EECS 370 - Lecture 6 Function Calls



Announcements

- Project 1a due tonight
- Project 1s+m due next Thursday
- HW 1 Posted
 - Due Monday 9/22
- Let us know about exam conflicts in the next week
 - Form on Ed



- Two varieties of conditional branches
 - 1. One type compares a register to see if it is equal to zero.
 - 2. Another type checks the condition codes set in the status register.

	compare and branch on equal 0	CBZ X1, 25	if (X1 == 0) go to PC + 100	Equal 0 test; PC-relative branch	
Conditional branch	compare and branch on not equal 0	CBNZ X1, 25	if (X1 != 0) go to PC + 100	Not equal 0 test; PC-relative branch	
	branch conditionally	B.cond 25	if (condition true) go to PC + 100	Test condition codes; if true, branch	

- Let's look at the first type: CBZ and CBNZ
 - CBZ: Conditional Branch if Zero
 - CBNZ: Conditional Branch if Not Zero



- CBZ/CBNZ: test a register against zero and branch to a PC relative address
 - The relative address is a 19 bit signed integer—the number of instructions.
 Recall instructions are 32 bits of 4 bytes

compare and branch on equal 0	CBZ X1, 25	if (X1 == 0) go to PC + 100	Equal 0 test; PC-relative branch	
 compare and branch on not equal 0	CBNZ X1, 25	if (X1 != 0) go to PC + 100	Not equal 0 test; PC-relative branch	
branch conditionally	B.cond Z5	IT (condition true) go to PC + 100	Test condition codes; if true, branch	

- Example: CBNZ X3, Again
 - If X3 doesn't equal 0, then branch to label "Again"
 - "Again" is an offset from the PC of the current instruction (CBNZ)
 - Why does "25" in the above table result in PC + 100?



• Example: What would the offset or displacement be if there were two instructions between ADDI and CBNZ?

```
Again: ADDI X3, X3, #-1
```

CBNZ X3, Again

What's the offset?

- a) -16
- b) -12
- c) -4
- d) -3
- e) 0



 Example: What would the offset or displacement be if there were two instructions between ADDI and CBNZ?

```
Again: ADDI X3, X3, #-1
------
CBNZ X3, Again
```

- Answer = -3
 - The offset field is 19 bits signed so the bit pattern would be 111 1111 1111 1111
 - Two 00's are appended to the above 19 bits and then the result would be sign-extended (with one's) to 64 bits and added to the value of PC at CBNZ
 - Why the two 00's?



- Motivation:
 - Some types of branches makes sense to check if a certain value is zero or not
 - while(a)
 - But not all:
 - if(a > b)
 - if(a == b)
 - Using an extra program status register to check for various conditions allows for a greater breadth of branching behavior



LEGv8 Conditional Instructions Using FLAGS

- FLAGS: NZVC record the results of (arithmetic) operations
 Negative, Zero, oVerflow, Carry—not present in LC2K
- We explicitly set them using the "set" modification to ADD/SUB etc.
- Example: ADDS causes the 4 flag bits to be set according as the outcome is negative, zero, overflows, or generates a carry

Category I	nstructionExample		Meaning	Comments
	add	ADD X1, X2, X3	X1 = X2 + X3	Three register operands
	subtract	SUB X1, X2, X3	X1 = X2 - X3	Three register operands
	add immediate	ADDI X1, X2, 20	X1 = X2 + 20	Used to add constants
	subtract immediate	SUBI X1, X2, 20	X1 = X2 - 20	Used to subtract constants
	add and set flags	ADDS X1, X2, X3	X1 = X2 + X3	Add, set condition codes
Arithmetic	subtract and set flags	SUBS X1, X2, X3	X1 = X2 - X3	Subtract, set condition codes
	add immediate and set flags	ADDIS X1, X2, 20	X1 = X2 + 20	Add constant, set condition codes
	subtract immediate and set flags	SUBIS X1, X2, 20	X1 = X2 - 20	Subtract constant, set condition codes



ARM Condition Codes Determine Direction of Branch

- In LEGv8 only ADDS / SUBS / ADDIS / SUBIS / CMP / CMPI set the condition codes FLAGs or condition codes in PSR—the program status register
- Four primary condition codes evaluated:
 - N set if the result is negative (i.e., bit 63 is non-zero)
 - Z set if the result is zero (i.e., all 64 bits are zero)
 - C set if last addition/subtraction had a carry/borrow out of bit 63
 - V set if the last addition/subtraction produced an overflow (e.g., two negative numbers added together produce a positive result)
- Don't worry about the C and V for this class



ARM Condition Codes Determine Direction of Branch--continued

	Encoding	Name (& alias)	Meaning (integer)	Flags	
	0000	EQ	Equal	Z==1	
	0001	NE	Not equal	Z==0	
	0010	HS (CS)	Unsigned higher or same (Carry set)	C==1	
	0011	LO (CC)	Unsigned lower (Carry clear)	C==0	
	0100	MI	Minus (negative)	N==1	
	0101	PL	Plus (positive or zero)	N==0	
	0110	VS	Overflow set	V==1	
	0111	VC	Overflow clear	V==0	
	1000	HI	Unsigned higher	C==1 && Z==0	
ĺ	1001	LS	Unsigned lower or same	!(C==1 && Z==0)	
	1010	GE	Signed greater than or equal	N==V	
	1011	LT	Signed less than	N!=V	
	1100	GT	Signed greater than	Z==0 && N==V	
	1101	LE	Signed less than or equal ! (Z==0 &&		
	1110	AL	Always	Anar	
	1111	NV^{\dagger}	- Always	Any	

Need to know the 7 with the red arrows

> CMP X1, X2 B.LE Label1

For this example, we branch if X1 is <= to X2



Conditional Branches: How to use

- CMP instruction lets you compare two registers.
 - Could also use SUBS etc.
 - That could save you an instruction.
- B.cond lets you branch based on that comparison.
- Example:

```
CMP X1, X2
B.GT Label1
```

• Branches to Label1 if X1 is greater than X2.



Agenda

- Memory alignment
 - Aligning Structs
- Control flow instructions
 - C-code examples
- Extra Problems



Branch—Example

Convert the following C code into LEGv8 assembly (assume x is in X1, y in X2):

```
int x, y;
if (x == y)
   x++;
else
   y++;
// ...
```



Branch—Example

Convert the following C code into LEGv8 assembly (assume x is in X1,

Note that

y in X2):

```
int x, y;
if (x == y)
   x++;
else
   y++;
// ...
```

```
Using Labels

CMP X1, X2

B.NE L1

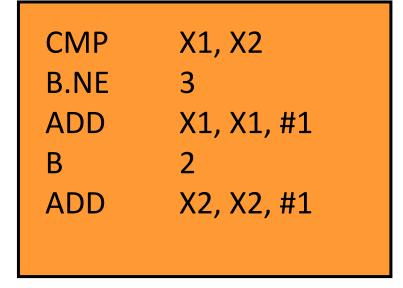
ADD X1, X1, #1

B L2

L1: ADD X2, X2, #1

L2: ...
```

Without Labels



Assemblers must deal with labels and assign displacements



Loop—Example

// assume all variables are long long integers (64 bits or 8 bytes)
// i is in X1, start of a is at address 100, sum is in X2

```
sum = 0;
for (i=0 ; i < 10 ; i++) {
   if (a[i] >= 0) {
      sum += a[i];
   }
}

# of branch instructions
= 3*10 + 1= 31
a.k.a. while-do template
```

```
MOV
                      X1, XZR
                      X2, XZR
           MOV
Loop1:
           CMPI
                      X1, #10
           B.EQ
                      endLoop
           LSL
                     X6, X1, #3
                     X5, [X6, #100]
           LDUR
           CMPI
                     X5, #0
           B.LT
                     endif
           ADD
                     X2, X2, X5
endif:
           ADDI
                     X1, X1, #1
           В
                      Loop1
endLoop:
```



Instruction Set Architecture (ISA) Design Lectures

- Lecture 2: ISA storage types, binary and addressing modes
- Lecture 3: LC2K
- Lecture 4: ARM
- Lecture 5 : Converting C to assembly basic blocks
- Lecture 6 : Converting C to assembly functions
- Lecture 7: Translation software; libraries, memory layout



Agenda

- Branching far away
- Function calls and the call stack
- Assigning variables to memory locations
- Saving registers
- Caller/callee example



Branching far away

- Underlying philosophy of ISA design: make the common case fast
- Most branches target nearby instructions
 - Displacement of 19 bits is usually enough
- BUT what if we need to branch really far away (more than 2¹⁹ words)?
 CBZ X15, FarLabel
- The assembler is smart enough to replace that with

```
CBNZ X15, L1
B FarLabel
L1:
```

- The simple branch instruction (B) has a 26 bit offset which spans about 64 million instructions!
- In LC2K, we can do a similar thing by using JALR instead of BEQ



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Implementing Functions

Poll: What's wrong with this?

Does this assembly code do what we need?

```
int mult_2(int x) {
  int temp = x*2;
  return temp;
}

int GLOBAL = 6;

int main() {
  int result = mult_2(GLOBAL+1);
  printf(result);
}
```

```
LDURSW X1, [XZR, GLOBAL]
       ADD X2, X1, #1
                             // Inc GLOBAL
      STURW X2, [XZR, X] // Pass arg
                             // Execute func
             MULT 2
RETURN:
       LDURSW X3, [XZR, TEMP] // load result
       STURW X3, [XZR, STRING] // Pass arg
       B PRINTF
                             // Execute func
MULT_2:
       LDURSW X1, [XZR, X] // load arg
      ADD X2, X1, X1 // mult by 2
       STURW X2, [XZR, TEMP]
                             // return result
       B RETURN
                                return
```



Problem 1: Returning from Functions

Branches so far have hard-coded destination

```
B.NE L1
ADD X1, X1, #1
B L2
L1: ADD X2, X2, #1
L2: ...
```

```
B.NE 3
ADD X1, X1, #1
B 2
ADD X2, X2, #1
```

- This is fine for if-statements, for-loops etc
- But functions can be called from multiple places
 - Meaning we'll return to different spots on each func call! Can't hardcode offset!

```
int func(int x) {
  printf(x * 10);
  return;
}
int helper() {
  func(7);
}
int main() {
  helper();
  func(13);
}
Should this return to
"helper" or "main"?
```



Solution: Indirect Jumps

- Indirect branches or "jumps" don't hardcode destination
- They index a register whose value holds destination

	branch	В	2500	go to PC + 10000	Branch to target address; PC-relative
Unconditional branch	branch to register	BR	X30	go to X30	For switch, procedure return
	branch with link	BL	2500	X30 = PC + 4; PC + 10000	For procedure call PC-relative

- Use "BL" to call a function
 - Destination is hardcoded
 - PC +4 (return address) stored in X30
- Use "BR" to return from a function
 - X30 is read for return address
 - Allows us to return to different places



Solution: Indirect Jumps

```
ADD
int mult_2(int x) {
                                                 BL
int temp = x*2;
                   Also don't
                                     RETURN:
return temp;
                  need "return"
                     labels
                                                 BL PRINTF
int GLOBAL = 6;
                                     MULT_2:
int main() {
int result = mult 2(GLOBAL+1);
                                                 ADD
printf(result);
                   Now MULT 2
                                                           X30
                                                 BR
                   can return to
                     whatever
                     function
```

called it

```
LDURSW X1, [XZR, GLOBAL]
      X2, X1, #1
                       // Inc GLOBAL
STURW X2, [XZR, X]
                       // Pass arg
                       // Execute func
      MULT 2
LDURSW X3, [XZR, TEMP] // load result
STURW X3, [XZR, STRING] // Pass arg
                       // Execute func
LDURSW X1, [XZR, X] // load arg
      X2, X1, X1 // mult by 2
STURW X2, [XZR, TEMP]
                       // return result
                            return
```



Problem 2: Passing Parameters

For any recursive functions, global variables will be overwritten

```
int mult_2(int x) {
  int temp = x*2;
  return temp;
}

int GLOBAL = 6;

int main() {
  int result = mult_2(GLOBAL+1);
  printf(result);
}
```

```
LDURSW X1, [XZR, GLOBAL]
      ADD X2, X1, #1 // Inc GLOBAL
      STURW X2, [XZR, X]
                             // Pass arg
      BL MULT 2 // Execute func
       LDURSW X3, [XZR, TEMP] // load result
      STURW X3, [XZR, STRING] // Pass arg
                             // Execute func
      BL PRINTF
MULT_2:
       LDURSW X1, [XZR, X] // load arg
                             // mult by 2
      ADD X2, X1, X1
      STURW X2, [XZR, TEMP]
                             // return result
       BR
                             // return
```



Passing parameters

- Where should you put all of the parameters?
 - Registers?
 - Fast access but few in number and wrong size for some objects
 - Memory?
 - Good general solution but slow
- ARMv8 solution—and the usual answer:
 - Both
 - Put the first few parameters in registers (if they fit) (X0 X7)
 - Put the rest in memory on the call stack— important concept



Call stack

- ARM conventions (and most other processors) allocate a region of memory for the "call" stack
 - This memory is used to manage all the storage requirements to simulate function call semantics
 - Parameters (that were not passed through registers)
 - Local variables
 - Temporary storage (when you run out of registers and need somewhere to save a value)
 - Return address
 - Etc.
- Sections of memory on the call stack [stack frames] are allocated when you
 make a function call, and de-allocated when you return from a function



The stack grows as functions are called

```
void foo()
{
  int x, y[2];
  bar(x);
}

void bar(int x)
{
  int a[3];
  printf();
}
```

inside foo

foo's stack frame

foo calls bar

foo's stack frame

bar's stack frame

bar calls printf

foo's stack frame

bar's stack frame

printf's stack frame





The stack shrinks as functions return

void foo() { int x, y[2]; bar(x); } void bar(int x) { int a[3]; printf(); }

printf returns

foo's stack frame

bar's stack frame

bar returns

foo's stack frame



Stack frame contents



```
void foo()
{
  int x, y[2];
  bar(x);
}

void bar(int x)
{
  int a[3];
  printf();
}
```

foo's stack frame

return addr to main				
X				
y[0]				
y[1]				
spilled registers in foo				



Stack frame contents (2)



foo calls bar

```
void foo()
{
  int x, y[2];
  bar(x);
}

void bar(int x)
{
  int a[3];
  printf();
}
```

Spill data—not enough room in x0-x7 for params and also caller and callee saves

foo's frame bar's frame

return addr to main
X
y[0]
y[1]
spilled regs in foo
X
return addr to foo
a[0]
a[1]
a[2]
spilled regs in bar



Agenda

- Branching far away
- Function calls and the call stack
- Assigning variables to memory locations
- Saving registers
- Caller/callee example



Review: Where do the variables go?

Assigning variables to memory spaces



```
int w;
void foo(int x)
{
   static int y[4];
   char* p;
   p = malloc(10);
   //...
   printf("%s\n", p);
}
```

stack

heap

static

text



Assigning variables to memory spaces



```
int w;
void foo(int x)
{
   static int y[4];
   char* p;
   p = malloc(10);
   //...
   printf("%s\n", p);
}
```

w goes in static, as it's a global x goes on the stack, as it's a parameter

y goes in static, 1 copy of this!!

p goes on the stack

allocate 10 bytes on heap, ptr

set to the address

string literal "%s\n" goes in static,

implicit pointer to string on stack, p goes

The addresses of local variables will be different depending on where we are in the call stack

on stack

stack

heap

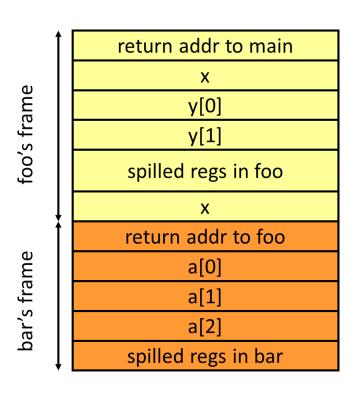
static

text



Accessing Local Variables

- Stack pointer (SP):
 - register that keeps track of current top of stack
- Compiler (or assembly writer) knows relative offsets of objects in stack
- Can access using lw/sw offsets





Agenda

- Branching far away
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Problem 3: Reusing registers

- Higher level languages (like C/C++) provide many abstractions that don't exist at the assembly level
- E.g. in C, each function has its own local variables
 - Even if different function have local variables with the same name, they are independent and guaranteed not to interfere with each other!

```
int main() {
  int a=1;
  foo();
  printf(a);
}
Still prints "1"...

these don't
  int a=2;
  return;
  }

Int main() {
  int a=2;
  return;
  }

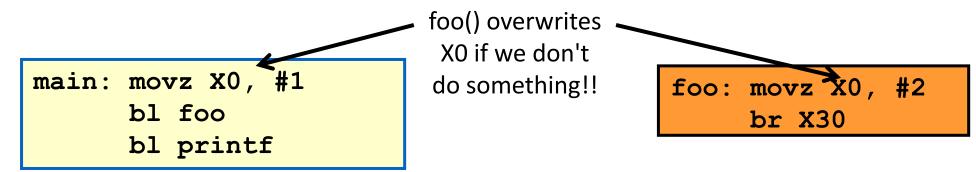
Int a=2;
  return;
  }

Int a=2;
  return;
  int a=2;
  int a=2;
```



What about registers?

- But in assembly, all functions share a small set (e.g. 32) of registers
 - Called functions will overwrite registers needed by calling functions



• "Someone" needs to save/restore values when a function is called to ensure this doesn't happen



Two Possible Solutions

 Either the called function saves register values before it overwrites them and restores them before the function returns (callee saved)...

```
main: movz X0, #1
bl foo
bl printf
```

```
foo: stur X0, [stack]
movz X0, #2
ldur X0, [stack]
br X30
```

• Or the **calling** function saves register values before the function call and restores them after the function call (**caller** saved)...

```
main: movz X0, #1
    stur X0, [stack]
    bl foo
    ldur X0, [stack]
    bl printf
```

foo: movz X0, #2 br X30



Another example

No need to

save r2/r3.

Why?

Original C Code

```
void foo() {
  int a,b,c,d;

a = 5; b = 6;
  c = a+1; d=c-1;

bar();

d = a+d;
  return();
}
```

Additions for Caller-save

```
void foo() {
  int a,b,c,d;

a = 5; b = 6;
  c = a+1; d=c-1;
  save r1 to stack
  save r4 to stack
  bar();
  restore r4
  restore r1
  d = a+d;
  return();
}
```

Assume bar() will overwrite registers holding a,d

Additions for Callee-save

```
void foo(){
  int a,b,c,d;
  save r1
  save r2
  save r3
  save r4
  a = 5; b = 6;
  c = a+1; d=c-1;
  bar();
  d = a+d;
  restore r4
  restore r3
  restore r2
  restore r1
  return();
```

bar() will save a,b, but now foo() must save main's variables

"caller-save" vs. "callee-save"

- Caller-save
 - What if bar() doesn't use r1/r4?
 - No harm done, but wasted work
- Callee-save
 - What if main() doesn't use r1-r4?
 - No harm done, but wasted work

```
void foo() {
  int a,b,c,d;

a = 5; b = 6;
  c = a+1; d=c-1;
  save r1 to stack
  save r4 to stack
  bar();
  restore r1
  restore r4
  d = a+d;
  return();
}
```

```
void foo() {
   int a,b,c,d;
   save r1
   save r2
   save r3
   save r4
   a = 5; b = 6;
   c = a+1; d=c-1;
   bar();
   d = a+d;
   restore r1
   restore r2
   restore r3
   restore r4
   return();
}
```



Saving/Restoring Optimizations



- Where can we avoid loads/stores?
- Caller-saved
 - Only needs saving if value is "live" across function call
 - Live = contains a useful value: Assign value before function call, use that value after the function call

• In a leaf function (a function that calls no other function), caller saves can be

used without saving/restoring

a, d are live

b, c are NOT live

```
void foo() {
  int a,b,c,d;

a = 5; b = 6;
  c = a+1; d=c-1;

bar();

d = a+d;
  return();
}
```

Saving/Restoring Optimizations



- Where can we avoid loads/stores?
- Callee-saved
 - Only needs saving at beginning of function and restoring at end of function
 - Only save/restore it if function overwrites the register

Only use r1r4

No need to save other registers

```
void foo(){
  int a,b,c,d;

a = 5; b = 6;
  c = a+1; d=c-1;

bar();

d = a+d;
  return();
}
```



Agenda

- Branching far away
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Caller versus Callee

- Which is better??
- Let's look at some examples...
- Simplifying assumptions:
 - A function can be invoked by many different call sites in different functions.
 - Assume no inter-procedural analysis (hard problem)
 - A function has no knowledge about which registers are used in either its caller or callee
 - Assume main() is not invoked by another function
 - Implication
 - Any register allocation optimization is done using function local information



Caller-saved vs. callee saved — Multiple function case

```
void final(){
void main(){
                    void foo(){
                                        void bar(){
                      int e,f;
                                          int g,h,i,j;
  int a,b,c,d;
                                                              int y,z;
                                            = 0; h =
                                                              y = 2; z = 3;
  foo();
                                          final();
                                          j = g+h+i;
  d = a+b+c+d;
                      e = e + f;
                                                              z = y+z;
```

Note: assume main does not have to save any callee registers



Caller-saved vs. callee saved — Multiple function case

- Questions:
- 1. How many registers need to be saved/restored if we use a caller-save convention?
- 2. How many registers need to be saved/restored if we use a callee-save convention?
- 3. How many registers need to be saved/restored if we use a mix of caller-save and callee-save?



Question 1: Caller-save

```
void main(){
  int a,b,c,d;
  c = 5; d = 6;
  a = 2; b = 3;
  [4 STUR]
  foo();
  [4 LDUR]
  d = a+b+c+d;
}
```

```
void foo() {
  int e,f;

e = 2; f = 3;
  [2 STUR]
  bar();
  [2 LDUR]
  e = e + f;
}
```

```
void bar() {
  int g,h,i,j;
  g = 0; h = 1;
  i = 2; j = 3;
  [3 STUR]
  final();
  [3 LDUR]
  j = g+h+i;
}
```

```
void final() {
  int y,z;

y = 2; z = 3;

z = y+z;
}
```

Total: 9 STUR / 9 LDUR



Question 2: Callee-save

Poll: How many Id/st pairs are needed?

```
void main() {
  int a,b,c,d;

c = 5; d = 6;
  a = 2; b = 3;
  foo();
  d = a+b+c+d;
}
```

```
void foo(){
  [2 STUR]
  int e,f;

e = 2; f = 3;
  bar();
  e = e + f;

[2 LDUR]
}
```

```
void bar() {
   [4 STUR]
   int g,h,i,j;
   g = 0; h = 1;
   i = 2; j = 3;
   final();
   j = g+h+i;

[4 LDUR]
}
```

```
void final() {
   [2 STUR]
   int y,z;

   y = 2; z = 3;

   z = y+z;

[2 LDUR]
}
```

Total: 8 STUR / 8 LDUR



Is one better?

- Caller-save works best when we don't have many live values across function call
- Callee-save works best when we don't use many registers overall
- We probably see functions of both kinds across an entire program
- Solution:
 - Use both!
 - E.g. if we have 6 registers, use some (say r0-r2) as caller-save and others (say r3-r5) as callee-save
 - Now each function can optimize for each situation to reduce saving/restoring
 - Not discussed further in this class



LEGv8 ABI- Application Binary Interface

- The ABI is an agreement about how to use the various registers
- Not enforced by hardware, just a convention by programmers / compilers
- If you want your code to work with other functions / libraries, follow these
- Some register conventions in ARMv8
 - X30 is the **link register** used to hold return address
 - X28 is **stack pointer** holds address of top of stack
 - X19-X27 are callee-saved function must save these before writing to them
 - X0-15 are caller-saved –function must save live values before call
 - X0-X7 used for **arguments** (memory used if more space is needed)
 - X0 used for return value



Next Time

- Finish Up Function Calls
- Talks about linking the final puzzle piece of software

