$\hat{x}$  为KKT点的必要条件是,存在乘子 $w_i \ge 0 (i \in I)$  和 $v_j (j = 1, ..., l)$ ,使得

$$\nabla f(\hat{x}) - \sum_{i \in I} w_i \nabla g_i(\hat{x}) - \sum_{i=1}^l v_j \nabla h_j(\hat{x}) = 0$$

$$\begin{split} i \not \exists A_1 &= \big[ \nabla g_{i_1}(\hat{x}), \dots, \nabla g_{i_k}(\hat{x}) \big], w = (w_1, \dots, w_k)^T, B = \big[ \nabla h_1(\hat{x}), \dots, \nabla h_l(\hat{x}) \big], v = (v_1, \dots, v_l)^T \\ &= p - q, p \ge 0, q \ge 0. \end{split}$$

Lagrange 函数可改写为
$$(-A_1, -B_1, B)$$
  $\begin{bmatrix} w \\ p \\ q \end{bmatrix} = -\nabla f(\hat{x}), \begin{bmatrix} w \\ p \\ q \end{bmatrix} \ge 0$ 

根据Farkas引理,上式有解的充要条件是

$$\begin{bmatrix} -A_1^T \\ -B_1^T \\ B^T \end{bmatrix} d \le 0, -\nabla f(\hat{x})^T d > 0 \ \mathcal{E} \mathbf{m}$$

即
$$\begin{cases} \nabla f(\hat{x})^T d < 0, \\ A_1^T d \geq 0 &$$
无解。因此线性规划的最优值为  $0 \\ B^T d = 0 \end{cases}$