Lecture 7: Support Vector Machine (Part 2)

Sep 24 2019

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Dual Formulation of SVM

Let us first recall the soft-margin SVM problem formulation.

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \xi_{i} \quad \text{such that}$$
 (1)

$$\forall i, \qquad y_i(\mathbf{w}^{\mathsf{T}} x_i) \ge 1 - \xi_i \tag{2}$$

$$\forall i, \qquad \xi_i \ge 0 \tag{3}$$

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Now we can introduce the tools of Lagrange duality and utilitze KKT conditions. First, we can rewrite each constraint in (2) as

$$1 - \xi_i - y_i \mathbf{w}^{\mathsf{T}} x_i \le 0$$

and introduce a dual variable $\lambda_i \geq 0$. For each constraint $\xi_i \geq 0$, we introduce a dual variable $\alpha_i \geq 0$. The set of variables w and ξ that are called the primal variables. This allows us to write down the Lagrangian objective:

$$L(\mathbf{w}, \xi, \lambda, \alpha) = \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \xi_{i} + \sum_{i=1}^{n} \lambda_{i} (1 - \xi_{i} - y_{i} \mathbf{w}^{\mathsf{T}} x_{i}) - \sum_{i=1}^{n} \alpha_{i} \xi_{i}$$

Now we can apply the KKT conditions to obtain some characterizations of the SVM solution. First, applying the staionarity condition $\nabla_{\mathbf{w},\xi}L(\mathbf{w}^*,\xi^*,\lambda^*,\alpha^*)=\mathbf{0}$:

$$\mathbf{w} = \sum_{i} y_i \lambda_i^* x_i \qquad (\frac{\partial L}{\partial \mathbf{w}} = 0)$$

$$C - \lambda_i^* - \alpha_i^* = 0 \quad \forall i$$
 $(\frac{\partial L}{\partial \xi_i} = 0)$

Let us plug these back into *L*:

$$L(\mathbf{w}, \xi, \lambda, \alpha) = C \sum_{i=1}^{n} \xi_{i} + \frac{1}{2} \left\| \sum_{i=1}^{n} y_{i} \lambda_{i} x_{i} \right\|_{2}^{2} - \sum_{i=1}^{n} \alpha_{i} \xi_{i} + \sum_{i=1}^{n} \lambda_{i} (1 - \xi_{i} - y_{i} \mathbf{w}^{\mathsf{T}} x_{i})$$

$$= \frac{1}{2} \left\| \sum_{i=1}^{n} y_{i} \lambda_{i} x_{i} \right\|_{2}^{2} + \sum_{i} \lambda_{i} - \sum_{i} \lambda_{i} \left(y_{i} \left(\sum_{j} y_{j} \lambda_{j} x_{j} \right)^{\mathsf{T}} x_{i} \right)$$

$$(\text{Plug in } C = \alpha_{i} + \lambda_{i})$$

$$= \frac{1}{2} \left\| \sum_{i=1}^{n} y_{i} \lambda_{i} x_{i} \right\|_{2}^{2} + \sum_{i} \lambda_{i} - \sum_{i,j \in [n]} \lambda_{i} \lambda_{j} y_{i} y_{j} x_{i}^{\mathsf{T}} x_{j}$$

$$= \sum_{i} \lambda_{i} - \frac{1}{2} \sum_{i,j \in [n]} \lambda_{i} \lambda_{j} y_{i} y_{j} x_{i}^{\mathsf{T}} x_{j}$$

$$(6)$$

The optimization problem then becomes:

$$\max_{\alpha,\lambda} \sum_i \lambda_i - \frac{1}{2} \sum_{i,j \in [n]} \lambda_i \lambda_j y_i y_j x_i^\intercal x_j$$
 such that for all i :
$$C = \lambda_i + \alpha_i$$

$$\lambda_i, \alpha_i \geq 0$$

Observe that we could also replace the constraints by the following so that we only have one set of decision variables to optimize:

for all
$$i: 0 < \lambda_i < C$$

This is a quadratic program with a quadratic objective function and a set of linear constraints. Suppose we are given the optimal solution λ^* . What is the linear predictor we get from this dual solution? We know from the KKT conditions that

$$\mathbf{w}^* = \sum_{i=1}^n y_i \lambda_i^* x_i = \sum_{i: \lambda_i^* > 0} y_i \lambda^* x_i$$

Any point i with $\lambda_i^* > 0$ is called a *support vector*, hence the name SVM. Now let us apply complementary slackness from the KKT conditions:

for all
$$i$$
, $\alpha_i^* \xi_i^* = 0$, $\lambda_i^* (1 - \xi_i^* - y_i \langle \mathbf{w}^*, x_i \rangle) = 0$

For any support vector with $\lambda_i^* > 0$, we then also have

$$(1 - \xi_i^* - y_i \langle \mathbf{w}^*, x_i \rangle) = 0 \Leftrightarrow 1 - \xi_i^* = y_i \langle \mathbf{w}^*, x_i \rangle$$

We can break it down into a couple cases:

- If $\xi_i^* = 0$, then $y_i \langle \mathbf{w}^*, x_i \rangle = 1$, which means the point is exactly $1/\|\mathbf{w}\|$ away from the decision boundary.
- If $\xi_i^* < 1$, then $y_i \langle \mathbf{w}^*, x_i \rangle \in (0, 1)$, then this point is classified correctly but pretty close to the decision boundary with distance less than $1/\|\mathbf{w}\|$.
- If $\xi_i^* > 1$, then $y_i \langle \mathbf{w}^*, x_i \rangle < 0$, then this point is classified incorrectly.

SVM can also be viewed as a form of compression, since we only need the support vectors to define the final solution.

Kernels: Feature Expansion

Note that all of our derivation holds if we replace each feature vector x_i by some feature expansion $\phi(x_i)$. The optimization problem then becomes:

$$\max_{\alpha,\lambda} \sum_{i} \lambda_i - \frac{1}{2} \sum_{i,j \in [n]} \lambda_i \lambda_j y_i y_j \phi(x_i)^{\mathsf{T}} \phi(x_j)$$

such that for all $i: 0 \le \lambda_i \le C$

In linear regression, we have already seen several examples for such feature expansion. Some of these mappings lift the feature vector to much higher dimensional space.

Quadratic expansion For example, for $x \in \mathbb{R}^d$, consider the following variant of the quadratic (or polynomial of order 2) expansion:

$$\phi(x) = (1, \sqrt{2}x_1, \dots, \sqrt{2}x_d, x_1^2, \dots, x_d^2, \sqrt{2}x_1x_2, \dots, \sqrt{2}x_{d-1}x_d)$$

Under this expansion, the product

$$\phi(x)^{\mathsf{T}}\phi(x') = (1 + x^{\mathsf{T}}x')^2$$

which can be computed in O(d) time, as opposed to $O(d^2)$.

Products of all subsets. Let's blow up the dimension even more. Consider the following feature expansion mapping

$$\phi(x) = \left(\prod_{i \in S} x_i\right)_{S \subseteq [d]}$$

Then we still compute the product in time O(d) (instead of 2^d):

$$\phi(x)^{\mathsf{T}}\phi(x) = \prod_{i=1}^{d} (1 + x_i x_i')$$

Gaussian kernel. Next, let's be more ambitious and push the dimension to infinity. For any parameter $\sigma > 0$, consider a feature expansion such that

$$\phi(x)^{\intercal}\phi(x') = \exp\left(-\frac{\|x - x'\|_2^2}{2\sigma^2}\right)$$

This product can be computed in O(d) time. So what is ϕ ? Let us try the simple case of d=1. Then

$$\phi(x)\phi(y) = \exp(-(x-y)^2/(2\sigma^2))$$

$$= \exp(-x^2/(2\sigma^2)) \exp(-y^2/(2\sigma^2)) \exp(xy/\sigma^2)$$

$$= \exp(-x^2/(2\sigma^2)) \exp(-y^2/(2\sigma^2)) \sum_{j=0}^{\infty} \frac{1}{j!} (xy/\sigma^2)^j$$

This gives

$$\phi(x) = \exp(-x^2/(2\sigma^2)) \left(1, \frac{x}{\sigma}, \frac{1}{2!} \left(\frac{x}{\sigma}\right)^2, \frac{1}{3!} \left(\frac{x}{\sigma}\right)^3 \dots\right)$$

The product above is called RBF kernel or Gaussian kernel. We will revisit in the next lecture.