

## MATH 417 Homework 8

Note that this is problems: Section 14.3 #1,2,8; Section 15.1 #1,4,6.

1. Analyze the local extrema of the following functions:

- (a)  $f(x, y) = e^{x^2-4y+y^2}$  for  $(x, y) \in \mathbb{R}^2$ ,
- (b)  $g(x, y, z) = e^{x^2-4y+y^2} + z^2$  for  $(x, y, z) \in \mathbb{R}^3$ ,
- (c)  $f(x, y) = (x^2 + y^2)e^{x^2+y^2}$  for  $(x, y) \in \mathbb{R}^2$ ,
- (d)  $f(x, y) = x^3y^2(6 - x - y)$  for  $(x, y) \in \mathbb{R}^2$ ,

**Solution:**

(a) We have

$$\nabla f(x, y) = (2xe^{x^2-4y+y^2}, (-4+2y)e^{x^2-4y+y^2}).$$

This is equal to  $(0, 0)$  when  $(x, y) = (0, 2)$ . At this point the Hessian is

$$\nabla^2 f(0, 2) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}.$$

This matrix is positive definite and hence  $(0, 2)$  is a local minimizer of  $f$ .

(b) We have

$$\nabla g(x, y, z) = (2xe^{x^2-4y+y^2}, (-4+2y)e^{x^2-4y+y^2}, 2z).$$

This is zero when  $(x, y, z) = (0, 2, 0)$ . At  $(0, 2, 0)$  the Hessian is

$$\nabla^2 g(0, 2, 0) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}.$$

This matrix is positive definite and hence  $(0, 2, 0)$  is a local minimizer of  $g$ .

(c) We have

$$\nabla f(x, y) = (2x(x^2 + y^2 + 1)e^{x^2+y^2}, 2y(x^2 + y^2 + 1)e^{x^2+y^2}).$$

This is equal to  $(0, 0)$  when  $(x, y) = (0, 0)$ . At  $(0, 0)$  the Hessian is

$$\nabla^2 f(0, 0) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}.$$

So this point is a local minimizer of  $f$ .

(d) We have

$$\nabla f(x, y) = (x^2y^2(18 - 4x - 3y), x^3y(12 - 2x - 3y)).$$

This is equal to  $(0, 0)$  when  $(x, y) = (0, 0)$  or  $(x, y) = (3, 2)$ . At  $(0, 0)$  the Hessian is

$$\nabla^2 f(0, 0) = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.$$

Therefore we cannot say if this point is a maximizer or minimizer of  $f$ . At  $(3, 2)$  the Hessian is

$$\nabla^2 f(3, 2) = \begin{bmatrix} -504 & -108 \\ -108 & -162 \end{bmatrix}.$$

We notice that the top left element is negative and the determinant of this matrix is positive, then this point is a strict maximizer of  $f$ .

Suppose that

- Find necessary and sufficient conditions for a  $2 \times 2$  symmetric matrix to be negative definite. Use this information to state and prove a sufficient condition for a point to be a local maximizer for a function of two variables.

**Solution:** A  $2 \times 2$  matrix

$$A = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$$

is negative definite if  $a < 0$  and  $ac - b^2 > 0$ . The argument is completely analogous to Proposition 14.15. The function  $Q : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  associated with  $A$  is

$$Q(x, y) = ax^2 + 2bxy + cy^2 \quad \text{for } (x, y) \in \mathbb{R}^2.$$

For points  $(x, y)$  with  $y \neq 0$ , set  $t = x/y$  and  $p(t) = at^2 + 2bt + c$ . Observe that

$$Q(x, y) = y^2(a(x/y)^2 + 2b(x/y) + c) = y^2p(t).$$

The polynomial  $p(t)$  is negative for all  $t$  if and only if  $a < 0$  and  $ac - b^2 > 0$ . If  $y = 0$  then  $Q(x, 0) = ax^2 < 0$  if and only if  $a < 0$ .

Applying this to Theorem 14.22 we get that  $\mathbf{x} \in \mathbb{R}^2$  is a strict local maximizer for  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  if

$$(a) \quad \frac{\partial f}{\partial x}(\mathbf{x}) = 0 \text{ and } \frac{\partial f}{\partial y}(\mathbf{x}) = 0$$

$$(b) \quad \frac{\partial^2 f}{\partial x^2}(\mathbf{x}) < 0 \text{ and}$$

$$\frac{\partial^2 f}{\partial x^2}(\mathbf{x}) \frac{\partial^2 f}{\partial y^2}(\mathbf{x}) - \left( \frac{\partial^2 f}{\partial x \partial y}(\mathbf{x}) \right)^2 > 0.$$

- Suppose that the function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  has continuous second-order partial derivatives. Let  $\mathbf{x}$  be a point in  $\mathbb{R}^n$  at which  $\nabla f(\mathbf{x}) = 0$  and such that all entries of the Hessian matrix  $\nabla^2 f(\mathbf{x})$  are also 0. By giving specific examples, show that it is possible for the point  $\mathbf{x}$  to be a local maximum, a local minimum, or neither.

**Solution:** Consider the function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  defined by

$$f(x_1, \dots, x_n) = c$$

for all  $(x_1, \dots, x_n) \in \mathbb{R}^n$  with  $c \in \mathbb{R}$  some constant. Then every point  $\mathbf{x}$  is both a local maximizer and a local minimizer (though not strict). Furthermore, it is easy to check that  $\nabla f(\mathbf{x}) = \mathbf{0}$  and  $\nabla^2 f(\mathbf{x})$  is the matrix of zeros.

Consider the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $f(x, y) = x^3 + y^3$ . The point  $(x, y) = (0, 0)$  is not a maximizer or minimizer for  $f$ . At this point you can check that  $\nabla f(0, 0) = 0$  and  $\nabla^2 f$  is the matrix of zeros.

- Which of the following mappings  $\mathbf{F} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is linear.

$$(a) \quad \mathbf{F}(x, y) = (-y, e^x) \text{ for } (x, y) \in \mathbb{R}^2,$$

$$(b) \quad \mathbf{F}(x, y) = (x - y^2, 2y) \text{ for } (x, y) \in \mathbb{R}^2,$$

$$(c) \quad \mathbf{F}(x, y) = 17(x, y) \text{ for } (x, y) \in \mathbb{R}^2,$$

**Solution:** (a) and (b) are not linear. (c) is linear.

- Show that there is no linear mapping  $\mathbf{T} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ .

**Solution:** We use proof by contradiction. Suppose that  $\mathbf{T}$  is linear. Then

$$(0, 1) = \mathbf{T}(-2, -2) = -2\mathbf{T}(1, 1) = -2(4, 0) = (-8, 0),$$

a contradiction. Hence  $\mathbf{T}$  cannot be linear.

- For a point  $(x, y)$  in the plane  $\mathbb{R}^2$ , define  $\mathbf{T}(x, y)$  to be the point on the line  $\ell = \{(x, y) \in \mathbb{R}^2 \mid y = 2x\}$  that is closest to  $(x, y)$ . Show that the mapping  $\mathbf{T} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is linear and find the  $3 \times 3$  matrix associated to this mapping.

**Solution:** Given a point  $(x_0, y_0) \in \mathbb{R}^2$ . The shortest line from  $(x_0, y_0)$  to  $\ell$  will intersect  $\ell$  at the point on  $\ell$  that is closest to  $(x_0, y_0)$  and this line will necessarily be orthogonal to  $\ell$ . Hence the line should have slope  $-\frac{1}{2}$  and must pass through the point  $(x_0, y_0)$ . The equation such a line is

$$y - y_0 = -\frac{1}{2}(x - x_0)$$

that is

$$y = -\frac{1}{2}(x - x_0) + y_0.$$

We want the intersection of this line with  $\ell$ . This gives the two equations

$$x = \frac{1}{5}x_0 + \frac{2}{5}y_0 \quad \text{and} \quad y = \frac{2}{5}x_0 + \frac{4}{5}y_0.$$

Hence, given a point  $(x_0, y_0)$ , projection onto the closest point on  $\ell$  is given by

$$\begin{bmatrix} \frac{1}{5} & \frac{2}{5} \\ \frac{2}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}.$$

It follows from this observation that the mapping is linear.