Installation of Ubuntu / ROS Kinetic on VirtualBox

Download Ubuntu 16.04 from:

https://releases.ubuntu.com/16.04.7/ubuntu-16.04.7-desktop-amd64.iso

Download VirtualBox from :

https://www.virtualbox.org/

Install VirtualBox and run.
Machine, new.
Name: Ubuntu
Memory 2048Mb
Create a virtual hard disk now
VDI
Dynamically allocated
50Gb
Right click on ubuntu vm and click settings
System, Processor, select as many processors as it will allow
Storage, click on the empty DVD then under attributes click on the down arrow on the DVD and select "choose a disk file". Browse to the Ubuntu ISO file you downloaded earlier.
Make sure Network is enabled and attached to NAT
Click OK
Double click the Ubuntu VM to start it.
If it asks to select a start up disk select Ubuntu 16.04.7 and click start
When the Ubuntu DVD loads click Install Ubuntu
Click the Download updates box and click continue
Select Erase disk and install Ubuntu, Install now
Select continue
Select London as location and continue
Select English(UK) and continue
Enter a name and password and continue
When installation is complete click Restart now
Press enter
Log in to Ubuntu
Right click on the desktop and select Open Terminal
In the terminal window type the following:

sudo apt update

sudo apt upgrade

sudo sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb_release -sc) main" > /etc/apt/sources.list.d/ros-latest.list '
(the above statement is all one line with a space after the >)

sudo apt install curl

curl -s https://raw.githubusercontent.com/ros/rosdistro/master/ros.asc | sudo apt-key add -

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sudo apt update

sudo apt install ros-kinetic-desktop-full

echo "source /opt/ros/kinetic/setup.bash">> ~/.bashrc


source ~/.bashrc

sudo apt install python-rosdep python-rosinstall python-rosintall-generator python-wstool
build-essential

sudo rosdep init

rosdep update
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