



# Subdivision Surfaces

General surfaces  
Doo-Sabin Subdivision  
Basic Terminology

Modeling for Computer Graphics  
Faramarz Samavati

## Outline

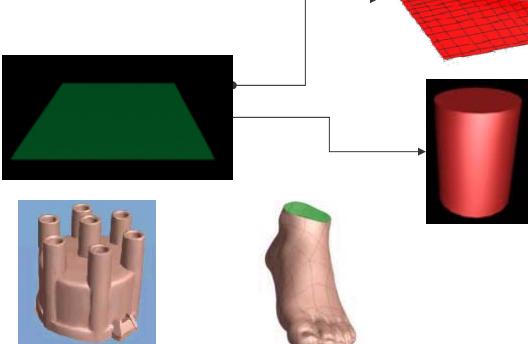
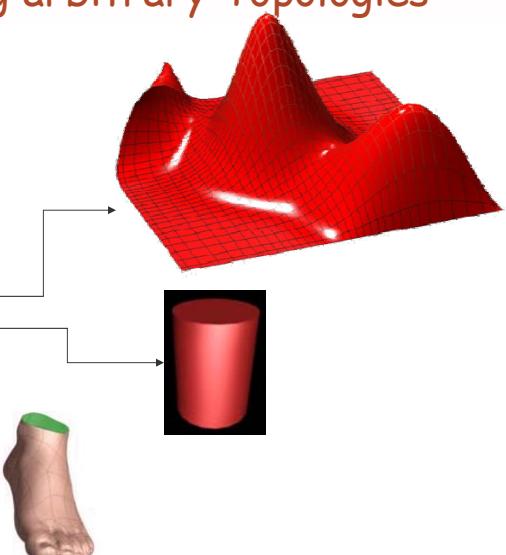
- ❖ B-Spline Based Subdivision curves
- ❖ Non-Bspline subdivision Curves
- ❖ Subdivision for Tensor-product surfaces, images
- ❖ Subdivision for General Topology surfaces, Doo-Sabin, Loop, Catmull-Clark
- ❖ Basic Terminology for General surfaces
- ❖ Sharp features and creases
- ❖ Adaptive Subdivision
- ❖ Data structures for subdivision Surfaces

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## Surfaces Having arbitrary Topologies

- ❖ Tensor Product Surfaces
- ❖ Non Tensor Surfaces
- ❖ We can't find u-curves and v-curves in general surfaces

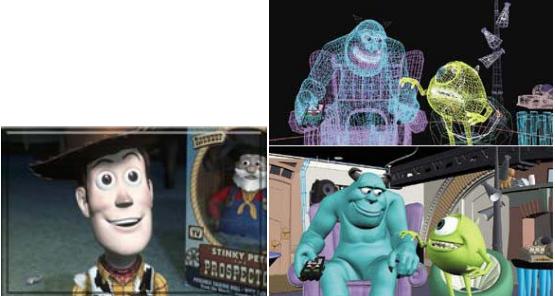



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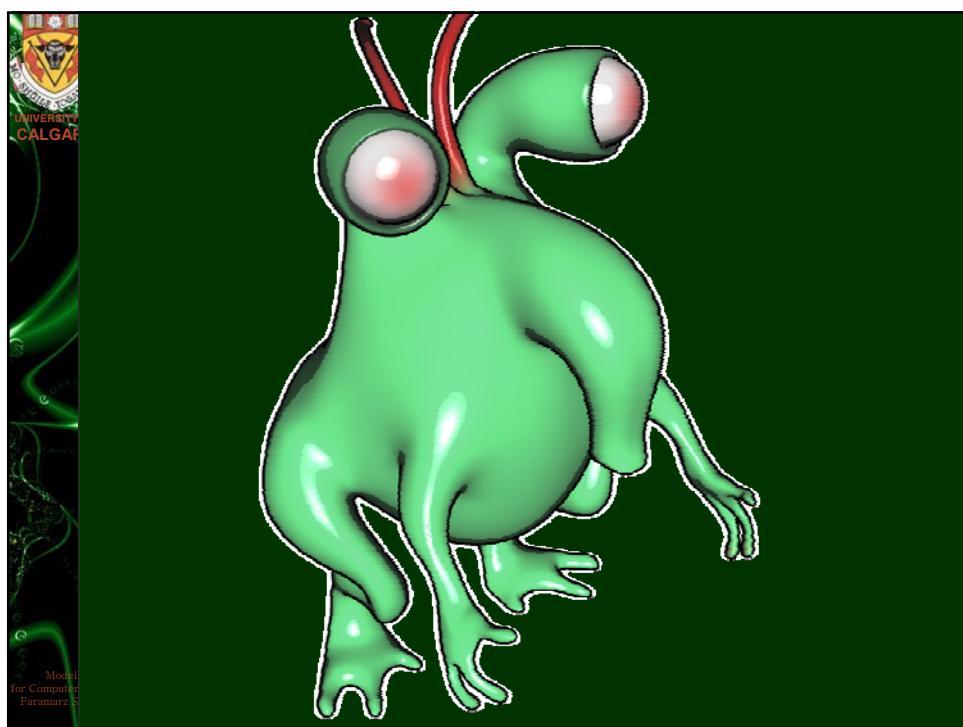
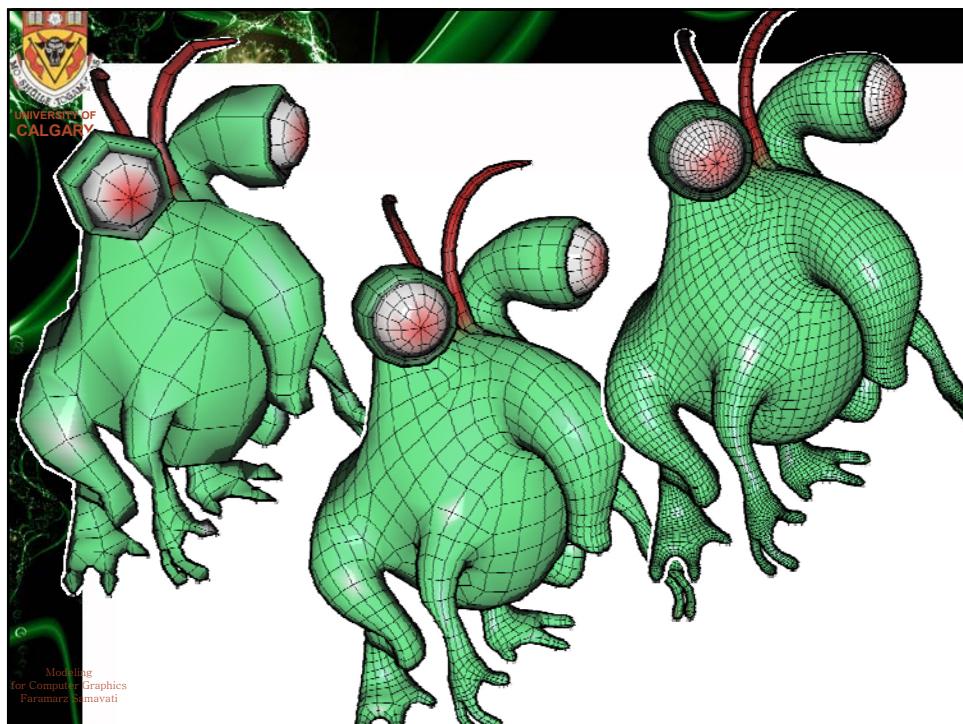
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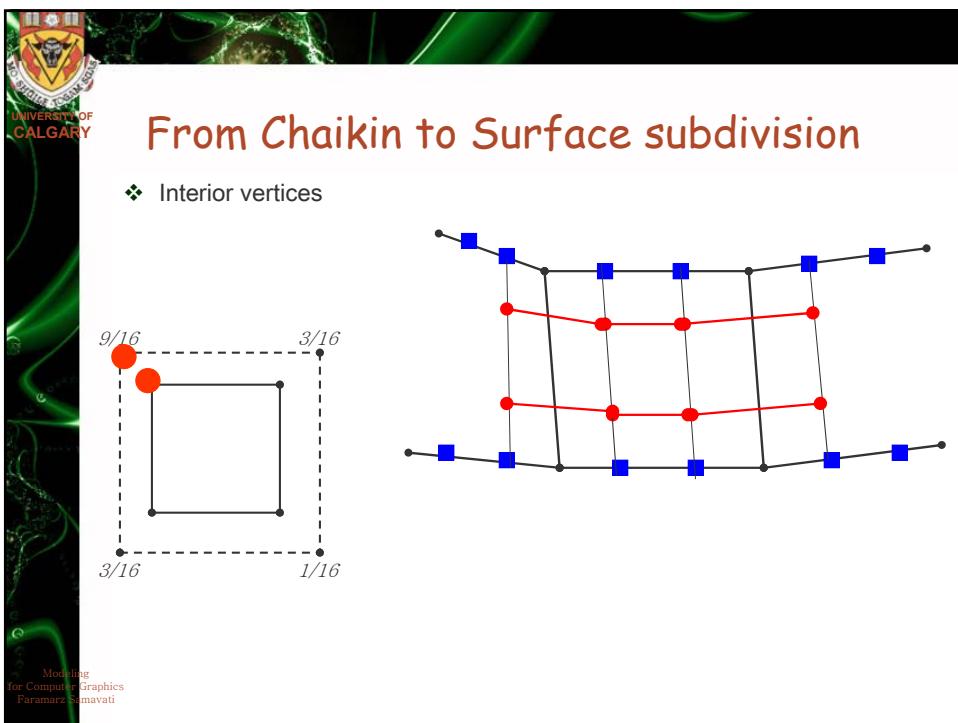
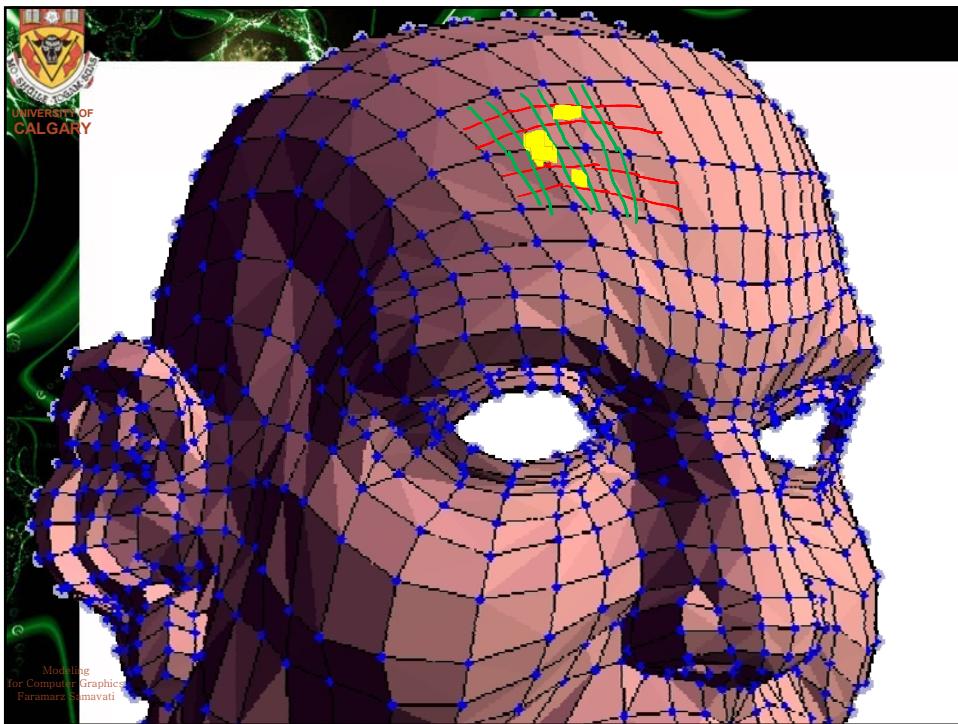
## General Subdivision

- ❖ Coarse mesh  Subdivision Fine mesh

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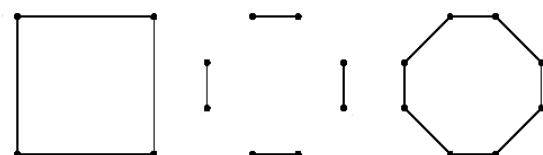






## From Chaikin to Doo-Sabin Subdivision

- ❖ 3D corner cutting method
- ❖ Generalization of Chaikin
- ❖ Each step =2 stages
- ❖ Contracting and adjoining

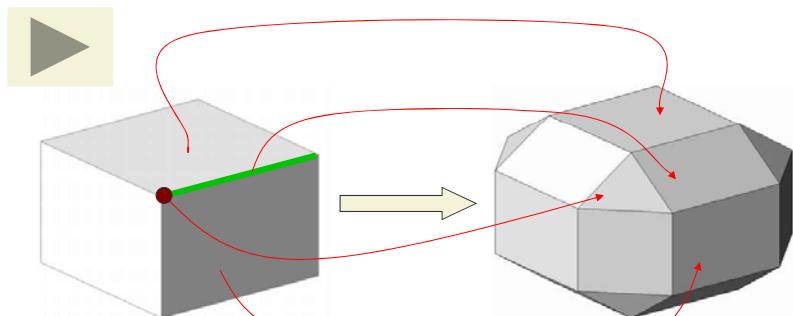


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## One Step of Doo-Sabin Subdivision

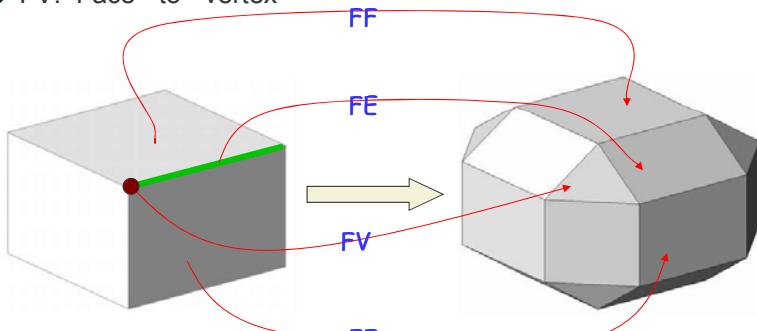
- ❖ One Step of Subdivision ( $F, V$ )  $\longrightarrow$  ( $NF, NV$ )
- ❖ Line  $\longrightarrow$  Face  $\longrightarrow$  Curve  $\longrightarrow$  Surface



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## Types of Faces

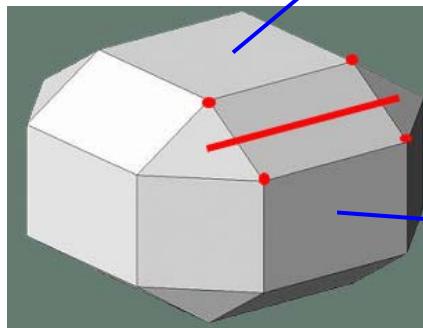
- ❖ Three types of New Faces(NF) :
- ❖ FF : Face- to - Face
- ❖ FE : Face - to - Edge
- ❖ FV: Face - to - vertex



## Edge-to-faces

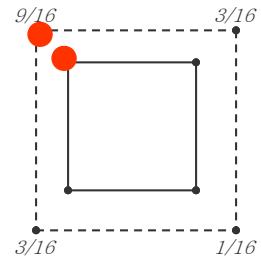
New Contracted Face

New Contracted Face



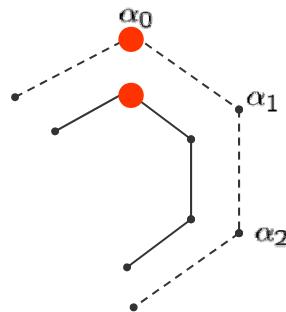
## Mask Details

- ❖ Interior vertices



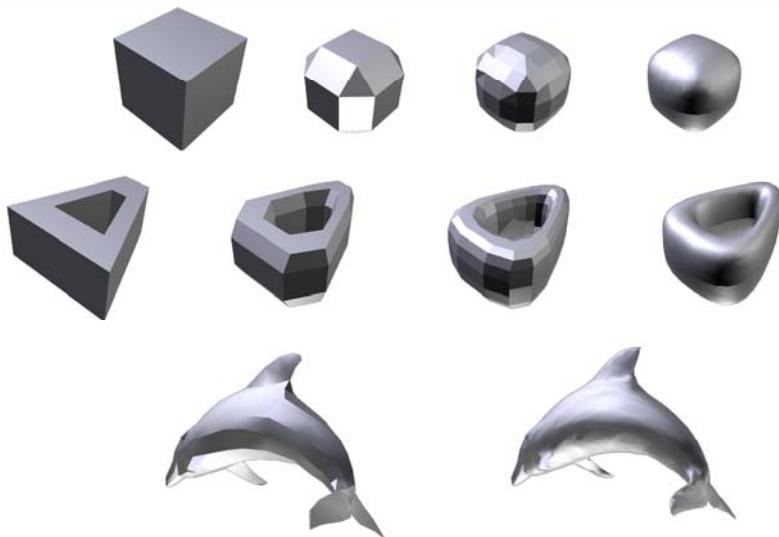
$$\alpha_0 = \frac{1}{4} + \frac{5}{4n}$$

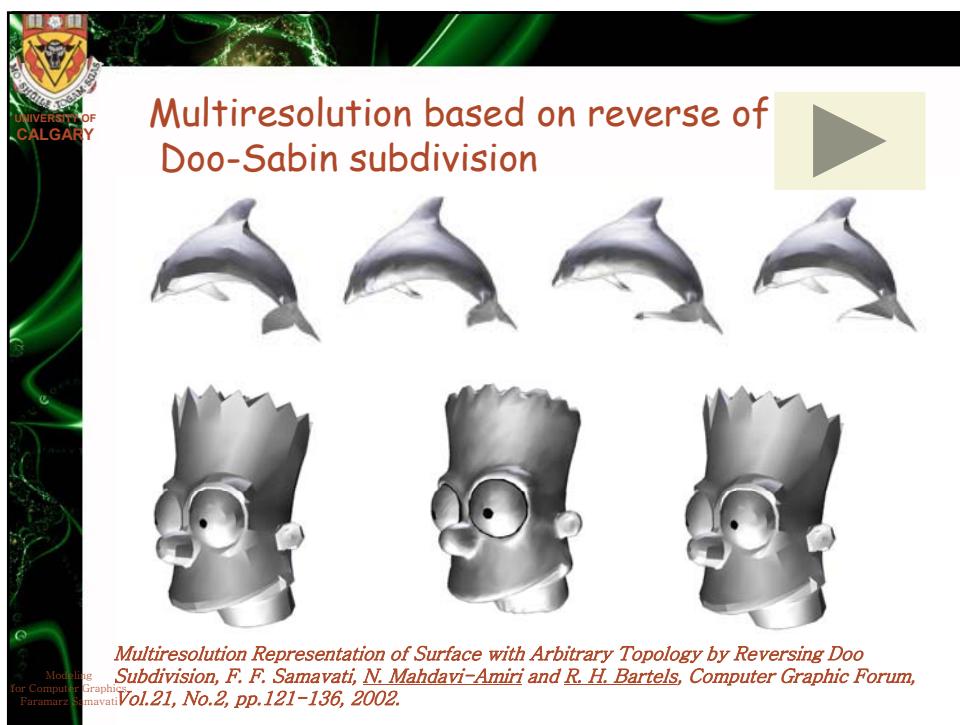
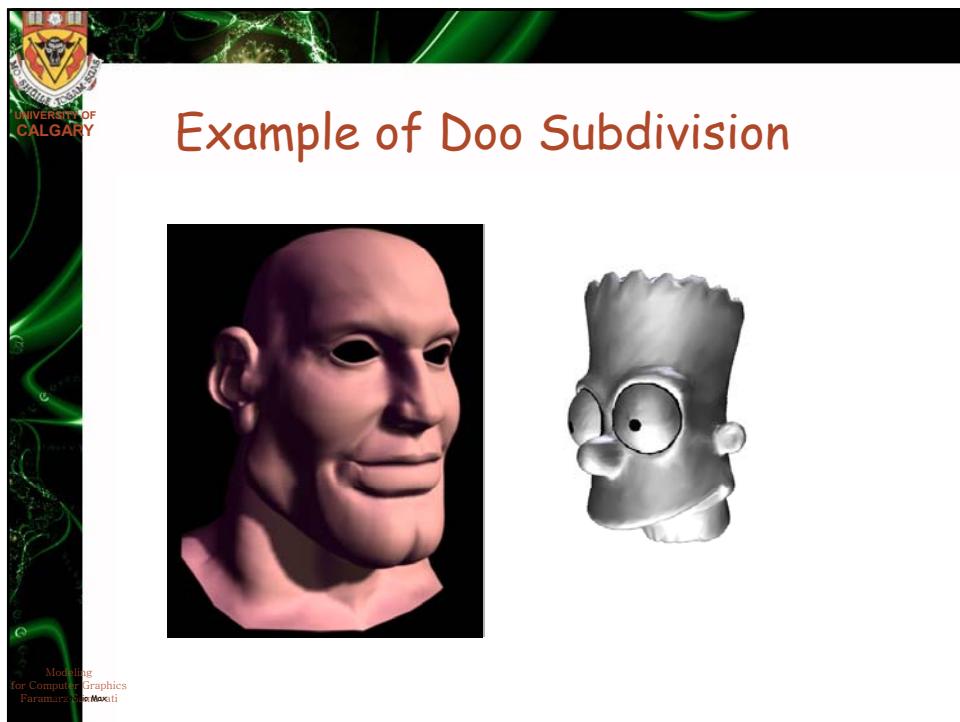
$$\alpha_i = \frac{(3+2\cos(2i\pi/n))}{4n}$$

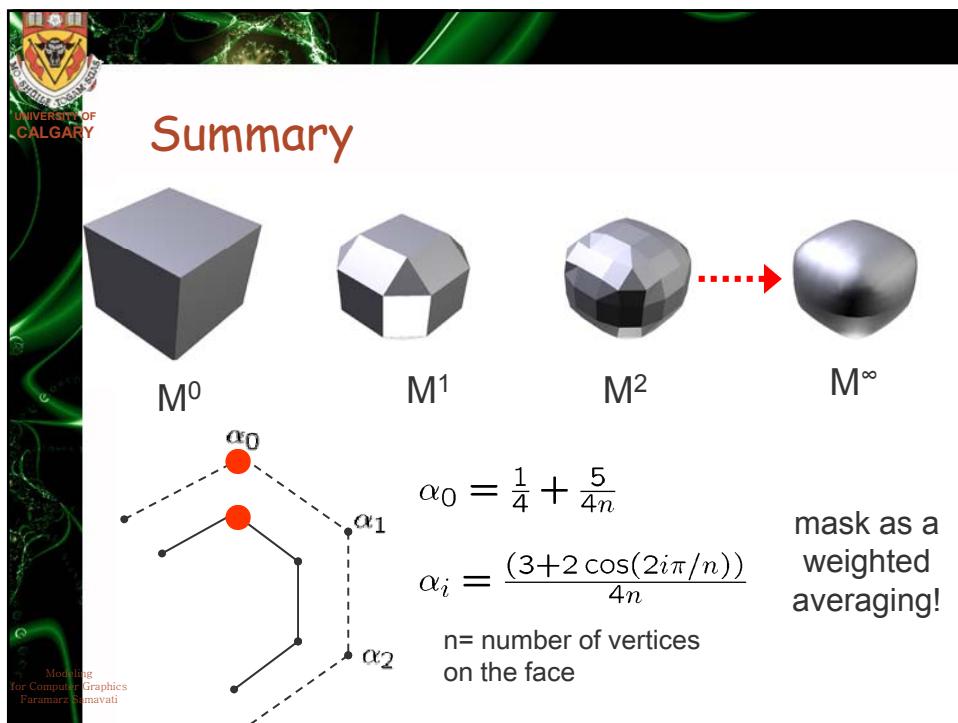
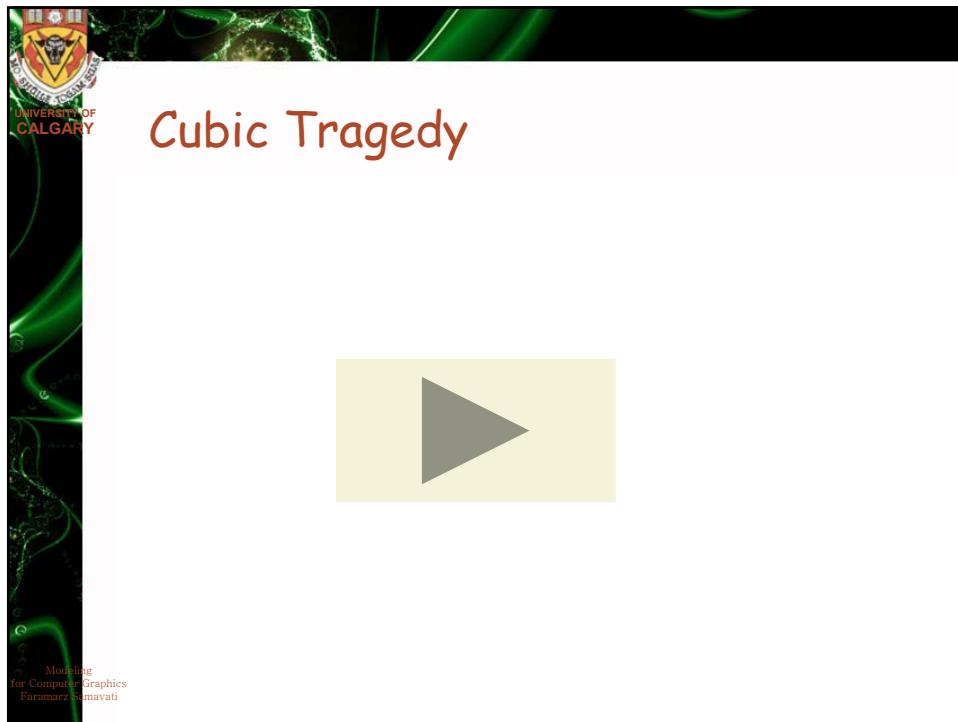


n= number of vertices  
on the face

## Examples









## Basic Terminology

- ❖ Topology
- ❖ 2d Manifold
- ❖ Closed/open meshes
- ❖ Orientable surfaces
- ❖ Euler characteristic formula
- ❖ Parametric/geometric smoothness

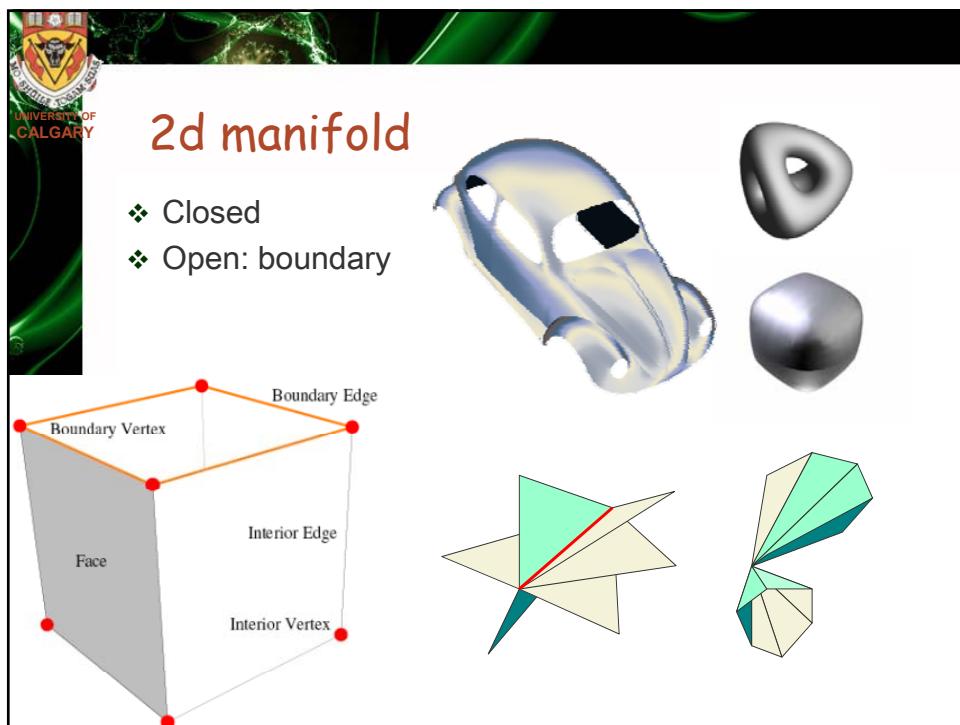
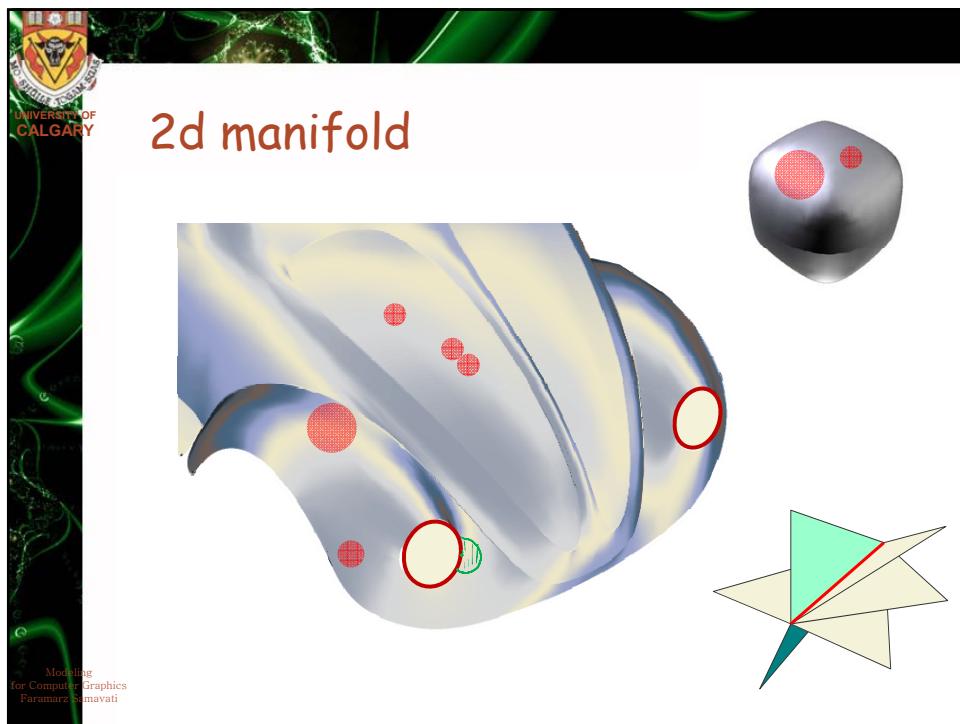
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## Topology

- ❖ Imagine all objects are made by a flexible material
- ❖ Stretch and shrink are allowed
- ❖ Cut and making hole are not allowed
- ❖ The resulting surfaces are called topologically “isomorph”



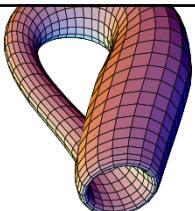
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## Orientation

- ❖ Consistent orientation  
For all points (or faces in mesh)





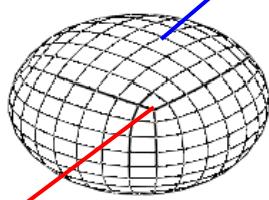


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## Parametric smoothness and geometric smoothness

Regular: inherited from u- and v-curves  
Usually parametric smoothness



Ir-regular: requires eigenanalysis  
just geometric smoothness can be checked

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## Euler characteristic formula

Name	Image	V (vertices)	E (edges)	F (faces)	
Tetrahedron		4	6	4	Simple closed meshes: $E=V+F-2$
Hexahedron or cube		8	12	6	
Octahedron		6	12	8	
Dodecahedron		20	30	12	
Icosahedron		12	30	20	



## Euler-Poincare Formula

- ❖  $E=V+F-2(1-G)$
- ❖ G is the genus of the surface
- ❖  $O(E)=O(V+F)$



Geneus
0
1
4

## Doo Surface Properties

- ❖ Convex hull property ( $\sum \alpha_i = 1$ )
- ❖ It produces mostly four sided faces
- ❖ Large region of the new polyhedron are covered with tensor product surface .
- ❖ Doo-Sabin surfaces are thus “mostly bi-quadratic B-splines”
- ❖ Limit surface has the first degree of parametric smoothness for regular vertices and first degree of geometric smoothness for ir-regular vertices



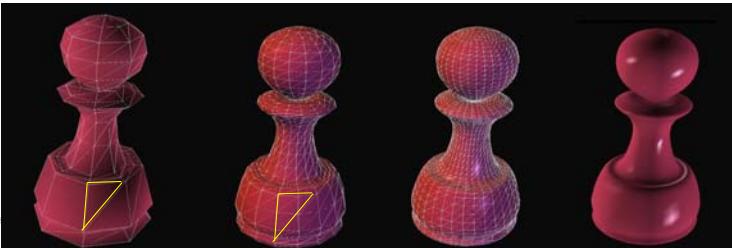
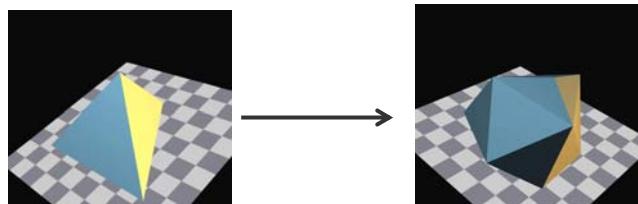
## Subdivision Surfaces

Loop and Catmull-Clark Subdivision

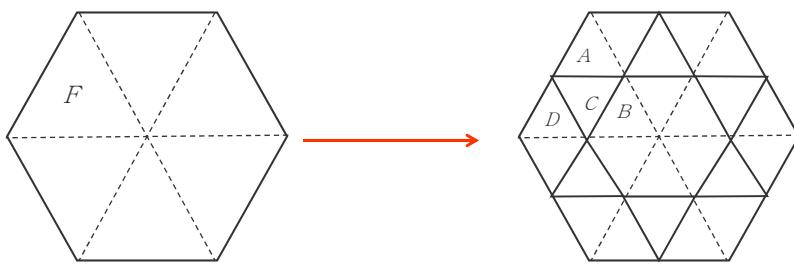
## Loop Subdivision



- ❖ A triangle-based subdivision



## Face Splitting

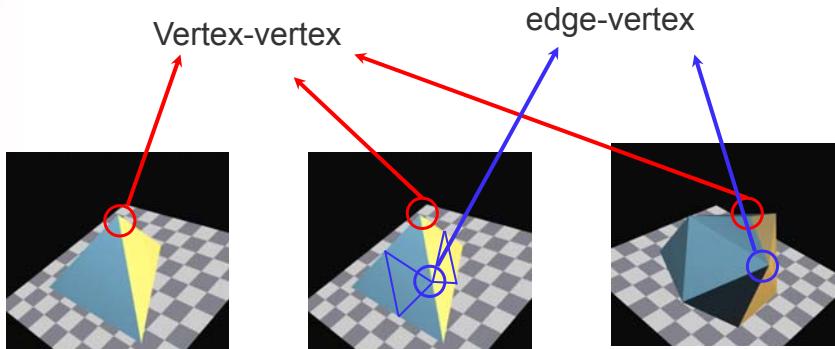


- ❖ Every face splits to four new faces  
 $F \rightarrow A, B, C, D$
- ❖ Updating the face structure
- ❖ Or equivalently: insert midpoints



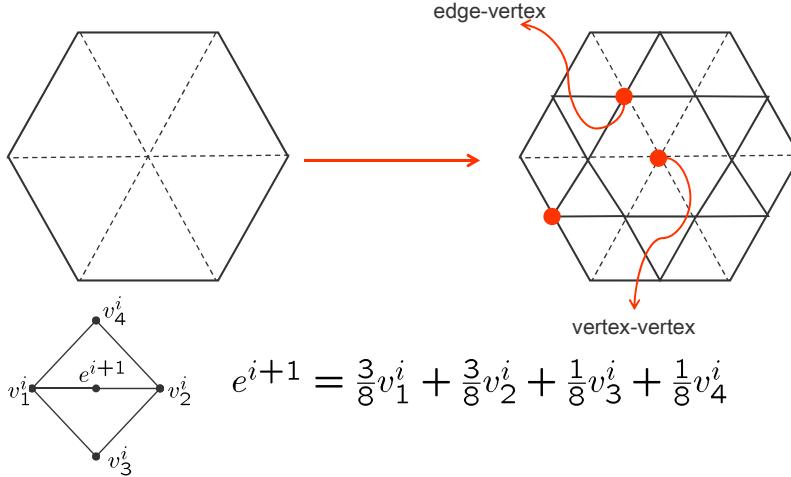
## Vertex-vertex and edge-vertex

- ❖ Or even and odd vertices
- ❖ Face split and then reposition



## Weighted averaging: Mask for Edge-Vertex

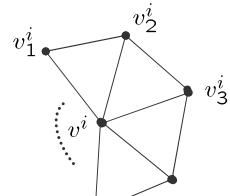
- ❖ Edge-vertex mask





## Mask for Vertex-Vertex

- ❖ n: number of adjacent vertices (valences)
- ❖ n > s



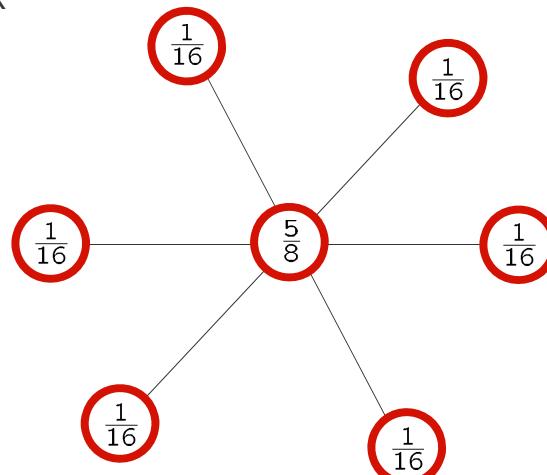
$$v^{i+1} = (1 - n\alpha)v^i + \alpha \sum v_j^i$$
$$\alpha = \frac{1}{n} \left( \frac{5}{8} - \left( \frac{3}{8} + \frac{1}{4} \cos \frac{2\pi}{n} \right)^2 \right)$$

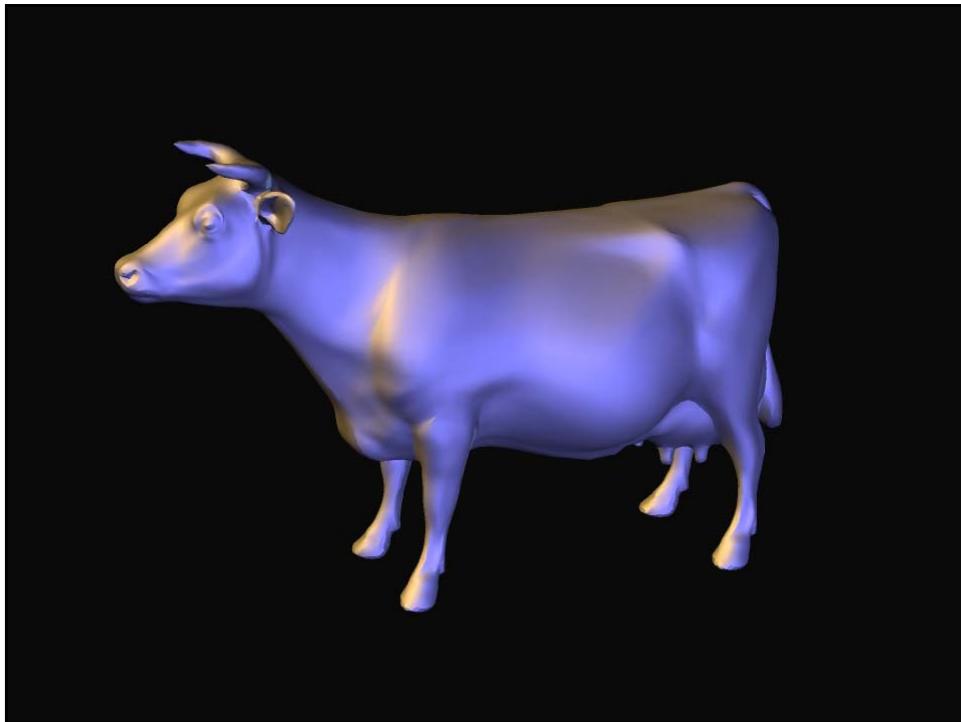
- ❖  $v^i$  has much more influence on  $v^{i+1}$
- ❖  $n=3, \alpha = \frac{3}{16}$  or  $v^{i+1} = \frac{7}{16}v^i + \frac{3}{16}(v_1^i + v_2^i + v_3^i)$



## Example: regular mask (n=6)

- ❖ Displacement Mask





Demo: NPR effects

The slide features a title "Demo: NPR effects" in red text at the top center. To the left of the text is the University of Calgary logo, which includes a crest with a bison and the text "UNIVERSITY OF CALGARY". Below the title, there are four versions of a cow model, each demonstrating a different rendering technique or effect:

- Top Left:** A wireframe or outline version of the cow.
- Top Right:** A version of the cow with a color gradient, similar to the one in the first image.
- Bottom Left:** A version of the cow with a more detailed shading and lighting, appearing as a white silhouette with some internal structure.
- Bottom Right:** A version of the cow with a smooth, solid-colored surface, possibly representing a different material or rendering style.

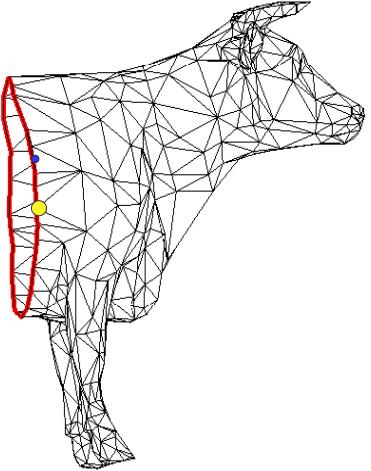
At the bottom left of the slide, there is a small copyright notice: "Modelling for Computer Graphics Faramorz Samavati".



## Boundary

- ❖ It is extension of the open curves
- ❖ No enough neighbours
- ❖ Using internal points move the boundary vertices!

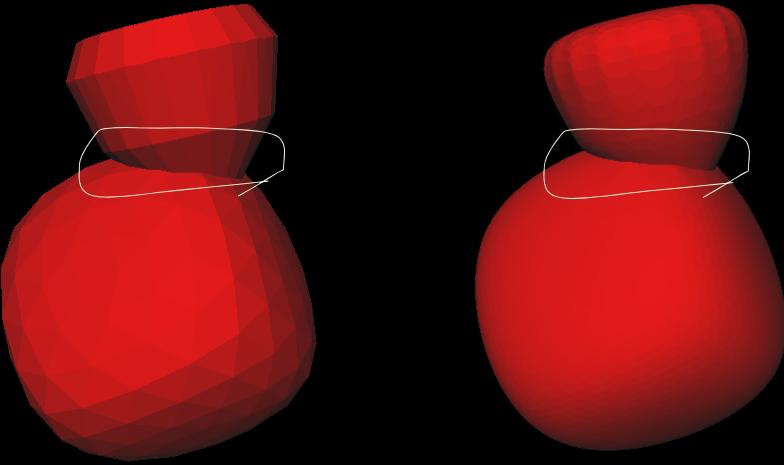
❖ Demo with open cube

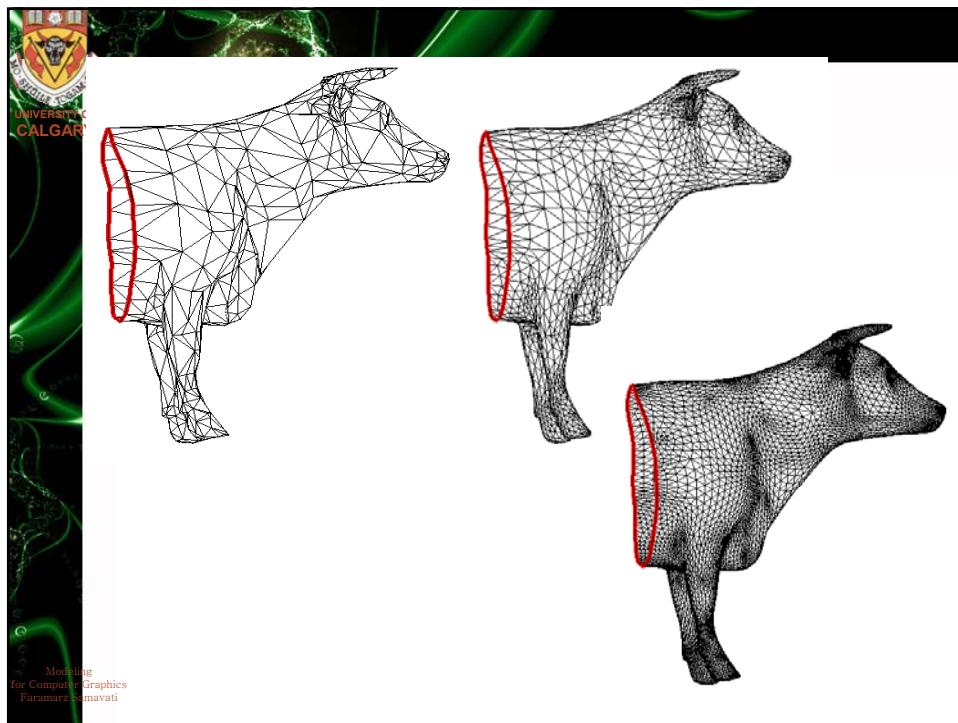
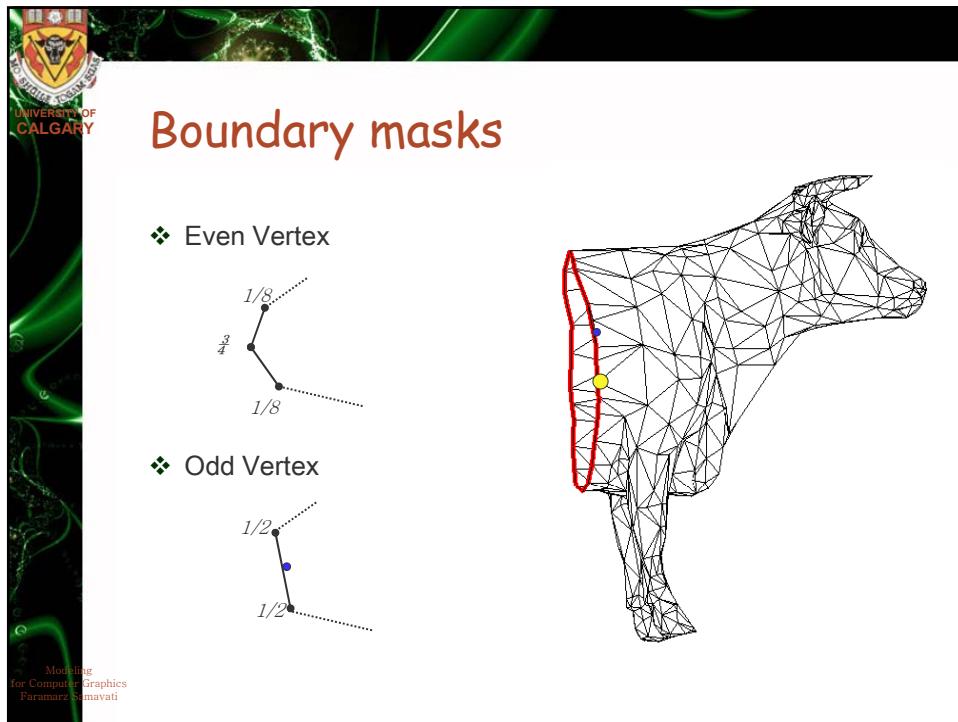


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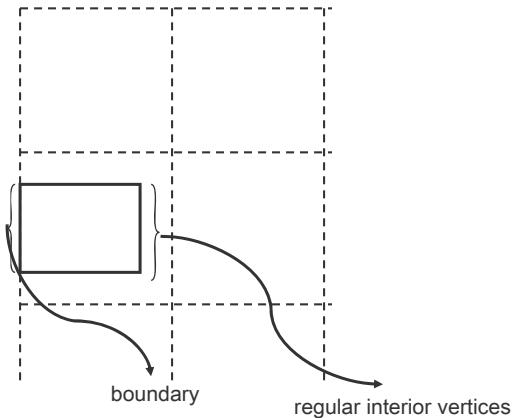


## Matched boundaries for two disjoint meshes





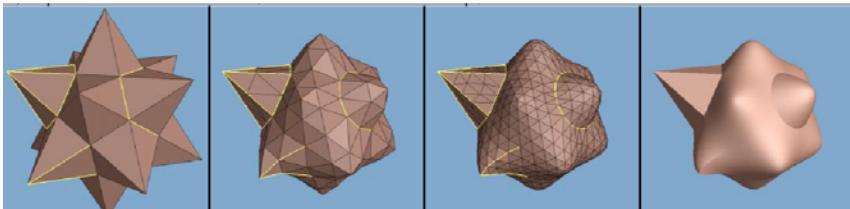
## Boundary Mask for Doo-Sabin



❖ Chaikin scheme for the boundary

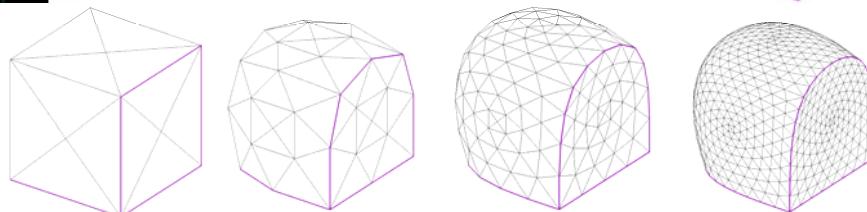
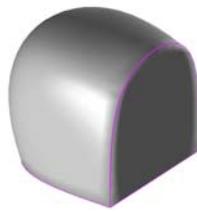
## Creases and Corners

- ❖ Using sharp edges to create creases and corners
- ❖ Tangent planes continuity across sharp edges is relaxed
- ❖ Creases are considered as boundary
- ❖ Resulting edges of sharp edges are tagged as sharp



## Corner points

- ❖  $v^i = v^{i+1}$  (are unchanged by subdivision)
- ❖ Vertices with sharp valence more than two are usually considered as corner point



## Properties

- ❖ Second degree of continuity for regular vertices
- ❖ First degree of geometric continuity for non-regular vertices
- ❖ Strong convex hull property
- ❖ *It produces mostly regular vertices*



## V -Clark Subdivision

- ❖ It is introduced in Computer Aided Design 1978.
- ❖ based on the tensor product of cubic B-spline
- ❖  $C^2$  at regular points and with the smooth tangent at extraordinary points

**Subdivision Surfaces in Character Animation**  
 Tony DeRose      Michael Kass      Tien Truong  
 Pixar Animation Studios

SIGGRAPH 98



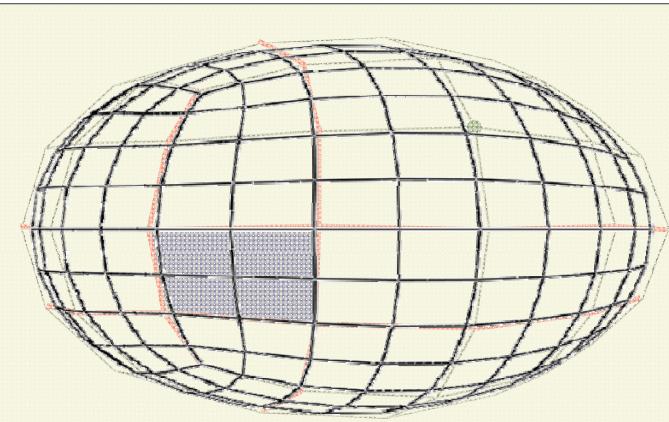


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## Bi-cubic B-Spline subdivision to a general subdivision surface

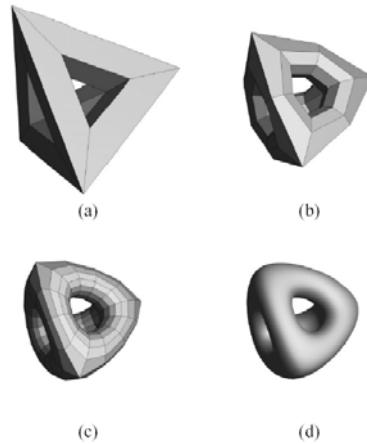




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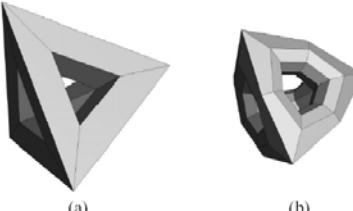
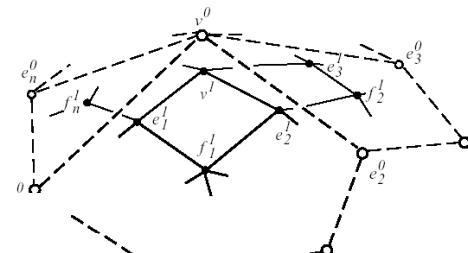
## Catmull-Clark Subdivision

- ❖ Splitting each face into a collection of quadrilateral subsurfaces
- ❖ The new vertices are computed using certain weighted average

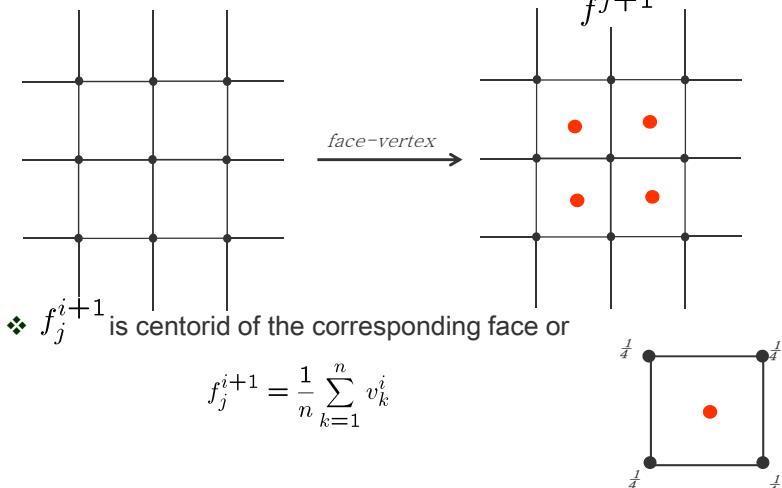


## Weighted average

- ❖ Three different types of vertices
- ❖ Face point
- ❖ Edge point
- ❖ Vertex point



## Face points

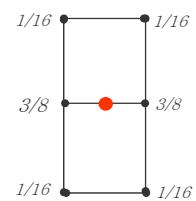


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## Edge-Vertex

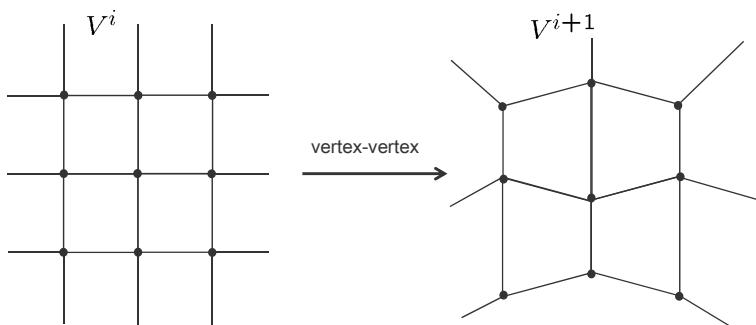
$e_j^{i+1}$  average the edge's end points and two face points on either side of the edge

$$e_j^{i+1} = \frac{v^i + e_j^i + f_{j-1}^{i+1} + f_j^{i+1}}{4}$$



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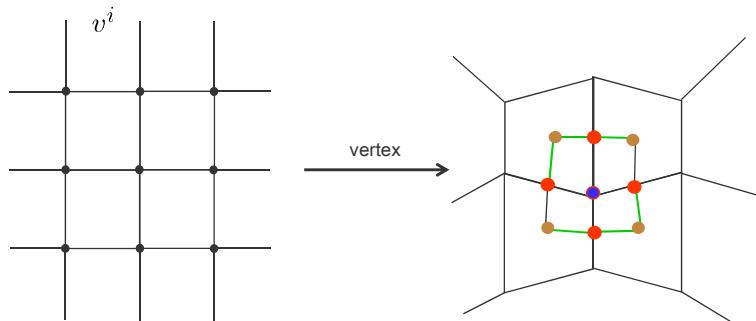
## Vertex-Vertex



- ❖ New vertex point  $v^{i+1}$ : assuming there are  $n$  faces around  $v^i$ . It is computed by:

$$v^{i+1} = \frac{n-2}{n}v^i + \frac{1}{n^2} \sum_j e_j^i + \frac{1}{n^2} \sum_j f_j^{i+1}$$

## New Faces



- ❖ Each new face consist of a loop:

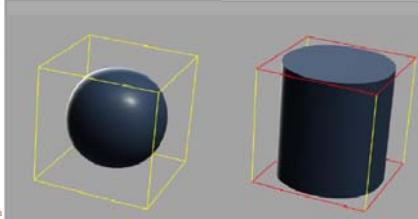
$$v \rightarrow e_j \rightarrow f_j \rightarrow e_{j+1} \rightarrow v$$

## Boundary, sharp edges, corners

- ❖ Cubic B-Spline curve masks for boundary and sharp edges
- ❖ Crease is a chain of sharp edges
- ❖ Corner points keep unchanged

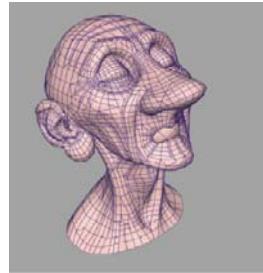
Red edges are tagged sharp

sharp creases are used between the skin and the finger nails



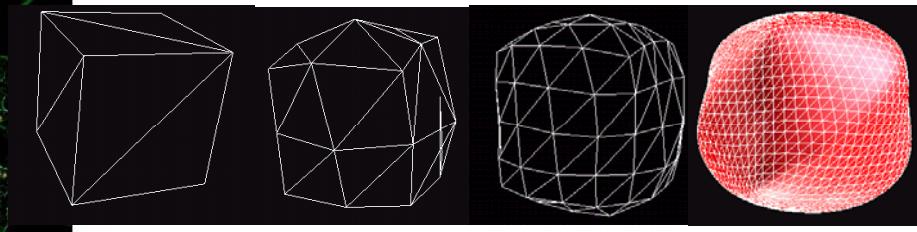
## Example

- ❖ Geri's
  - ❖ Head
  - ❖ Hands
  - ❖ Clothing: Jacket, pants, shirt, tie and shoes



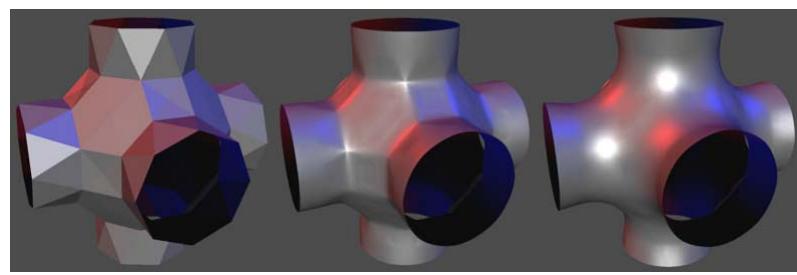
## Butterfly Scheme

- ❖ It was proposed by Dyn, Levin and Gregory (TOG 1991)
- ❖ It is a triangular based subdivision
  - ❖ Face split step is the same as Loop
- ❖ Interpolating  $C^1$  subdivision



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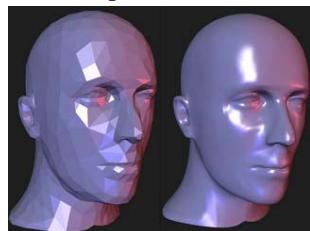
## Modified Butterfly Subdivision



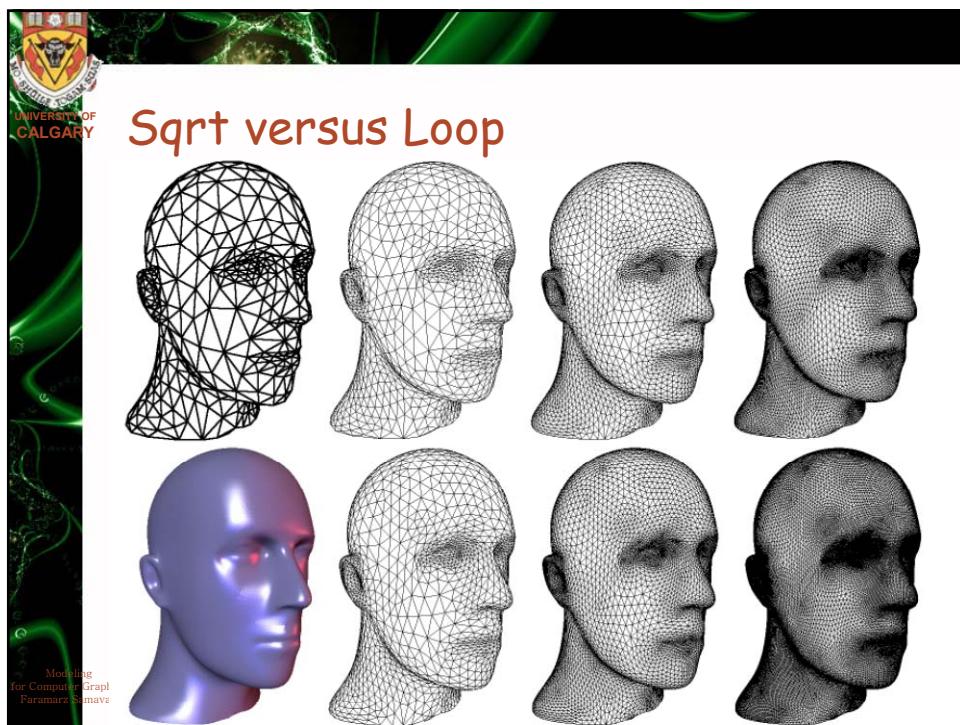
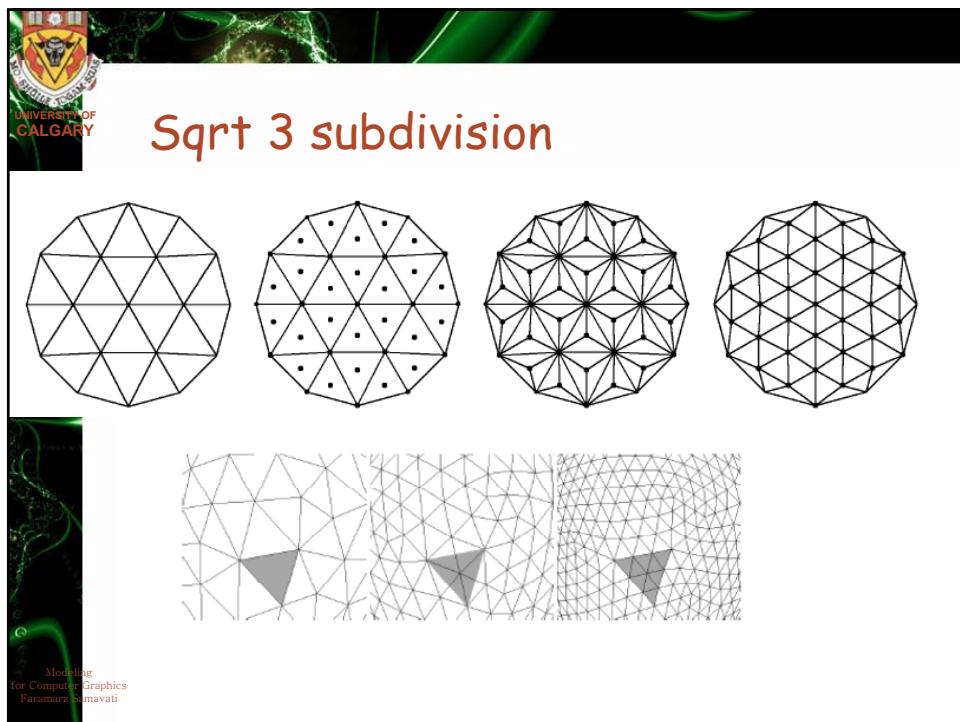
Control mesh

original scheme

Modified scheme



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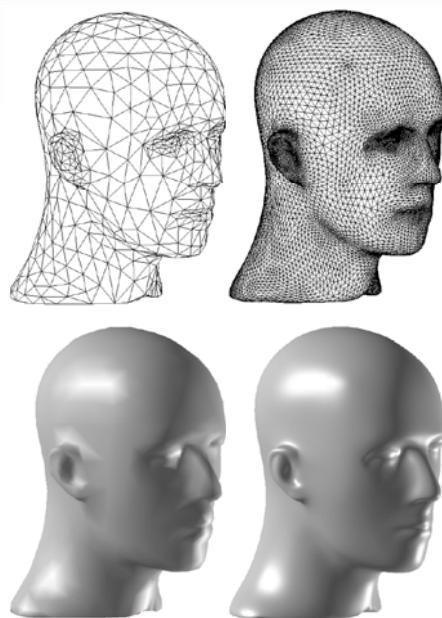
# Subdivision Surfaces

Adaptive subdivision  
Data Structure

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## Adaptive Subdivision

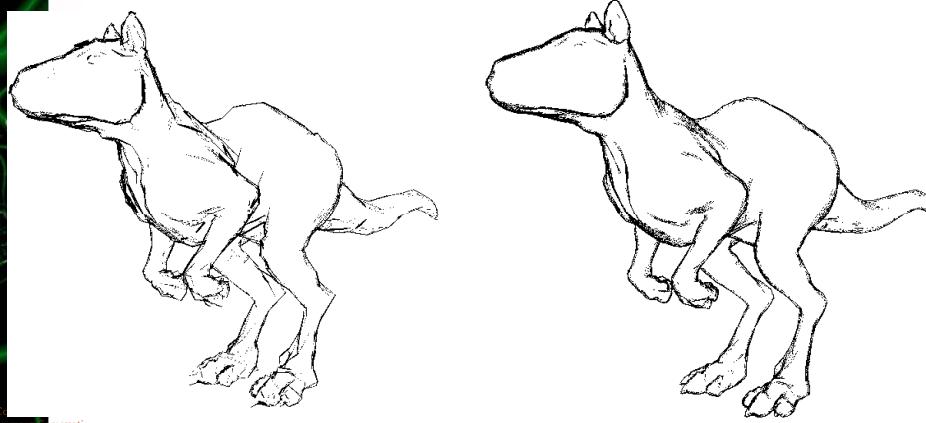
- ❖ Do we really need to subdivide flat areas?
- ❖ Growth factor of faces?
- ❖ Flat area : Low curvature area



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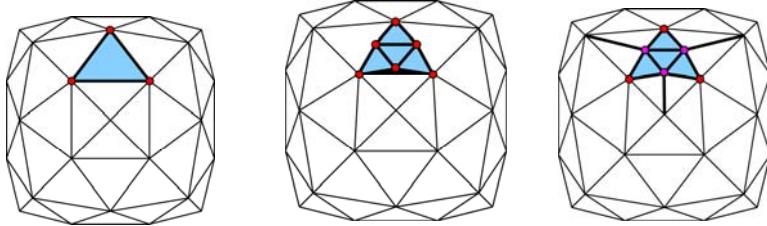
## Interest based selected area

- ❖ Features: silhouette, high curvature, ...



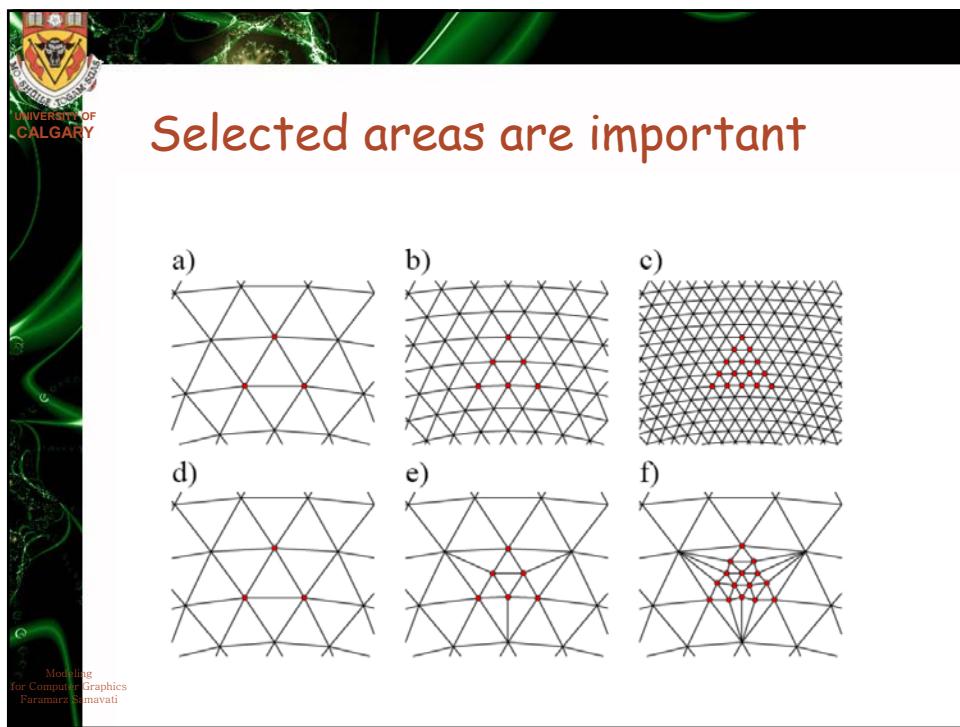
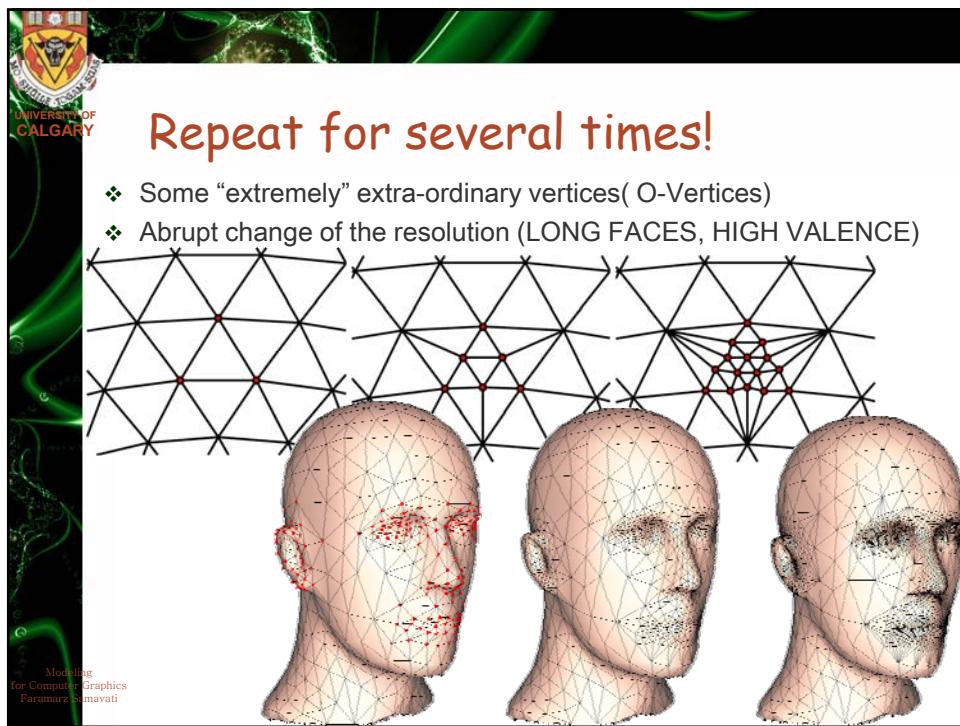
## Adaptive subdivision (Loop)

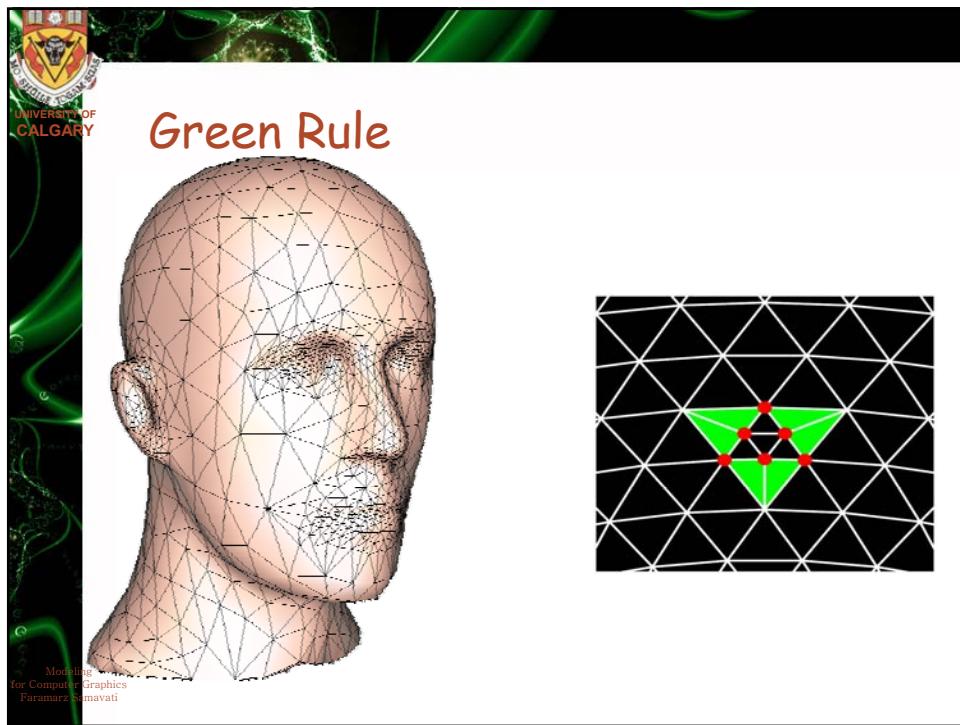
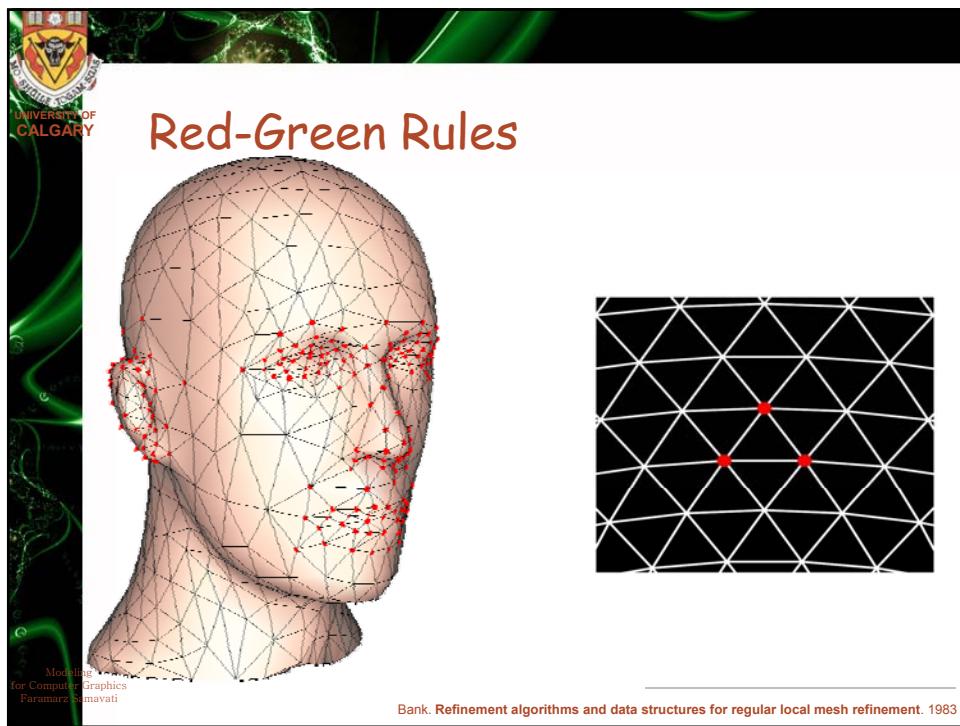
- ❖ Just subdivide and split some triangles
- ❖ Cracks !
- ❖ Solution: insert new edges (T-junctions)

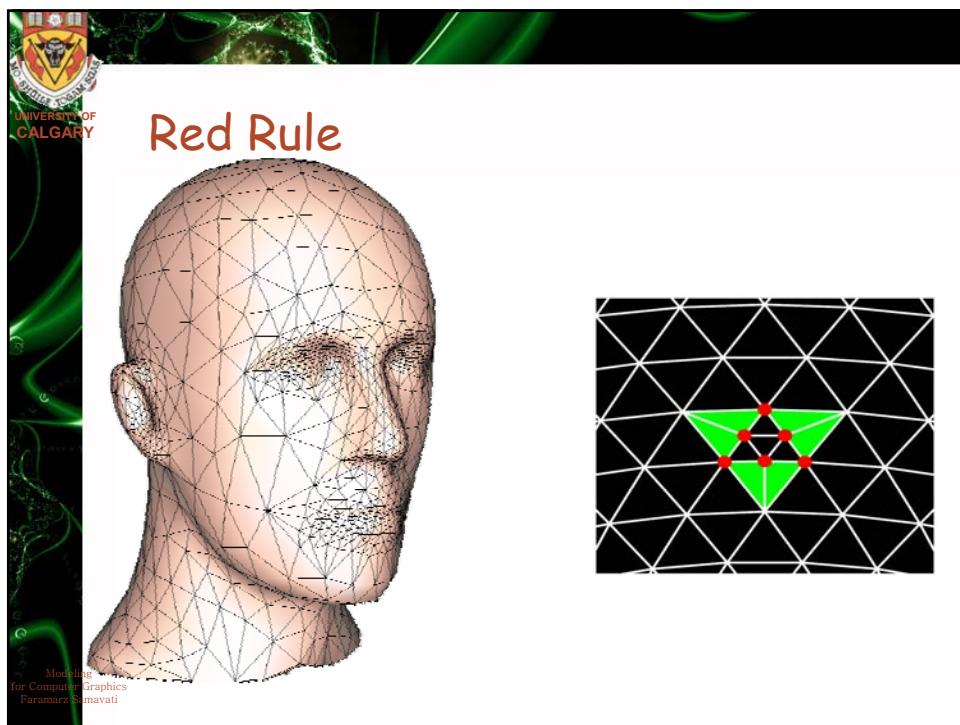
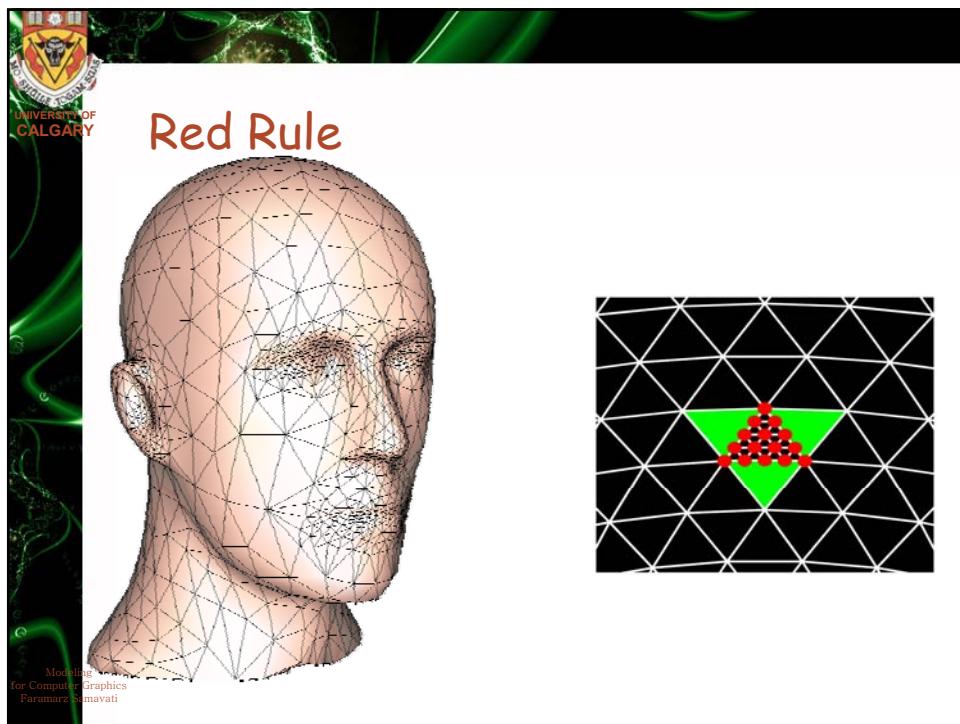


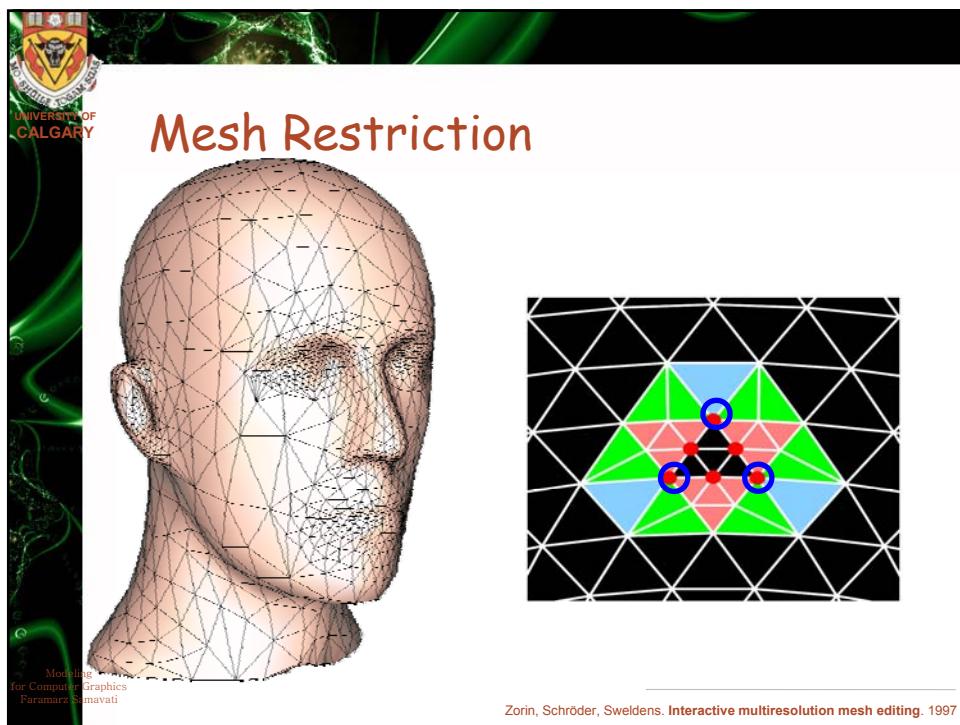
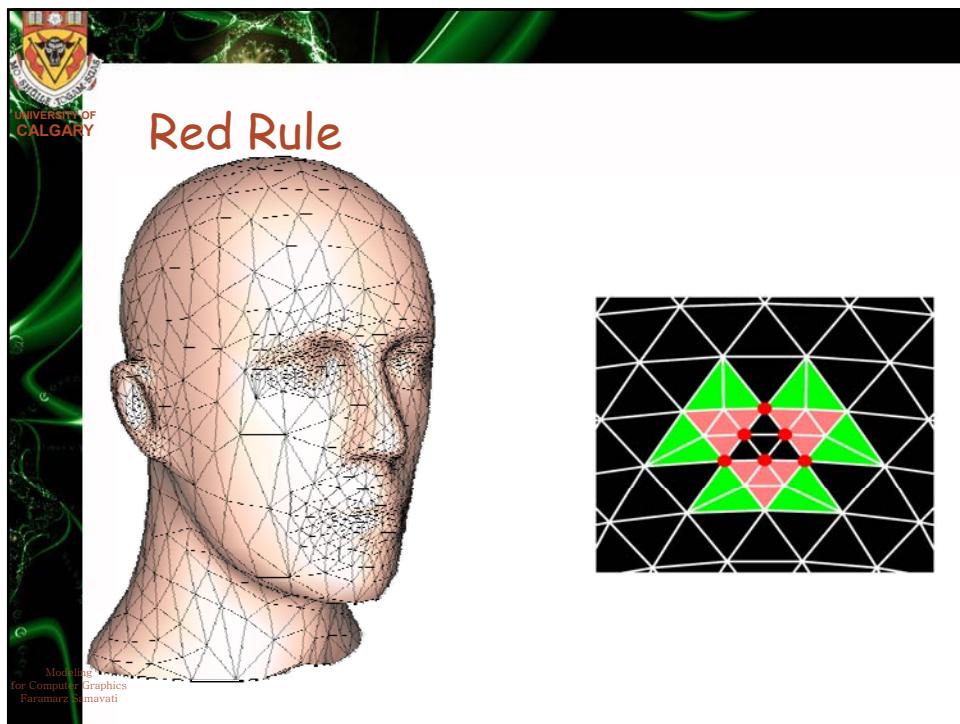
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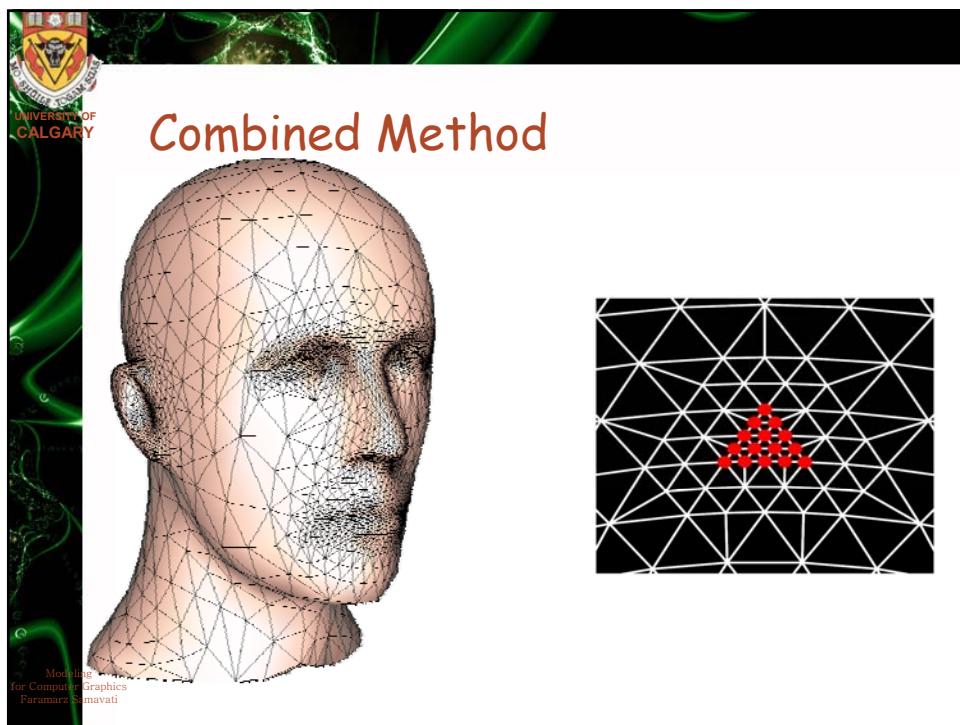
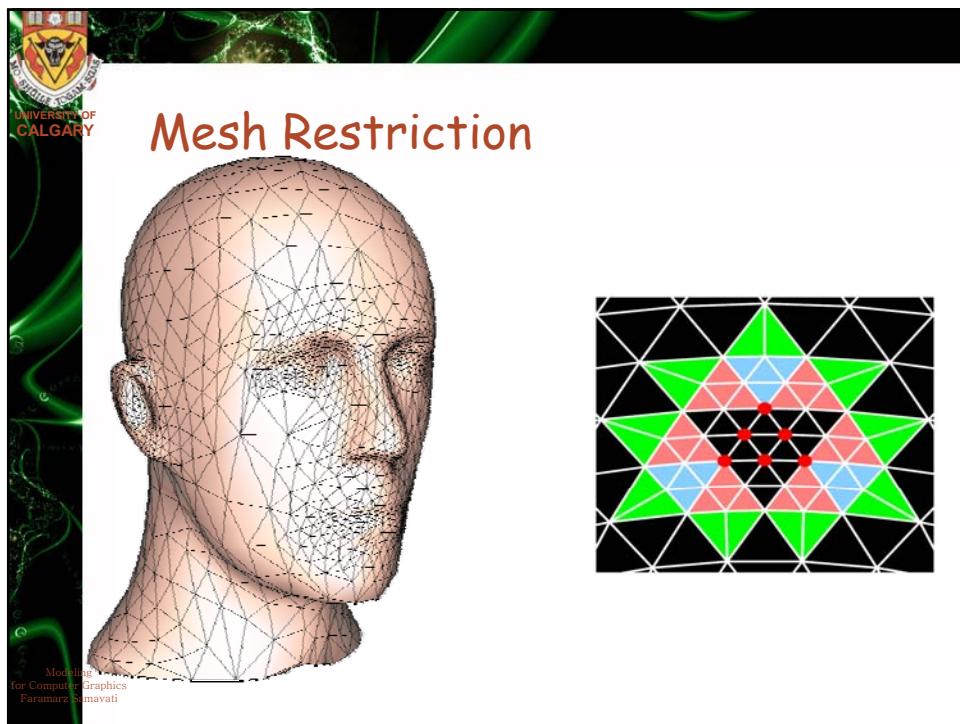
A. Amresh, G. Farin, and A. Razdan. Adaptive subdivision schemes for triangular meshes, 2003

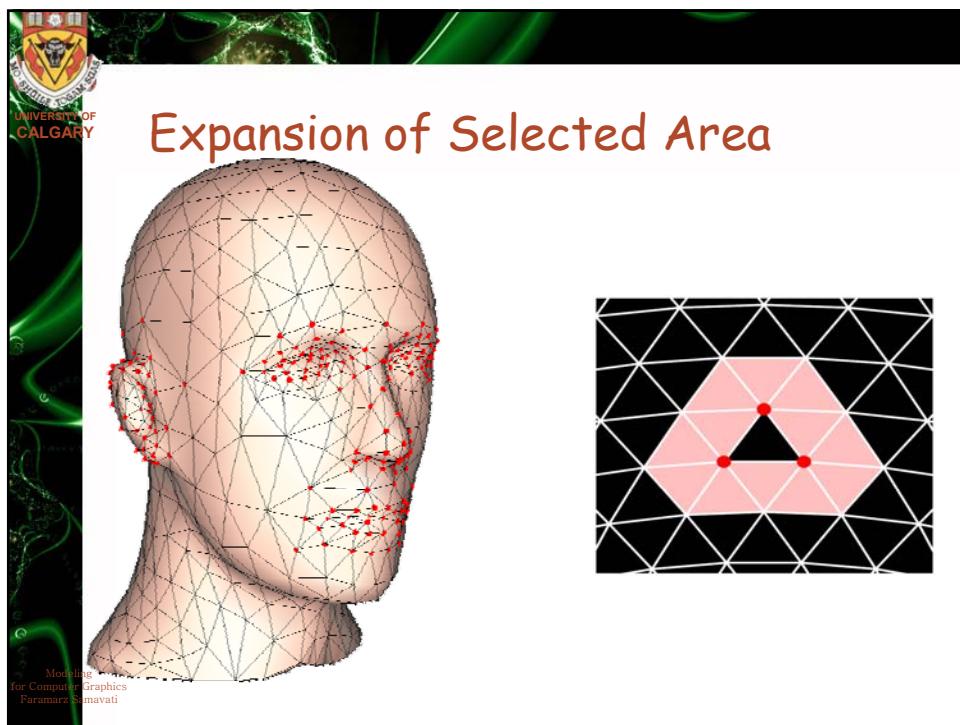
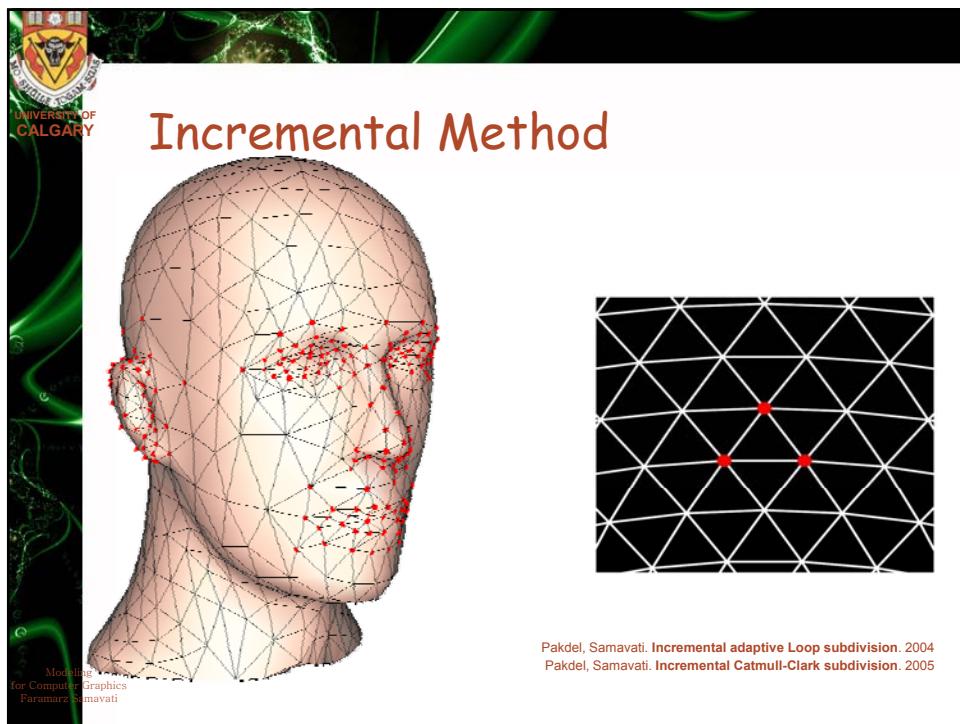


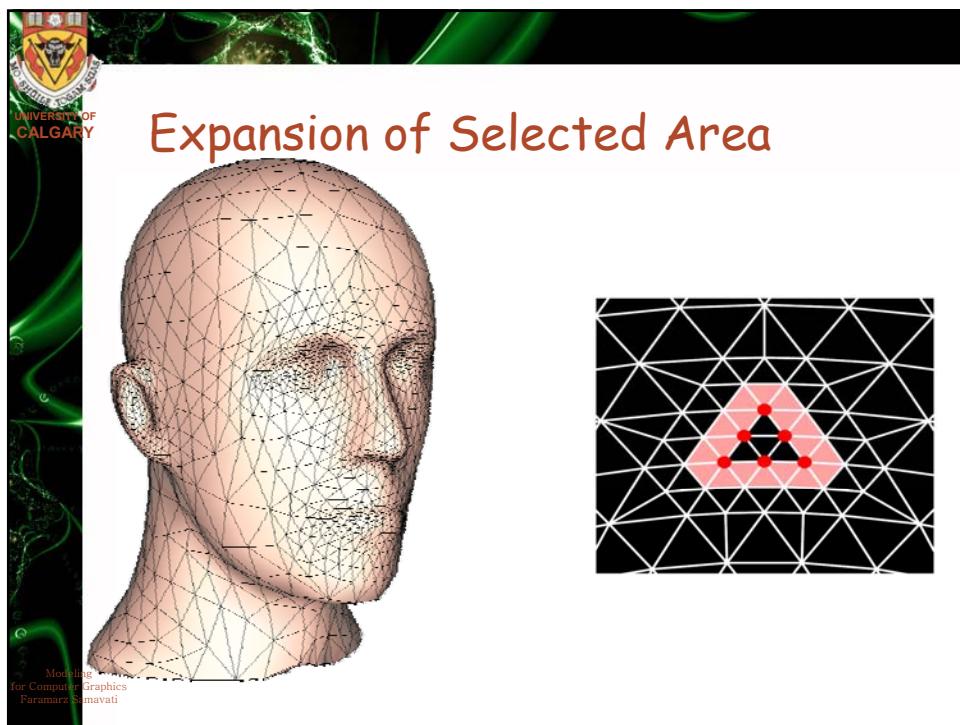
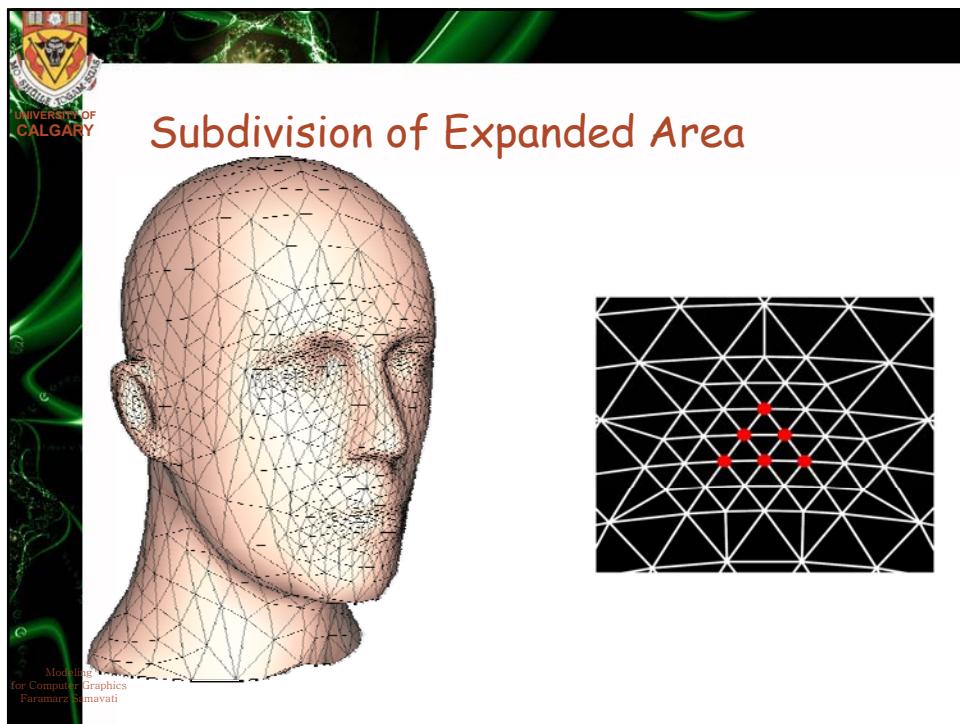


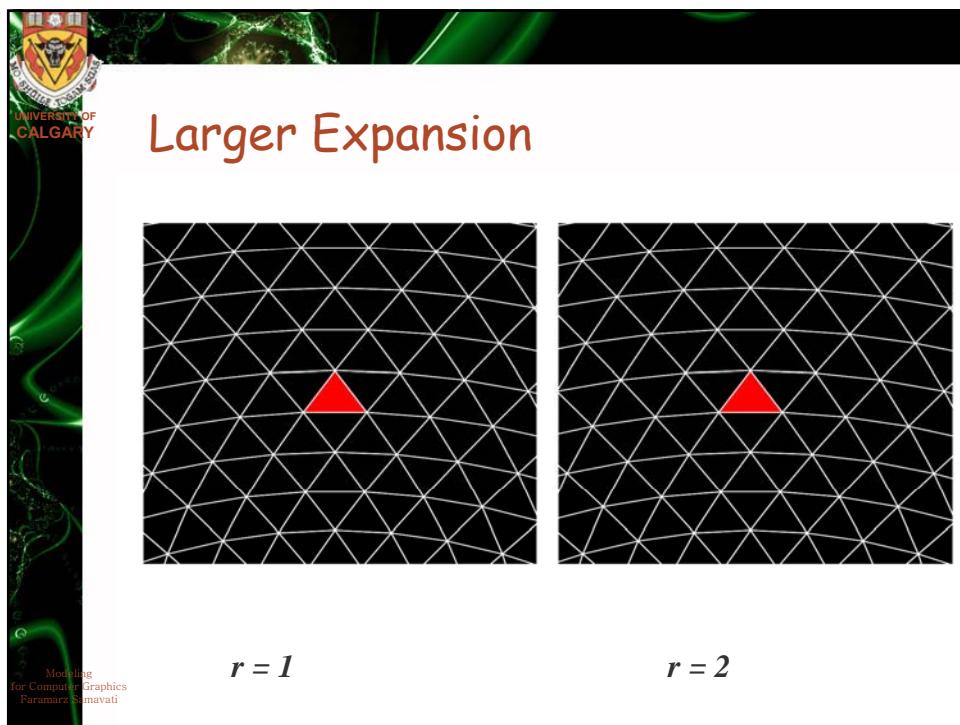
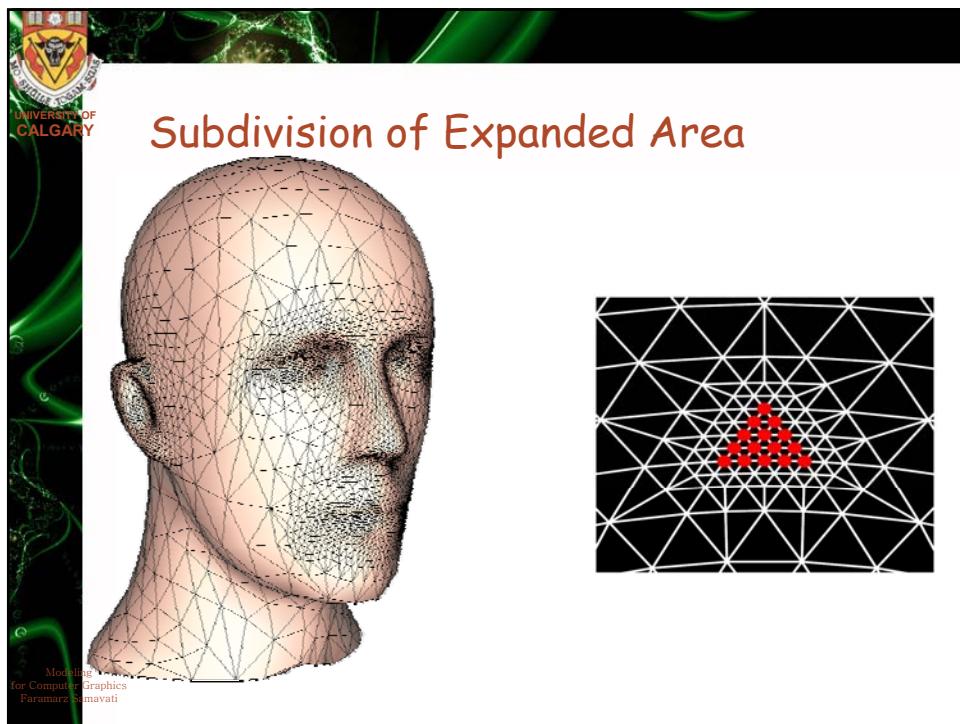


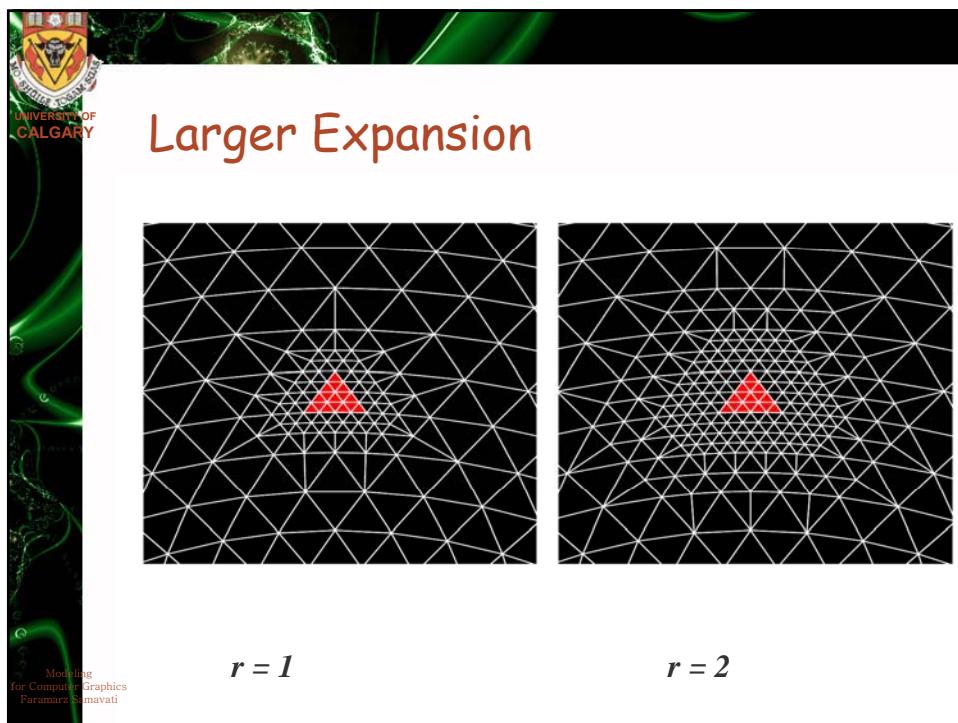
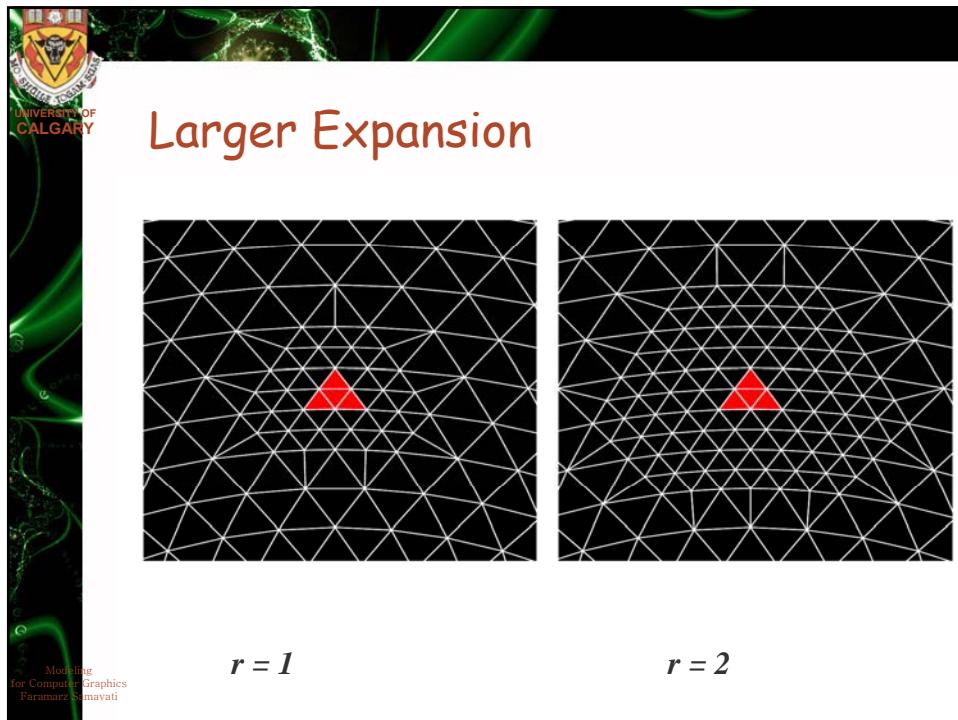


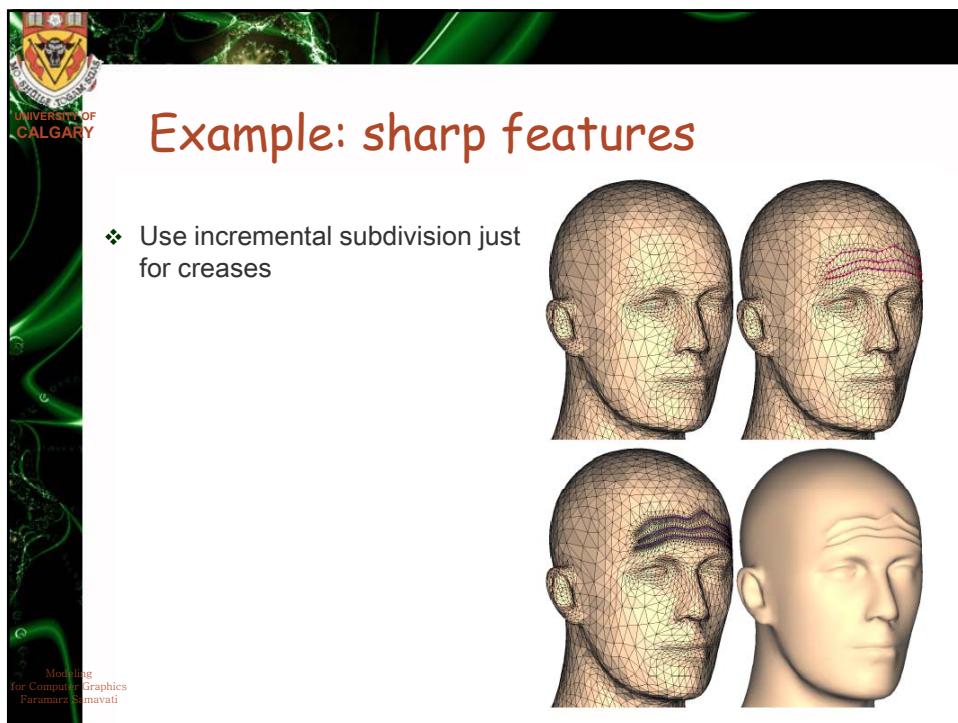
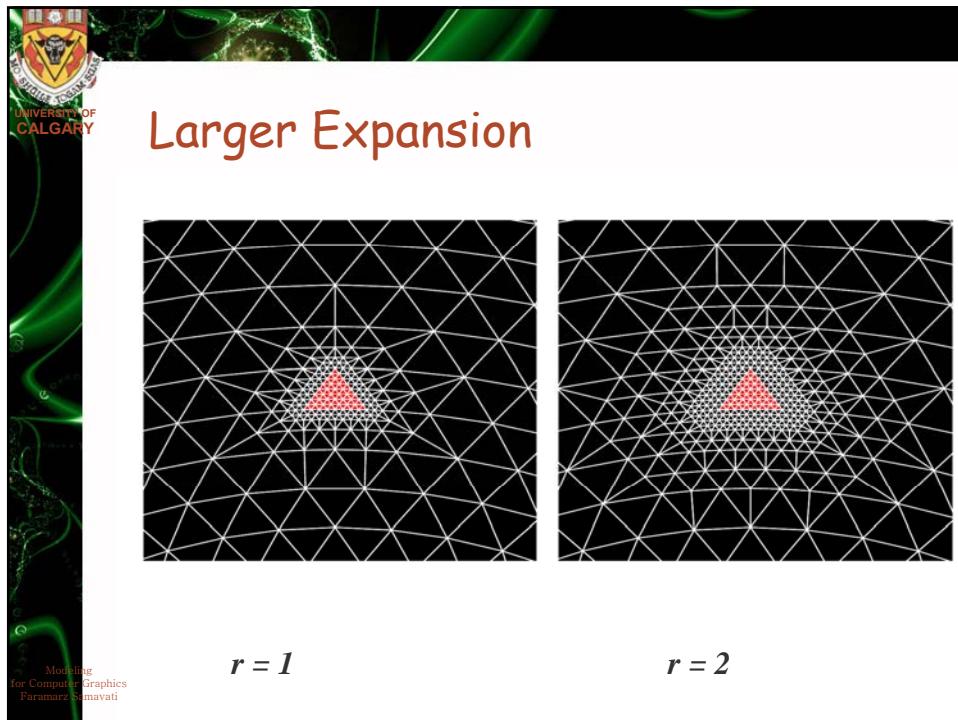


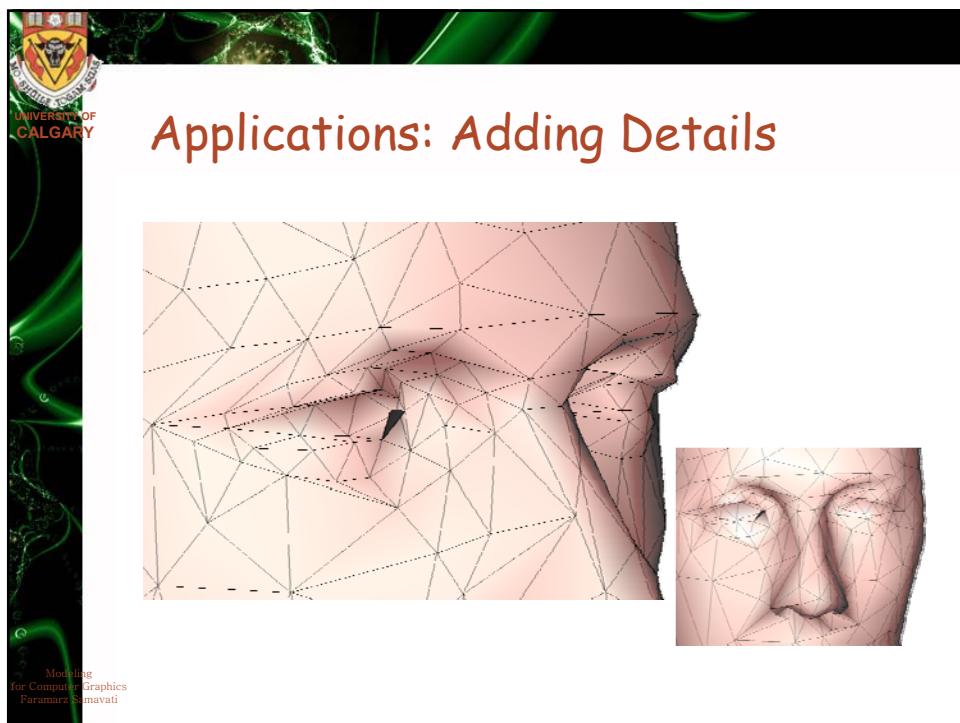
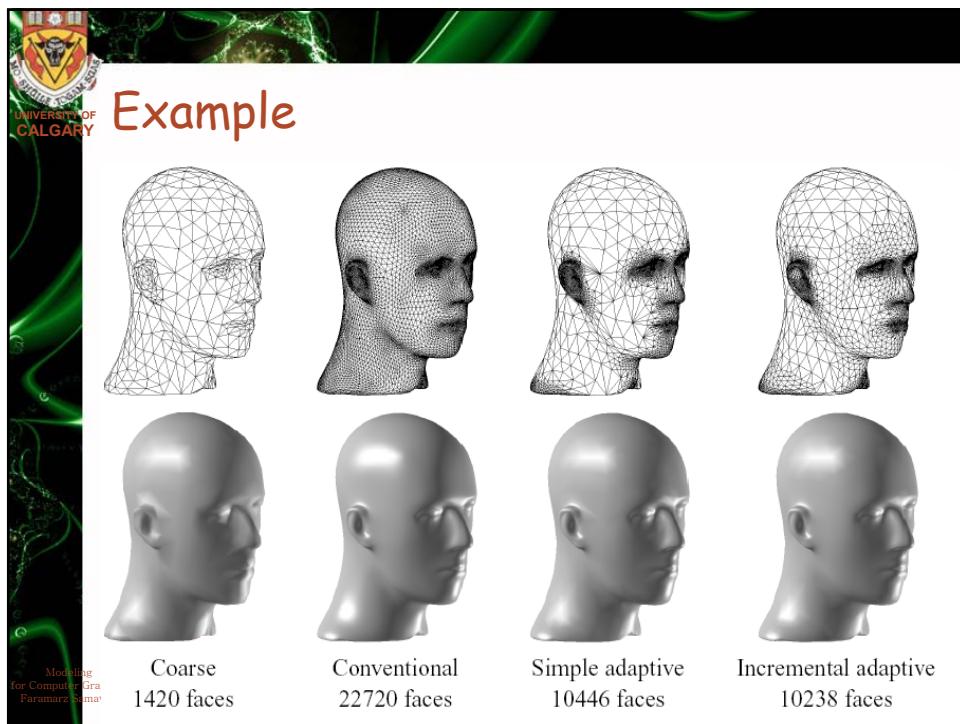


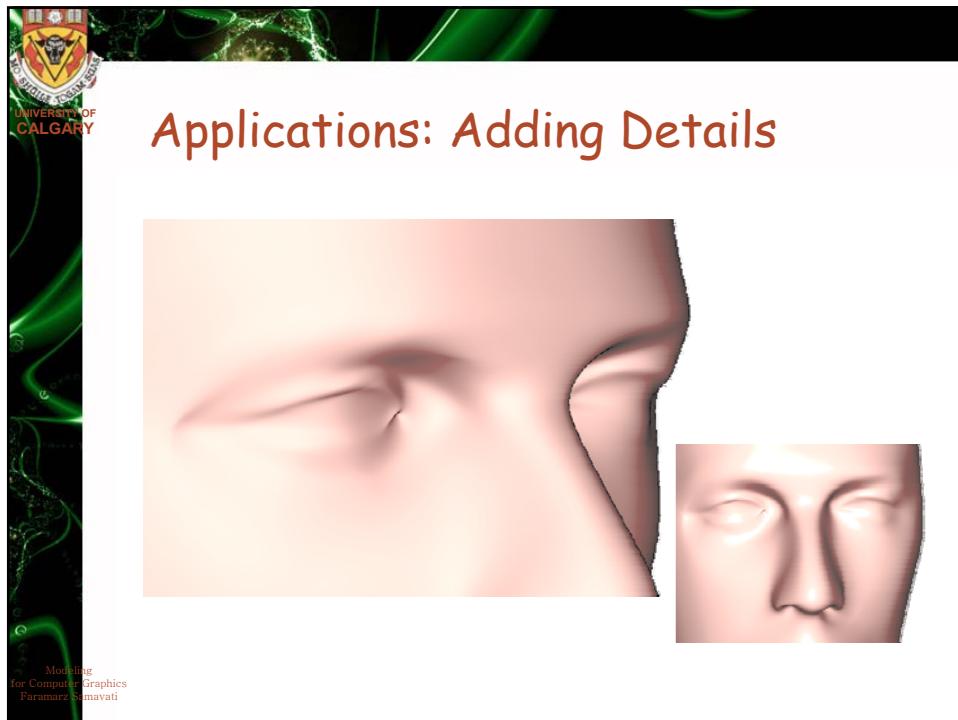


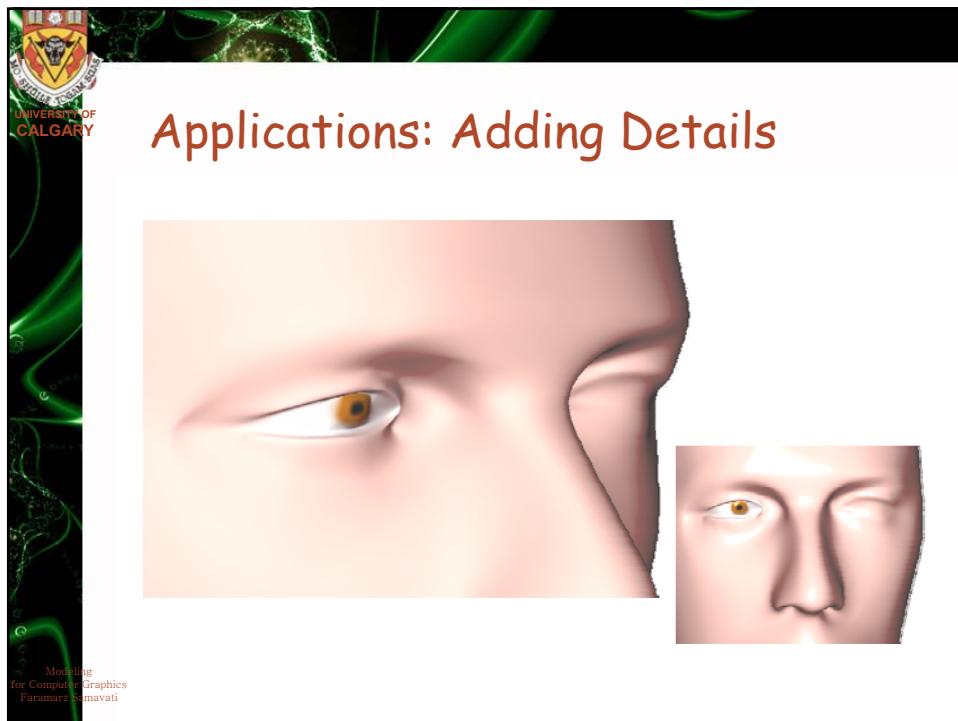
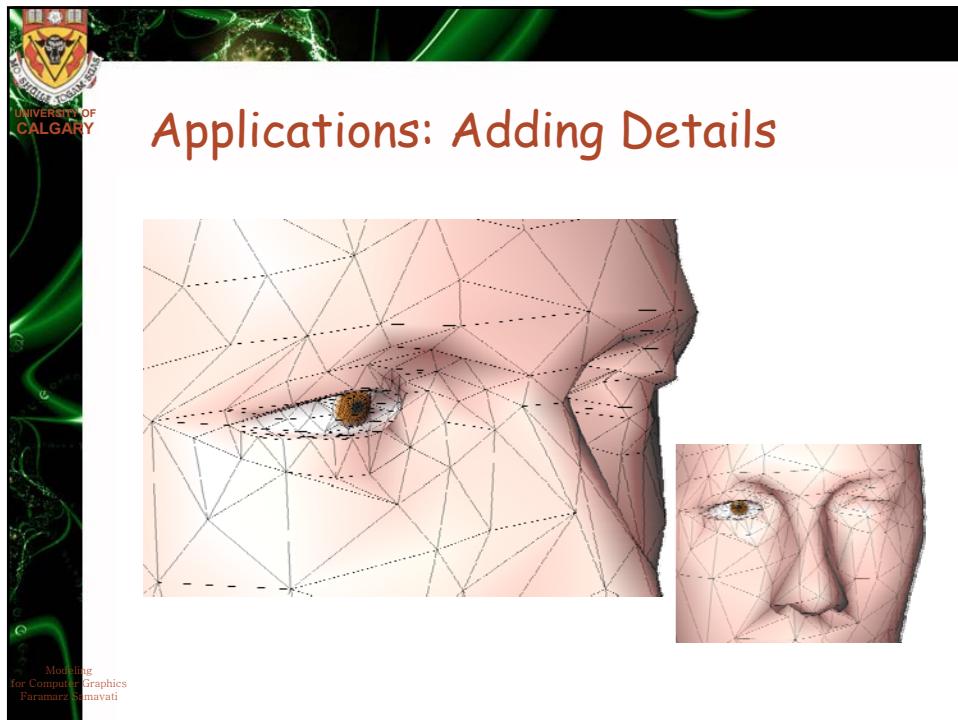


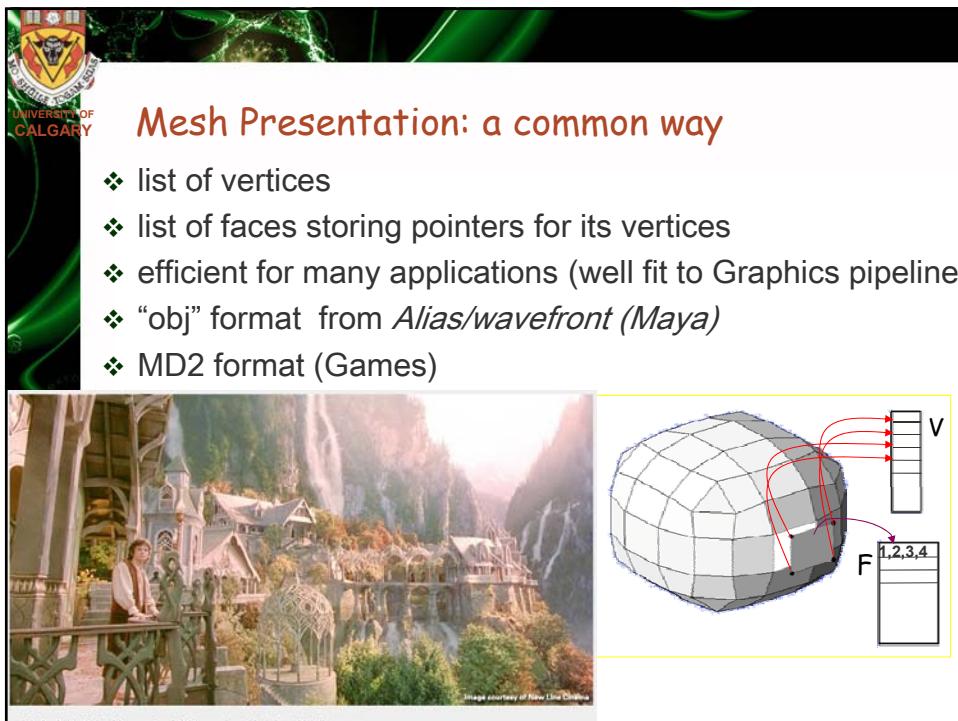
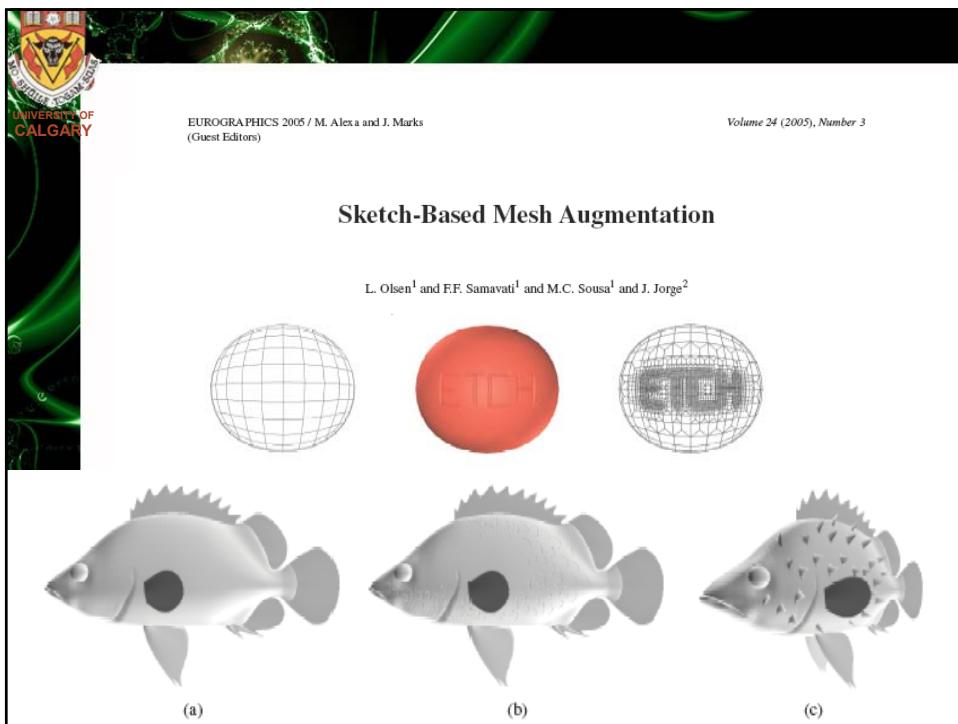












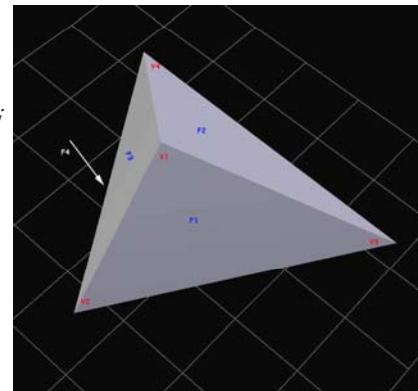


## Obj Example

### ❖ Tetrahedron

# Obj file format with ext .obj

```
v 1.0 1.0 1.0
v 2.0 0.0 0.0
v 0.0 0.0 0.0
v 1.0 1.6 0.0
f 1 3 2
f 1 2 4
f 1 4 3
f 2 3 4
```

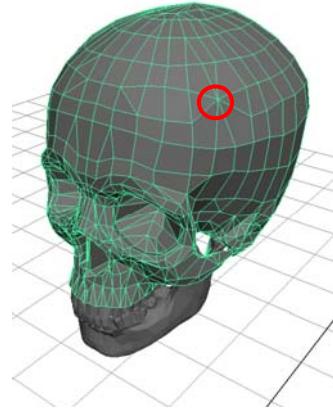
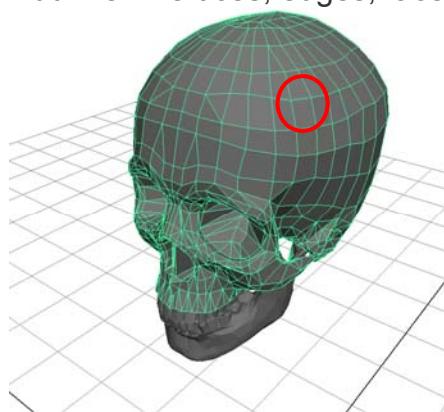
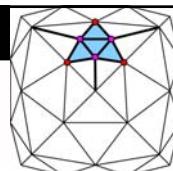


## Mesh processing

Collapse: edge, vertex, face

Split: edge, vertex, face

Add: new vertices, edges, faces





## Queries

- ❖ Given a vertex, Which edges are share it?
- ❖ Given a vertex, Which vertices are adjacent to it?
- ❖ Given a vertex, which faces are adjacent to it?
- ❖ ...

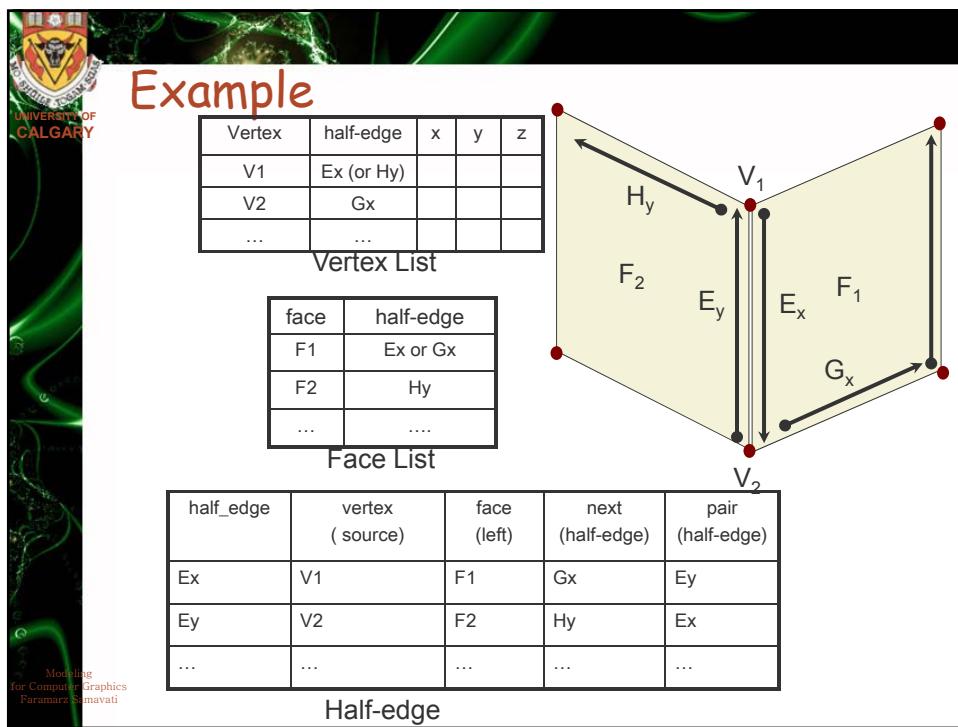
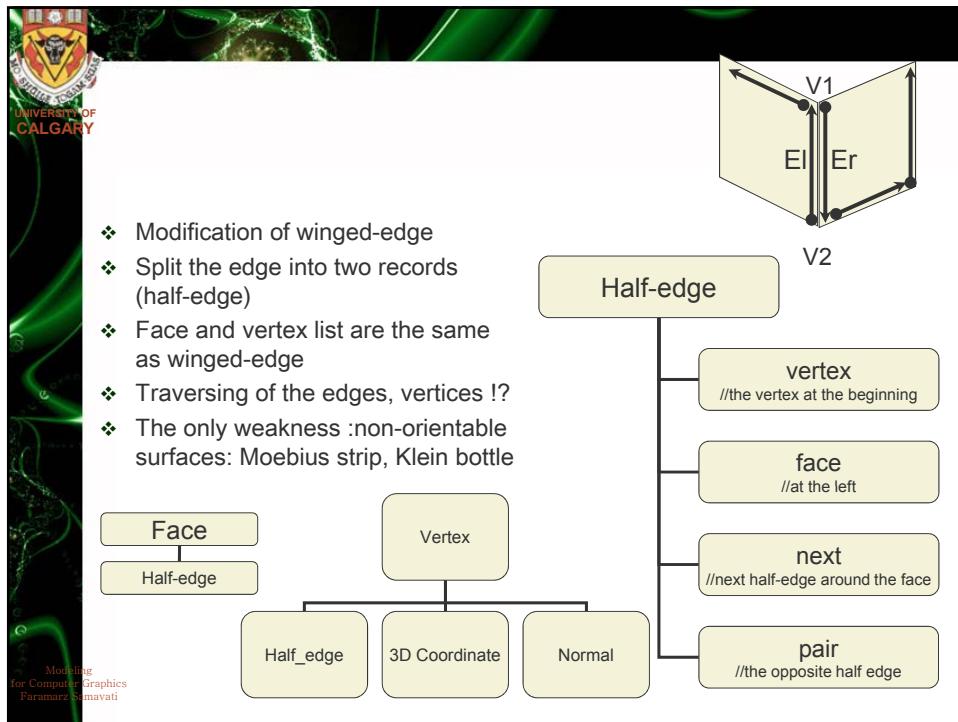
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## Inefficiencies for mesh processing

- ❖ Hard to add a new point/vertex/face
- ❖ find the vertex neighborhood which is important for any mesh operation is very hard
- ❖ Better methods ??

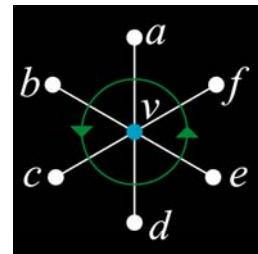
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VV

- ❖ Fast access to vertex neighborhoods
- ❖ Vertex-vertex systems
  - o Vertex + neighbors
  - o Efficient
  - o Formal language
  - o Readily available C++ library



$$v^* = \{a, b, c, d, e, f\}$$