



Performance of a SystemVerilog Sudoku Solver with Synopsys VCS

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Agenda

Why do we care about Sudoku?

Constraint Composition

Results

Conclusions



Constraint Solver Efficiency



- Write a bunch of constraints in the test bench
- No real concern with how well the solver will perform

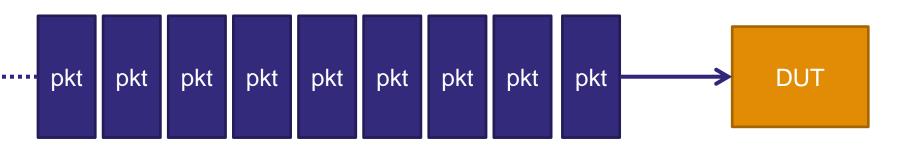
```
... until ...
... much later in the project ...
```

- Hey we're spending a lot of time in the constraint solver!
- Why is that?

Constraints in a Packet



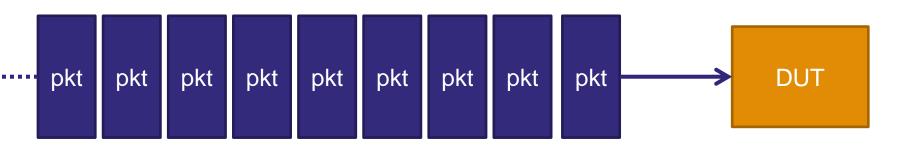
- How many packets are generated?
 - 10? 50,000?
- How long does each packet take to solve?
- Why does the solver take time?



Constraints in a Packet



- How many packets are generated?
- How long does each packet take to solve?
- Why does the solver take time?
- Seemingly simple constraint construction could lead to an inefficient constraint formula to solve
- Proprietary methods to analyze and solve formula



Proprietary Analysis



- Boolean Satisfaction is an Art
 - NP-complete problem
 - <u>N</u>ondeterministic <u>P</u>olynomial time
- Different solvers' approaches may be style-dependent

Fast & efficient for one simulator may be slow for another

Why Sudoku?



- We don't care about Sudoku
- Sudoku as testing vehicle
- Concrete Boolean problem
- Simple constraint composition
- Scalable
 - Boolean clauses are scalable (artifact of the CNF formula)
- Scales exponentially
- Saturate the solver
 - Small changes should have a noticeable affect



Sudoku Solving Performance

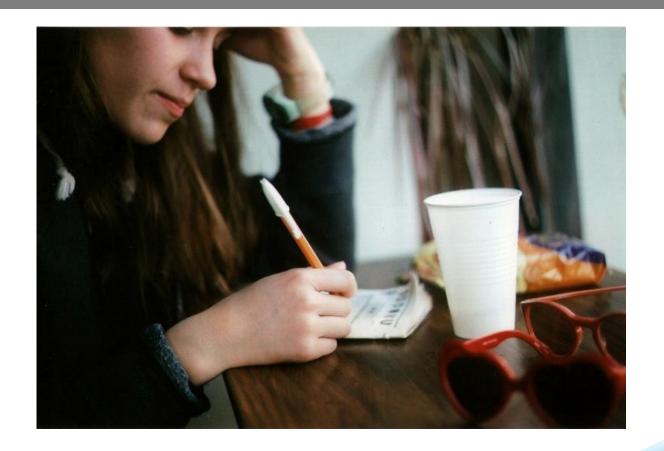


- Dissect the Sudoku constraints in SystemVerilog
- Compare VCS solver efficiency over differing constraint compositions
- Compare VCS solver efficiency against public solvers
 - MathSAT5, University of Trento, Trento, Italy
 - Yices, SRI International, Menlo Park, CA
 - Z3, Microsoft Research, Redmond, WA





Playing the game of Sudoku



Sudoku Defined

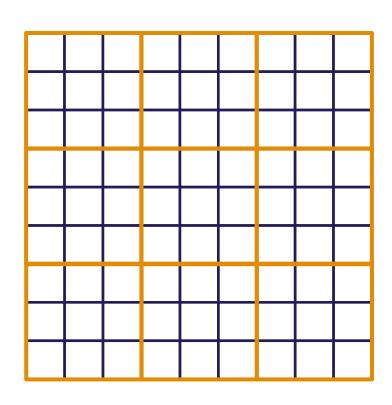




n = number of cells
per square side

 n^2 = number of cells in Latin Square

Each cell contains a unique value

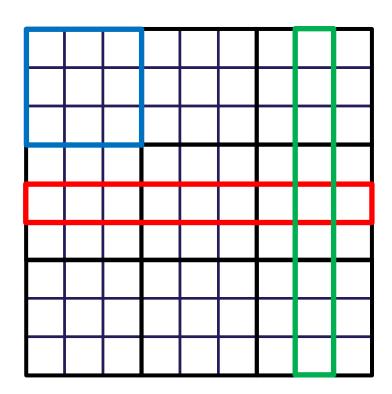


9x9 Sudoku Board $n^2 = 9$

Sudoku Defined



- Cell value is unique in:
 - Latin Square
 - Row
 - Column

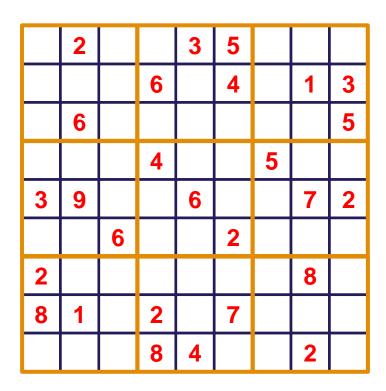


9x9 Sudoku Board $n^2 = 9$

Playing Sudoku



Subset of cells have an initial value -- hints



Playing Sudoku



- Subset of cells have an initial value -- hints
- Fill in the empty cells with valid values to solve

	2			3	5			
			6		4		1	3
	6							5
			4			5		
3	9			6			7	2
		6			2			
2							8	
8	1		2		7			
			8	4			2	

Solving SystemVerilog Sudoku



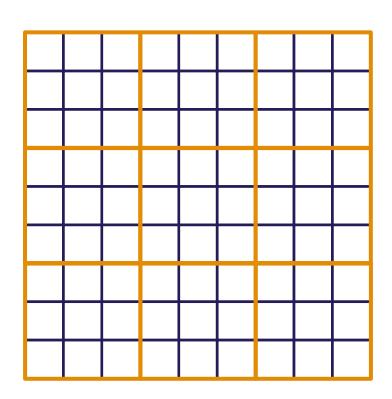
 Hint cell values reduce number of constraints for simulator's solver to solve

	2			3	5			
			6		4		1	3
	6							5
			4			5		
3	9			6			7	2
		6			2			
2							8	
8	1		2		7			
			8	4			2	

Solving SystemVerilog Sudoku

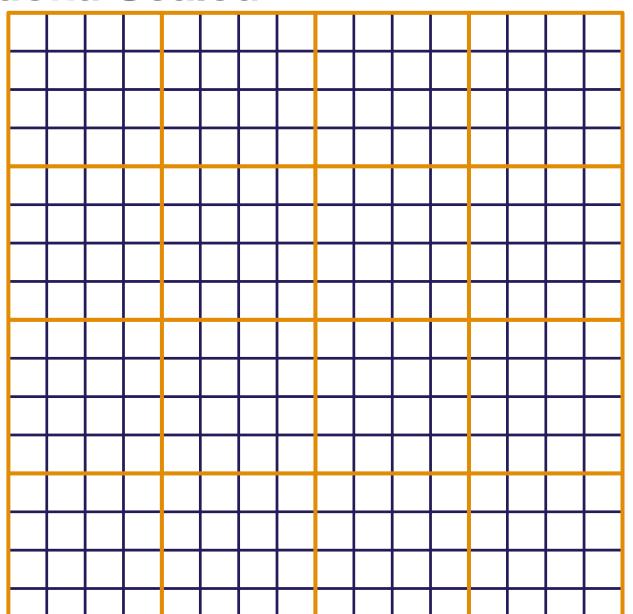


- Hint cell values reduce number of constraints for simulator's solver to solve
- Instead, we used a blank board and a random seed
 - Total 9x9 grids: 6.67×10²¹



Sudoku Scaled





Scales in Latin-Squares

16x16 Sudoku Board $n^2 = 16$



Constraint Composition

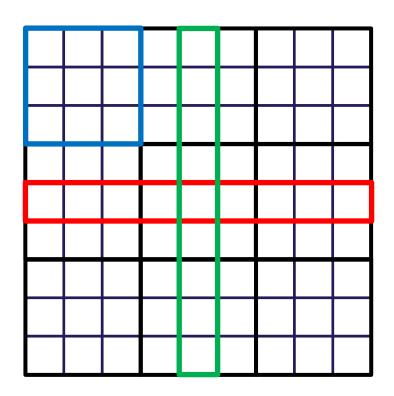
Object Oriented Game Board



Composing Sudoku Formula



- Assume cell takes integer value greater than zero
- Cell constraint
 cell.value inside {[1:n²]};
- Square constraint
- Row constraint
- Column constraint



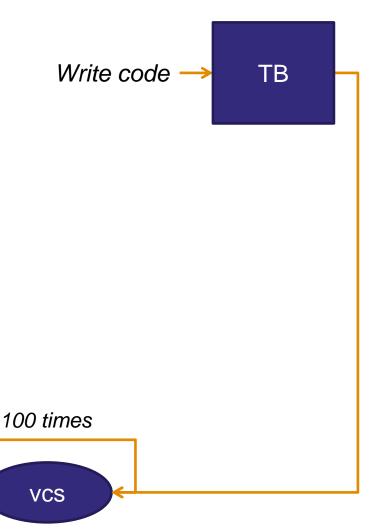
Sudoku Test benches



1. Object Oriented

- a) with full set of constraints
- b) with limited set of constraints

analyze



Sudoku Test benches

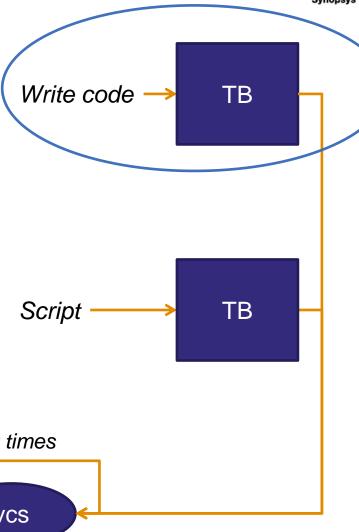


1. Object Oriented

- a) with full set of constraints
- b) with limited set of constraints

2. Flat Game Board

- a) with full set of constraints
- b) with minimal set of constraints

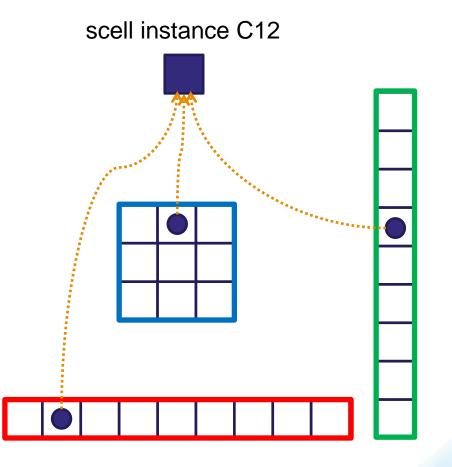






Single cell instance in Sudoku board

```
'define N2 9
class scell;
 rand int val;
 constraint c {
  val inside { [1:`N2] }; }
endclass
class slist;
 rand scell cel[];
 constraint c {
  foreach (cel[i])
   foreach (cel[j])
     i != j -> cel[i].val != cel[j].val;
endclass
```



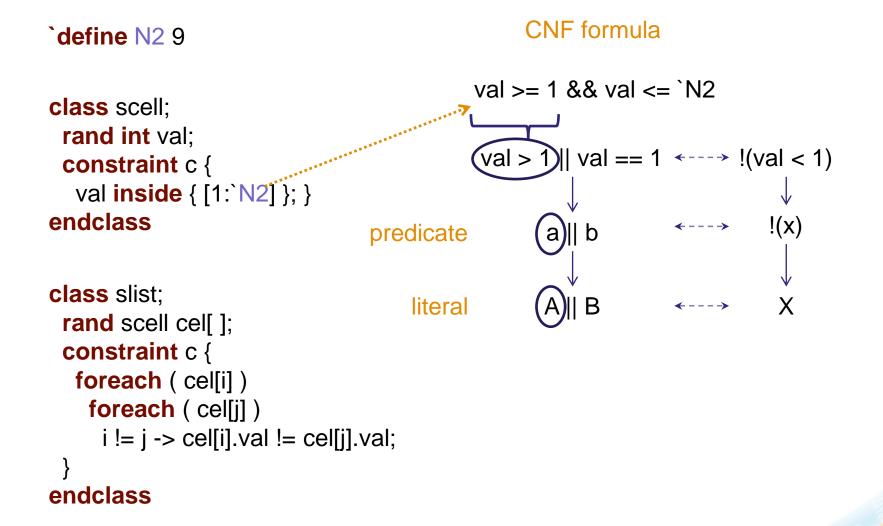


Boolean formula to solve

```
CNF formula
define N2 9
                                         val >= 1 && val <= `N2
class scell;
 rand int val;
                                          Clause
                                                        Clause
 constraint c {
  val inside { [1:`N2] }; }
endclass
class slist;
 rand scell cel[];
 constraint c {
  foreach (cel[i])
   foreach (cel[j])
     i != j -> cel[i].val != cel[j].val;
endclass
```



Boolean formula to solve





Boolean formula to solve

```
CNF formula
define N2 9
                                           val >= 1 && val <= N2
class scell;
 rand int val;
                                           val > 1 || val == 1
 constraint c {
  val inside { [1:`N2] }; }
endclass
                                predicate
                                                  a || b
class slist;
                                    literal
                                                  A \parallel B
 rand scell cel[];
                                                                       unit clause
 constraint c {
  foreach (cel[i])
                                                (X|B) && (C||D) && (B)
   foreach ( cel[j] )
     i != i -> cel[i].val != cel[i].val;
                                                                  C18: val == 1
endclass
```

Lazy Solving Approach



a) full set of constraints

endclass

```
define N2 9
                                           val >= 1 && val <= N2
class scell;
 rand int val;
                                          Crow column: C12, C18
 constraint c {
                                          Crow_index col_index: C01, C07
  val inside { [1:`N2] }; }
endclass
                                                       cel[i] cel[j]
class slist;
                                             <del>(0 -- 0 || C11 !- C11) &&</del>
                                                                           reduce?
 rand scell cel[];
                                              (0 == 1 \parallel C11 != C12) \&\&
 constraint c {
                                                                             optimize?
  foreach ( cel[i] )
    foreach ( cel[j] )
     i != j -> cel[i].val != cel[j].val;
                                                 Row 1 Constraint
```



b) limited set of constraints

endclass

```
define N2 9
                                          val >= 1 && val <= N2
class scell;
 rand int val;
                                          Crow column: C12, C18
 constraint c {
                                          Crow_index col_index: C01, C07
  val inside { [1:`N2] }; }
endclass
                                                      cel[i] cel[j]
class slist;
                                                                            reduce?
 rand scell cel[];
                                                                            reduce?
 constraint c {
  foreach ( cel[i] )
                                             (1 \le 0 \parallel C12 = C11) \&\&
    foreach ( cel[j] )
     i > j -> cel[i].val != cel[j].val;
                                                 Row 1 Constraint
```

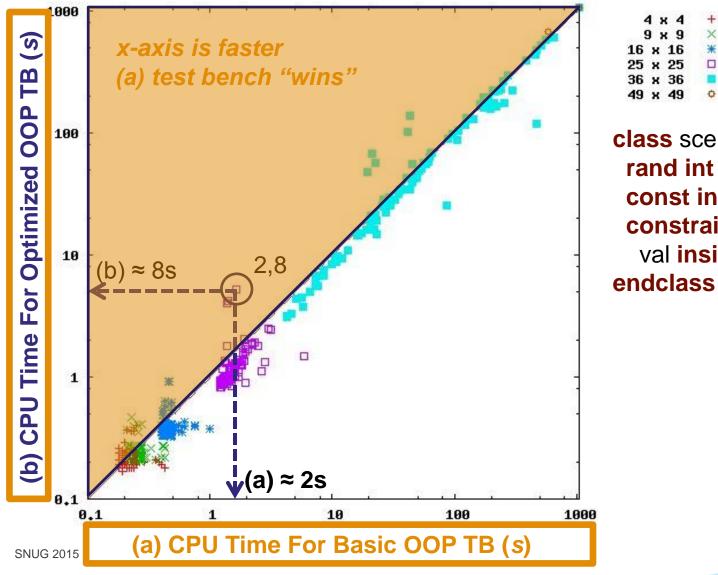


Optimized TB halves the solving space

	Sudoku Board	# of Cells	Tot # scell	# slist	# Total	Reduction
- II	4x4	16	32	64	224 = 3	32 + (64*3)
ОР h (!:	9x9	81	162	729	2,349	-
ic O enc	16x16	256	512	4,096	12,800	-
a) Basic OOP Test bench (!=)	25x25	625	1,250	15,625	48,125	-
(a) Te	36x36	1,296	2,592	46,656	142,560	-
	49x49	2,401	4,802	117,649	357,749	-
Р (4x4	16	32	24	104	53.67%
00P (>)	9x9	81	162	324	1,134	51.7%
zed	16x16	256	512	1,920	6,272	51%
Optimized OO Test bench (>)	25x25	625	1,250	7,500	23,750	50.7%
	36x36	1,296	2,592	22,680	70,632	50.5%
(Q)	49x49	2,401	4,802	57,624	177,674	50.3%

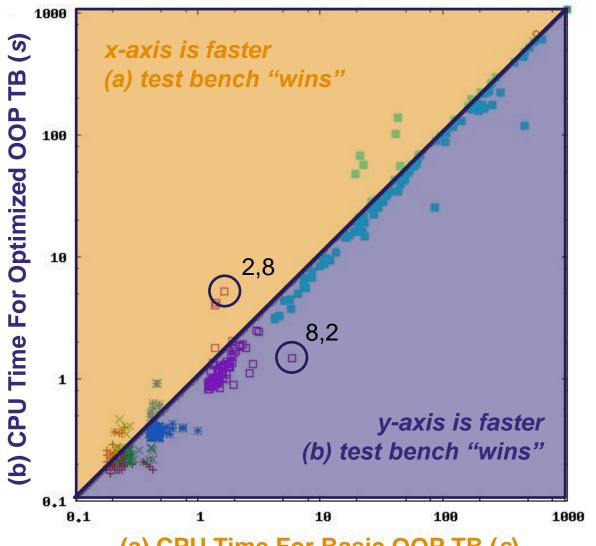


Basic vs. Optimized 4 using a const variable





Basic vs. Optimized 4 using a const variable

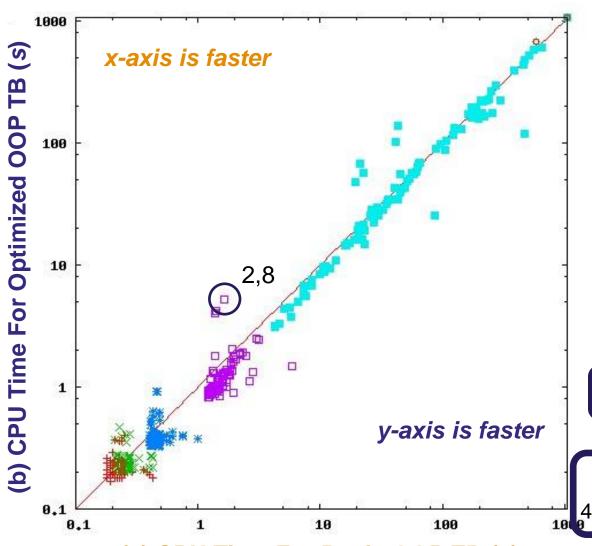


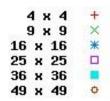
```
4 x 4 + 9 x 9 × 16 x 16 * 25 x 25 □ 36 x 36 ■ 49 x 49 •
```

```
class scell;
  rand int val;
  const int max = `N2;
  constraint c {
    val inside { [1:max] }; }
endclass
```



Basic vs. Optimized 4 using a const variable





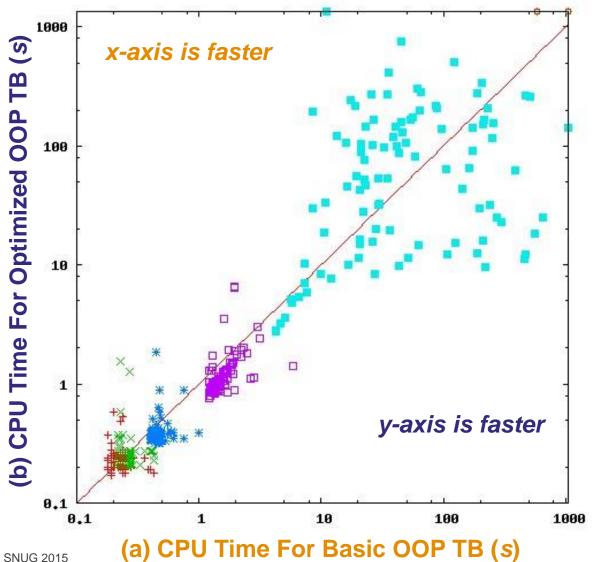
Average Solving Time with VCS (seconds)

Board	(a)	(b)				
4x4	0.23	0.22				
9x9	0.26	0.24				
16x16	0.47	0.39				
25x25	1.60	1.25				
36x36	48,125	23,750				
49x49	587.48	679.28				
9x49 = 1 solved (a), 1 solved (b)						

(a) CPU Time For Basic OOP TB (s)



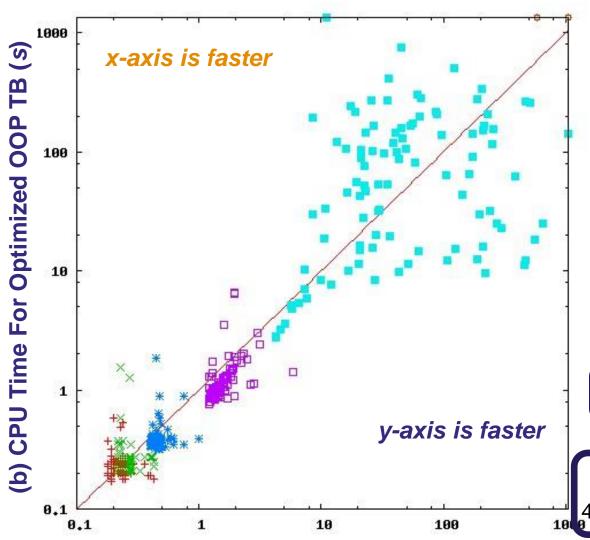
Basic vs. Optimized 4 using a `define

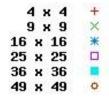


class scell; rand int val; constraint c { val **inside** { [1: N2] }; } endclass



Basic vs. Optimized 4 using a `define





Average Solving Time with VCS (seconds)

Board	(a)	(b)				
4x4	0.23	0.23				
9x9	0.26	0.28				
16x16	0.47	0.40				
25x25	1.60	1.27				
36x36	48,125	23,750				
49x49	587.48	-				
9x49 = 1 solved (a), 0 solved (b)						

(a) CPU Time For Basic OOP TB (s)



b) limited set of constraints

```
`define N2 9

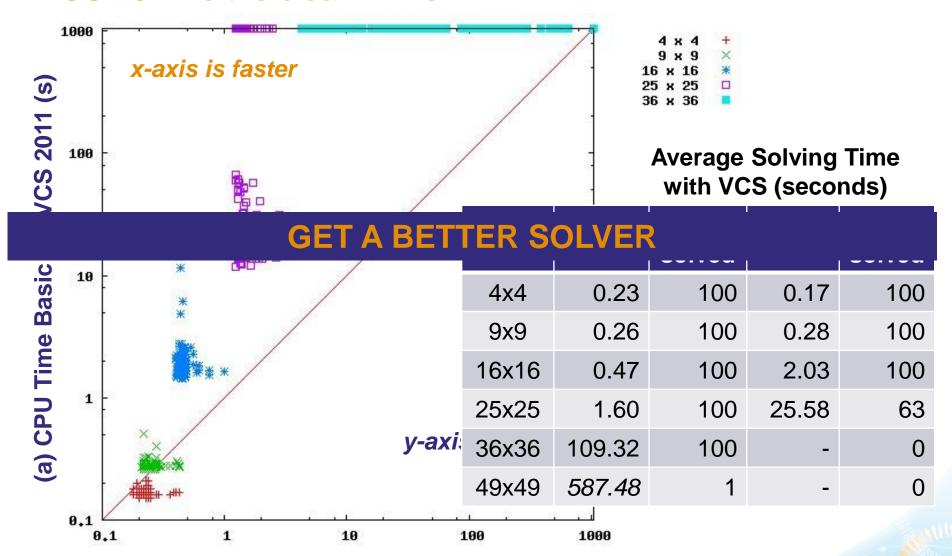
class scell;
  rand int val;
  constraint c {
    val inside { [1:`N2] }; }

class scell;
  constraint c {
    constraint c {
        Crow column: C12, C18
        Crow_index col_index: C01, C07
    endclass
```

Empirically, "yes" formula is reduced. No benefit rewriting.



VCS 2014 is the clear winner





Constraint Composition

Flat Game Board

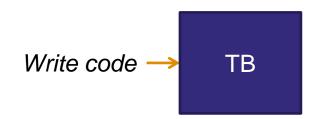


Sudoku Test benches



1. Object Oriented

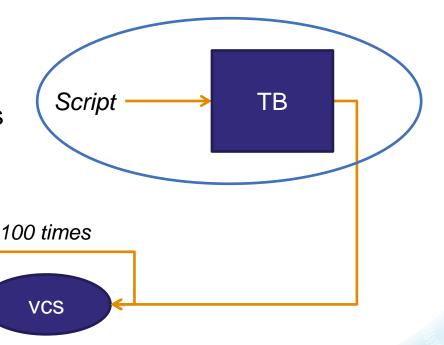
- a) with full set of constraints
- b) with limited set of constraints



2. Flat Game Board

- a) with full set of constraints
- b) with minimal set of constraints

analyze



Synopsys Users Group

a) full set of constraints

```
class sboard;
               rand int cel 1 1;
               rand int cel 1 2;
               rand int cel 9 9;
               constraint cells {
                cel 1 1 inside { [1:9] };
                cel_1_2 inside { [1:9] };
                cel_9_9 inside { [1:9] };
optimize
             constraint rows {
between
                col 1 1 != col 1 2;
blocks?
                cel 1 1 != cel 1 3:
optimize
within
                cel 1 2 != cel 1 1
block?
```

```
constraint cols {
  cel_1_1 != cel_2_1;
  cel 1 1!= cel 3 1;
                              optimize
                              within
  <del>ccl 2 1 != ccl 1 1;</del>
                              block?
 constraint sqrs {
                              optimize
  ccl 1 1!= ccl 1 2;
                              between
  cel 1 1 != cel 1 3;
                              blocks?
  cel_1_1! = cel_2_1;
                              optimize
  col 2 1 != col 1 1; •
                              within
                              block?
endclass
```

b) minimal set of constraints



```
class sboard;
 rand int cel 1 1;
 rand int cel 1 2;
 rand int cel_9_9;
 constraint cells {
  cel_1_1 inside { [1:9] };
  cel_1_2 inside { [1:9] };
  cel_9_9 inside { [1:9] };
constraint rows {
  cel 1 1 != cel 1 2;
  cel 1 1 != cel 1 3;
```

```
constraint cols {
  cel_1_1 != cel_2_1;
  cel_1_1 != cel_3_1;
  ...
}
constraint sqrs {
  cel_1_1 != cel_1_5;
  cel_1_1 != cel_1_6;
  ...
}
endclass
```

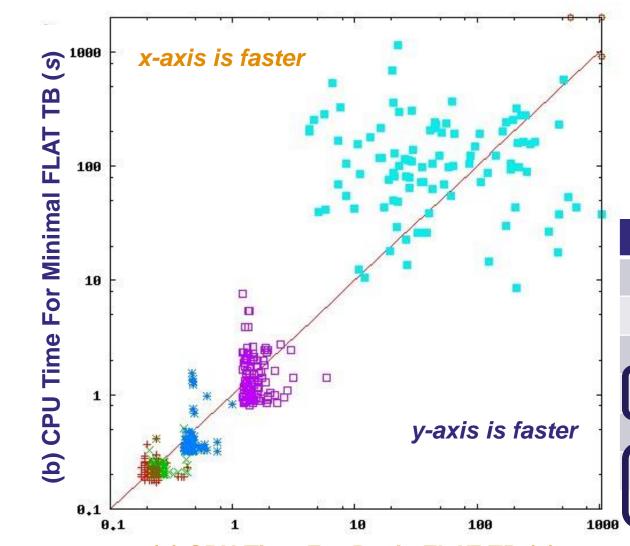


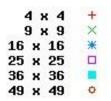
Minimal TB at least halves the solving space

	Sudoku	# of cells	# cell	# row/col	# sqr	# Total	Reduction
	4x4	16	32	48	48	176	-
c FLAT bench	9x9	81	162	648	648	2,106	-
ic FI t ber	16x16	256	512	3,840	3,840	12,032	-
Basic Test b	25x25	625	1,250	15,000	15,000	46,250	48,125
(a) l	36x36	1,296	2,592	43,360	43,360	138,672	-
	49x49	2,401	4,802	115,248	115,248	350,546	-
ь	4x4	16	32	24	8	88	50.00%
FLAT ch	9x9	81	162	324	162	972	53.85%
	16x16	256	512	1,920	1,152	5,504	54.26%
Minimal FL Test bench	25x25	625	1,250	7,500	5,000	21,250	23,750 05%
(b) № Te	36x36	1,296	2,592	22,680	16,200	64,152	53.74%
3	49x49	2,401	4,802	57,624	43,218	163,268	53.42%



Basic vs. Optimized 3 with unique clauses





Average Solving Time with VCS (seconds)

Board		(a)	(b)			
4x4		0.28	0.22			
9x9		0.25	0.22			
16x16		0.58	0.42			
25x25		1.90	1.61			
36x36		46,250	21,250			
49x49	1	,700.46	1,459.09			
49x49 = 2 solved (a), 2 solved						
			(b)			

(a) CPU Time For Basic FLAT TB (s)

40

OOP vs FLAT



- OOP test bench outperforms larger FLAT test benches
- FLAT solved more of the largest test benches

Average Solving Time with VCS (seconds)

Sudoku	OOP (a)	OOP (b)	FLAT(a)	FLAT(b)		
4x4	0.23	0.22	0.28	0.22		
9x9	0.26	0.24	0.25	0.22		
16x16	0.47	0.39	0.58	0.42		
25x25	1.60	1.25	1.90	1.61		
36x36	109.32	104.32	137.72	148.51		
49x49	<i>587.4</i> 8	679.28	1,700.46	1,459.09		
49x49 = OOP(a) 1 solved, OOP (b) 1 solved, FLAT(a) 2 solved, FLAT (b) 2 solved						

OOP vs MATHSAT5 vs YICES



- Same flat board in SMT2 language
- Showing unique case for Mathsat5, YICES, and Z3

Average Solving Time (seconds)

Sudoku	OOP (a)	OOP (b)	MSAT5	YICES	Z 3
4x4	0.23	0.22	0.02	0.00	0.01
9x9	0.26	0.24	21.99	7.70	174.64
16x16	0.47	0.39	-	-	
25x25	1.60	1.25	-	-	
36x36	109.32	104.32	-	-	
49x49	587.48	679.28	-	-	

49x49 = OOP(a) 1 solved, OOP (b) 1 solved, MSAT, YICES, and Z3 did not solve any board greater than 9x9 in time window.

Conclusions



- Hierarchical constraints about as good as flat
 - Object oriented vs. all in one class
- Constant variable access about as good as hard values
 - const vs. `define (parameter)
- Composing the constraint to limit its size has very little impact on solving time
 - Solver effectively reduces the formula

Take Aways



- Readability of constraint is most important
- Maintainability of constraint is important
- Obtaining an efficient solver is important
 - VCS 2014



Pictures



Man Playing Sudoku on Subway While Women Look Over His Shoulder, https://www.flickr.com/photos/wnyc/19953592074

el viejo, el mar y el sudok, https://www.flickr.com/photos/altamar/2652472523

last august friday, with Flor, https://www.flickr.com/photos/perfumedsecrets/7934536812/

Art in Embassies - Jonathan Anderson, Construction (no. 6), 2009, https://www.flickr.com/photos/us_embassy_newzealand/6071070490/

How do students measure up?, https://www.flickr.com/photos/venosdale/4376443940/

summer 4, https://www.flickr.com/photos/26315381@N06/3403505001/





Thank You



Constraint Solver Efficiency



- Random verification relies on efficient and constrained stimulus generation
- Seemingly simple constraint construction can lead to an inefficient constraint formula to solve
- Proprietary methods to analyze and solve formula

