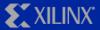


# MPEG decoding in FPGAs

## Why compress?

- Typical HDTV standard: 1920 x 1080 at 30 frames/sec
- 8 bits for each of three primary colors
- ◆ 1.5 Gb/sec!
- Bandwidth limitation => 18 Mb/sec per channel for video
- Require 83:1 compression
- With high quality video to end user

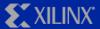


#### MPEG format

Transmission in form of series of frames

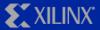
Use YCbCr color-space instead of RGB

- Each frame comprises a set of macroblocks
  - Macroblocks comprise set of blocks
  - e.g. formats 4:4:4 4:2:2 4:2:0



### MPEG format

- High correlation between neighboring pixels
- Use Discrete Cosine Transform
  - Near optimal for energy concentration and decorrelation
  - Transform 8x8 block to produce 8x8 DCT coeffs
  - Most higher-order coeffs are 0
  - Drastically reduces bandwidth requirement



## Discrete Cosine Transform

22	19	13	13	15
18	13	7	6	9
14	11	5	5	7
12	8	1	2	3
12	14	9	3	5
10	12	2	2	5

8	4	2	0	0
4	2	0	0	0
2	0	0	0	0
0	0	0	0	0
0	1	0	0	0
0	0	0	0	0



#### Discrete Cosine Transform

$$F(\mu,\nu) =$$

$$\frac{1}{4}C(\mu)C(\nu)\sum_{x=0}^{7}\sum_{y=0}^{7}f(x,y)\cos\left[\frac{(2x+1)\mu\pi}{16}\right]\cos\left[\frac{(2y+1)\nu\pi}{16}\right]$$

$$C(\mu) = \frac{1}{\sqrt{2}} \text{ for } \mu = 0$$
  $C(\mu) = 1 \text{ for } \mu = 1,2...7$ 

$$f(x,y) =$$

$$\frac{1}{4} \sum_{\mu=0}^{7} \sum_{\nu=0}^{7} C(\mu) C(\nu) F(\mu, \nu) \cos \left[ \frac{(2x+1)\mu\pi}{16} \right] \cos \left[ \frac{(2y+1)\nu\pi}{16} \right]$$



#### Discrete Cosine Transform

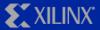
Implementing 2D DCT with two 1D DCTs

$$f(x,y) =$$

$$\frac{1}{4} \sum_{\mu=0}^{7} \sum_{\nu=0}^{7} C(\mu) C(\nu) F(\mu, \nu) \cos \left[ \frac{(2x+1)\mu\pi}{16} \right] \cos \left[ \frac{(2y+1)\nu\pi}{16} \right]$$

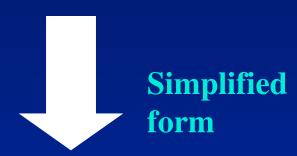
$$G(\mu, y) = \frac{1}{2} \sum_{\nu=0}^{7} C(\nu) F(\mu, \nu) \cos \left[ \frac{(2y+1)\nu\pi}{16} \right]$$

$$f(x,y) = \frac{1}{2} \sum_{\mu=0}^{7} C(\mu) G(\mu, y) \cos \left[ \frac{(2x+1)\mu\pi}{16} \right]$$



# 1D-DCT using DA

$$G(\mu, y) = \frac{1}{2} \sum_{\nu=0}^{7} C(\nu) F(\mu, \nu) \cos \left[ \frac{(2y+1)\nu\pi}{16} \right]$$



$$G(y) = \sum_{\nu=0}^{7} F(\nu) \cos \left[ \frac{(2y+1)\nu\pi}{16} \right]$$



## 1D-DCT using DA

$$F(0) \quad F(1)$$

$$C_0 \quad C_1 \quad C_2 \quad C_3 \quad C_4 \quad C_5 \quad C_6 \quad C_7$$

$$C_0 \quad C_3 \quad C_6 \quad C_9 \quad C_{12} \quad C_{15} \quad C_{18} \quad C_{21}$$

$$C_0 \quad C_5 \quad C_{10} \quad C_{15} \quad C_{20} \quad C_{25} \quad C_{30} \quad C_{35}$$

$$C_0 \quad C_7 \quad C_{14} \quad C_{21} \quad C_{28} \quad C_{35} \quad C_{42} \quad C_{49}$$

$$C_0 \quad C_9 \quad C_{18} \quad C_{27} \quad C_{36} \quad C_{45} \quad C_{54} \quad C_{63}$$

$$C_0 \quad C_{11} \quad C_{22} \quad C_{33} \quad C_{44} \quad C_{55} \quad C_{66} \quad C_{77}$$

$$C_0 \quad C_{13} \quad C_{26} \quad C_{39} \quad C_{52} \quad C_{65} \quad C_{78} \quad C_{91}$$

$$C_0 \quad C_{15} \quad C_{30} \quad C_{45} \quad C_{60} \quad C_{75} \quad C_{90} \quad C_{105}$$

$$G(7)$$

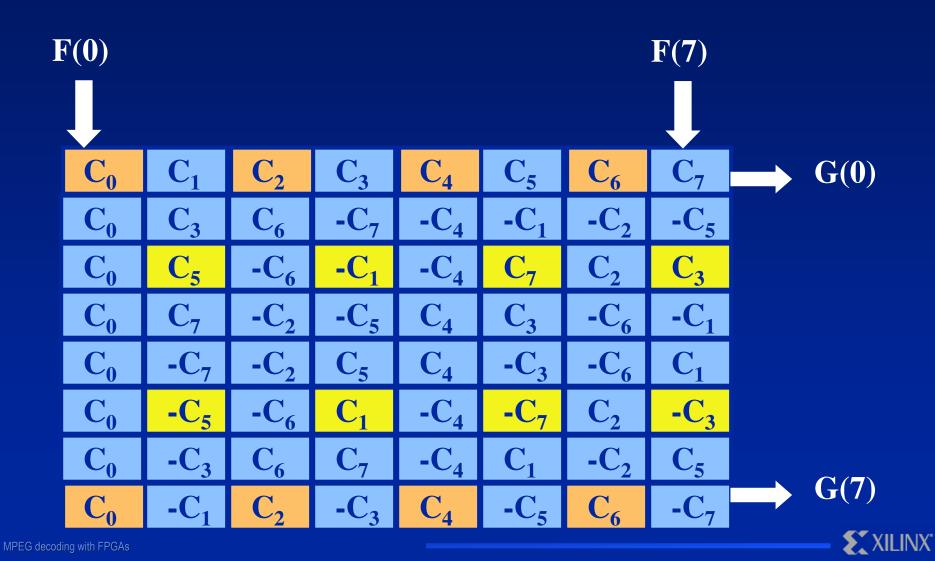
**XILINX** 

# 1D-DCT: simplified coeffs

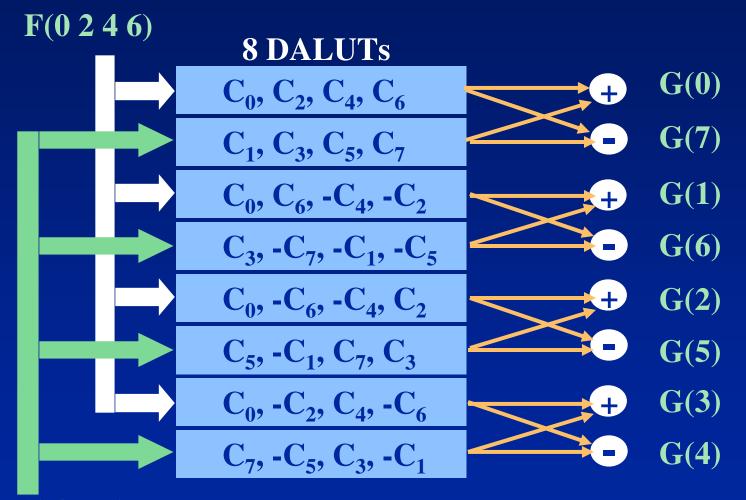
$C_0$	$\mathbf{C}_1$	$\mathbb{C}_2$	$\mathbb{C}_3$	$\mathbf{C}_{4}$	$C_5$	$C_6$	<b>C</b> <sub>7</sub>
$C_0$	$\mathbb{C}_3$	$C_6$	-C <sub>7</sub>	-C <sub>4</sub>	-C <sub>1</sub>	-C <sub>2</sub>	-C <sub>5</sub>
$C_0$	$C_5$	-C <sub>6</sub>	-C <sub>1</sub>	-C <sub>4</sub>	<b>C</b> <sub>7</sub>	$\mathbb{C}_2$	$\mathbb{C}_3$
$C_0$	<b>C</b> <sub>7</sub>	-C <sub>2</sub>	-C <sub>5</sub>	$C_4$	$\mathbb{C}_3$	-C <sub>6</sub>	-C <sub>1</sub>
$C_0$	-C <sub>7</sub>	-C <sub>2</sub>	$C_5$	$C_4$	-C <sub>3</sub>	-C <sub>6</sub>	$C_1$
$C_0$	-C <sub>5</sub>	-C <sub>6</sub>	$C_1$	-C <sub>4</sub>	-C <sub>7</sub>	$\mathbb{C}_2$	-C <sub>3</sub>
$C_0$	-C <sub>3</sub>	$C_6$	<b>C</b> <sub>7</sub>	-C <sub>4</sub>	$C_1$	-C <sub>2</sub>	$C_5$
$C_0$	-C <sub>1</sub>	$C_2$	-C <sub>3</sub>	C <sub>4</sub>	-C <sub>5</sub>	$C_6$	-C <sub>7</sub>



## 1D-DCT: simplified coeffs



## Block diagram for 1D-DCT

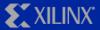


F(1 3 5 7)



# Original Picture block

22	19	13	13	15
18	13	7	6	9
14	11	5	5	7
12	8	1	2	3
12	14	9	3	5
10	12	2	2	5



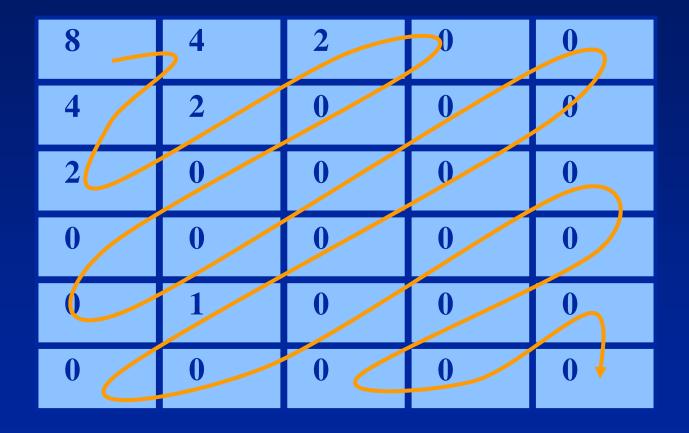
## DC-transformed block

8	4	2	0	0
4	2	0	0	0
2	0	0	0	0
0	0	0	0	0
0	1	0	0	0
0	0	0	0	0

84200420002000000000100000000



## Zigzag scan ordering



8442220000000000001000000000000



# Variable-length code table

Zero run-length	Amplitude	MPEG code value
N/A	8	110 1000
0	4	0000 1100
0	4	0000 1100
0	2	0100 0
0	2	0100 0
0	2	0100 0
12	1	0010 0010 0
EOB	EOB	10



#### Huffman codes

- ◆ Typically 20% 90% compression
- Coding based on frequency of occurrence

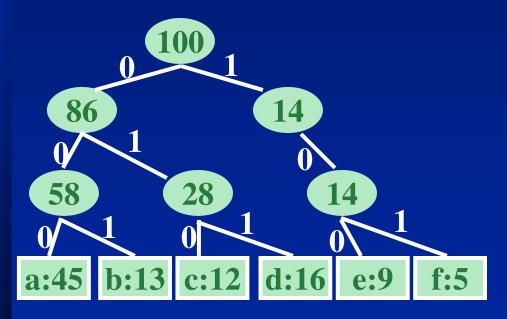
	a	b	c	d	e	f
Frequency (%)	60	11	12	15	1	1
Fixed-length code	000	001	010	011	100	101
<b>Huffman code</b>	0	101	100	111	1101	1100

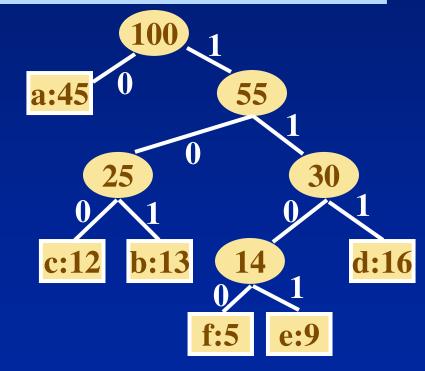
◆ 100char: Fixed-length: 300 bits Huffman-code: 182 bits



## Huffman codes

	a	b	c	d	e	f
Frequency (%)	60	11	12	15	1	1
Fixed-length code	000	001	010	011	100	101
Huffman code	0	101	100	111	1101	1100

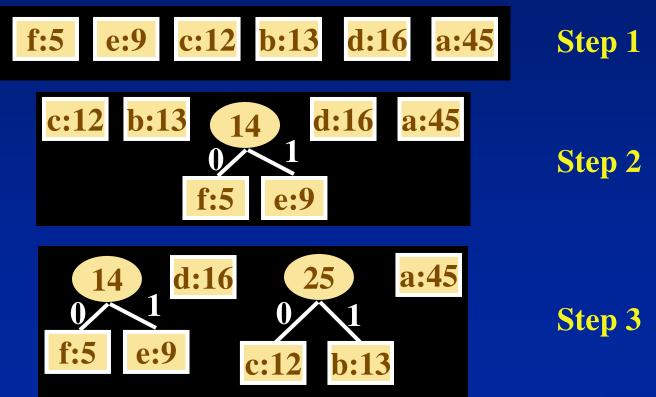






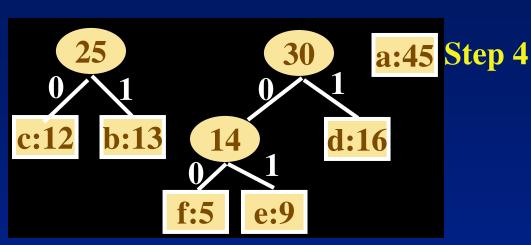
## Construction of Huffman codes

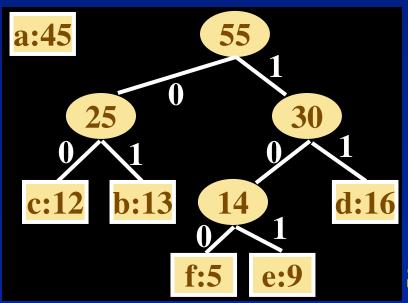
- Sort objects
- Merge 2 objects with least frequencies



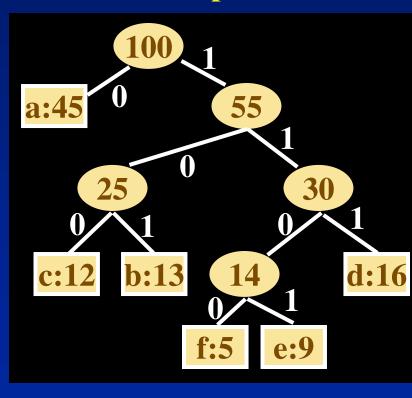


## Huffman codes





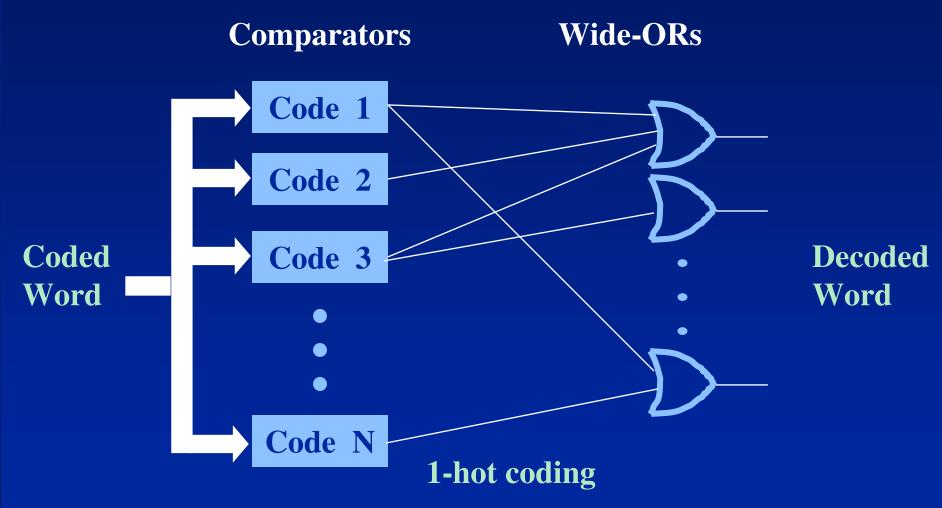
Step 6



Step 5



## Huffman decoder in FPGA





## MPEG decoding in FPGA

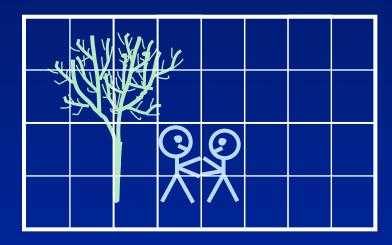
- Variable-length decoding
  - Comparators
  - Wide-ORs

- IDCT
  - Distributed Arithmetic
- All these functions can be implemented very efficiently in VIRTEX

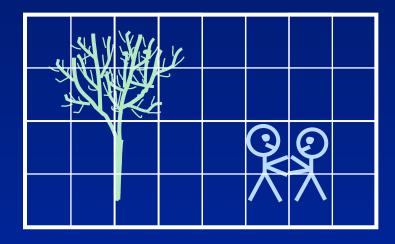


- Consecutive video frames similar
- Small movement => block matches very likely
  - search space based on encoder
- Use motion vectors
- Four motion vectors for bidirectional prediction
- Residual error frame encoded efficiently

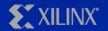


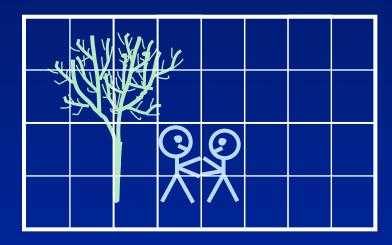


FRAME 1

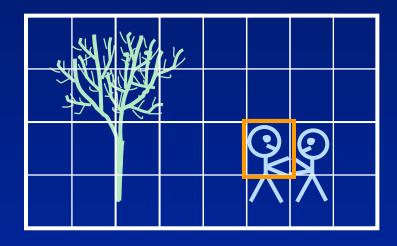


FRAME 2

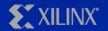


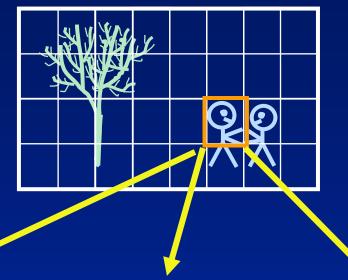


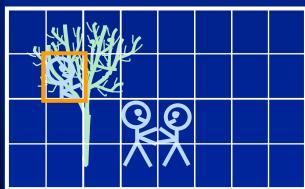
FRAME 1

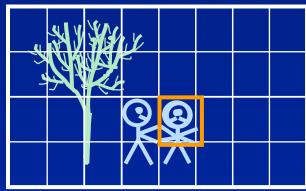


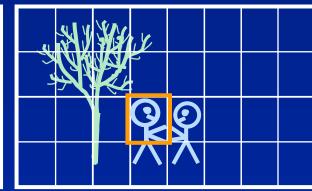
FRAME 2











**BAD MATCH** 

**FAIR MATCH** 

**GOOD MATCH** 



#### Frames

- Transmission in form of series of frames
- Each frame comprises a set of macroblocks
- 3 types of frames
  - I frame
    - Exploits spatial redundancy
  - P/B frames
    - Exploit temporal redundancy



#### P Frames

- Predictor frames
- Macroblocks comprise motion-vectors relative to previous frame's macroblocks
- ◆ | P P P P P | P P P P
  - P frame predicted from frame before
  - I frames coded spatially no reference to any other frames



#### **B** Frames

- Bidirectional frames
- Macroblocks comprise motion-vectors relative to previous AND next frame's macroblocks
- ◆ IBPBPBIBPBPB
  - P frame predicted from frame before
  - I frames coded spatially no reference to any other frames
  - B frame predicted from frame before and after



#### Conclusions

- Image compression
  - YCbCr color-space
  - DCT
  - Variable-length coding
  - Motion compensation
- Primary components for MPEG decoding (IDCT/Huffman decoding) can be implemented efficiently in FPGAs for speed

