2, 3] = 6$	
2..6..3	Path(2, 6)	$pred[2, 6] = 5$	
2..5..6..3	Path(2, 5)	$pred[2, 5] = nil$	<i>Output(2,5)</i>
25..6..3	Path(5, 6)	$pred[5, 6] = nil$	<i>Output(5,6)</i>
256..3	Path(6, 3)	$pred[6, 3] = 4$	
256..4..3	Path(6, 4)	$pred[6, 4] = nil$	<i>Output(6,4)</i>
2564..3	Path(4, 3)	$pred[4, 3] = nil$	<i>Output(4,3)</i>
25643			