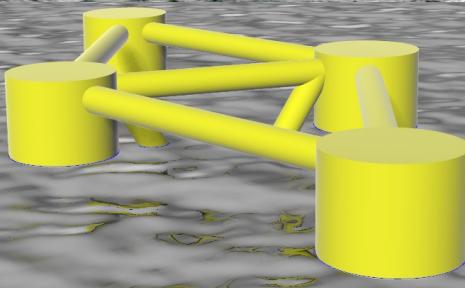




# OpenFAST for Marine Turbines

Hannah Ross, Will Wiley, Thanh Toan Tran  
Adapted from material developed by Jason Jonkman  
NREL

October 4, 2023  
UMERC Conference



# NREL Water Power Research

NREL researchers are **leveraging R&D expertise**, such as numerical modeling, laboratory testing, and open-water validation.



Modeling and analysis



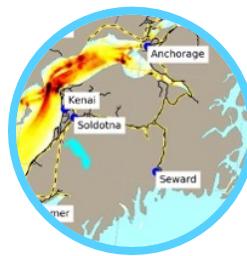
Innovation and design



Laboratory validation



Open-water demonstration



Pilot deployment support



Workforce and infrastructure

**NREL:**

**~3000**  
Employees

**\$670M+**  
FY22 project portfolio

**NREL Water Power:**

**45+**  
Full-time staff

**\$28M+**  
FY22 project portfolio

# Workshop Summary

**OpenFAST Overview**  
**2:00 – 2:50**

**Break (2:50 – 3:00)**

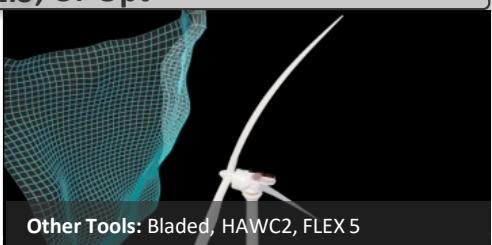
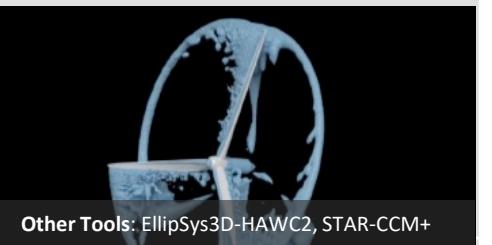
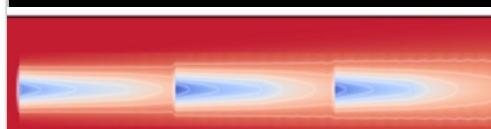
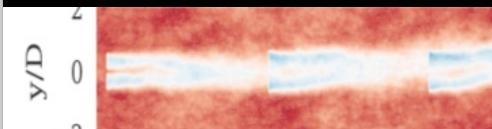
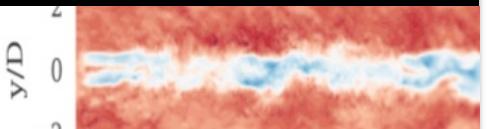
**OpenFAST Demonstration**  
**3:00 – 3:45**

# Outline: OpenFAST Overview

- NREL/DOE open-source modeling tool overview
- Overview of OpenFAST
- OpenFAST modules
- Marine turbine features
  - Feature overview
  - Modifications to OpenFAST modules
- Future development

# NREL/DOE Open-Source Modeling Tool Overview

## Model Fidelity / Computational Intensity

Application	Design Exploration	Detailed Design	Highly Resolving
Single Turbine Performance and Loads	<b>WISDEM, RAFT</b> Multidisciplinary design optimization and cost modeling	<b>OpenFAST</b> Turbine loads analysis, detailed turbine design, IEC standards	<b>ExaWind/SOWFA</b> Understand physics, final turbine design check, calibrate / validate lower fidelity
	 <b>WEIS, CT-Opt</b> Other Tools: Turbine Architect, CpMax, HawtOpt2	 <b>Bladed, HAWC2, FLEX 5</b> Other Tools: Bladed, HAWC2, FLEX 5	 <b>EllipSys3D-HAWC2, STAR-CCM+</b> Other Tools: EllipSys3D-HAWC2, STAR-CCM+
Full Wind-Plant Performance and Loads	<b>FLORIS</b> Wind-plant controls and siting optimization	<b>FAST.Farm, WindSE</b> Turbine siting within plant, wind-plant controls, plant loads analysis, detailed plant design	<b>ExaWind/ERF/SOWFA</b> Understand physics, final plant design check, calibrate / validate lower fidelity
	 <b>WAsP, WindFarmer, Fuga</b> Other Tools: WAsP, WindFarmer, Fuga	 <b>openWind, MeteoDyn WT, DWM</b> Other Tools: openWind, MeteoDyn WT, DWM	 <b>EllipSys3D, PALM, WRF-LES, W2A2KE3D, VFS-Wind</b> Other Tools: EllipSys3D, PALM, WRF-LES, W2A2KE3D, VFS-Wind

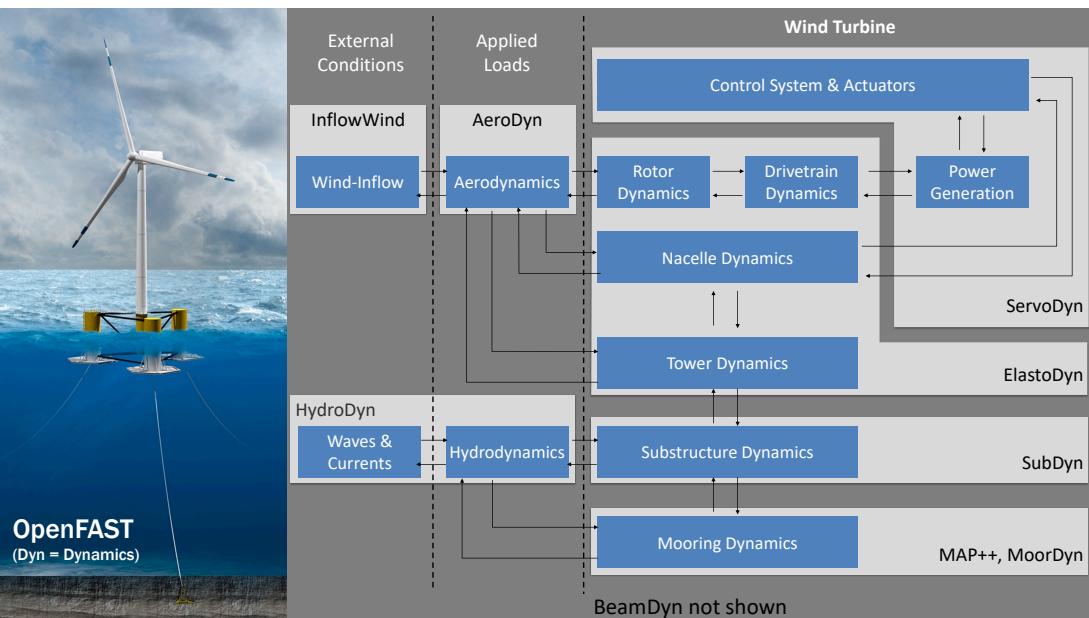
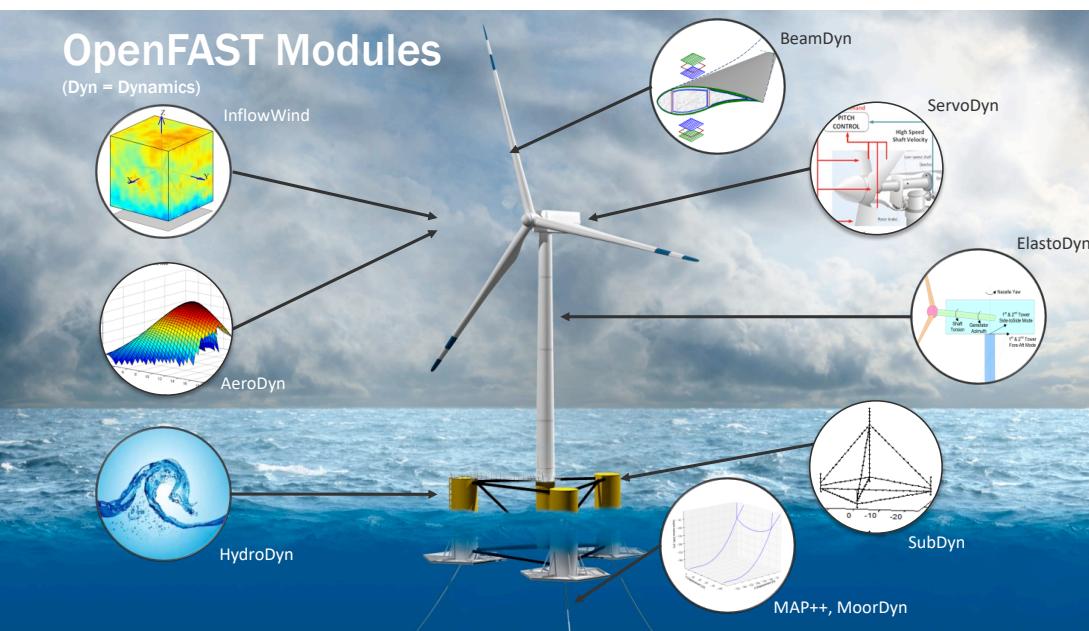
\*Other tools are other widely-used tools with similar capabilities

# Overview of OpenFAST

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# OpenFAST Capabilities

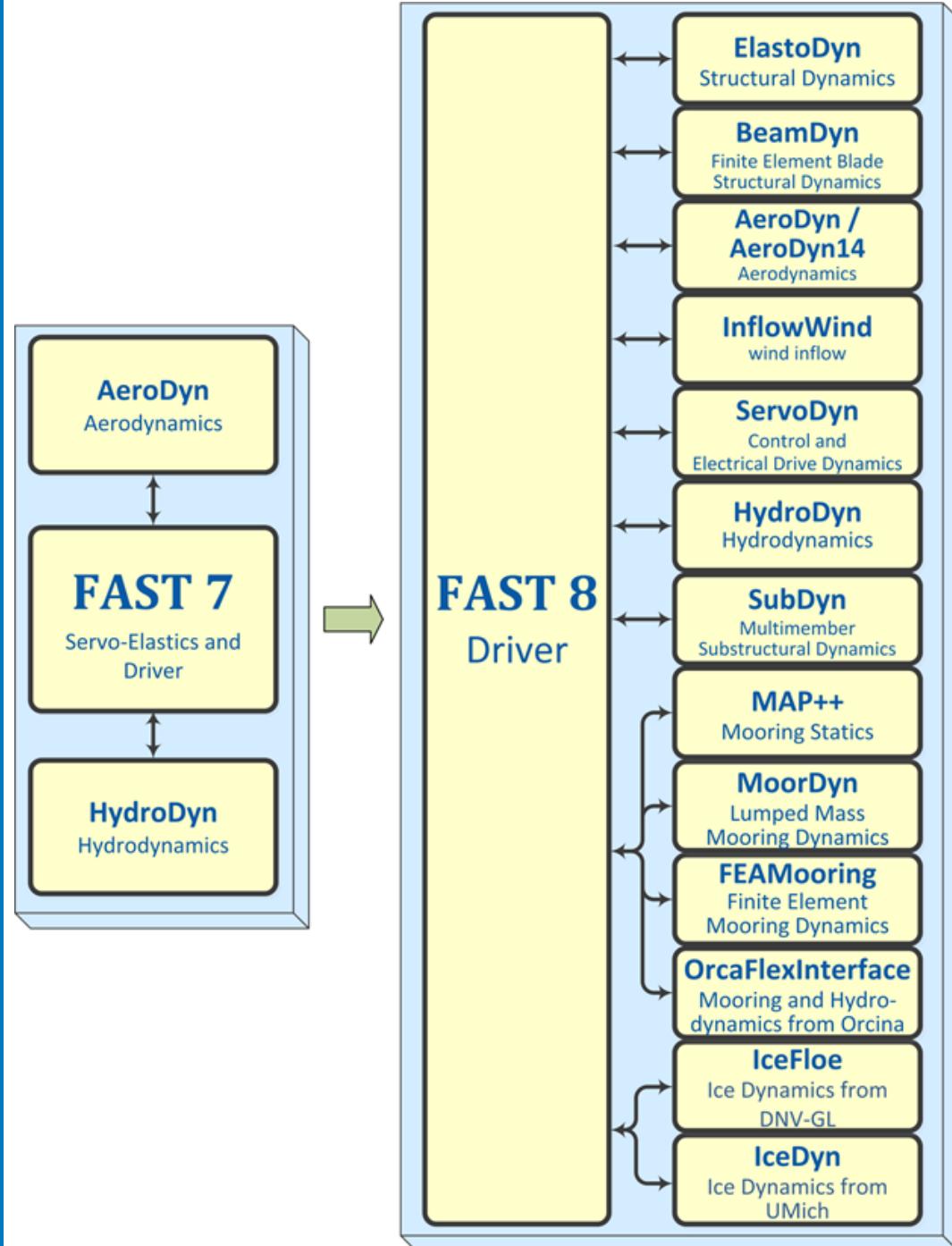
- Coupled aero-hydro-servo-elastic simulations
- Individual turbine modeling
- Land-based, fixed-bottom offshore, and floating offshore wind turbines
- Fixed-bottom and floating marine turbines
- Run extensive numbers of nonlinear time-domain simulations in real time to enable standards-based loads analysis for predicting system ultimate and fatigue loads
- Linearize\* the underlying nonlinear model about an operating point to understand the system response and enable modal analysis; controls design; and aero-elastic instability studies



\*linearization in progress for marine turbines

# OpenFAST History

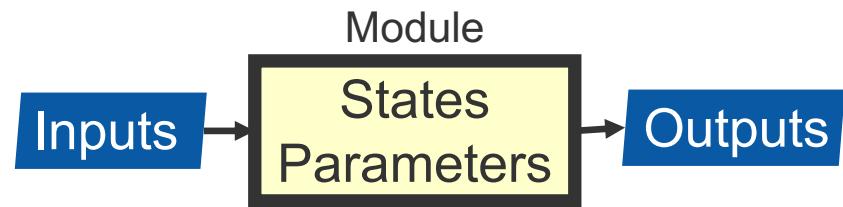
- OpenFAST is DOE / NREL's premier open-source wind/marine turbine physics-based engineering tool
- FAST has undergone major restructuring -- new modularization framework (v8)
- Framework supports expanded functionality
- Facilitates the establishment of an open-source code-development community for physics-based engineering models (**OpenFAST\***)



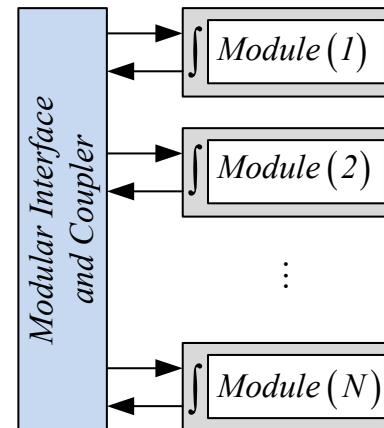
\*<https://github.com/OpenFAST/openfast/tree/main>

# OpenFAST Modularization Framework

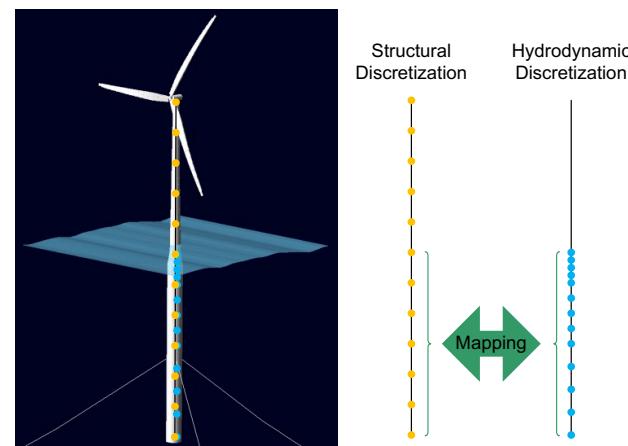
- Module-independent inputs, outputs, states, and parameters
- States in continuous-time, discrete-time, constraint, & “other” form
- Loose & tight\* coupling
- Independent time & spatial discretizations
- Time marching, operating-point determination, & linearization
- Data encapsulation & dynamic allocation
- Checkpoint/restart capability



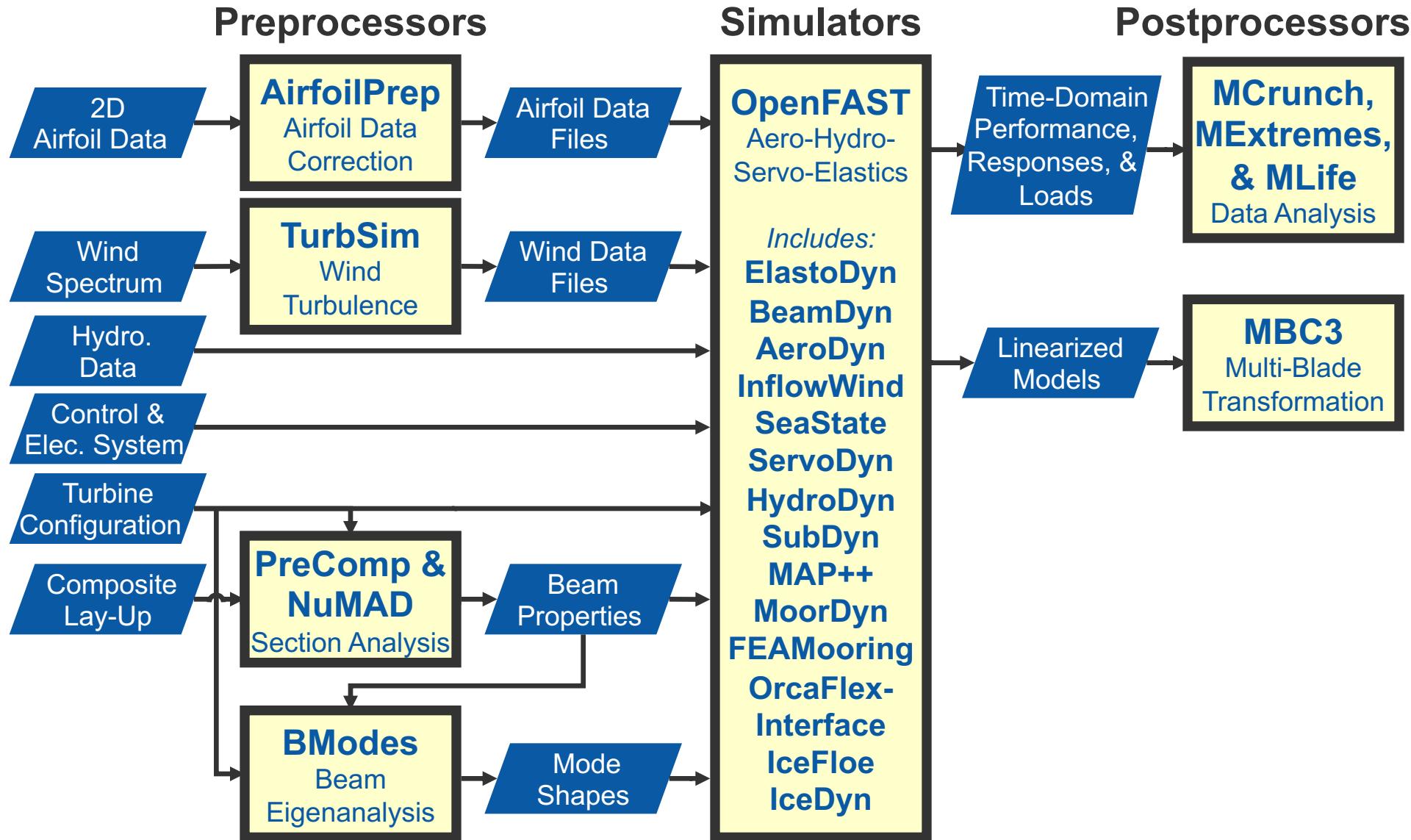
Implicit Loose Coupling Scheme



Mapping Independent Discretizations



# Key DOE/NREL Tools in the Design Process

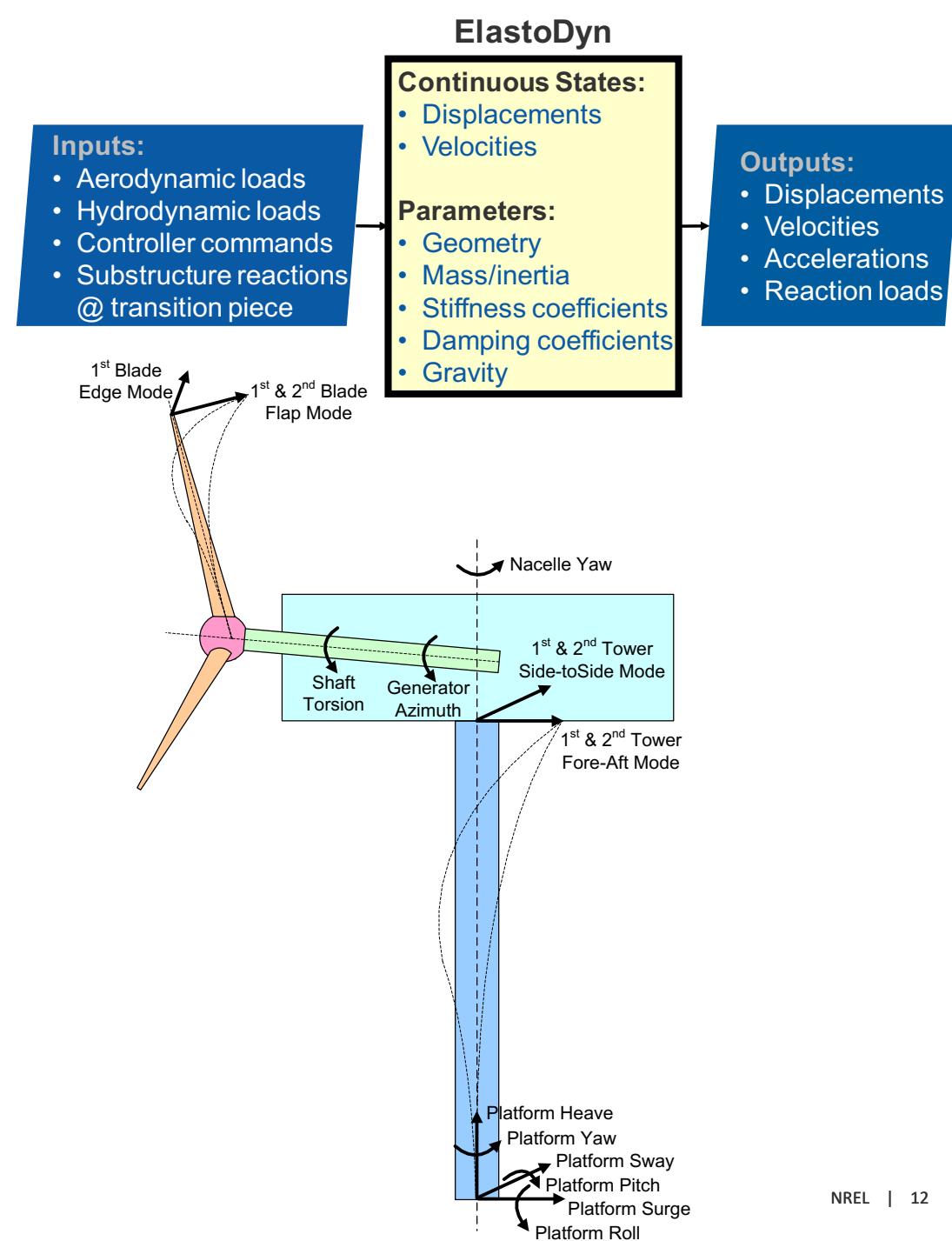


# OpenFAST Modules

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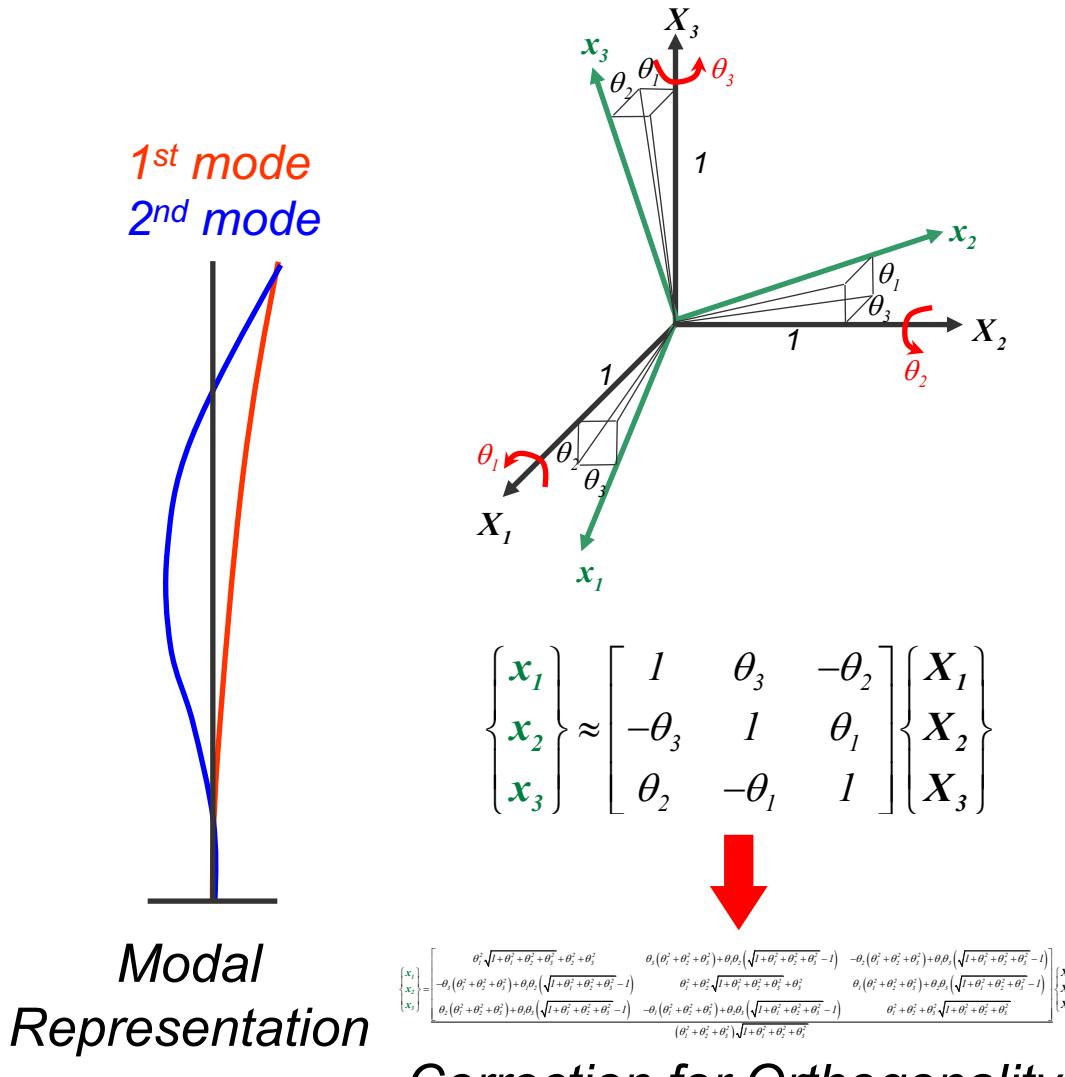
# ElastoDyn

- Turbine configuration:
  - Horizontal-axis (HAWT)
  - 2- or 3-bladed rotor
  - Upwind or downwind rotor
  - Rigid or teetering hub
  - Conventional configuration or inclusion of rotor- and/or tail-furling
  - Support structure that includes a tower atop a platform
- Combined modal & multi-body representation through 24 DOFs
  - Modal: blades, tower
  - Multi-body: platform, nacelle, generator, gears, hub, tail



# ElastoDyn

- Utilizes relative DOFs w/o constraints:
  - Platform rotations and blade / tower deflections employ small-angle approximations with correction for orthogonality (accuracy drops considerably for angles  $\gg 20^\circ$ )
  - All other DOFs may exhibit large motions w/o loss of accuracy
  - Nonlinear* equations of motion
  - Explicit (RK4) or PC (AB4, ABM4) time integration
- Beam model:
  - Euler-Bernoulli beam
  - Straight & isotropic
  - Bending only (no twist)
  - Assumed-mode method
  - Some geometric nonlinearity



$$\begin{Bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \mathbf{x}_3 \end{Bmatrix} \approx \begin{bmatrix} 1 & \theta_3 & -\theta_2 \\ -\theta_3 & 1 & \theta_1 \\ \theta_2 & -\theta_1 & 1 \end{bmatrix} \begin{Bmatrix} X_1 \\ X_2 \\ X_3 \end{Bmatrix}$$

$$\begin{Bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \mathbf{x}_3 \end{Bmatrix} = \begin{bmatrix} \theta_1^2 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2} + \theta_1^2 + \theta_2^2 & \theta_1 (\theta_1^2 + \theta_2^2 + \theta_3^2) + \theta_2 \theta_3 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2 - l} & -\theta_1 (\theta_1^2 + \theta_2^2 + \theta_3^2) + \theta_2 \theta_3 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2 - l} \\ \theta_1 (\theta_1^2 + \theta_2^2 + \theta_3^2) + \theta_2 \theta_3 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2 - l} & \theta_1^2 + \theta_2^2 + \theta_3^2 + \theta_1^2 + \theta_2^2 + \theta_3^2 & \theta_1 (\theta_1^2 + \theta_2^2 + \theta_3^2) + \theta_2 \theta_3 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2 - l} \\ \theta_1 (\theta_1^2 + \theta_2^2 + \theta_3^2) + \theta_2 \theta_3 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2 - l} & -\theta_1 (\theta_1^2 + \theta_2^2 + \theta_3^2) + \theta_2 \theta_3 \sqrt{\theta_1^2 + \theta_2^2 + \theta_3^2 - l} & \theta_1^2 + \theta_2^2 + \theta_3^2 + \theta_1^2 + \theta_2^2 + \theta_3^2 \end{bmatrix} \begin{Bmatrix} X_1 \\ X_2 \\ X_3 \end{Bmatrix}$$

*Correction for Orthogonality*

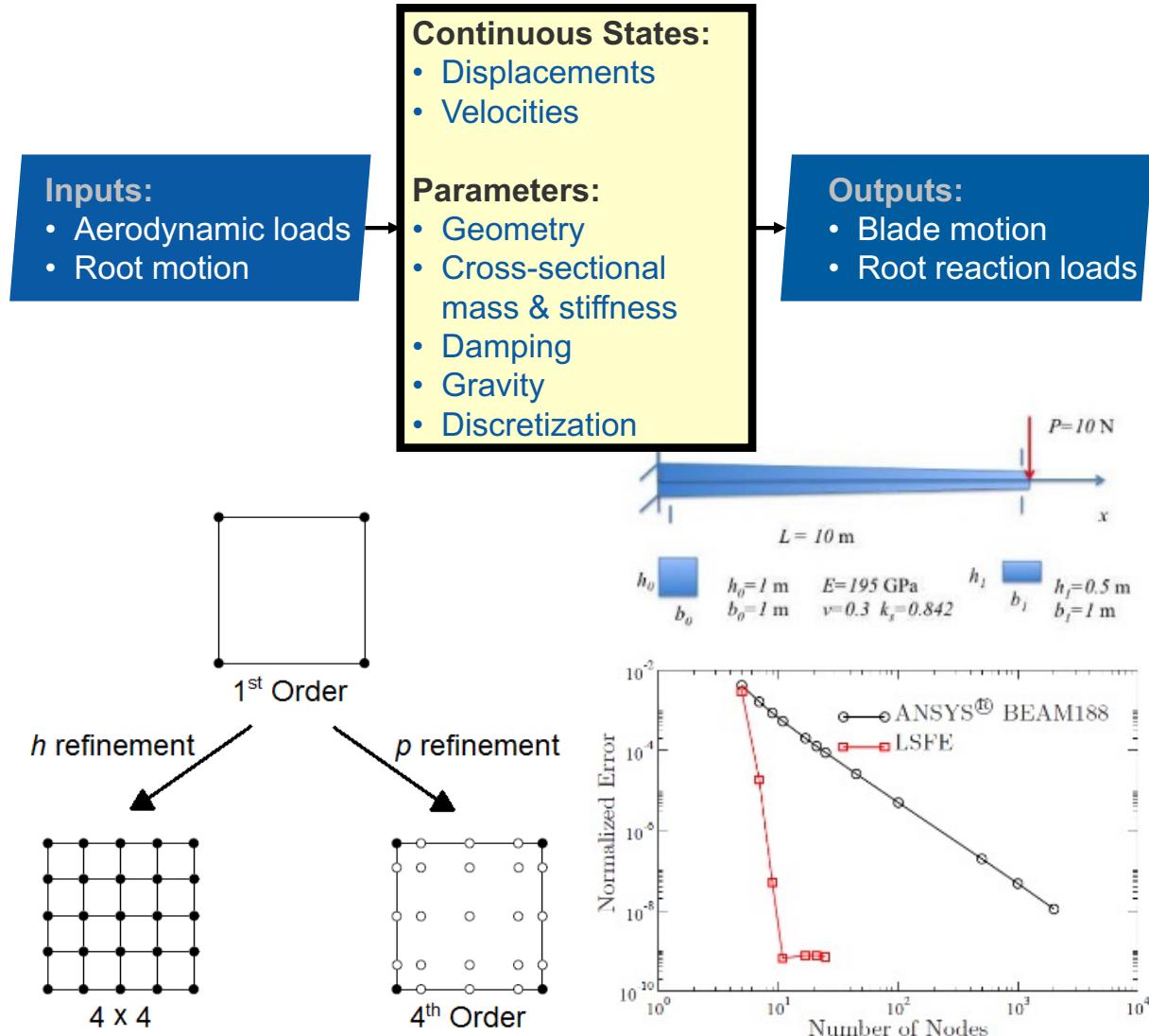
# BeamDyn

- Geometrically exact beam theory (GEBT)
  - Full  $6 \times 6$  cross-sectional mass & stiffness
  - Stiffness-proportional damping
  - Curved/swept reference axis (spline based)
  - Nonlinear geometrically exact large deflection
- Legendre spectral finite element (LSFE)
  - Analyze blade w/ single LSFE
- Both Gauss & Trapezoidal-Rule spatial integration
- Both statics & dynamics
  - Time integration via generalized- $\alpha$

K. Thomsen, Siemens (2013)

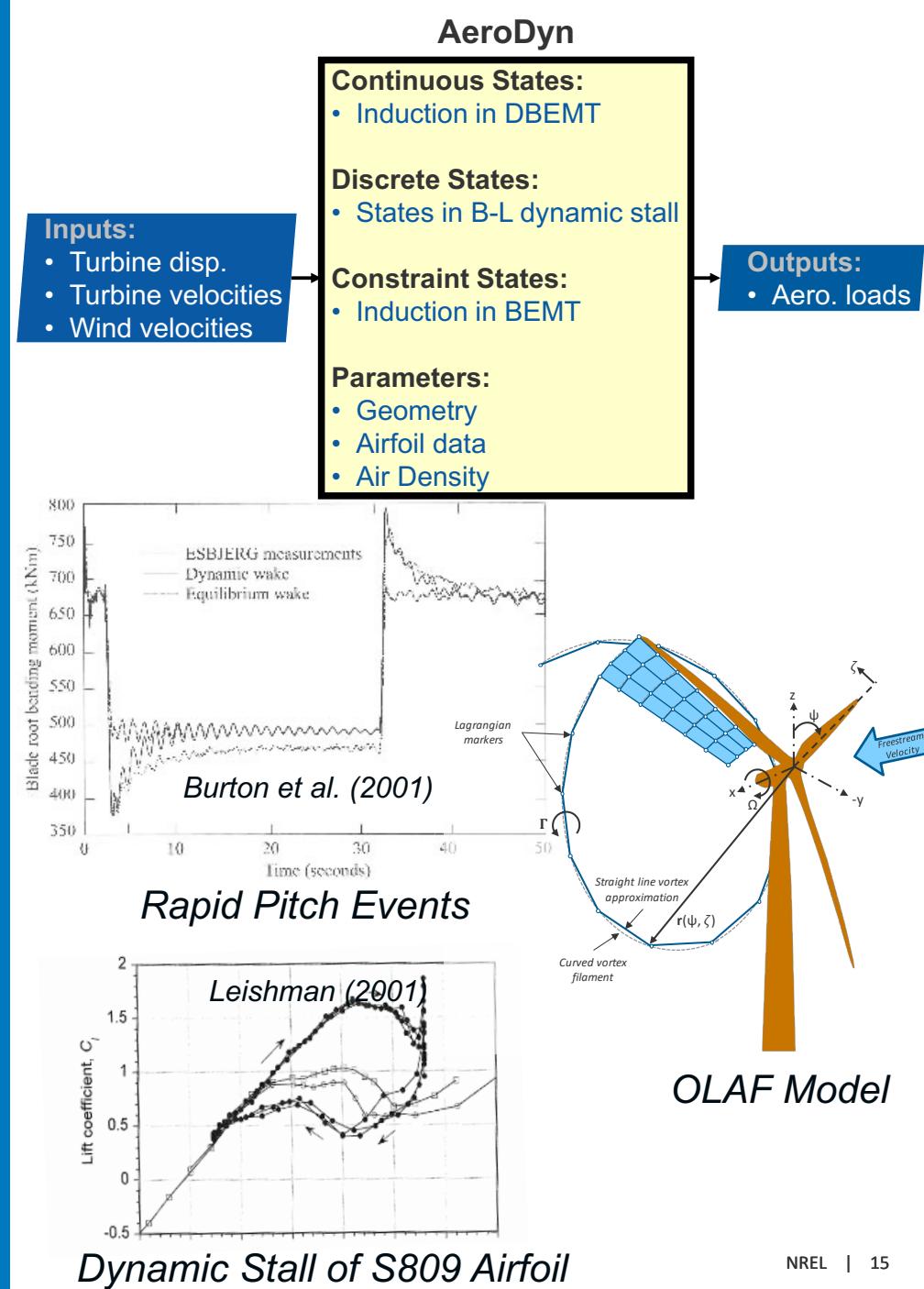


## Advancement in Blade Design BeamDyn



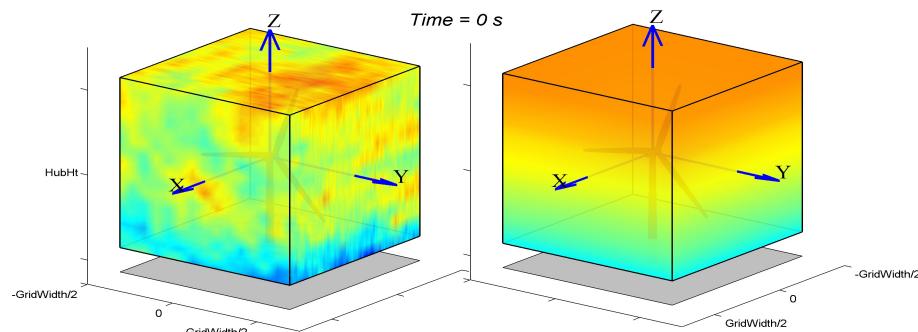
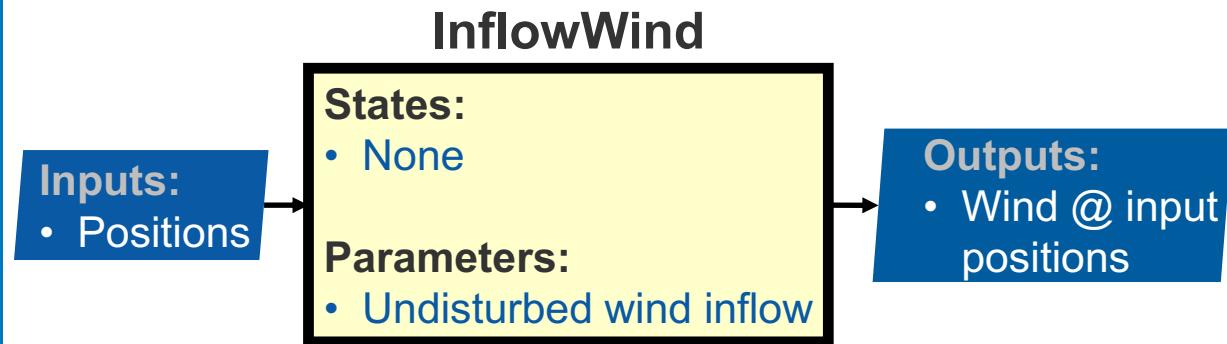
# AeroDyn, including OLAF

- Actuator-line physics:
  - Wake / induction: quasi-static momentum (BEM), dynamic wake (DBEMT), or free-vortex wake (OLAF)
  - Airfoil: quasi-steady or unsteady airfoil aerodynamics (BL, HGM) (relies on airfoil polars)
  - Tower drag & influence on wind
- cOnvecting LAgrangian Filaments (OLAF) model:
  - Lagrangian approach – Wake discretized into Lagrangian markers connected by vortex filaments
  - Hybrid lattice / filament (near wake / tip and root vortices) method
  - Biot-Savart law for computed induced velocities
  - Multiple regularization methods
  - Optional OpenMP parallelization



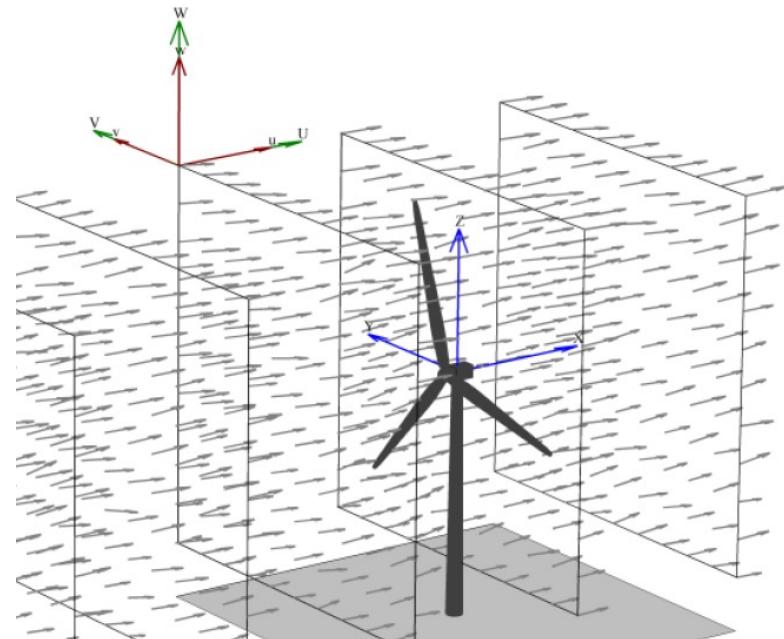
# InflowWind

- Undisturbed wind inflow:
  - Steady
  - Uniform, but time-varying (e.g., deterministic gusts from IEC)
  - Full-field (FF) turbulence (TurbSim, Bladed, HAWC2)
  - User-defined



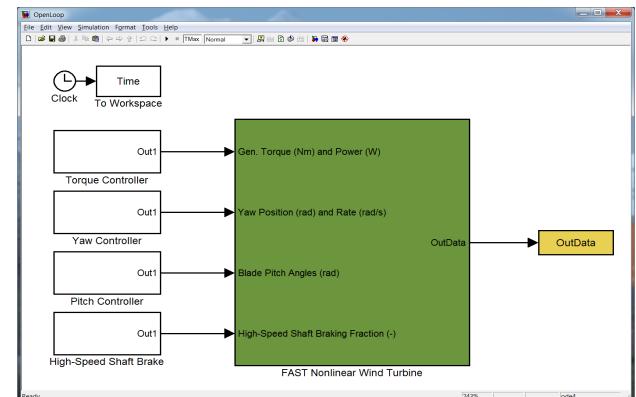
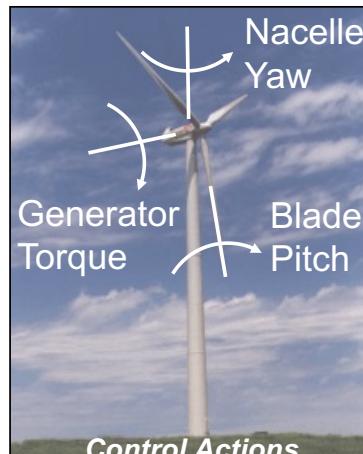
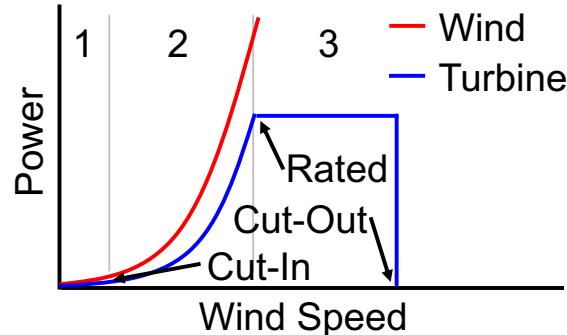
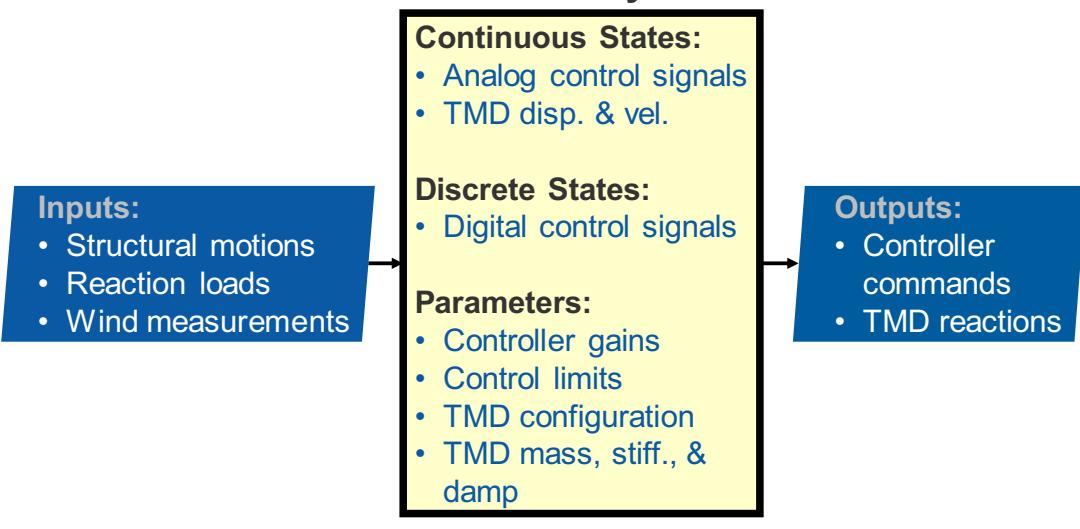
*FF Versus Uniform Wind*

*FF Wind Treated w/  
Taylor's Frozen  
Turbulence Hypothesis*



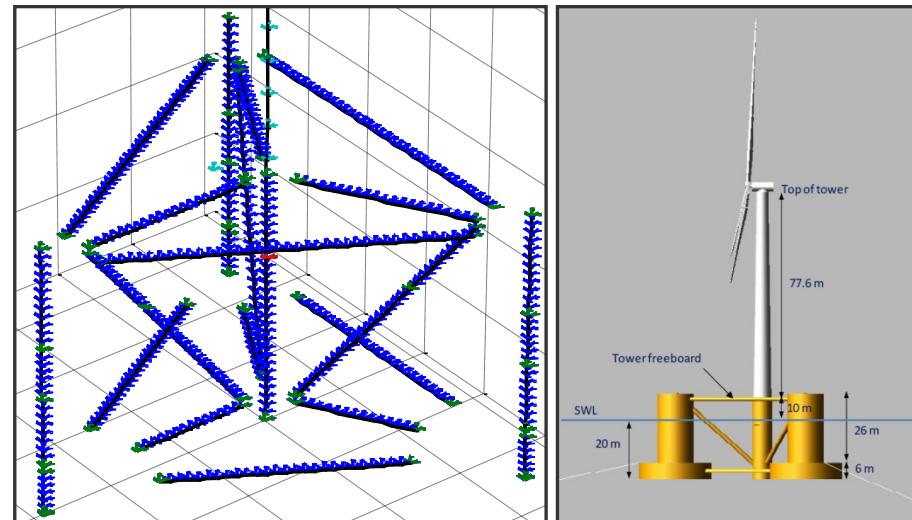
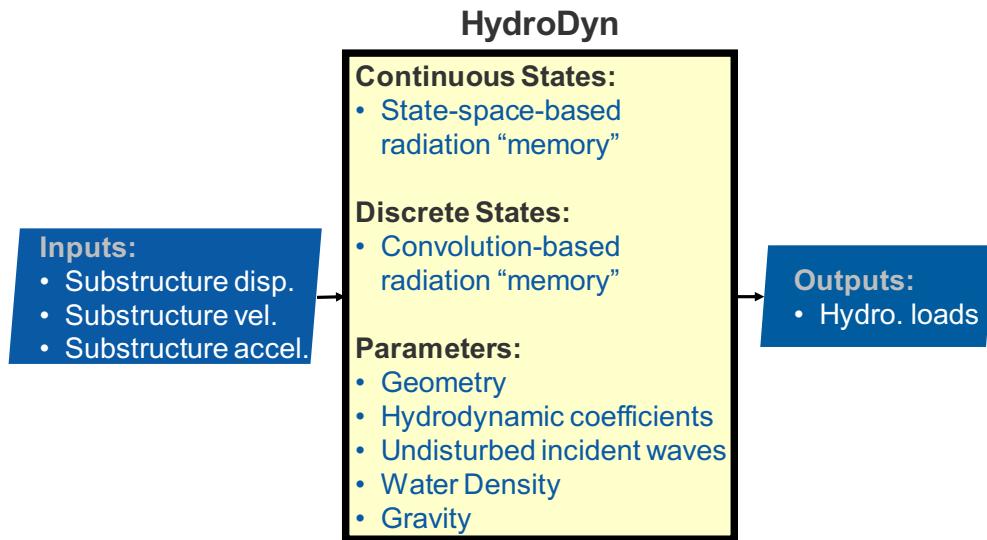
# ServoDyn

- Control & electrical-drive functions
- Actuators:
  - Blade pitch
  - Generator torque
  - HSS brake
  - Nacelle yaw
  - Structural controls (TMDs, TLCDs)
- Implementations:
  - Simple built-in
  - User Fortran subroutines
  - Bladed-style dynamic link library (DLL)
  - MATLAB/Simulink interface
  - LabVIEW interface
- Faults



# HydroDyn – Hydrodynamics for fixed & floating substructures

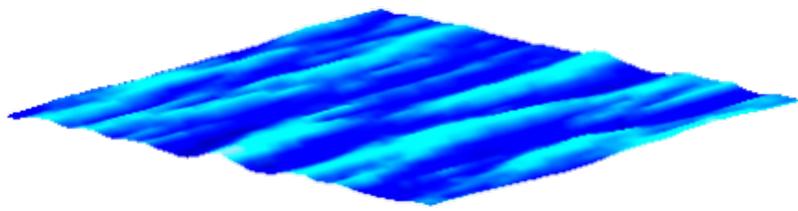
- Strip theory (Morison):
  - For “slender” members
  - Inertia, added mass, viscous, & buoyancy loads
  - Multiple interconnected members
- Potential flow (WAMIT):
  - For “large” platforms
  - Radiation, diffraction, & buoyancy loads
  - Linear state-space-based radiation formulation alternative to convolution
  - 1<sup>st</sup>- (RAO) & 2nd-order (QTF)
  - 2<sup>nd</sup>-order via Newman’s approximation or full QTF
- Hybrid combination of these two
- Wave stretching\*
- Surface tracking\*
- Instantaneous hydrostatics and hydrodynamics at surface\*



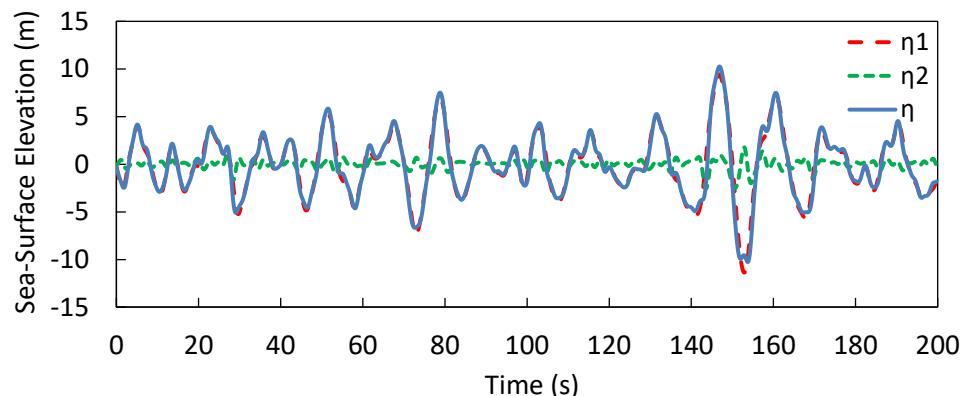
*Strip-Theory Nodes for the OC4-DeepCwind Semisubmersible*

# SeaState\*

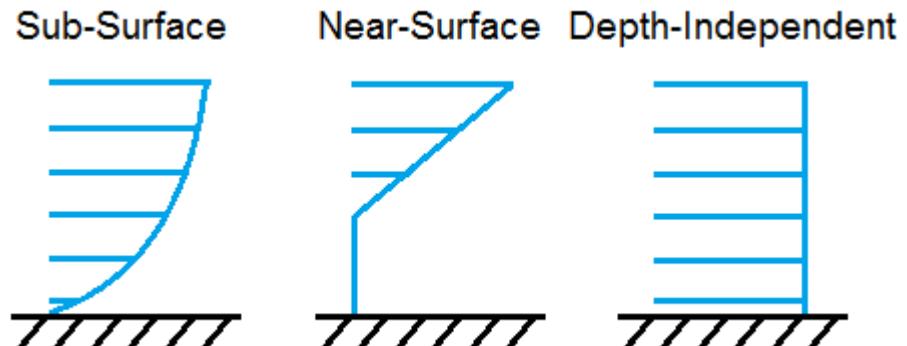
- Regular, irregular, or white noise waves:
  - Pierson-Moskowitz, JONSWAP, white-noise, or user-defined
  - Or externally generated wave elevations or full wave kinematics
- Wave direction & directional spreading:
  - Requires  $S(\omega, \beta) = S(\omega)D(\beta)$
- 1<sup>st</sup>- (Airy) & 2<sup>nd</sup>-order (Sharma/Dean):
  - Analytical for finite-depth
- Steady sea currents:
  - IEC-style sub-surface, near-surface, & depth-independent
  - Or user-defined
- Grid of velocities and accelerations



*Multi-Directional Sea State*



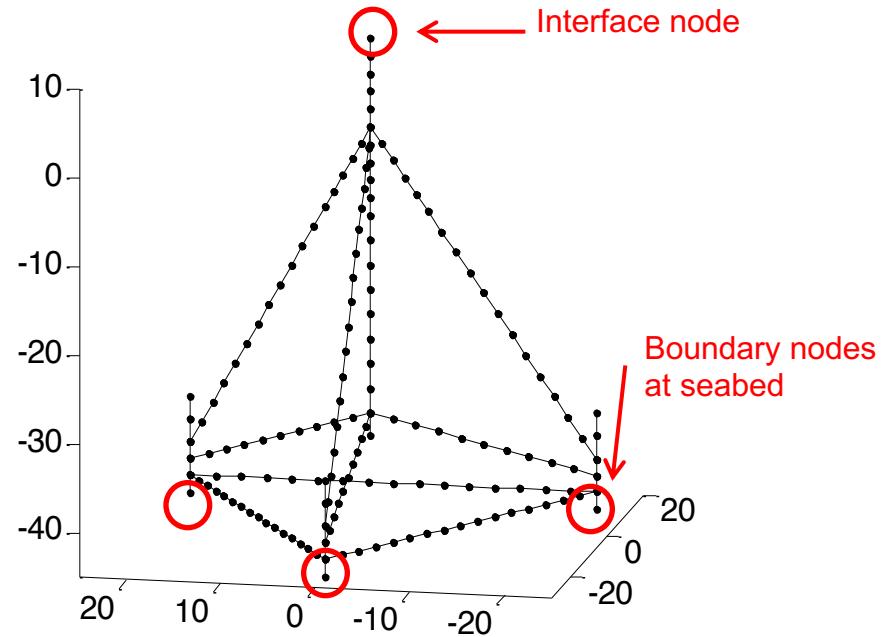
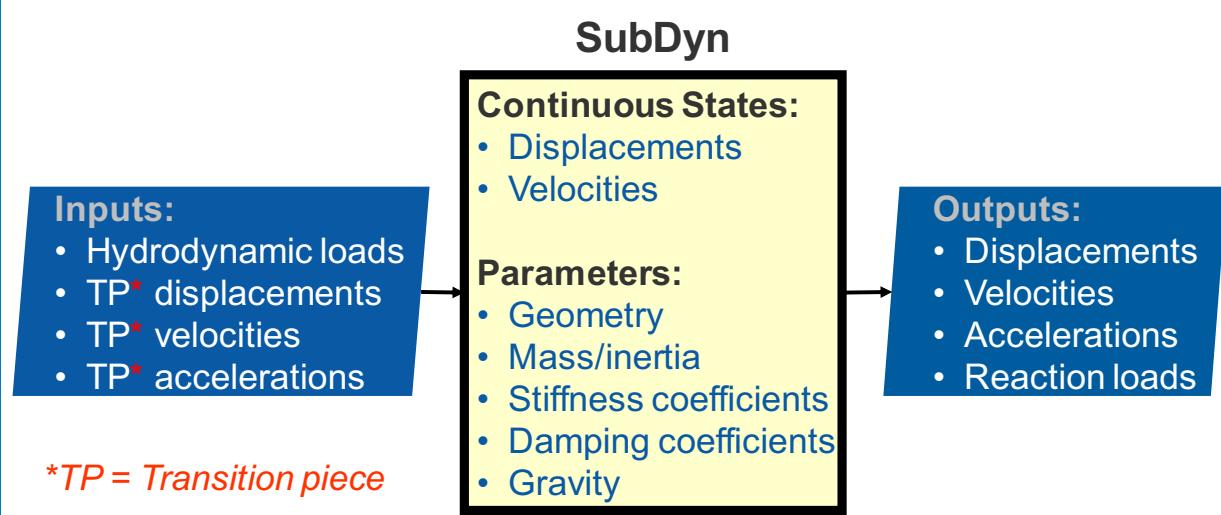
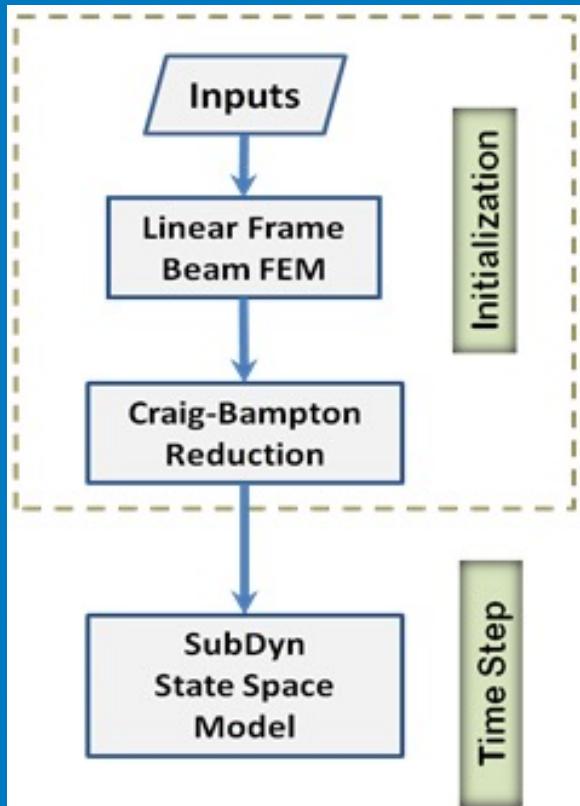
*Sea-Surface Elevation ( $\eta$ ) from the Summing of 1<sup>st</sup>- ( $\eta_1$ ) & 2<sup>nd</sup>- ( $\eta_2$ ) Order Waves*



*IEC Sea Currents*

# SubDyn

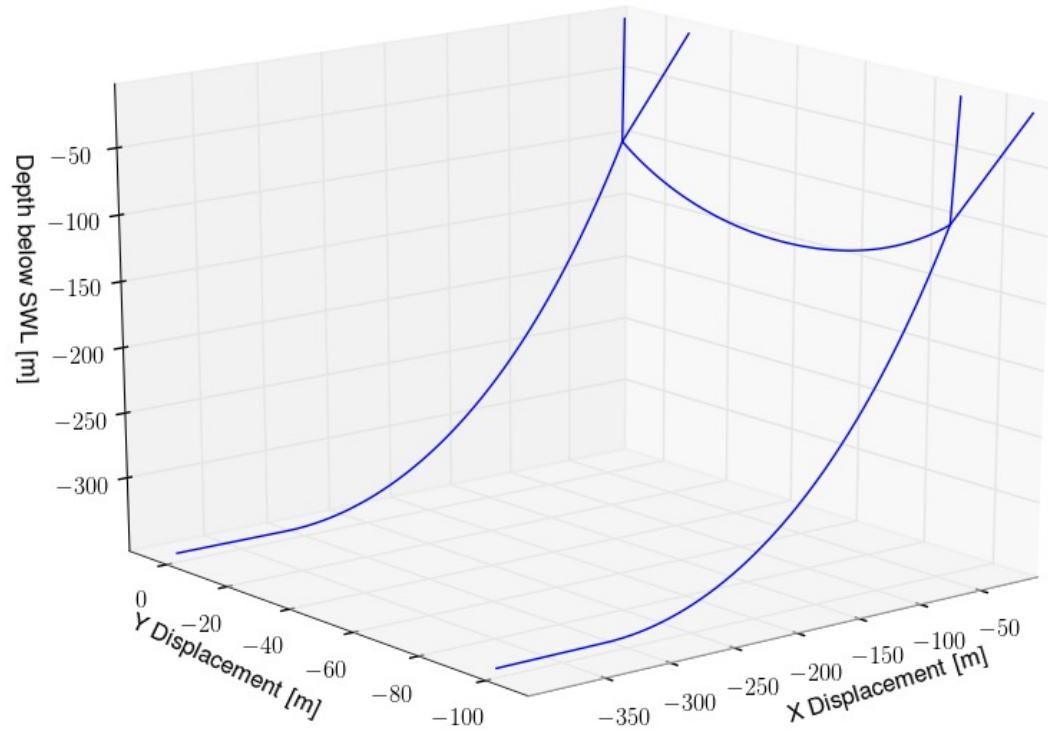
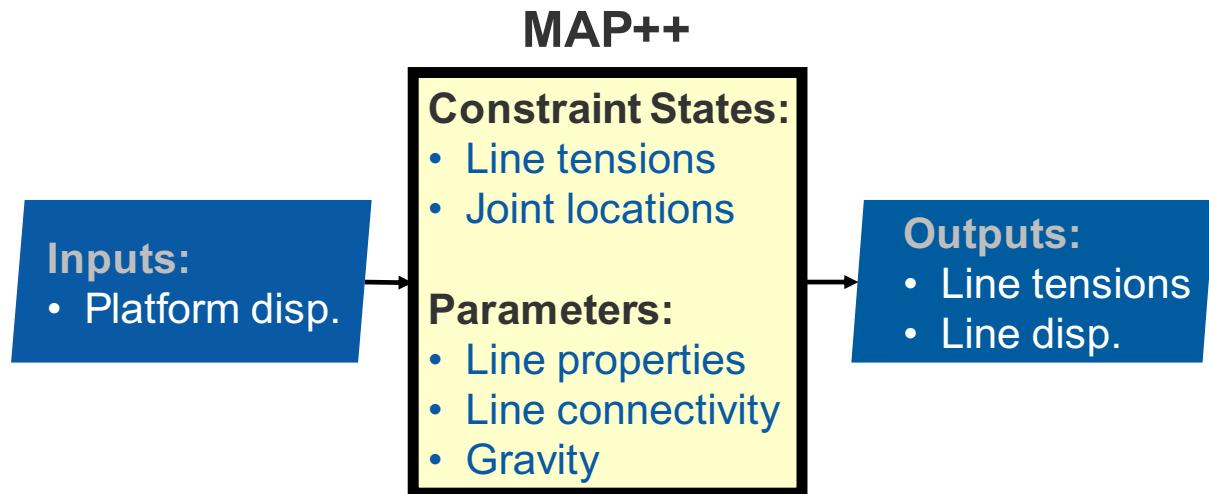
- Linear frame finite-element beam model
- Craig-Bampton dynamic system reduction
- Static-improvement method



*Finite-Element Discretization of the OC3-Tripod*

# MAP++

- Quasi static
- Multi-segmented array of taut or catenary lines
- Elastic stretching
- Apparent weight of lines
- Clump weights & buoyancy tanks
- Seabed friction
- Nonlinear geometric restoring

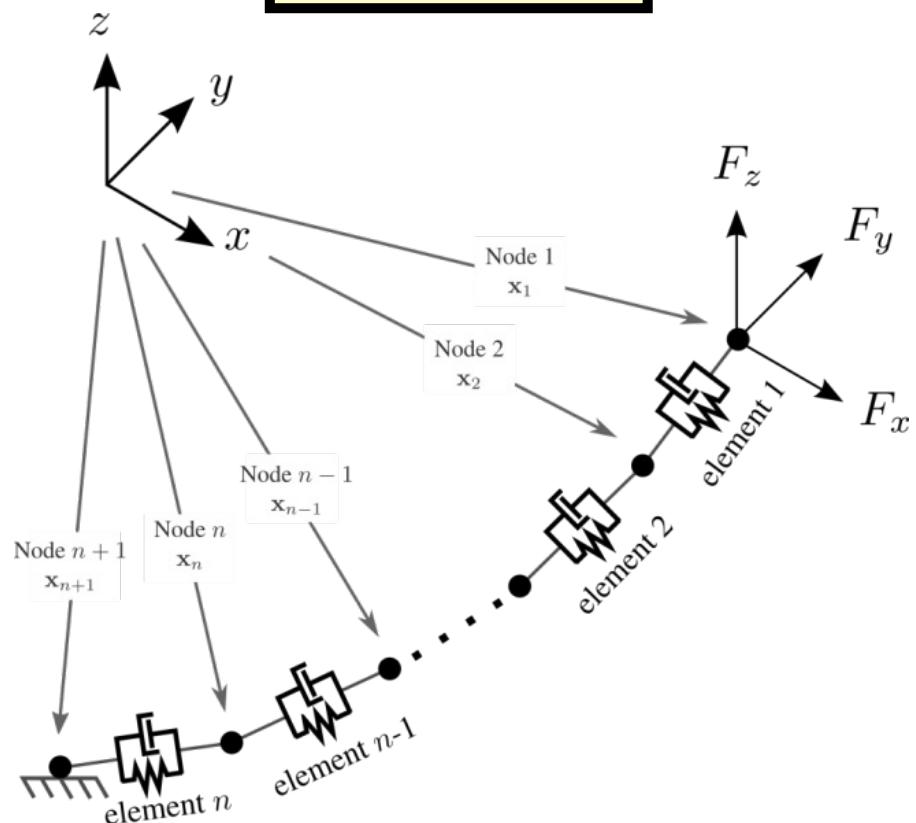
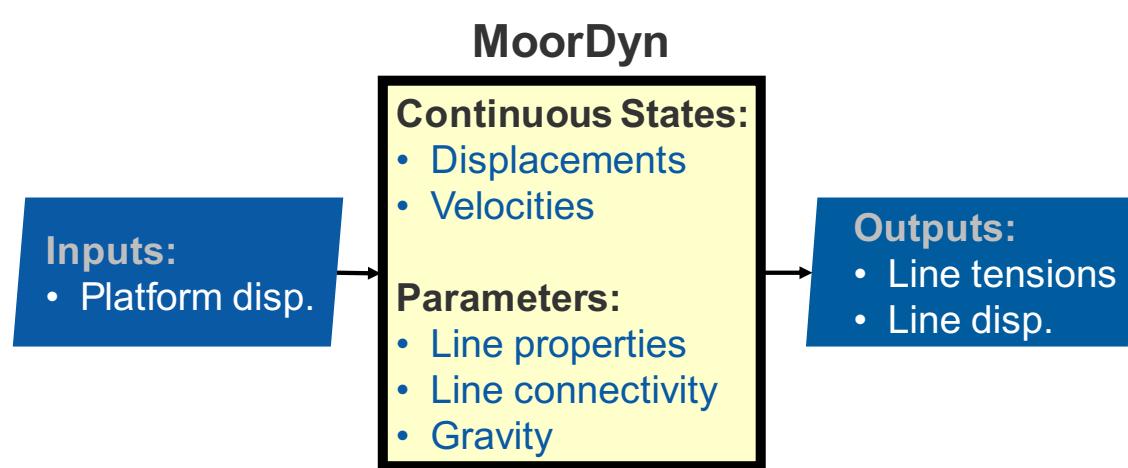


*Example Multi-Segmented Mooring System Analyzed by MAP++*

# MoorDyn

- Lumped-mass dynamics
- Multi-segmented array of taut or catenary lines
- Elastic stretching & damping
- Still-water hydrodynamic added mass & drag
- Apparent weight of lines
- Clump weights & buoyancy tanks
- Seabed friction
- Nonlinear geometric restoring

## MoorDyn



*Lumped-Mass Mooring Dynamics*

# Marine Turbine Features

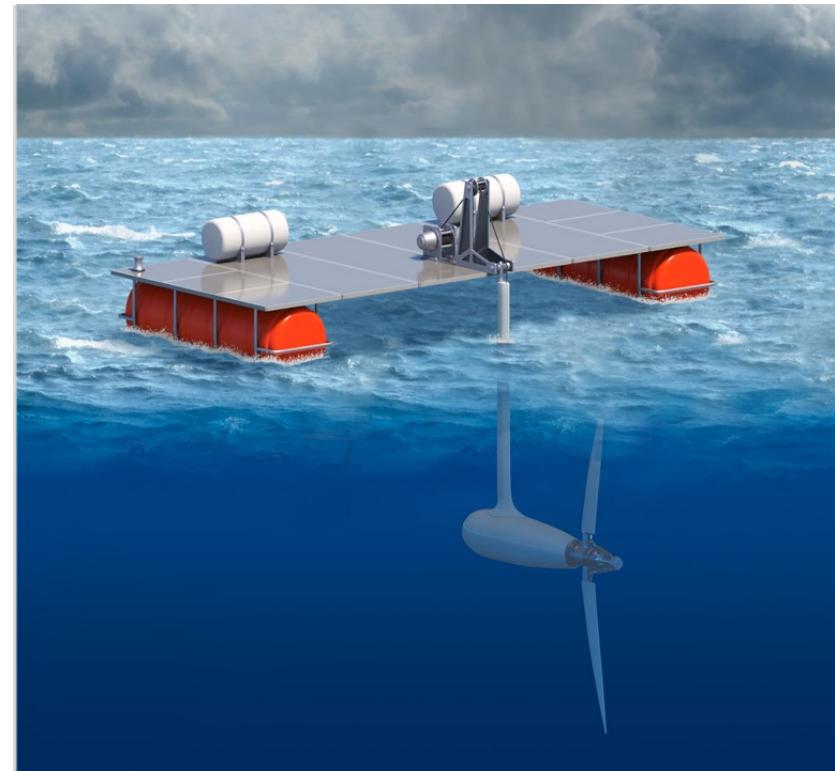
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# Turbine Archetypes: Axial-Flow

Fixed Marine Turbine



Floating Marine Turbine



*Illustration by Besiki Kazaishvili, NREL*

*Illustration by Besiki Kazaishvili, NREL*

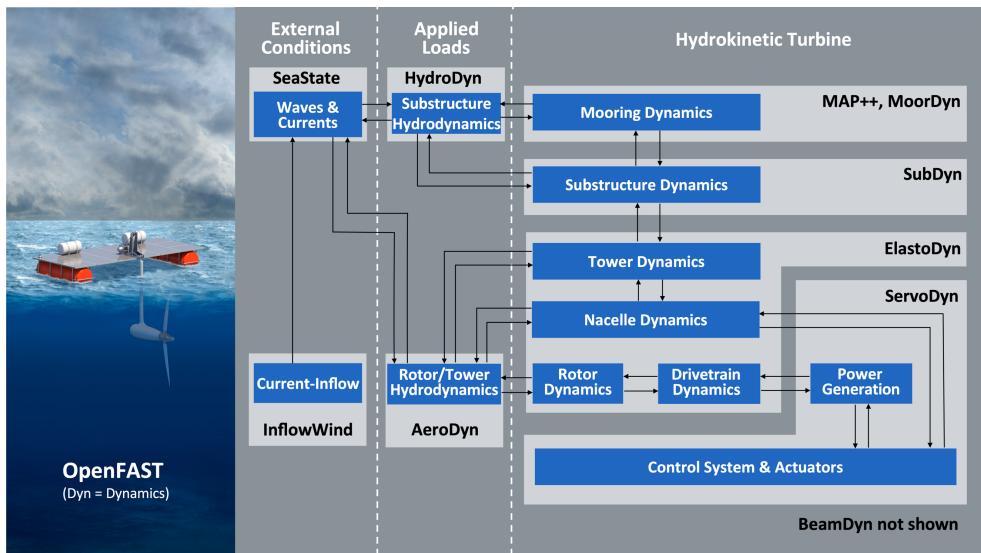
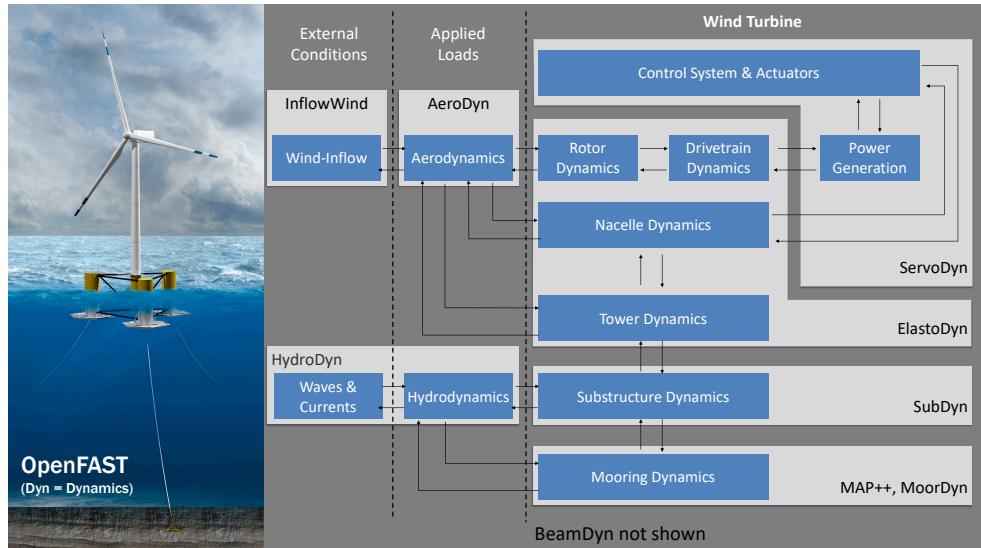
# New Capabilities

## Capture physics of marine turbines

- Cavitation check
- Buoyant loads on blades, support structure, hub, and nacelle
- Added mass loads due to structure motion and deformation (including blade pitch accelerations)
- Inertial loads due to inflow accelerations
- Rotor-nacelle assembly and support structure below sea surface
- Lifting forces on faired components

## Account for wave and current loads on system

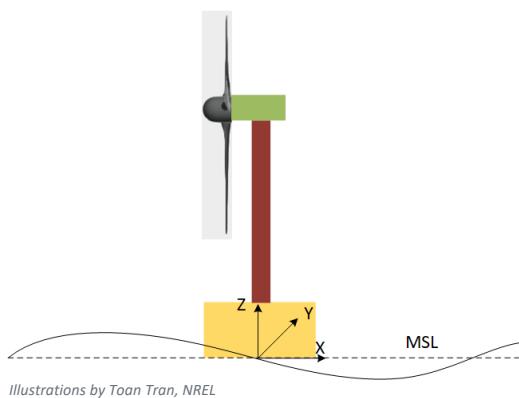
- Inflow accelerations
- Wave and current velocity superposition/coupling



OpenFAST architecture for a floating marine turbine. Illustration by Besiki Kazaishvili, NREL

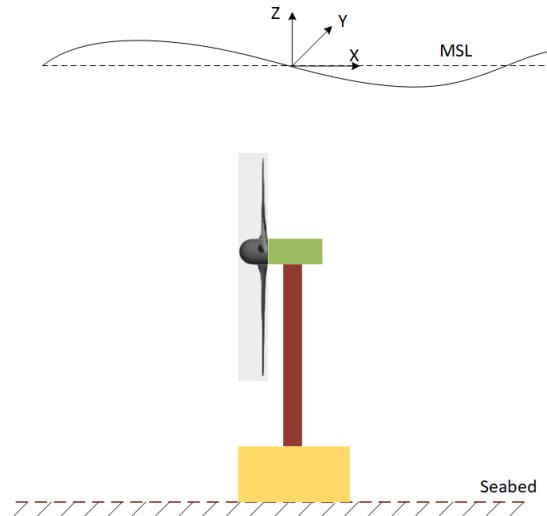
# Coordinate Systems

Floating wind

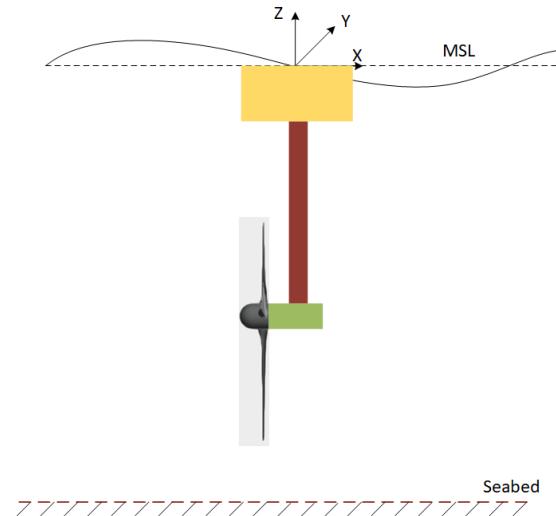


Illustrations by Toan Tran, NREL

Fixed marine



Floating marine



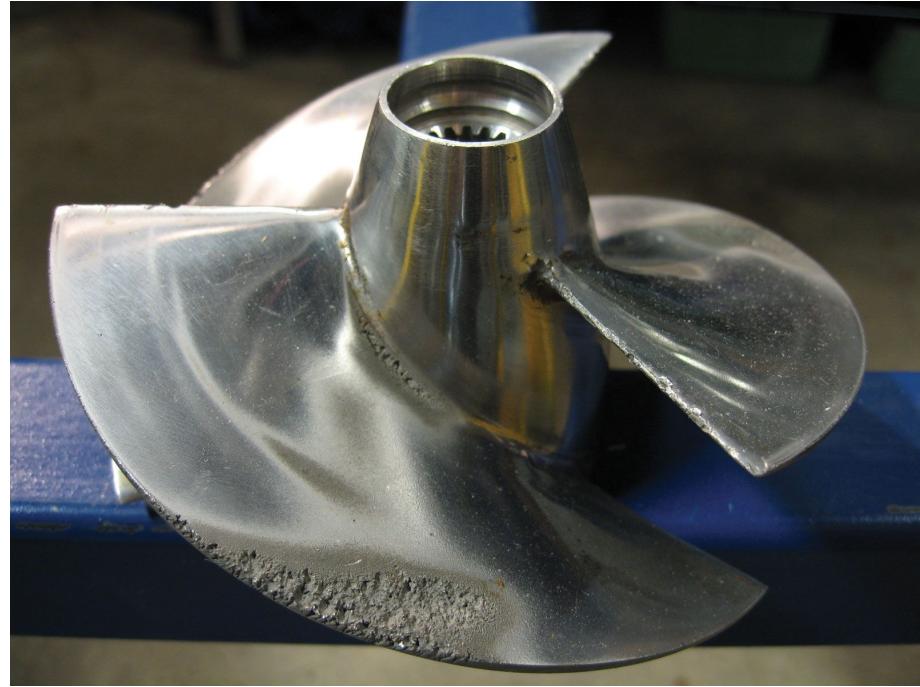
# Cavitation Check

- Checks for cavitation along the span of each blade
- Compares local and critical cavitation numbers
- Cavitation occurs if  $\sigma_{crit} < \sigma_l$

Calculated from

- Atmospheric pressure
- Vapor pressure
- Fluid density
- Gravity
- Rotor depth
- Relative velocity

↑  
User input



Pitted surface of a boat propeller due to cavitation. Image from Erik Axda, Encyclopedia Britannica

# Buoyancy

- Buoyant forces and moments calculated for the blades, hub, nacelle, and support structure
- Offset between load center and center of buoyancy allowed for blades, hub, and nacelle

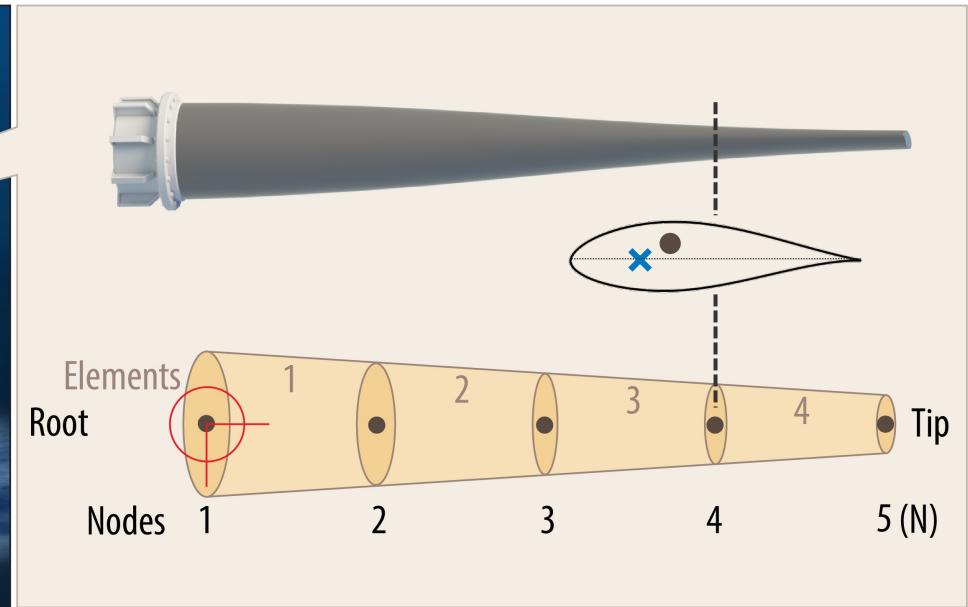
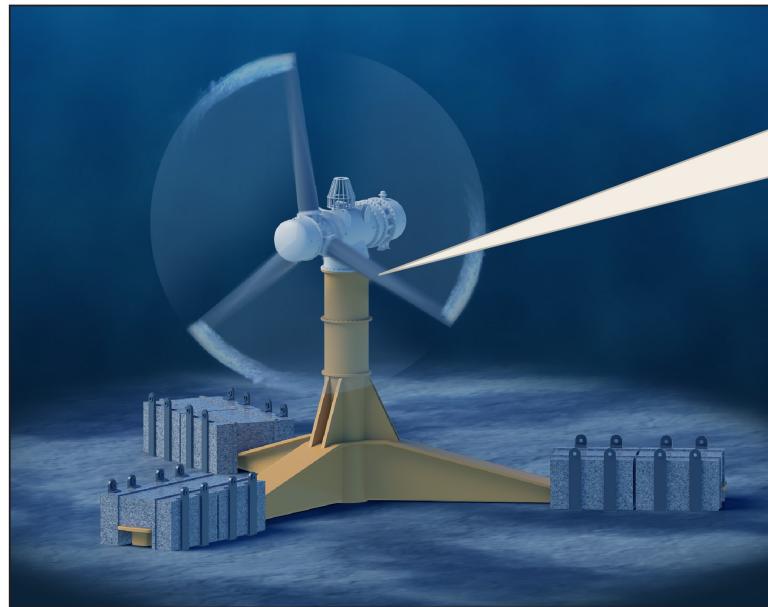
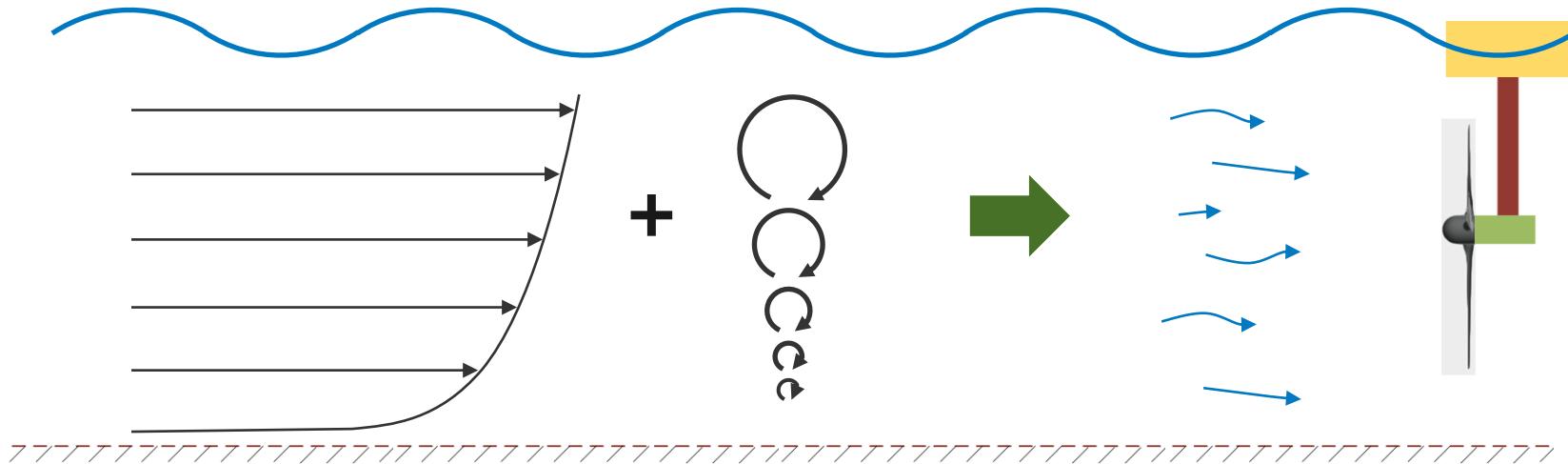


Illustration by Besiki Kazaishvili and Matt Hall, NREL

# Inflow Superposition/Coupling



- Entire system sees a consistent flow field that includes current and wave velocities and accelerations

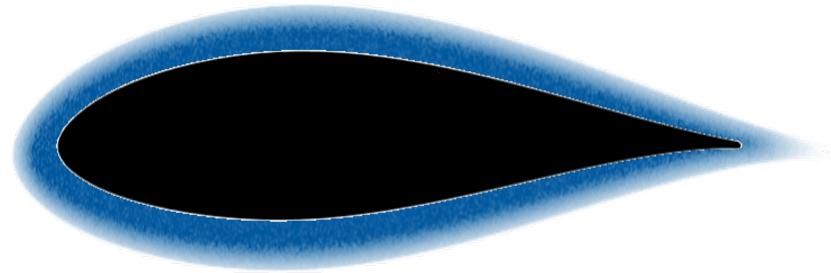
**Superposition:** Linear summation of current and wave velocities

**Coupling:** Current velocities affect wave frequencies

# Added Mass

Added mass loads are considered for

- structure motion
- structure deformation
- blade pitch



Added mass loads are calculated using Morison's equation

$$F = \underbrace{\rho(C_p + C_a)V\dot{u}}_{\text{inertia}} - \underbrace{\rho C_a V\dot{v}}_{\text{added mass}} + \underbrace{\frac{1}{2}\rho C_d A(u - v)|u - v|}_{\text{drag}} \xrightarrow{\text{included in BEM}}$$

$$F_a = -\rho C_a V\dot{v}$$

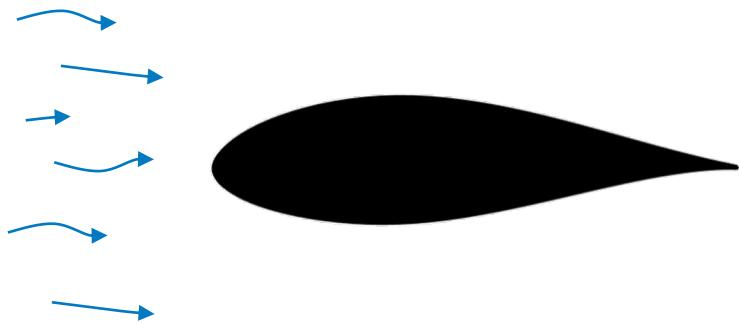
structure acceleration from ElastoDyn/BeamDyn (tight coupling)

user-defined added mass coefficient

# Inertial Loads

Inertial loads are considered for

- turbulent inflow



Inertial loads are calculated using Morison's equation

$$F = \underbrace{\rho(C_p + C_a)V\dot{u}}_{\text{inertia}} - \underbrace{\rho C_a V\dot{v}}_{\text{added mass}} + \underbrace{\frac{1}{2}\rho C_d A(u - v)|u - v|}_{\text{drag}} \xrightarrow{\text{included in BEM}}$$

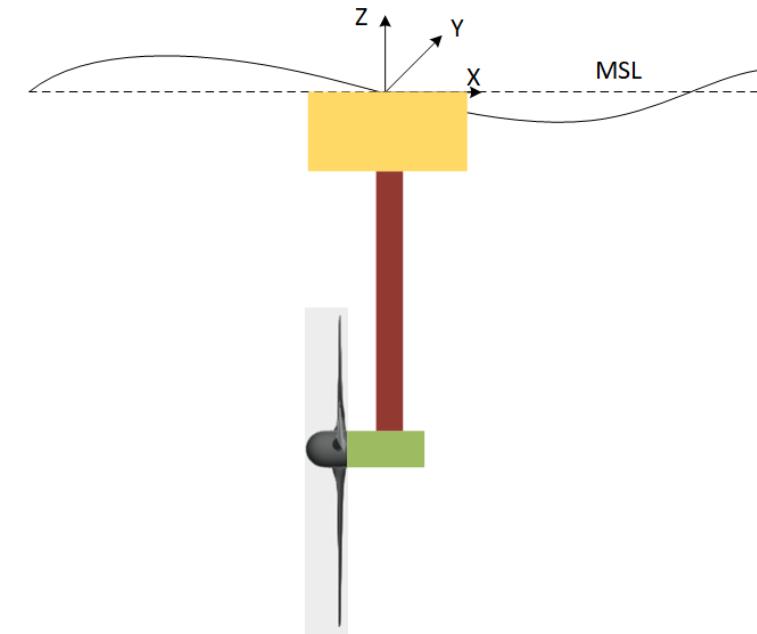
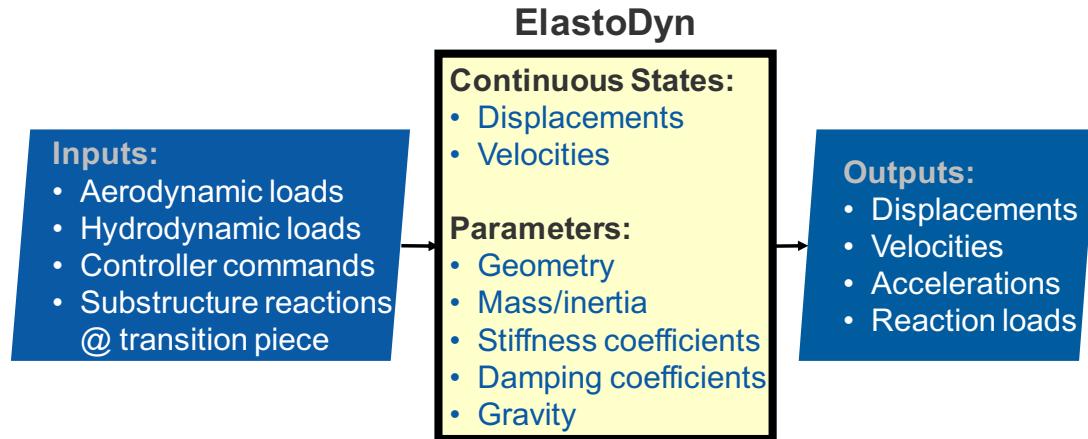
$$F_i = \rho(C_p + C_a)V\dot{u}$$

user-defined dynamic pressure coefficient

inflow acceleration from waves and currents

# ElastoDyn

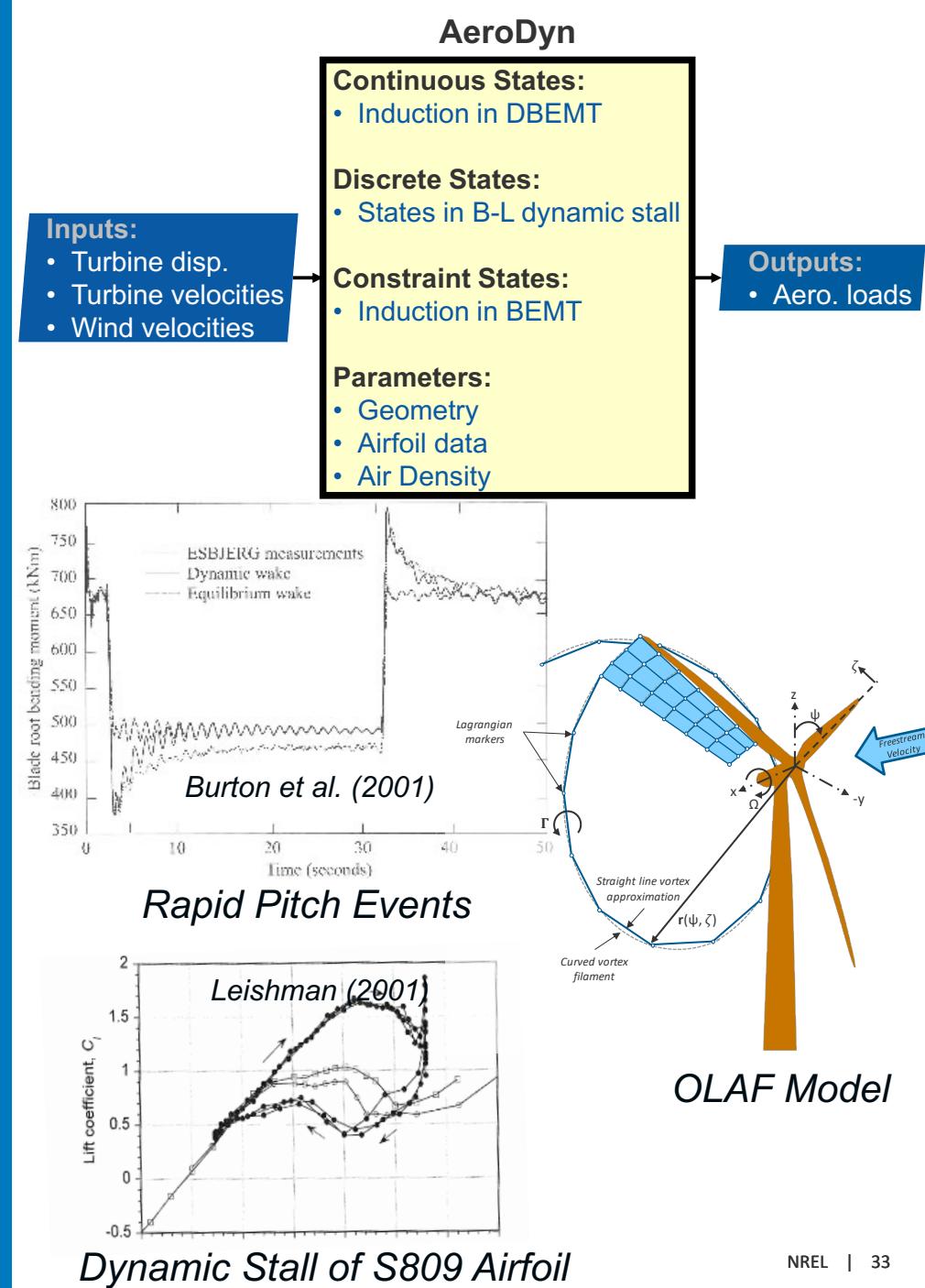
- Turbine configuration:
    - Horizontal-axis (HAWT)
    - 2- or 3-bladed rotor
    - Upwind or downwind rotor
    - Rigid or teetering hub
    - Conventional configuration  
~~or inclusion of rotor and/or tail-furling~~
    - Support structure that includes a (tower) ~~atop~~ above or below a platform
  - Combined modal & multi-body representation through 24 DOFs
    - Modal: blades, tower
    - Multi-body: platform, nacelle, generator, gears, hub, tail



Seabed

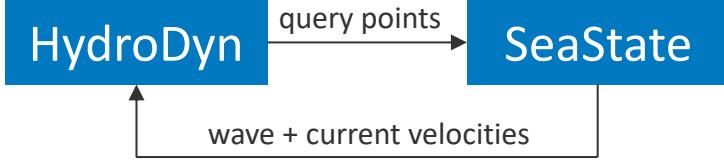
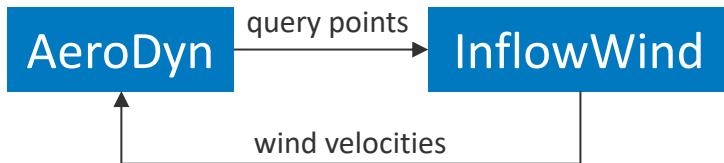
# AeroDyn, including OLAf

- Actuator-line physics
- cOnvecting LAgrangian Filaments (OLAf) model
- Cavitation check
- Buoyant loads
- Added mass } glue code changes
- Inertial loads } (tight coupling)



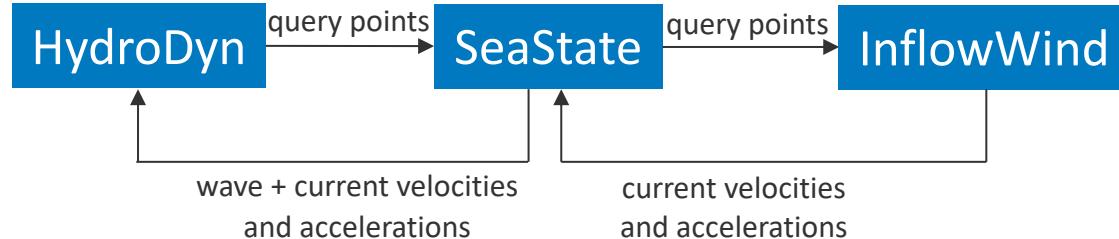
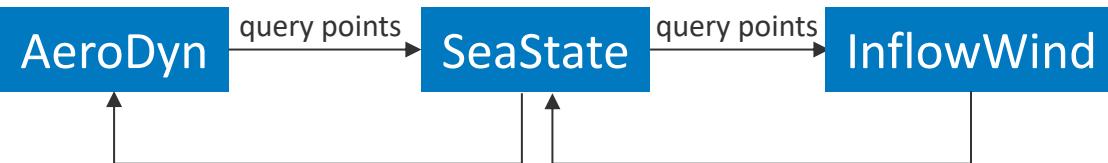
# InflowWind / SeaState

## Wind Turbines



- Rotor and support structure see different flow fields

## Marine Turbines



- All components see the same flow field
- SeaState current must always be set to 0
- For current only cases, SeaState flow field will be set to 0
- For wave only cases, InflowWind will not be called
- Superimposed wave + current velocities will be used for all velocities
- Superimposed wave + current accelerations will be used for inertia loads

# Future Development

---

# Additional Features

- Verification and validation
- Inclusion of additional modeling capabilities
  - Cross-flow turbines (in progress for wind)
  - Wave and current coupling
  - Multi-rotor platforms
  - Flow confinement
  - Rotor and mooring biofouling
  - Varied member cross-sectional shapes
  - Hydroacoustics
  - Other device topologies (e.g., foils and kite devices)
- Other surrogate modeling methods and uses
- Coupling with HFM



Illustration by Besiki Kazaishvili, NREL

# OpenFAST Demonstration: Floating Marine Turbine – Floating RM1 Quad

---

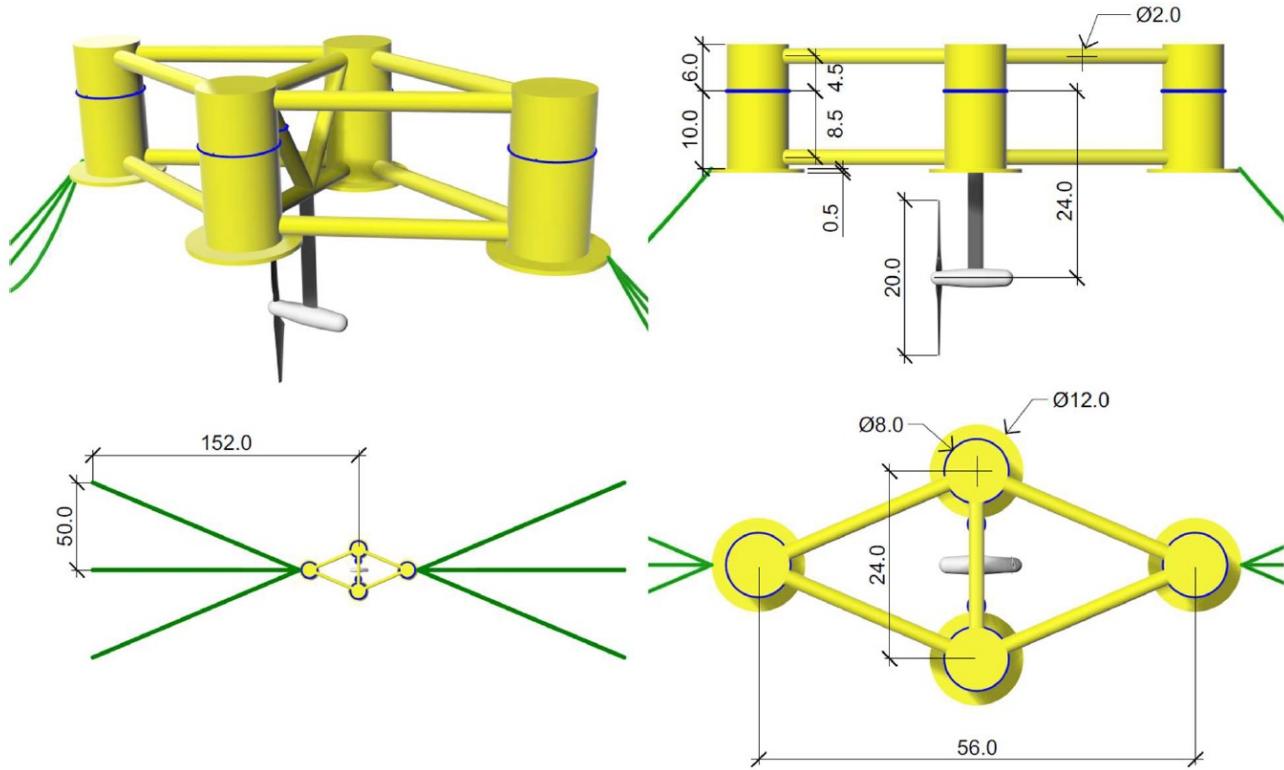
# Outline: OpenFAST Demonstration

- Overview of Floating RM1 Quad
- OpenFAST input files (Floating RM1)
  - ElastoDyn
  - AeroDyn
  - HydroDyn
  - SeaState
  - MoorDyn
  - InflowWind
- Demonstrate running OpenFAST
- Output files
- Time series of results

# Floating RM1 Quad

## RM1 Turbine

- 500 kW reference turbine designed by NREL in 2011
- 2-bladed
- Variable speed – variable pitch
- 20 m rotor diameter
- 1.9 m/s rated speed
- Specifications include:
  - Blade structural + aerodynamic properties
  - Nacelle and hub
  - Drivetrain
  - Operating profile



## Floating Quad Platform

- Robust test platform designed by NREL in 2023
- Similar elements to typical FOWT semisubmersible
  - Large diameter columns
  - Heave plates
  - Catenary mooring system
- Fairied tower

	Platform Structure	Platform Structure + Ballast	Platform Structure + Ballast + Tower & RNA
Mass [kg]	1.050e6	2.525e6	2.588e6
COG [m]	[0.0, 0.0, -5.63]	[0.0, 0.0, -6.09]	[-0.02, 0.0, -6.52]
Ixx [kg·m <sup>2</sup> ]	8.866e7	1.952e8	2.155e8
Iyy [kg·m <sup>2</sup> ]	3.408e8	9.194e8	9.403e8
Izz [kg·m <sup>2</sup> ]	3.691e8	1.054e9	1.054e9

[https://github.com/OpenFAST/r-test/tree/dev/glue-codes/openfast/MHK\\_RM1\\_Floating](https://github.com/OpenFAST/r-test/tree/dev/glue-codes/openfast/MHK_RM1_Floating)

# OpenFAST Modules

- ElastoDyn — Structural dynamics
- BeamDyn
- AeroDyn — Turbine hydrodynamics
- InflowWind — Current inflow
- SeaState — Wave and current field
- ServoDyn
- HydroDyn — Platform hydrodynamics
- SubDyn
- MoorDyn — Dynamic mooring
- MAP++
- FEAMooring
- OrcaFlexInterface
- IceFloe
- IceDyn

- Steady, 1.9 m/s current
- Power law shear
- No control
- Fixed rotational speed
- Blade, tower, and drivetrain DOFs

# OpenFAST Input File Format

```
----- OpenFAST EXAMPLE INPUT FILE -----
Floating MHK turbine, based on the RM1 tidal current rotor
----- SIMULATION CONTROL -----
False
"FATAL"
      6
0.003
      2
      5
99999
1000000
Echo
AbortLevel
TMax
DT
InterpOrder
NumCrctn
DT_UJac
UJacSclFact
- Echo input data to <RootName>.ech (flag)
- Error level when simulation should abort (string) {"WARNING", "SEVERE", "FATAL"}
- Total run time (s)
- Recommended module time step (s)
- Interpolation order for input/output time history (-) {1=linear, 2=quadratic}
- Number of correction iterations (-) {0=explicit calculation, i.e., no corrections}
- Time between calls to get Jacobians (s)
- Scaling factor used in Jacobians (-)
```

- **Description**
  - Brief description, including options/units
- **Keyword**
  - Variable name/identifier
- **Value**
  - Numerical, logical, flag, or string

# OpenFAST Driver Input File

```
----- OpenFAST EXAMPLE INPUT FILE -----
Floating MHK turbine, based on the RM1 tidal current rotor
----- SIMULATION CONTROL -----
False      Echo          - Echo input data to <RootName>.ech (flag)
"FATAL"    AbortLevel   - Error level when simulation should abort (string) {"WARNING", "SEVERE", "FATAL"}
6          Tmax          - Total run time (s)
0.003     DT             - Recommended module time step (s)
2          InterpOrder   - Interpolation order for input/output time history (-) {1=linear, 2=quadratic}
5          NumCrcn      - Number of correction iterations (-) {0=explicit calculation, i.e., no corrections}
99999     DT_UJac       - Time between calls to get Jacobians (s)
1000000   UJacSclFact  - Scaling factor used in Jacobians (-)
----- FEATURE SWITCHES AND FLAGS -----
1          CompElast     - Compute structural dynamics (switch) {1=ElastoDyn; 2=ElastoDyn + BeamDyn for blades}
1          CompInflow    - Compute inflow wind velocities (switch) {0=still air; 1=InflowWind; 2=external from OpenFOAM}
2          CompAero       - Compute aerodynamic loads (switch) {0=None; 1=AeroDyn v14; 2=AeroDyn v15}
0          CompServo     - Compute control and electrical-drive dynamics (switch) {0=None; 1=ServoDyn}
1          CompSeaSt    - Compute sea state response (switch) {0=None; 1=SeaDyn}
1          CompHydro     - Compute hydrodynamic loads (switch) {0=None; 1=HydroDyn}
0          CompSub       - Compute submerged volume (switch) {0=None; 1=SubDyn}
3          CompMooring   - Compute mooring loads (switch) {0=None; 1=MooringDyn}
0          CompIce       - Compute ice interaction loads (switch) {0=None; 1=IceDyn}
2          MHK           - MHK turbine (switch) {0=None; 1=MHK}
----- ENVIRONMENTAL CONDITIONS -----
9.80665  Gravity       - Gravitational acceleration (m/s^2)
1.225    AirDens       - Air density (kg/m^3)
1025     WtrDens       - Water density (kg/m^3)
1.06E-06  KinVisc      - Kinematic viscosity of working fluid (m^2/s)
1500     SpdSound      - Speed of sound in working fluid (m/s)
101325   Patm          - Atmospheric pressure (Pa) [used only for an MHK turbine cavitation check]
2500     Pvap          - Vapour pressure of working fluid (Pa) [used only for an MHK turbine cavitation check]
50       WtrDpth       - Water depth (m)
0        MSL2SWL       - Offset between still-water level and mean sea level (m) [positive upward]
```

**TMax** should allow convergence  
**DT** should resolve structural frequencies ( $\leq 1/10$  of the highest frequency DOF)

ine

# OpenFAST Driver Input File

```
----- OpenFAST EXAMPLE INPUT FILE -----
Floating MHK turbine, based on the RM1 tidal current rotor
----- SIMULATION CONTROL -----
False      Echo          - Echo input data to <RootName>.ech (flag)
"FATAL"    AbortLevel   - Error level when simulation should abort (string) {"WARNING", "SEVERE", "FATAL"}
       6   Tmax          - Total run time (s)
0.003     DT            - Recommended module time step (s)
       2   InterpOrder   - Interpolation order for input/output time history (-) {1=linear, 2=quadratic}
       5   NumCrcn      - Number of correction iterations (-) {0=explicit calculation, i.e., no corrections}
99999     DT_UJac      - Time between calls to get Jacobians (s)
1000000   UJacSclFact - Scaling factor used in Jacobians (-)
----- FEATURE SWITCHES AND FLAGS -----
1   CompElast      - Computer ElastoDyn
1   CompInflow      - Computer Inflow set by InflowWind
2   CompAero         - Computer Aerodynamics computed by AeroDyn15
0   CompServo        - Computer Servo
1   CompSeaSt        - Computer Full grid wave field with SeaState
1   CompHydro        - Computer Hydrodynamic platform forces
0   CompSub          - Computer Substructure
3   CompMooring      - Computer Dynamic mooring with MoorDyn
0   CompIce          - Computer Ice
2   MHK             - MHK turbine
• CompElast=1: ElastoDyn without BeamDyn
• CompInflow=1: Inflow set by InflowWind
CompAero=2: Aerodynamics computed by AeroDyn15
CompSeaSt=1: Full grid wave field with SeaState
CompHydro=1: Hydrodynamic platform forces
CompMooring=3: Dynamic mooring with MoorDyn
MHK=2: Floating marine turbine
----- ENVIRONMENTAL -----
9.80665  Gravity       - Gravity
1.225    AirDens       - Air density (kg/m^3)
1025     WtrDens       - Water density (kg/m^3)
1.06E-06  KinVisc       - Kinematic viscosity of working fluid (m^2/s)
1500     SpdSound      - Speed of sound in working fluid (m/s)
101325   Patm          - Atmospheric pressure (Pa) [used only for an MHK turbine cavitation check]
2500     Pvap          - Vapour pressure of working fluid (Pa) [used only for an MHK turbine cavitation check]
50      WtrDpth        - Water depth (m)
0       MSL2SWL        - Offset between still-water level and mean sea level (m) [positive upward]
```

# OpenFAST Driver Input File

```
--> FEATURE SWITCHES AND FLAGS <-->
  1 CompElast      - Compute structural dynamics (switch) {1=ElastoDyn; 2=ElastoDyn + BeamDyn for blades}
  1 CompInflow     - Compute inflow wind velocities (switch) {0=still air; 1=InflowWind; 2=external from OpenFOAM}
  2 CompAero       - Compute aerodynamic loads (switch) {0=None; 1=AeroDyn v14; 2=AeroDyn v15}
  0 CompServo      - Compute control and electrical-drive dynamics (switch) {0=None; 1=ServoDyn}
  1 CompSeast      - Compute sea state information (switch) {0=None; 1=SeaState}
  1 CompHydro      - Compute hydrodynamic loads (switch) {0=None; 1=HydroDyn}
  0 CompSub        - Compute sub-structural dynamics (switch) {0=None; 1=SubDyn; 2=External Platform MCKF}
  3 CompMooring    - Compute mooring system (switch) {0=None; 1=MAP++; 2=FEAMooring; 3=MoorDyn; 4=OrcaFlex}
  0 CompIce         - Compute ice loads (switch) {0=None; 1=IceFlo; 2=IceDyn}
  2 MHK            - MHK turbine type (switch) {0=Not an MHK turbine; 1=Fixed MHK turbine; 2=Floating MHK turbine}

--> ENVIRONMENTAL CONDITIONS <-->
  9.80665 Gravity      - Gravitational acceleration (m/s^2)
  1.225 AirDens      - Air density (kg/m^3)
  1025 WtrDens      - Water density (kg/m^3)
  1.06E-06 KinVisc      - Kinematic viscosity of working fluid (m^2/s)
  1500 SpdSound      - Speed of sound (m/s)
  101325 Patm         - Atmospheric pressure (Pa)
  2500 Pvap          - Vapour pressure (Pa)
  50 WtDepth        - Water depth (m)
  0 MSL2SWL         - Offset between MSL and SWL (m)

--> INPUT FILES <-->
"MHK_RM1_Floating_ElastoDyn.dat"   EDFile           - Name of file containing ElastoDyn input parameters (quoted string)
"unused"      BDBldFile(1)        - Name of file containing BeamDyn input parameters for blade 1 (quoted string)
"unused"      BDBldFile(2)        - Name of file containing BeamDyn input parameters for blade 2 (quoted string)
"unused"      BDBldFile(3)        - Name of file containing BeamDyn input parameters for blade 3 (quoted string)
"MHK_RM1_Floating_InflowWind.dat"  InflowFile      - Name of file containing inflow wind input parameters (quoted string)
"MHK_RM1_Floating_AeroDyn15.dat"   AeroFile        - Name of file containing aerodynamic input parameters (quoted string)
"unused"      ServoFile        - Name of file containing control and electrical-drive input parameters (quoted string)
"SeaState.dat"  SeaStFile       - Name of file containing sea state input parameters (quoted string)
"MHK_RM1_Floating_HydroDyn.dat"   HydroFile       - Name of file containing hydrodynamic input parameters (quoted string)
"unused"      SubFile          - Name of file containing sub-structural input parameters (quoted string)
"MHK_RM1_Floating_MoorDyn.dat"   MooringFile     - Name of file containing mooring system input parameters (quoted string)
"unused"      IceFile          - Name of file containing ice input parameters (quoted string)
```

- Specify module primary input files
  - Path relative to folder containing .fst file
- Unused modules not specified

# OpenFAST Driver Input File

----- OUTPUT -----		
True	SumPrint	- Print summary data to "<RootName>.sum" (flag)
5	SttsTime	- Amount of time between screen status messages (s)
99999	ChkptTime	- Amount of time between creating checkpoint files for potential restart (s)
0.03	DT_Out	- Time step for tabular output (s) (or "default")
0	tStart	- Time to begin tabular output (s)
3	OutFileFmt	- Format for tabular (time-marching) output file (switch) {1: text file [<RootName>.out], 2: binary file}
True	TabDelim	- Use tab delimiters in text tabular output file? (flag) {uses spaces if false}
"ES10.3E2"	OutFmt	- Format used for text tabular output, excluding the time channel. Resulting field should be 10 characters
----- LINEARIZATION -----		
False	Linearize	- Linearize
False	CalcSteady	- Calculate steady state
1	TrimCase	- Control trim case
0.01	TrimTol	- Tolerance for trim
0.01	TrimGain	- Proporional gain for trim
0	Twr_Kdmp	- Damping factor for trim
0	Bld_Kdmp	- Damping factor for trim
0	NLinTimes	- Number of linearization times
0	LinTimes	- List of linearization times
0	LinInputs	- Inputs for linearization
0	LinOutputs	- Outputs for linearization
False	LinOutJac	- Include full Jacobian in linearization output (for debug) [disabled if Linearize=False; used only if CalcSteady=True]
False	LinOutMod	- Write module-level linearization output files in addition to output for full system? (flag) [unused if Linearize=False]
----- VISUALIZATION -----		
0	WrVTK	- VTK visualization data output: (switch) {0=none; 1=initialization data only; 2=animation; 3=mode shape}
1	VTK_type	- Type of VTK visualization data: (switch) {1=surfaces; 2=basic meshes (lines/points); 3=all meshes (debris)}
False	VTK_fields	- Write mesh fields to VTK data files? (flag) {true/false} [unused if WrVTK=0]
0	VTK_fps	- Frame rate for VTK output (frames per second){will use closest integer multiple of DT} [used only if WrVTK>0]

- Summary file prints inputs as read by the code
  - Useful for debugging inputs
- **SttsTime** should balance screen updates with time required to write to screen
- **DT\_Out** can downsample calculated values when writing to file

```
linearize=False] (flag)
dy=True] (-)

(rad/(rad/s) for

true and calcSteady
debug}) [unused if
outputs (debug)] [
linearize=False; used on

true and calcSteady
debug}) [unused if
outputs (debug)] [
linearize=False; used on

true and calcSteady
debug}) [unused if
outputs (debug)] [
linearize=False; used on
```

# OpenFAST Driver Input File

```
----- OUTPUT -----
True      SumPrint      - Print summary data to "<RootName>.sum" (flag)
          5   SttsTime     - Amount of time between screen status messages (s)
99999     ChkptTime    - Amount of time between creating checkpoint files for potential restart (s)
0.03      DT_Out       - Time step for tabular output (s) (or "default")
          0   TStart        - Time to begin tabular output (s)
          3   OutFileFmt   - Format for tabular (time-marching) output file (switch) {1: text file [<RootName>.out], 2: binary file}
True      TabDelim      - Use tab delimiters in text tabular output file? (flag) {uses spaces if false}
"ES10.3E2" OutFmt       - Format used for text tabular output, excluding the time channel. Resulting field should be 10 characters
----- LINEARIZATION -----
False     Linearize     - Linearization analysis (flag)
False     CalcSteady   - Calculate a steady-state periodic operating point before linearization? [unused if Linearize=False] (-)
          1   TrimCase      - Controller parameter to be trimmed {1:yaw; 2:torque; 3:pitch} [used only if CalcSteady=True] (-)
0.01      TrimTol       - Tolerance for the rotational speed convergence [used only if CalcSteady=True] (-)
0.01      TrimGain      - Proportion of trim to be applied to each controller
          0   Twr_Kdmp     - Damping for trim calculation
          0   Bld_Kdmp     - Damping for trim calculation
          0   NLinTimes    - Number of linearizations to perform
          0   LinTimes     - List of controllers to linearize
          0   LinInputs    - Inputs to linearize
          0   LinOutputs   - Outputs from linearized system
          0   LinOutJac    - Include Jacobian matrix in output
          0   LinOutMod    - Write module-level linearization output files in addition to output for full system? (flag) [unused if Linearize=False]
----- VISUALIZATION -----
          0   WrVTK        - VTK visualization data output: (switch) {0=none; 1=initialization data only; 2=animation; 3=mode shape}
          1   VTK_type      - Type of VTK visualization data: (switch) {1=surfaces; 2=basic meshes (lines/points); 3=all meshes (debris)}
False     VTK_fields    - Write mesh fields to VTK data files? (flag) {true/false} [unused if WrVTK=0]
          0   VTK_fps       - Frame rate for VTK output (frames per second){will use closest integer multiple of DT} [used only if WrVTK>0]
```

- **Linearization=True** enables linearization of the full coupled solution
  - Linearized equations can be output for use in other models

# OpenFAST Driver Input File

```
--> OUTPUT
True   SumPrint      - Print summary data to "<RootName>.sum" (flag)
      | 5 SttsTime     - Amount of time between screen status messages (s)
99999  ChkptTime    - Amount of time between creating checkpoint files for potential restart (s)
0.03   DT_Out       - Time step for tabular output (s) (or "default")
      | 0 TStart        - Time to begin tabular output (s)
      | 3 OutFileFmt   - Format for tabular (time-marching) output file (switch) {1: text file [<RootName>.out], 2: binary file}
True   TabDelim      - Use tab delimiters in text tabular output file? (flag) {uses spaces if false}
"ES10.3E2" OutFmt    - Format used for text tabular output, excluding the time channel. Resulting field should be 10 characters

--> LINEARIZATION
False  Linearize     - Linearization analysis (flag)
False  CalcSteady    - Calculate a steady-state periodic operating point before linearization? [unused if Linearize=False] (f)
      | 1 TrimCase     - Controller parameter to be trimmed {1:yaw; 2:torque; 3:pitch} [used only if CalcSteady=True] (-)
0.01   TrimTol       - Tolerance for the rotational speed convergence [used only if CalcSteady=True] (-)
0.01   TrimGain      - Proportional gain for the rotational speed error (>0) [used only if CalcSteady=True] (rad/(rad/s) for
      | 0 Twr_Kdmp     - Damping factor for the tower [used only if CalcSteady=True] (N/(m/s))
      | 0 Bld_Kdmp     - Damping factor for the blades [used only if CalcSteady=True] (N/(m/s))
      | 0 NLinTimes    - Number of times to linearize (-) [>=1] [unused if Linearize=False]
      | 0 LinTimes     - List of times at which to linearize (s) [1 to NLinTimes] [used only when Linearize=True and CalcSteady=True]
      | 0 LinInputs    - Inputs included in linearization (switch) {0=none; 1=standard; 2=all module inputs (debug)} [unused if
      | 0 LinOutputs   - Outputs included in linearization (switch) {0=none; 1=standard; 2=all module outputs (debug)} [unused if
      | LinOutJac     - Include Jacobian matrix in linearization output files? (flag) [0=False; 1=True]
False  LinOutMod     - Write module-level linearization output files in addition to output for full system? (flag) [unused if WrVTK=0]

--> VISUALIZATION
      | 0 WrVTK        - VTK visualization data output: (switch) {0=none; 1=initialization data only; 2=animation; 3=mode shape}
      | 1 VTK_type      - Type of VTK visualization data: (switch) {1=surfaces; 2=basic meshes (lines/points); 3=all meshes (debug)}
False  VTK_fields    - Write mesh fields to VTK data files? (flag) {true/false} [unused if WrVTK=0]
      | 0 VTK_fps       - Frame rate for VTK output (frames per second){will use closest integer multiple of DT} [used only if WrVTK=1]
```

## • Visualization using VTK (Visualization ToolKit)

WrVTK

# ElastoDyn Primary Input File

```
----- ELASTODYN for OpenFAST I  
Floating MHK turbine structural  
----- SIMULATION  
False | | | | 3 Echo Method - Echo  
"default" DT - Inte - Inte  
----- DEGREES OF FREEDOM -----
```

- Blade and tower bending DOFs enabled
- Platform 6 DOFs enabled
- Generator and yaw DOFs disabled
  - Fixed RPM specified
- Teeter and platform DOFs not applicable

True	FlapDOF1
True	FlapDOF2
True	EdgeDOF
False	TeetDOF
True	DrTrDOF
False	GenDOF
False	YawDOF
True	TwFADOF1
True	TwFADOF2
True	TwSSDOF1
True	TwSSDOF2
True	PtfmSgDOF
True	PtfmSwDOF
True	PtfmHvDOF
True	PtfmRDOF
True	PtfmPDOF
True	PtfmYDOF

- First flapwise blade mode DOF (flag)
- Second flapwise blade mode DOF (flag)
- First edgewise blade mode DOF (flag)
- Rotor-teeter DOF (flag) [unused for 3 blades]
- Drivetrain **rotational-flexibility** DOF (flag)
- Generator DOF (flag)
- Yaw DOF (flag)
- First fore-aft tower bending-mode DOF (flag)
- Second fore-aft tower bending-mode DOF (flag)
- First side-to-side tower bending-mode DOF (flag)
- Second side-to-side tower bending-mode DOF (flag)
- Platform horizontal surge translation DOF (flag)
- Platform horizontal sway translation DOF (flag)
- Platform vertical heave translation DOF (flag)
- Platform roll tilt rotation DOF (flag)
- Platform pitch tilt rotation DOF (flag)
- Platform yaw rotation DOF (flag)

# ElastoDyn Primary Input File

```
----- INITIAL CONDITIONS -----  
0 OoPDefl - Initial out-of-plane blade-tip displacement (meters)  
0 IPDefl - Initial in-plane blade-tip deflection (meters)  
0 BlPitch(1) - Blade 1 initial pitch (degrees)  
0 BlPitch(2) - Blade 2 initial pitch (degrees)  
0 BlPitch(3) - Blade 3 initial pitch (degrees) [unused for 2 blades]  
0 TeetDefl - Initial or fixed teeter angle (degrees) [unused for 3 blades]  
0 Azimuth - Initial azimuth angle for blade 1 (degrees)  
11.5 RotSpeed - Initial or fixed rotor speed (rpm)  
0 NacYaw - Initial or fixed nacelle-yaw angle (degrees)  
0 TTDspFA - Initial fore-aft tower-top displacement (meters)  
0 TTDspSS - Initial side-to-side tower-top displacement (meters)  
20 PtfrmSurge - Initial or fixed horizontal surge translational displacement of platform (meters)  
0 PtfrmSway - Initial or fixed horizontal sway translational displacement of platform (meters)  
0 PtfrmHeave - Initial or fixed vertical heave translational displacement of platform (meters)  
0 PtfrmRoll - Initial or fixed roll tilt rotational displacement of platform (degrees)  
0 PtfrmPitch - Initial or fixed pitch tilt rotational displacement of platform (degrees)  
0 PtfrmYaw - Initial or fixed yaw rotational displacement of platform (degrees)
```

- Specify initial angles, displacements, and motions
- Fixed rotor speed of rated 11.5 rpm
- Initial surge based on rated thrust

# ElastoDyn Primary Input File

## TURBINE CONFIGURATION

2	NumBl	- Number of blades (-)
10	TipRad	- The distance from the rotor apex to the blade tip (meters)
1	HubRad	- The distance from the rotor apex to the blade root (meters)
0	PreCone(1)	- Blade 1 cone angle (degrees)
0	PreCone(2)	- Blade 2 cone angle (degrees)
0	PreCone(3)	- Blade 3 cone angle (degrees) [unused for 2 blades]
0.2222	HubCM	- Distance from rotor apex to hub mass [positive downwind] (meters)
0	UndSling	- Undersling length [distance from teeter pin to the rotor apex] (meters) [unused for 3 blades]
0	Delta3	- Delta-3 angle for teetering rotors (degrees) [unused for 3 blades]
0	AzimB1Up	- Azimuth value to use for I/O when blade 1 points up (degrees)
-4.91	OverHang	- Distance from yaw axis to rotor apex [3 blades] or teeter pin [2 blades] (meters)
0	ShftGagL	- Distance from rotor apex [3 blades] or teeter pin [2 blades] to shaft strain gages [positive for upwind]
0	ShftTilt	- Rotor shaft tilt angle (degrees)
0.43	NacCMxn	- Downwind distance from the tower-top to the nacelle CM (meters)
0	NacCMyn	- Lateral distance from the tower-top to the nacelle CM (meters)
-1.2	NacCMzn	- Vertical distance from the tower-top to the nacelle CM (meters)
0	NcIMUxn	- Downwind distance from the tower-top to the nacelle IMU (meters)
0	NcIMUyn	- Lateral distance from the tower-top to the nacelle IMU (meters)
-1.2	NcIMUzn	- Vertical distance from the tower-top to the nacelle IMU (meters)
-1.2	Twr2Shft	- Vertical distance from the tower-top to the rotor shaft (meters)
-24	TowerHt	- Height of tower relative to ground level [onshore], MSL [offshore wind or floating MHK], or seabed [fixed]
-9	TowerBsHt	- Height of tower base relative to ground level [onshore], MSL [offshore wind or floating MHK], or seabed [fixed]
0	PtfmCMxt	- Downwind distance from the ground level [onshore], MSL [offshore wind or floating MHK], or seabed [fixed]
0	PtfmCMyt	- Lateral distance from the ground level [onshore], MSL [offshore wind or floating MHK], or seabed [fixed]
-6.09	PtfmCMzt	- Vertical distance from the ground level [onshore], MSL [offshore wind or floating MHK], or seabed [fixed]
0	PtfmRefzt	- Vertical distance from the ground level [onshore], MSL [offshore wind or floating MHK], or seabed [fixed]

- Specify turbine geometry
- Platform COG

# ElastoDyn Primary Input File

```
-- MASS AND INERTIA --
0   TipMass(1)      - Tip-brake mass, blade 1 (kg)
0   TipMass(2)      - Tip-brake mass, blade 2 (kg)
0   TipMass(3)      - Tip-brake mass, blade 3 (kg) [unused for 2 blades]
140  HubMass        - Hub mass (kg)
79.6  HubIner       - Hub inertia about rotor axis [3 blades] or teeter axis [2 blades] (kg m^2)
139.5 GenIner       - Generator inertia about HSS (kg m^2)
40100 NacMass        - Nacelle mass (kg)
244643 NacYIner     - Nacelle inertia about yaw axis (kg m^2)
          | 0 YawBrMass    - Yaw bearing mass (kg)
2525214 PtfmMass     - Platform mass (kg)
195242474 PtfmRIner   - Platform inertia for roll tilt rotation about the platform CM (kg m^2)
919435755 PtfmPIner   - Platform inertia for pitch tilt rotation about the platform CM (kg m^2)
1053535885 PtfmYIner   - Platform inertia for yaw rotation about the platform CM (kg m^2)
```

- Specify turbine mass and inertia
- Specify platform mass and inertia

# ElastoDyn Primary Input File

- Specify blade structural input files
- **BldFile(3)** ignored for 2-bladed rotor

```
|----- PERIMETER -----| Parameters needed for yaw rotation about the platform on (Rg = z) |
----- BLADE -----|
  8  BldNodes   - Number of blade nodes (per blade) used for analysis (-)
"MHK_RM1_ElastoDyn_Blade.dat"    BldFile(1)  - Name of file containing properties for blade 1 (quoted string)
"MHK_RM1_ElastoDyn_Blade.dat"    BldFile(2)  - Name of file containing properties for blade 2 (quoted string)
"unused"      BldFile(3)  - Name of file containing properties for blade 3 (quoted string) [unused for 2 blades]
```

# ElastoDyn Primary Input File

```
-- BLADE --
  8 BldNodes      - Number of blade nodes (per blade) used for analysis (-)
"MHK_RM1_ElastoDyn_Blade.dat"    BldFile(1)  - Name of file containing properties for blade 1 (quoted string)
"MHK_RM1_ElastoDyn_Blade.dat"    BldFile(2)  - Name of file containing properties for blade 2 (quoted string)
"unused"        BldFile(3)  - Name of file containing properties for blade 3 (quoted string) [unused for 2 blades]
-- ROTOR-TEETER --
  0 TeetMod       - Rotor-teeter spring/damper model {0: none, 1: standard, 2: user-defined from routine UserTeet} (switch) [u]
  0 TeetDmpP      - Rotor-teeter damper position (degrees) [used only for 2 blades and when TeetMod=1]
  0 TeetDmp       - Rotor-teeter damping constant (N-m/(rad/s)) [used only for 2 blades and when TeetMod=1]
  0 TeetCDmp      - Rotor-teeter rate-independent Coulomb-damping moment (N-m) [used only for 2 blades and when TeetMod=1]
  0 TeetSStP      - Rotor-teeter soft-stop position (degrees) [used only for 2 blades and when TeetMod=1]
  0 TeetHStP      - Rotor-teeter hard-stop position (degrees) [used only for 2 blades and when TeetMod=1]
  0 TeetSSSp      - Rotor-teeter soft-stop linear-spring constant (N-m/rad) [used only for 2 blades and when TeetMod=1]
  0 TeetHSSp      - Rotor-teeter hard-stop linear-spring constant (N-m/rad) [used only for 2 blades and when TeetMod=1]
-- DRIVETRAIN --
  92 GBoxEff      - Gearbox efficiency (%)
  53 GBRatio      - Gearbox ratio (-)
 600000 DTTorSpr   - Drivetrain torsional spring (N-m/rad)
100000 DTTorDmp   - Drivetrain torsional damper (N-m/(rad/s))
```

- Specifications for teetering rotors

# ElastoDyn Primary Input File

```
-- BLADE --
  8 BldNodes    - Number of blade nodes (per blade) used for analysis (-)
"MHK_RM1_ElastoDyn_Blade.dat"   BldFile(1)  - Name of file containing properties for blade 1 (quoted string)
"MHK_RM1_ElastoDyn_Blade.dat"   BldFile(2)  - Name of file containing properties for blade 2 (quoted string)
"unused"      BldFile(3)  - Name of file containing properties for blade 3 (quoted string) [unused for 2 blades]
-- ROTOR-TEETER --
  0 TeetMod     - Rotor-teeter spring/damper model {0: none, 1: standard, 2: user-defined from routine UserTeet} (switch) [u
  0 TeetDmpP    - Rotor-teeter damper position (degrees) [used only for 2 blades and when TeetMod=1]
  0 TeetDmp     - Rotor-teeter damping constant (N-m/(rad/s)) [used only for 2 blades and when TeetMod=1]
  0 TeetCDmp    - Rotor-teeter rate-independent Coulomb-damping moment (N-m) [used only for 2 blades and when TeetMod=1]
  0 TeetSStP    - Rotor-teeter soft-stop position (degrees) [used only for 2 blades and when TeetMod=1]
  0 TeetHStP    - Rotor-teeter hard-stop position (degrees) [used only for 2 blades and when TeetMod=1]
  0 TeetSSSp    - Rotor-teeter soft-stop linear-spring constant (N-m/rad) [used only for 2 blades and when TeetMod=1]
  0 TeetHSSp    - Rotor-teeter hard-stop linear-spring constant (N-m/rad) [used only for 2 blades and when TeetMod=1]
-- DRIVETRAIN --
  92 GBoxEff    - Gearbox efficiency (%)
  53 GBRatio    - Gearbox ratio (-)
 600000 DTTorSpr - Drivetrain torsional spring (N-m/rad)
100000 DTTorDmp - Drivetrain torsional damper (N-m/(rad/s))
```

- Gearbox and drivetrain specifications, including drivetrain rotational flexibility

# ElastoDyn Primary Input File

```
----- FURLING -----
False      Furling    - Read in additional model properties for furling turbine (flag) [must currently be FALSE]
"unused"   FurlFile   - Name of file containing furling properties (quoted string) [unused when Furling=False]

----- TOWER -----
2        TwrNodes  - Number of tower nodes used for analysis (-)
"MHK_RM1_Floating_ElastoDyn_Tower.dat"  TwrFile   - Name of file containing tower properties (quoted string)

----- OUTPUT -----
True     SumPrint   - Print summary data to "<RootName>.sum" (flag)
1        OutFile    - Switch to determine where output will be placed: {1: in module output file only; 2: in glue code
True     TabDelim   - Use tab delimiters in text tabular output file? (flag) (currently unused)
"ES10.3E2" OutFmt    - Format used for tabular output (0 to 9) (-)
0        TStart     - Time to begin
1        DecFact   - Decimation factor for tabular output {1: output every time step} (-) (currently unused)
0        NTwGages  - Number of tower nodes that have strain gages for output [0 to 9] (-)
0        TwrGagNd  - List of tower nodes that have strain gages [1 to TwrNodes] (-) [unused if NTwGages=0]
0        NBlGages  - Number of blade nodes that have strain gages for output [0 to 9] (-)
0        BldGagNd  - List of blade nodes that have strain gages [1 to BldNodes] (-) [unused if NBlGages=0]
OutList  OutList    - The next line(s) contains a list of output parameters. See OutListParameters.xlsx for a listing

"PtfmSurge"
"PtfmSway"
"PtfmHeave"
"PtfmRoll"
"PtfmPitch"
"PtfmYaw"
"TwrTpTDxi"
"TwrTpTDyi"
"TwrTpTDz"
"OoPDefl1"

END of OutList section (the word "END" must appear in the first 3 columns of the last OutList line)
```

## • Furling properties (currently unused)

# ElastoDyn Primary Input File

```
----- FURLING -----
False      Furling     - Read in additional model properties for furling turbine (flag) [must currently be FALSE)
"unused"   FurlFile    - Name of file containing furling properties (quoted string) [unused when Furling=False]
----- TOWER -----
| 2 TwrNodes - Number of tower nodes used for analysis (-)
|M "MHK_RM1_Floating_ElastoDyn_Tower.dat" TwrFile - Name of file containing tower properties (quoted string)
----- OUTPUT -----
True       SumPrint   - Print summary data to "<RootName>.sum" (flag)
| 1 OutFile    - Switch to determine where output will be placed: {1: in module output file only; 2: in glue code
True       TabDelim   - Use tab delimiters in text tabular output file? (flag) (currently unused)
"ES10.3E2" OutFmt     - Format used for text tabular output (except time). Resulting field should be 10 characters. (qu
| 0 TStart     - Time to begin tabular output (s) (currently unused)
| 1 DecFact    - Decimation factor (currently unused)
| 0 NTwGages   - Number of tower nodes that have strain gages (-)
| 0 TwrGagNd   - List of tower nodes that have strain gages [1 to TwrNodes] (-) [unused if NTwGages=0]
| 0 NBlGages   - Number of blade nodes that have strain gages for output [0 to 9] (-)
| 0 BldGagNd   - List of blade nodes that have strain gages [1 to BldNodes] (-) [unused if NBlGages=0]
| OutList     - The next line(s) contains a list of output parameters. See OutListParameters.xlsx for a listing
"PtfmSurge"
"PtfmSway"
"PtfmHeave"
"PtfmRoll"
"PtfmPitch"
"PtfmYaw"
"TwrTpTDxi"
"TwrTpTDyi"
"TwrTpTDz"
"OoPDefl1"
END of OutList section (the word "END" must appear in the first 3 columns of the last OutList line)
```

- Specify tower structural input file

# ElastoDyn Primary Input File

```
----- FURLING -----
False      Furling    - Read in additional model properties for furling turbine (flag) [must currently be FALSE)
"unused"   FurlFile   - Name of file containing furling properties (quoted string) [unused when Furling=False]
----- TOWER -----
| | | 2 TwrNodes   - Number of tower nodes used for analysis (-)
|M "MHK_RM1_Floating_ElastoDyn_Tower.dat" TwrFile   - Name of file containing tower properties (quoted string)
----- OUTPUT -----
True       SumPrint  - Print summary data to "<RootName>.sum" (flag)
True       1 OutFile   - Switch to output file only; 1: in glue code
True       TabDelim  - Use tab delimiter for output
"ES10.3E2" OutFmt   - Format of output file (currently unused)
0 TStart    - Time to start output
1 DecFact  - Decimation factor for tabular output {1: output every time step} (-) (currently unused)
0 NTwGages  - Number of tower nodes that have strain gages for output [0 to 9] (-)
0 TwrGagNd  - List of tower nodes that have strain gages [1 to TwrNodes] (-) [unused if NTwGages=0]
0 NBlGages  - Number of blade nodes that have strain gages for output [0 to 9] (-)
0 BldGagNd  - List of blade nodes that have strain gages [1 to BldNodes] (-) [unused if NBlGages=0]
OutList   - The next line(s) contains a list of output parameters. See OutListParameters.xlsx for a listing
"PtfmSurge"
"PtfmSway"
"PtfmHeave"
"PtfmRoll"
"PtfmPitch"
"PtfmYaw"
"TwrTpTDxi"
"TwrTpTDyi"
"TwrTpTDzi"
"OoPDefl1"
END of OutList section (the word "END" must appear in the first 3 columns of the last OutList line)
```

• Specify formatting of outputs written to file

# ElastoDyn Primary Input File

```
----- FURLING -----
False      Furling    - Read in additional model properties for furling turbine (flag) [must currently be FALSE)
"unused"   FurlFile   - Name of file containing furling properties (quoted string) [unused when Furling=False]
----- TOWER -----
| | | 2 TwrNodes   - Number of tower nodes used for analysis (-)
|M "MHK_RM1_Floating_ElastoDyn_Tower.dat" TwrFile   - Name of file containing tower properties (quoted string)
----- OUTPUT -----
True       SumPrint   - Print summary data to "<RootName>.sum" (flag)
| | | 1 OutFile    - Switch to determine where output will be placed: {1: in module output file only; 2: in glue code
True       TabDelim   - Use tab delimiters in text tabular output file? (flag) (currently unused)
"ES10.3E2" OutFmt    - Format used for text tabular output (except time). Resulting field should be 10 characters. (qu
| | | 0 TStart     - Time to begin tabular output (s) (currently unused)
| | | 1 DecFact   - Decimation factor for tabular output {1: output every time step} (-) (currently unused)
| | | 0 NTwGages  - Number of tower nodes that have strain gages for output [0 to 9] (-)
| | | 0 TwrGagNd  - List of tower nodes that have strain gages [1 to TwrNodes] (-) [unused if NTwGages=0]
| | | 0 NBlGages  - Number of blade nodes that have strain gages for output [0 to 9] (-)
| | | 0 BldGagNd  - List of blade nodes that have strain gages [1 to BldNodes] (-) [unused if NBlGages=0]
| | | OutList    - The next line(s) contains a list of output parameters. See OutListParameters.xlsx for a listing
| |
| | "PtfmSurge"
| | "PtfmSway"
| | "PtfmHeave"
| | "PtfmRoll"
| | "PtfmPitch"
| | "PtfmYaw"
| | "TwrTpTDxi"
| | "TwrTpTDyi"
| | "TwrTpTDzzi"
| | "OoPDefl1"
|
END of OutList section (the word "END" must appear in the first 3 columns of the last OutList line)
```

- List of user-selectable outputs  
(not comprehensive)

# AeroDyn Primary Input File

```
-- AERODYN v15 for OpenFAST INPUT FILE --
Floating MHK turbine hydrodynamic input properties, based on the RM1 tidal current rotor
===== General Options =====
False      Echo          - Echo the input to "<rootname>.AD.ech"? (flag)
"default"  DTAero       - Time interval for aerodynamic calculations {or "default"} (s)
                           - Type of wake/induction model (switch) {0=none, 1=BEMT, 2=DBEMT, 3=OLAF} [WakeMod cannot be 2 or
                           - Type of blade airfoil aerodynamics model (switch) {1=steady model, 2=Beddoes-Leishman unsteady m
                           2 WakeMod
                           1 AFAeroMod
                           1 TwrPotent
                           0 TwrShadow
                           TwrAero
                           FrozenWake
                           CavitCheck
                           Buoyancy
                           CompAA
                           AA_InputFile
===== Environmental Conditions =====
"default"  AirDens      - Air density (kg/m^3)
"default"  KinVisc      - Kinematic viscosity of working fluid (m^2/s)
"default"  SpdSound     - Speed of sound in working fluid (m/s)
"default"  Patm          - Atmospheric pressure (Pa) [used only when CavitCheck=True]
"default"  Pvap          - Vapour pressure of working fluid (Pa) [used only when CavitCheck=True]
===== Blade-Element/Momentum Theory Options ===== [unused when WakeMod=0 or 3]
                           - Type of skewed-wake correction model (switch) {1=uncoupled, 2=Pitt/Peters, 3=coupled} [unused wh
                           2 SkewMod
                           "default" SkewModFactor - Constant used in Pitt/Peters skewed wake model {or "default" is 15/32*pi} (-) [used only when SK
                           True      TipLoss       - Use the Prandtl tip-loss model? (flag) [unused when WakeMod=0 or 3]
                           True      HubLoss       - Use the Prandtl hub-loss model? (flag) [unused when WakeMod=0 or 3]
                           True      TanInd        - Include tangential induction in BEMT calculations? (flag) [unused when WakeMod=0 or 3]
                           True      AIDrag         - Include the drag term in the axial-induction calculation? (flag) [unused when WakeMod=0 or 3]
                           True      TIDrag         - Include the drag term in the tangential-induction calculation? (flag) [unused when WakeMod=0,3 o
                           "default" IndToler     - Convergence tolerance for BEMT nonlinear solve residual equation {or "default"} (-) [unused when
                           1000     MaxIter       - Maximum number of iteration steps (-) [unused when WakeMod=0]
                           1=baseline
                           =Powles
                           arizing]
```

- **WakeMod** options include steady and dynamic BEM and OLAF (vortex model)
  - **AFAeroMod** options include steady and unsteady aerodynamics models

# AeroDyn Primary Input File

```
----- AERODYN v15 for OpenFAST INPUT FILE -----
Floating MHK turbine hydrodynamic input properties, based on the RM1 tidal current rotor
===== General Options =====
False      Echo          - Echo the input to "<rootname>.AD.ech"? (flag)
"default"  DTAero       - Time interval for aerodynamic calculations {or "default"} (s)
                  2 WakeMod      - Type of wake/induction model (switch) {0=none, 1=BEMT, 2=DBEMT, 3=OLAF} [WakeMod cannot be 2 or
                  1 AFAeroMod    - Type of blade airfoil aerodynamics model (switch) {1=steady model, 2=Beddoes-Leishman unsteady m
                  1 TwrPotent    - Type tower influence on wind based on potential flow around the tower (switch) {0=none, 1=baseli
                  0 TwrShadow    - Calculate tower influence on wind based on downstream tower shadow? (switch) {0=none, 1=Powles m
True       TwrAero       - Calculate tower aerodynamic loads? (flag)
False      FrozenWake   - Assume frozen wake? (flag) [linearizing]
True       CavitCheck  - Perform cavitation calculations? (flag)
True       Buoyancy     - Include buoyancy effects? (flag)
False      CompAA       - Flag to compute AeroAcoustics calculation [used only when WakeMod = 1 or 2]
"unused"   AA_InputFile - AeroAcoustics input file [used only when CompAA=true]
===== Environmental Conditions =====
"default"  AirDens      - Air density (kg/m^3)
"default"  KinVisc      - Kinematic viscosity of working fluid (m^2/s)
"default"  SpdSound     - Speed of sound in working fluid (m/s)
"default"  Patm         - Atmospheric pressure (Pa) [used only when CavitCheck=True]
"default"  Pvap         - Vapour pressure of working fluid (Pa) [used only when CavitCheck=True]
===== Blade-Element/Momentum Theory Options ===== [unused when WakeMod=0 or 3]
                  2 SkewMod      - Type of skewed-wake correction model (switch) {1=uncoupled, 2=Pitt/Peters, 3=coupled} [unused wh
"default"  SkewModFactor - Constant used in Pitt/Peters skewed wake model {or "default" is 15/32*pi} (-) [used only when Sk
True       TipLoss       - Use the Prandtl tip-loss model? (flag) [unused when WakeMod=0 or 3]
True       HubLoss       - Use the Prandtl hub-loss model? (flag) [unused when WakeMod=0 or 3]
True       TanInd        - Include tangential induction in BEMT calculations? (flag) [unused when WakeMod=0 or 3]
True       AIDrag        - Include the drag term in the axial-induction calculation? (flag) [unused when WakeMod=0 or 3]
True       TIDrag        - Include the drag term in the tangential-induction calculation? (flag) [unused when WakeMod=0,3 o
"default"  IndToler     - Convergence tolerance for BEMT nonlinear solve residual equation {or "default"} (-) [unused when
                  1000 MaxIter     - Maximum number of iteration steps (-) [unused when WakeMod=0]
```

## • Options to calculate tower influence and loads

# AeroDyn Primary Input File

```
----- AERODYN v15 for OpenFAST INPUT FILE -----
Floating MHK turbine hydrodynamic input properties, based on the RM1 tidal current rotor
===== General Options =====
False      Echo          - Echo the input to "<rootname>.AD.ech"? (flag)
"default"  DTAero       - Time interval for aerodynamic calculations {or "default"} (s)
                  2  WakeMod      - Type of wake/induction model (switch) {0=none, 1=BEMT, 2=DBEMT, 3=OLAF} [WakeMod cannot be 2 or 3]
                  1  AFAeroMod    - Type of blade airfoil aerodynamics model (switch) {1=steady model, 2=Beddoes-Leishman unsteady model}
                  1  TwrPotent     - Type tower influence on wind based on potential flow around the tower (switch) {0=none, 1=baseline}
                  0  TwrShadow     - Calculate tower influence on wind based on downstream tower shadow? (switch) {0=none, 1=Powles method}
True       TwrAero       - Calculate tower aerodynamic loads? (flag)
False      FrozenWake   - Assume frozen wake during linearization? (flag) [used only when WakeMod=1 and when linearizing]
True       CavitCheck   - Perform cavitation check? (flag) [AFAeroMod must be 1 when CavitCheck=true]
True       Buoyancy     - Include buoyancy effects? (flag)
False      CompAA        - Flag to compute AeroAcoustics calculation [used only when WakeMod = 1 or 2]
"unused"   AA_InputFile - AeroAcoustics input file name
===== Environmental Conditions =====
"default"  AirDens      - Air density (kg/m^3)
"default"  KinVisc      - Kinematic viscosity (m^2/s)
"default"  SpdSound     - Speed of sound (m/s)
"default"  Patm         - Atmospheric pressure (Pa)
"default"  Pvap         - Vapour pressure (Pa)
===== Blade-Element/Momentum Theory Options =====
                  2  SkewMod      - Type of skewed-wake correction model (switch) {1=uncoupled, 2=Pitt/Peters, 3=coupled} [unused when WakeMod=0 or 3]
"default"  SkewModFactor - Constant used in Pitt/Peters skewed wake model {or "default" is 15/32*pi} (-) [used only when SkewMod=2]
True       TipLoss       - Use the Prandtl tip-loss model? (flag) [unused when WakeMod=0 or 3]
True       HubLoss       - Use the Prandtl hub-loss model? (flag) [unused when WakeMod=0 or 3]
True       TanInd        - Include tangential induction in BEMT calculations? (flag) [unused when WakeMod=0 or 3]
True       AIDrag        - Include the drag term in the axial-induction calculation? (flag) [unused when WakeMod=0 or 3]
True       TIDrag        - Include the drag term in the tangential-induction calculation? (flag) [unused when WakeMod=0,3 or 4]
"default"  IndToler     - Convergence tolerance for BEMT nonlinear solve residual equation {or "default"} (-) [unused when WakeMod=0 or 3]
                  1000 MaxIter     - Maximum number of iteration steps (-) [unused when WakeMod=0]
```

- Cavitation check for MHK turbines
- Buoyancy for MHK turbines
- Future releases will include options to calculate added mass

# AeroDyn Primary Input File

```
----- AERODYN v15 for OpenFAST INPUT FILE -----
Floating MHK turbine hydrodynamic input properties, based on the RM1 tidal current rotor
===== General Options =====
False      Echo          - Echo the input to "<rootname>.AD.ech"? (flag)
"default"  DTAero       - Time interval for aerodynamic calculations {or "default"} (s)
|           2 WakeMod    - Type of wake/induction model (switch) {0=none, 1=BEMT, 2=DBEMT, 3=OLAF} [WakeMod cannot be 2 or
|           1 AFAeroMod   - Type of blade airfoil aerodynamics model (switch) {1=steady model, 2=Beddoes-Leishman unsteady m
|           1 TwrPotent    - Type tower influence on wind based on potential flow around the tower (switch) {0=none, 1=baseli
|           0 TwrShadow    - Calculate tower influence on wind based on downstream tower shadow? (switch) {0=none, 1=Powles m
True        TwrAero      - Calculate tower aerodynamic loads? (flag)
False       FrozenWake   - Assume frozen wake during linearization? (flag) [used only when WakeMod=1 and when linearizing]
True        CavitCheck   - Perform cavitation check? (flag) [AFAeroMod must be 1 when CavitCheck=true]
True        Buoyancy     - Include buoyancy effects? (flag)
False       CompAA       -
"unused"   AA_InputFile -
===== Environmental Conditions =====
"default"  AirDens      - Air density (kg/m^3)
"default"  KinVisc      - Kinematic viscosity of working fluid (m^2/s)
"default"  SpdSound     - Speed of sound in working fluid (m/s)
"default"  Patm         - Atmospheric pressure (Pa) [used only when CavitCheck=True]
"default"  Pvap         - Vapour pressure of working fluid (Pa) [used only when CavitCheck=True]
===== Blade-Element/Momentum Theory Options ===== [unused when WakeMod=0 or 3]
|           2 SkewMod     - Type of skewed-wake correction model (switch) {1=uncoupled, 2=Pitt/Peters, 3=coupled} [unused wh
"default"  SkewModFactor - Constant used in Pitt/Peters skewed wake model {or "default" is 15/32*pi} (-) [used only when SK
True        TipLoss      - Use the Prandtl tip-loss model? (flag) [unused when WakeMod=0 or 3]
True        HubLoss      - Use the Prandtl hub-loss model? (flag) [unused when WakeMod=0 or 3]
True        TanInd       - Include tangential induction in BEMT calculations? (flag) [unused when WakeMod=0 or 3]
True        AIDrag        - Include the drag term in the axial-induction calculation? (flag) [unused when WakeMod=0 or 3]
True        TIDrag        - Include the drag term in the tangential-induction calculation? (flag) [unused when WakeMod=0,3 o
"default"  IndToler     - Convergence tolerance for BEMT nonlinear solve residual equation {or "default"} (-) [unused when
|           1000 MaxIter    - Maximum number of iteration steps (-) [unused when WakeMod=0]
```

## • Environmental conditions in driver input files

# AeroDyn Primary Input File

```
----- AERODYN v15 for OpenFAST INPUT FILE -----
Floating MHK turbine hydrodynamic input properties, based on the RM1 tidal current rotor
===== General Options =====
False      Echo          - Echo the input to "<rootname>.AD.ech"? (flag)
"default"  DTAero       - Time interval for aerodynamic calculations {or "default"} (s)
                  2  WakeMod      - Type of wake/induction model (switch) {0=none, 1=BEMT, 2=DBEMT, 3=OLAF} [WakeMod cannot be 2 or
                  1  AFAeroMod    - Type of blade airfoil aerodynamics model (switch) {1=steady model, 2=Beddoes-Leishman unsteady model}
                  1  TwrPotent     - Type tower influence on wind based on potential flow around the tower (switch) {0=none, 1=baseline}
                  0  TwrShadow     - Calculate tower influence on wind based on downstream tower shadow? (switch) {0=none, 1=Powles model}
True        TwrAero       - Calculate tower aerodynamic loads? (flag)
False       FrozenWake   - Assume frozen wake during linearization? (flag) [used only when WakeMod=1 and when linearizing]
True        CavitCheck   - Perform cavitation check? (flag) [AFAeroMod must be 1 when CavitCheck=true]
True        Buoyancy     - Include buoyancy effects? (flag)
False       CompAA        - 
"unused"   AA_InputFile - 
===== Environmental Conditions =====
"default"  AirDens      - Kinematic viscosity of working fluid (m2/s)
"default"  KinVisc      - Speed of sound in working fluid (m/s)
"default"  SpdSound     - Atmospheric pressure (Pa) [used only when CavitCheck=True]
"default"  Patm         - Vapour pressure of working fluid (Pa) [used only when CavitCheck=True]
"default"  Pvap         - 
===== Blade-Element/Momentum Theory Options ===== [unused when WakeMod=0 or 3]
                  2  SkewMod      - Type of skewed-wake correction model (switch) {1=uncoupled, 2=Pitt/Peters, 3=coupled} [unused when WakeMod=0 or 3]
"default"  SkewModFactor - Constant used in Pitt/Peters skewed wake model {or "default" is 15/32*pi} (-) [used only when SkewMod=2]
True        TipLoss      - Use the Prandtl tip-loss model? (flag) [unused when WakeMod=0 or 3]
True        HubLoss      - Use the Prandtl hub-loss model? (flag) [unused when WakeMod=0 or 3]
True        TanInd       - Include tangential induction in BEMT calculations? (flag) [unused when WakeMod=0 or 3]
True        AIDrag        - Include the drag term in the axial-induction calculation? (flag) [unused when WakeMod=0 or 3]
True        TIDrag        - Include the drag term in the tangential-induction calculation? (flag) [unused when WakeMod=0,3 or 4]
"default"  IndToler     - Convergence tolerance for BEMT nonlinear solve residual equation {or "default"} (-) [unused when WakeMod=0 or 3]
                  1000 MaxIter     - Maximum number of iteration steps (-) [unused when WakeMod=0]
```

- BEM options, including optional correction models

[2]

# AeroDyn Primary Input File

- Dynamic BEM, OLAF, and unsteady aerodynamics model options

```
===== Dynamic Blade-Element/Momentum =====
      2 DBEMT_Mod           - Type of dynamic aerodynamics model
      4 tau1_const            - Time constant for dynamic stall
===== OLAF -- cOnvecting LAgrangian filaments (Vortex vertex wake) theory options [used only when WakeMod=3]
"unused"   OLAFInputFileName - Input file for OLAF [used only when WakeMod=3]
===== Beddoes-Leishman Unsteady Airfoil Aerodynamics Options ===== [used only when WakeMod=3]
True        3 UAMod          - Unsteady Aero Model Switch (switch) {2=B-L Gonzalez, 3=B-L Minnema/Pierce, 4=B-L Ho
                  FLookup         - Flag to indicate whether a lookup for f' will be calculated (TRUE) or whether best-fit
                  0 UAStartRad       - Starting radius for dynamic stall (fraction of rotor radius [0.0,1.0]) [used only when WakeMod=3]
                  1 UAEndRad         - Ending radius for dynamic stall (fraction of rotor radius [0.0,1.0]) [used only when WakeMod=3]
===== Airfoil Information =====
      2 AFTabMod          - Interpolation method for multiple airfoil tables {1=1D interpolation on AoA (first)
      1 InCol_Alfa         - The column in the airfoil tables that contains the angle of attack (-)
      2 InCol_Cl            - The column in the airfoil tables that contains the lift coefficient (-)
      3 InCol_Cd            - The column in the airfoil tables that contains the drag coefficient (-)
      0 InCol_Cm            - The column in the airfoil tables that contains the pitching-moment coefficient; use zero if not
      4 InCol_Cpmin         - The column in the airfoil tables that contains the Cpmin coefficient; use zero if not
      9 NumAFFiles         - Number of airfoil files used (-)
      "Airfoils/NACA6_1000.dat" AFNames - Airfoil file names (NumAFFiles lines) (quoted strings)
      "Airfoils/NACA6_0864.dat"
      "Airfoils/NACA6_0629.dat"
      "Airfoils/NACA6_0444.dat"
      "Airfoils/NACA6_0329.dat"
      "Airfoils/NACA6_0276.dat"
      "Airfoils/NACA6_0259.dat"
      "Airfoils/NACA6_0247.dat"
      "Airfoils/NACA6_0240.dat"
```

# AeroDyn Primary Input File

```
===== Dynamic Blade-Element/Momentum Theory Options ===== [used only when
    2 DBEMT_Mod           - Type of dynamic BEMT (DBEMT) model {1=constant tau1, 2=time-dependent tau1, 3=const
    4 tau1_const          - Time constant for DBEMT (s) [used only when WakeMod=2 and DBEMT_Mod=1 or 3]
===== OLAFF -- cOnvecting LAgrangian Filaments (Free Vortex Wake) Theory Options ===== [used only when
"unused"   OLAFInputFileName - Input file for OLAF [used only when WakeMod=3]
===== Beddoes-Leishman Unsteady Airfoil Aerodynamics Options ===== [used only when
    3 UAMod              - Unsteady Aero Model Switch (switch) {2=B-L Gonzalez, 3=B-L Minnema/Pierce, 4=B-L Ho
True      FLookup           - Flag to indicate whether a lookup for f' will be calculated (TRUE) or whether best-
    0 UAStartRad         - Starting radius for dynamic stall (fraction of rotor radius [0.0,1.0]) [used only w
    1 UAEndRad           - Ending radius for dynamic stall (fraction of rotor radius [0.0,1.0]) [used only wh
===== Airfoil Information =====
    2 AFTabMod           - Interpolation method for multiple airfoil tables {1=1D interpolation on AoA (first
    1 InCol_Alfa          - The column in the airfoil tables that contains the angle of attack (-)
    2 InCol_Cl             - The column in the airfoil tables that contains the lift coefficient (-)
    3 InCol_Cd             - The column in the airfoil tables that contains the drag coefficient (-)
    0 InCol_Cm             - The column in the airfoil tables that contains the pitching-moment coefficient; use zero if t
    4 InCol_Cpmin          - The column in the airfoil tables that contains the Cpmin coefficient; use zero if t
    9 NumAFFiles          - Number of airfoil files used (-)
AFNames      - Airfoil file names (NumAFFiles lines) (quoted strings)
"Airfoils/NACA6_1000.dat"
"Airfoils/NACA6_0864.dat"
"Airfoils/NACA6_0629.dat"
"Airfoils/NACA6_0444.dat"
"Airfoils/NACA6_0329.dat"
"Airfoils/NACA6_0276.dat"
"Airfoils/NACA6_0259.dat"
"Airfoils/NACA6_0247.dat"
"Airfoils/NACA6_0240.dat"
```

- Specify airfoil input file format and names

# AeroDyn Primary Input File

- Specify blade input files

```
===== Rotor/Blade Properties =====
False      UseBlCm          - Include aerodynamic pitching moment in calculations? (flag)
"MHK_RM1_AeroDyn15_Blade.dat" ADBlFile(1)      - Name of file containing distributed aerodynamic properties
"MHK_RM1_AeroDyn15_Blade.dat" ADBlFile(2)      - Name of file containing distributed aerodynamic properties
"unused"    ADBlFile(3)      - Name of file containing distributed aerodynamic properties for Blade #3 (-) [used only]

===== Hub Properties ===== [used only]
| 7.2   VolHub            - Hub volume (m^3)
| 0.2222  HubCenBx        - Hub center of buoyancy x direction offset (m)

===== Nacelle Properties ===== [used only]
| 38.6   VolNac           - Nacelle volume (m^3)
| 0.43,     0,             0   NacCenB         - Position of nacelle center of buoyancy from yaw bearing

===== Tail Fin Aerodynamics =====
False      TFinAero          - Calculate tail fin aerodynamics model (flag)
"unused"    TFinFile         - Input file for tail fin aerodynamics [used only when TFinAero=True]

===== Tower Influence and Aerodynamics ===== [used only]
| 4       NumTwrNds        - Number of tower nodes used in the analysis (-) [used only when TwrPotent/=0,
TwrElev   TwrDiam           TwrCd            TwrTI            TwrCb ! TwrTI used only when TwrShadow=2; TwrCb us
(m)        (m)              (-)              (-)              (-)
-9.0000000E+00 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-1.4000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-1.9000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-2.4000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
```

# AeroDyn Primary Input File

```
===== Rotor/Blade Properties =====
False      UseBlCm      - Include aero
"MHK_RM1_AeroDyn15_Blade.dat" ADBlFile(1)
"MHK_RM1_AeroDyn15_Blade.dat" ADBlFile(2)
"unused"    ADBlFile(3)   - Name of file
===== Hub Properties =====
| 7.2  VolHub      - Hub volume (m^3)
| 0.2222  HubCenBx - Hub center of buoyancy x direction offset (m)
===== Nacelle Properties ===== [used only]
| 38.6  VolNac      - Nacelle volume (m^3)
| 0.43,     0,        0  NaccenB
===== Tail Fin Aerodynamics =====
False      TFInAero      - Calculate tail fin aerodynamics model (flag)
"unused"    TFInFile      - Input file for tail fin aerodynamics [used only when TFInAero=True]
===== Tower Influence and Aerodynamics ===== [used only]
| 4  NumTwrNds      - Number of tower nodes used in the analysis (-) [used only when TwrPotent/=0,
TwrElev    TwrDiam       TwrCd       TwrTI      TwrCb ! TwrTI used only when TwrShadow=2; TwrCb us
(m)          (m)         (-)        (-)        (-)
-9.0000000E+00 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-1.4000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-1.9000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-2.4000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
```

• Specify hub buoyant properties  
• Note that VolHub must  $\neq 0$  or blade root forces will be incorrect

• Specify nacelle buoyant properties

ties  
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only

bear

# AeroDyn Primary Input File

```
===== Rotor/Blade Properties =====
False      UseBlCm          - Include aerodynamic pitching moment in calculations? (flag)
"MHK_RM1_AeroDyn15_Blade.dat" ADBlFile(1)      - Name of file containing distributed aerodynamic properties
"MHK_RM1_AeroDyn15_Blade.dat" ADBlFile(2)      - Name of file containing distributed aerodynamic properties
"unused"    ADBlFile(3)      - Name of file containing distributed aerodynamic properties for Blade #3 (-) [used only]
===== Hub Properties ===== [used only]
| 7.2      VolHub          - Hub volume (m^3)
| 0.2222   HubCenBx        - Hub center of buoyancy x direction offset (m)
===== Nacelle Properties ===== [used only]
| 38.6     VolNac          - Nacelle volume (m^3)
| 0.43,     0,              0      NacCenB       - Position of nacelle center of buoyancy from yaw bearing
===== Tail Fin Aerodynamics =====
False      TFinAero         - Calculate tail fin aerodynamics model (flag)
"unused"   TFinFile         - Input file for tail fin aerodynamics [used only when TFinAero=True]
===== Tower Influence and Aerodynamics ===== [used only]
| 4        NumTwrNds       - Number of tower nodes used in the analysis (-) [used only when TwrPotent/=0, TwrElev<0]
TwrElev   TwrDiam          TwrCd           TwrTI           TwrCb
(m)       (m)             (-)            (-)            (-)
-9.000000E+00 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-1.4000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-1.9000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00
-2.4000000E+01 3.2530000E-01 2.0000000E-01 0.0000000E+00 1.0000000E+00 }
```

- Tower geometric, hydrodynamic, and buoyant properties

# AeroDyn Primary Input File

```
===== Outputs =====
True      SumPrint      - Generate a summary file listing input options and interpolated properties to "<root>
          9 NBlOuts      - Number of blade node outputs [0 - 9] (-)
          1,           5,    9,       13,       17,       21,       25,       27,       30   BlOutNd
          4 NTwOuts      - Number of tower node outputs [0 - 9] (-)
          1,           2,    3,       4   TwOutNd      - Tower nodes whose values will be output (-)
          OutList      - The next line(s) contains a list of output parameters. See OutListParameters.xlsx
"TwN1Fbx"      - x-component of buoyant force per unit length at Tw node 1
"TwN3Fby"      - y-component of buoyant force per unit length at Tw node 3
"TwN4Fbz"      - z-component of buoyant force per unit length at Tw node 4
"TwN1Mbx"      - x-component of buoyant moment per unit length at Tw node 6
"TwN2Mby"      - y-component of buoyant moment per unit length at Tw node 5
"TwN3Mbz"      - z-component of buoyant moment per unit length at Tw node 2
"B2N4Fbn"      - Buoyant force normal to chord per unit length at blade 2 node 4
"B1N7Fbt"      - Buoyant force tangential to chord per unit length at blade 1 node 7
"B2N8Fbs"      - Buoyant spanwise force per unit length at blade 2 node 8
"B1N2Mbn"      - Buoyant moment normal to chord per unit length at blade 1 node 2
"B2N3Mb"       - Buoyant moment tangential to chord per unit length at blade 2 node 3
"B1N6Mbs"      - Buoyant spanwise moment at hub node
"B1FlxFz"      - Total blade aerodynamic force in x direction
"B2FlxFx"      - Total blade aerodynamic force in x direction
"HbFbx"        - x-component of buoyant force at hub node
"HbFby"        - y-component of buoyant force at hub node
"HbFbz"        - z-component of buoyant force at hub node
"HbMbx"        - x-component of buoyant moment at hub node
"HbMby"        - y-component of buoyant moment at hub node
"HbMbz"        - z-component of buoyant moment at hub node
"NcFbx"        - x-component of buoyant force at nacelle node
"NcFby"        - y-component of buoyant force at nacelle node
"NcFbz"        - z-component of buoyant force at nacelle node
"NcMbx"        - x-component of buoyant moment at nacelle node
"NcMby"        - y-component of buoyant moment at nacelle node
"NcMbz"        - z-component of buoyant moment at nacelle node
"RtFlxFxh"     - Total rotor aerodynamic/hydrodynamic and buoyant load (force in x direction)
"RtFlxFyh"     - Total rotor aerodynamic/hydrodynamic and buoyant load (force in y direction)
"RtFlxFzg"     - Total rotor aerodynamic/hydrodynamic and buoyant load (force in global z direction)
"RtFlxFxh"     - Total rotor aerodynamic/hydrodynamic and buoyant load (moment in x direction)
"RtFlxFyg"     - Total rotor aerodynamic/hydrodynamic and buoyant load (moment in global y direction)
"RtFlxFzh"     - Total rotor aerodynamic/hydrodynamic and buoyant load (moment in z direction)
"B1N3SigCr"    - Critical cavitation number blade 1 node 3
"B2N5SigCr"    - Critical cavitation number blade 2 node 5
"B1N2SgCav"    - Cavitation number blade 1 node 2
"B2N6SgCav"    - Cavitation number blade 2 node 6
```

- Specify formatting of outputs written to file
- Select blade/tower nodes for output

# InflowWind Primary Input File

```
----- InflowWind INPUT FILE -----
Steady 1.9 m/s inflow for floating MHK turbine, based on the RM1 tidal current rotor

----- Parameters for WindType -----
False      Echo      - Echo input data to <RootName>.ech (flag)
           1 WindType - switch for wind file type (1=steady; 2=uniform; 3=binary TurbSim FF; 4=binary Bladed-st
           0 PropagationDir - Direction of wind propagation (meteorological rotation from aligned with X (positive ro
           0 VFlowAng     - Upflow angle (degrees) (not used for native Bladed format WindType=7)

----- Parameters for Steady -----
False      VelInterpCubic - Use cubic interpolation for velocity in time (false=linear, true=cubic) [Used with Wind
           1 NWindVel    - Number of wind velocity components
           0 WindVxiList  - List
           0 WindVyiList  - List
           24.8 WindVziList - List

----- Parameters for Uniform -----
           1.9 HWindSpeed - Horizontal wind speed
           24.8 RefHt     - Reference height
           0.1429 PLExp    - Power law exponent

----- Parameters for TurbSim -----
"unused"   FileName_Uni - File name for uniform wind file
           30 RefHt_Uni   - Reference height for uniform wind file
           125.88 RefLength - Reference length for uniform wind file

----- Parameters for Bladed -----
           "unused"   FileName_BTS - Name of the Full field wind file to use (.bts)

----- Parameters for HAWC -----
           "unused"   FileNameRoot - WindType=4: Rootname of the full-field wind file to use (.wnd, .sum); WindType=7: name
           False       TowerFile   - Have tower file (.twr) (flag) ignored when WindType = 7

----- Parameters for HAWC-format binary files [Only used with WindType = 5] -----
           "unused"   FileName_u   - name of the file containing the u-component fluctuating wind (.bin)
           "unused"   FileName_v   - name of the file containing the v-component fluctuating wind (.bin)
           "unused"   FileName_w   - name of the file containing the w-component fluctuating wind (.bin)
```

- Type of wind specification

- Steady
- Uniform
- TurbSim
- Bladed
- HAWC
- Etc.

# InflowWind Primary Input File

```
----- InflowWind INPUT FILE -----
Steady 1.9 m/s inflow for floating MHK turbine, based on the RM1 tidal current rotor

False      Echo          - Echo input data to <RootName>.ech (flag)
1          WindType       - switch for wind file type (1=steady; 2=uniform; 3=binary TurbSim FF; 4=binary Bladed-st
0          PropagationDir - Direction of wind propagation (meteorological rotation from aligned with X (positive ro
0          VFlowAng       - Upflow angle (degrees) (not used for native Bladed format WindType=7)
False      VelInterpCubic - Use cubic interpolation for velocity in time (false=linear, true=cubic) [Used with Wind
1          NWindVel        - Number of points to output the wind velocity    (0 to 9)
0          WindVxiList     - List of coordinates in the inertial X direction (m)
0          WindVyiList     - List of coordinates in the inertial Y direction (m)
24.8       WindVziList     - List of coordinates in the inertial Z direction (m)
===== Parameters for Steady Wind Conditions [used only for WindType = 1] =====
1.9        HWindSpeed    - Horizontal wind speed                      (m/s)
24.8       RefHt          - Reference height for horizontal wind speed   (m)
0.1429     PLExp          - Power law exponent                         (-)
===== Parameters for Uniform wind file [used only for WindType = 2] =====
"unused"   FileName_Uni   - Filename of time series data for uniform wind field   (.txt)
30         RefHt_Uni     - Reference height for uniform wind field           (m)
125.88     RefLength      - Reference length for uniform wind field          (m)
===== Parameters for Binary
"unused"   FileName_BTS   - Name of the binary file for the uniform wind field (.bin)
===== Parameters for Binary
"unused"   FileNameRoot   - WindType=4
False      TowerFile      - Have tower file
===== Parameters for HAWC-format
"unused"   FileName_u     - name of the u-component fluctuating wind (.bin)
"unused"   FileName_v     - name of the v-component fluctuating wind (.bin)
"unused"   FileName_w     - name of the w-component fluctuating wind (.bin)
```

- Steady current speed
  - Should match current speed in SeaState
  - Future release will couple the current from inflow wind and waves from SeaState
- Reference height
- Shear exponent

# HydroDyn Primary Input File

```
-- HydroDyn Input File --
Floating MHK turbine hydrodynamic support st
False          Echo           - Echo the
                - PotMod
                - ExctnMod
                - ExctnDisp
                - ExctnCutOff
                - RdtnMod
                - RdtnTMax
                "DEFAULT"   RdtnDT
                1             NBody
                2             NBodyMod
                "MHK_RM1_Floating" PotFile
                1             WAMITULEN
                0             PtfmRefxt
                0             PtfmRefyt
                0             PtfmRefzt
                0             PtfmRefztRot
                2671.85      PtfmVol0
                0             PtfmCOBxt
                0             PtfmCOByt
                0             MnDrift
                0             NewmanApp
                0             DiffQTF
                0             SumQTF
-- FLOATING PLATFORM --
                - Potential
                - Wave-excit
                - Method of
                - Cutoff (co
                - Radiation
                - Analysis t
                - Time step
                - Number of WAMIT bodies to be used (-) [>=1; only used when PotMod=1. If NBodyMod=1, the WA
                - Body coupling model {1: include coupling terms between each body and NBody in HydroDyn equ
                    - Root name of potential-flow model data; WAMIT output files containing the linear, nond
                    - Characteristic body length scale used to redimensionalize WAMIT output (meters) [1 to NBod
                    - The xt offset of the body reference point(s) from (0,0,0) (meters) [1 to NBody] [only used
                    - The yt offset of the body reference point(s) from (0,0,0) (meters) [1 to NBody] [only used
                    - The zt offset of the body reference point(s) from (0,0,0) (meters) [1 to NBody] [only used
                    - The rotation about zt of the body reference frame(s) from xt/yt (degrees) [1 to NBody] [on
                    - Displaced volume of water when the body is in its undisplaced position (m^3) [1 to NBody]
                    - The xt offset of the center of buoyancy (COB) from (0,0) (meters) [1 to NBody] [only used
                    - The yt offset of the center of buoyancy (COB) from (0,0) (meters) [1 to NBody] [only used
-- 2ND-ORDER FLOATING PLATFORM FORCES -- [unused with WaveMod=0 or 6, or PotMod=0 or 1]
                - Mean-drift 2nd-order forces computed
                - Mean- and slow-drift 2nd-order forces computed with Newman's approximation
                - Full difference-frequency 2nd-order forces computed with full QTF
                - Full summation -frequency 2nd-order forces computed with full QTF
```

- Define if potential flow is used
- Point to WAMIT files
- Platform volume should match WAMIT.hst or be 0 if potential flow is not used
  - Full strip theory Morrison elements often used for slender membered platforms
- 2<sup>nd</sup> order potential flow forces available

# HydroDyn Primary Input File

- Additional matrices can be added
    - Often used to tune to free decays
  - Only applied if potential flow files are present
  - Dummy files can be used if additional matrices are desired with full strip theory elements

# HydroDyn Primary Input File

-- AXIAL COEFFICIENTS --							
AxCoefID	AxCd	AxCa	AxCp	AxFDMod	AxVnCOff	AxFDLoFSc	
(-)	(-)	(-)	(-)	(-)	(-)	(-)	
1	0.00	0.00	0.00	0	-1.00	1.00	! Columns / Braces (r)
2	1.00	1.00	1.00	0	-1.00	1.00	! Heave Plates

-- MEMBER JOINTS --						
JointID	Jointxi	Jointyi	Jointzi	JointAxID	JointOvrlp [JointOvrlp= 0: do nothing]	
(-)	(m)	(m)	(m)	(-)	(switch)	
0	28.00000	0.00000	-10.00000	1	0	! Downstream Column
1	28.00000	0.00000	6.00000	1	0	! Upstream Column
2	-28.00000	0.00000	-10.00000	1	0	! Starboard Column
3	-28.00000	0.00000	6.00000	1	0	! Port Column
4	0.00000	-12.00000	-10.00000	1	0	! Upper Braces
5	0.00000	-12.00000	6.00000	1	0	
6	0.00000	12.00000	-10.00000	1	0	
7	0.00000	12.00000	6.00000	1	0	
8	3.67658	10.42430	4.50000	1	0	
9	24.32340	1.57568	4.50000	1	0	
10	3.67658	-10.42430	4.50000	1	0	
11	24.32340	-1.57568	4.50000	1	0	
12	-3.67658	10.42430	4.50000	1	0	
13	-24.32340	1.57568	4.50000	1	0	
14	-3.67658	-10.42430	4.50000	1	0	
15	-24.32340	-1.57568	4.50000	1	0	! Lower Brace
16	3.67658	10.42430	-8.50000	1	0	
17	24.32340	1.57568	-8.50000	1	0	
18	3.67658	-10.42430	-8.50000	1	0	
19	24.32340	-1.57568	-8.50000	1	0	
20	-3.67658	10.42430	-8.50000	1	0	
21	-24.32340	1.57568	-8.50000	1	0	
22	-3.67658	-10.42430	-8.50000	1	0	
23	-24.32340	-1.57568	-8.50000	1	0	
24	0.00000	-8.00000	4.50000	1	0	! Tower Braces
25	0.00000	8.00000	4.50000	1	0	
26	0.00000	-8.00000	-8.50000	1	0	
27	0.00000	8.00000	-8.50000	1	0	
28	0.00000	0.00000	-8.50000	1	0	
29	28.00000	0.00000	-10.50000	2	0	
30	-28.00000	0.00000	-10.50000	2	0	
31	0.00000	-12.00000	-10.50000	2	0	
32	0.00000	12.00000	-10.50000	2	0	! Heave Plates

- Member axial drag and added mass forces

- Define location of all platform joints
- Corresponding axial force ID
- Ovrlp turns off axial forces for members that intersect other members

# HydroDyn Primary Input File

----- MEMBER CROSS-SECTION PROPERTIES -----											
PropSetID	PropD (-)	PropThck (m)	- Number of member property sets (-)								
0	8.00000	0.02000	! Columns								
1	2.00000	0.02000	! Braces								
2	2.00000	0.08100	! Flooded Braces (not flooded in hydrodyn)								
3	12.00000	0.39250	! Flooded Heave Plates (not flooded in hydrodyn)								
----- SIMPLE HYDRODYNAMIC COEFFICIENTS (model 1) -----											
SimplCd	SimplCdMG (-)	SimplCa (-)	SimplCaMG (-)	SimplCp (-)	SimplCpMG (-)	SimplAxCd (-)	SimplAxCdMG (-)	SimplAxCa (-)	SimplAxCaMG (-)	SimplAxCp (-)	SimplAxCpMG (-)
1.20	0.00	1.00	0.00	1.00	1.00	0.00	0.00	0.00	0.00	1.00	1.00
----- DEPTH-BASED HYDRODYNAMIC COEFFICIENTS (model 2) -----											
Dpth	DpthCd (m)	DpthCdMG (-)	DpthCa (-)	DpthCaMG (-)	DpthCp (-)	DpthCpMG (-)	DpthAxCd (-)	DpthAxCdMG (-)	DpthAxCa (-)	DpthAxCaMG (-)	DpthAxCp (-)
----- MEMBER-BASED HYDRODYNAMIC COEFFICIENTS (model 3) -----											
MemberID	MemberCd1 (-)	MemberCd2 (-)	MemberCdMG1 (-)	MemberCdMG2 (-)	MemberCa1 (-)	MemberCa2 (-)	MemberCaMG1 (-)	MemberCaMG2 (-)	MemberCp1 (-)	MemberCp2 (-)	
MEMBERS											

- Member ID with diameter

- Member hydrodynamic coefficients
- Can apply to all members
- Can be grouped by member ID or by depth

# HydroDyn Primary Input File

-- MEMBERS --										
	20	NMembers	- Number of members (-)							
MemberID	MJointID1	MJointID2	MPropSetID1	MPropSetID2	MDivSize	MCoefMod	MHstLMod	PropPot	[MCoefMod=1: use simp	
(-)	(-)	(-)	(-)	(-)	(m)	(switch)	(switch)	(flag)		
0	0	1	0	0	0.1000	1	1	TRUE	! Columns	
1	2	3	0	0	0.1000	1	1	TRUE		
2	4	5	0	0	0.1000	1	1	TRUE		
3	6	7	0	0	0.1000	1	1	TRUE		
4	8	9	1	1	0.1000	1	1	TRUE	! Upper Braces	
5	10	11	1	1	0.1000	1	1	TRUE		
6	12	13	1	1	0.1000	1	1	TRUE		
7	14	15	1	1	0.1000	1	1	TRUE		
8	16	17	2	2	0.1000	1	1	TRUE	! Lower Braces	
9	18	19	2	2	0.1000	1	1	TRUE		
10	20	21	2	2	0.1000	1	1	TRUE		
11	22	23	2	2	0.1000	1	1	TRUE		
12	24	25	1	1	0.1000	1	1	TRUE	! Tower Braces	
13	26	27	1	1	0.1000	1	1	TRUE		
14	24	28	1	1	0.1000	1	1	TRUE		
15	25	28	1	1	0.1000	1	1	TRUE		
16	0	29	3	3	0.1000	1	1	TRUE	! Heave Plates	
17	2	30	3	3	0.1000	1	1	TRUE		
18	4	31	3	3	0.1000	1	1	TRUE		
19	6	32	3							

- Members connect between defined joints
- Assign property ID

# HydroDyn Primary Input File

```
-- FILLED MEMBERS --
| | | | 0 NFillGroups - Number of filled member groups (-) [If FillDens = DEFAULT, then FillDens = WtrDens;
FillNumM FillMList           FillFSLoc   FillDens
(-)      (-)                 (m)        (kg/m^3)

-- MARINE GROWTH --
| | | | 0 NMGDepths - Number of marine-growth depths specified (-)
MGDpth  MGThck    MGDens
(m)      (m)       (kg/m^3)

-- MEMBER OUTPUT LIST --
| | | | 0 NMOutputs - Number of member ou
MemberID NOutLoc   NodeLocs [NOutLoc < 10; node locations are normalized distance from the start of the member, and
(-)      (-)       (-)

-- JOINT OUTPUT LIST --
| | | | 0 NJOutputs - Number of joint outputs [Must be < 10]
| | | | 0 JOutLst   - List of JointIDs which are to be output (-)[unused if NJOutputs=0]

-- OUTPUT --
True      HDSum     - Output a summary file [flag]
False     OutAll    - Output all user-specified member and joint loads (only at each member end, not inter
| | | | 2 OutSwtch  - Output requested channels to: [1=Hydrodyn.out, 2=GlueCode.out, 3=both files]
"E15.7e2" OutFmt    - Output format for numerical results (quoted string) [not checked for validity!]
"A11"     OutSFmt   - Output format for header strings (quoted string) [not checked for validity!]

-- OUTPUT CHANNELS --
Wave1Elev          - Wave elevation at the platform reference point (0, 0)
HydroFxi           - Buoyancy force [N]
HydroFyi           - Buoyancy force [N]
HydroFzi           - Buoyancy force [N] in the vertical direction (Z).
END of output channels and end of file. (the word "END" must appear in the first 3 columns of this line)
```

- Ballast included in platform mass and inertia instead of filled members
- List outputs

# SeaState Primary Input File

```
----- SeaState Input File -----
Floating MHK turbine hydrodynamic support structure input properties, based on the RM1 tidal current rotor with a
False          Echo           - Echo the input file data (flag)
----- ENVIRONMENTAL CONDITIONS -----
"DEFAULT"      WtrDens        - Water density (kg/m^3)
"DEFAULT"      WtrDpth        - Water depth (meters) relative to MSL
"DEFAULT"      MSL2SWL       - Offset between still-water level and mean sea level (meters) [positive upward]
----- SPATIAL DISCRETIZATION -----
 30  X_HalfWidth   Half-width of the domain in the X direction (m) [>0, NOTE: X[nX] = nX*dX, where
 30  Y_HalfWidth   Half-width of the domain in the Y direction (m) [>0, NOTE: Y[nY] = nY*dY, where
 50  Z_Depth        Depth of the domain the Z direction (m) relative to SWL [0 < Z_Depth <= WtrDpth]
 11  NX             Number of nodes in half of the X-direction domain (-) [>=2]
 11  NY             Number of nodes in half of the Y-direction domain (-) [>=2]
 10  NZ             Number of nodes in the Z direction (-) [>=2]
```

- Define grid for wave generation
- Should cover full expected range of displacements

# SeaState Primary Input File

WAVES		- Incident wave kinematics model {0: none=still water, 1: regular (periodic), 1P#: regular with user-specified phase, 2: random}
1	WaveMod	- Model for stretching incident wave kinematics to instantaneous free surface {0: none=no stretching, 1: vertical stretch}
0	WaveStMod	- Analysis time for incident wave calculations (sec) [unused when WaveMod=0; determines WaveDOmega=2Pi/WaveTMax in the analysis]
600	WaveTMax	- Time step for incident wave calculations (sec) [unused when WaveMod=0 or 7; 0.1<=WaveDT<=1.0 recommended; determines WaveDOmega=2Pi/WaveTMax in the analysis]
0.1	WaveDT	- Significant wave height of incident waves (meters) [used only when WaveMod=1, 2, or 3]
2.0	WaveHs	- Peak-spectral period of incident waves (sec) [used only when WaveMod=1 or 2]
6.75	WaveTp	- Peak-shape parameter of incident wave spectrum (-) on DEFAULT (string) [used only when WaveMod=2; use 1.0 for Pierson-Moskowitz spectrum]
"DEFAULT"	WavePkShp	- Low cut-off frequency (rad/s)
0.314159	WvLowCOff	- High cut-off frequency (rad/s)
1.570796	WvHiCOff	- Incident wave propagation direction [0: no propagation, 1: horizontal, 2: vertical, 3: diagonal up-right, 4: diagonal up-left, 5: diagonal down-right, 6: diagonal down-left, 7: random]
0	WaveDir	- Directional spread
0	WaveDirMod	- Wave direction spread
1	WaveDirSpread	- Number of wave directions
1	WaveNDir	- Range of wave directions (full range: waveDir +/- 1/2*waveDirRange) (degrees) [only used when waveMod=2, 3, or 4 and WaveDirMod>0]
0	WaveDirRange	- First random seed of incident waves [-2147483648 to 2147483647] (-) [unused when WaveMod=0, 5, or 6]
123456789	WaveSeed(1)	- Second random seed of incident waves [-2147483648 to 2147483647] for intrinsic pRNG, or an alternative pRNG: "RanLux"
"RANLUX"	WaveSeed(2)	- Flag for normally distributed amplitudes (flag) [only used when WaveMod=2, 3, or 4]
FALSE	WaveNDamp	- Root name of externally generated wave data file(s) (quoted string) [used only when WaveMod=5, 6 or 7]
"	WvKinFile	----- 2ND-ORDER WAVES ----- [unused with WaveMod=0 or 6]
FALSE	WvDiffQTF	- Full difference-frequency 2nd-order wave kinematics (flag)
FALSE	WvSumQTF	- Full summation-frequency 2nd-order wave kinematics (flag)
0	WvLowCOffD	- Low frequency cutoff used in the difference-frequencies (rad/s) [Only used with a difference-frequency method]
1.256637	WvHiCOffD	- High frequency cutoff used in the difference-frequencies (rad/s) [Only used with a difference-frequency method]
0.618319	WvLowCOffS	- Low frequency cutoff used in the summation-frequencies (rad/s) [Only used with a summation-frequency method]
3.141593	WvHiCOffS	- High frequency cutoff used in the summation-frequencies (rad/s) [Only used with a summation-frequency method]

- Regular wave
- Options for irregular wave and user input time series

# SeaState Primary Input File

```
----- CURRENT ----- [unused with WaveMod=6]
 1 CurrMod      - Current profile model {0: none=no current, 1: standard, 2: user-defined from routine User
 0 CurrSSV0     - Sub-surface current velocity at still water level (m/s) [used only when CurrMod=1]
 0 CurrSSDir    - Sub-surface current heading direction (degrees) or DEFAULT (string) [used only when CurrM
12.2 CurrNSRef   - Near-surface current reference depth                      (meters) [used only when CurrMod=1]
 0 CurrNSV0     - Near-surface current velocity at still water level (m/s) [used only when CurrMod=1]
 0 CurrNSDir    - Near-surface current heading direction                  (degrees) [used only when CurrMod=1]
1.9 CurrDIV      - Depth-independent current velocity                   (m/s) [used only when CurrMod=1]
 0 CurrDIDir    - Depth-independent current heading direction       (degrees) [used only when CurrMod=1]
----- MacCamy-Fuchs diffraction model -----
 0 MCFD         - MacCamy-Fuchs member radius (ignored if radius <= 0) [must be 0 when WaveMod 0 or 6]
----- OUTPUT -----
True          SeaStSum      - Output a summary of the sea state
 2 OutSwtch     - Output recent wave statistics
"E15.7e2"      OutFmt        - Output formatted output
"A11"          OutSFmt      - Output formatted output
 1 NWaveElev    - Number of points where wave elevations can be output (-)
 0 WaveElevxi   - List of xi-coordinates for points where the incident wave elevations can be output (meter
 0 WaveElevyi   - List of yi-coordinates for points where the incident wave elevations can be output (meter
 2 NWaveKin    - Number of points where the wave kinematics can be output (-)      [maximum of 9 output p
14.43376,     -18.4752    WaveKinxi  - List of xi-coordinates for points where the wave kinematics can be output (met
 25,           -6          WaveKinyi  - List of yi-coordinates for points where the wave kinematics can be output (met
-14,          -17          WaveKinzi - List of zi-coordinates for points where the wave kinematics can be output (met
----- OUTPUT CHANNELS -----
"Wave1Elev"    - Wave elevation at the platform reference point
END of output channels and end of file. (the word "END" must appear in the first 3 columns of this line)
```

- Current speed
  - Should match inflow wind
  - Future release will couple to inflow wind

# MoorDyn Primary Input File

----- MoorDyn Input File -----										
Floating MHK turbine mooring input properties, based on the RM1 tidal current rotor with a quad-sty										
FALSE	Echo	- echo the input file data (flag)								
----- LINE TYPES Chain studless 0.018m -----										
Name	Diam	MassDen	EA	BA/-zeta	EI	Cd	Ca	CdAx	CaAx	
(-)	(m)	(kg/m)	(N)	(N-s/-)	(-)	(-)	(-)	(-)	(-)	
main	0.324	644.8	85.4e8	-0.8	0.8	2.4	1.0	1.15	0.5	
----- POINTS -----										
Node	Type	X	Y	Z	M	V	CdA	CA		
(-)	(-)	(m)	(m)	(m)	(kg)	(m^3)	(m^2)	(-)		
1	Fixed	-152.0	-50.0	-50.0	0	0	0	0		
2	Fixed	-152.0	0.0	-50.0	0	0	0	0		
3	Fixed	-152.0	50.0	-50.0	0	0	0	0		
4	Fixed	152.0	-50.0	-50.0	0	0	0	0		
5	Fixed	152.0	0.0	-50.0	0	0	0	0		
6	Fixed	152.0	50.0	-50.0	0	0	0	0		
7	Vessel	-34.0	0.0	-10.0	0	0	0	0		
8	Vessel	-34.0	0.0	-10.0	0	0	0	0		
9	Vessel	-34.0	0.0	-10.0	0	0	0	0		
10	Vessel	34.0	0.0	-10.0	0	0	0	0		
11	Vessel	34.0	0.0	-10.0	0	0	0	0		
12	Vessel	34.0	0.0	-10.0	0	0	0	0		

- Define line properties
- New release includes bending

- Define fairlead and anchor locations
- If multiple line types or mooring components are used – define initial location

# MoorDyn Primary Input File

-- LINES --						
Line	LineType	AttachA	AttachB	UnstrLen	NumSegs	Outputs
(-)	(-)	(-)	(-)	(m)	(-)	(-)
1	main	1	7	160.0	30	-
2	main	2	8	152.0	30	-
3	main	3	9	160.0	30	-
4	main	4	10	160.0	30	-
5	main	5	11	152.0	30	-
6	main	6	12	160.0	30	-

- Lines connect between defined points

## -- SOLVER OPTIONS --

0.5e-4	dtM	- time step to use in mooring integration (s)
3.0e6	kbot	- bottom stiffness (Pa/m)
3.0e5	cbot	- bottom damping (Pa-s/m)
1.0	dtIC	- time interval for analyzing convergence during IC gen (s)
10.0	TmaxIC	- max time for ic gen (s)
4.0	CdScaleIC	- factor by which to scale drag coefficients during dynamic relaxation (-)
0.1	threshIC	- threshold for IC convergence (-)

- Bottom stiffness must support chain
- Time and time step used in initialization convergence

# Supporting Files

- ElastoDyn blade structural properties
  - Pre-calculated mode shapes (BModes)
- ElastoDyn tower structural properties
  - Pre-calculated mode shapes (BModes)
- AeroDyn blade geometric properties
- AeroDyn blade aerodynamic properties
- Airfoil polars

# Running OpenFAST

- In a terminal, navigate to the folder containing the relevant OpenFAST executable for your system and the simulation input files
- For Mac users, run OpenFAST using the following command for the example
  - `./openfast_Mac "Onshore/ MHK_RM1_Floating.fst"`
- For Windows users, run OpenFAST using the following command for the example
  - `openfast_Windows.exe Onshore\ MHK_RM1_Floating.fst`
- For Linux users, run OpenFAST using the following command for the example
  - `./openfast_Linux Onshore/MHK_RM1_Floating.fst`

# OpenFAST Outputs

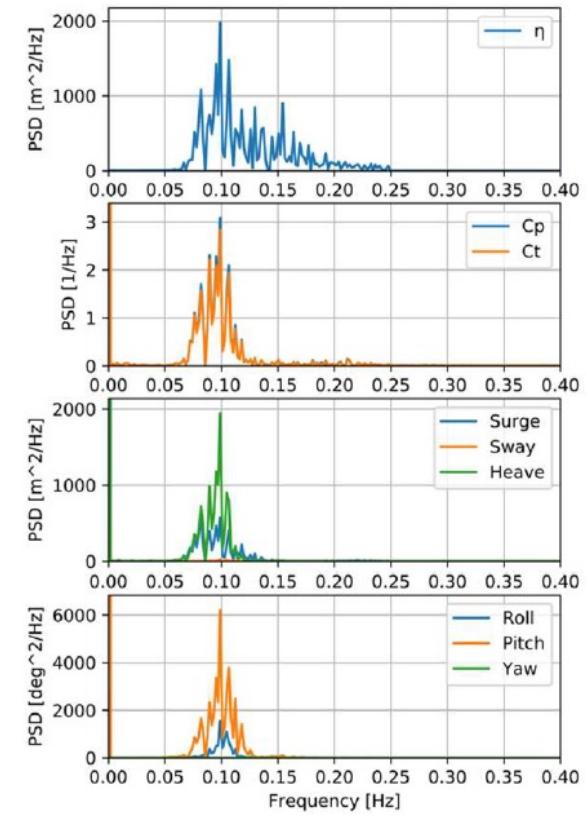
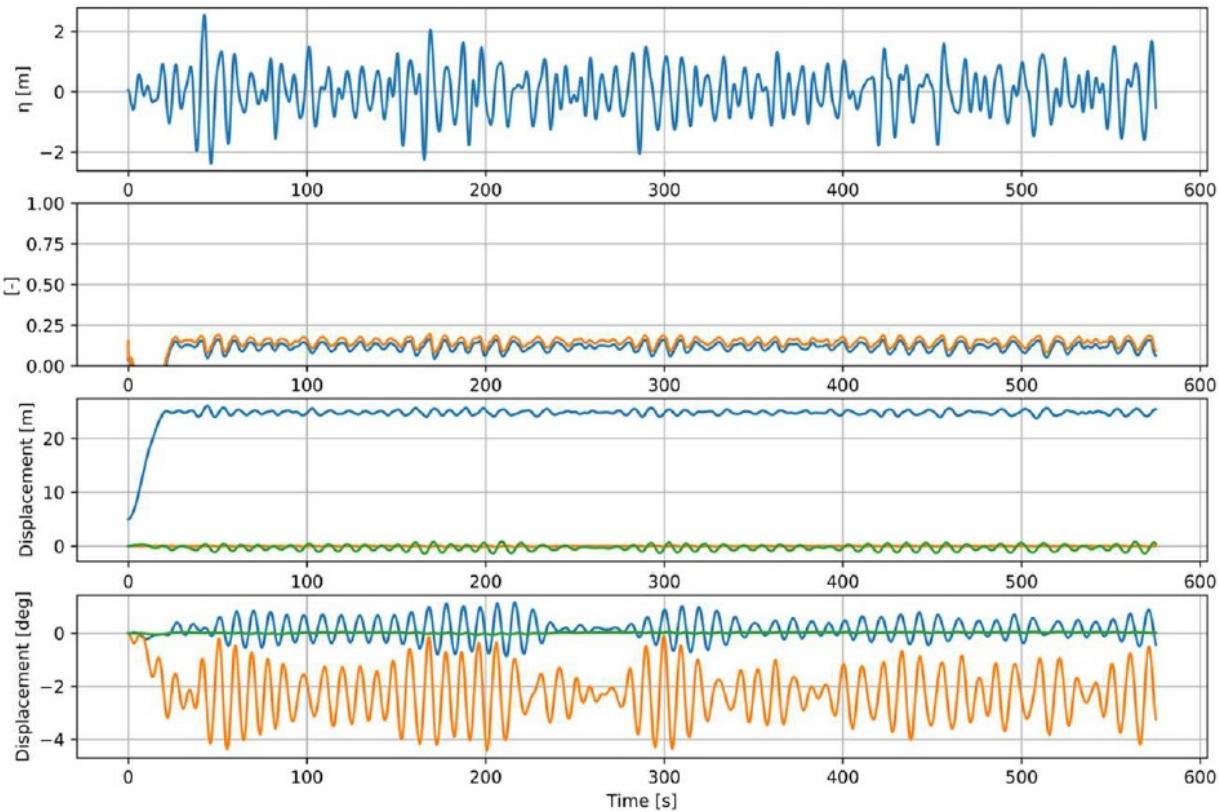
- Summary files
  - OpenFAST (MHK\_RM1\_Floating.sum)
  - ElastoDyn (MHK\_RM1\_Floating.sum)
  - AeroDyn (MHK\_RM1\_Floating.sum)
- Output file
  - MHK\_RM1\_Floating.out

Predictions were generated on 16-Jan-2022 at 20:07:40 using OpenFAST, compiled as a 64-bit application using double precision at commit v3.0.0  
linked with NWTC Subroutine Library; ElastoDyn; InflowWind; AeroDyn

Description from the FAST input file: MECC OpenFAST Webinar: NREL 5.0 MW Baseline Wind Turbine (Onshore)

Time	Wind1VelX	Wind1VelY	Wind1VelZ	OoPDefl1	IPDefl1	TwstDefl1	BldPitch1	Azimuth	RotSpeed	GenSpeed	TTDspFA	TTDspSS	TTDspTwst	Spn2MLxb1	Spn2MLyb1	RootFx1b1	RootFyb1
(s)	(m/s)	(m/s)	(m)	(m)	(deg)	(deg)	(rpm)	(m)	(deg)	(kN-m)	(kN)	(kN)	(kN-m)	(kN-m)	(kN-m)	(kN)	(kN)
0.0000	8.000E+00	-0.000E+00	0.000E+00	0.000E+00	0.000E+00	0.000E+00	0.000E+00	0.000E+00	0.000E+00	9.000E+00	8.730E+02	0.000E+00	-0.000E+00	0.000E+00	3.179E+00	-8.463E+00	
0.0125	8.000E+00	-0.000E+00	0.000E+00	4.536E-03	-7.934E-05	0.000E+00	0.000E+00	6.752E-01	9.005E+00	8.730E+02	-6.648E-06	-9.360E-08	0.000E+00	2.637E+00	-1.772E+01		
0.0250	8.000E+00	-0.000E+00	0.000E+00	1.753E-02	-2.317E-04	0.000E+00	0.000E+00	1.351E+00	9.010E+00	8.730E+02	-2.619E-05	-1.031E-06	0.000E+00	-4.740E+00	-1.089E+01		
0.0375	8.000E+00	-0.000E+00	0.000E+00	3.791E-02	-3.428E-04	0.000E+00	0.000E+00	2.027E+00	9.014E+00	8.730E+02	-5.740E-05	-3.834E-06	0.000E+00	-1.259E+01	-1.121E+00		
0.0500	8.000E+00	-0.000E+00	0.000E+00	6.530E-02	-5.111E-04	0.000E+00	0.000E+00	2.703E+00	9.018E+00	8.730E+02	-9.823E-05	-9.546E-06	0.000E+00	-2.322E+01	1.254E+01		
0.0625	8.000E+00	-0.000E+00	0.000E+00	9.902E-02	-8.166E-04	0.000E+00	0.000E+00	3.379E+00	9.020E+00	8.730E+02	-1.460E-04	-1.920E-05	0.000E+00	-3.524E+01	2.920E+01		
0.0750	8.000E+00	-0.000E+00	0.000E+00	1.385E-01	-1.409E-03	0.000E+00	0.000E+00	4.056E+00	9.021E+00	8.730E+02	-1.973E-04	-3.379E-05	0.000E+00	-4.819E+01	4.890E+01		
0.0875	8.000E+00	-0.000E+00	0.000E+00	1.833E-01	-2.459E-03	0.000E+00	0.000E+00	4.732E+00	9.020E+00	8.730E+02	-2.481E-04	-5.421E-05	0.000E+00	-6.136E+01	7.130E+01		
0.1000	8.000E+00	-0.000E+00	0.000E+00	2.329E-01	-4.153E-03	0.000E+00	0.000E+00	5.409E+00	9.018E+00	8.730E+02	-2.940E-04	-8.127E-05	0.000E+00	-7.405E+01	9.622E+01		
0.1125	8.000E+00	-0.000E+00	0.000E+00	2.869E-01	-6.672E-03	0.000E+00	0.000E+00	6.085E+00	9.014E+00	8.730E+02	-3.300E-04	-1.156E-04	0.000E+00	-8.555E+01	1.235E+02		
0.1250	8.000E+00	-0.000E+00	0.000E+00	3.448E-01	-1.018E-02	0.000E+00	0.000E+00	6.761E+00	9.010E+00	8.730E+02	-3.588E-04	-1.577E-04	0.000E+00	-9.529E+01	1.529E+02		
0.1375	8.000E+00	-0.000E+00	0.000E+00	4.063E-01	-1.481E-02	0.000E+00	0.000E+00	7.436E+00	9.004E+00	8.730E+02	-3.510E-04	-2.078E-04	0.000E+00	-1.028E+02	1.843E+02		
0.1500	8.000E+00	-0.000E+00	0.000E+00	4.711E-01	-2.066E-02	0.000E+00	0.000E+00	8.112E+00	8.999E+00	8.730E+02	-3.249E-04	-2.660E-04	0.000E+00	-1.083E+02	2.174E+02		
0.1625	8.000E+00	-0.000E+00	0.000E+00	5.388E-01	-2.777E-02	0.000E+00	0.000E+00	8.786E+00	8.994E+00	8.730E+02	-2.670E-04	-3.322E-04	0.000E+00	-1.102E+02	2.520E+02		
0.1750	8.000E+00	-0.000E+00	0.000E+00	6.086E-01	-3.611E-02	0.000E+00	0.000E+00	9.461E+00	8.989E+00	8.730E+02	-1.719E-04	-4.059E-04	0.000E+00	-1.085E+02	3.070E+02		
0.1875	8.000E+00	-0.000E+00	0.000E+00	6.799E-01	-4.561E-02	0.000E+00	0.000E+00	1.013E+01	8.985E+00	8.730E+02	-3.381E-05	-4.866E-04	0.000E+00	-1.063E+02	3.219E+02		
0.2000	8.000E+00	-0.000E+00	0.000E+00	7.532E-01	-5.617E-02	0.000E+00	0.000E+00	1.081E+01	8.983E+00	8.730E+02	1.537E-04	-5.737E-04	0.000E+00	-1.006E+02	3.656E+02		
0.2125	8.000E+00	-0.000E+00	0.000E+00	8.280E-01	-6.764E-02	0.000E+00	0.000E+00	1.148E+01	8.983E+00	8.730E+02	3.964E-04	-6.664E-04	0.000E+00	-9.368E+01	4.036E+02		
0.2250	8.000E+00	-0.000E+00	0.000E+00	9.044E-01	-7.987E-02	0.000E+00	0.000E+00	1.216E+01	8.984E+00	8.730E+02	6.999E-04	-7.639E-04	0.000E+00	-8.589E+01	4.420E+02		
0.2375	8.000E+00	-0.000E+00	0.000E+00	9.823E-01	-9.269E-02	0.000E+00	0.000E+00	1.283E+01	8.986E+00	8.730E+02	1.069E-03	-8.651E-04	0.000E+00	-7.733E+01	4.803E+02		
0.2500	8.000E+00	-0.000E+00	0.000E+00	1.061E+00	-1.059E-01	0.000E+00	0.000E+00	1.350E+01	8.990E+00	8.730E+02	1.510E-03	-9.692E-04	0.000E+00	-6.742E+01	5.224E+02		

# OpenFAST Outputs



# OpenFAST Post Processing

openfast

Public

Main repository for the NREL-supported OpenFAST whole-turbine and FAST.Farm wind farm simulation codes.

● Fortran ⭐ 326 📂 292

python-toolbox

Public

● Python ⭐ 25 📂 22

KiteFAST

Public

KiteFAST is a simulator for airborne wind energy systems based on the OpenFAST whole turbine simulator.

● Fortran 🔍 ⏪ ⏴



**E. Branlard**  
ebranlard

matlab-toolbox

Public

Collection of Matlab tools developed for use with OpenFAST

● MATLAB ⭐ 28 📂 47

r-test

Public

● Roff ⭐ 22 📂 53

openfast-feedstock

Public

Forked from conda-forge/openfast-feedstock

A conda-smithy repository for openfast.

Find a repository...

Type ▾

Language ▾

Sort ▾

⭐ Star ▾

pyDatView

Public

A crossplatform GUI to plot tabulated data from files (e.g. CSV, Excel, OpenFAST, HAWC2, Flex...), or python pandas dataframes

● Python ⭐ 81 📂 32 🔒 MIT License Updated 11 hours ago

openfast

Public

Forked from OpenFAST/openfast

Main repository for the NREL-supported OpenFAST whole-turbine simulation code. Documentation is available at <http://openfast.readthedocs.io>

● Fortran ⭐ 3 📂 3 🔒 Apache License 2.0 Updated 12 hours ago

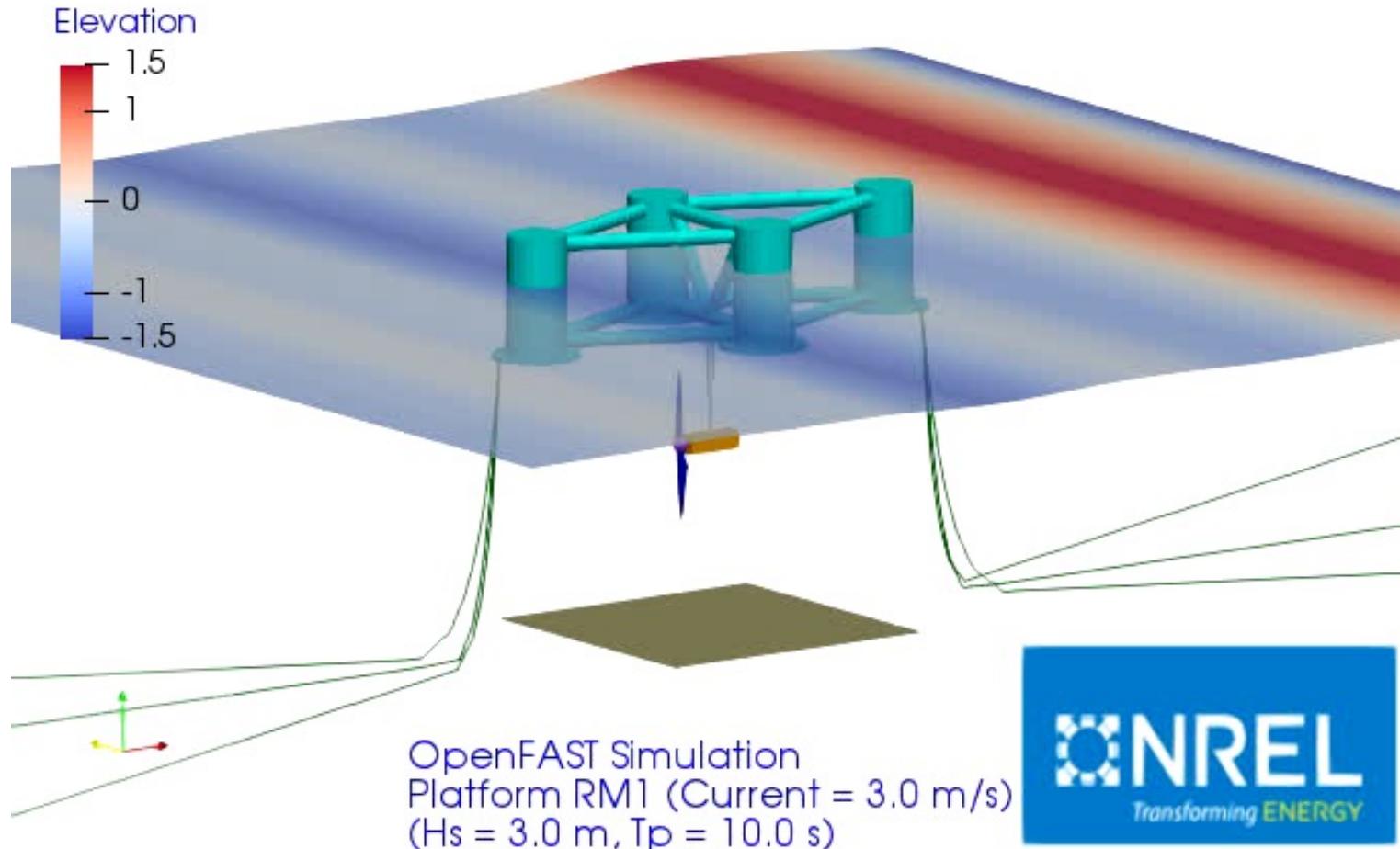
⭐ Star ▾

# Demonstration

- GitHub pages
- Documentation
- Forum
- Floating RM1 input files
  - Total run time, DT (OpenFAST driver), NumCrctn
  - DOFs (ElastoDyn)
  - Irregular waves
- Run OpenFAST
  - ./openfast\_Mac “Onshore/ MHK\_RM1\_Floating.fst”
  - openfast\_Windows.exe Onshore\ MHK\_RM1\_Floating.fst
- PyDatView
- Simulation visualization (vtk)\*

\*full capabilities in dev branch

# Floating RM1 Quad Animation



# Thank you!

OpenFAST Code: <https://github.com/OpenFAST/openfast>

OpenFAST Documentation: <https://openfast.readthedocs.io/en/main/>

OpenFAST Examples: <https://github.com/OpenFAST/r-test>

OpenFAST Data Visualization: <https://github.com/ebranlard/pyDatView>

Wind and Water Forum: <https://forums.nrel.gov/t/welcome-to-discourse-based-wind-water-forum/7>

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