Multiparty session types

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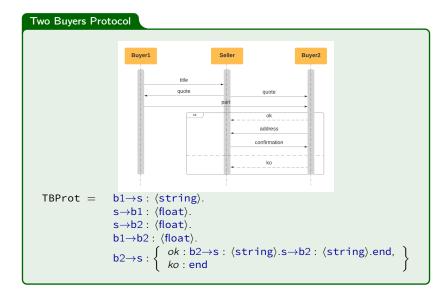
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Multiparty session types¹

- Extension of binary session types to multiparty sessions
- Asynchronous communications
- ▶ Interactions are abstracted as a global scenario, namely, Global types
 - specify dependencies and causal chains of multiparty asynchronous interactions

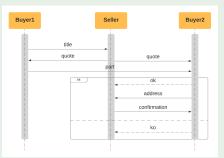
¹Honda, K., Yoshida, N., & Carbone, M. Multiparty asynchronous session types. POPL 2008

Global Graph (Choreography)



Local Types

Two Buyers Protocol



Buyer1 = !string.?float.!float.end

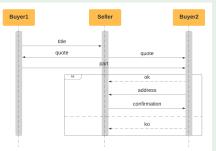
- ► The first message (string) is for the Seller and the second one (float) is for Buyer2? Information absent in the local type
- ▶ There are alternatives:
 - ▶ a là communicating machines: one channel for each pair in each direction

Buyer1 =
$$b_1s!\langle string \rangle.sb_1?\langle float \rangle.b_1b_2!\langle float \rangle.end$$

Decorated global graphs

Global Graph (Choreography)

Two Buyers Protocol



```
\label{eq:tring} \begin{split} \mathsf{TBProt} &= \mathsf{b1} \!\!\to \!\! \mathsf{s} : x \, \langle \mathsf{string} \rangle, \\ &\quad \mathsf{s} \!\!\to \!\! \mathsf{b1} : y \, \langle \mathsf{float} \rangle, \\ &\quad \mathsf{s} \!\!\to \!\! \mathsf{b2} : z_1 \, \langle \mathsf{float} \rangle, \\ &\quad \mathsf{b1} \!\!\to \!\! \mathsf{b2} : z_2 \, \langle \mathsf{float} \rangle, \\ &\quad \mathsf{b2} \!\!\to \!\! \mathsf{s} : x \left\{ \begin{array}{l} \mathit{ok} : \mathsf{b2} \!\!\to \!\! \mathsf{s} : x \, \langle \mathsf{string} \rangle. \mathsf{s} \!\!\to \!\! \mathsf{b2} : z_1 \, \langle \mathsf{string} \rangle. \mathsf{end}, \\ \mathit{ko} : \mathsf{end} \end{array} \right\} \\ \mathsf{Buyer1} &= x! \, \langle \mathsf{string} \rangle. y? \, \langle \mathsf{float} \rangle. z_2! \, \langle \mathsf{float} \rangle. \mathsf{end} \end{split}
```

First-order, finite MST

Syntax

- p, r, ... : participants (also roles)
- ▶ x, y, ...: communication channels
- ▶ /, ... : labels
- ▶ _: tuples

$$\begin{array}{ll} \mathsf{G} &= \mathsf{p} \!\!\to\! \mathsf{q} : x \langle \mathsf{int} \rangle. \mathsf{p} \!\!\to\! \mathsf{r} : y \langle \mathsf{bool} \rangle. \mathsf{end} \\ P_p &= x ! 1. y ! \mathsf{true.0} \\ P_q &= x ?(i).0 \\ P_r &= y ?(j).0 \end{array}$$

G =
$$p \rightarrow q : x \langle int \rangle. p \rightarrow r : x \langle bool \rangle. end$$

 $P_p = x! 1.x! true.0$
 $P_q = x?(i).0$
 $P_r = x?(j).0$

Example

```
G = p \rightarrow q : x \langle int \rangle . p \rightarrow r : x \langle bool \rangle . end

P_p = x! 1.x! true.0

P_q = x?(i).0

P_r = x?(j).0
```

We cannot ensure that P_q gets 1 and P_r gets true (race on x) Hence, G is bad (Output-to-Output bad)

G =
$$p \rightarrow q : x \langle int \rangle . r \rightarrow q : y \langle bool \rangle . end$$

 $P_p = x!1.0$
 $P_q = x?(i).y?(j).0$
 $P_r = y!true.0$

Example

G =
$$p \rightarrow q : x \langle int \rangle . r \rightarrow q : y \langle bool \rangle . end$$

 $P_p = x!1.0$
 $P_q = x?(i).y?(j).0$
 $P_r = y!true.0$

No races on channels x and yHence, G is good (Input-to-Input good)

G =
$$p \rightarrow q : x \langle int \rangle . r \rightarrow q : x \langle bool \rangle . end$$

 $P_p = x! 1.0$
 $P_q = x?(i).x?(j).0$
 $P_r = x! true.0$

Example

G =
$$p \rightarrow q : x \langle int \rangle . r \rightarrow q : x \langle bool \rangle . end$$

 $P_p = x ! 1.0$
 $P_q = x ? (i) . x ? (j) . 0$
 $P_r = x ! true . 0$

Race on x

Hence, G is bad (Input-to-Input bad)

G =
$$p\rightarrow q: x \langle int \rangle. q\rightarrow r: x \langle int \rangle. end$$

 $P_p = x!1.0$
 $P_q = x?(i).x!i.0$
 $P_r = x?(i).0$

Example

G =
$$p\rightarrow q: x \langle int \rangle. q\rightarrow r: x \langle int \rangle. end$$

 $P_p = x!1.0$
 $P_q = x?(i).x!i.0$
 $P_r = x?(i).0$

Race on x

Hence, G is bad (Input-to-Output bad)

G =
$$p\rightarrow q: x \langle int \rangle. q\rightarrow r: y \langle int \rangle. end$$

 $P_p = x!1.0$
 $P_q = x?(i).y!i.0$
 $P_r = y?(i).0$

Example

G =
$$p\rightarrow q: x \langle int \rangle. q\rightarrow r: y \langle int \rangle. end$$

 $P_p = x!1.0$
 $P_q = x?(i).y!i.0$
 $P_r = y?(i).0$

No Races on x and yHence, G is good (Input-to-Output good)

$$\begin{array}{ll} \mathsf{G} &= \mathsf{p} \!\!\to\! \mathsf{q} : x \, \langle \mathsf{int} \rangle \, . \, \mathsf{p} \!\!\to\! \mathsf{q} : x \, \langle \mathsf{bool} \rangle \, . \, \mathsf{end} \\ P_p &= x \!\!:\! 1 . x \!\!:\! \mathsf{true.0} \\ P_q &= x \!\!? (i) . y \!\!? (j) . \mathbf{0} \end{array}$$

Example

$$G = p \rightarrow q : x \langle int \rangle . p \rightarrow q : x \langle bool \rangle . end$$

 $P_p = x!1.x!true.0$
 $P_q = x?(i).y?(j).0$

No Races on x

Hence, G is good (Input-to-Input, Output-to-Output good)

```
G = p\rightarrow q: x \langle int \rangle.s \rightarrow r: y \langle bool \rangle.p \rightarrow r: x \langle bool \rangle.end

P_p = x!1.x!true.0

P_q = x?(i).0

P_r = y?(i).x?(j).0

P_s = y!true.0
```

Example

```
G = p\rightarrow q: x\langle int\rangle.s\rightarrow r: y\langle bool\rangle.p\rightarrow r: x\langle bool\rangle.end

P_p = x!1.x!true.0

P_q = x?(i).0

P_r = y?(i).x?(j).0

P_s = y!true.0
```

Races on \boldsymbol{x}

Hence, G is bad

```
G = p\rightarrow q: x \langle int \rangle. q\rightarrow r: y \langle bool \rangle. p\rightarrow r: x \langle bool \rangle. end

P_p = x!1.x!true.0

P_q = x?(i).y!true.0

P_r = y?(i).x?(j).0
```

Example

```
\begin{array}{ll} \mathsf{G} &= \mathsf{p} {\rightarrow} \mathsf{q} : x \langle \mathsf{int} \rangle. \mathsf{q} {\rightarrow} \mathsf{r} : y \langle \mathsf{bool} \rangle. \mathsf{p} {\rightarrow} \mathsf{r} : x \langle \mathsf{bool} \rangle. \mathsf{end} \\ P_p &= x ! 1. x ! \mathsf{true.0} \\ P_q &= x ? (i). y ! \mathsf{true.0} \\ P_r &= y ? (i). x ? (j).0 \\ \end{array} No races on x and y Hence, \mathsf{G} is good
```

This notion is formalised as LINEARITY (we postpone its definition)

Local types

Syntax

$$\begin{array}{lll} \mathsf{T} ::= & x?\langle \tilde{\mathsf{S}} \rangle . \, \mathsf{T} & \text{receive} \\ & \mid & x!\langle \tilde{\mathsf{S}} \rangle . \, \mathsf{T} & \text{send} \\ & \mid & x \oplus \{I_i : \mathsf{T}_i\}_{i \in I} & \text{select} \\ & \mid & x \& \{I_i : \mathsf{T}_i\}_{i \in I} & \text{branch} \\ & \mid & \text{end} & \text{termination} \\ \\ \mathsf{S} ::= & \text{int} \mid & \text{unit} \mid & \text{bool} \mid & \dots & \text{basic sorts} \end{array}$$

Projection

Definition

$$\mathsf{G}\!\!\upharpoonright \!\! \mathsf{p} = \begin{cases} x\! \mid \! \langle \tilde{\mathsf{S}} \rangle . \mathsf{G}'\!\!\upharpoonright \!\! \mathsf{p} & \text{if } \mathsf{G} = \mathsf{p} \!\!\to \!\! \mathsf{q} : x \, \langle \tilde{\mathsf{S}} \rangle . \mathsf{G}' \ and \ \mathsf{p} \neq \mathsf{q} \\ x\! \mid \! \langle \tilde{\mathsf{S}} \rangle . \mathsf{G}'\!\!\upharpoonright \!\! \mathsf{p} & \text{if } \mathsf{G} = \mathsf{q} \!\!\to \!\! \mathsf{p} : x \, \langle \tilde{\mathsf{S}} \rangle . \mathsf{G}' \ and \ \mathsf{p} \neq \mathsf{q} \\ \mathsf{G}'\!\!\upharpoonright \!\! \mathsf{p} & \text{if } \mathsf{G} = \mathsf{q} \!\!\to \!\! \mathsf{r} : x \, \langle \tilde{\mathsf{S}} \rangle . \mathsf{G}' \ and \ \mathsf{p} \neq \mathsf{q} \neq \mathsf{r} \\ x \oplus \{\mathit{l}_i : \mathsf{G}_i \!\!\upharpoonright \!\! \mathsf{p}\}_{i \in \mathcal{I}} & \text{if } \mathsf{G} = \mathsf{p} \!\!\to \!\! \mathsf{q} : x \{\mathit{l}_i : \mathsf{G}_i\}_{i \in \mathcal{I}} \ and \ \mathsf{p} \neq \mathsf{q} \\ x \& \{\mathit{l}_i : \mathsf{G}_i \!\!\upharpoonright \!\! \mathsf{p}\}_{i \in \mathcal{I}} & \text{if } \mathsf{G} = \mathsf{q} \!\!\to \!\! \mathsf{p} : x \{\mathit{l}_i : \mathsf{G}_i\}_{i \in \mathcal{I}} \ and \ \mathsf{p} \neq \mathsf{q} \\ \mathsf{G}_1 \!\!\upharpoonright \!\! \mathsf{p} & \text{if } \mathsf{G} = \mathsf{q} \!\!\to \!\! \mathsf{r} : x \{\mathit{l}_i : \mathsf{G}_i\}_{i \in \mathcal{I}} \ and \ \mathsf{p} \neq \mathsf{q} \neq \mathsf{r} \ and \\ \forall i, j.\mathsf{G}_i \!\!\upharpoonright \!\! \mathsf{p} = \mathsf{G}_j \!\!\upharpoonright \!\! \mathsf{p} \\ \mathsf{G}_i \!\!\upharpoonright \!\! \mathsf{p} & \text{if } \mathsf{G} = \mathsf{G}_1 \mid \mathsf{G}_2 \ and \ \mathsf{p} \in \mathsf{G}_i \ and \ \mathsf{p} \not \in \mathsf{G}_j \ and \\ i \neq j \in \{1, 2\} \\ \mathsf{end} & \text{if } \mathsf{G} = \mathsf{G}_1 \mid \mathsf{G}_2 \ and \ \mathsf{p} \not \in \mathsf{G}_1 \ and \ \mathsf{p} \not \in \mathsf{G}_2 \end{cases}$$