RBE595 - Week 2 Programming Assignment

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This is a programming assignment where we were tasked with recreating a figure in our textbooks. The figure demonstrated the effects of modifying the ϵ for epsilon-greedy approaches. That figure and the code utilized to generate it is shared below:

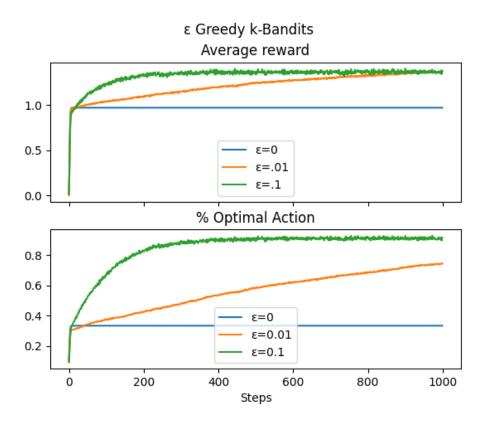


Figure 1: Recreated figure

```
from math import sqrt
from random import gauss, randint, uniform
from typing import List, Tuple

import matplotlib.pyplot as plt

def perform_run(
    steps: int, epsilon: float, k_bandits: int
) -> Tuple[List[float], List[int]]:
    """
    perform_run takes a given number of steps and an epsilon, and then takes that run for :steps: steps. Once this is done it returns a list of each rewards on that step, and whether or not it was the optimal action (represented as 0 or 1)
    """
    rewards: List[float] = []
```

```
optimal: List[int] = []
    \# We need to create a specified amount of bandits with mean 0
    # and variance 1 for our problem
    mean = 0
    variance = 1
    bandits = [gauss(mean, sqrt(variance)) for i in range(0, k_bandits)]
    best_bandit = bandits.index(max(bandits))
    # We assume some knowledge about the bandits. Over time we will learn
    # more as we explore.
    knowledge = [gauss(mean, sqrt(variance)) for i in range(0, k_bandits)]
    for i in range(0, steps):
        if uniform(0, 1) <= 1 - epsilon:</pre>
             # In this situation we act greedily.
             index = knowledge.index(max(knowledge))
        else:
             # We explore here
             index = randint(0, k_bandits - 1)
        # Grab our reward
        reward = bandits[index]
        knowledge[index] = reward
        rewards.append(reward)
        # Is it optimal? Record that
        optimal.append(1 if index == best_bandit else 0)
    return rewards, optimal
def run_experiment(runs: int, steps_per_run: int, epsilon: float, k_bandits: int):
    all_rewards: List[float] = [0.0] * steps_per_run
    all_optimal: List[float] = [0.0] * steps_per_run
    for _ in range(0, runs):
        rewards, optimal = perform_run(steps_per_run, epsilon, k_bandits)
        # We are iterativeley calculating the all_rewards
        # and all_optimal averages so we can avoid holding
        # it all in memory
        for index, _ in enumerate(all_rewards):
             all_rewards[index] += rewards[index] / runs
             all_optimal[index] += optimal[index] / runs
    return all_rewards, all_optimal
if __name__ == "__main__":
   runs = 2000
    steps = 1000
    bandits = 10
    rewards_00, optimal_00 = run_experiment(runs, steps, 0.00, bandits)
    rewards_01, optimal_01 = run_experiment(runs, steps, 0.01, bandits)
    rewards_10, optimal_10 = run_experiment(runs, steps, 0.10, bandits)
    figure, axis = plt.subplots(2, sharex=True)
    plt.xlabel("Steps")
    figure.suptitle(" Greedy k-Bandits")
    axis[0].set_title("Average reward")
    axis[0].plot(rewards_00, label=" =0")
axis[0].plot(rewards_01, label=" =.01")
axis[0].plot(rewards_10, label=" =.1")
    axis[0].legend(loc="lower center")
    axis[1].set_title("% Optimal Action")
    axis[1].plot(optimal_00, label=" =0")
axis[1].plot(optimal_01, label=" =0.01")
axis[1].plot(optimal_10, label=" =0.1")
    axis[1].legend(loc="lower center")
```

figure.savefig("./epsilon_greedy.png")