

The Fast Fourier Transform and Polynomial Multiplication

Version of November 5, 2014

Polynomial Multiplication

If $A(x) = \sum_{i=0}^{n-1} a_i x^i$, $B(x) = \sum_{i=0}^{n-1} b_i x^i$ then

$$C(x) = A(x)B(x) \quad \Leftrightarrow \quad C(x) = \sum_{i=0}^{2n-1} c_i x^i \quad \text{where} \quad c_i = \sum_{j=0}^i a_j b_{i-j}$$

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- sequence $\langle c_i \rangle$ is *convolution* of $\langle a_i \rangle$ and $\langle b_i \rangle$
- polynomial multiplication equivalent to calculating convolutions
- Straightforward multiplication alg is $\Theta(n^2)$
- Divide and conquer Karatsuba mult is $O(n^{\log_2 3})$

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This Lecture

- $O(n \log n)$ divide and conquer algorithm
- Uses Fast Fourier Transform (FFT)
- FFT calculates the Discrete Fourier Transform

Polynomial Evaluation & Interpolation

Coefficient Representation

- $A(x) = \sum_{i=0}^{n-1} a_i x^i$
- Evaluation of $A(x)$ for fixed x : $O(n)$ time
- Evaluation at n fixed values, x_0, x_1, \dots, x_{n-1} : $O(n^2)$ time

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Point Representation

- Polynomial of degree n uniquely represented by $n + 1$ values
 - e.g., 2 points determine a line; 3 points, a parabola
- Reconstructing coefficients of $A(x)$ from $n + 1$ values $A(x_1), A(x_2), \dots, A(x_n)$
requires $O(n^2)$ time using Lagrangian Interpolation

Review of Lagrangian Interpolation

To construct degree- n polynomial $A(x)$ from values $A(x_0), A(x_1), \dots, A(x_n)$

Set
$$I_i(x) = \prod_{0 \leq j \leq n, j \neq i} \frac{x - x_j}{x_i - x_j}$$

Review of Lagrangian Interpolation

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$$\text{Set } I_i(x) = \prod_{0 \leq j \leq n, j \neq i} \frac{x - x_j}{x_i - x_j} \quad \Rightarrow \quad I_i(x_j) = \begin{cases} 0 & \text{if } j \neq i \\ 1 & \text{if } j = i \end{cases}$$

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$$\text{Set } P(x) = \sum_i A(x_i) I_i(x). \quad \Rightarrow \quad P(x_i) = A(x_i) I_i(x_i) = A(x_i).$$

Review of Lagrangian Interpolation

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Since $P(x)$ has degree n (why?), $P(x)$ is the *unique* polynomial satisfying $P(x_i) = A(x_i)$ for all i , so $A(x) = P(x)$.

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Since $P(x)$ has degree n (why?), $P(x)$ is the *unique* polynomial satisfying $P(x_i) = A(x_i)$ for all i , so $A(x) = P(x)$.

Note: $P(x)$ can be constructed in $O(n^2)$ time.

A New Approach To Polynomial Multiplication

$x_0, x_1, \dots, x_{2n-1}$ are given values

$$A(x) : a_0, \dots, a_{n-1}$$

$$B(x) : b_0, \dots, b_{n-1}$$

A New Approach To Polynomial Multiplication

$x_0, x_1, \dots, x_{2n-1}$ are given values

$$\begin{array}{l} A(x) : a_0, \dots, a_{n-1} \\ B(x) : b_0, \dots, b_{n-1} \end{array}$$

Polynomial Multiplication/Convolution

$O(n^2)$

$$\begin{array}{l} C(x) : c_0, \dots, c_{2n-1} \\ C(x) = A(x)B(x) \end{array}$$

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Polynomial Multiplication/Convolution

$O(n^2)$

$$\begin{array}{l} C(x) : c_0, \dots, c_{2n-1} \\ C(x) = A(x)B(x) \end{array}$$

Evaluate
 $A(x_i), B(x_i)$
for all x_i

$O(n^2)$

$$\begin{array}{l} A(x_i), B(x_i) \\ 0 \leq i \leq 2n-1 \end{array}$$

Pointwise Multiplication: $C(x_i) = A(x_i)B(x_i)$

$O(n)$

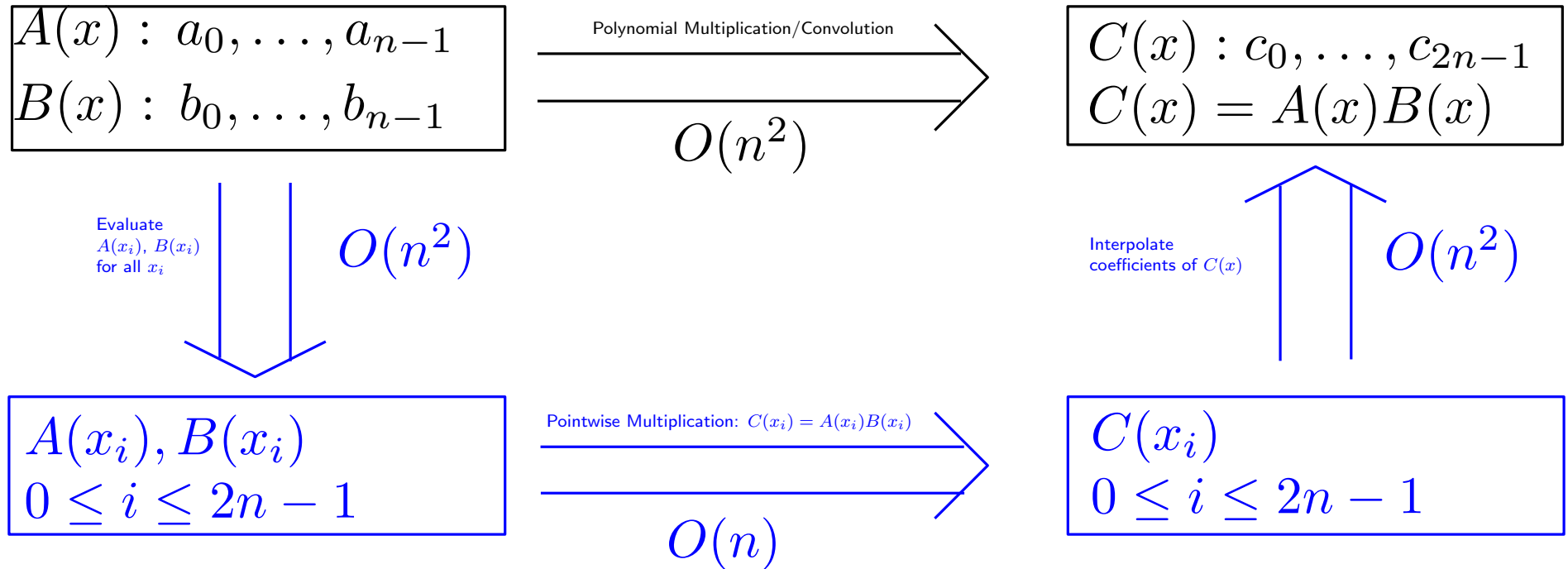
$$\begin{array}{l} C(x_i) \\ 0 \leq i \leq 2n-1 \end{array}$$

Interpolate
coefficients of $C(x)$

$O(n^2)$

A New Approach To Polynomial Multiplication

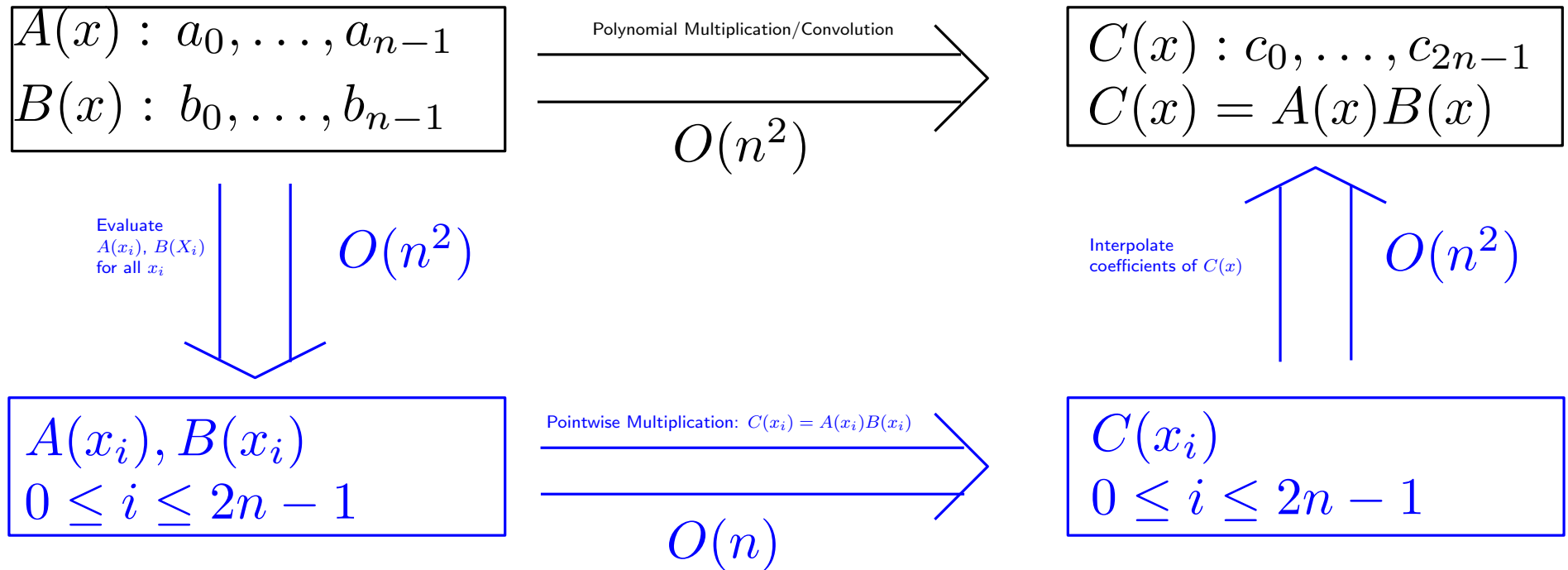
$x_0, x_1, \dots, x_{2n-1}$ are given values



- An alternative convolution method is to
 - (1) evaluate all values $A(x_i), B(x_i)$
 - (2) pointwise multiply to find $C(x_i) = A(x_i)B(x_i)$
 - (3) interpolate to find $C(x)$
- Since Evaluation and Interpolation require $O(n^2)$, new method still requires $O(n^2)$.

A New Approach To Polynomial Multiplication

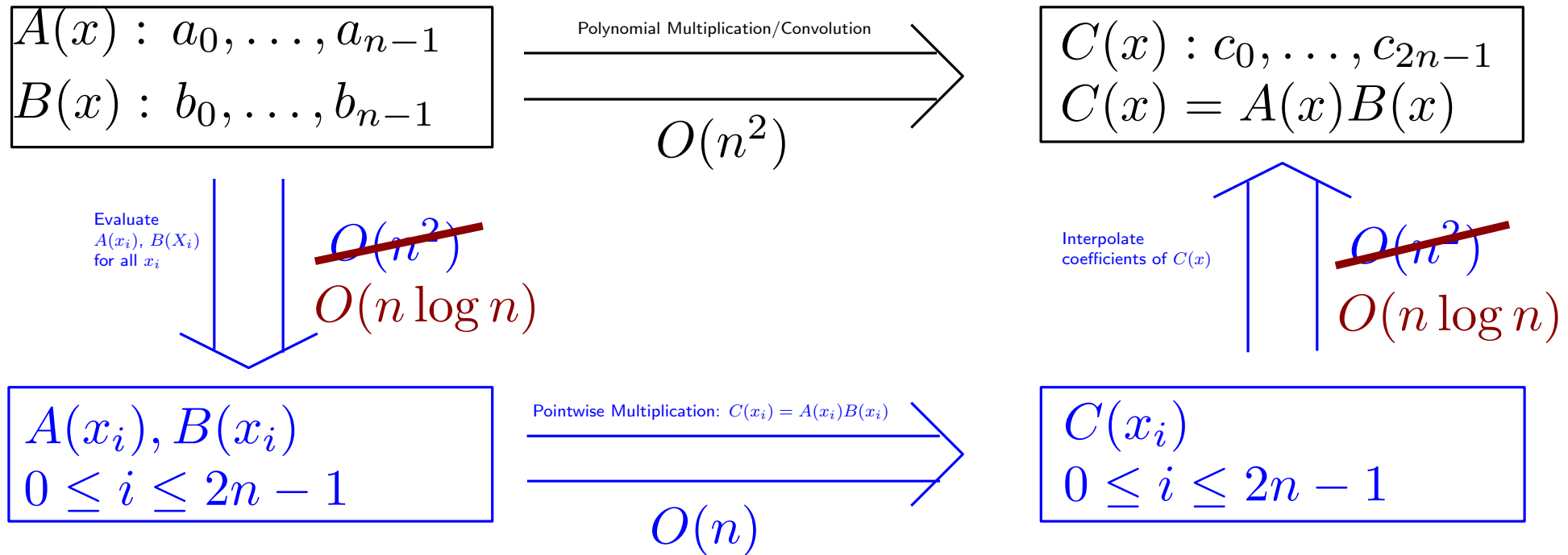
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- Assumption was that the x_i were arbitrary values
- If x_i are specified to be the (complex) roots of unity, FFT can evaluate and interpolate the values in $O(n \log n)$ time.

A New Approach To Polynomial Multiplication

$x_0, x_1, \dots, x_{2n-1}$ are given values



- Assumption was that the x_i were arbitrary values
- If x_i are specified to be the (complex) roots of unity, FFT can evaluate and interpolate the values in $O(n \log n)$ time.
- Resulting in an $O(n \log n)$ convolution algorithm!

Review of Complex Numbers & Roots of Unity

- $\mathbf{i} = \sqrt{-1}$
- $e^{\mathbf{i}x} = \cos x + \mathbf{i} \sin x$
- $w_n = e^{2\pi\mathbf{i}/n}$ is the n 'th principle root of unity; $w_n^n = 1$
- The n roots of unity are $w_n^0, w_n^1, w_n^2, \dots, w_n^{n-1}$
 w_n^i denotes $(w_n)^i$
- These n roots of unity are the n points, $e^{2j\pi\mathbf{i}/n}$, $j = 0, 1, \dots, n-1$, equally spaced around the circle

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If n is even

- If $i < n/2$ then

$$(w_n^i)^2 = w_n^{2i} = w_{n/2}^i \quad \text{and} \quad (w_n^{i+n/2})^2 = w_n^n w_n^{2i} = w_{n/2}^i$$

- $w_n^{n/2} = -1$

FFT Definition

FFT Definition

- Input: Coefficients a_0, a_1, \dots, a_{n-1}
- Output: Values $A(w_n^0), A(w_n^1), \dots, A(w_n^{n-1})$.
Output is called the *Discrete Fourier Transform* ($DFT_n(A)$)
of sequence $\langle a_i \rangle$
- Will denote algorithm by $FFT_n(A)$

Assumption

- n is a power of 2;
- if not, add zero coefficients, increasing size to power of 2

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Termination Condition

- If $n = 1$ then sequence has only one value a_0 and $FFT_n(A)$ just returns the value a_0 .

FFT Main Body

Want to evaluate $A(w_n^0), A(w_n^1), \dots, A(w_n^{n-1})$

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Split $A(x)$ into even and odd parts: $A(x) = A_0(x^2) + xA_1(x^2)$

$$A_0(x) = a_0 + a_2x + a_4x^2 + \dots \quad A_1(x) = a_1 + a_3x + a_5x^2 + \dots$$

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If $i < \frac{n}{2}$ then

$$\begin{aligned} A(w_n^i) &= A_0\left((w_n^i)^2\right) + w_n^i A_1\left((w_n^i)^2\right) \\ &= A_0\left(w_{n/2}^i\right) + w_n^i A_1\left(w_{n/2}^i\right) \end{aligned}$$

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$$\begin{aligned} A(w_n^{i+n/2}) &= A_0\left(\left(w_n^{i+n/2}\right)^2\right) - w_n^i A_1\left(\left(w_n^{i+n/2}\right)^2\right) \\ &= A_0\left(w_{n/2}^i\right) - w_n^i A_1\left(w_{n/2}^i\right) \end{aligned}$$

FFT Algorithm

Just saw that
when n even

*(always true since
 n a power of 2)*

$$A(w_n^i) = A_0(w_{n/2}^i) + w_n^i A_1(w_{n/2}^i)$$

$$A(w_n^{i+n/2}) = A_0(w_{n/2}^i) - w_n^i A_1(w_{n/2}^i)$$

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Note that $A_0(x), A_1(x)$ have degree $\frac{n}{2} - 1$ so can recursively call *FFT* to evaluate them on the $n/2$ roots of unity.

FFT Algorithm

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Note that $A_0(x), A_1(x)$ have degree $\frac{n}{2} - 1$ so can recursively call FFT to evaluate them on the $n/2$ roots of unity.

$FFT_n(A)$

If $n = 1$

return a_0

otherwise

Evaluate $FFT_{n/2}(A_0), FFT_{n/2}(A_1)$

Calculate $A(w_n^i)$ for all i using those precalculated values

FFT Algorithm

Just saw that
when n even

$$A(w_n^i) = A_0(w_{n/2}^i) + w_n^i A_1(w_{n/2}^i)$$

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 n a power of 2)

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Note that $A_0(x), A_1(x)$ have degree $\frac{n}{2} - 1$ so can recursively call FFT to evaluate them on the $n/2$ roots of unity.

$FFT_n(A)$ $T(n)$

If $n = 1$

return a_0

otherwise

Evaluate $FFT_{n/2}(A_0), FFT_{n/2}(A_1)$ $2T(n/2)$

Calculate $A(w_n^i)$ for all i using those precalculated values $O(n)$

Running Time: $T(n) = 2T(n/2) + O(n)$

FFT Algorithm

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$$A(w_n^i) = A_0(w_{n/2}^i) + w_n^i A_1(w_{n/2}^i)$$

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Note that $A_0(x), A_1(x)$ have degree $\frac{n}{2} - 1$ so can recursively call FFT to evaluate them on the $n/2$ roots of unity.

$FFT_n(A)$ $T(n)$

If $n = 1$

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Evaluate $FFT_{n/2}(A_0), FFT_{n/2}(A_1)$ $2T(n/2)$

Calculate $A(w_n^i)$ for all i using those precalculated values $O(n)$

Running Time: $T(n) = 2T(n/2) + O(n)$

$$\Rightarrow T(n) = O(n \log n)$$

FFT Based Interpolation

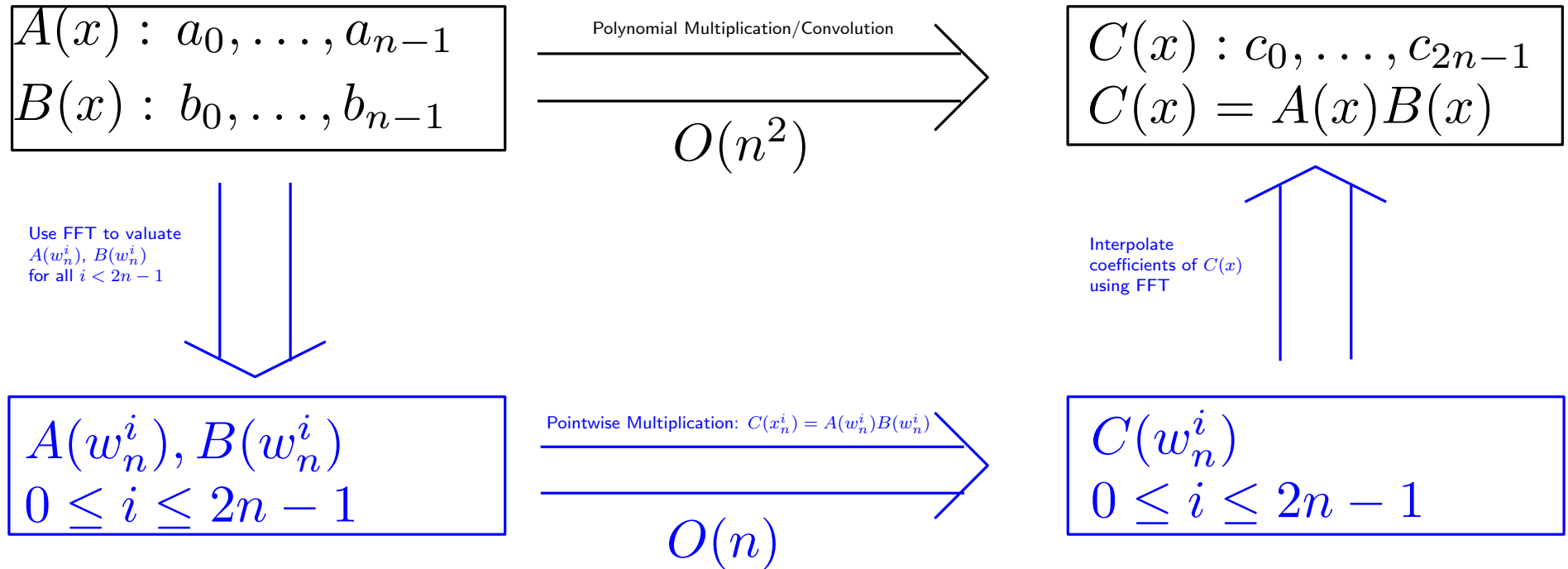
- Just saw that $FFT_n(A)$ evaluates $A(x)$ at n roots of unity in $O(n \log n)$ time
- Now need to see how to efficiently interpolate A 's coefficients given $DFT_n(A) = \{A(w_n^0), A(w_n^1), \dots, A(w_n^{n-1})\}$
- Amazingly, (proof soon)

Lemma: If $d_j = A(w_n^j)$ set $D(x) = \sum_j d_j x^j$. Then, for all $i < n$,

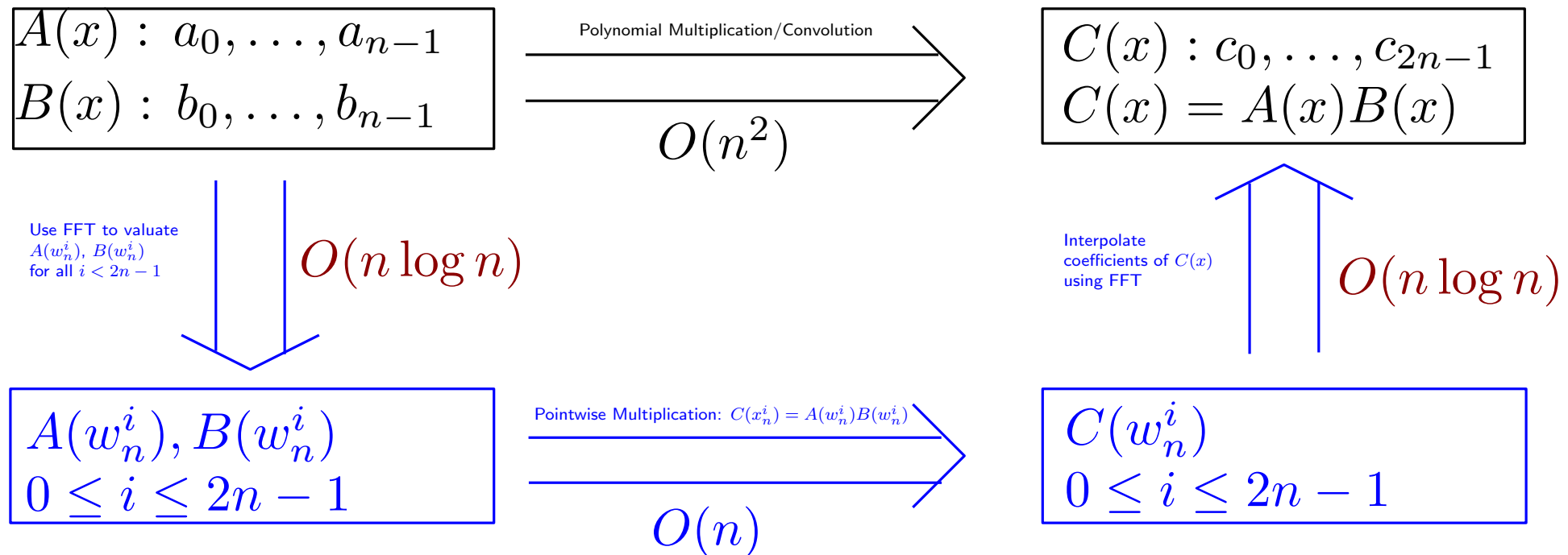
$$D(w_n^i) = \begin{cases} na_0 & \text{if } i = 0 \\ na_{n-i} & \text{if } i \neq 0 \end{cases}$$

- This says that given $DFT_n(A)$ we can calculate coefficients of A in $O(n \log n)$ time by another call to FFT and dividing answers by n .

A New Approach To Polynomial Multiplication



A New Approach To Polynomial Multiplication



- Following the blue arrows gives an $O(n \log n)$ polynomial multiplication algorithm!

Last Piece

Lemma: If $d_j = A(w_n^i)$ then, for all $i < n$,

$$D(w_n^i) = \begin{cases} na_0 & \text{if } i = 0 \\ na_{n-i} & \text{if } i \neq 0 \end{cases}$$

Proof:

Last Piece

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Proof:

First note

$$\sum_{j=0}^{n-1} (w_n^t)^j = \begin{cases} n & \text{if } t = 0, n \\ 0 & \text{if } t \neq 0, n \end{cases}$$

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If $t = 0, n$, $w_n^t = 1$ and obvious. If $t \neq 0, 1$, $\sum_{j=0}^{n-1} (w_n^t)^j = \frac{w_n^{nt} - 1}{w_n^t - 1} = 0$

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$$\begin{aligned} D(w_n^i) &= \sum_{j=0}^{n-1} d_j (w_n^i)^j \\ &= \sum_{j=0}^{n-1} \left(\sum_{k=0}^{n-1} a_k (w_n^j)^k \right) (w_n^i)^j \\ &= \sum_{k=0}^{n-1} a_k \left(\sum_{j=0}^{n-1} (w_n^{k+i})^j \right) \end{aligned}$$

Last Piece

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Odds and Ends

- Note that FFT presented here as divide-and-conquer algorithm
- Can also be written iteratively and also implemented in a dedicated circuit (butterfly pattern)
- Can design $O(n \log n)$ algorithms that work on powers of other numbers, e.g., $n = 3^k$ or $n = 5^k$.
- Some other transforms using other orthogonal function bases can be implemented quickly, similar to the FFT, e.g., Hadamard Transforms
- Gauss actually developed something similar to FFT in 1805. Rediscovered many times afterwards
- Was “forgotten” until Cooley and Tukey published a paper describing it in 1965.
After that, became one of the most used algorithms in the world!

A Matrix View of DFTs

$$\begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & w_n^1 & w_n^2 & \cdots & w_n^{n-1} \\ 1 & w_n^2 & w_n^4 & \cdots & w_n^{2(n-1)} \\ \vdots & \vdots & \cdots & \ddots & \vdots \\ 1 & w_n^{n-1} & w_n^{2(n-1)} & \cdots & w_n^{(n-1)(n-1)} \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} A(w_n^0) \\ A(w_n^1) \\ A(w_n^2) \\ \vdots \\ A(w_n^{n-1}) \end{pmatrix}$$

Let V be the Vandermonde matrix on the left and use A to denote the vector of the a_i .

The DFT can then be seen as calculating $VA = DFT(A)$.

A little bit of work (similar to lemma on slides) shows that the (j, k) -th entry of the inverse matrix of V has value w_n^{-kj}/n .

Using the fact that $w_n^{-k} = w_n^{n-k}$ we see that

The (j, k) -th entry of the inverse matrix of V has value w_n^{-kj} / n and $w_n^{-k} = w_n^{n-k}$ so

$$V = \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & w_n^1 & w_n^2 & \cdots & w_n^{n-1} \\ 1 & w_n^2 & w_n^4 & \cdots & w_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w_n^{n-1} & w_n^{2(n-1)} & \cdots & w_n^{(n-1)(n-1)} \end{pmatrix} \quad \text{and} \quad V^{-1} = \frac{1}{n} \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & w_n^{n-1} & w_n^{2(n-1)} & \cdots & w_n^{(n-1)(n-1)} \\ 1 & w_n^{n-2} & w_n^{2(n-2)} & \cdots & w_n^{(n-1)(n-2)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w_n^1 & w_n^2 & \cdots & w_n^{n-1} \end{pmatrix}$$

Since $V \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} A(w_n^0) \\ A(w_n^1) \\ A(w_n^2) \\ \vdots \\ A(w_n^{n-1}) \end{pmatrix},$ we have $V^{-1} \begin{pmatrix} A(w_n^0) \\ A(w_n^1) \\ A(w_n^2) \\ \vdots \\ A(w_n^{n-1}) \end{pmatrix} = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{pmatrix}$

This allows implementing the inverse DFT by multiplying by V^{-1} .

But, from the above, multiplying by V^{-1} is the same as multiplying by V , flipping some of the results and then dividing by n .

This can be done in $O(n \log n)$ by running the FFT algorithm and then doing $O(n)$ more work.

Definition: The *Vandermonde matrix* on n values x_1, x_2, \dots, x_n is the matrix below.

If $x_i \neq x_j$ for all i, j , the Vandermonde matrix is invertable.

$$\begin{pmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ 1 & x_3 & x_3^2 & \cdots & x_3^{n-1} \\ \vdots & \vdots & \cdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^{n-1} \end{pmatrix}$$