

ACTIVE LEARNING



WHOAMI



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Slides: https://github.com/rosen-group/conferences

INTRODUCING THE ROSEN GROUP





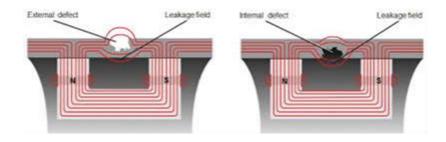
ROSEN develops and manufactures equipment, software, and methods for the inspection, diagnosis, and protection of industrial structures in a wide range of industries.

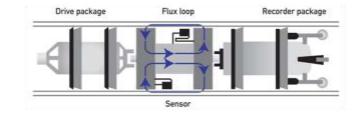
Because damage can cause serious impacts!

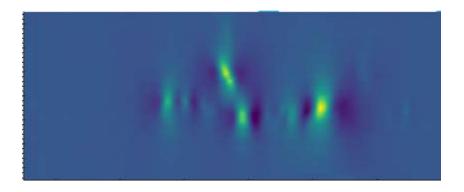


MAGNETIC FLUX LEAKAGE

- Measure volume loss in pipeline wall
- Indirect measurement principle
- Image-like data (2d array of amplitudes)
- Tasks: Detect, classify and estimate defect geometry from measured data.









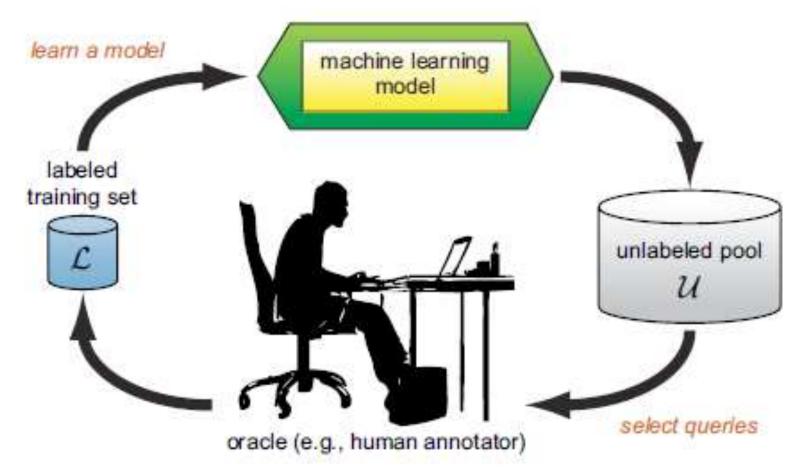


- Computer Vision problems
 - Large amounts of unlabeled data available
 - Human annotators can provide ground truth
 - Which instances to label?
 - Achieve high accuracy using as few labeled instances as possible



WHAT IS ACTIVE LEARNING?

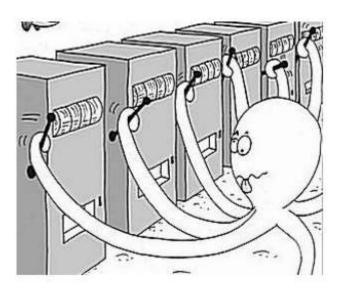








- How to design query algorithms?
 - Exploitation: make best decision based on currently available information
 - Exploration: gather more information





RANDOM QUERY

- Select instance to label randomly
- Good starting point
- Baseline algorithm : Compare other algorithms against random query

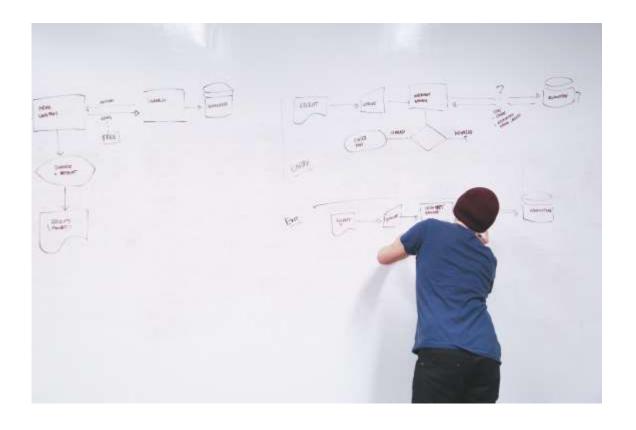






DETERMINISTIC QUERY

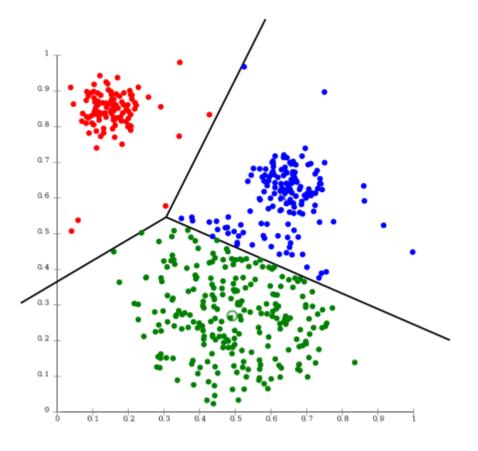
- Use knowledge about features and data to select instances
- Good starting point
- Class discovery







- Cluster label and unlabeled data
- Are cluster labeled inhomogeneously (by annotator or by classifier)?
- Heuristic algorithm
- Good for exploration







- Most popular algorithm
- Query the instance which the classifier is most uncertain how to label
- Least confident prediction in terms of prediction probability
- Make use of margin between most probable classes or entropy of class prediction probabilities to capture the whole distribution

$$x_{LC}^* = \underset{x}{\operatorname{argmax}} 1 - P_{\theta}(\hat{y}|x)$$

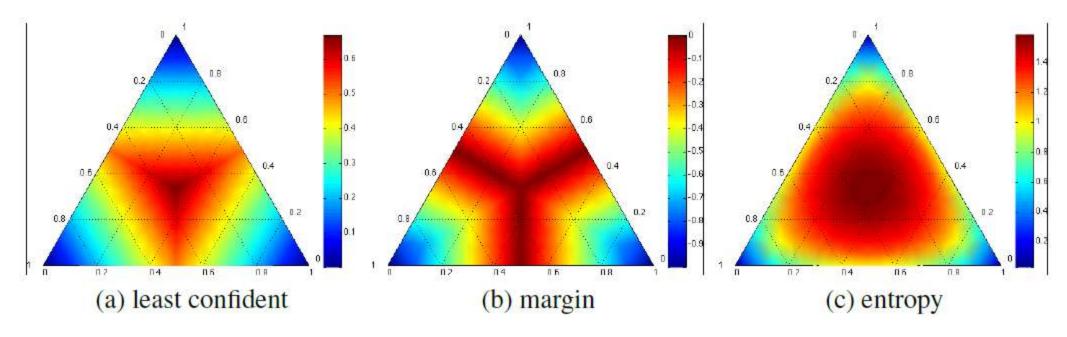
$$\hat{y} = \operatorname{argmax}_{y} P_{\theta}(y|x)$$

$$x_M^* = \operatorname*{argmin}_{x} P_{\theta}(\hat{y}_1|x) - P_{\theta}(\hat{y}_2|x)$$

$$x_H^* = \underset{x}{\operatorname{argmax}} - \sum_{i} P_{\theta}(y_i|x) \log P_{\theta}(y_i|x)$$

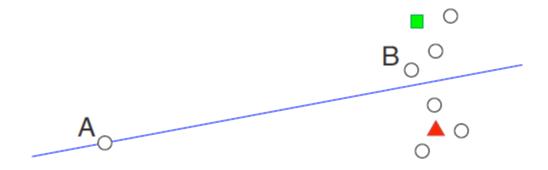
UNCERTAINTY SAMPLING









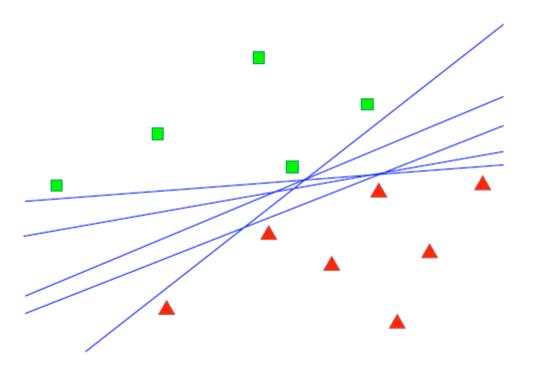






- Train a set of different classifiers
- Select the instance which the classifiers most degree about
- "Query controversial regions"
- Bagging can be used to construct the committee

$$x_{VE}^* = \underset{x}{\operatorname{argmax}} - \sum_{i} \frac{V(y_i)}{C} \log \frac{V(y_i)}{C}$$





EXPECTED MODEL CHANGE

- Select the instance which implies the greatest change of the current classifier if its label would be known
- Possible strategy: Which instance has greatest impact on the training gradient
- True labels are unknown so expectation value is used
- Can be computationally expensive

$$x_{EGL}^* = \underset{x}{\operatorname{argmax}} \sum_{i} P_{\theta}(y_i|x) \left\| \nabla \ell_{\theta}(\mathcal{L} \cup \langle x, y_i \rangle) \right\|$$





EXPECTED ERROR REDUCTION

- Select instance which is likely to reduce classification error on unlabeled instances
- Since true labels are unknown expectation values of the loss function for the unlabeled instances is used.
- Very high computational costs
- Sum can be approximated with Monte Carlo sampling to reduce the sum over all unlabeled instances

$$x_{\text{log}}^* = \underset{x}{\operatorname{argmin}} \sum_{i} P_{\theta}(y_i|x) \left(-\sum_{u=1}^{U} \sum_{j} P_{\theta^{+\langle x, y_i \rangle}}(y_j|x^{(u)}) \log P_{\theta^{+\langle x, y_i \rangle}}(y_j|x^{(u)}) \right)$$





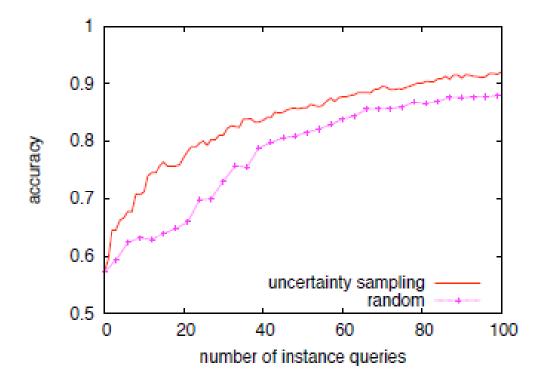
- Algorithm for cold start when no classifier is available (random query, deterministic query)
- Balance exploration and exploitation
- Combine different selection strategies
- Test test test







- Active learning can be simulated on a fully labeled data set
- Human annotator is simulated by giving the correct label
- Compare performance over number of labeled instances against random query



CONVERGENCE



- When to stop labeling?
 - Costs
 - Human annotator notices convergence
 - Stopping criterion

T-DISTRIBUTED STOCHASTIC NEIGHBOR EMBEDDING (TSNE)



- Learn low-dimensional embedding of feature vector by minimizing KL between similarities in both spaces
- Different distribution in low-dimensional space to compute similarities
- "Tends to cluster points by their classes"
- Van der Maaten, JMLR 2008

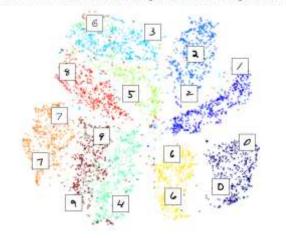
$$p_{j|i} = rac{\exp\left(-d(oldsymbol{x}_i, oldsymbol{x}_j)/(2\sigma_i^2)
ight)}{\sum_{i
eq k} \exp\left(-d(oldsymbol{x}_i, oldsymbol{x}_k)/(2\sigma_i^2)
ight)}, \quad p_{i|i} = 0,$$

$$p_{ij} = rac{p_{j|i} + p_{i|j}}{2N}.$$

$$q_{ij} = rac{(1 + ||oldsymbol{y}_i - oldsymbol{y}_j)||^2)^{-1}}{\sum_{k
eq l} (1 + ||oldsymbol{y}_k - oldsymbol{y}_l)||^2)^{-1}},$$

$$\mathit{KL}(P|Q) = \sum_{i \neq j} p_{ij} \log rac{p_{ij}}{q_{ij}}$$

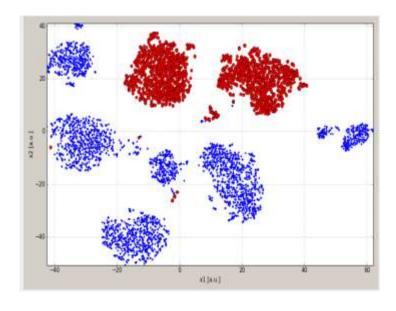
MNIST dataset - Two-dimensional embedding of 70,000 handwritten digits with t-SNI





STRATEGIES FOR MEASURING CONVERGENCE

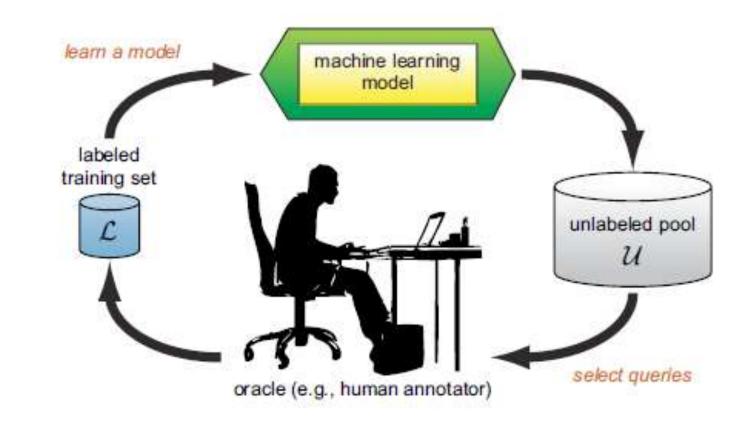
- Color TSNE visualization by classifier decisions and manual labels for the human annotator
- Track the changes of the classifier predictions on unlabeled data
- Cluster consistency





CONCLUSION

- Active learning can help you if you have a huge amount of unlabeled data and humans can provide ground truth
- There is no best query algorithm
- There is no best way to measure convergence
- Problems to consider:
 - Noisy human annotators
 - Class discovery
 - Training speed of ml algorithms



[TRUST] [INDUSTRIES] [PEOPLE] [COMPETENCE] [RELIABILITY] [TECHNOLOGY] [INNOVATION] [INDEPENDENT] [CAN DO]

THANK YOU FOR JOINING THIS PRESENTATION.

