# Hamza Anwar

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### Education

# The Ohio State University, College of Engineering

Jan 2018 – May 2023

Doctor of Philosophy in Electrical and Computer Engineering; GPA: 3.95/4.0

• Dynamic powertrain control and optimization at the Center for Automotive Research

# New York University, Tandon School of Engineering

Sep 2015 – Sep 2017

Master of Science in Electrical Engineering; Ernst Weber Fellow; GPA (w/o research credits): 3.62/4.0

- Research and teaching in IoT, cyber-physical systems and networks at NYU Center for Cybersecurity
- Selected Coursework: Advanced Machine Learning, Optimization in Cyber-Physical Networks, Game Theory.

#### Lahore University of Management Sciences

Aug 2010 – Jun 2014

Bachelor of Science in Electrical Engineering with Minor in Computer Science; Dean's Honor List; GPA: 3.61/4.0.

#### **Patents**

**H. Anwar** and Q. Ahmed. Comprehensive Energy Footprint Benchmarking Algorithm for Electrified Powertrains. PCT/US2023/024137. (Pending).

# **Experience**

#### Graduate Research Associate, Center of Automotive Research, OSU, USA

Aug 2018 – May 2023

- Developed a numerical optimization control technique for energy management in commercial electrified fleets. Graduate Teaching Fellow, Dept. of Electrical and Computer Engineering (ECE), OSU, USA Sep 2021 – Dec 2021
- Independently taught a section of ECE 2020: Intro. To Analog Systems and Circuits

# Electronic Systems Product Engineer-Intern, Cummins Inc., IN, USA

Jun 2021 – Aug 2021

- Gap analysis in multivehicle route optimization tools for pickup-delivery and regional-haul trucks (Corp R&T).
- Powertrain Electrification Systems and Controls Engineer–Intern, Cummins Inc., IN, USA Jun 2020 Aug 2020
- Dynamic optimization framework development in powertrain electrification systems and controls (Corp R&T).
   Research Assistant, Center for Cybersecurity, NYU, USA
   Sep 2015 Sep 2017
- Designed robust minimax controller and filter for multiscale cyber-physical systems in Internet of Things (IoT).

  \*Research Assistant\*, Cyber-Physical-Networks Lab, LUMS, Pakistan

  \*Aug 2014 May 2015\*
- A novel framework that inspects watercourses for 3D profiling of silt accumulations using Gaussian Processes
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  Visiting Researcher, Robotics Research Lab, TU Kaiserslautern, Germany

  Summer 2013 & 2014
- Analyzed silted canal terrains for outdoor volume estimation of accumulated soil in canals and bucket excavators.

#### Selected Publications

- [J-1] H. Anwar, A. Vishwanath, Q. Ahmed, and A. Chunodkar. Comprehensive Energy Footprint Benchmarking of Commercial Electrified Powertrains. *Applied Energy* 345 (2023): 121299.
- [J-2] M. Q. Fahim, M. Villani, H. Anwar, Q. Ahmed, and K. Ramakrishnan. Co-optimization of Design and Control of Energy Efficient Hybrid Electric Vehicles using Coordination Schemes. ASME J. Dyn. Sys., Meas., Control, 2023
- [J-3] H. Anwar, A. Vishwanath, A. Chunodkar, and Q. Ahmed. Comprehensive Energy Footprint Benchmarking Algorithm for Electrified Powertrains. *IEEE Transactions on Control System Technology*, 2021 [under review]
- **[C-1]** J. Moon, **H. Anwar**, M. Villani, M. Q. Fahim, P. Jain, Q. Ahmed, and K. Ramakrishnan. Energy-Efficient Optimal Routing of Electrified Powertrain Fleet. *IEEE Conf. on Control Tech. and Applications*, 2023
- **[C-2]** M. Arasu, **H. Anwar**, Q. Ahmed, and G. Rizzoni. Energy Optimal Routing of a Delivery Vehicle Fleet with Diverse Powertrains. *ASME 2019 Dynamic Systems and Control Conference*. Park City, Utah, 2019.
- **[C-3] H. Anwar**, M. Arasu, and Q. Ahmed. Ensuring Fuel Economy Performance of Commercial Vehicle Fleets using Blockchain Technology. *SAE Technical Paper 2019-01-1078*. Detroit, Michigan, 2019.
- [C-4] H. Anwar, A. Muhammad, and K. Berns. A Framework for Aerial Inspection of Siltation in Waterways. In IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Hamburg, Germany, October 2015.

### **Projects**

# Multivehicle Commercial Fleet Design and Operations Optimization

Jan 2021 – present

• Framework development for vehicle routing problems that seeks to minimize total cost of ownership for batteryelectric, plug-in hybrid electric and conventional powertrains, using realistic urban geospatial and traffic data

#### Mixed-Integer Optimal Powertrain Control using Pseudo-Spectral Collocation

Mar 2019 – Dec 2020

Developed a comprehensive benchmarking optimization framework to solve large-sized mixed-integer optimal
control problems in electrified powertrains, applying to various powertrain architectures and scenarios

#### ADMM-based Networked Stochastic Variational Inference

Sep 2015 – Aug 2017

• Proposed an algorithm for network of deep learning agents performing state-of-art stochastic variational inference for big data applications: topic modeling and classification over large corpora (e.g. *Wikipedia* articles).

#### Visual Servoing of Robotic Mine-Detector Arm, BS Thesis

Sep 2013 – May 2014

• Involves uneven terrain profiling, 3D motion planning and maneuvering of a real 5 DoF robotic arm. Learned vision-based 3D perception skills, programming for Arduino board, and real-time feedback controller design.

# Honors & Awards

•	Nominated for <b>Presidential Fellowship</b> Competition, OSU	2022 – 2023
•	ASME DSCD Rising Stars Award; gave invited talk at IFAC Modeling, Estimation & Control Confer	rence 2022
•	Recipient Ernst Weber Fellowship, ECE Dept. NYU	2015 – 2017
•	Graduated on <b>Dean's Honor List</b> (for maintaining a CGPA above 3.6)	2012 - 2014
•	Semi Finalist in Dell Social Innovation Challenge	2013
•	National Finalist in Microsoft Imagine Cup	2012
•	Gold Medalist at 1st GIKI All Pakistan Mathematics Olympiad	2011

# Leadership

Mentor for 6+ Masters' and PhD students at Center for Automotive Research, OSU in succeeding to keep up with the demands of industry-sponsored collaborative projects, with efficient delivery of output, project management, teamwork, conducive learning, and enhanced presentation skills

2019 – 2023

Founder and President of Graduate Muslim Club, a student organization at OSU

2022 - 2023

Lab Instructor (x3): Supervised students, designed experiments, and delivered lectures to perform lab tasks, Feedback Control Systems (NYU, 2017); Circuits II (NYU, 2016); Mobile Robotics (LUMS, 2015)

Teaching Assistant (x4): Supervised projects, conducted tutorial sessions, designed, and graded coursework,

Numerical Methods (OSU, 2021); Digital Control Systems (LUMS, 2014); Feedback Control Systems (LUMS, 2014); Computational Problem Solving (LUMS, 2012)

# Skills

Programming: MATLAB & Simulink, Python, C++

**Software experience:** CasADi, YOP, Torch (Machine Learning), VowPal Wabbit, Robot Operating System (ROS), Gazebo, Point Cloud Library (PCL), OpenCV, Linux, ModelSim, Proteus, CoCreate, NI LabView

Hardware proficiency: 2D LiDAR sensors (SICK, Hokuyo), Parrot AR-Drone, iRobot Create 2, Arduino boards, Verilog, stereo cameras, Microsoft Kinect, Mini6410, Xilinx Virtex-II Pro.