

Maximum Flow

Revision of November 7, 2016

Outline

- Introduction
 - Definitions
 - Multi-Source Multi-Sink
- The Ford-Fulkerson Method
 - Residual Networks
 - Augmenting Paths
 - The Max-Flow Min-Cut Theorem
 - The Edmonds-Karp algorithm
- Max Bipartite Matching
- Odds and Ends

Maximum Flow

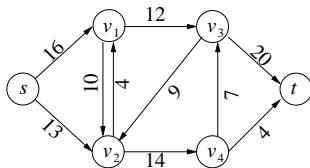
Main Reference: Sections 26.1-26.3 in CLRS.

- Input: a directed graph $G = (V, E)$:
(flow network)
- Source (producer) s and destination t .
- Internal Nodes are *warehouses*
- Edge costs are *capacities*
Maximum amount that can be shipped over edge
- No storage at internal nodes
All goods shipped into warehouse must leave warehouse

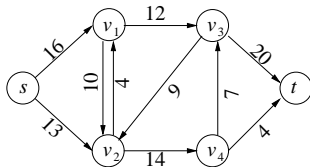
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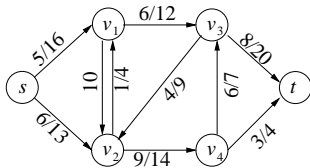
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- Internal Nodes are *warehouses*
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- **Objective:**
Ship Maximum amount (flow) from s to t .



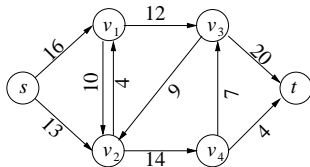
A Flow Network and its capacities



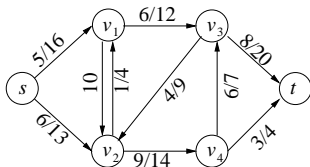
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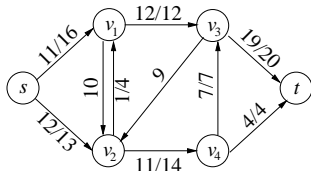
A flow: value 11



A Flow Network and its capacities



A flow: value 11



A max-flow: value = 23

Flow Definition: I

A flow network is a graph $G = (V, E)$.

Source $s \in V$, sink $t \in V$.

Every edge $(u, v) \in E$ has capacity , $c(u, v) \geq 0$.

Assume that for every $v \in V$,

there is a path from s to v and from v to t .

Flow Definition: II

A **FLOW** is a function $f : V \times V \rightarrow R$ satisfying:

- **Capacity Constraint:**

$$\forall u, v \in V, \quad f(u, v) \leq c(u, v).$$

- **Skew Symmetry:**

$$\forall u, v \in V, \quad f(u, v) = -f(v, u).$$

- **Flow Conservation:**

$$\forall u \in V - \{s, t\}, \quad \sum_{v \in V} f(u, v) = 0.$$

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MAXIMUM-FLOW PROBLEM:

Given G, c, s, t , find f that maximizes $|f|$.

Multi-Source Multi-Sink Problem

Max-Flow problem has **only one source s , and one sink t .**
Suppose there are
multiple sources s_1, s_2, \dots, s_k and multiple sinks t_1, t_2, \dots, t_ℓ .

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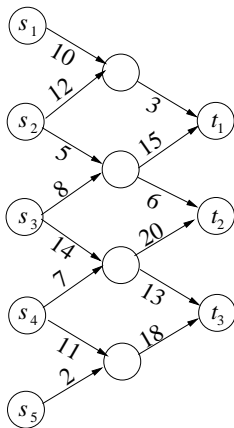
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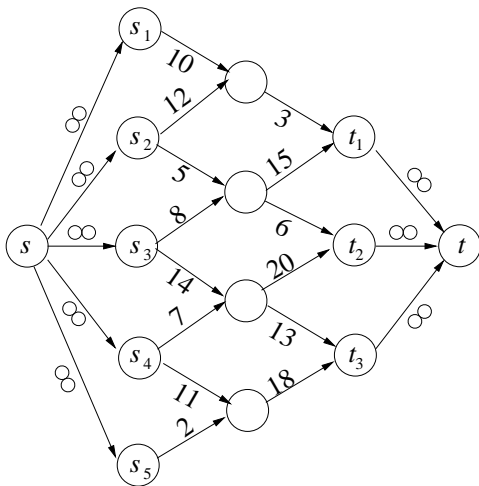
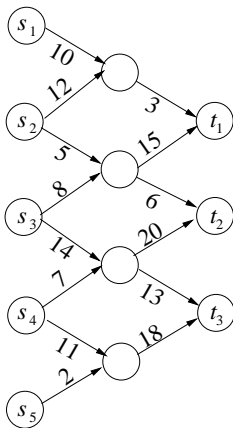
$$|f| = \sum_{i=1}^k \sum_{v \in V} f(s_i, v).$$

This problem can be reduced to the original one by introducing a **supersource** s_0 , a **supersink** t_0 and edges $\cup_i(s_0, s_i)$ and $\cup_j(t_j, t_0)$, all of which have capacity ∞ .

A multi-source multi-sink problem and its equivalent single-source single-sink version.



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Manipulating Flows

Let $X, Y \subseteq V$. We define

$$f(X, Y) = \sum_{x \in X} \sum_{y \in Y} f(x, y).$$

The *flow-conservation* constraint then just says

$$\forall u \in V - \{s, t\}, \quad f(u, V) = 0.$$

Lemma: (Proof in Homework)

$$\forall X \subseteq V, \quad f(X, X) = 0.$$

$$\forall X, Y \subseteq V, \quad f(X, Y) = -f(Y, X).$$

$$\begin{aligned} \forall X, Y, Z \subseteq V \text{ with } X \cap Y = \emptyset \\ f(X \cup Y, Z) = f(X, Z) + f(Y, Z) \quad \text{and} \\ f(Z, X \cup Y) = f(Z, X) + f(Z, Y) \end{aligned}$$

Flow f was defined as
amount that leaves source s .

We now see that this is the same as
amount that enters sink t .

$$\begin{aligned}|f| &= f(s, V) \\ &= f(V, V) - f(V - s, V) \\ &= -f(V - s, V) \\ &= f(V, V - s) \\ &= f(V, t) + f(V, V - s - t) \\ &= f(V, t)\end{aligned}$$

definition

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flow conservation

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 $V = S \cup T, \quad S \cap T = \emptyset, \quad s \in S, \text{ and } t \in T.$

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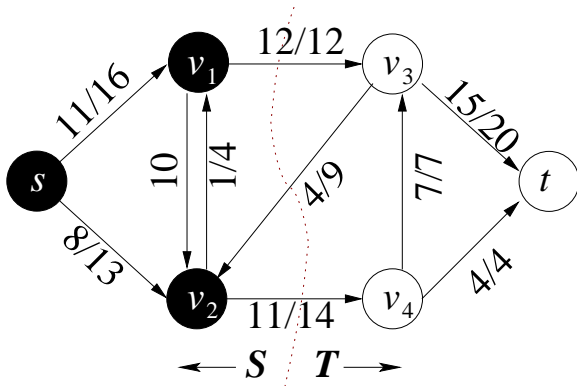
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The **flow across** the cut is $f(S, T)$.

The **capacity** of a cut is $C(S, T) = \sum_{x \in S, y \in T} c(x, y)$.

Note that for *any* cut, $f(S, T) \leq C(S, T)$.



Cut (S, T) : $S = \{s, v_1, v_2\}$, $T = \{v_3, v_4, t\}$.

The flow value is $|f| = 19$ and $C(S, T) = 26$.

Note that, in this example, $|f| < C(S, T)$.

Lemma:

If S, T is any cut, f any flow, then

$$|f| \leq C(S, T).$$

Proof:

$$\begin{aligned} |f| &= f(s, V) \\ &= f(s, V) + f(S - s, V) \\ &= f(S, V) \\ &= f(S, V) - f(S, S) \\ &= f(S, V - S) \\ &= f(S, T) \\ &\leq C(S, T) \end{aligned}$$

We now develop the **Ford-Fulkerson method** for finding max-flows. When FF terminates it provides a flow f and a cut S, T such that $|f| = C(S, T)$, so f is maximal.

The Ford-Fulkerson Method

- Is iterative.
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 - pushes f' units of flow along p .
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- S = set of nodes reachable from s in G_f & $T = V - S$.
- At end of algorithm: $|f| = C(S, T) \Rightarrow f$ is optimal

Residual networks

Given flow f , the residual network G_f consists of the edges along which we can (still) push more flow. The amount that can (still) be pushed across (u, v) is called the *residual capacity* $c_f(u, v)$.

$$c_f(u, v) = c(u, v) - f(u, v).$$

If there is flow from u to v then $f(u, v) > 0$ and $c_f(u, v)$ is the remaining capacity on (u, v) .

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If there is flow from v to u then $f(u, v) < 0$,
and $c_f(u, v) = c(u, v) + f(v, u)$ is the capacity of (u, v)
plus amount of existing flow that can be pushed
backwards from u to v .

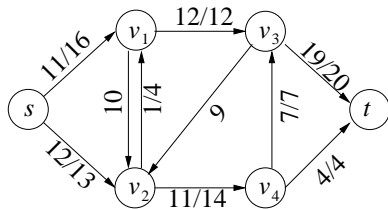
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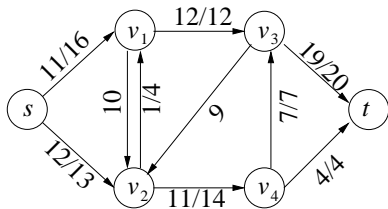
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The *Residual Network* G_f is $G_f = (V, E_f)$ where

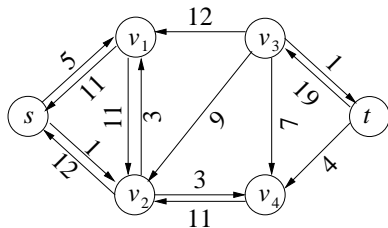
$$E_f = \{(u, v) \in V \times V : c_f(u, v) > 0\}$$



A Flow



A Flow



Its residual network

Lemma:

Let f be a flow in $G = (V, E)$ and G_f its residual network.

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Let f be a flow in $G = (V, E)$ and G_f its residual network. Let f' be a flow in G_f .

Define $f + f'$ as $(f + f')(u, v) = f(u, v) + f'(u, v)$.

Then $f + f'$ is a flow in G with value $|f + f'| = |f| + |f'|$.

Augmenting path p is a simple s - t path in G_f .

The **residual capacity** of a.p. p is

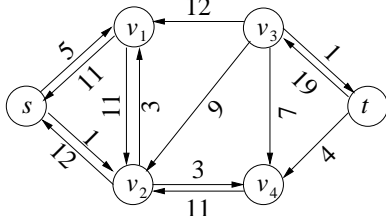
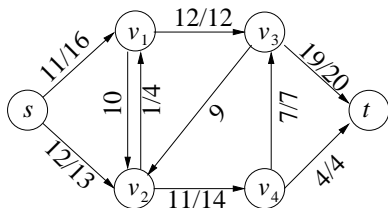
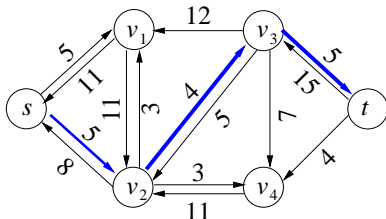
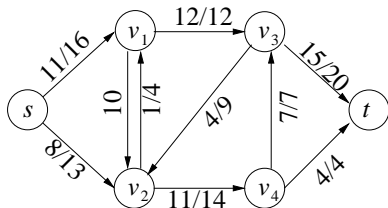
$$c_f(p) = \min\{c_f(u, v) : (u, v) \text{ on } p\}.$$

Let p be an augmenting path in G_f and define

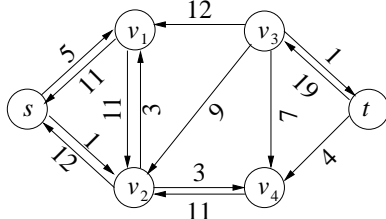
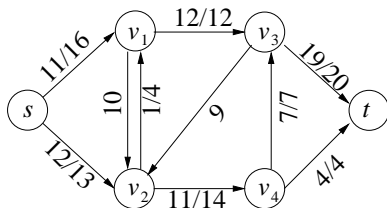
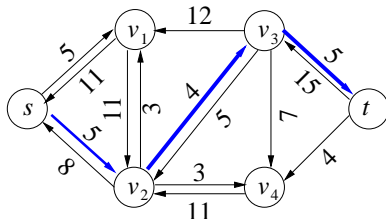
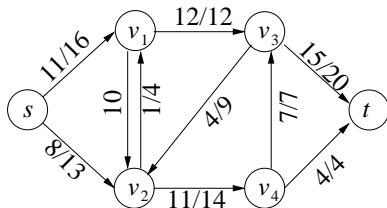
$$f_p(u, v) = \begin{cases} c_f(p) & \text{if } (u, v) \text{ is on } p \\ -c_f(p) & \text{if } (v, u) \text{ is on } p \\ 0 & \text{otherwise} \end{cases}$$

Lemma: If f is a flow and p an a.p. in G_f then:
 f_p is a flow in G_f with $|f_p| = c_f(p) > 0$.

$f' = f + f_p$ is a flow in G with $|f'| = |f| + |f_p| > |f|$.

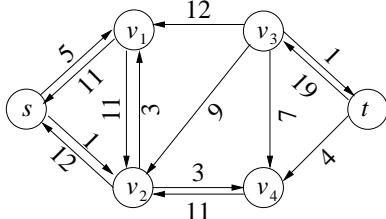
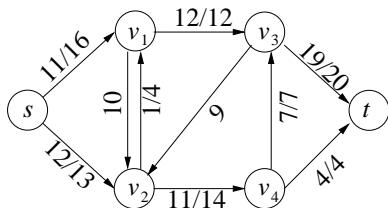
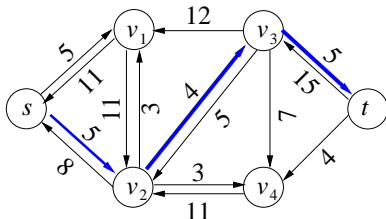
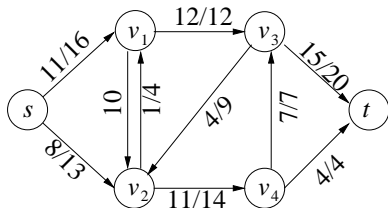


An initial flow f .



An initial flow f .

Its residual network G_f and an augmenting path f' in G_f .



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Its residual network G_f and an augmenting path f' in G_f .

The flow $f + f'$ and its residual network.

Optimality

Theorem: (Max-Flow Min-Cut Theorem)

Let f be a flow.

Then the following three conditions are equivalent:

- 1 f is a maximum flow in G .
- 2 G_f contains no augmenting paths
- 3 $|f| = C(S, T)$ for some (S, T) cut.

Proof:

- (1) \Rightarrow (2): If G_f contained an augmenting path p then $|f + f_p| > |f|$ so f could not be maximal.

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- (2) \Rightarrow (3): Let $S = \{u \in V : \exists \text{ path from } s \text{ to } u \text{ in } G_f\}$.
 $T = V - S$. Then

$$f(S, T) = f(S, V) - f(S, S) = f(S, V) = f(s, V) + f(S - s, V) = |f|.$$

Now note that $\forall u \in S, v \in T, f(u, v) = c(u, v)$ since otherwise $c_f(u, v) > 0$ and $v \in S$.

Thus $C(S, T) = f(S, T) = |f|$.

Proof:

- **(1) \Rightarrow (2):** If G_f contained an augmenting path p then $|f + f_p| > |f|$ so f could not be maximal.
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$$f(S, T) = f(S, V) - f(S, S) = f(S, V) = f(s, V) + f(S - s, V) = |f|.$$

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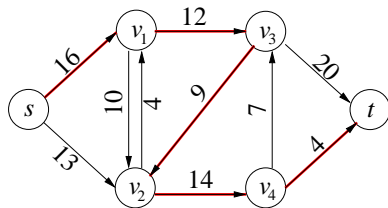
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- **(3) \Rightarrow (1):** We previously saw that every flow f' must satisfy $|f'| \leq C(S, T)$ so if $|f| = C(S, T)$, f must be optimal.

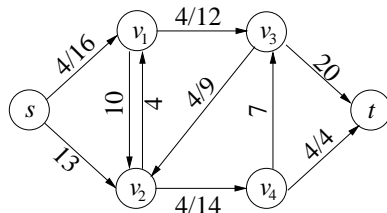
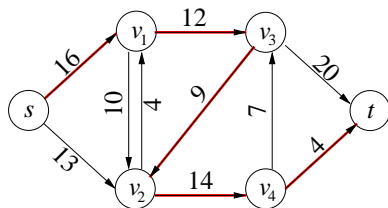
The Ford-Fulkerson Method

- Starts with flow $f \equiv 0$, ($\forall u, v, f(u, v) = 0$)
- Construct residual network G_f .
If G_f contains no augmenting path, stop
(f is optimal by MFMC theorem).
Otherwise.
 - 1 Find an **augmenting path** ($s - t$ path) p in G_f
 - 2 Let f_p be the flow in G_f that pushes $c_f(p)$ units of flow along p .
 - 3 Let $f = f + f_p$ be new flow in G .

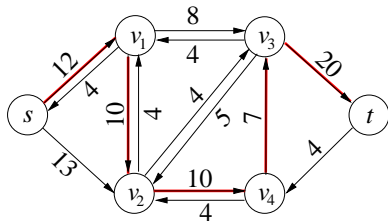
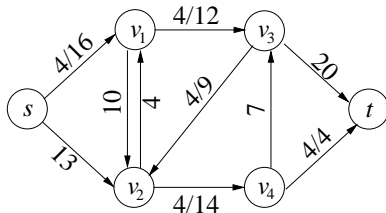
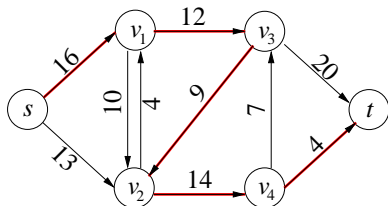
FF Example: Steps 1 & 2



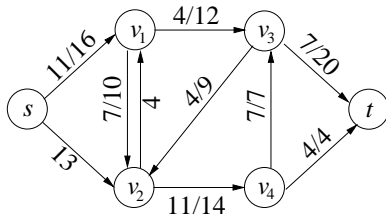
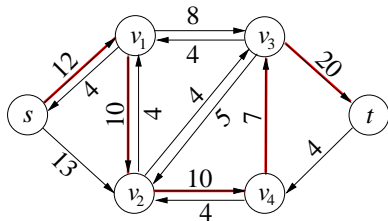
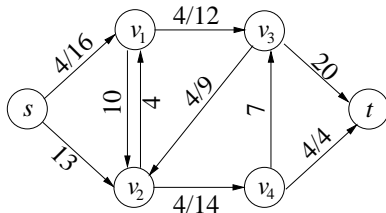
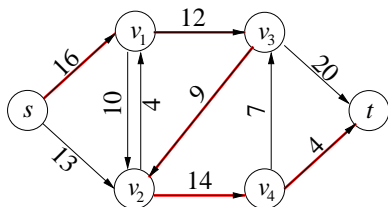
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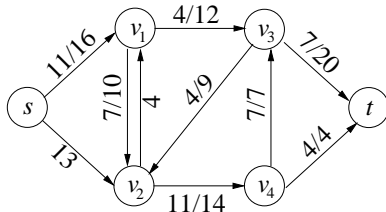
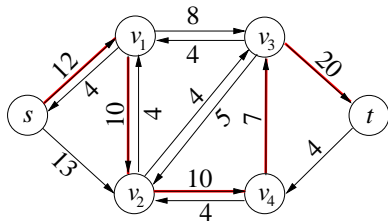
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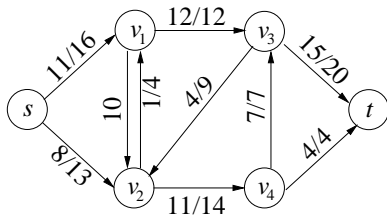
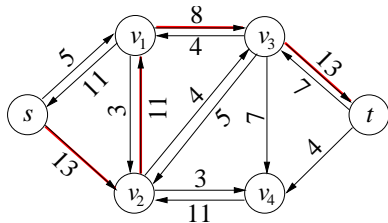
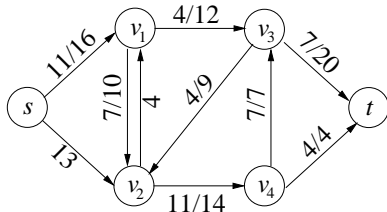
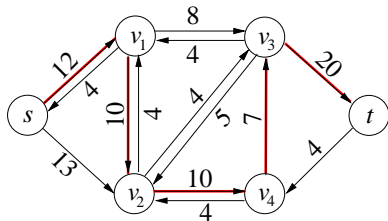
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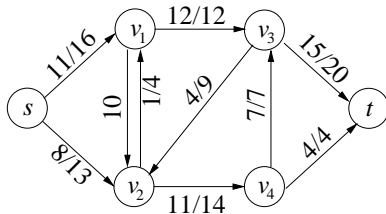
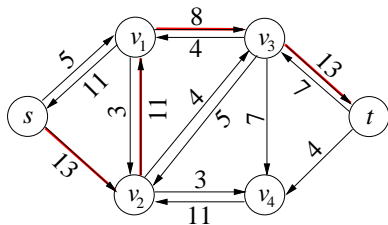
FF Example: Steps 2 & 3



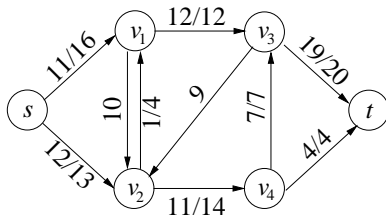
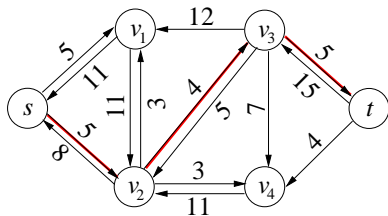
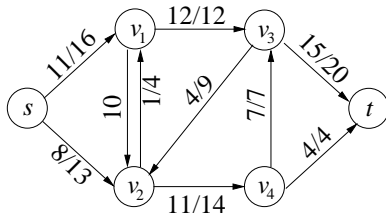
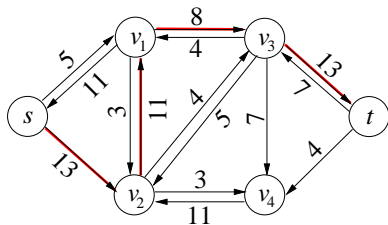
FF Example: Steps 2 & 3



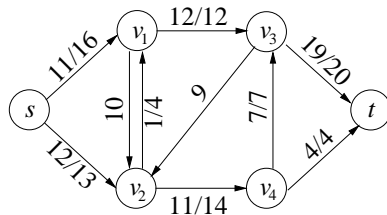
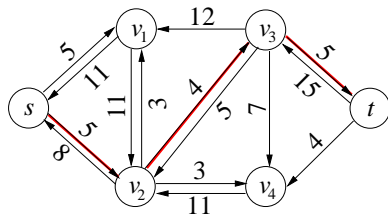
FF Example: Steps 3 & 4



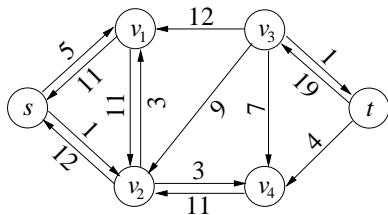
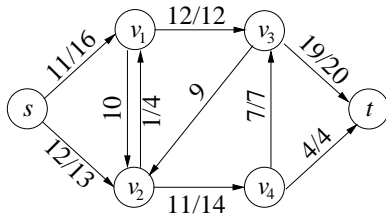
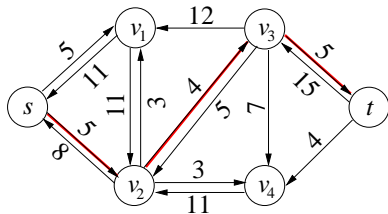
FF Example: Steps 3 & 4



FF Example: Steps 4 & 5 (End)



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Running Time & Finiteness

The FF method is not a completely defined algorithm since it doesn't specify how to *choose* the augmenting paths.

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In fact, if the capacities are irrational, it is possible that a “bad” way of choosing the a.p. will lead to a non-terminating algorithm that will never stop (it will keep on adding cheaper and cheaper augmenting paths).

If the capacities are all integers

⇒ then each c_p will be an integer ≥ 1

⇒ the algorithm must terminate after $|f^*|$ steps,
where f^* is a max-flow.

Maintaining the graphs G and G_f and the flow f using adjacency lists, while using DFS or BFS to find a s - t path, the algorithm can then be implemented to run in $O(|f^*||E|)$ time.

Note: This can be normalized to work if the capacities are rational.

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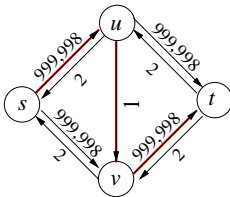
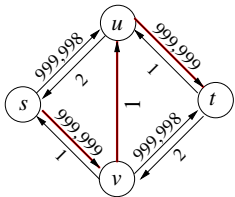
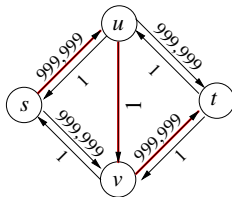
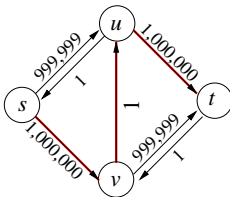
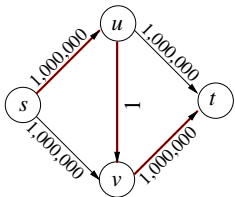
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A pathological example in which each augmenting path only increases flow value by 1 unit.



The Edmonds-Karp Algorithm

Always choose an augmenting path of minimum-length in G_f (where each edge has unit length). This can be done **in $O(E)$ time** using BFS.

Theorem: The EK alg performs at most **$O(VE)$** path-augmentations, so the E.K. alg runs in **$O(VE^2)$** time.

Let $\delta_f(u, v)$ denote shortest-path distance from u to v in G_f .

The proof of the Theorem is a consequence of the following two lemmas:

Lemma: $\forall v \in V - \{s, t\}$, $\delta_f(s, v)$ does not decrease after a flow augmentation.

Lemma:

Edge (u, v) is *critical* on a.p. p if $c_f(u, v) = c_f(p)$.

Suppose when running the E.K. algorithm that (u, v) is critical for a.p. p in G_f , and is later critical again for another a.p. p' in $G_{f'}$. Then

$$\delta_{f'}(s, u) \geq \delta_f(s, u) + 2.$$

Augmenting paths are simple and do not contain s, t internally, so $\delta_f(s, v)$ is always $\leq |V| - 2$ (as long as v is reachable). Combining the two lemmas therefore shows that no specific edge can become critical more than $(|V| - 2)/2 = O(|V|)$ times. *Some* edge is critical in each step, so there can be at most $O(|V||E|)$ steps.

Application: Max Bipartite Matching

A graph $G = (V, E)$ is *bipartite* if there exists partition $V = L \cup R$ with $L \cap R = \emptyset$ and $E \subseteq L \times R$.

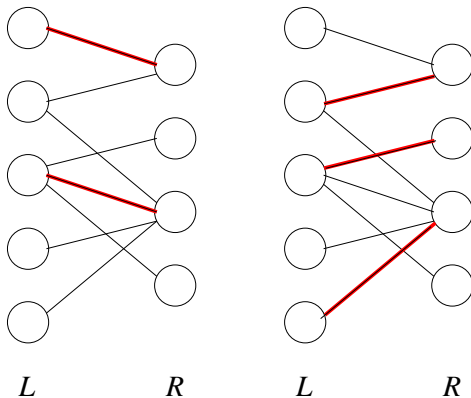
A *Matching* is a subset $M \subseteq E$ such that $\forall v \in V$ at most one edge in M is incident upon v .

The *size* of a matching is $|M|$, the number of edges in M .

A *Maximum Matching* is matching M such that every other matching M' satisfies $|M'| \leq |M|$.

Problem: Given bipartite graph G , find a maximum matching.

A bipartite graph with 2 matchings



Our approach will be to write the Max Bipartite Matching problem as a Max-Flow problem.

Our *flow network* will be $G' = (V', E')$ where

$V' = V \cup \{s, t\}$ and

$E' = \{(s, u) : u \in L\} \cup \{(u, v) : u \in L, v \in R \text{ and } (u, v) \in E\}$
 $\cup \{(v, t) : v \in R\}$

We also assign

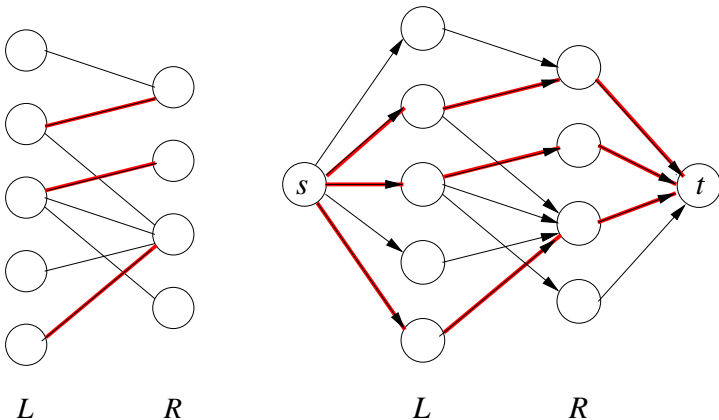
$\forall (u, v) \in E', c(u, v) = 1.$

Lemma: If f is an integer valued flow in G' then there is a matching M of G with $|f| = |M|$.
Similarly, if M is a matching of G then there is an integer valued flow f with $|f| = |M|$.

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This *almost* tells us that Max-Flow solves our problem. The difficulty is that it's possible that the max-flow might not have integer value (it is possible that $|f|$ might be an integer but some $f(u, v)$ might not be integers).

A bipartite graph and its associated flow network.
A matching and associated flow are illustrated



Theorem:

Let $G' = (V', E')$ be a flow network in which c is integral.
Then the max-flow f found by the F.F. method has the property that

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Then the max-flow f found by the F.F. method has the property that

$$\forall u, v, f(u, v) \text{ is integer valued.}$$

The proof is by induction on the steps in the FF method.

At each step the current flow f is integer so the residual capacities are all integer.

This implies that the a.p. found has $c_f(p)$ integral, so the new flow $f + f'$ created is also integral.

The theorem guarantees that if G' is the flow network corresponding to a bipartite matching problem then max flow value $|f|$ is the value of a maximum matching.

The flow found by the FF algorithm can be modified to yield the max matching.

The FF algorithm run on this special graph will take $O(VE)$ time (why?).

Odds and Ends

- A faster implementation of the FF method uses the idea of *blocking flows* developed by Dinic. This approach finds many augmenting paths at once.
- A totally different approach to the Max-Flow algorithm is the *push-relabel* method (see CLRS for details). This can run in $O(|V|^3)$ time as compared to the $O(|V||E|^2)$ of FF.
- General Culture: The max-flow problem can be written as a *linear program*. The FF method is essentially a special case of the *primal-dual* algorithm for solving combinatorial Linear Programs.