

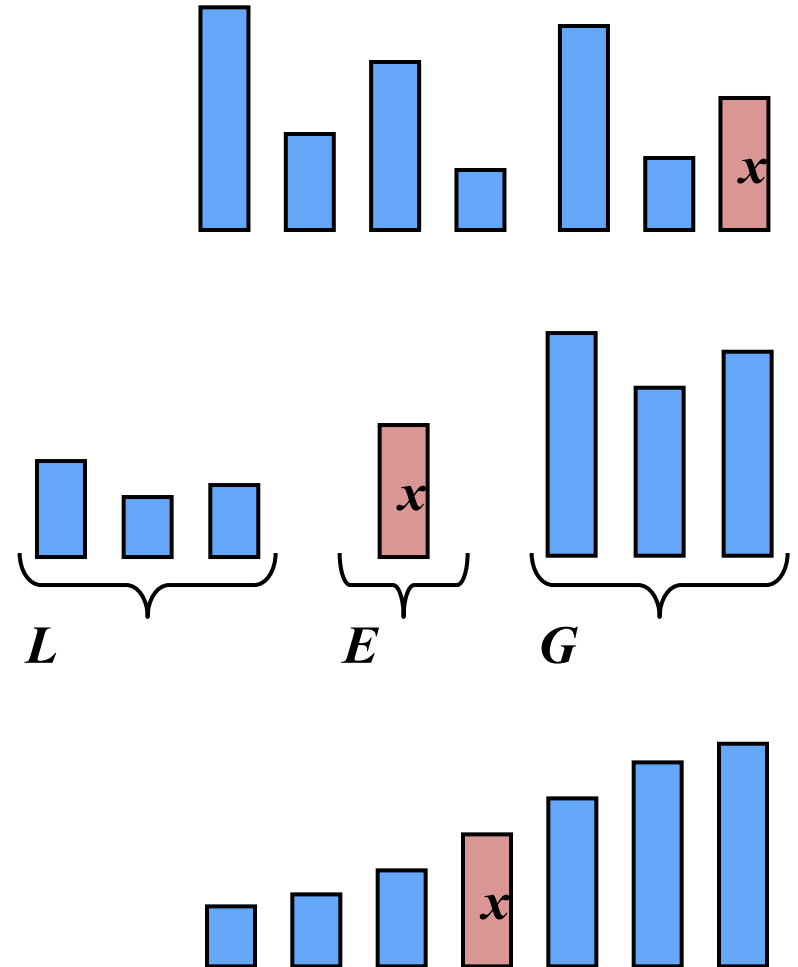
Quick Sort

Quick Sort

A sorting algorithm based on the divide-and-conquer paradigm

- **Divide**: pick a **pivot** element x and partition S into
 - L elements less than x
 - E elements equal to x
 - G elements greater than x
- **Recur**: sort L and G
- **Conquer**: join L , E and G

The choice of the pivot affects the algorithm's performance.



Partition

1. Remove each element y from S
 2. Insert y into L , E or G , depending on the result of the comparison with the pivot x
- Each insert/remove takes $O(1)$ time.
 - Thus, the partition step of quick-sort takes $O(n)$ time.



Algorithm *partition*(S, p)

Input sequence S , position p of pivot

Output subsequences L, E, G

$L, E, G \leftarrow$ empty sequences

$x \leftarrow S.remove(p)$

while $\neg S.isEmpty()$

$y \leftarrow S.remove(S.first())$

if $y < x$

$L.insertLast(y)$

else if $y = x$

$E.insertLast(y)$

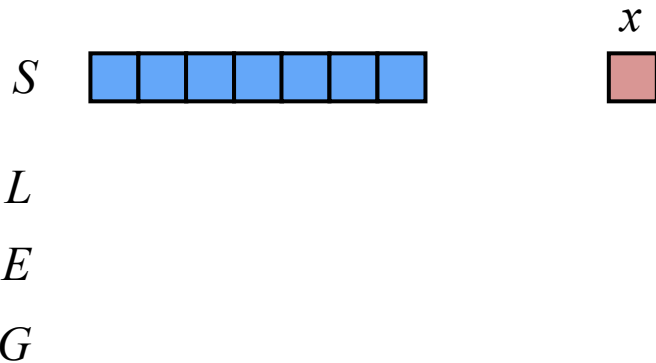
else $\{ y > x \}$

$G.insertLast(y)$

return L, E, G

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The choice of the pivot affects the performance of Quick Sort.

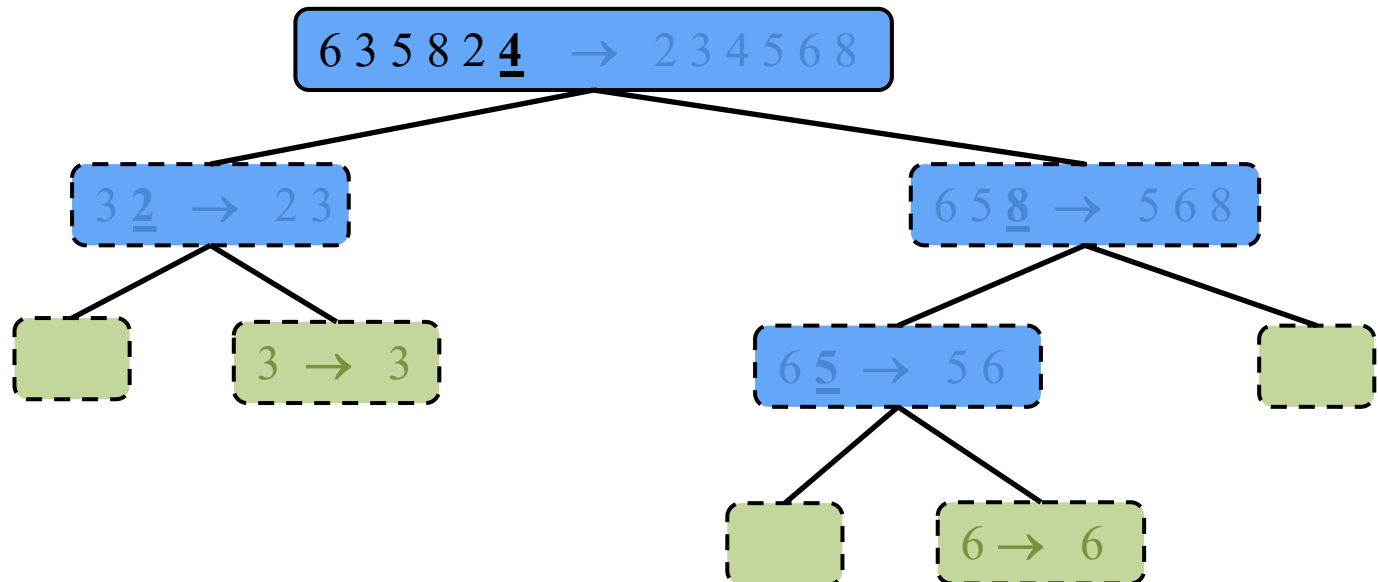
Quick-Sort Tree

An execution of quick-sort depicted by a binary tree

- Each node represents a recursive call of quick-sort and stores
 - Unsorted sequence before the execution and its pivot
 - Sorted sequence at the end of the execution
- The root is the initial call
- The leaves are calls on subsequences of size 0 or 1

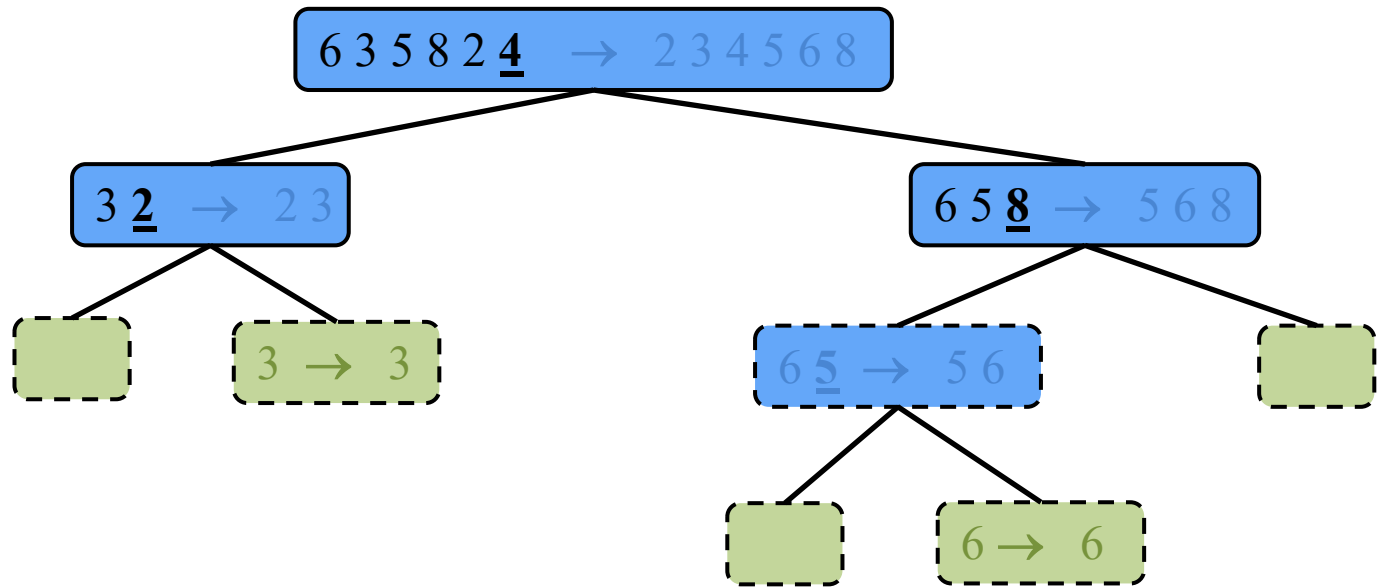
Quick Sort Execution

- Strategy: Select the last element as the pivot



Quick Sort Execution

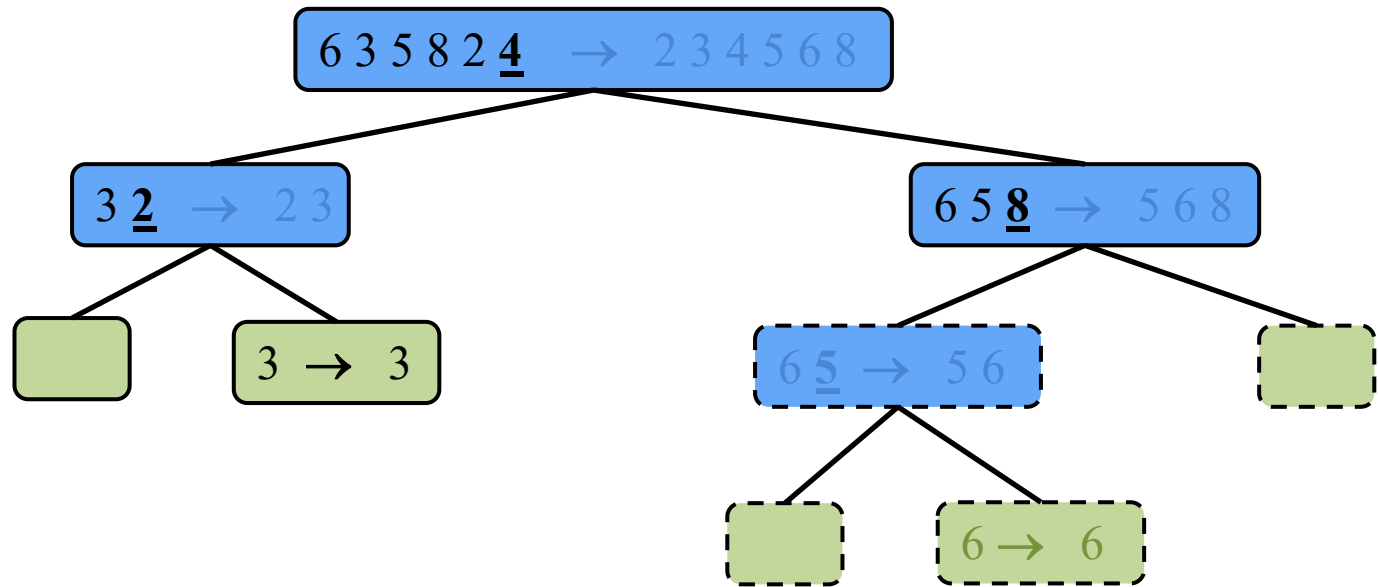
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- Select pivot, partition, recursive call

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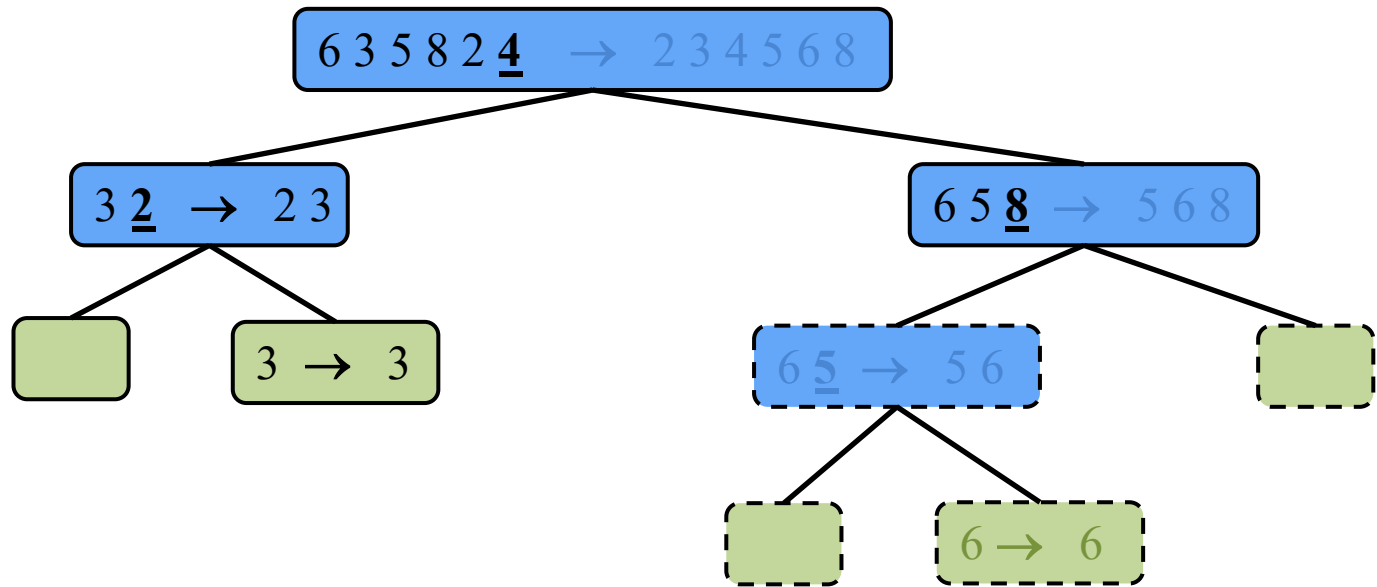
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- Select pivot, partition, recursive call

Quick Sort Execution

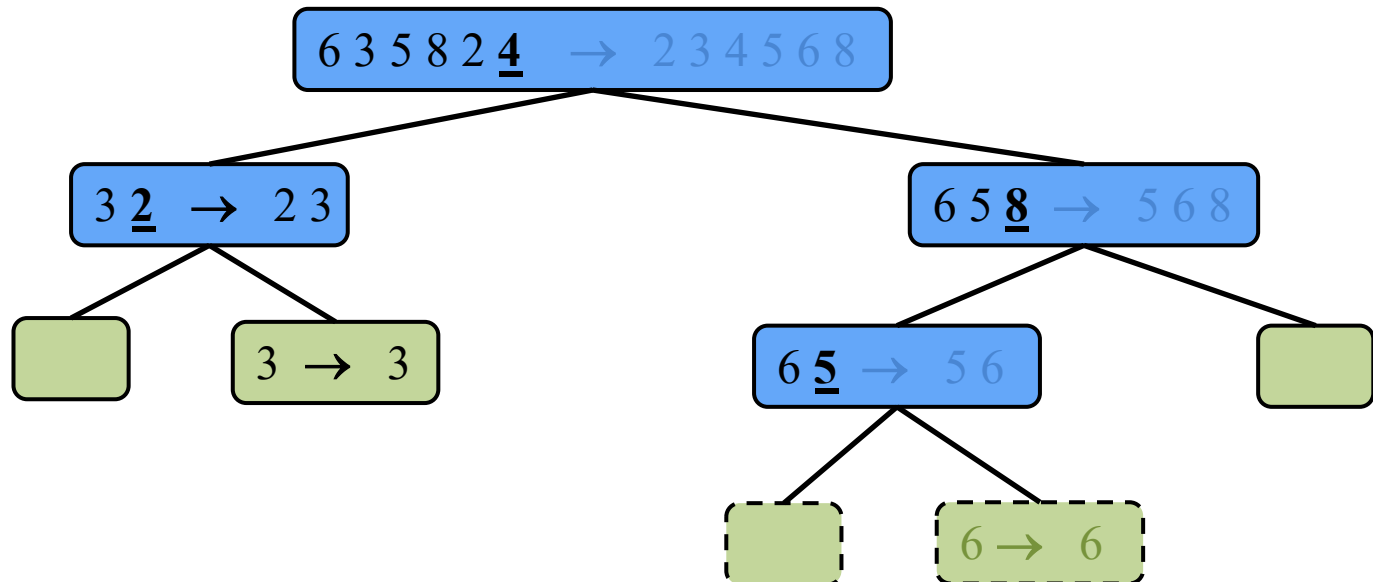
- Strategy: Select the last element as the pivot



- Join

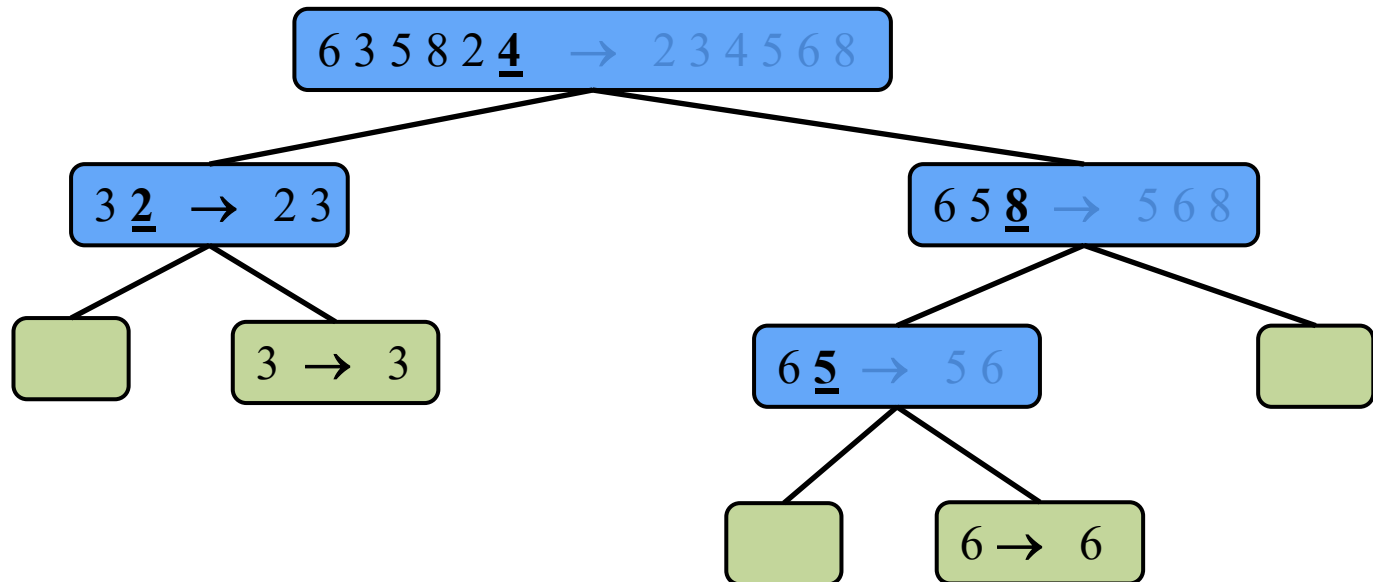
Quick Sort Execution

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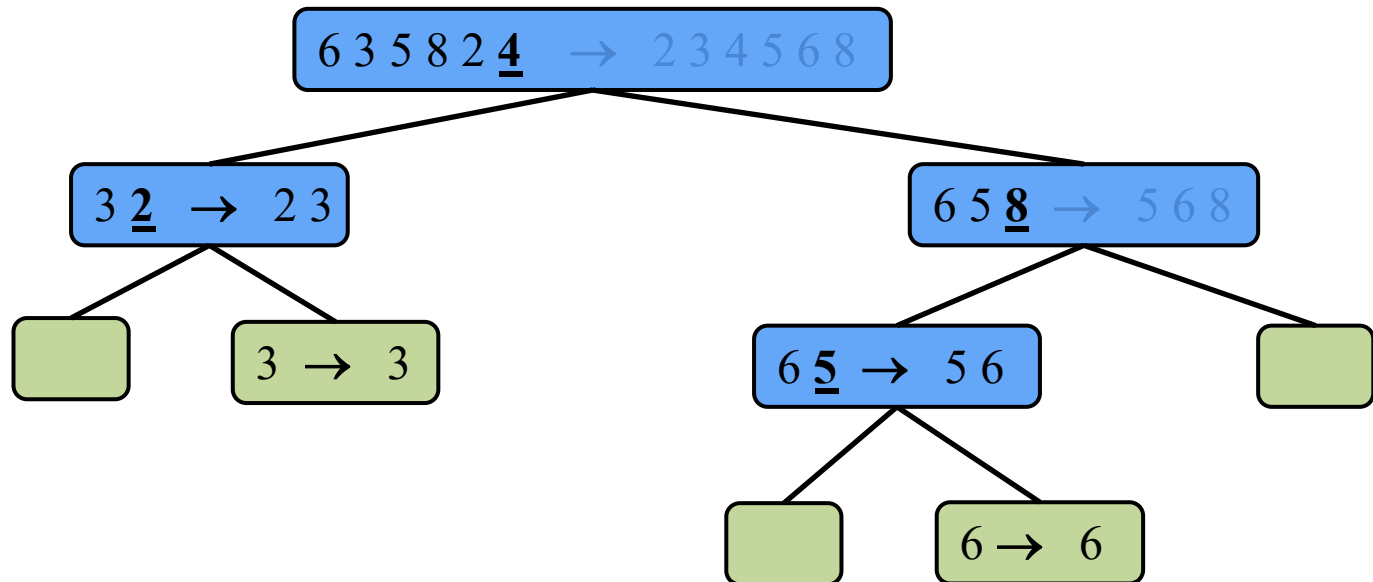
Quick Sort Execution

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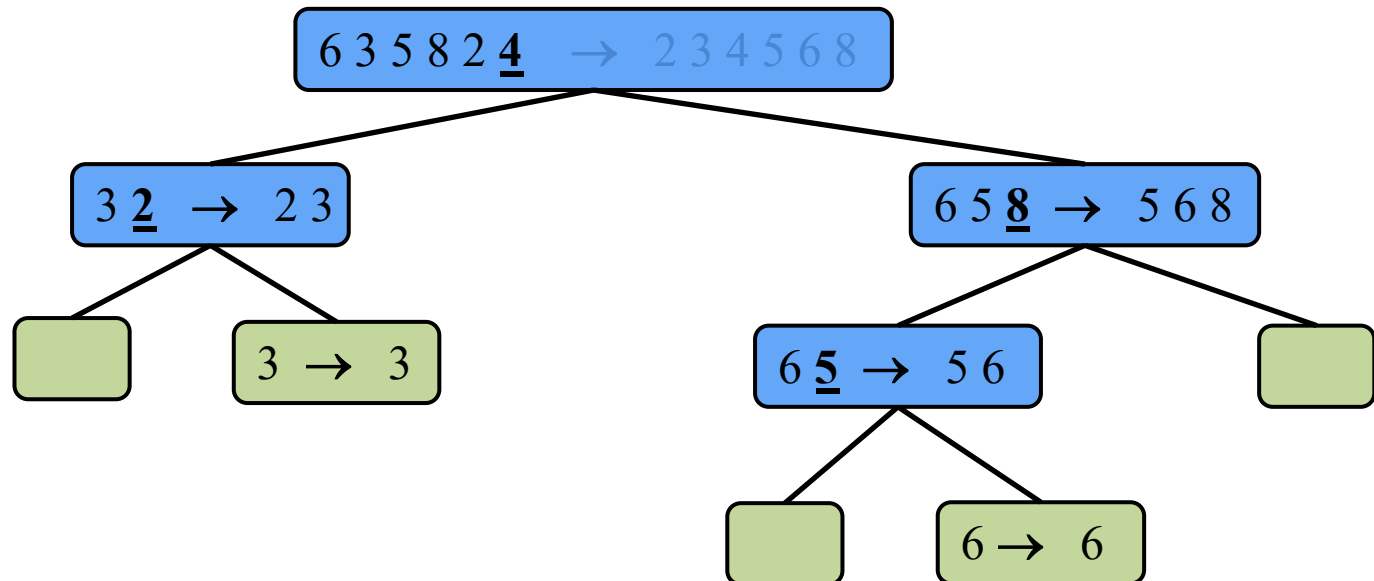
Quick Sort Execution

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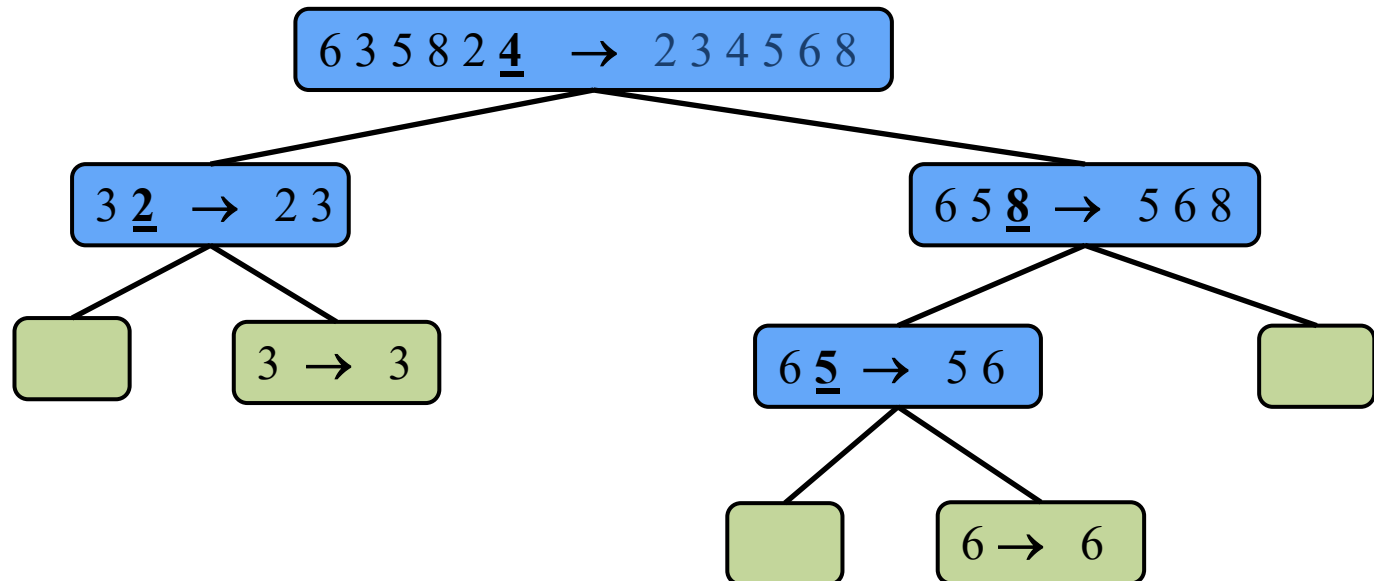
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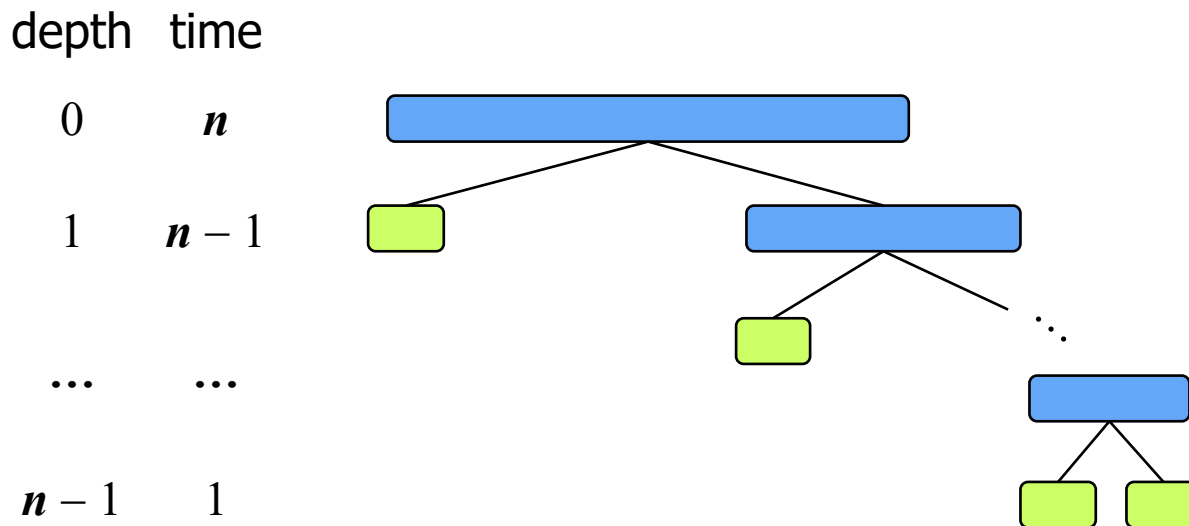


Worst-case Running Time

Occurs when the pivot is the unique minimum or maximum element

- One of L and G has size $n - 1$ and the other has size 0
- The running time is proportional to the sum: $n + (n - 1) + \dots + 2 + 1$
- If we use the strategy of selecting the **last element** as the pivot, this happens when the list is already sorted!

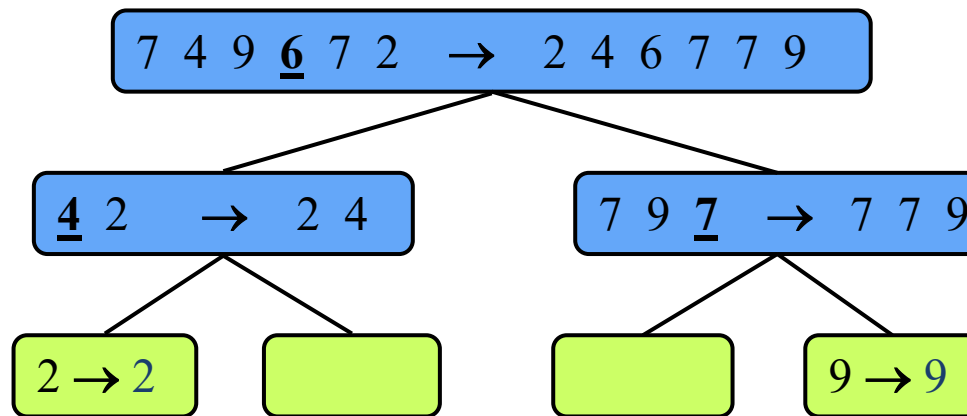
Thus, the worst-case running time of quick-sort is $O(n^2)$



Randomized Quick Sort

Pivot selection strategy: choose a **random** element as the pivot

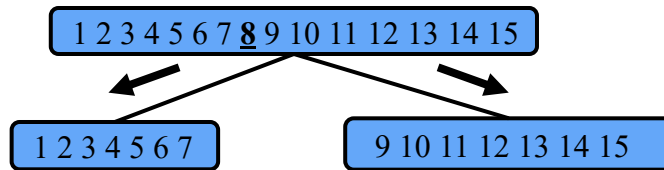
- Still has worst-case running time $O(n^2)$
 - Due to random selection, this case is highly unlikely
- Expected running time is $O(n \log n)$



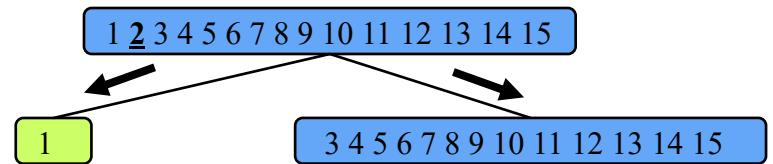
Expected Running Time

Consider a recursive call of quick-sort on a sequence of size s

- **Good call:** the sizes of L and G are each less than $3s/4$
- **Bad call:** one of L and G has size greater than $3s/4$



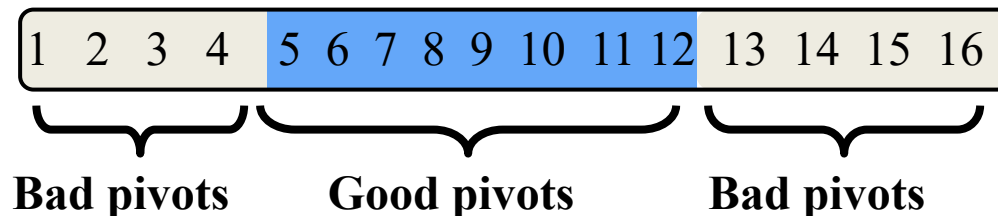
Good call



Bad call

A call is **good** with probability $1/2$

- $1/2$ of the possible pivots cause good calls:



Expected Running Time (continued)

Probabilistic Fact: The expected number of coin tosses required in order to get k heads is $2k$.

For a node of depth i , we expect

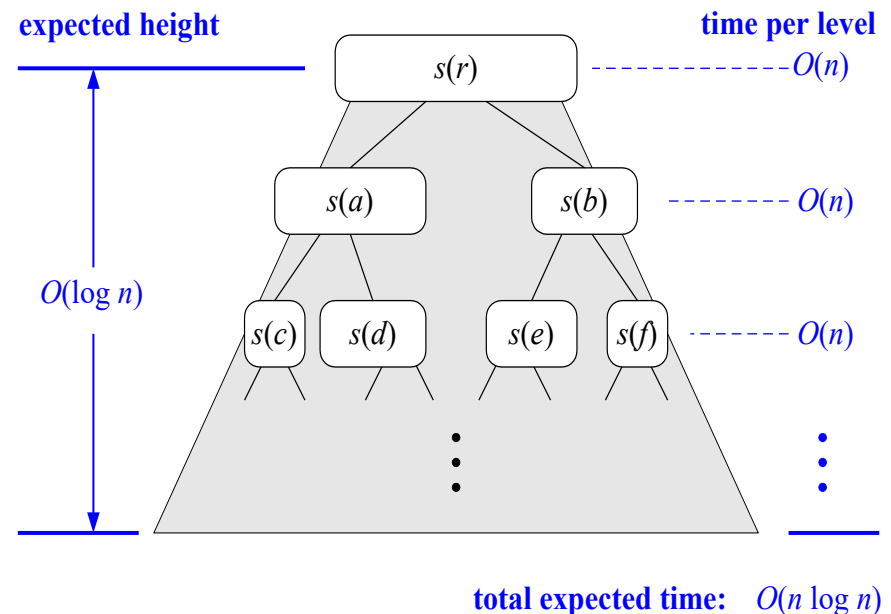
- $i/2$ ancestors are good calls
- size of the input sequence for the current call is at most $(3/4)^{i/2}n$

For a node of depth $2\log_{4/3}n$

- the expected input size is one
- the expected height of the quick-sort tree is $O(\log n)$

The amount of work done at the nodes of the same depth is $O(n)$

Thus, the **expected running time** of quick-sort is $O(n \log n)$



In-Place Quick-Sort

During the partition step, use replace operations to rearrange elements of the input sequences such that:

- elements less than pivot have rank $< h$
- elements equal to pivot have rank between $[h, k]$
- elements greater than pivot have rank $> k$

Algorithm *inPlaceQuickSort*(S, l, r)

Input sequence S , ranks l and r

Output sequence S with the
elements of rank between l and r
rearranged in increasing order

if $l \geq r$

return

$i \leftarrow$ a random integer between l and r

$x \leftarrow S.\text{elemAtRank}(i)$

$(h, k) \leftarrow \text{inPlacePartition}(x)$

inPlaceQuickSort($S, l, h - 1$)

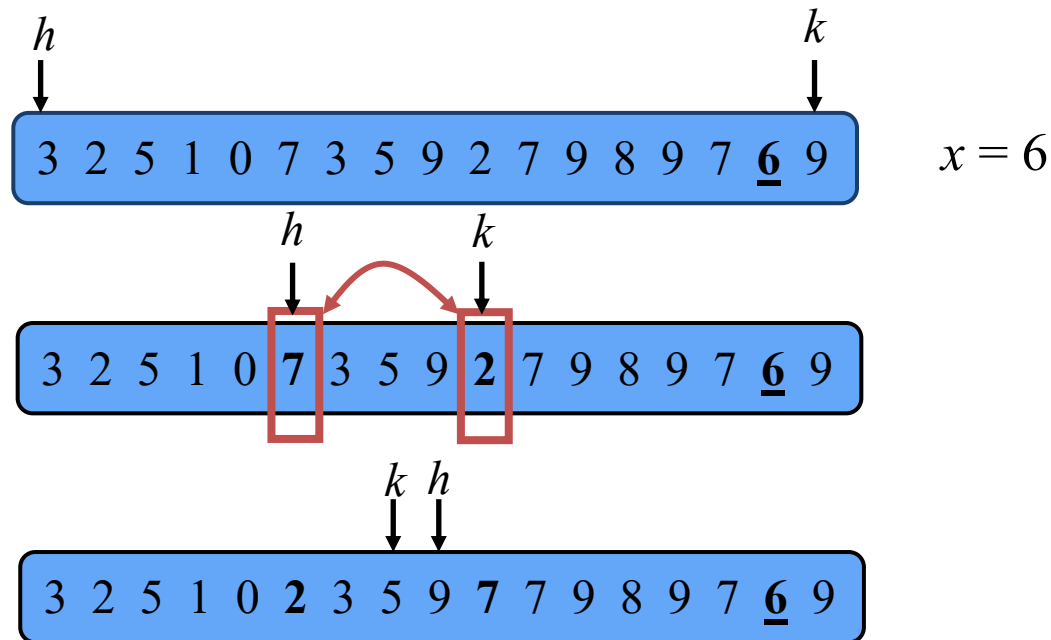
inPlaceQuickSort($S, k + 1, r$)

In-Place Partition

Performs a partitioning using two indices to split S into L and $E \cup G$ (a similar method can split $E \cup G$ into E and G).

Repeat until h and k cross:

- Scan h to the right until it finds an element $\geq x$
- Scan k to the left until it finds an element $< x$
- Swap elements at indices h and k



Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	<ul style="list-style-type: none"> ◆ in-place, not stable ◆ slow (good for small inputs)
insertion-sort	$O(n^2)$	<ul style="list-style-type: none"> ◆ in-place, stable ◆ slow (good for small inputs)
quick-sort	$O(n \log n)$ expected	<ul style="list-style-type: none"> ◆ in-place, not stable ◆ randomized ◆ fastest (good for large inputs)
heap-sort	$O(n \log n)$	<ul style="list-style-type: none"> ◆ in-place, not stable ◆ fast (good for large inputs)
merge-sort	$O(n \log n)$	<ul style="list-style-type: none"> ◆ not in-place, stable ◆ sequential data access ◆ fast (good for huge inputs)

Other: Nuts and Bolts



You are given a collection of n bolts of different widths, and n corresponding nuts.

- You can test whether a given nut and bolt fit together, from which you learn whether the nut is too large, too small, or an exact match for the bolt.
- The differences in size between pairs of nuts or bolts are too small to see by eye, so you cannot compare the sizes of two nuts or two bolts directly.
- You are to match each bolt to each nut.

Give an efficient algorithm to solve the nuts and bolts problem.