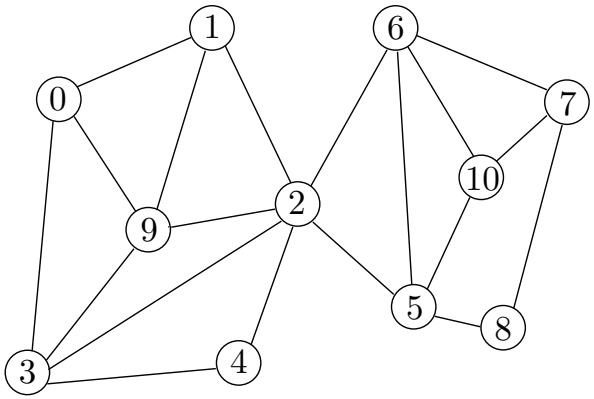
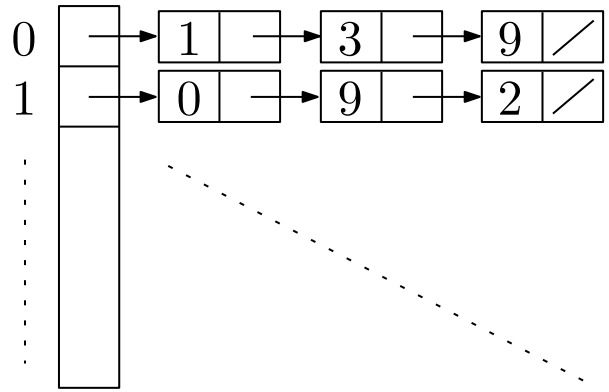
Breadth-First Search

Version of September 23, 2016

Representations of Graphs: Adjacency List

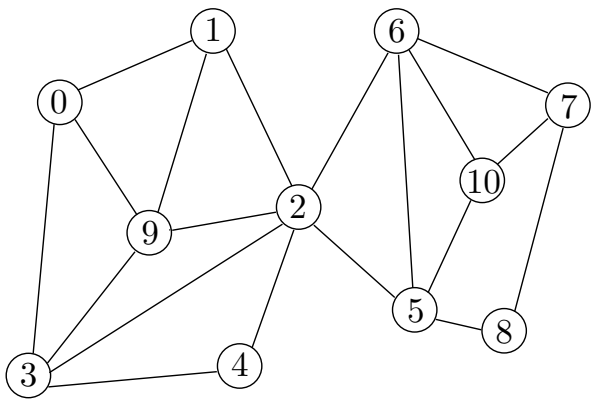
- V: set of vertices, E: set of edges. (We will sometimes also simultaneously use V to denote the number of vertices, and E to denote the number of edges.)
- Adjacency list representation: $O(V + E)$ storage
  $Adj[u]$ — linked list of all v such that $(u, v) \in E$.
  - $Adj[0] = \{1, 3, 9\}$; $Adj[1] = \{0, 9, 2\}$; ...
- Can retrieve all the neighbors of u in $O(\text{degree}(u))$ time.





Representations of Graphs: Adjacency Matrix

- Adjacency matrix representation: $O(V^2)$ storage
  $A = [a_{ij}]$, $a_{ij} = 1$ if $(v_i, v_j) \in E$;
  $a_{ij} = 0$ if $(v_i, v_j) \notin E$.
  For undirected graph, adjacency matrix is always symmetric.
- Can check if u and v are connected in $O(1)$ time.



	0	1	2	3	4	5	6	7	8	9	10
0	0	1	0	1	0	0	0	0	0	1	0
1	1	0	1	0	0	0	0	0	0	1	0
2	0	1	0	1	1	1	1	0	0	1	0
3	1	0	1	0	1	0	0	0	0	1	0
4	0	0	1	1	0	0	0	0	0	0	0
5	0	0	1	0	0	0	1	0	1	0	1
6	0	0	1	0	0	1	0	1	0	0	1
7	0	0	0	0	0	0	1	0	1	0	1
8	0	0	0	0	0	1	0	1	0	0	0
9	1	1	1	1	0	0	0	0	0	0	0
10	0	0	0	0	0	1	1	1	0	0	0

The Breadth-First Search (BFS) Algorithm

What does Breadth-First Search (BFS) do?

- Traverse all vertices in graph, and thereby
- Reveal properties of the graph.

Three arrays are used to keep information gathered during traversal

1. *color*[*u*]: the color of each vertex visited
   - WHITE: undiscovered
   - GRAY: discovered but not finished processing
   - BLACK: finished processing
2. *pred*[*u*]: the predecessor pointer
   - pointing back to the vertex from which *u* was discovered
3. *d*[*u*]: the distance from the source to vertex *u*

BFS Algorithm

BFS(G)

```
// Initialize
foreach u in V do
    color[u] = WHITE; // undiscovered
    pred[u] = NULL; // no predecessor
end
time= 0;
foreach u in V do
    // start a new tree
    if color[u] = WHITE then
        BFSVisit(u);
    end
end
```

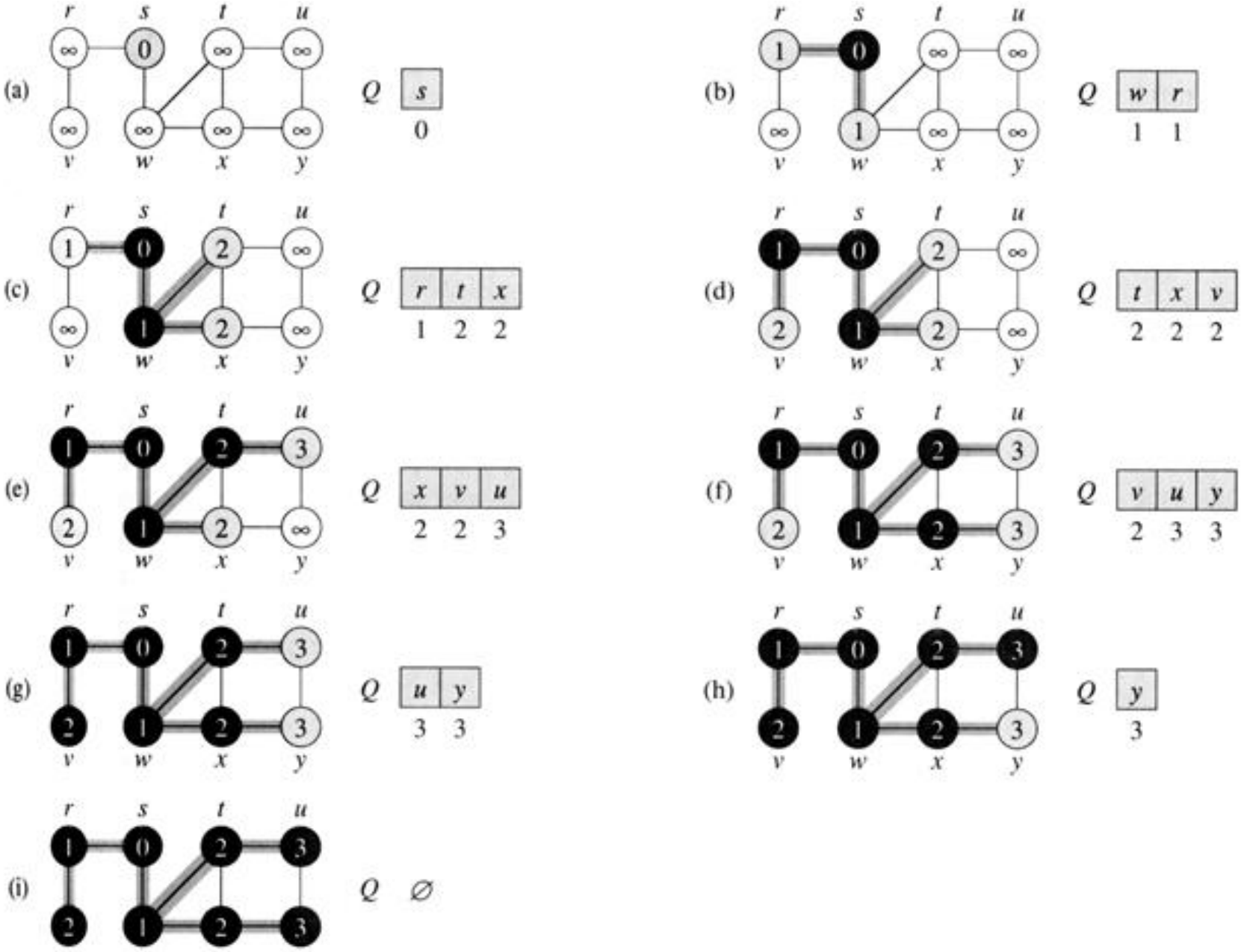
BFSVisit(s)

```
color[s] = GRAY; pred[s] = NULL; d[s] = 0;
Q = ∅; Enqueue(Q,s);
while Q ≠ ∅ do
    u = Dequeue(Q);
    foreach v ∈ Adj[u] do
        if color[v] = WHITE then
            color[v] = GRAY;
            d[v] = d[u]+1 ;
            pred[v] = u;
            Enqueue(Q,v);
        end
    end
    color[u] = BLACK;
end
```

Question

Which graph representation shall we use?

BFS Example


(a)
r s t u
∞ 0 ∞ ∞
∞ ∞ ∞ ∞
v w x y
Q s
0
(b)
r s t u
1 0 ∞ ∞
∞ 1 ∞ ∞
v w x y
Q w r
1 1
(c)
r s t u
1 0 2 ∞
∞ 1 2 ∞
v w x y
Q r t x
1 2 2
(d)
r s t u
1 0 2 ∞
2 1 2 ∞
v w x y
Q t x v
2 2 2
(e)
r s t u
1 0 2 3
2 1 2 ∞
v w x y
Q x v u
2 2 3
(f)
r s t u
1 0 2 3
2 1 2 3
v w x y
Q v u y
2 3 3
(g)
r s t u
1 0 2 3
2 1 2 3
v w x y
Q u y
3 3
(h)
r s t u
1 0 2 3
2 1 2 3
v w x y
Q y
3
(i)
r s t u
1 0 2 3
2 1 2 3
Q ∅

The BFS Algorithm

The outputs of BFS:

1. Distance array: $d[v]$
2. Predecessor array $pred[v]$

The BFS Forest:

- Use $pred[v]$ to define a graph $F = (V, E_f)$ as follows:

$$E_f = \{(pred[v], v) | v \in V, pred[v] \neq \text{NULL}\}$$

- This graph has no cycles (why?), and is therefore a forest, i.e. a collection of trees. We call it a BFS Forest.
- In each tree, $d[v]$ gives the shortest distance to the initial vertex of the tree.
- Following $pred[v]$ gives *a* shortest path to the initial vertex of the tree.

Running Time of BFS

On each vertex u, we spend time $T_u = O(1 + \text{degree}(u))$

The total running time is

$$\sum_{u \in V} T_u \leq \sum_{u \in V} (O(1 + \text{degree}(u))) = O(V + E)$$

Hence, the running of BFS on a graph with V vertices and E edges is $O(V + E)$

Applications:

1. Shortest paths in a graph
   - What if the graph is weighted?
2. Finding connected components