

Practice Exam 1

1. Suppose that $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear transformation such that

$$T\left(\begin{pmatrix} 2 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 8 \\ -2 \end{pmatrix} \quad \text{and} \quad T\left(\begin{pmatrix} 0 \\ 3 \end{pmatrix}\right) = \begin{pmatrix} 3 \\ 6 \end{pmatrix}.$$

. What is the value of

$$T\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right)?$$

Solution: Using the linearity of T we have

$$T\left(\begin{pmatrix} 2 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 8 \\ -2 \end{pmatrix} \implies 2T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 8 \\ -2 \end{pmatrix} \implies T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 4 \\ -1 \end{pmatrix},$$

and

$$T\left(\begin{pmatrix} 0 \\ 3 \end{pmatrix}\right) = \begin{pmatrix} 3 \\ 6 \end{pmatrix} \implies 3T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 3 \\ 6 \end{pmatrix} \implies T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

Thus by the linearity of T

$$\begin{aligned} T\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right) &= T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) + T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) \\ &= \begin{pmatrix} 4 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 5 \\ 1 \end{pmatrix}. \end{aligned}$$

2. Use the definition of a linear transformation to explain why the function $F : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by

$$F\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} 4x^2 + y - z \\ 2y + 8z \end{pmatrix}$$

is NOT linear. (You would need to use the definition to get full credit on this).

Solution: Part of the definition of a linear transformation says that for any choice of x, y, z we should have

$$2F\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = F\left(\begin{pmatrix} 2x \\ 2y \\ 2z \end{pmatrix}\right).$$

Choose $x = 1, y = 0, z = 0$. Then we have

$$2F\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right) = 2\begin{pmatrix} 4 \\ 0 \end{pmatrix} = \begin{pmatrix} 8 \\ 0 \end{pmatrix}.$$

On the other hand

$$F\left(\begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 16 \\ 0 \end{pmatrix}.$$

It follows that F cannot be a linear transformation.

3. Calculate the value of the determinant of A where

$$A = \begin{pmatrix} 1 & -1 & 4 \\ 2 & -5 & 3 \\ 2 & 1 & 0 \end{pmatrix}.$$

Solution: The determinant of A is 39.

4. Find the value of x which minimizes the determinant of the matrix:

$$\begin{pmatrix} x & 1 & 0 \\ 0 & x & 6 \\ 0 & 4 & 2 \end{pmatrix}.$$

Solution: The determinant of this matrix is $2x^2 - 24x$. The minimum of this function is attained at $x = 6$.

5. Suppose that for two vectors \mathbf{u}, \mathbf{v} in \mathbb{R}^n , we know that $\|\mathbf{u}\| = \sqrt{6}$, $\|\mathbf{v}\| = \sqrt{24}$, and $\mathbf{u} \cdot \mathbf{v} = 12$. What is the angle between \mathbf{u} and \mathbf{v} ?

Solution: Using the formula

$$\theta = \cos^{-1} \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|} \right).$$

we get

$$\cos^{-1}(1) = 0 = \theta.$$

So \mathbf{u} and \mathbf{v} actually point in the same direction.

6. Find real values x_1 and x_2 so that the vector

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

is a unit vector AND orthogonal to

$$\mathbf{u} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Solution: This amounts to solving two problems:

$$0 = \mathbf{x} \cdot \mathbf{u} = x_1 + 2x_2$$

and

$$1 = \|\mathbf{x}\| = \sqrt{x_1^2 + x_2^2}.$$

Using basic algebra one can find two different solutions:

$$\mathbf{x} = \begin{pmatrix} -\frac{2\sqrt{5}}{2} \\ \frac{\sqrt{5}}{2} \end{pmatrix} \quad \text{and} \quad \mathbf{x} = \begin{pmatrix} \frac{2\sqrt{5}}{2} \\ -\frac{\sqrt{5}}{2} \end{pmatrix}$$

7. Recall that the set V of all real valued functions $f : \mathbb{R} \rightarrow \mathbb{R}$ with the usual addition of functions and multiplication of functions by scalars is a vector space. Consider the subset W

$$W = \{ \text{functions } f : \mathbb{R} \rightarrow \mathbb{R} \text{ with } f(0) = 1 \}$$

Is W a subspace V ?

Solution: No. There are quite a few ways to see this, but one is to note that if $f : \mathbb{R} \rightarrow \mathbb{R}$ is in W (so $f(0) = 1$), then $2f$ is not in W since $2f(0) = 2(1) = 2 \neq 1$.

8. Show that the collection of all vectors

$$V = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \text{ with } 2x_1 + 3x_2 + x_3 = 1 \right\}$$

with the usual scalar multiplication and vector addition is NOT a vector space.

Solution: Note that the zero vector, which we know to be

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$$

does not satisfy the equation $2x_1 + 3x_2 + x_3 = 1$ and is therefore not in V .