Understanding Priors in Bayesian Neural Networks at the Unit Level

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Joint work with Julyan Arbel, Jakob Verbeek

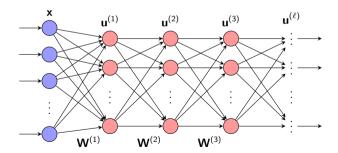
Machine Learning Reading Group, Grenoble July 3, 2019



Bayesian neural networks: why?

Neal [1996], MacKay [1992]

- Prior on weights, $w \sim N(\mu, \sigma^2)$
- Allows to model uncertainty
- Represents a standard neural network





Outline

Recent works on distributional properties

Sub-Weibull distributions

Main result: Prior on units gets heavier-tailed with depth

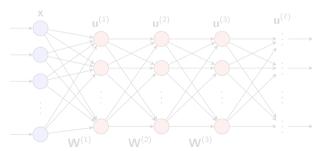
Regularization interpretation

Theorem (Neal [1996])

Consider a Bayesian neural network with (A1) iid Gaussian priors on the weights

(A2) with bounded variances and

(A3) ReLU activation function. Then conditional on input x, the marginal prior distribution of a unit $u^{(2)}$ of 2-nd hidden layer converges to a Gaussian process in a wide regime.





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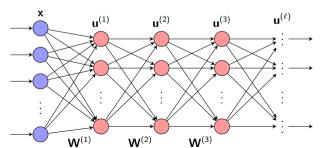
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Proof.

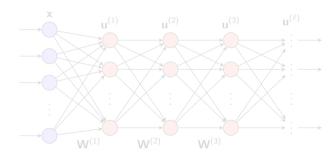
Components of $\mathbf{u}^{(1)}$ are iid \Rightarrow CLT





Theorem (Matthews et al. [2018], Lee et al. [2018])

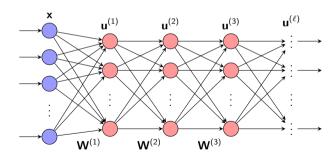
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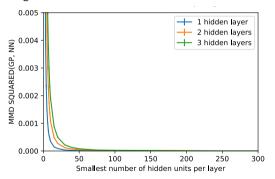


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Recent works on distributional properties

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Alexander G de G Matthews, Mark Rowland, Jiri Hron, Richard E Turner, and Zoubin Ghahramani, "Gaussian Process Behaviour in Wide Deep Neural Networks." ICLR (2018).

Jaehoon Lee, Jascha Sohl-dickstein, Jeffrey Pennington, Roman Novak, Sam Schoenholz, and Yasaman Bahri. "Deep neural networks as Gaussian processes." ICLR (2018).

Gaussian process approximation

Samuel S. Schoenholz, Justin Gilmer, Surya Ganguli, Jascha Sohl-Dickstein. "Deep Information Propagation." ICLR (2017).

- Prior on weights, $w \sim N(0, \sigma^2)$ iid
- Initialisation is a crucial step in deep NN
- "Edge of Chaos" initialization can lead to good performances

Soufiane Hayou, Arnaud Doucet, and Judith Rousseau. "On the Impact of the Activation Function on Deep Neural Networks Training." ICML (2019).

- Prior on weights, $w \sim N(0, \sigma^2)$ iid
- Gaussian process approximation $u^\ell \approx \mathcal{GP}(0,K^\ell)$ marginally
- "Edge of Chaos" initialization

Results:

- ullet Smooth activation functions (e.g. ELU) are better than ReLU activation, especially if ℓ is large
- "Edge of Chaos" accelerates the training and improves performances



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Distribution families with respect to tail behavior

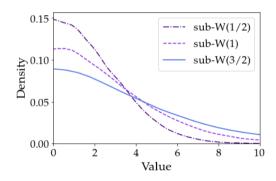
Vershynin [2018] - subG, subE;

Kuchibhotla and Chakrabortty [2018]; Vladimirova and Arbel [2019] - subW

For all $k \in \mathbb{N}$, k-th row moment: $||X||_k = (\mathbb{E}|X|^k)^{1/k}$

Distribution	Tail	Moments
Sub-Gaussian	$\overline{F}(x) \le e^{-\lambda x^2}$	$ X _k \leq C\sqrt{k}$
	$\overline{F}(x) \le e^{-\lambda x}$	$ X _k \leq Ck$
Sub-Weibull	$\overline{F}(x) \le e^{-\lambda x^{1/\theta}}$	$ X _k \leq Ck^{\theta}$

- $\theta > 0$ called tail parameter
- $\|X\|_k \asymp k^{\theta} \implies X \sim \text{subW}(\theta), \ \theta \text{ called}$ optimal
- subW(1/2) = subG, subW(1) = subE





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Assumptions on neural network

We analyze Bayesian neural networks which satisfy the following assumptions

(A1) Parameters. The weights w have i.i.d. Gaussian prior

$$extbf{\textit{w}} \sim \mathcal{N}(\mu, \sigma^2)$$

(A2) Nonlinearity. ReLU-like with envelope property: exist $c_1, c_2, d_2 \ge 0$, $d_1 > 0$ s.t.

$$|\phi(u)| \ge c_1 + d_1|u|$$
 for all $u \in \mathbb{R}_+$ or $u \in \mathbb{R}_-$, $|\phi(u)| \le c_2 + d_2|u|$ for all $u \in \mathbb{R}$.

- Examples: ReLU, ELU, PReLU etc, but no compactly supported like sigmoid and tanh.
- Nonlinearity does not harm the distributional tail

$$\|\phi(X)\|_ksymp \|X\|_k,\quad k\in\mathbb{N}$$



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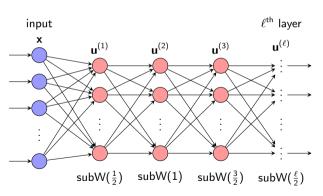
$$\|\phi(X)\|_k \asymp \|X\|_k, \quad k \in \mathbb{N}$$

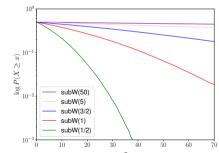


Main theorem

Consider a Bayesian neural network with (A1) i.i.d. Gaussian priors on the weights and (A2) nonlinearity satisfying envelope property.

Then conditional on input x, the marginal prior distribution of a unit $u^{(\ell)}$ of ℓ -th hidden layer is sub-Weibull with optimal tail parameter $\theta = \ell/2$: $\pi^{(\ell)}(u) \sim \text{subW}(\ell/2)$







Main result 00000

Recall. $X \sim \text{subW}(\theta) \iff \exists C > 0, ||X||_k = (\mathbb{E}|X|^k)^{1/k} \leq Ck^{\theta}, \text{ for all } k \in \mathbb{N}.$

$$\begin{split} \mathbf{g}^{(1)}(\mathbf{x}) &= \mathbf{W}^{(1)}\mathbf{x}, \quad \mathbf{h}^{(1)}(\mathbf{x}) = \phi(\mathbf{g}^{(1)}), \\ \mathbf{g}^{(\ell)}(\mathbf{x}) &= \mathbf{W}^{(\ell)}\mathbf{h}^{(\ell-1)}(\mathbf{x}), \quad \mathbf{h}^{(\ell)}(\mathbf{x}) = \phi(\mathbf{g}^{(\ell)}), \quad \ell = \{2, \dots, L\}. \end{split}$$

$$\|h^{(\ell)}\|_k \asymp k^{\ell/2}$$



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Notations. $\phi(\cdot)$ — nonlinearity, **g** — pre-nonlinearity, **h** — post-nonlinearity

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Goal. By induction with respect to hidden layer depth ℓ we want to show that

$$||h^{(\ell)}||_k \asymp k^{\ell/2}.$$



1. Base step: weights $w_i^{(1)}$ are iid Gaussian $\Rightarrow ||w||_k \times k^{1/2}$; for 1st layer

$$\|g^{(1)}\|_k = \left\|\sum_{i=1}^{H_1} w_i^{(1)} x_i\right\|_k \asymp k^{1/2}$$

From nonlinearity ϕ assumption

$$||h^{(1)}||_k = ||\phi(g^{(1)})||_k \times ||g^{(1)}||_k \times k^{1/2}$$

2. Induction step: if $g^{(\ell-1)}$, $h^{(\ell-1)} \sim subW((\ell-1)/2)$, then for ℓ -th layer

$$\|g^{(\ell)}\|_k = \left\|\sum_{i=1}^H w_i^{(\ell)} h_i^{(\ell-1)}\right\|_k \stackrel{(*)}{\sim} k^{1/2} \cdot k^{(\ell-1)/2} = k^{\ell/2}$$

2.1 Lower bound for (\star) by positive covariance result: $\forall s, t, \text{Cov}[(h^{(\ell-1)})^s, (\tilde{h}^{(\ell-1)})^t] \geq 0$

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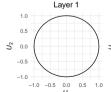


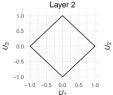
Interpretation: shrinkage effect

Maximum a Posteriori (MAP) is a Regularized Gaussian prior on the weights: problem

$$\begin{aligned} \max_{\mathbf{W}} \pi(\mathbf{W}|\mathcal{D}) &\propto \mathcal{L}(\mathcal{D}|\mathbf{W})\pi(\mathbf{W}) \\ \min_{\mathbf{W}} -\log \mathcal{L}(\mathcal{D}|\mathbf{W}) -\log \pi(\mathbf{W}) \\ \min_{\mathbf{W}} L(\mathbf{W}) + \lambda R(\mathbf{W}) \end{aligned}$$

 $L(\mathbf{W})$ is a loss function. $R(\mathbf{W})$ is a norm on \mathbb{R}^p , regularizer.

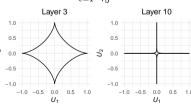




$$\pi(\mathbf{W}) = \prod_{\ell=1}^{L} \prod_{i,j} e^{-\frac{1}{2}(W_{i,j}^{(\ell)})^2}$$

Equivalent to the weight decay penalty (\mathcal{L}^2) :

$$R(\mathbf{W}) = \sum_{\ell=1}^{L} \sum_{i,i} (W_{i,j}^{(\ell)})^2 = \|\mathbf{W}\|_2^2,$$





Weight distribution
$$\pi(w) \approx e^{-w^2}$$

$$\Rightarrow$$

$$\ell$$
-th layer unit distribution $\pi^{(\ell)}(u) \approx e^{-u^{2/\ell}}$

Sklar's representation theorem:

$$\pi(\mathbf{U}) = \prod_{\ell=1}^L \prod_{m=1}^{H_\ell} \pi_m^{(\ell)}(U_m^{(\ell)}) C(F(\mathbf{U})),$$

where C represents the copula of \mathbf{U} (which characterizes all the dependence between the units).

Regularizer:

$$\begin{split} R(\mathbf{U}) &= -\sum_{\ell=1}^{L} \sum_{m=1}^{H_{\ell}} \log \pi_m^{(\ell)}(U_m^{(\ell)}) - \log C(F(\mathbf{U})), \\ &\approx \|\mathbf{U}^{(1)}\|_2^2 + \|\mathbf{U}_1^{(2)}\|_1 + \dots + \|\mathbf{U}^{(L)}\|_{2/L}^{2/L} - \log C(F(\mathbf{U})). \end{split}$$

Layer	Penalty on W	Penalty on	U
1	$\ {f W}^{(1)} \ _2^2$, ${\cal L}^2$	$\ \mathbf{U}^{(1)} \ _2^2$	\mathcal{L}^2 (weight decay)
2	$\ \mathbf{W}^{(2)}\ _2^2$, \mathcal{L}^2	$\ \mathbf{U}^{(2)}\ $	\mathcal{L}^1 (Lasso)
ℓ	$\ \mathbf{W}^{(\ell)}\ _2^2$, \mathcal{L}^2	$\ \mathbf{U}^{(\ell)} \ _{2/\ell}^{2/\ell}$	$\mathcal{L}^{2/\ell}$



Conclusion

- (i) We define the notion of sub-Weibull distributions, which are characterized by tails lighter than (or equally light as) Weibull distributions.
- (ii) We proved that the marginal prior distribution of the units are heavier-tailed as depth increases.
- (iii) We offered an interpretation from a regularization viewpoint.

Future directions:

- prove the Gaussian process limit of sub-Weibull distributions in the wide regime using Kuchibhotla and Chakrabortty [2018];
- investigate if the described regularization mechanism induces sparsity at the unit level.



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