INTRO TO DATA SCIENCE LECTURE 10: SUPPORT VECTOR MACHINES

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LAST TIME:

- DECISION TREES
- BUILDING DECISION TREES
- OBJECTIVE SPLITTING FUNCTIONS
- PREVENTING OVERFITTING IN DECISION TREES

QUESTIONS?

I. SUPPORT VECTOR MACHINES
II. SOFT-MARGIN SVM
III. NONLINEAR SVM
HANDS-ON: SVM

I. SUPPORT VECTOR MACHINES

SUPPORT VECTOR MACHINES

Q: What is a support vector machine?

A: A binary linear classifier whose decision boundary is explicitly constructed to minimize generalization error.

recall:

binary classifier — solves two-class problem linear classifier — creates linear decision boundary (in 2d)

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Q: How is the decision boundary derived?

A: Using **geometric reasoning** (as opposed to the algebraic reasoning we've used to derive other classifiers).

The generalization error is equated with the geometric concept of **margin**, which is the region along the decision boundary that is free of data points.

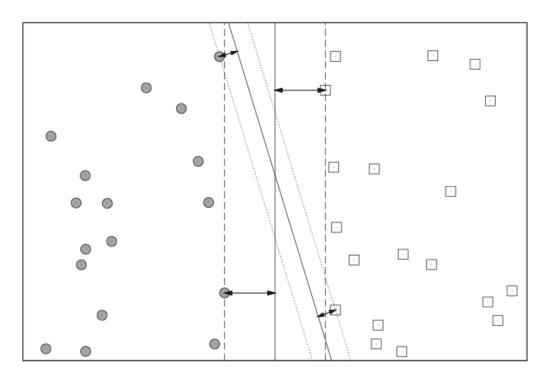


FIGURE 18-4. Two decision boundaries and their margins. Note that the vertical decision boundary has a wider margin than the other one. The arrows indicate the distance between the respective support vectors and the decision boundary.

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Q: How is the decision boundary derived?

A: Using **geometric reasoning** (as opposed to the algebraic reasoning we've used to derive other classifiers).

The goal of an SVM is to create the linear decision boundary with the largest margin. This is commonly called the maximum margin hyperplane.

Q: How is the decision boundary (**mmh**) derived?

A: By the discriminant function,

$$f(\mathbf{x}) = \mathbf{w}^\mathsf{T} \mathbf{x} + b.$$

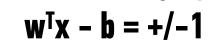
such that w is the weight vector and b is the bias.

The sign of f(x) determines the (binary) class label of a record x.

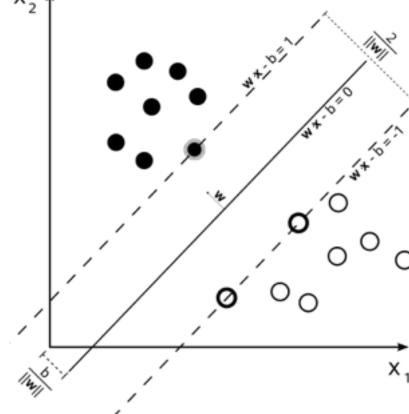
 Any hyperplane can be written as the set of points where $\mathbf{w}^{\mathsf{T}}\mathbf{x} - \mathbf{b} = \mathbf{0}$

How is the decision boundary (mmh) derived?

- w sets the plane's orientation (it's perpendicular to the plane)
- b sets the offset from the origin
- Set the margin planes for each class such that



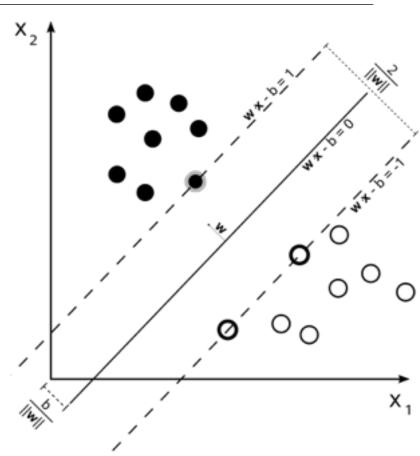
+1 for positive class, -1 for negative class



- Thus, our goal of maximizing the margin width amounts to maximizing **2/||w||**

How is the decision boundary (mmh) derived?

- To do this, we must minimize | | w | |
- Easier to minimize ||w||²/2
- We do this subject to the constraint: $y_i^*(\mathbf{w}^T\mathbf{x}_i - \mathbf{b}) \ge 1$
- This is a Quadratic Programming (QP)
 optimization problem, yielding w and b



- This is a Quadratic Programming (QP) optimization problem, yielding w and b
- Solving this QP problem yields a solution of the form: $w = \sum \alpha_i y_i X_i$

How is the decision boundary (mmh) derived?

- Most of these alpha are 0
- Only the "support vectors" will be nonzero – Thus only they contribute!

II. SOFT-MARGIN SVM

- So far we've been dealing with what's called a hard margin SVM - what does this mean?
 - We assume the data is perfectly separable by our hyperplane
 - No classification instances will fall within the margin
- As we've seen, probably not realistic (especially in linear case)
- So how do we allow for some error/noise in our model?

Q: How do we handle potentially inseparable data?

A: By training a **soft margin SVM** rather than a hard margin

soft margin — basically allows for a fuzzy boundary, where some proportion of elements may be misclassified in order to maintain a simpler boundary

Remember, simpler boundaries are probably more likely to generalize.

Q: How do we train a soft margin SVM?

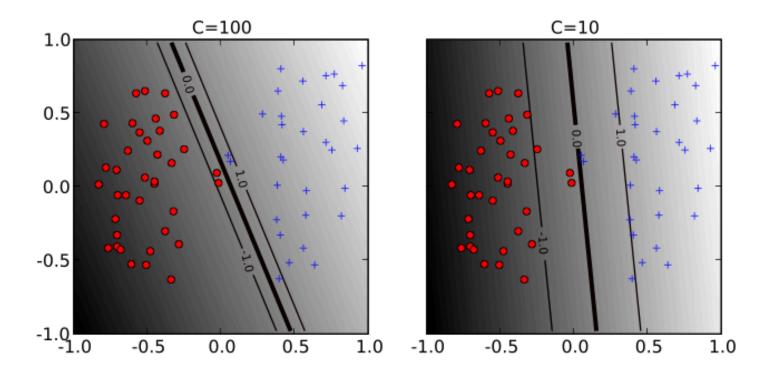
A: By making use of **slack variables** that allow a proportion of instances to be misclassified

Slack variables ξ_i generalize the optimization problem to permit some misclassified training records (which come at a **cost C**).

The resulting soft margin QP problem is given by:

minimize
$$\frac{1}{2}||\mathbf{w}||^2 + C\sum_{i=1}^n \xi_i$$

subject to: $y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b) \ge 1 - \xi_i, \quad \xi_i \ge 0.$



III. NONLINEAR SVM

Recall that our soft-margin SVM optimization function can be written as

follows:
$$\min_{\mathbf{w},b} \frac{1}{2} ||\mathbf{w}||^2 + C \sum_{i=1}^n \xi_i$$

subject to:
$$y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b) \ge 1 - \xi_i, \quad \xi_i \ge 0.$$

This can be rewritten in the following form:

maximize
$$\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} y_i y_j \alpha_i \alpha_j \mathbf{x}_i^\mathsf{T} \mathbf{x}_j$$
subject to:
$$\sum_{i=1}^{n} y_i \alpha_i = 0, \quad 0 \le \alpha_i \le C.$$

NOTE

This is called the *dual* formulation of the optimization problem.

(reached via Lagrange multipliers)

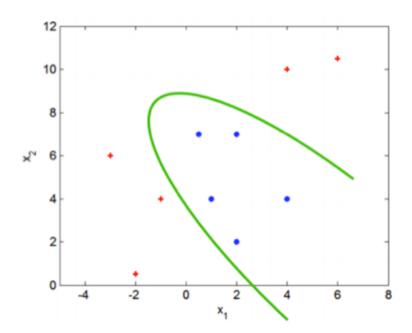
Notice that this expression depends only on inner products $x_i^T x_j$

The inner product (dot product) is an operation that takes two vectors and returns a real number.

The fact that we we can rewrite the optimization problem in terms of the inner product means that we don't actually have to do any calculations in the feature space *K*, just dot products.

In particular, we can easily change K to be some other space K'.

Suppose we need a more complex classifier than a linear decision boundary allows.

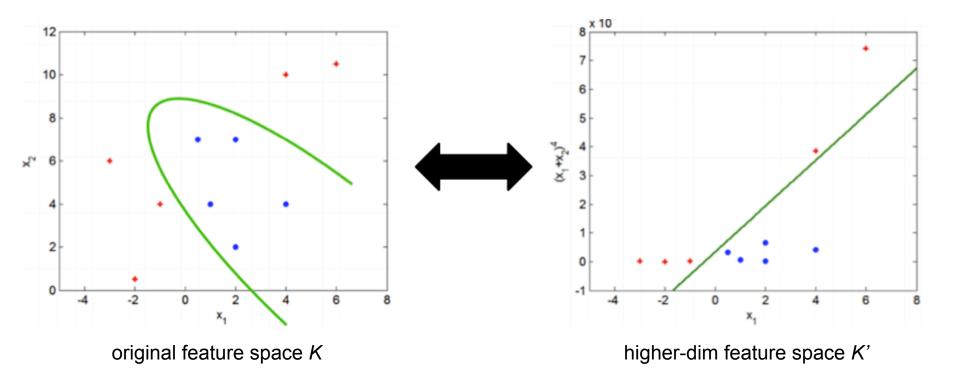


NONLINEAR SVM

Suppose we need a more complex classifier than a linear decision boundary allows.

One possibility is to add nonlinear combinations of features to the data, and then to create a linear decision boundary in the enhanced (higher-dimensional) feature space.

This **linear** decision boundary will be mapped to a **nonlinear** decision boundary in the original feature space.



The logic of this approach is sound, but there are a few problems with this version.

In particular, this will not scale well, since it requires many highdimensional calculations.

It will likely lead to more complexity (both modeling complexity and computational complexity) than we want.

Let's hang on to the logic of the previous example, namely:

- remap the feature vectors x_i into a higher-dimensional space K'
- create a linear decision boundary in K'
- back out the nonlinear decision boundary in K from the result

But we want to save ourselves the trouble of doing a lot of additional high-dimensional calculations. How can we do this?

Recall that our optimization problem depends on the features only through the inner product x^Tx :

maximize
$$\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} y_i y_j \alpha_i \alpha_j \mathbf{x}_i^\mathsf{T} \mathbf{x}_j$$

subject to: $\sum_{i=1}^{n} y_i \alpha_i = 0, \quad 0 \le \alpha_i \le C.$

We can replace this inner product with a more general "**kernel function**" that has the same type of output as the inner product.

NONLINEAR SVM

The upshot is that we can use a kernel function to *implicitly* train our model in a higher-dimensional feature space, *without* incurring additional computational complexity!

As long as the kernel function satisfies certain conditions, our conclusions above regarding the mmh continue to hold.

NOTE

These conditions are contained in a result called *Mercer's* theorem.

some popular kernels:

linear kernel

....

polynomial kernel

Gaussian (RBF) kernel

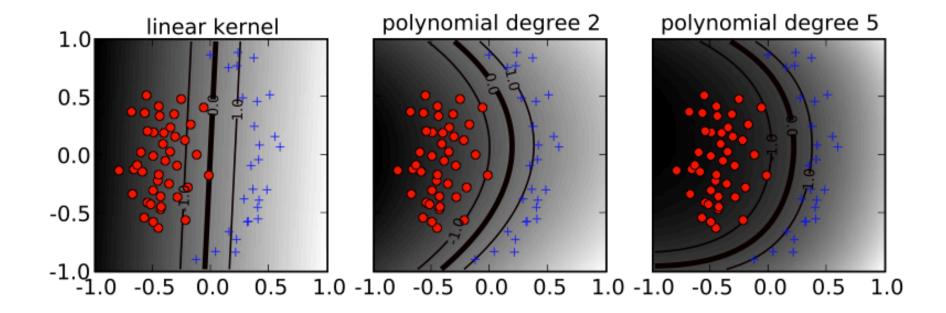
The **hyperparameters** d, **y** affect the flexibility

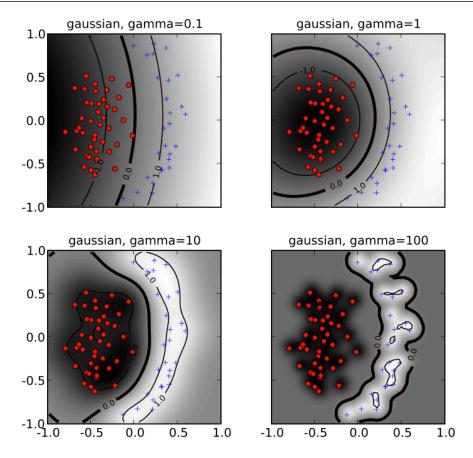
 $k(\mathbf{x}, \mathbf{x}') = \langle \mathbf{x}, \mathbf{x}' \rangle$

 $k(\mathbf{x}, \mathbf{x}') = (\mathbf{x}^\mathsf{T} \mathbf{x}' + 1)^d$

 $k(\mathbf{x}, \mathbf{x}') = \exp(-\gamma ||\mathbf{x} - \mathbf{x}'||^2)$

NONLINEAR SVM





SVM STRENGTHS/WEAKNESSES

SVMs (and kernel methods in general) are versatile, powerful, and popular techniques that can produce accurate results for a wide array of classification problems.

The main disadvantage of SVMs is the lack of intuition they produce. These models are truly black boxes!

HANDS-ON: SVM