

Give me a function block written in ST (based on IEC 61131) to read 5 values from remote IO-Link master along with status of operation.



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used to read 5 values from a remote IO-Link master along with the status of operation:

Copy code

Sure, here's an example function block written in Structured Text (ST) that can be

```
FUNCTION_BLOCK Read_IO_Link
VAR_INPUT
    Slave_Address: BYTE; // IO-Link Master Slave Address
END_VAR
VAR_OUTPUT
    Value1: REAL;
    Value2: REAL;
    Value3: REAL;
    Value4: REAL;
    Value5: REAL;
    Status: BYTE; // Status of operation (0=0K, 1=Error)
END_VAR
VAR
    // Local variables
    Read_Buffer: ARRAY[0..15] OF BYTE;
    Write_Buffer: ARRAY[0..15] OF BYTE;
    Tx_Length: WORD;
    Rx_Length: WORD;
    ErrorCode: WORD;
END_VAR
// Set up Write Buffer with IO-Link Command to read 5 values
Write_Buffer[0] := 128#10; // IO-Link Command: Read
Write_Buffer[1] := 5; // Number of values to read
Write_Buffer[2] := 1; // Starting address of read
// Call the IO-Link Master Communication Function Block
Tx_Length := 3;
Rx_Length := 23;
Status := IO_Link_Comm(Slave_Address, Write_Buffer, Tx_Length, Read_Buffer,
// Check if communication was successful
IF Status = ∅ THEN
    // Extract the 5 values from the Read Buffer
    Value1 := REAL_TO_LREAL(DINT_TO_REAL(Read_Buffer[3] + (Read_Buffer[4] *
    Value2 := REAL_TO_LREAL(DINT_TO_REAL(Read_Buffer[7] + (Read_Buffer[8] *
    Value3 := REAL_TO_LREAL(DINT_TO_REAL(Read_Buffer[11] + (Read_Buffer[12]
    Value4 := REAL_TO_LREAL(DINT_TO_REAL(Read_Buffer[15] + (Read_Buffer[16]
    Value5 := REAL_TO_LREAL(DINT_TO_REAL(Read_Buffer[19] + (Read_Buffer[20]
ELSE
    // Set all output values to zero in case of communication error
    Value1 := 0;
    Value2 := 0;
    Value3 := 0;
    Value4 := 0;
    Value5 := 0;
END_IF
```

Certainly, here's an example implementation of an IO\_Link\_Comm function block in

Tx\_Buffer: ARRAY[0..15] OF BYTE; // Buffer containing data to be transm

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This function block assumes that there is an existing IO-Link Master

Communication Function Block (named `Io\_Link\_Comm`) that can handle the low-

level communication with the remote IO-Link master. The `slave\_Address` input

with. The `value1` to `value5` outputs represent the 5 values that are read from

the IO-Link master. The `status` output is a status byte that indicates whether the

specifies the IO-Link master slave address that the function block will communicate



Structured Text (ST):

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VAR\_INPUT

FUNCTION\_BLOCK IO\_Link\_Comm

Slave\_Address: BYTE; // IO-Link Master Slave Address

Tx\_Length: WORD; // Length of data to be transmitted

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Rx_Buffer: ARRAY[0..15] OF BYTE; // Buffer to store received data
    Rx_Length: WORD; // Length of received data buffer
END_VAR
VAR_OUTPUT
    Status: BYTE; // Status of operation (0=0K, 1=Error)
    ErrorCode: WORD; // Error code (0=No error, other values depend on impl
END_VAR
VAR
    // Local variables
    Tx_Data: ARRAY[0..31] OF BYTE; // Buffer to store transmitted data (inc
    Rx_Data: ARRAY[0..31] OF BYTE; // Buffer to store received data (include
    Tx_Index: WORD;
    Rx_Index: WORD;
    Tx_Checksum: WORD;
    Rx_Checksum: WORD;
    i: INT;
END_VAR
// Calculate Tx checksum
Tx_Checksum := 0;
FOR i := 0 TO Tx_Length - 1 DO
    Tx_Data[i + 2] := Tx_Buffer[i];
    Tx_Checksum := Tx_Checksum XOR Tx_Buffer[i];
END_FOR
Tx_Data[0] := Slave_Address;
Tx_Data[1] := Tx_Length;
Tx_Checksum := Tx_Checksum XOR Slave_Address XOR Tx_Length;
Tx_Data[Tx_Length + 2] := Tx_Checksum MOD 256;
Tx_Data[Tx_Length + 3] := Tx_Checksum DIV 256;
// Transmit data and receive response
IF Send_IO_Link_Data(Tx_Data, Tx_Length + 4, Rx_Data, Rx_Length + 4, Error(
    // Extract Rx data and calculate checksum
    Rx_Index := 0;
    Rx_Checksum := 0;
    FOR i := 0 TO Rx_Length - 1 DO
        Rx_Buffer[i] := Rx_Data[i + 2];
        Rx_Checksum := Rx_Checksum XOR Rx_Buffer[i];
    END_FOR
    FOR i := 0 TO 3 DO
        Rx_Checksum := Rx_Checksum XOR Rx_Data[Rx_Length + i];
    END_FOR
    // Check if checksums match
    IF Rx_Checksum = 0 THEN
        Status := 0; // Communication successful
    ELSE
        Status := 1; // Checksum error
    END_IF
ELSE
    Status := 1; // Communication error
END_IF
```

This implementation assumes that there is an existing Send\_IO\_Link\_Data function block that can handle the low-level communication with the IO-Link master. The `Slave\_Address` input specifies the IO-Link master slave address that the function block will communicate with. The `Tx\_Buffer` input is an array of bytes that contains the data to be transmitted to the IO-Link master. The `Tx\_Length` input specifies the length of the data to be transmitted. The `Rx\_Buffer` input is an array of bytes that will store the received data from the IO-Link master. The `Rx\_Length` input specifies the expected length of the received data.

The `Status` output is a status byte that indicates whether the communication was

successful (0) or if there was an error (1). The `ErrorCode` output is an error code that depends on the specific implementation of the function block.

The function block calculates a checksum for the transmitted data and appends it



to the data before