



Ph.D. thesis defense, July 15, 2019 by Henrik Deshpande at the ISAE-SPARCO, University of Toronto

Collapsed during simulation execution (Fig 2.6).

and causality, is illustrated in Figure 2.6.

ronautics is our main target in this research
 afts, in particular Full Flight Simulator (FFS)
 dy exists [KJ98, Lee17].

on of the movements and acceleration of
 ble of representing up to six degrees of
 Figure 2.7.

plified, for flight
 and visual.



Figure 2.6 – Wallclock, simulation and physical time

- Hardware-in-the-loop (HWIL) — A technique for simulation.
- Human-in-the-loop (HIL) — A technique for simulation.

Scheduling of a

Cyber-Physical System Simulation

Gerlando Cappello

Primer Sirron

Supervised by:

Janette Cardoso

ISARE-SUIPAREO

Airbus Group

ISAE



Institut Supérieur de l'Aéronautique et de l'Espace

SUPAERO

ARRBUS



UNIVERSITÉ
TOULOUSE III
PAUL SABATIER



anrt



association nationale
recherche technologie

Scheduling of Cyber-Physical System Simulation



Outline of the slides show

2. Objectives and approach

5. Design and implementation of the solution

1. Introduction

3. Theoretical framework

4. Formalization of simulation scheduling

6. Conclusion, openings

56



