

Scheduling of Cyber-Physical System Simulation

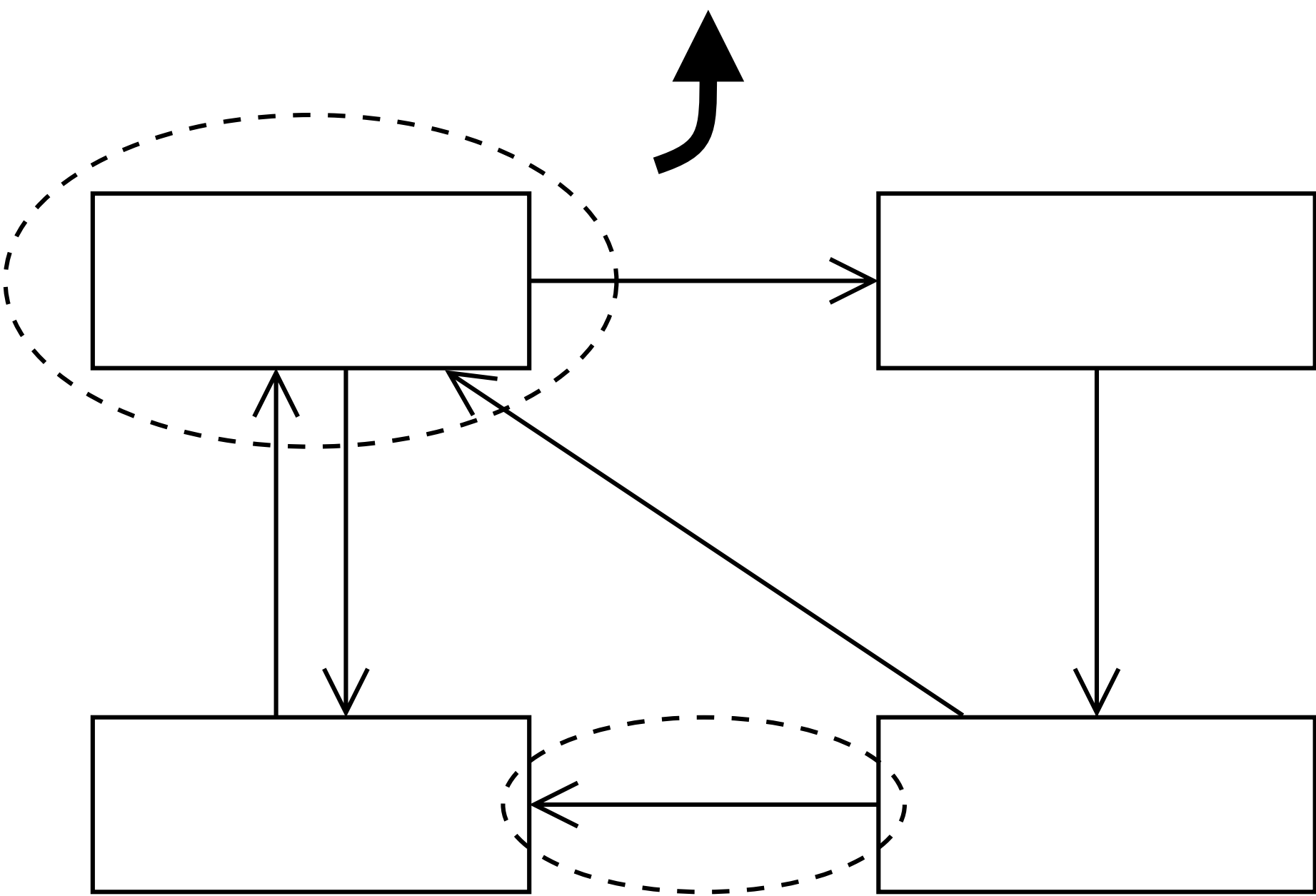
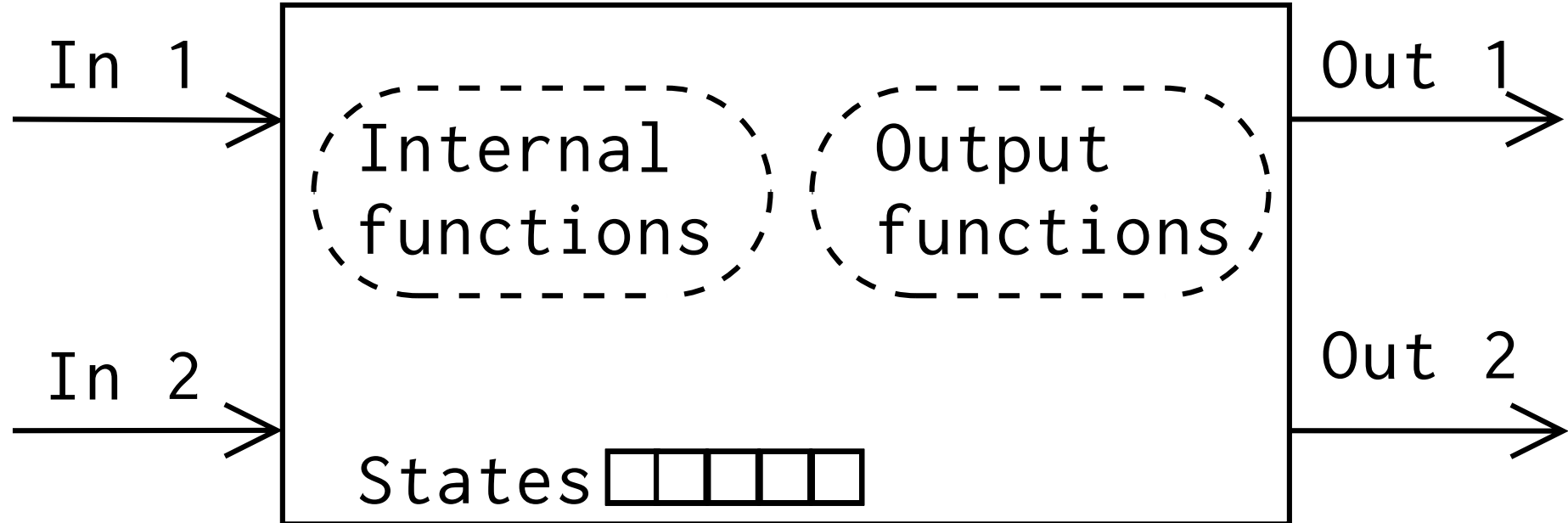
56



The simulation logical architecture

Formalization of simulation scheduling





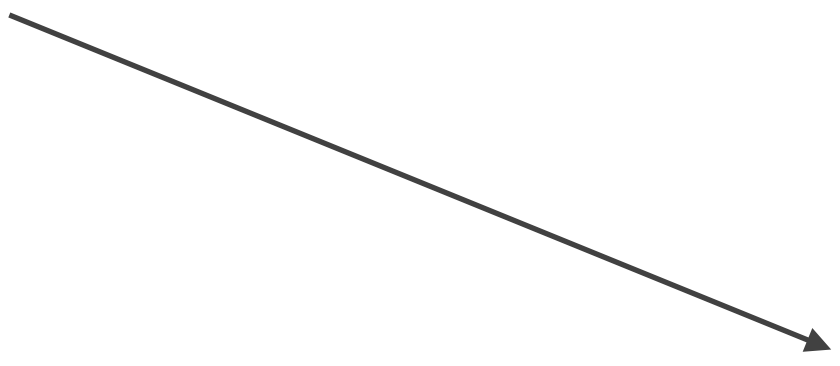
sl_a \equiv $\langle C, \Lambda, R \rangle$

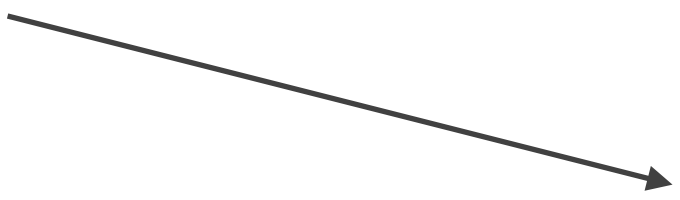
$$c = \langle P_{in}, P_{out}, S_0, S, \Delta_{in}, \Delta_{out} \rangle$$

$$\delta_{out} = \langle 0, I, S, \delta_{in} \times s^m \rightarrow 0, t \rangle$$

$$\delta_{in} = \langle I, S_{in}, S_{out}, \delta_{in \times s^{n \rightarrow s}}, f, t \rangle$$

$$\lambda = \langle P_{in}, P_{out} \rangle$$





Requirements

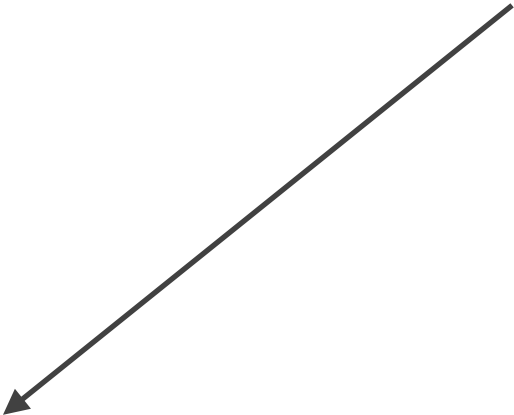
Charnels

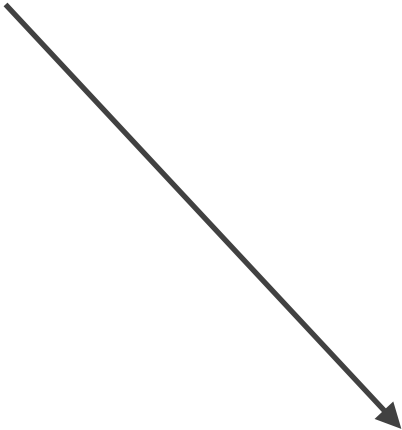
Components

Internal Advancement



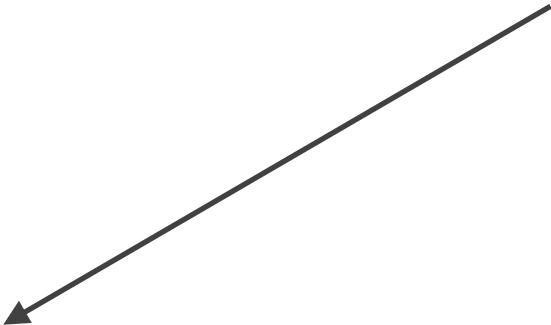
Output

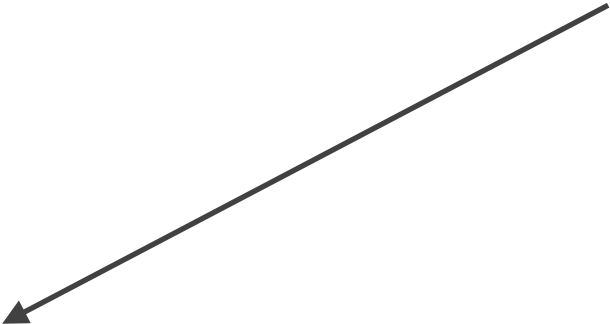


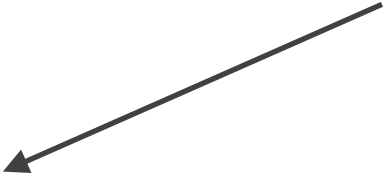


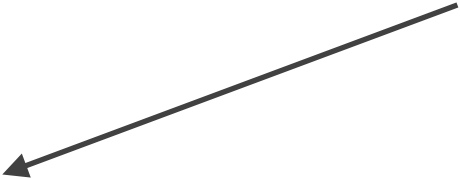
Ports

States









Ports

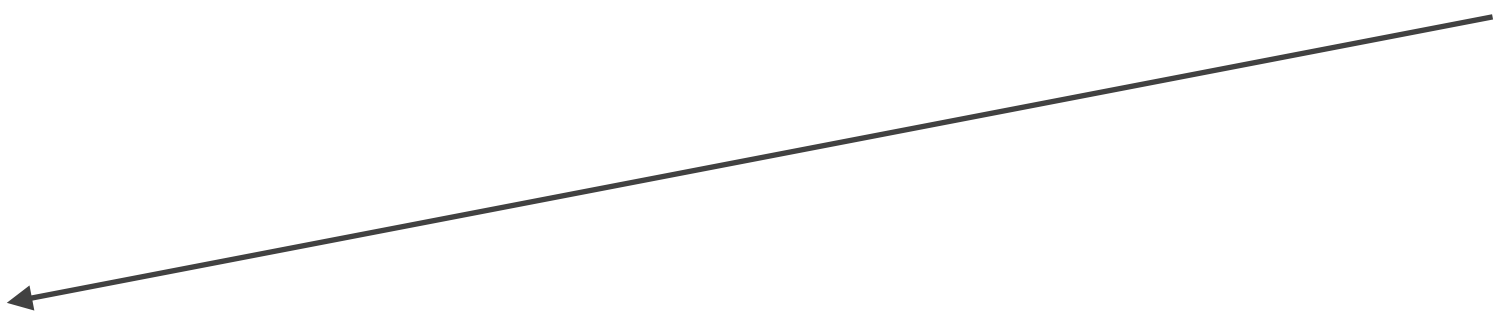
Inputs

States

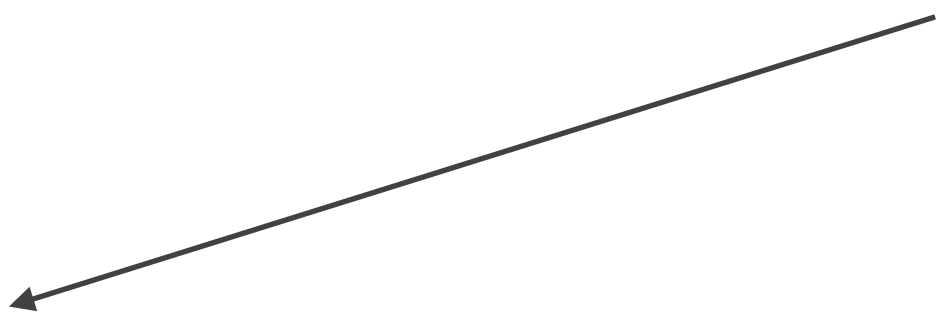
Functions

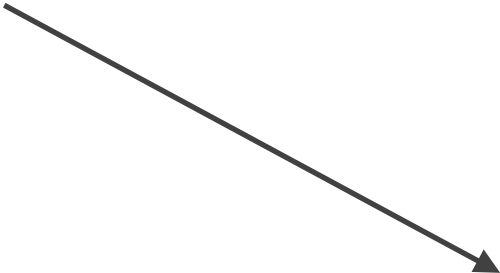
Frequency

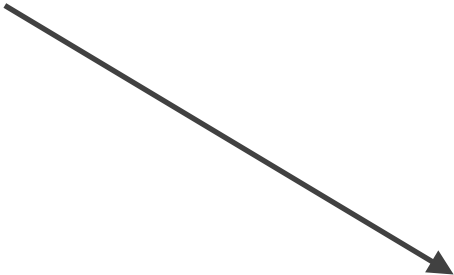
Budget

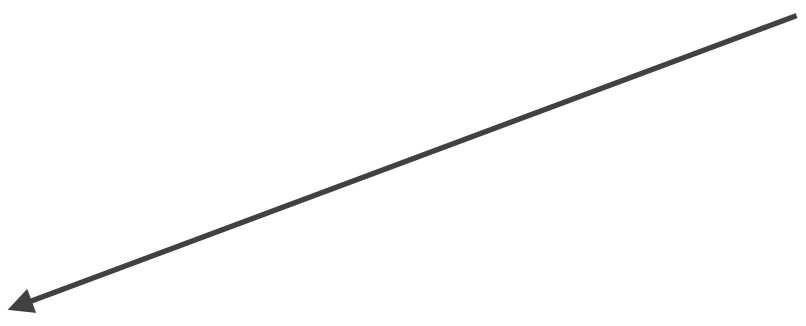


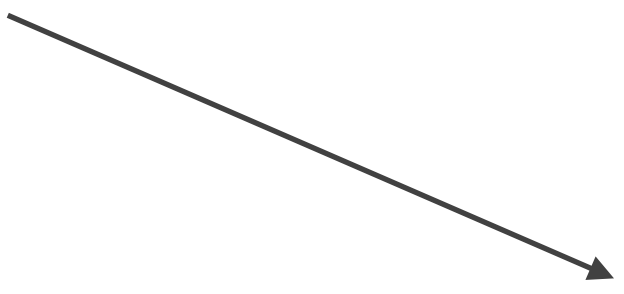


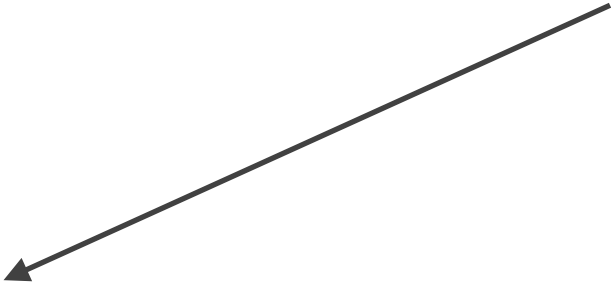


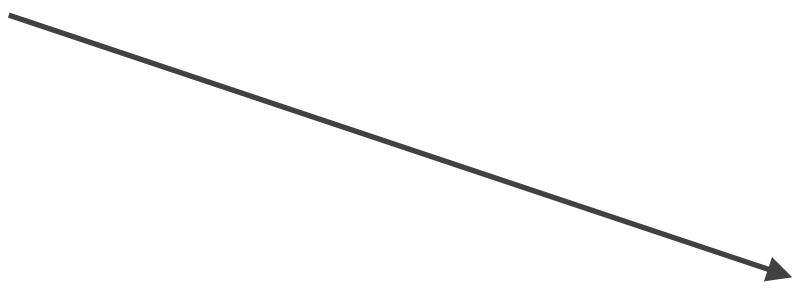


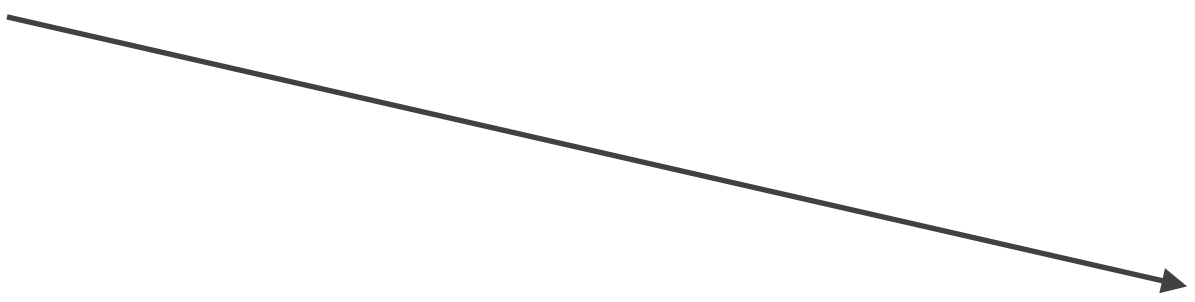










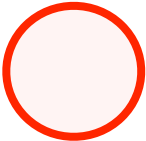




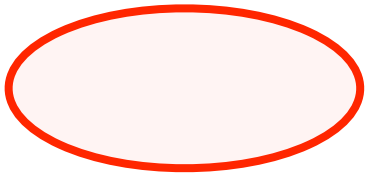












The simulation executive architecture

$$sla \equiv \langle C, \Lambda, R \rangle$$

$$c = \langle P_{in}, P_{out}, S_0, S, \Delta_{in}, \Delta_{out} \rangle$$

$$\delta_{out} = \langle 0, I, S, \delta_{in} \times s^m \rightarrow 0, t \rangle$$



































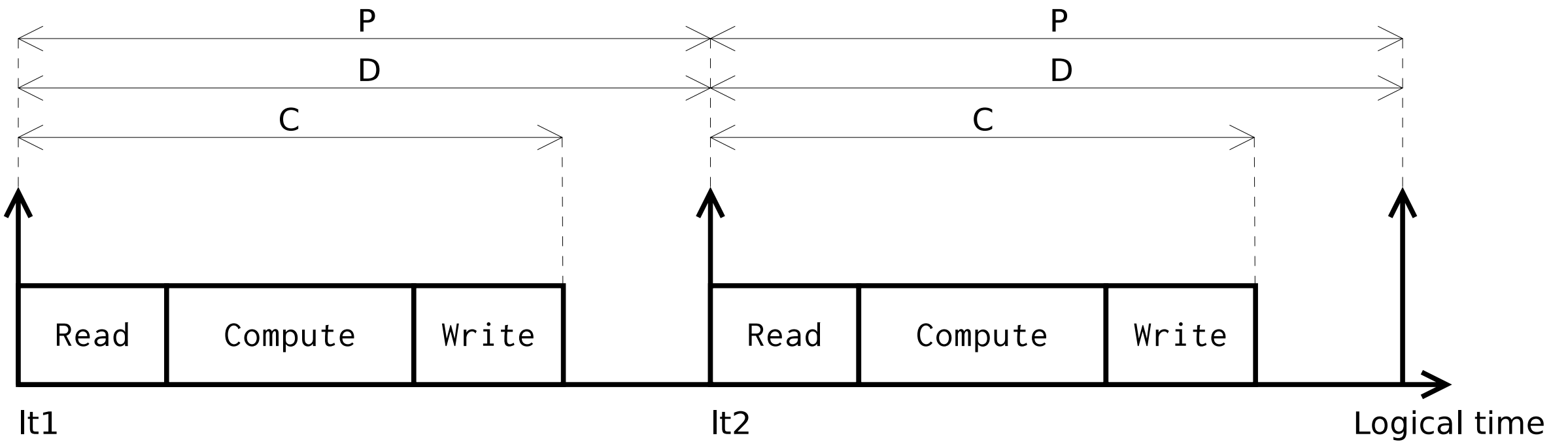
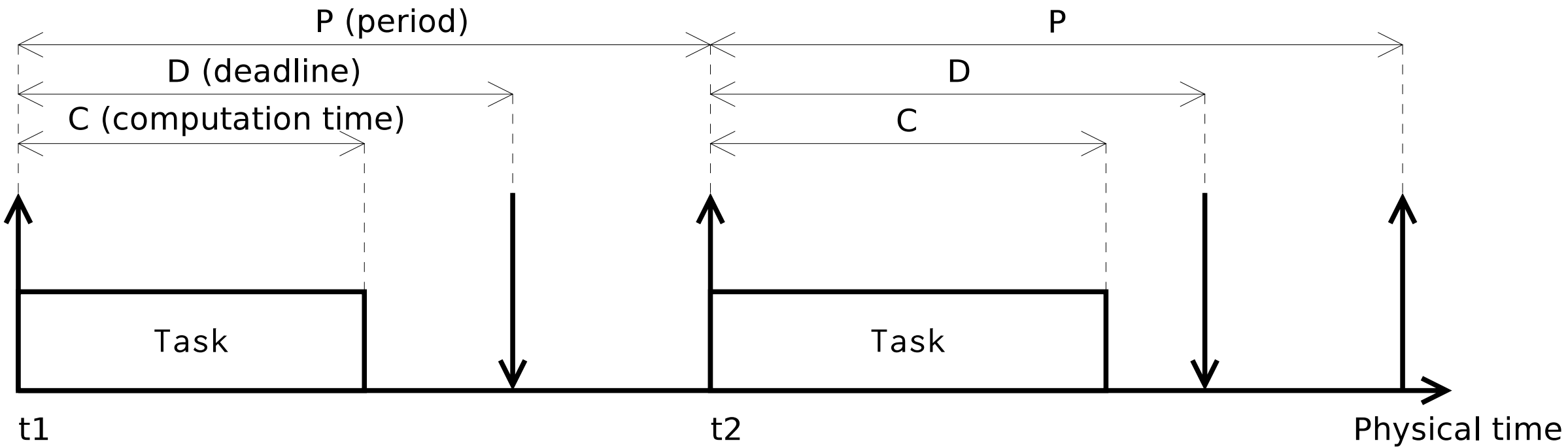












2

3