All-Pairs Shortest Paths

Version of November 5, 2014





Outline

- A third example of dynamic programming
- Will see two different dynamic programming formulations for same problem.

Outline

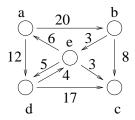
- The all-pairs shortest path problem.
- A first dynamic programming solution.
- The Floyd-Warshall algorithm
- Extracting shortest paths.

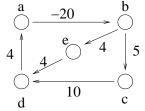
The All-Pairs Shortest Paths Problem

Input: weighted digraph G=(V,E) with weight function $w:E \to \mathbb{R}$

Find: lengths of the shortest paths (i.e., distance) between all pairs of vertices in G.

we assume that there are no cycles with zero or negative cost.





without negative cost cycle with negative cost cycle

Solution 1: Using Dijkstra's Algorithm

- Where there are no negative cost edges.
 - Apply Dijkstra's algorithm *n* times, once with each vertex (as the source) of the shortest path tree.
 - Recall that Dijkstra algorithm runs in $\Theta(e \log n)$
 - n = |V| and e = |E|.
 - This gives a $\Theta(ne \log n)$ time algorithm
 - If the digraph is dense, this is a $\Theta(n^3 \log n)$ algorithm.
- When negative-weight edges are present:
 - Run the Bellman-Ford algorithm from each vertex.
 - $O(n^2e)$, which is $O(n^4)$ for dense graphs.
 - We don't learn Bellman-Ford in this class.

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Input and Output Formats

Input Format:

- To simplify the notation, we assume that $V = \{1, 2, ..., n\}$.
- Adjacency matrix: graph is represented by an n × n matrix containing edge weights

$$w_{ij} = \begin{cases} 0 & \text{if } i = j, \\ w(i,j) & \text{if } i \neq j \text{ and } (i,j) \in E, \\ \infty & \text{if } i \neq j \text{ and } (i,j) \notin E. \end{cases}$$

Output Format: an $n \times n$ matrix $D = [d_{ij}]$ in which d_{ij} is the length of the shortest path from vertex i to j.

Step 1: Space of Subproblems

For $m = 1, 2, 3 \dots$

- Define $d_{ij}^{(m)}$ to be the length of the shortest path from i to j that contains at most m edges.
- Let $D^{(m)}$ be the $n \times n$ matrix $[d_{ij}^{(m)}]$.

We will see (next page) that solution D satisfies $D = D^{n-1}$.

Subproblems: (Iteratively) compute $D^{(m)}$ for m = 1, ..., n - 1.

Step 1: Space of Subproblems

Lemma

```
D_{ij}^{(n-1)} = D, i.e.
d_{ij}^{(n-1)} = true distance from i to j
```

Proof.

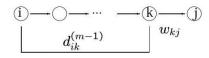
We prove that any shortest path P from i to j contains at most n-1 edges.

First note that since all cycles have positive weight, a shortest path can have no cycles (if there were a cycle, we could remove it and lower the length of the path).

A path without cycles can have length at most n-1 (since a longer path must contain some vertex twice, that is, contain a cycle). \Box

Step 2: Building $D^{(m)}$ from $D^{(m-1)}$.

Consider a shortest path from i to j that contains at most m edges.



Let k be the vertex immediately before j on the shortest path (k could be i).

The sub-path from i to k must be the shortest1-k path with at most m-1 edges. Then $\dfrac{d_{ij}^{(m)}=d_{ik}^{(m-1)}+w_{kj}}{d_{ik}^{(m)}}$.

Since we don't know k, we try all possible choices: $1 \le k \le n$.

$$d_{ij}^{(m)} = \min_{1 \le k \le n} \left\{ d_{ik}^{(m-1)} + w_{kj} \right\}$$

Step 3: Bottom-up Computation of $D^{(n-1)}$

- Initialization: $D^{(1)} = [w_{ij}]$, the weight matrix.
- Iteration step: Compute $D^{(m)}$ from $D^{(m-1)}$, for m=2,...,n-1, using

$$d_{ij}^{(m)} = \min_{1 \le k \le n} \left\{ d_{ik}^{(m-1)} + w_{kj} \right\}$$

Example: Bottom-up Computation of $D^{(n-1)}$

$$D^{(1)} = [w_{ij}]$$
 is just the weight matrix:

$$D^{(1)} = \begin{bmatrix} 0 & 3 & 8 & \infty \\ \infty & 0 & 4 & 11 \\ \infty & \infty & 0 & 7 \\ 4 & \infty & \infty & 0 \end{bmatrix}$$

$$d_{ij}^{(2)} = \min_{1 \le k \le 4} \left\{ d_{ik}^{(1)} + w_{kj} \right\}$$

$$D^{(2)} = \begin{bmatrix} 0 & 3 & 7 & 14 \\ 15 & 0 & 4 & 11 \\ 11 & \infty & 0 & 7 \\ 4 & 7 & 12 & 0 \end{bmatrix}$$

$$d_{ij}^{(3)} = \min_{1 \le k \le 4} \left\{ d_{ik}^{(2)} + w_{kj} \right\}$$

$$D^{(3)} = \begin{bmatrix} 0 & 3 & 7 & 14 \\ 15 & 0 & 4 & 11 \\ 11 & 14 & 0 & 7 \\ 4 & 7 & 11 & 0 \end{bmatrix}$$

 $D^{(3)}$ gives the distances between any pair of vertices.

$$d_{ij}^{(m)} = \min_{1 \le k \le n} \left\{ d_{ik}^{(m-1)} + w_{kj} \right\}$$

```
for m = 1 to n - 1 do
    for i = 1 to n do
        for j = 1 to n do
            min = \infty;
            for k = 1 to n do
               new = d_{ik}^{(m-1)} + w_{kj};
                if new < min then
                min = new
                end
            end
           d_{ii}^{(m)} = min;
        end
    end
end
```

Notes

Running time $O(n^4)$, much worse than the solution using Dijkstra's algorithm.

Question

Can we improve this?

Repeated Squaring

We use the recurrence relation:

- Initialization: $D^{(1)} = [w_{ij}]$, the weight matrix.
- For $s \ge 1$ compute $D^{(2s)}$ using

$$d_{ij}^{(2s)} = \min_{1 \le k \le n} \left\{ d_{ik}^{(s)} + d_{kj}^{(s)} \right\}$$

- From equation, can calculate $D^{(2^i)}$ from $D^{(2^{i-1})}$ in $O(n^3)$ time.
- have shown earlier that the shortest path between any two vertices contains no more than n-1 edges. So

$$D^i = D^{(n-1)}$$
 for all $i \ge n$.

We can therefore calculate all of

$$D^{(2)}, D^{(4)}, D^{(8)}, \dots, D^{(2^{\lceil \log_2 n \rceil})} = D^{(n-1)}$$

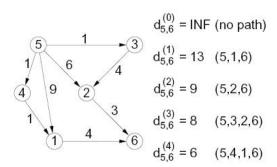
in $O(n^3 \log n)$ time, improving our running time.

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- Extracting shortest paths.

Step 1: Space of subproblems

- The vertices $v_2, v_3, ..., v_{l-1}$ are called the intermediate vertices of the path $p = \langle v_1, v_2, ..., v_{l-1}, v_l \rangle$.
- For any k=0, 1, ..., n, let $d_{ij}^{(k)}$ be the length of the shortest path from i to j such that all intermediate vertices on the path (if any) are in the set $\{1, 2, ..., k\}$.



Step 1: Space of subproblems

- $d_{ij}^{(k)}$ is the length of the shortest path from i to j such that all intermediate vertices on the path (if any) are in the set $\{1, 2, \ldots, k\}$.
- Let $D^{(k)}$ be the $n \times n$ matrix $[d_{ij}^{(k)}]$.
- Subproblems: compute $D^{(k)}$ for $k = 0, 1, \dots, n$.
- Original Problem: $D = D^{(n)}$, i.e. $d_{ij}^{(n)}$ is the shortest distance from i to j

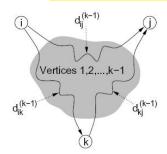
Step 2: Relating Subproblems

Observation : For a shortest path from i to j with intermediate vertices from the set $\{1, 2, ..., k\}$, there are two possibilities:

- k is not a vertex on the path: $d_{ij}^{(k)} = d_{ij}^{(k-1)}$
- ② k is a vertex on the path.: $d_{ij}^{(k)} = d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$

(Impossible for k to appear in path twice. Why?) So:

$$d_{ij}^{(k)} = \min \left\{ d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right\}$$



Step 2: Relating Subproblems

Proof.

- Consider a shortest path from i to j with intermediate vertices from the set $\{1, 2, ..., k\}$. Either it contains vertex k or it does not.
- If it does not contain vertex k, then its length must be $d_{ij}^{(k-1)}$.
- Otherwise, it contains vertex k, and we can decompose it into a subpath from i to k and a subpath from k to j.
- Each subpath can only contain intermediate vertices in $\{1,...,k-1\}$, and must be as short as possible. Hence they have lengths $d_{ik}^{(k-1)}$ and $d_{kj}^{(k-1)}$.
- Hence the shortest path from i to j has length $\min\left\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\right\}$.



Step 3: Bottom-up Computation

- Initialization: $D^{(0)} = [w_{ij}]$, the weight matrix.
- Compute $D^{(k)}$ from $D^{(k-1)}$ using

$$d_{ij}^{(k)} = \min\left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\right)$$

for k = 1, ..., n.

The Floyd-Warshall Algorithm: Version 1

```
Floyd-Warshall(w, n): d_{ij}^{(k)} = \min \left( d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right)
```

```
for i = 1 to n do
    for i = 1 to n do
         d^{(0)}[i,j] = w[i,j]; pred[i,j] = nil; // initialize
    end
end
// dynamic programming
for k = 1 to n do
    for i = 1 to n do
         for i = 1 to n do
              if \left(d^{(k-1)}[i,k] + d^{(k-1)}[k,j] < d^{(k-1)}[i,j]\right) then
               d^{(k)}[i,j] = d^{(k-1)}[i,k] + d^{(k-1)}[k,j];
                 pred[i, j] = k;
              else
              end
             d^{(k)}[i,j] = d^{(k-1)}[i,j];
         end
    end
```

Comments on the Floyd-Warshall Algorithm

- The algorithm's running time is clearly $\Theta(n^3)$.
- The predecessor pointer pred[i, j] can be used to extract the shortest paths (see later).

Problem: the algorithm uses $\Theta(n^3)$ space.

- It is possible to reduce this to $\Theta(n^2)$ space by keeping only one matrix instead of n.
- Algorithm is on next page. Convince yourself that it works.

The Floyd-Warshall Algorithm: Version 2

$$d_{ij}^{(k)} = \min\left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\right)$$

Floyd-Warshall(w, n)

```
for i = 1 to n do
   for j = 1 to n do
    d[i,j] = w[i,j]; pred[i,j] = nil; // initialize
    end
end
// dynamic programming
for k = 1 to n do
    for i = 1 to n do
        for i = 1 to n do
            if (d[i, k] + d[k, j] < d[i, j]) then
            d[i,j] = d[i,k] + d[k,j];
             pred[i,j] = k;
        end
    end
end
return d[1..n, 1..n];
```

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Extracting the Shortest Paths

predecessor pointers pred[i, j] can be used to extract the shortest paths.

Idea:

- Whenever we discover that the shortest path from i to j passes through an intermediate vertex k, we set pred[i,j] = k.
- If the shortest path does not pass through any intermediate vertex, then pred[i,j] = nil.
- To find the shortest path from i to j, we consult pred[i, j].
 - If it is nil, then the shortest path is just the edge (i,j).
 - ② Otherwise, we recursively construct the shortest path from i to pred[i,j] and the shortest path from pred[i,j] to j.

The Algorithm for Extracting the Shortest Paths

Path(i,j)

```
if pred[i,j] = nil then
    // single edge
    output (i,j);
else
    // compute the two parts of the path
    Path(i, pred[i,j]);
    Path( pred[i,j],j);
end
```

Example of Extracting the Shortest Paths

Find the shortest path from vertex 2 to vertex 3.

```
2..3 Path(2,3) pred[2,3] = 6

2..6..3 Path(2,6) pred[2,6] = 5

2..5..6..3 Path(2,5) pred[2,5] = nil Output(2,5)

25..6..3 Path(5,6) pred[5,6] = nil Output(5,6)

256..3 Path(6,3) pred[6,3] = 4

256..4..3 Path(6,4) pred[6,4] = nil Output(6,4)

2564..3 Path(4,3) pred[4,3] = nil Output(4,3)
```