

# MATH 417 Homework 10

Note that this is problems: Section 15.3 #1,2,3. Section 16.1 #7,8,9

1. Suppose that the function  $\psi : \mathbb{R}^2 \rightarrow \mathbb{R}$  is continuously differentiable. Define the function  $g : \mathbb{R}^2 \rightarrow \mathbb{R}$  by

$$g(s, t) = \psi(s^2t, s) \quad \text{for } (s, t) \in \mathbb{R}^2.$$

Find  $\frac{\partial g}{\partial s}(s, t)$  and  $\frac{\partial g}{\partial t}(s, t)$ .

**Solution:**

Define  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $F(s, t) = (s^2t, s)$  and to keep notation clear, write  $\psi(x, y)$ . Then  $g = (\psi \circ F)$  with  $F_1(s, t) = s^2t$  and  $F_2(s, t) = s$ . In particular, observe that  $F_1(s, t) = s^2t$  and  $F_2(s, t) = s$ . Then we have

$$\begin{aligned} \frac{\partial F_1}{\partial s} &= 2st, \\ \frac{\partial F_1}{\partial t} &= s^2, \\ \frac{\partial F_2}{\partial s} &= 1, \\ \frac{\partial F_2}{\partial t} &= 0. \end{aligned}$$

Thus, the chain rule gives us that

$$\begin{aligned} \frac{\partial g}{\partial s}(s, t) &= \frac{\partial \psi}{\partial x}(s^2t, s)(2st) + \frac{\partial \psi}{\partial y}(s^2t, s), \\ \frac{\partial g}{\partial t}(s, t) &= \frac{\partial \psi}{\partial x}(s^2t, s)s^2. \end{aligned}$$

2. Suppose that the function  $h : \mathbb{R}^3 \rightarrow \mathbb{R}$  is continuously differentiable. Define the function  $\eta : \mathbb{R}^3 \rightarrow \mathbb{R}$  by

$$\eta(u, v, w) = (3u + 2v)h(u^2, v^2, uvw) \quad \text{for all } (u, v, w) \in \mathbb{R}^3.$$

Find  $D_1\eta(u, v, w)$ ,  $D_2\eta(u, v, w)$ ,  $D_3\eta(u, v, w)$ .

**Solution:** Define  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  as

$$F(u, v, w) = (u^2, v^2, uvw)$$

and to keep notation clear, write  $h(x, y, z)$ . Then  $F_1(u, v, w) = u^2 = x$ ,  $F_2(u, v, w) = v^2 = y$ , and  $F_3(u, v, w) = uvw = z$ . Thus we have

$$\begin{aligned} \frac{\partial F_1}{\partial u} &= 2u, & \frac{\partial F_1}{\partial v} &= 0, & \frac{\partial F_1}{\partial w} &= 0, \\ \frac{\partial F_2}{\partial u} &= 0, & \frac{\partial F_2}{\partial v} &= 2v, & \frac{\partial F_2}{\partial w} &= 0, \\ \frac{\partial F_3}{\partial u} &= vw, & \frac{\partial F_3}{\partial v} &= uw, & \frac{\partial F_3}{\partial w} &= uv. \end{aligned}$$

Then the chain rule gives

$$\begin{aligned} D_1\eta(u, v, w) &= 3h(u^2, v^2, uvw) + (3u + 2v)\left(D_1h(F(u, v, w))2u + D_3h(F(u, v, w))vw\right), \\ D_2\eta(u, v, w) &= 2h(u^2, v^2, uvw) + (3u + 2v)\left(D_2h(F(u, v, w))2v + D_3h(F(u, v, w))uw\right), \\ D_3\eta(u, v, w) &= (3u + 2v)D_3h(F(u, v, w))uv. \end{aligned}$$

3. Suppose that the functions  $g : \mathbb{R} \rightarrow \mathbb{R}$  and  $h : \mathbb{R} \rightarrow \mathbb{R}$  have continuous second-order partial derivatives. Define the function  $u : \mathbb{R}^2 \rightarrow \mathbb{R}$  by

$$u(s, t) = g(s - t) + h(s + t) \quad \text{for all } (s, t) \in \mathbb{R}^2.$$

Prove that

$$\frac{\partial^2 u}{\partial t^2}(s, t) - \frac{\partial^2 u}{\partial s^2}(s, t) = 0 \quad \text{for all } (s, t) \in \mathbb{R}^2.$$

**Solution:** We can actually use the chain rule for functions of single variable to prove this. We calculate,

$$\frac{\partial^2 g}{\partial t^2} = g''(s - t),$$

$$\frac{\partial^2 g}{\partial s^2} = g''(s - t),$$

$$\frac{\partial^2 h}{\partial t^2} = h''(s + t),$$

$$\frac{\partial^2 h}{\partial s^2} = h''(s + t).$$

Since the operators  $\frac{\partial^2}{\partial t^2}$  and  $\frac{\partial^2}{\partial s^2}$  are linear, then

$$\frac{\partial^2 u}{\partial t^2}(s, t) - \frac{\partial^2 u}{\partial s^2}(s, t) = (g''(s - t) + h''(s + t)) - (g''(s - t) + h''(s + t)) = 0$$

as desired.

7. Let  $\mathcal{O}$  and  $V$  be open subsets of  $\mathbb{R}$  and suppose that the differentiable function  $f : \mathcal{O} \rightarrow V$  is one-to-one and onto. Suppose that  $x_0$  is a point in  $\mathcal{O}$  at which  $f'(x_0) = 0$ . Show that the inverse function  $f^{-1} : V \rightarrow \mathbb{R}$  cannot be differentiable at the point  $f(x_0)$ .

**Solution:** We use proof by contradiction. Suppose that  $f^{-1}$  is differentiable. Then it follows that we can use implicit differentiation to obtain

$$\frac{df^{-1}}{dx}(f(x)) \frac{df}{dx}(x) = 1$$

from

$$f^{-1}(f(x)) = x.$$

But since  $\frac{df}{dx}(x) = 0$ , this then tells us that  $1 = 0$ , a contradiction.

8. For each of the following mappings  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , apply the Inverse Function Theorem at the point  $(x_0, y_0) = (0, 0)$  and calculate the partial derivatives of the components of the inverse mapping at the point  $(u_0, v_0) = F(0, 0)$ :

(a)  $F(x, y) = (x + x^2 + e^{x^2 y^2}, -x - y + \sin(xy))$

(b)  $F(x, y) = (e^{x+y}, e^{x-y})$ .

**Solution:**

- (a) It is clear that  $F$  is continuously differentiable. The derivative matrix for  $F$  is

$$DF(x, y) = \begin{bmatrix} 1 + 2x + 2xy^2 e^{x^2 y^2} & 2yx^2 e^{x^2 y^2} \\ -1 + y \cos(xy) & -1 + x \cos(xy) \end{bmatrix}.$$

Then at  $(x, y) = (0, 0)$  we have

$$DF(0, 0) = \begin{bmatrix} 1 & 0 \\ -1 & -1 \end{bmatrix}$$

and  $F(0, 0) = (1, 0)$ . This matrix is invertible as its determinant is  $-1$ . The inverse of this matrix is,

$$[DF(0, 0)]^{-1} = \begin{bmatrix} 1 & 0 \\ -1 & -1 \end{bmatrix}.$$

Therefore, if we write the inverse as  $F^{-1} = (G_1(u, v), G_2(u, v))$  then we can calculate the partial derivatives of  $G_1$  and  $G_2$  at  $(1, 0)$  to be

$$\begin{aligned}\frac{\partial G_1}{\partial u}(1, 0) &= 1 & \text{and} & & \frac{\partial G_1}{\partial v}(1, 0) &= 0 \\ \frac{\partial G_2}{\partial u}(1, 0) &= -1 & \text{and} & & \frac{\partial G_2}{\partial v}(1, 0) &= -1.\end{aligned}$$

(b) It is clear that  $F$  is continuously differentiable. The derivative matrix for  $F$  is

$$DF(x, y) = \begin{bmatrix} e^{x+y} & e^{x+y} \\ e^{x-y} & -e^{x-y} \end{bmatrix}.$$

Then at  $(x, y) = (0, 0)$  we have

$$DF(0, 0) = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

and  $F(0, 0) = (1, 1)$ . This matrix is invertible as its determinant is  $-2$ . The inverse of this matrix is,

$$[DF(0, 0)]^{-1} = -\frac{1}{2} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}.$$

Therefore, if we write the inverse as  $F^{-1} = (G_1(u, v), G_2(u, v))$  then we can calculate the partial derivatives of  $G_1$  and  $G_2$  at  $(1, 1)$  to be

$$\begin{aligned}\frac{\partial G_1}{\partial u} &= \frac{1}{2} & \text{and} & & \frac{\partial G_1}{\partial v} &= \frac{1}{2} \\ \frac{\partial G_2}{\partial u} &= \frac{1}{2} & \text{and} & & \frac{\partial G_2}{\partial v} &= -\frac{1}{2}.\end{aligned}$$

9. Define the function  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by

$$F(x, y) = (e^x \cos(y), e^x \sin(y)).$$

- (a) Show that the Inverse Function Theorem is applicable at every point  $(x_0, y_0)$  in the plane  $\mathbb{R}^2$ .
- (b) Show that the function  $F$  is not one-to-one.
- (c) Does (b) contradict (a).

**Solution:**

- (a) The derivative matrix for this function is

$$DF(x, y) = \begin{bmatrix} e^x \cos(y) & -e^x \sin(y) \\ e^x \sin(y) & e^x \cos(y) \end{bmatrix}.$$

The determinant of this matrix is  $e^x(\cos^2(y) + \sin^2(y)) = e^x > 0$ , and hence this matrix is invertible for any point  $(x_0, y_0) \in \mathbb{R}^2$ .

- (b) On the other hand,  $F$  is not one-to-one. For example,  $F(0, 0) = F(0, 2\pi)$ .
- (c) This is not a contradiction because the Inverse Function Theorem only tells us that a function is one-to-one locally in some neighborhood (potentially very small) of the function that we are interested in.