# Clinical Reinforcement Learning

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## Housekeeping

#### 1. Final projects

- Start early
- Reach out to professors and TAs if you need help

#### 2. HW5 and HW6

- Final stretch!
- HW6 going out Thurs

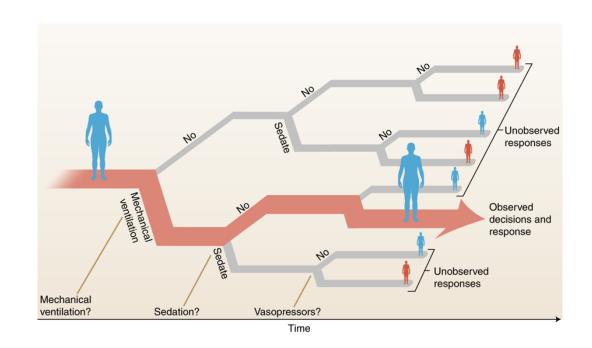
#### Agenda for today

- 1. Housekeeping
- 2. Review lecture material [15 mins]
- 3. Smoking cessation two-stage example [15 mins]
- 4. Broader discussion [15 mins]

**Goal:** 1) contextualize RL lectures this week, 2) balance optimism and skepticism about RL in healthcare

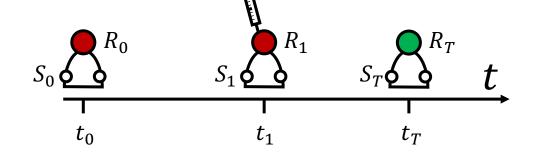
## Why clinical reinforcement learning?

- Recent wins from AlphaGo,
   AlphaStar, and other video games
- Computational gains and methodological advances mean we can model more complex state and action spaces.
- With tools learned so far, we can only make static decisions.
- How can we make dynamic treatment policies?



# Great! Now let's treat patients

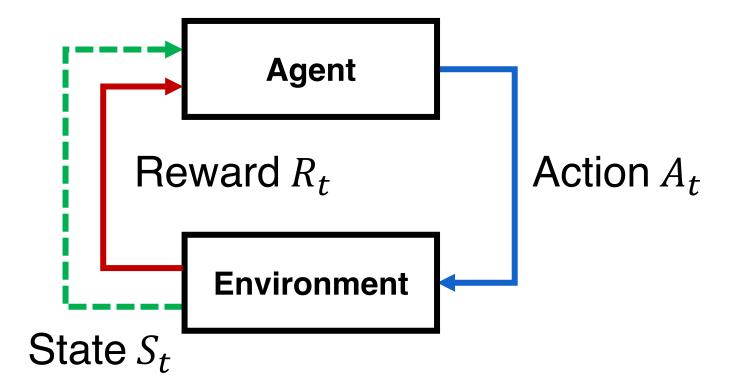
- Patient state at time  $S_t$  is like the game board
- Medical treatments  $A_t$  are like the actions
- Outcomes  $R_t$  are the rewards in the game
- What could **possibly** go wrong?



[Slide 14 of Lecture 16]

#### Decision processes

• An agent repeatedly, at times t takes actions  $A_t$  to receive rewards  $R_t$  from an environment, the state  $S_t$  of which is (partially) observed



[Slide 16 of Lecture 16]

#### Model-based RL Value-based RL Policy-based RL

Want to learn

**Tools** 

Useful for observational data?

Relevant Lectures

#### Model-based RL

Value-based RL

**Policy-based RL** 

Want to learn

Transitions Value/return  $p(S_t \mid S_{t-1}, A_{t-1})$   $p(G_t \mid S_t, A_t)$ 

Policy  $p(A_t \mid S_t)$ 

**Tools** 

Useful for data?

> Relevant Lectures

observational

# Model-based RL Transitions Want to learn $p(S_t | S_{t-1}, A_{t-1}) p(G_t | S_t, A_t)$ **Tools**



**Policy-based RL** 

Value/return **Policy**  $p(A_t \mid S_t)$ 

Q-learning, Gestimation

Yes

Relevant Lectures

Fredrik Johansson (L16)

Useful for observational data?

	Model-based RL	Value-based RL	Policy-based RL
Want to learn	Transitions $p(S_t   S_{t-1}, A_{t-1})$	Value/return $p(G_t \mid S_t, A_t)$	Policy $p(A_t \mid S_t)$
Tools	G-computation, MDP estimation	Q-learning, G- estimation	
Useful for observational data?	Yes	Yes	
Relevant Lectures	Barbra Dickerman (L17)	Fredrik Johansson (L16)	

	Model-based RL	Value-based RL	Policy-based RL
Want to learn	Transitions $p(S_t   S_{t-1}, A_{t-1})$	Value/return $p(G_t \mid S_t, A_t)$	Policy $p(A_t \mid S_t)$
Tools	G-computation, MDP estimation	Q-learning, G- estimation	REINFORCE, marginal structural models
Useful for observational data?	Yes	Yes	No
Relevant Lectures	Barbra Dickerman (L17)	Fredrik Johansson (L16)	AlphaGo on Netflix

#### Recap: Fredrik Johansson (Lecture 16)

- "Assign value to a state-action pair and maximize over time"
- Similar to covariate adjustment (from causal inference) with regression as a moving target
- Solve Bellman equations with dynamic programming

#### Recap: Barbra Dickerman (Lecture 17)

- "Simulate a weighted average of risks and then analyze"
- G-formula assesses a given policy based on observational data
- MC sampling to estimate risk over 10k population, bootstrap to get confidence intervals
- Sensitivity analysis for the confounder of serious medical condition

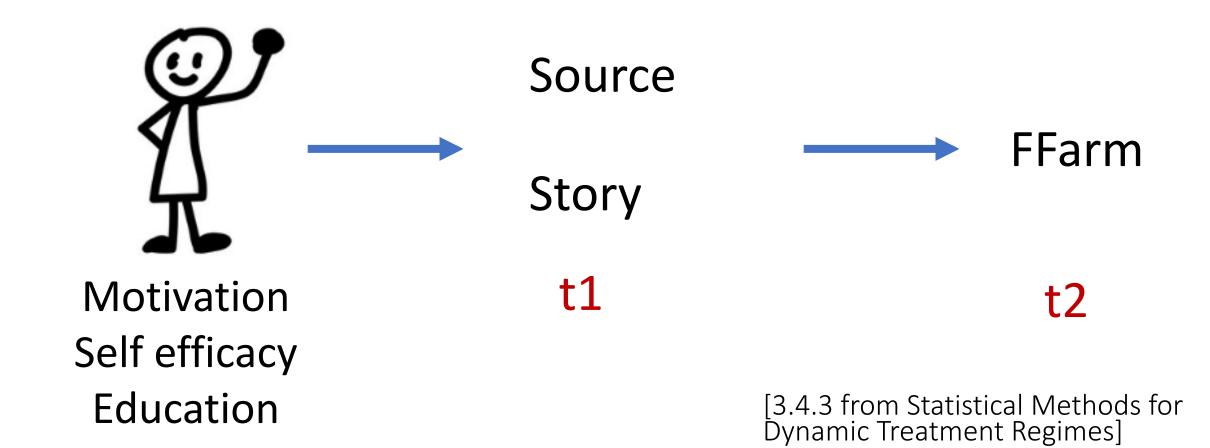
#### FAQs: Clinical Reinforcement Learning

- Where does the deep learning come in?
  - Anywhere we have a probability function, we can estimate the probability density
- When should we use model-based vs value-based learning?
  - Model-based when you can build simulator; value-based otherwise
- Why can we beat the world's best player in Go but not solve a problem of when to use vassopressors for sepsis?
  - Review lectures 16 and 17.
- All of these papers and approaches have big limitations.
  - Yes, yes they do. We make assumptions and then sensitivity analyses.

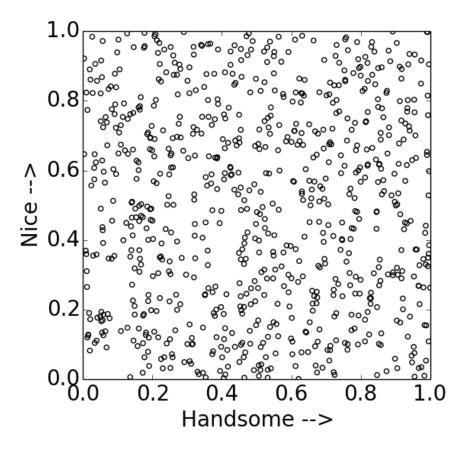
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#### Smoking Cessation: Two steps



# Interlude: Berkson's paradox

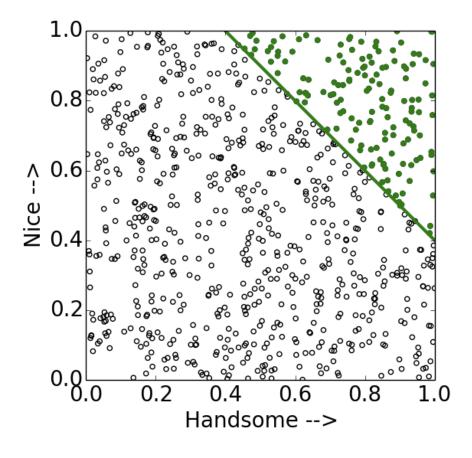


$$P(A|B) = A$$
  
 $P(B|A) = B$ 

Q: Are handsome guys really jerks?

[corysimon.github.io]

# Interlude: Berkson's paradox

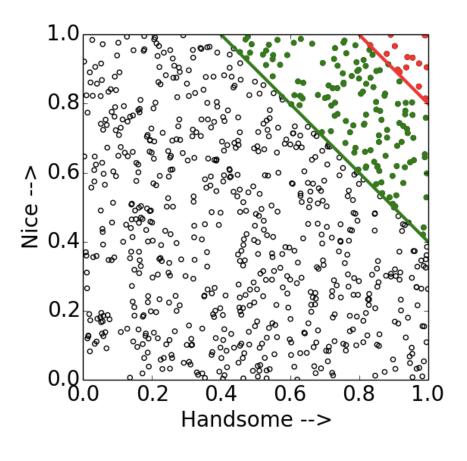


P(A|B, A or B) < P(A|A or B)

Dating criterion is subset of field.

[corysimon.github.io]

# Interlude: Berkson's paradox



P(A | B, A or B) < P(A | A or B)

Therefore, negative correlation in variables in subset despite uncorrelated overall.

[corysimon.github.io]

#### Back to Smoking Cessation

- Clearly naïve estimation at the end is wrong.
- How can we estimate the impact of the first stage of treatment?
- Assuming linear (with some interaction terms) models, how can set up a two-stage analysis?



#### Smoking Cessation: Two steps

#### • Actions:

- A1: Source x Story
- A2: FFarm

#### Observed:

- O1: motivation, self efficacy, education at t0
- O2: quit status, reduction in avg cigarettes smoked, num months not smoked at t1
- O3: same variables as O2 but at t2

#### Outcome:

- Y: quit status at the end of the study
- PQ6Quitstatus: quit at stage 1
- PQ6Quitstatus: quit at stage 2

[3.4.3 from Statistical Methods for Dynamic Treatment Regimes]

1. Fit stage 2 regression (n = 281) of FF6Quitstatus using the model:

$$\begin{split} \text{FF6Quitstatus} &= \beta_{20} + \beta_{21} \times \text{motivation} + \beta_{22} \times \text{source} \\ &+ \beta_{23} \times \text{selfefficacy} + \beta_{24} \times \text{story} \\ &+ \beta_{25} \times \text{education} + \beta_{26} \times \text{PQ6Quitstatus} \\ &+ \beta_{27} \times \text{source} \times \text{selfefficacy} \\ &+ \beta_{28} \times \text{story} \times \text{education} \\ &+ \left( \psi_{20} + \psi_{21} \times \text{PQ6Quitstatus} \right) \times \text{FFarm} + \text{error.} \end{split}$$

Actions

Outcomes

2. Construct the pseudo-outcome  $(\hat{Y}_1)$  for the stage 1 regression by plugging in the stage 2 estimates:

$$\begin{split} \hat{Y}_1 &= \texttt{PQ6Quitstatus} + \hat{\beta}_{20} + \hat{\beta}_{21} \times \texttt{motivation} + \hat{\beta}_{22} \times \texttt{source} \\ &+ \hat{\beta}_{23} \times \texttt{selfefficacy} + \hat{\beta}_{24} \times \texttt{story} \\ &+ \hat{\beta}_{25} \times \texttt{education} + \hat{\beta}_{26} \times \texttt{PQ6Quitstatus} \\ &+ \hat{\beta}_{27} \times \texttt{source} \times \texttt{selfefficacy} + \hat{\beta}_{28} \times \texttt{story} \times \texttt{education} \\ &+ \hat{\psi}_{20} + \hat{\psi}_{21} \times \texttt{PQ6Quitstatus} \end{split}$$

.....

3. Fit stage 1 regression (n = 1,401) of the pseudo-outcome using a model of the form:

$$\hat{Y}_1 = \beta_{10} + \beta_{11} \times \text{motivation} + \beta_{12} \times \text{selfefficacy} + \beta_{13} \times \text{education} + \left(\psi_{10}^{(1)} + \psi_{11}^{(1)} \times \text{selfefficacy}\right) \times \text{source} + \left(\psi_{10}^{(2)} + \psi_{11}^{(2)} \times \text{education}\right) \times \text{story} + \text{error.}$$

**Table 3.1** Regression coefficients and 95 % bootstrap confidence intervals at stage 1 (significant effects are in bold)

Variable		Coefficient	95 % CI
motivation		0.04	(-0.00, 0.08)
selfefficacy		0.03	(0.00, 0.06)
education		-0.01	(-0.07, 0.06)
source		-0.15	(-0.35, 0.06)
source	$\times$ selfefficacy	0.03	(0.00, 0.06)
story		0.05	(-0.01, 0.11)
story × education		-0.07	(-0.13, -0.01)

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#### Evaluating Reinforcement Learning Algorithms in Observational Health Settings

Omer Gottesman<sup>1</sup>, Fredrik Johansson<sup>2</sup>, Joshua Meier<sup>1</sup>, Jack Dent<sup>1</sup>, Donghun Lee<sup>1</sup>, Srivatsan Srinivasan<sup>1</sup>, Linying Zhang<sup>3</sup>, Yi Ding<sup>3</sup>, David Wihl<sup>1</sup>, Xuefeng Peng<sup>1</sup>, Jiayu Yao<sup>1</sup>, Isaac Lage<sup>1</sup>, Christopher Mosch<sup>4</sup>, Li-wei H. Lehman<sup>2</sup>, Matthieu Komorowski<sup>5,6</sup>, Aldo Faisal<sup>7</sup>, Leo Anthony Celi<sup>5,8,9</sup>, David Sontag<sup>2</sup>, and Finale Doshi-Velez<sup>1</sup>

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<sup>2</sup>Institute for Medical Engineering and Science, MIT

<sup>3</sup>T.H. Chan School of Public Health, Harvard University

<sup>4</sup>Department of Statistics, Harvard University

<sup>5</sup>Laboratory for Computational Physiology, Harvard-MIT Health Sciences & Technology, MIT

<sup>6</sup>Department of Surgery and Cancer, Faculty of Medicine, Imperial College

<sup>7</sup>Department of Bioengineering, Imperial College London
<sup>8</sup>Division of Pulmonary, Critical Care and Sleep Medicine, Beth Israel
Deaconess Medical Center
<sup>9</sup>MIT Critical Data

London

https://arxiv.org/pdf/1805.12298.pdf

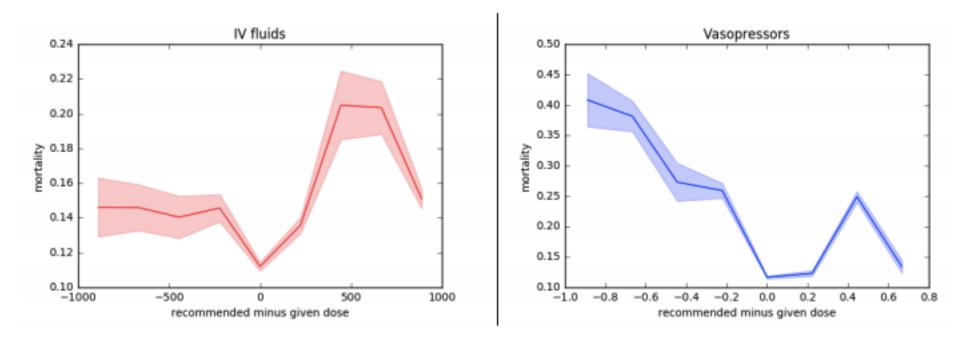
### What is the correct representation?

- We want to include all confounders in patient history
- Large feature spaces may make reinforcement learning intractable, so how do we learn a succinct but comprehensive representation?
- Mini experiment:
  - K-means cluster into 100 or 200 "patient types"
  - Find optimal sepsis treatment based on patient type as covariate
  - Repeat 5 times with different clustering initializations
- When 100 types, agreement on optimal treatment was 26%; when 200 types, agreement was 14%

[Gottesman et al, 2018 Nature Medicine]

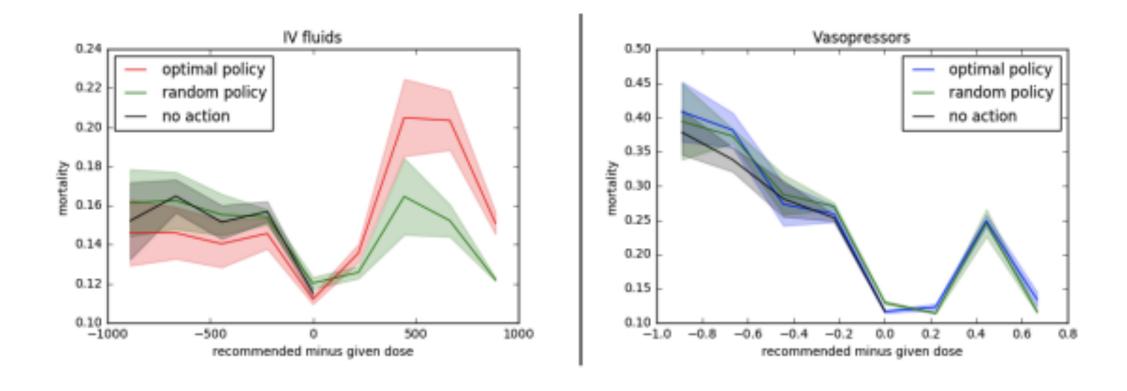
#### What about ad-hoc evaluation methods?

 U-curve evaluation: Difference between clinician policy and evaluation policy should be correlated with outcome like mortality



[Gottesman et al, 2018 Nature Medicine]

#### What about ad-hoc evaluation methods?



[Gottesman et al, 2018 Nature Medicine]

#### Other considerations and recommendations

- Design data collection and representations to make causal conclusions
- Limit yourself to actions and policies similar to physicians
- Be cognizant of effective sample size
- Clearly explain limitations

#### Takeaways: Clinical RL

- In theory, RL fits well into existing clinical workflow
- Model-based and value-based learning work well on observational healthcare data — with well defined actions and states
- Current bleeding edge research works through very few steps
- Design analysis to mimic clinician perspective and test sensitivity and robustness

# Have a great weekend!