

Ters Laplace Dönüşümü

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ters laplace
dönüşümü

$$\begin{array}{ccc} f(t) & \xrightarrow{\mathcal{L}} & F(s) \\ & \xleftarrow{\mathcal{L}^{-1}} & \end{array}$$

TERS LAPLACE DÖNÜŞÜMÜ

INVERSE LAPLACE TRANSFORM

Inverse Laplace Transform

Definition 4. Given a function $F(s)$, if there is a function $f(t)$ that is continuous on $[0, \infty)$ and satisfies

$$(2) \quad \mathcal{L}\{f\} = F,$$

then we say that $f(t)$ is the inverse Laplace transform of $F(s)$ and employ the notation $f = \mathcal{L}^{-1}\{F\}$.

In case every function $f(t)$ satisfying (2) is discontinuous (and hence not a solution of a differential equation), one could choose any one of them to be the inverse transform; the distinction among them has no physical significance. [Indeed, two *piecewise* continuous functions satisfying (2) can only differ at their points of discontinuity.]

Naturally the Laplace transform tables will be a great help in determining the inverse Laplace transform of a given function $F(s)$.

Example 1 Determine $\mathcal{L}^{-1}\{F\}$, where

$$(a) F(s) = \frac{2}{s^3} .$$

$$(b) F(s) = \frac{3}{s^2 + 9} .$$

$$(c) F(s) = \frac{s - 1}{s^2 - 2s + 5} .$$

$$\textcircled{a} \quad \mathcal{L}^{-1}\left\{\frac{2}{s^3}\right\} = t^2$$

$$\textcircled{b} \quad \mathcal{L}^{-1}\left\{\frac{3}{s^2+9}\right\} = \sin 3t$$

$$\textcircled{c} \quad \mathcal{L}^{-1}\left\{\frac{s-1}{s^2-2s+5}\right\}$$

$$\mathcal{L}\{t\} = \frac{1}{s}$$

$$\mathcal{L}\{t^2\} = \frac{1}{s^2}$$

$$\mathcal{L}\{t^3\} = \frac{2}{s^3}$$

$$\mathcal{L}\{t^4\} = \frac{6}{s^4}$$

:

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}$$

$$= \mathcal{L}^{-1}\left\{\frac{s-1}{(s-1)^2+4}\right\}$$

$$\mathcal{L}^{-1}\left\{\frac{s}{s^2+4}\right\} = \cos 2t$$

$$= \mathcal{L}^{-1}\left\{\frac{s-1}{(s-1)^2+4}\right\} = e^t \cos 2t$$

In practice, we do not always encounter a transform $F(s)$ that exactly corresponds to an entry in the second column of the Laplace transform table. To handle more complicated functions $F(s)$, we use properties of \mathcal{L}^{-1} , just as we used properties of \mathcal{L} . One such tool is the linearity of the inverse Laplace transform, a property that is inherited from the linearity of the operator \mathcal{L} .

Linearity of the Inverse Transform

Theorem 7. Assume that $\mathcal{L}^{-1}\{F\}$, $\mathcal{L}^{-1}\{F_1\}$, and $\mathcal{L}^{-1}\{F_2\}$ exist and are continuous on $[0, \infty)$ and let c be any constant. Then

$$\begin{aligned} \text{(3)} \quad & \mathcal{L}^{-1}\{F_1 + F_2\} = \mathcal{L}^{-1}\{F_1\} + \mathcal{L}^{-1}\{F_2\}, \quad \checkmark \\ \text{(4)} \quad & \mathcal{L}^{-1}\{cF\} = c\mathcal{L}^{-1}\{F\}. \quad \checkmark \end{aligned} \quad \left. \right\} \underline{\text{Linear}}$$

Example 2 Determine $\mathcal{L}^{-1}\left\{\frac{5}{s-6} - \frac{6s}{s^2+9} + \frac{3}{2s^2+8s+10}\right\}$.

$$\begin{aligned}
 &= \mathcal{L}^{-1}\left\{\frac{5}{s-6}\right\} - \mathcal{L}^{-1}\left\{\frac{6r}{s^2+9}\right\} + \mathcal{L}^{-1}\left\{\frac{3}{2s^2+8s+10}\right\} \\
 &= 5\mathcal{L}^{-1}\left\{\frac{1}{s-6}\right\} - 6\mathcal{L}^{-1}\left\{\frac{s}{s^2+9}\right\} + \frac{3}{2}\mathcal{L}^{-1}\left\{\frac{1}{s^2+4s+5}\right\} \\
 &\quad \downarrow \\
 &\mathcal{L}^{-1}\left\{\frac{1}{s-3}\right\} = 1 \qquad \qquad \qquad \underbrace{\frac{(s+2)^2+1}{e^{-2t}}}_{\text{Ansatz}} \\
 &\mathcal{L}^{-1}\left\{\frac{1}{s^2+9}\right\} = e^{6t} \\
 &= 5e^{6t} - 6\cos 3t + \frac{3}{2}e^{-2t} \sin t
 \end{aligned}$$

Ters Laplace Dönüşümünün Bazı Temel Özellikleri

Özellik 1: Linearlik ✓

$$L^{-1}\{C_1F_1(s) + C_2F_2(s)\} = C_1L^{-1}\{F_1(s)\} + C_2L^{-1}\{F_2(s)\}$$

Örnek

$$L^{-1}\left\{\frac{2}{s} - \frac{3}{s+5}\right\} = 2L^{-1}\left\{\frac{1}{s}\right\} - 3L^{-1}\left\{\frac{1}{s+5}\right\} = 2 - 3e^{-5t} \quad \text{✓}$$

Özellik 2: Öteleme

$$L^{-1}\{F(s-k)\} = e^{kt}L^{-1}\{F(s)\} \quad \text{✓}$$

Örnek

$$L^{-1}\left\{\frac{s+3}{(s+3)^2 - \omega^2}\right\} = e^{-3t}L^{-1}\left\{\frac{s}{s^2 - \omega^2}\right\} = e^{-3t} \cos(\omega t) \quad \text{✓}$$

$$\boxed{L\{y'\} = sY(s) - y(0)}$$

Özellik 3:

$$L^{-1}\{sF(s)\} = \frac{d}{dt}L^{-1}\{F(s)\} \quad \text{✓}$$

Örnek

$$L^{-1}\left\{\frac{s}{s^2+9}\right\} = L^{-1}\left\{s\left(\frac{1}{s^2+9}\right)\right\} = \frac{d}{dt}L^{-1}\left\{\frac{3}{s^2+9}\right\} = \frac{d}{dt}\left(\frac{\sin 3t}{3}\right) = \cos 3t \quad \text{✓}$$

$$\frac{1}{3} \sin 3t$$

$$\begin{aligned} L^{-1}\left\{\frac{s^2}{s^2+4}\right\} &= \\ &= L^{-1}\left\{s\left(\frac{s}{s^2+4}\right)\right\} = \left(\frac{d}{dt}\right)L^{-1}\left\{\frac{s}{s^2+4}\right\} \end{aligned}$$

$$= -2 \sin 2t \quad \text{✓}$$

Özellik 4:

$$L^{-1}\left\{\frac{F(s)}{s}\right\} = \int_0^t L^{-1}\{F(s)\} dt \quad \text{✓}$$

$$3(e^{2t} - e^0)$$

Örnek

$$L^{-1}\left\{\frac{6}{s(s-2)}\right\} = L^{-1}\left\{\frac{1}{s}\left(\frac{6}{(s-2)}\right)\right\} = \int_0^t L^{-1}\left\{\frac{6}{s-2}\right\} dt = 6 \int_0^t e^{2t} dt = 6 \frac{e^{2t}}{2} \Big|_0^t = 3e^{2t} - 3 \quad \text{✓}$$

$$(s - \alpha) = 0 \quad \Rightarrow \quad s = \alpha$$

Hikaye

(12) $\mathcal{L}\{te^{3t}\}$ $\rightarrow \mathcal{L}\{e^{3t} t\} = \frac{1}{(s-3)^2} \checkmark$

Türev olma

$$\mathcal{L}\{t e^{3t}\} = -\frac{d}{ds} \mathcal{L}\{e^{3t}\} = -\frac{d}{ds} \left(\frac{1}{s-3}\right)$$

$$= -\left(-\frac{1}{(s-3)^2}\right)$$

$$= \frac{1}{(s-3)^2} \checkmark$$

Özellik 5:

$$\boxed{\mathcal{L}^{-1}\left\{\frac{d^n F(s)}{ds^n}\right\} = (-t)^n \mathcal{L}^{-1}\{F(s)\}}$$

$$\left(\frac{1}{s}\right)' = -\frac{1}{s^2}$$

$$\left(-\frac{1}{s^2}\right)' = \frac{2}{s^3}$$

Örnek

$$\mathcal{L}^{-1}\left\{\frac{2}{s^3}\right\} = \mathcal{L}^{-1}\left\{\frac{d^2}{ds^2}\left(\frac{1}{s}\right)\right\} = (-t)^2 \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = t^2 \cdot 1 = t^2$$

$$\begin{matrix} & 1 \\ \cancel{*} & \cancel{2} \end{matrix}$$



Özellik 6:

$$\boxed{\mathcal{L}^{-1}\{e^{-t_0 s} F(s)\} = u(t - t_0) f(t - t_0)}$$

Bosnak funk.

Örnek

$$\mathcal{L}^{-1}\left\{\frac{2e^{-3s}}{s^3}\right\} = \underbrace{u(t-3)}_{\text{Bosnak funk.}} \mathcal{L}^{-1}\left\{\frac{2}{s^3}\right\} = u(t-3)(t^2) \Big|_{t \rightarrow (t-t_0)} = u(t-3)(t-3)^2$$

Özellik 7:

$$L^{-1}\{F(ks)\} = \frac{1}{k} f\left(\frac{t}{k}\right)$$

$\stackrel{=}{\Rightarrow}$

Örnek

$$L^{-1}\left\{\frac{5s}{25s^2 + 9}\right\} = L^{-1}\left\{\frac{(5s)}{(5s)^2 + 3^2}\right\} = \frac{1}{5} \cos 3 \frac{t}{5}$$

Example 3 Determine $\mathcal{L}^{-1}\left\{\frac{5}{(s+2)^4}\right\}$.

$$\mathcal{L}^{-1}\left\{\frac{5}{s^4}\right\} = 5 \mathcal{L}^{-1}\left\{\frac{1}{s^4}\right\} = \frac{5}{6} \mathcal{L}^{-1}\left\{\frac{6}{t^4}\right\}$$
$$= \frac{5}{6} t^3$$

$$\mathcal{L}^{-1}\left\{\frac{5}{(s+2)^4}\right\} \stackrel{\text{red}}{=} \frac{5}{6} e^{-2t} t^3 //$$

\downarrow
 $s = s+2$

Example 4 Determine $\mathcal{L}^{-1}\left\{\frac{3s+2}{s^2+2s+10}\right\}$. \mathcal{L}^{-1}\left\{\frac{P(s)}{Q(s)}\right\}

$$\frac{3s+2}{s^2+2s+10} = \frac{3s+2}{(s+1)^2+9}$$

$$\begin{aligned}
 &= \mathcal{L}^{-1}\left\{\frac{3s}{(s+1)^2+9}\right\} + \mathcal{L}^{-1}\left\{\frac{2}{(s+1)^2+9}\right\} \\
 &= 3 \mathcal{L}^{-1}\left\{\frac{s+1-1}{(s+1)^2+9}\right\} + 2 \mathcal{L}^{-1}\left\{\frac{1}{(s+1)^2+9}\right\} \\
 &= 3 \mathcal{L}^{-1}\left\{\frac{s+1}{(s+1)^2+9}\right\} - 3 \mathcal{L}^{-1}\left\{\frac{1}{(s+1)^2+9}\right\} + 2 \mathcal{L}^{-1}\left\{\frac{1}{(s+1)^2+9}\right\} \\
 &= 3 \mathcal{L}^{-1}\left\{\frac{s+1}{(s+1)^2+9}\right\} - \frac{1}{3} \mathcal{L}^{-1}\left\{\frac{3}{(s+1)^2+9}\right\} \\
 &= 3 e^t \cos 3t - \frac{1}{3} e^t \sin 3t //
 \end{aligned}$$

Thus, if we are faced with the problem of computing \mathcal{L}^{-1} of a rational function such as $F_1(s)$, we will first express it, as we did $F_2(s)$, as a sum of simple rational functions. This is accomplished by the **method of partial fractions**.

We briefly review this method. Recall from calculus that a rational function of the form $P(s)/Q(s)$, where $P(s)$ and $Q(s)$ are polynomials with the degree of P less than the degree of Q , has a partial fraction expansion whose form is based on the linear and quadratic factors of $Q(s)$. (We assume the coefficients of the polynomials to be real numbers.) There are three cases to consider:

1. Nonrepeated linear factors. ✓
2. Repeated linear factors. ✓
3. Quadratic factors. ✓

1. Nonrepeated Linear Factors

If $Q(s)$ can be factored into a product of distinct linear factors,

$$Q(s) = (s - r_1)(s - r_2) \cdots (s - r_n),$$

where the r_i 's are all distinct real numbers, then the partial fraction expansion has the form

$$\frac{P(s)}{Q(s)} = \frac{A_1}{s - r_1} + \frac{A_2}{s - r_2} + \cdots + \frac{A_n}{s - r_n},$$

where the A_i 's are real numbers. There are various ways of determining the constants A_1, \dots, A_n . In the next example, we demonstrate two such methods.

Example 5 Determine $\mathcal{L}^{-1}\{F\}$, where

$$F(s) = \frac{7s - 1}{(s + 1)(s + 2)(s - 3)} .$$

$$\mathcal{L}^{-1} \left\{ \frac{7s - 1}{(s+1)(s+2)(s-3)} \right\} = ?$$

$$\frac{7s - 1}{(s+1)(s+2)(s-3)} = \frac{A}{s+1} + \frac{B}{s+2} + \frac{C}{s-3}$$

$(s+2)(s-3)$ $(s+1)(s-3)$ $(s+1)(s+2)$

$$7s - 1 = A(s+2)(s-3) + B(s+1)(s-3) + C(s+1)(s+2)$$

$$s = -1 \Rightarrow -8 = A \cdot 1 \cdot (-4) \Rightarrow A = 2$$

$$s = -2 \Rightarrow -15 = B \cdot (-1) \cdot (-5) \Rightarrow B = -3$$

$$s = 3 \Rightarrow 20 = C \cdot (4) \cdot (5) \Rightarrow C = 1$$

$$\begin{aligned} \mathcal{L}^{-1} \left\{ \frac{7s - 1}{(s+1)(s+2)(s-3)} \right\} &= 2\mathcal{L}^{-1} \left\{ \frac{1}{s+1} \right\} - 3\mathcal{L}^{-1} \left\{ \frac{1}{s+2} \right\} + \mathcal{L}^{-1} \left\{ \frac{1}{s-3} \right\} \\ &= 2e^{-t} - 3e^{-2t} + e^{3t} \end{aligned}$$

2. Repeated Linear Factors

(Höher Koll. 1se)

Let $s - r$ be a factor of $Q(s)$ and suppose $(s - r)^m$ is the highest power of $s - r$ that divides $Q(s)$. Then the portion of the partial fraction expansion of $P(s)/Q(s)$ that corresponds to the term $(s - r)^m$ is

$$\frac{A_1}{s - r} + \frac{A_2}{(s - r)^2} + \cdots + \frac{A_m}{(s - r)^m},$$

where the A_i 's are real numbers.

Example 6 Determine $\mathcal{L}^{-1}\left\{\frac{s^2 + 9s + 2}{(s - 1)^2(s + 3)}\right\}$.

$$\frac{s^2 + 9s + 2}{(s-1)^2 \cdot (s+3)} = \frac{A}{s-1} + \frac{B}{(s-1)^2} + \frac{C}{s+3}$$

\downarrow

$(s-1)(s+1)$ $(s+3)(s-1)$ $(s+3)$ $(s-1)^2$

$$s^2 + 9s + 2 = A(s+3)(s-1) + B(s+3) + C(s-1)^2$$

$$s=1 \Rightarrow 12 = B \cdot 4 \Rightarrow B = 3$$

$$s=-3 \Rightarrow -16 = C \cdot 16 \Rightarrow C = -1$$

$$s=0 \Rightarrow 2 = -3A + 3B + C \Rightarrow A = 2$$

$$\mathcal{L}^{-1}\left\{\frac{s^2 + 9s + 2}{(s-1)^2 \cdot (s+3)}\right\} = 2\mathcal{L}^{-1}\left\{\frac{1}{s-1}\right\} + 3\mathcal{L}^{-1}\left\{\frac{1}{(s-1)^2}\right\} - \mathcal{L}^{-1}\left\{\frac{1}{s+3}\right\}$$

$$= \underline{\underline{2e^t + 3te^t}} - e^{-3t}$$

3. Quadratic Factors

Let $(s - \alpha)^2 + \beta^2$ be a quadratic factor of $Q(s)$ that cannot be reduced to linear factors with real coefficients. Suppose m is the highest power of $(s - \alpha)^2 + \beta^2$ that divides $Q(s)$. Then the portion of the partial fraction expansion that corresponds to $(s - \alpha)^2 + \beta^2$ is

$$\frac{C_1s + D_1}{(s - \alpha)^2 + \beta^2} + \frac{C_2s + D_2}{[(s - \alpha)^2 + \beta^2]^2} + \dots + \frac{C_ms + D_m}{[(s - \alpha)^2 + \beta^2]^m}.$$

As we saw in Example 4, it is more convenient to express $C_i s + D_i$ in the form $A_i(s - \alpha) + \beta B_i$ when we look up the Laplace transforms. So let's agree to write this portion of the partial fraction expansion in the equivalent form

$$\frac{A_1(s - \alpha) + \beta B_1}{(s - \alpha)^2 + \beta^2} + \frac{A_2(s - \alpha) + \beta B_2}{[(s - \alpha)^2 + \beta^2]^2} + \dots + \frac{A_m(s - \alpha) + \beta B_m}{[(s - \alpha)^2 + \beta^2]^m}.$$

Example 7 Determine $\mathcal{L}^{-1}\left\{\frac{2s^2 + 10s}{(s^2 - 2s + 5)(s + 1)}\right\}$.

$$\Delta = b^2 - 4ac \\ = 4 - 4 \cdot 1 \cdot 5 = -16 < 0$$

$$\frac{2s^2 + 10s}{(s^2 - 2s + 5)(s + 1)} = \frac{As + B}{s^2 - 2s + 5} + \frac{C}{s + 1}$$

$$2s^2 + 10s = (As + B)(s + 1) + C(s^2 - 2s + 5)$$

$$2s^2 + 10s = As^2 + As + Bs + B + Cs^2 - 2Cs + 5C$$

$$\begin{aligned} A + C &= 2 \\ A + B - 2C &= 10 \\ B + 5C &= 0 \end{aligned}$$

$$\begin{aligned} &\quad \left. \begin{aligned} &B - 3C = 8 \\ &B + 5C = 0 \end{aligned} \right\} \\ &\quad \begin{aligned} &8C = -8 \\ &C = -1 \end{aligned} \end{aligned}$$

$$B = 5$$

$$A = 3$$

$$\begin{aligned} \mathcal{L}^{-1}\left\{\frac{2s^2 + 10s}{(s^2 - 2s + 5)(s + 1)}\right\} &= \mathcal{L}^{-1}\left\{\frac{3s+5}{s^2 - 2s + 5}\right\} + \mathcal{L}^{-1}\left\{\frac{-1}{s+1}\right\} \rightarrow -e^{-t} \\ &\quad \downarrow \\ &\quad \frac{(s-1)^2 + 4}{(s-1)^2 + 4} \\ &= 3 \mathcal{L}^{-1}\left\{\frac{s-1+1}{(s-1)^2 + 4}\right\} + 5 \mathcal{L}^{-1}\left\{\frac{1}{(s-1)^2 + 4}\right\} \\ &= 3 \mathcal{L}^{-1}\left\{\frac{s-1}{(s-1)^2 + 4}\right\} + \frac{8}{2} \mathcal{L}^{-1}\left\{\frac{2}{(s-1)^2 + 4}\right\} \\ &= 3e^t \cos 2t + 4e^t \sin 2t = e^t (3 \cos 2t + 4 \sin 2t) \end{aligned}$$

$$\mathcal{L}^{-1} \left\{ \frac{2s^2 + 10s}{(s^2 - 2s + 5)(s+1)} \right\} = e^{t} (\underline{3 \cos 2t + 4 \sin 2t}) - e^{-t}$$

$$\mathcal{L}^{-1}\{F(s)\} = f(t)$$

$$\mathcal{L}^{-1}\{G(s)\} = g(t)$$

KONVOLÜSYON TEOREMI

Diferansiyel denklemleri Laplace yöntemiyle çözerken çoğu zaman doğrudan ters Laplace'ı olmayan, ancak s 'ye bağlı ve ters Laplace'ı bilinen iki fonksiyonun çarpımı şeklinde ifade edilebilen $Y(s)$ fonksiyonlarıyla karşılaşırız. Diğer bir ifadeyle $\boxed{Y(s) = F(s)G(s)}$ şeklinde ifade edilebilmekte ve buradaki $F(s)$ ve $G(s)$ fonksiyonlarının ters Laplace dönüşümleri olan $f(t)$ ve $g(t)$ bilinmektedir. Bu tür durumlarda $Y(s)$ fonksiyonunun ters Laplace'ı **konvolüsyon teoremi** ile belirlenebilir. Bu teorem;

$$\mathcal{L}^{-1}\{F(s)G(s)\} = \int_0^t f(t-\tau)g(\tau)d\tau = \int_0^t f(t)g(t-\tau)d\tau$$

olarak ifade edilir (τ geçici değişkendir). Bu integrale $f(t)$ ve $g(t)$ fonksiyonlarının **konvolüsyonu** adı verilir ve bazen $f(t) * g(t)$ şeklinde gösterilir. Alınan integralin üst limiti t olduğundan, sonuçta t 'ye bağlı bir ifade olacaktır.

ÖRNEK

Konvolüsyon teoremini kullanarak aşağıdaki ifadenin ters Laplace dönüşümünü bulunuz.

$$Y(s) = \frac{s}{(s+1)(s^2+1)}$$

$$\mathcal{L}^{-1}\{Y(s)\} = ? \quad , \quad y(t) = ?$$

$$F(s) = \frac{1}{s+1}, \quad G(s) = \frac{s}{s^2+1}$$

$$\mathcal{L}^{-1}\{F(s)\} = e^{-t} = f(t)$$

$$\mathcal{L}^{-1}\{G(s)\} = \cos t = g(t)$$

$$\begin{aligned} \mathcal{L}^{-1}\{F(s) \cdot G(s)\} &= \int_0^t f(t-x) g(x) dx \quad \text{veya} \quad \int_0^t f(x) g(t-x) dx \\ &= \int_0^t e^{-(t-x)} \cos x dx, \quad \int_0^t e^{-x} \cos(t-x) dx \\ &= \int_0^t e^{-t} \cdot e^x \cos x dx \\ &= \underline{\underline{e^{-t}} \int_0^t e^x \cos x dx} \end{aligned}$$

$$dx = du, \quad \cos x dx = dv$$

$$e^x dx = du, \quad \sin x = v$$

$$\int e^x \cos x dx = e^x \sin x - \int e^x \sin x dx$$

$$dx = du, \quad \sin x dx = dv$$

$$e^x dx = du, \quad -\cos x dx = dv$$

$$\int e^x \cos x dx = e^x \sin x - \left[-e^x \cos x + \int e^x \cos x dx \right]$$

$$2 \int e^x \cos x dx = e^x \sin x + e^x \cos x$$

$$\int_0^t e^x \cos x dx = \left[\frac{e^x}{2} (\sin x + \cos x) \right]_0^t$$

$$= \left[\frac{e^t}{2} (\sin t + \cos t) \right] - \left[\frac{e^0}{2} (\sin 0 + \cos 0) \right]$$

$$= \underline{\underline{\frac{e^t}{2} (\sin t + \cos t)}} - \frac{1}{2}$$

$$= \frac{e^t}{2} (\sin t + \cos t) - \frac{1}{2}$$

$$\mathcal{L}^{-1}\{F(s), G(s)\} = e^{-t} \left[\frac{e^t}{2} (\sin t + \cos t) - \frac{1}{2} \right]$$

$$\boxed{\mathcal{L}^{-1}\{F(s), G(s)\} = \frac{1}{2} (\sin t + \cos t) - \frac{1}{2} e^{-t}}$$