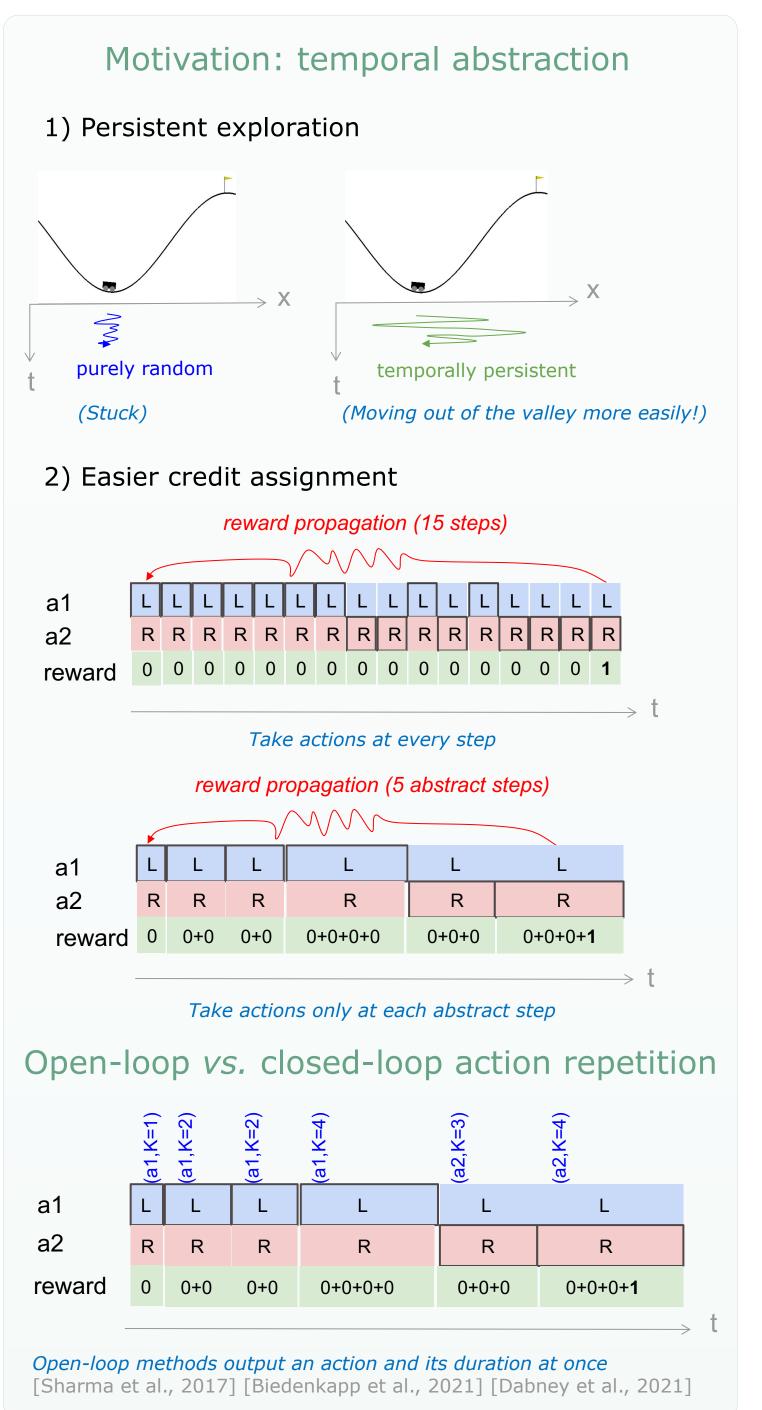
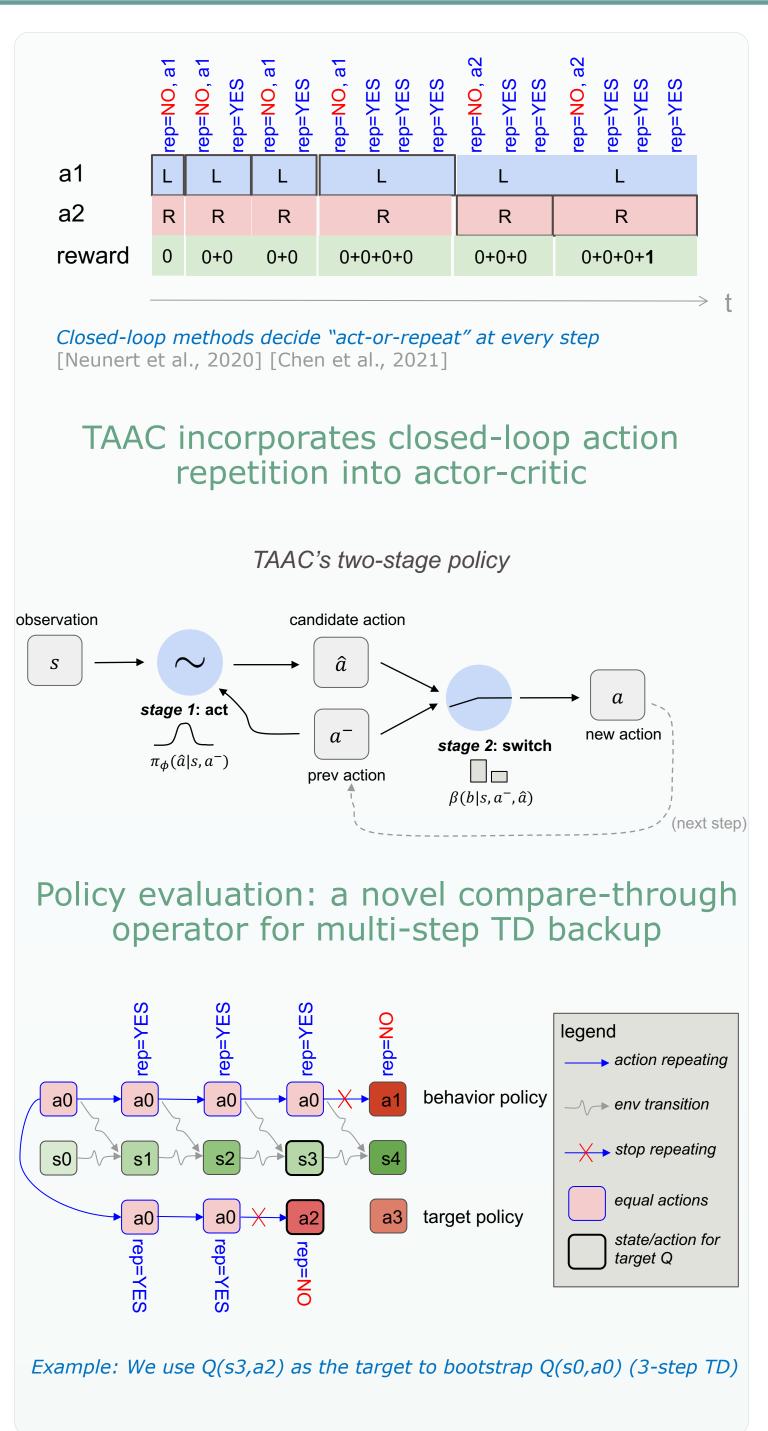
## TAAC: Temporally Abstract Actor-Critic for Continuous Control

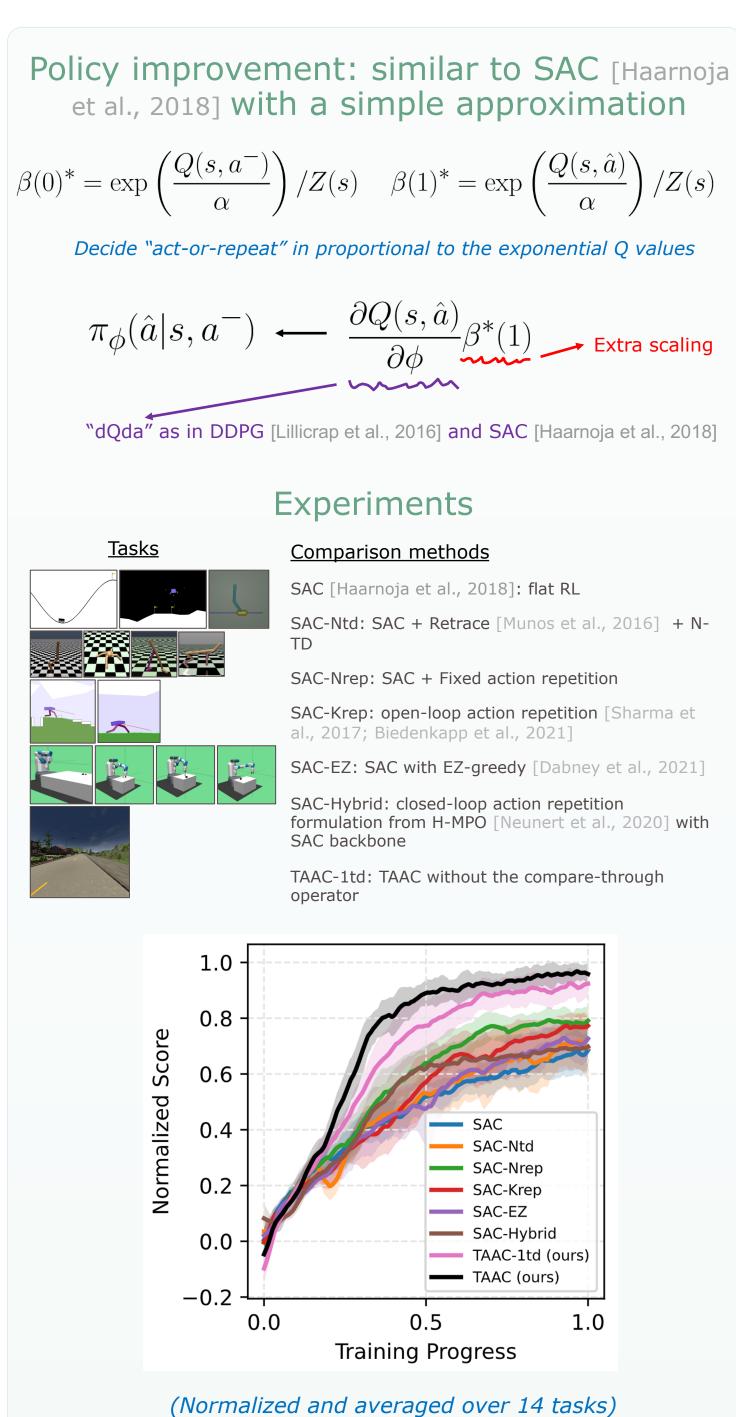
Haonan Yu, Wei Xu, Haichao Zhang

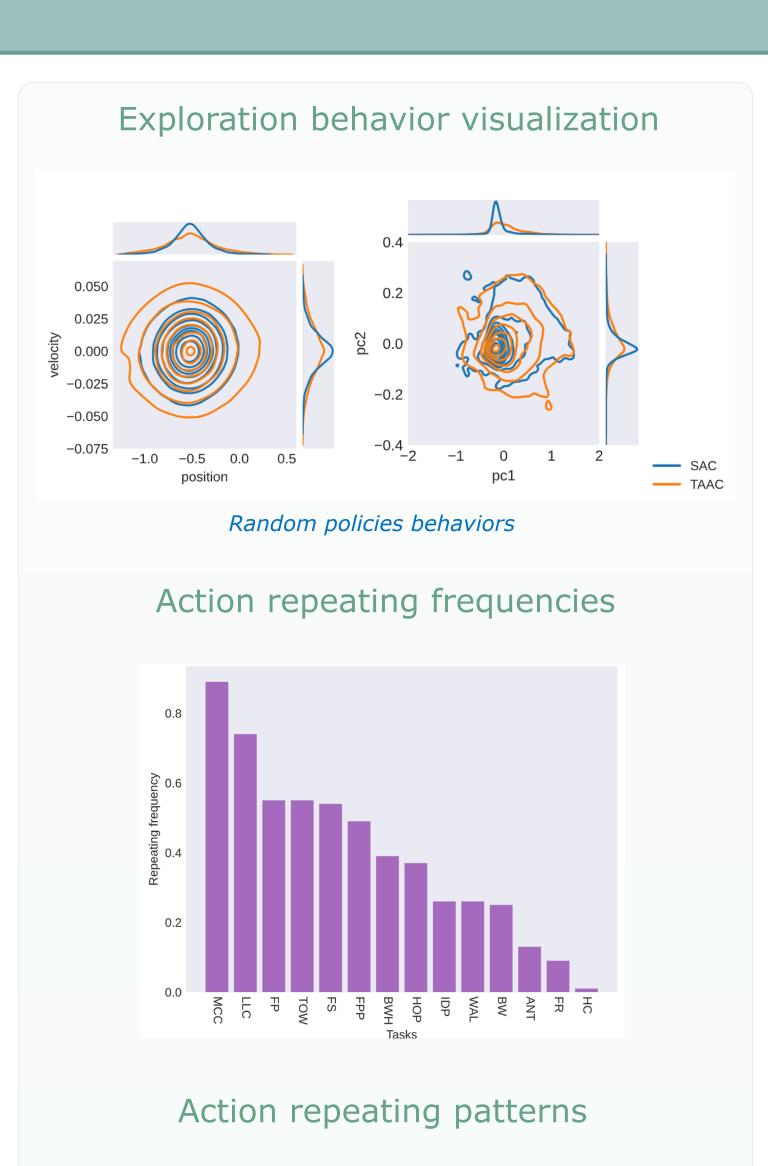


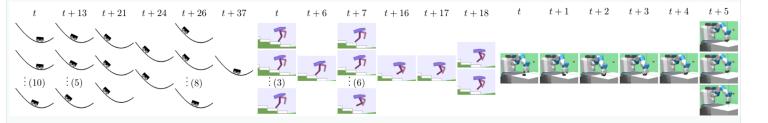
(Try code at https://github.com/hnyu/taac)











(Each column represents the same action)

Key observation: TAAC learns to skip learning to generate new actions at non-critical states, and save the actor network's representational power for critical states!