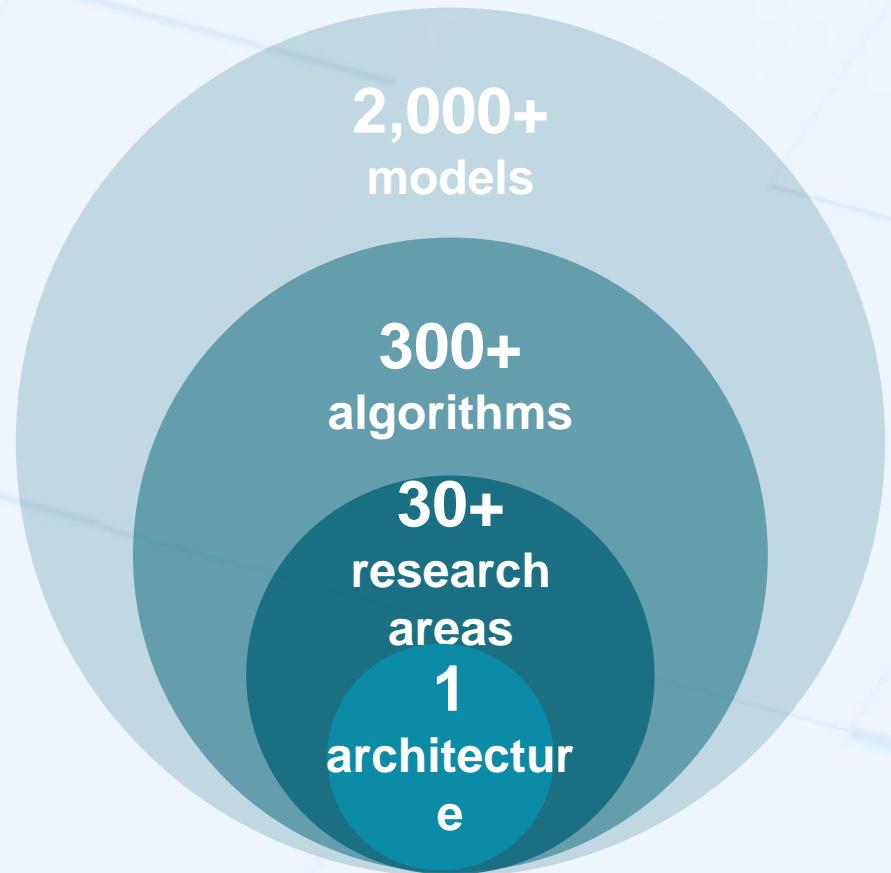


# OpenMMLab: A Foundational Platform for Computer Vision Research and Production

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Shanghai AI Laboratory

# Overview of OpenMMLab

Open-source computer vision algorithm platform



1

30+

300+

2000+

## Architecture

- unified architecture for training and evaluation

## Research Areas

- cover a wide range of research areas

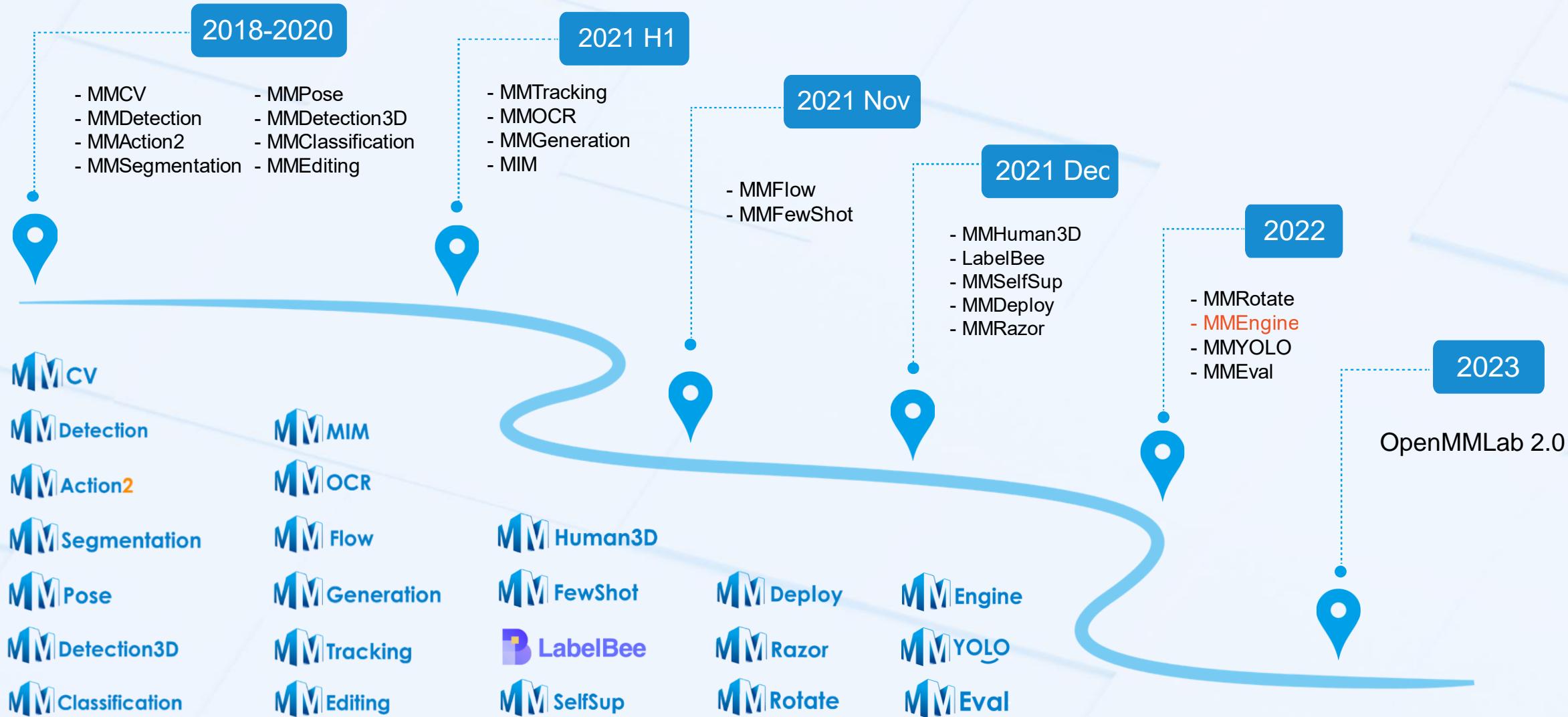
## Algorithms

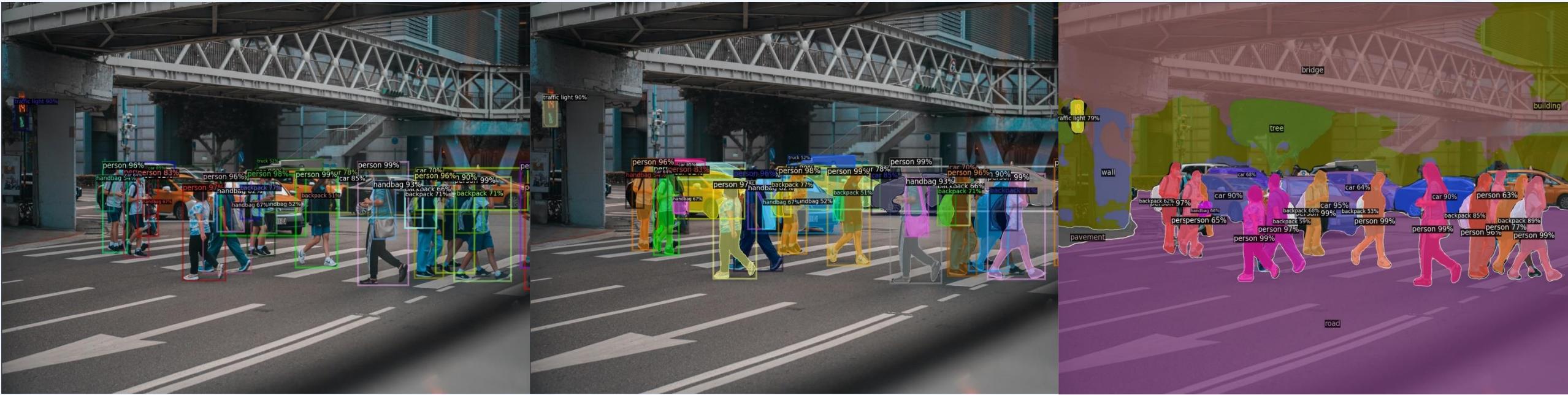
- classic and state-of-the art algorithms

## Pretrained Models

- fair benchmarks and out-of-the-box tools

# History of development

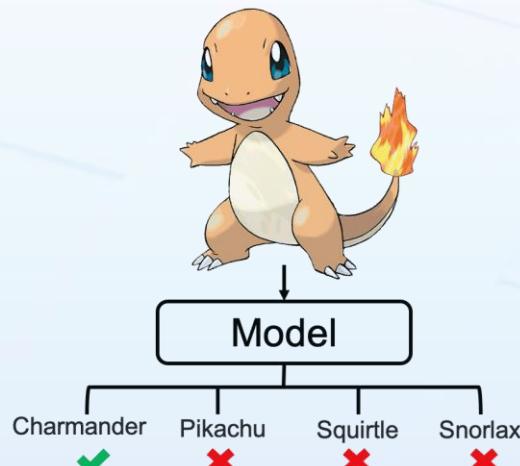




Object Detection

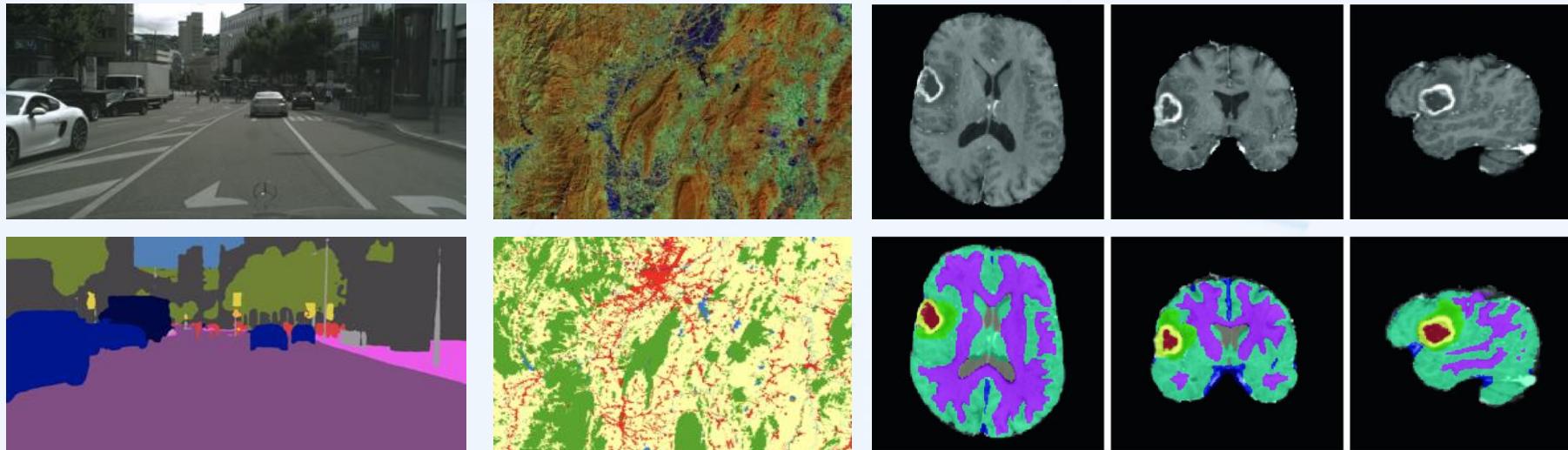
Instance Segmentation

Panoptic Segmentation



## Representative models

VGG	ResNet	ResNeXt ShuffleNet	ResNeSt RegNet	ViT Swin Transformer	ConvNeXt MobileOne
2014	2015	2017	2020	2021	2022
40+ backbones		mainstream datasets		rich training recipes	



Self-driving

Remote sensing

Medical image analysis

## Model zoo

400+ models

30+ algorithms

## Modular design

configurable

extensible

## Standard benchmark

ablation study

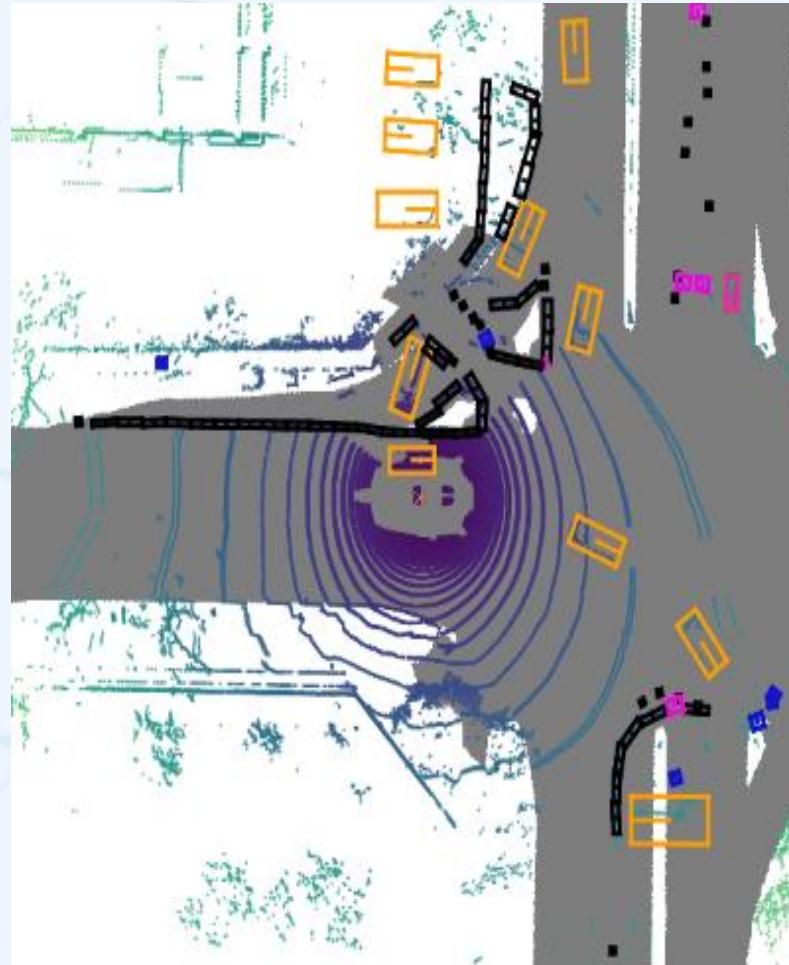
fair comparison

## Usage

training

testing

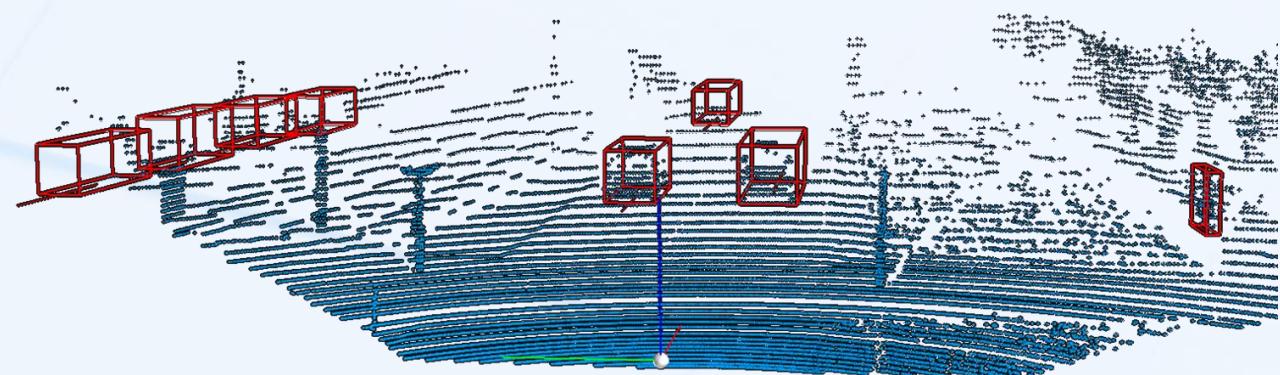
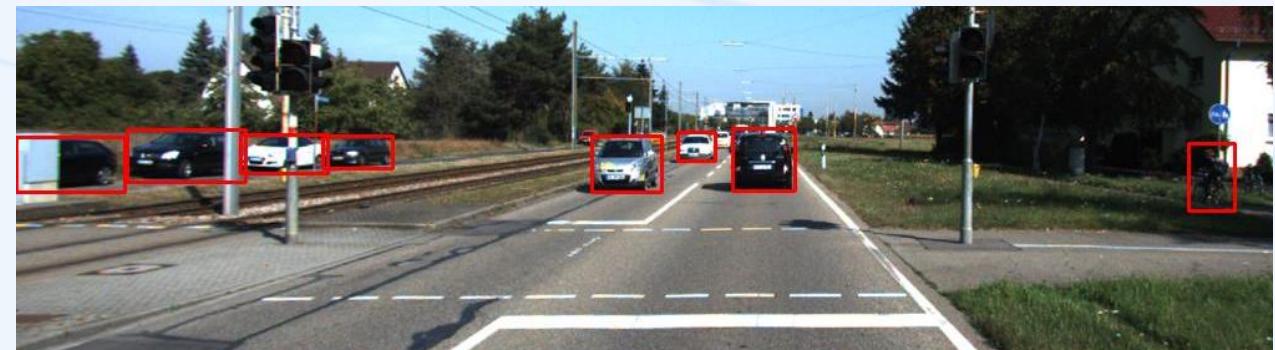
inference API



7 datasets

17 algorithms

80+ models



## Text detection

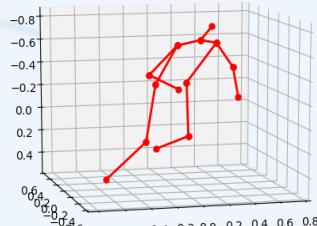


## Text recognition



## Key information extraction

	Others(0.98)	Others(1.00)
Prod_item_value(0.75)	Prod_item_value(0.97)	Prod_price_value(0.97)
Prod_item_value(0.97)	Prod_item_value(0.97)	Prod_price_value(0.99)
Prod_item_value(0.98)	Prod_item_value(0.98)	Prod_price_value(1.00)
Prod_item_value(0.82)	Prod_item_value(0.82)	Others(0.54)
Prod_item_value(1.00)	Prod_item_value(1.00)	Prod_price_value('1.00') Prod_price_value(1.00)
Prod_item_value(1.00)	Prod_item_value(1.00)	Prod_price_value(1.00)
Prod_item_value(1.00)	Prod_item_value(1.00)	Prod_price_value(1.00)
Prod_item_value(0.86)	Prod_item_value(0.86)	Prod_price_value(1.00)
Prod_item_value(1.00)	Prod_item_value(1.00)	Prod_price_value(1.00)
Prod_item_value(0.67)	Prod_item_value(0.67)	Prod_price_value(1.00)
Prod_item_value(1.00)	Prod_item_value(1.00)	Prod_price_value(1.00)
Prod_item_value(0.98)	Prod_item_value(0.98)	Prod_price_value(0.95)
SubTotal_key(0.99)	SubTotal_value(1.00)	Others(1.00)
Tax_key(1.00)	Tax_value(0.99)	Subtotal_value(1.00)
Total_key(0.99)	Total_value(0.99)	Tax_value(0.99)
Others(0.94)	Others(1.00)	TotalValue(0.99)
Others(1.00)	Others(1.00)	Others(0.87)



image/video



body/face/hand



part



output

Mesh/keypoints

dim

input

2D/3D





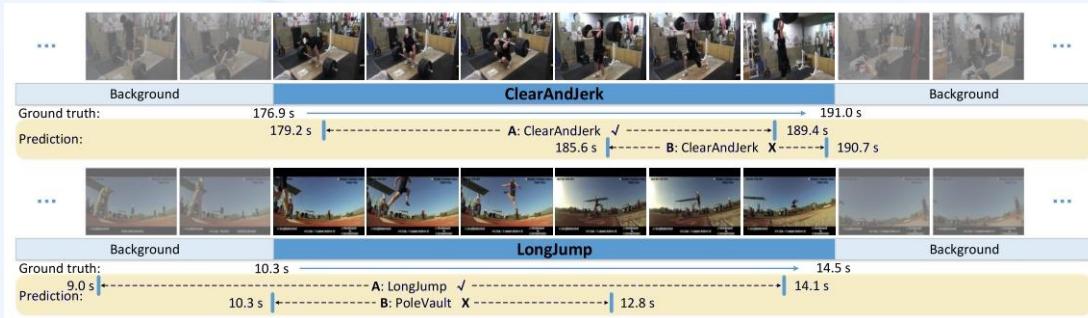
## Action recognition

### Tasks

recognition

localization

spatio-temporal



## Action localization

### Algorithms

200+ models

20+ algorithms

### Performance

faster training

higher accuracy

## Spatio-temporal action detection

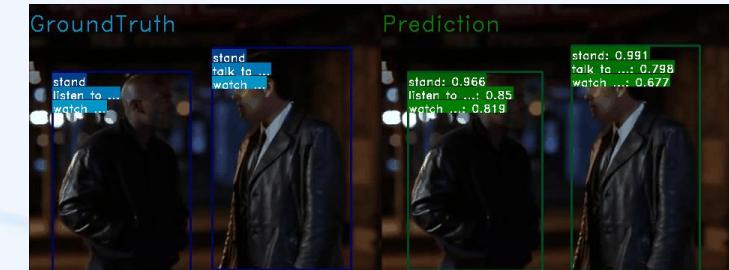
### Functionality

training

testing

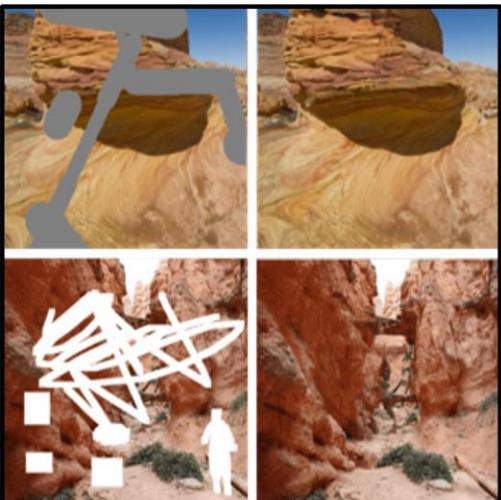
inference api

multiple IO backends





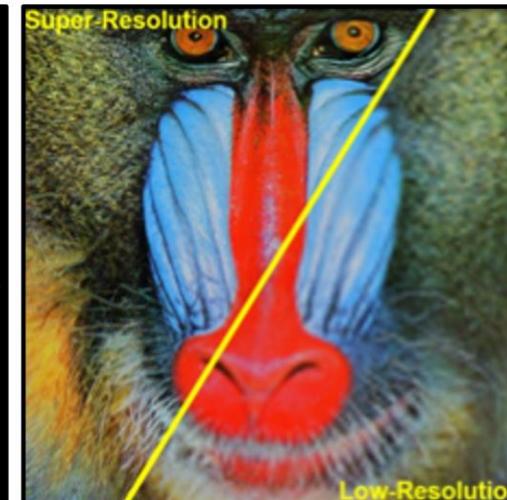
Inpainting



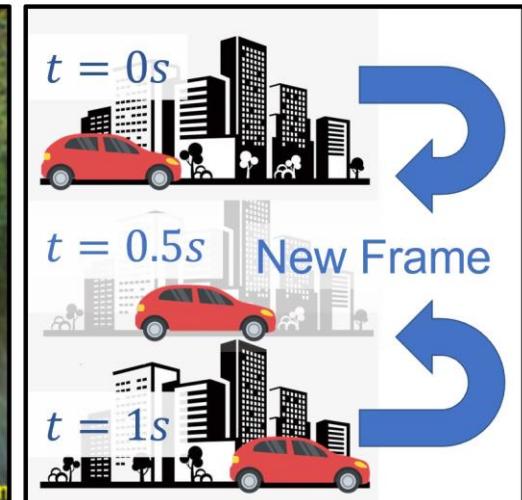
Matting



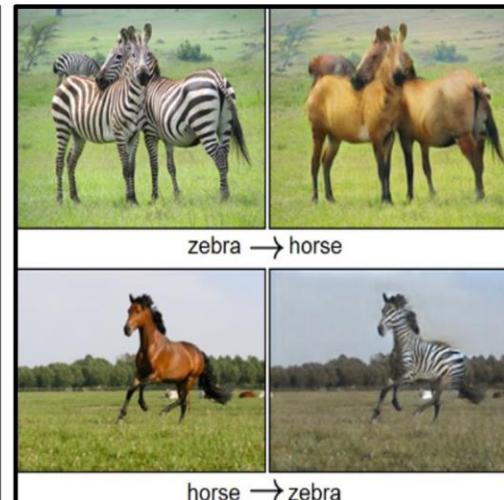
Super Resolution



Frame Interpolation



Translation



## Text to image



"a hedgehog using a calculator"



"a corgi wearing a red bowtie and a purple party hat"



"robots meditating in a vipassana retreat"



"a fall landscape with a small cottage next to a lake"



"a surrealist dream-like oil painting by salvador dali of a cat playing checkers"



"a professional photo of a sunset behind the grand canyon"



"a high-quality oil painting of a psychedelic hamster dragon"



"an illustration of albert einstein wearing a superhero costume"

## 3D aware generation



# From Research to Production

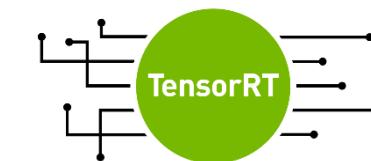
Training Framework

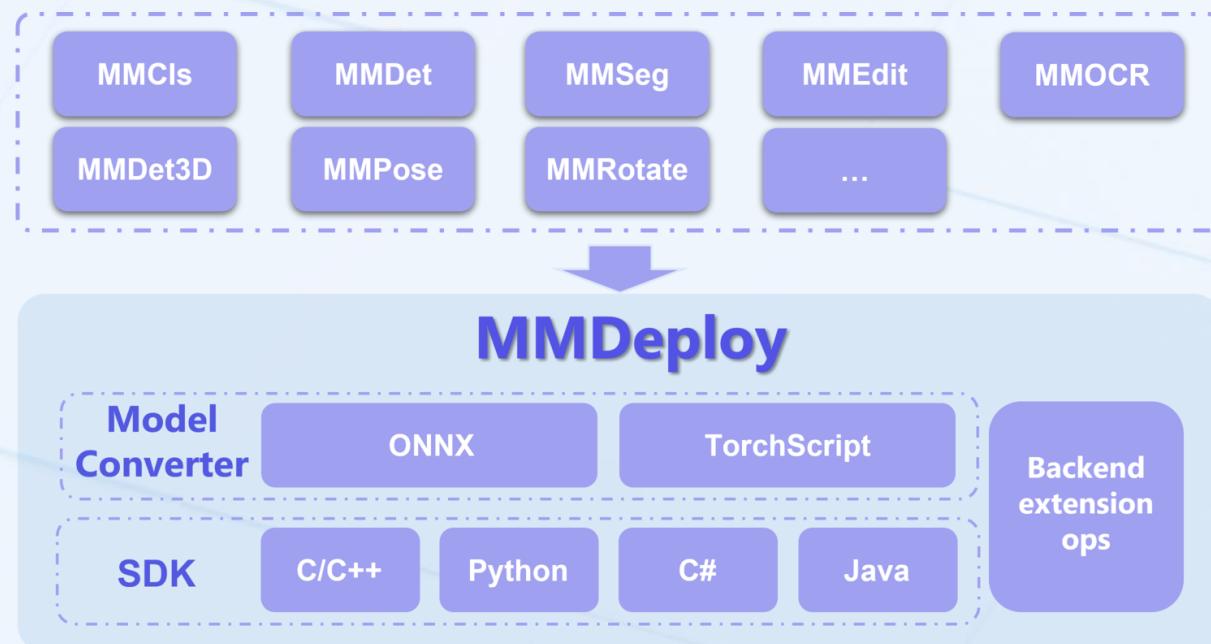


Intermediate Representation  
(IR)



Inference Engine





## Various inference engines

TensorRT、ONNXRuntime、OpenVINO、ncnn、libtorch、PPL.NN

## Multiple platforms

Linux、Windows、Android、macOS

## Multiple language support

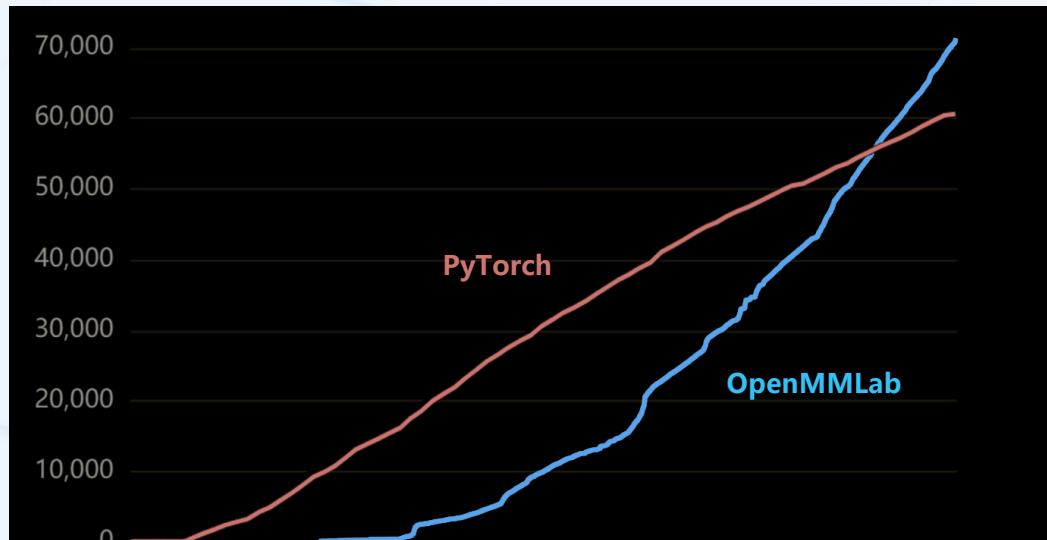
C/C++、Python、Java、C#

## Flexible integration to production system

IR models、Inference engine models、MMDeploy SDK

# Community Impact

## Users



- 70000+ GitHub stars (overall)
- 1000+ contributors from 40+ countries

## Academic

**1000+** papers adopted OpenMMLab

- Swin Transformer (ICCV 2021 best paper)
- EPro-PnP (CVPR 2022 best student paper)
- BeiT (ICLR 2022, 600+ citations)
- ConvNeXt (CVPR 2022, 700+ citations)
- SegFormer (NeurIPS 2021, 800+ citations)

**20+** challenge winners adopted OpenMMLab

- COCO 2018/2019
- LVIS 2021
- Waymo 2022
- NTIRE 2021/2022

# Benefits of adopting OpenMMLab

## Unified architecture

Learn once, use everywhere; implement once, use everywhere

## Unified benchmark

Provide fair baselines for academic research

## Modular design

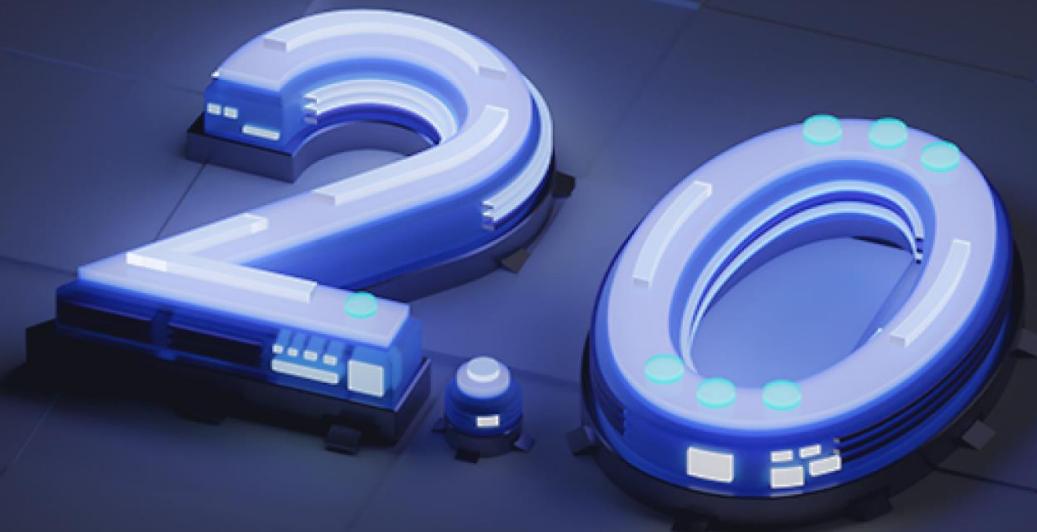
Fast to develop and try new components

## High-quality Implementation

Efficient, high performance, good code style

# Basic Usage

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# Contents

- Installation
- Inference with Pre-trained models
- Model training, testing and deployment
- Understand config files and internal mechanism
- Customization

# Installation

---

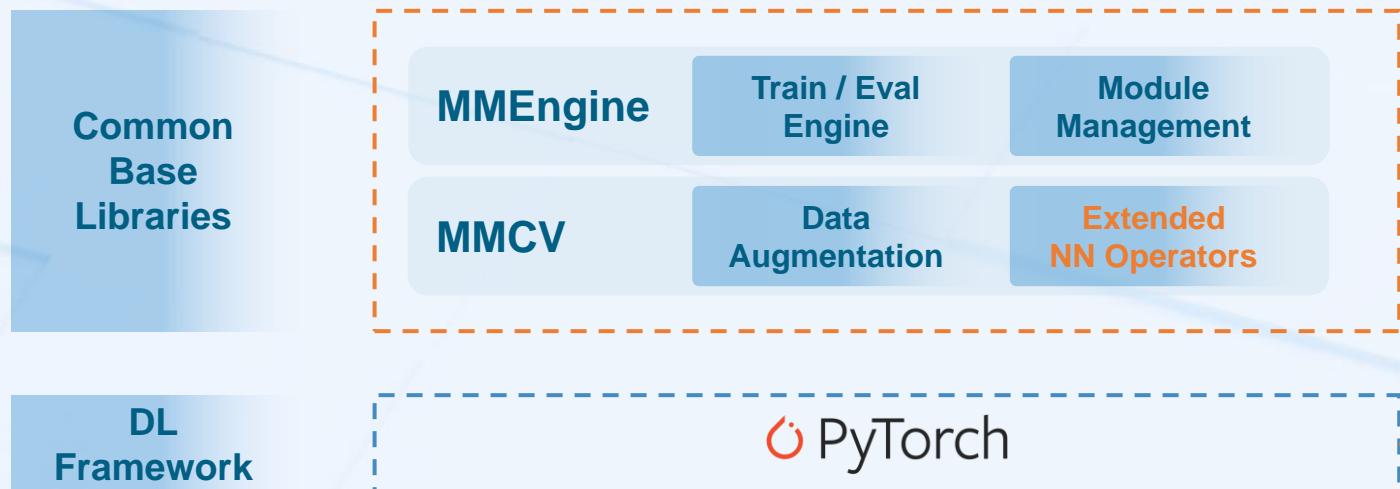


# Structures of OpenMMLab Tool System



E.g. Installing MMDetection require installing MMEngine and MMCV (also PyTorch) as dependencies.

Pure Python Packages



# Compatibility of MMCV

C/CUDA extension of MMCV should be **compiled** with the **same CUDA version** of as PyTorch

To simplify this process:

1. We provides pre-built packages of MMCV
2. We developed `mim` (**MIM Install OpenMMLab**) to detect and install the correct version of MMCV

```
# Suppose PyTorch is correctly setup
# install openmim to install other OpenMMLab packages
pip install openmim
# mim will detect the version of PyTorch and CUDA
# and download corresponding pre-built MMCV to install
mim install "mmcv>=2.0.0rc0" ←
# pip is unaware of the CUDA version of PyTorch
# will trigger compilation and takes lots of time
# (NOT recommended)
pip install "mmcv>=2.0.0rc0"
```

- Make sure specifying `>=2.0.0rc0` to install the new version
- MMEngine will be installed as dependencies 😊

# Install Other Packages

MIM can be used to install other OpenMMLab packages and solve internal dependencies as well

```
# Option 1
# Install directly using MIM
# More convenient if you don't plan to modify the source codes
mim install "mmcls>=1.0.0rc0" "mmdet>=3.0.0rc"
```

We also recommend installing from the source

```
# Option 2
# Install from source codes
# Modifying source codes are easier
# Make sure to checkout to the version 2.0 architecture branch
git clone -b 1.x https://github.com/open-mmlab/mmclassification.git

cd mmclassification
mim install -e .          # -e: editable mode
                           # enable in-place code modification without reinstallation
```

# Verify Installation

```
import mmcv
import mmcv.ops

print(mmcv.__version__)
# Output 2.0.0rc3
print(mmcv.ops.get_compiling_cuda_version())
# Output: 11.6
# Should match the CUDA version of pytorch, otherwise cause runtime error

import mmcls
print(mmcls.__version__)
# Output: 1.0.0rc5

import mmdet
print(mmdet.__version__)
# Output: 3.0.0rc5
```

# Note on the Version

**Note:** Up to now, OpenMMLab 2.0 toolboxes are all release candidates

Need explicitly specifying the version number, otherwise old versions will be installed

**Note:** OpenMMLab 2.0 is an overall name, it does NOT mean the exact version of every toolbox is 2.0

Exact version of commonly used packages are:

	OpenMMLab 1.0	OpenMMLab 2.0
MMEngine	N/A	mmengine
MMCV	mmcv-full	"mmcv>=2.0.0rc0"
MMClassification	mmcls	"mmcls>=1.0.0rc0"
MMDetection	mmdet	"mmdet>=3.0.0rc0"

# Note on the Version

If install from source, check the correct version or branch on GitHub

- Existing toolboxes has both 1.0 and 2.0 variant
- Recently developed toolboxes has only 2.0 variant

The image displays two GitHub repository interfaces side-by-side, illustrating the evolution of architecture versions.

**Left Repository: mmdetection3d**

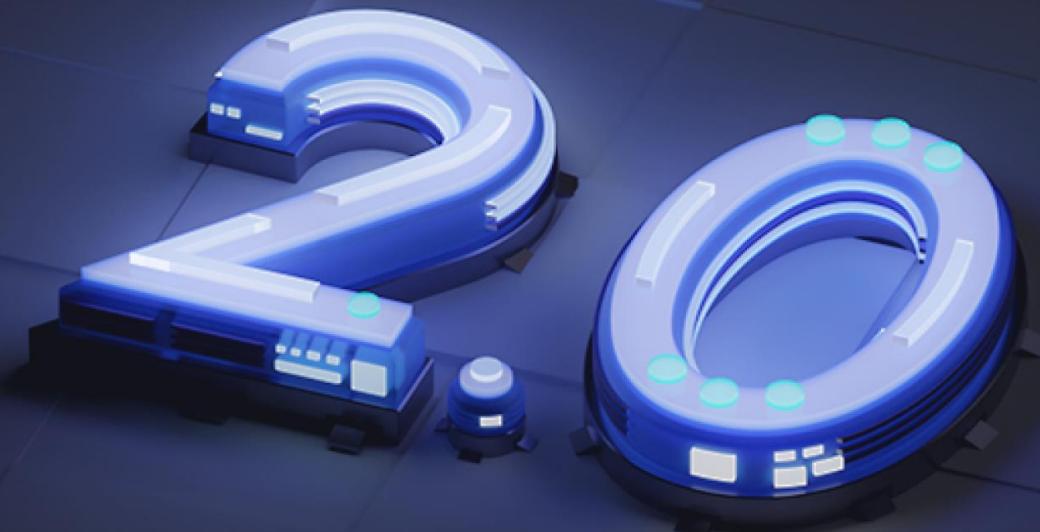
- Branch Selection: The dropdown shows "1.1".
- Branch List:
  - master → 1.0 architecture
  - master (default)
  - ✓ 1.1 → 2.0 architecture
  - coord\_sys\_refactor

**Right Repository: mmyolo**

- Branch Selection: The dropdown shows "main".
- Branch List:
  - main → 2.0 architecture
  - dev
  - yolov5\_seg

# Inference

---



# Inference with Pre-trained Models

OpenMMLab implements 300+ CV models and provides 2300+ pre-trained models weights with SOTA performance.

## 4 steps for inference

1. Select a model from the **model zoo**
2. Download the **config file** and the **checkpoint file**
3. Write some Python codes to **initialize the model and perform inference**
4. (Optional) visualize the results

# 1. Select from the Model Zoo

Full list of supported models are organized under the config directory of each repository.

A bunch of pre-trained weights for each model

Every pre-trained weights is associated with:

- A **config file**: includes the definition of model structure
- A **checkpoint file**: storing learned weights
- Metrics and training log for reference

The screenshot shows the GitHub repository `open-mmlab/mmdetection` at the `3.x` branch. The `mmdetection/configs/rtmdet/` directory is highlighted with a dashed orange box. Inside this box, several files are listed, with the last four labeled as 'Config files': `rtmdet-ins_l_8xb32-300e_coco.py`, `rtmdet-ins_m_8xb32-300e_coco.py`, `rtmdet-ins_s_8xb32-300e_coco.py`, and `rtmdet-ins_tiny_8xb32-300e_coco.py`. A yellow box highlights the text 'Config files'.

**RTMDet: An Empirical Study of Designing Real-Time Object Detectors**

**Abstract**

In this paper, we aim to design an efficient real-time object detector that exceeds the YOLO series and is easily extensible for many object recognition tasks such as instance segmentation and rotated object detection. To obtain a

**Results and Models**

Object Detection								Pre-trained Models and reported metrics	
Model	size	box AP	Params(M)	FLOPS(G)	TRT-FP16-Latency(ms)	Config	Download	Model	Log
RTMDet-tiny	640	41.1	4.8	8.1	0.98	<a href="#">config</a>	<a href="#">model   log</a>		
RTMDet-s	640	44.6	8.89	14.8	1.22	<a href="#">config</a>	<a href="#">model   log</a>		
RTMDet-m	640	49.4	24.71	39.27	1.62	<a href="#">config</a>	<a href="#">model   log</a>		
RTMDet-l	640	51.5	52.3	80.23	2.44	<a href="#">config</a>	<a href="#">model   log</a>		
RTMDet-x	640	52.8	94.86	141.67	3.10	<a href="#">config</a>	<a href="#">model   log</a>		

## 2. Download the Config file and Checkpoint file

### Option 1: Download with MIM

```
$ mim download mmdet --config rtmddet_s_8xb32-300e_coco --dest .
```

Downloading

<a href="#">rtmddet_l_8xb32-300e_coco.py</a>	[Feature] Support RTMDet-Ins and improve RTMDet test config. (#9494)
<a href="#">rtmddet_m_8xb32-300e_coco.py</a>	[Feature] Release RTMDet models and configs. (#8870)
<a href="#">rtmddet_s_8xb32-300e_coco.py</a>	[Feature] Support imagenet pre-training for RTMDet's backbone. (#8887)
<a href="#">rtmddet_tiny_8xb32-300e_coco.py</a>	[Feature] Support imagenet pre-training for RTMDet's backbone. (#8887)
<a href="#">rtmddet_x_8xb32-300e_coco.py</a>	[Feature] Release RTMDet models and configs. (#8870)

```
$ ls .
```

```
rtmddet_s_8xb32-300e_coco_20220905_161602-387a891e.pth ←  
rtmddet_s_8xb32-300e_coco.py ←
```

Model	size	box AP	Params(M)	FLOPS(G)	TRT-FP16-Latency(ms)	Config	Download
RTMDet-tiny	640	41.1	4.8	8.1	0.98	<a href="#">config</a>	<a href="#">model   log</a>
RTMDet-s	640	44.6	8.89	14.8	1.22	<a href="#">config</a>	<a href="#">model   log</a>
RTMDet-m	640	49.4	24.71	39.27	1.62	<a href="#">config</a>	<a href="#">model   log</a>
RTMDet-l	640	51.5	52.3	80.23	2.44	<a href="#">config</a>	<a href="#">model   log</a>
RTMDet-x	640	52.8	94.86	141.67	3.10	<a href="#">config</a>	<a href="#">model   log</a>

### Option 2: Manually from hyperlinks

### 3. Python API for Inference

Some Python codes to perform inference

```
from mmdet.utils import register_all_modules
from mmdet.apis import init_detector, inference_detector

# Necessary for registries to work, will introduce details later
register_all_modules()

# model is an nn.Module object
model = init_detector('rtmdet_s_8xb32-300e_coco.py',
                      'rtmdet_s_8xb32-300e_coco_20220905_161602-387a891e.pth',
                      device='cuda:0')

# Load Image -> Preprocess -> Forward the model
# Images as numpy.array are also acceptable
result = inference_detector(model, 'bench.jpg')
```

result is a data structure containing all detection boxes



Applies to ALL OpenMMLab toolboxes with possible difference on function names, e.g. `init_model`.

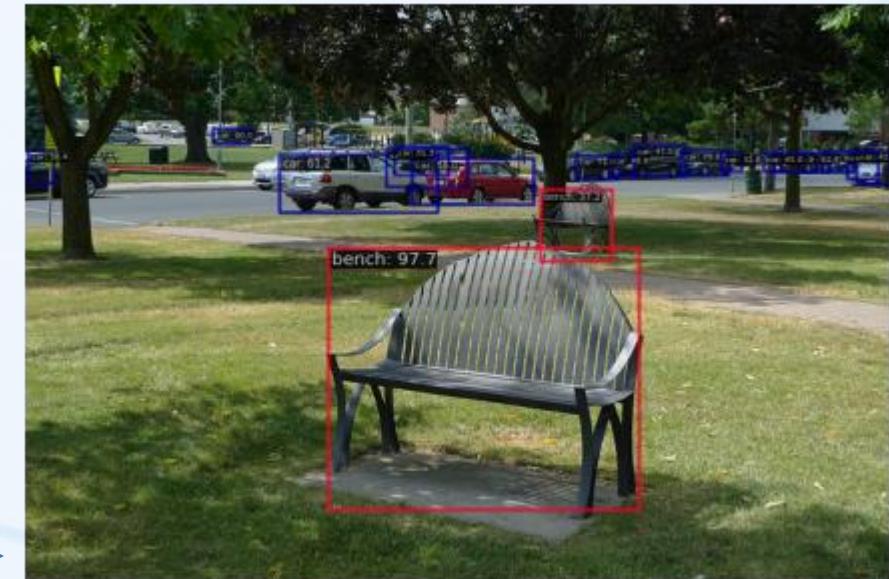
## 4. Visualize the result

Some toolboxes also provide utilities to visualize the results.

```
from mmdet.registry import VISUALIZERS
import mmcv

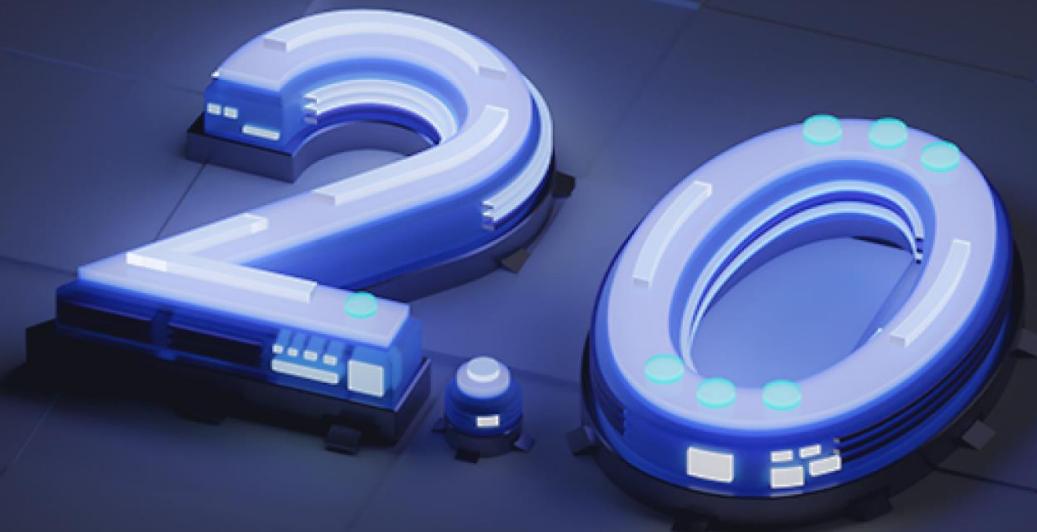
# init the visualizer(execute this only once)
visualizer = VISUALIZERS.build(model.cfg.visualizer)
visualizer.dataset_meta = model.dataset_meta
# the dataset_meta is loaded from the checkpoint and
# then pass to the model in init_detector

img = mmcv.imread('bench.jpg', channel_order='rgb')
# show the results
visualizer.add_datasample(
    'result',
    img,
    data_sample=result,
    draw_gt=False,
    wait_time=0,
)
visualizer.show() —————→
```



# Training

---



# Reproduce Training

Most of pre-trained models are trained by OpenMMLab toolboxes themselves.

Only a small fraction of models are converted from other source and support inference only.

To reproduce training, one need to:

1. Prepare the dataset
2. Launch the training with the config file

E.g. ImageNet for classification, COCO for detection, small dataset such as MNIST and CIFAR can be downloaded automatically.

```
# Option 1
python tools/train.py configs/lenet/lenet5_mnist.py
```

```
# Option 2
mim train mmcls configs/lenet/lenet5_mnist.py
```

The same config we used in inference

It defines everything (not only the model) required to launch training, including the model, dataset, learning algorithm, etc.

# Collect Results

During training, **logs** and **checkpoints** are automatically saved under a **working directory**.

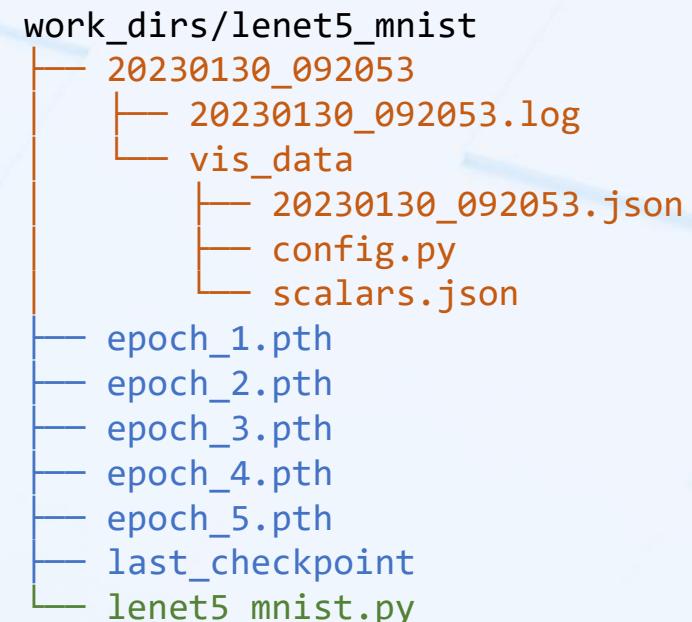
It is by default `work_dirs` under the current working directory.

Note: If train multiple times, checkpoints are **overwritten** to save space.  
Logs are separately saved with data time prepend.

Training logs &  
Visualization

Checkpoints

A copy of the config



Manually specify working directories

```
python tools/train.py ${CONFIG_FILE} --work-dir ${NEW_WORK_DIR}
```

# Evaluation / Testing

Once get trained model, we can evaluate the model and compute performance metrics.

```
python tools/test.py ${CONFIG_FILE} ${CHECKPOINT_FILE} [--out ${RESULT_FILE}] [--show]
```

Found in the working directory

Also defines data used to test the model

Alternative: test with MIM

```
mim test mmcls ${CONFIG_FILE} --checkpoint ${CHECKPOINT_FILE} [other arguments]
```

See `python tools/test.py -h` for more available options for each toolbox

# Distributed Training / Testing

Distributed training / testing

```
./tools/dist_train.sh ${CONFIG_FILE} ${GPU_NUM} [optional arguments]
```

```
./tools/dist_test.sh ${CONFIG_FILE} ${CHECKPOINT_FILE} ${GPU_NUM} [optional arguments]
```

Distributed training with Slurm task manager

```
[GPUS=${GPUS}] ./tools/slurm_train.sh ${PARTITION} ${JOB_NAME} \
${CONFIG_FILE} [optional arguments]
```

```
[GPUS=${GPUS}] ./tools/slurm_test.sh ${PARTITION} ${JOB_NAME} \
${CONFIG_FILE} ${CHECKPOINT_FILE} [optional arguments]
```

Reference:

[https://github.com/open-mmlab/mmdetection/blob/3.x/tools/dist\\_train.sh](https://github.com/open-mmlab/mmdetection/blob/3.x/tools/dist_train.sh)

[https://github.com/open-mmlab/mmdetection/blob/3.x/tools/slurm\\_train.sh](https://github.com/open-mmlab/mmdetection/blob/3.x/tools/slurm_train.sh)

# Distributed Training

Alternative: using MIM

```
mim train mmcls [arguments passes to tools/train.py] --gpus 4 --launcher pytorch
```

Alternative: using MIM with slurm

```
mim train mmcls [arguments passes to tools/train.py] --gpus 8 \
--gpus-per-node 8 --partition partition_name --launcher slurm
```

# Learning Rate Auto Scaling

## The Linear Scaling Rule:

To use difference number of GPUs, one need to scale learning rate proportional to total batch size

$$[\text{Total batch size}] = [\text{Batch size on single GPU}] \times [\text{Number of GPUs}]$$

Most provided configs are tuned on 8 GPU servers.

Need to tune the learning rate based on actual number of GPUs.

We support automatic learning rate scaling the with one additional argument

```
python tools/train.py ${CONFIG_FILE} --auto-scale-lr [optional arguments]
```

# More Options for Training

Resume training from existing checkpoints

```
python tools/train.py ${CONFIG_FILE} --resume work_dirs/lenet5_mnist/epoch_4.pth
```

Automatic mixed precision training

```
python tools/train.py ${CONFIG_FILE} --amp
```

Check `python tools/train.py -h` for more available options for each toolbox

# Dataset Customization

It is very common to train models based on users own dataset.

We offer two options to accomplish this:

## **Option 1:** Convert the dataset offline

- Convert the dataset to a standard format, e.g. ImageNet format for classification or COCO format for detection.
- Easier, existing codes work on organized data
- No modification to source codes, only some modification on dataset meta (e.g. class names) in config files.

# Dataset Customization

It is very common to train models based on users own dataset.

We offer two options to accomplish this:

## **Option 2:** Implement a new dataset class

- Requires to write some codes to read and parse your dataset.
- More modification to the config file.
- Generally more efficient, no requirement on offline storage.

# Model Deployment

For production purpose, deploy model to target device to make computation more efficient

MMDeploy toolbox supports convert model to different backends.

**Example:** The following command convert a YOLO v3 model to TensorRT backend.

```
python ./tools/deploy.py \
    configs/mmdet/detection/detection_tensorrt_dynamic-320x320-1344x1344.py \
    $PATH_TO_MMDET/configs/yolo/yolov3_d53_mstrain-608_273e_coco.py \
    $PATH_TO_MMDET/checkpoints/yolo/yolov3_d53_mstrain-608_273e_coco.pth \
    $PATH_TO_MMDET/demo/demo.jpg \
    --work-dir work_dir \
    --show \
    --device cuda:0
```

A deployment config

Config and checkpoints of a model

# MMDeploy Usage Example

```
python tools/deploy.py \
    mmdeploy/configs/mmdet/detection/detection_tensorrt_dynamic-320x320-1344x1344.py \
    mmdetection/configs/retinanet/retinanet_r50_fpn_1x_coco.py \
    retinanet_r50_fpn_1x_coco_20200130-c2398f9e.pth \
    mmdetection/demo/demo.jpg \
    --work-dir retinanet/tensorrt \
    --device cuda:0 \
    --dump-info
```

RetinaNet

Model Converter

MMDeploy Model

MMDeploy SDK



retinanet/tensorrt  
└── deploy.json  
└── detail.json  
└── end2end.engine  
└── end2end.onnx  
└── output\_pytorch.jpg  
└── output\_tensorrt.jpg  
└── pipeline.json

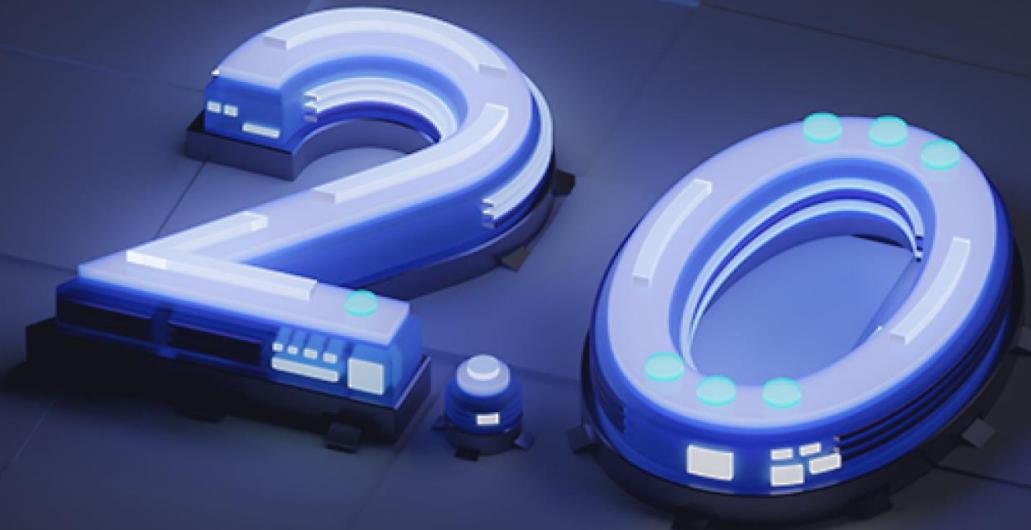
```
from mmdeploy_python import Detector
import cv2

model_path='retinanet/tensorrt'
image_path='mmdetection/demo/demo.jpg'
img = cv2.imread(image_path)
detector = Detector(model_path=model_path,
                     device_name='cuda',
                     device_id=0)
bboxes, labels, _ = detector(img)
```



# Config Files

---



# Components of a Config File

A **Config file** contains a bunch of key-value pairs, organized in python format.

It defines all items required to train and/or test a model.

4 major parts:

- **Model** structure
- **Dataset**, data augmentation and dataloader
- **Optimizer** and learning rate policies
- **Runtime** configs
  - Working directory, logs, checkpoints, visualizations
  - Multi-processing / distributed training environment
  - Random seeds

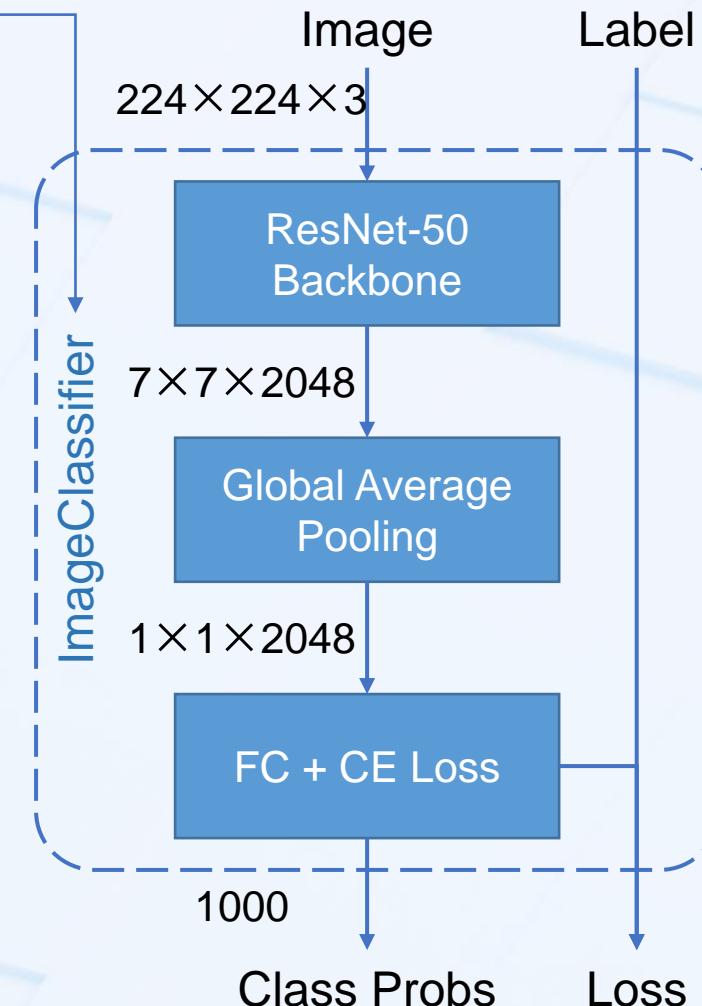
Config files in OpenMMLab are usually in **py** format, while **json/yaml** are also supported.

# The Model

```
model = dict(  
    type='ImageClassifier',  
    backbone=dict(  
        type='ResNet',  
        depth=50,  
        num_stages=4,  
        out_indices=(3, ),  
        style='pytorch'),  
    neck=dict(type='GlobalAveragePooling'),  
    head=dict(  
        type='LinearClsHead',  
        num_classes=1000,  
        in_channels=2048,  
        loss=dict(type='CrossEntropyLoss', loss_weight=1.0),  
        topk=(1, 5),  
    ))
```

The **type** key specify the type of the model

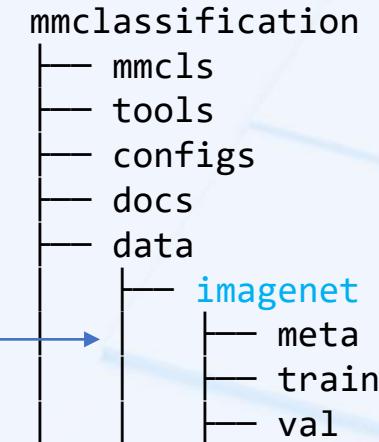
Nested key-value pairs define submodules in the model.



# Dataset and Dataloader

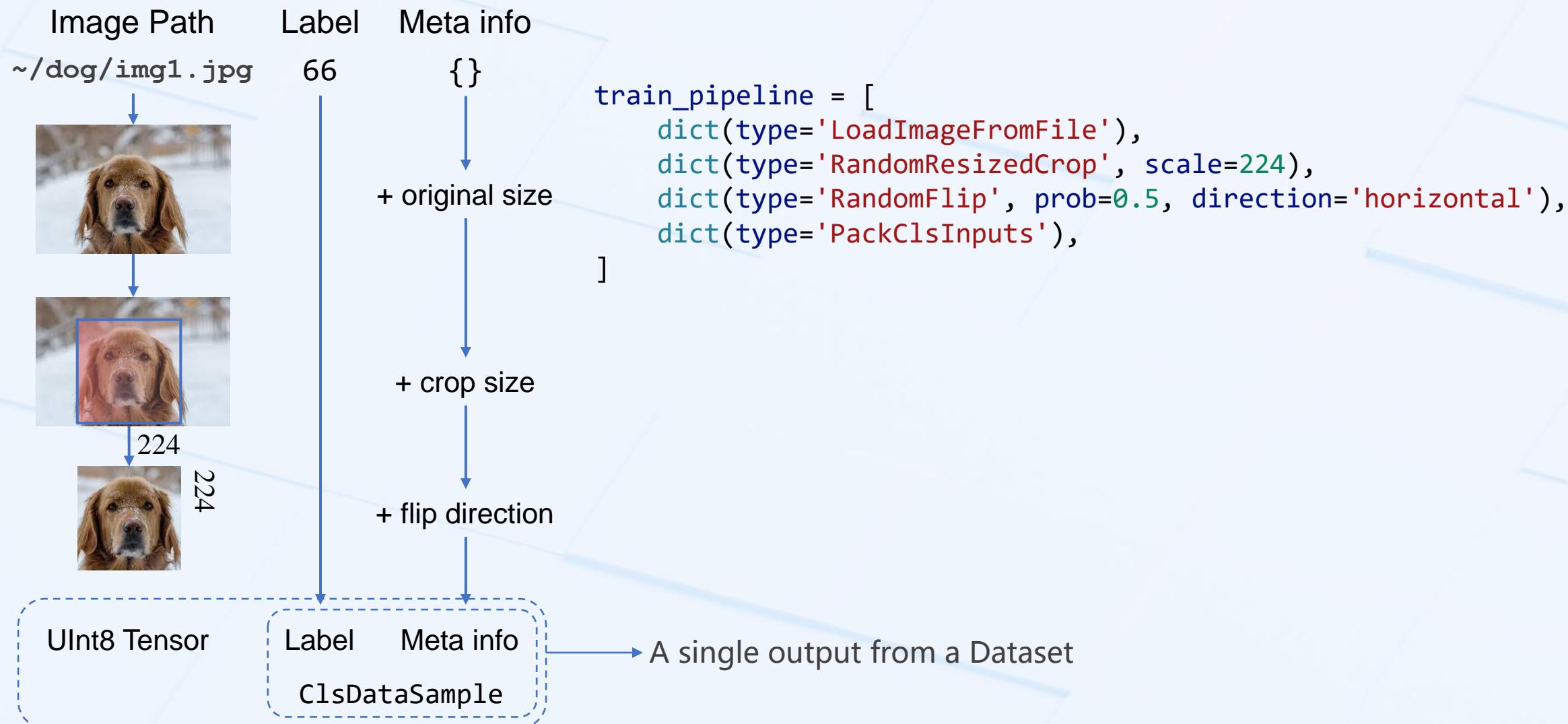
```
train_dataloader = dict(    Also validation and test loaders  
    batch_size=32,  
    num_workers=5,  
    dataset=dict(  
        type='ImageNet',  
        data_root='data/imagenet',  
        ann_file='meta/train.txt',  
        data_prefix='train',  
        pipeline=[  
            dict(type='LoadImageFromFile'),  
            dict(type='RandomResizedCrop', scale=224),  
            dict(type='RandomFlip', prob=0.5, direction='horizontal'),  
            dict(type='PackClsInputs'),  
        ],  
        sampler=dict(type='DefaultSampler', shuffle=True),  
    )
```

Dataset subkey specifies data paths and a pre-processing pipeline

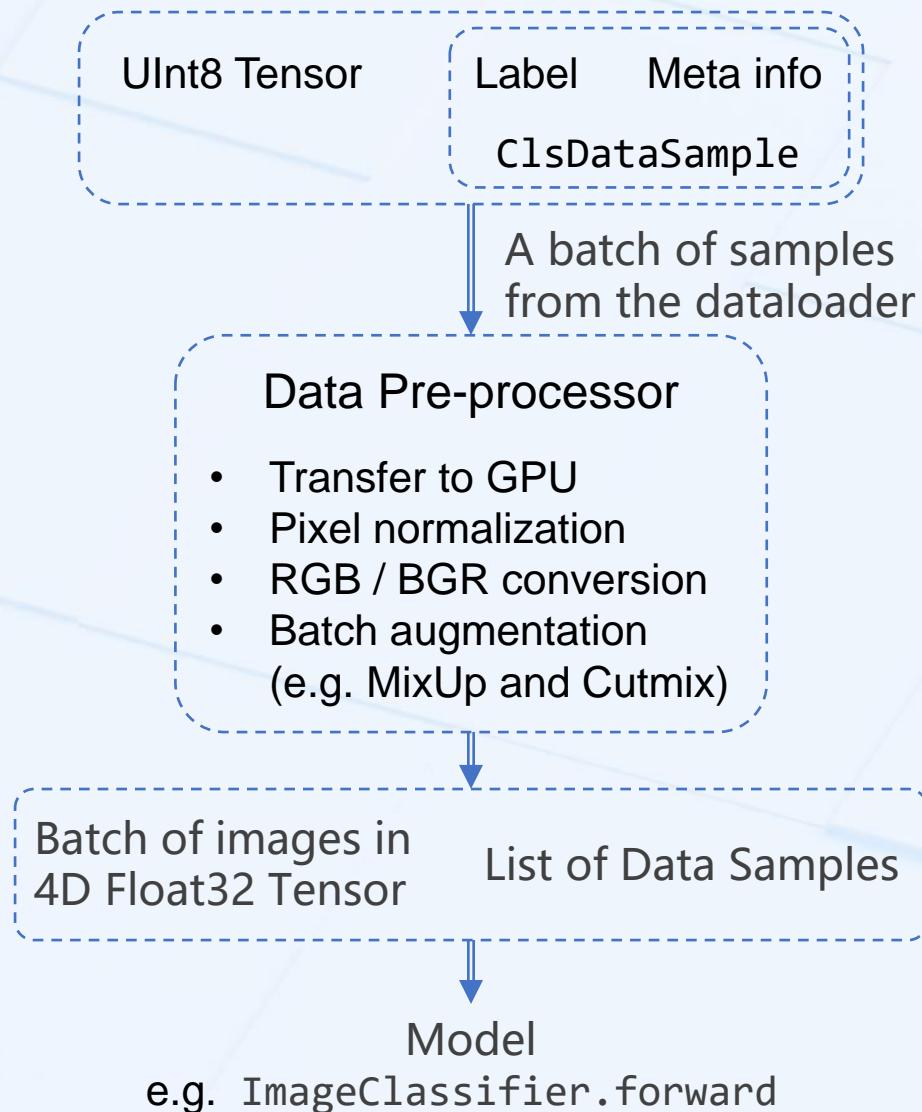


→ Arguments are aligned with PyTorch

# Data Pre-processing Pipeline (within dataloader)



# Data Pre-processing Pipeline (from dataloader to model)



```
data_preprocessor = dict(  
    num_classes=1000,  
    # RGB format normalization parameters  
    mean=[123.675, 116.28, 103.53],  
    std=[58.395, 57.12, 57.375],  
    # convert image from BGR to RGB  
    to_rgb=True,  
)
```

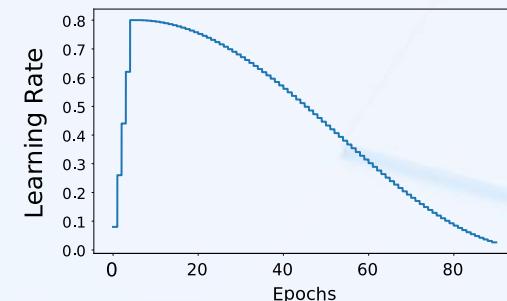
# Optimizer and Learning Rate Schedulers

```
# optimizer
optim_wrapper = dict(
    optimizer=dict(type='SGD', lr=0.8, momentum=0.9, weight_decay=5e-5))

# learning policy
param_scheduler = [
    dict(type='LinearLR', start_factor=0.1, by_epoch=True, begin=0, end=5),
    dict(type='CosineAnnealingLR', T_max=95, by_epoch=True, begin=5, end=100)
]

# train, val, test setting
train_cfg = dict(by_epoch=True, max_epochs=100, val_interval=1)
val_cfg = dict()
test_cfg = dict()

# NOTE: `auto_scale_lr` is for automatically scaling LR,
# based on the actual training batch size.
auto_scale_lr = dict(base_batch_size=1024)
```



# Runtime Configs

```
# configure default hooks
default_hooks = dict(
    # record the time of every iteration.
    timer=dict(type='IterTimerHook'),

    # print log every 100 iterations.
    logger=dict(type='LoggerHook', interval=100),

    # enable the parameter scheduler.
    param_scheduler=dict(type='ParamSchedulerHook'),

    # save checkpoint per epoch.
    checkpoint=dict(type='CheckpointHook', interval=1),

    # set sampler seed in distributed environment.
    sampler_seed=dict(type='DistSamplerSeedHook'),

    # validation results visualization, set True to enable it.
    visualization=dict(type='VisualizationHook', enable=False),
)
```

Interval of outputting log and saving checkpoints

The unit of interval can be epoch or iteration, by setting by\_epoch=True/False

We will cover more on hooks later.

# Runtime Configs

```
# set visualizer
vis_backends = [dict(type='LocalVisBackend')]
visualizer = dict(type='ClsVisualizer', vis_backends=vis_backends)

# set log level
log_level = 'INFO'

# load from which checkpoint
load_from = None
# whether to resume training from the loaded checkpoint
resume = False
# Defaults to use random seed and disable `deterministic`
randomness = dict(seed=None, deterministic=False)
```

Initialize model from other pre-trained weights  
No optimizer states

Resume from checkpoints (e.g. interrupted accidentally)  
Recover optimizer state too

# Runtime Configs

```
# configure environment
env_cfg = dict(
    # whether to enable cudnn benchmark
    cudnn_benchmark=False,
    # set multi process parameters
    mp_cfg=dict(mp_start_method='fork', opencv_num_threads=0),
    # set distributed parameters
    dist_cfg=dict(backend='nccl'),
)
```

Items configuring distributed environment

# Summary: 4 major parts of a config file

A Config file contains all items required to define a specific **experiment**, including 4 major parts:

- The structure of the model
- Data
  - Dataset used for training / validating / testing the model
  - Data pre-processing pipelines and data pre-processor
  - Dataloader parameters such as batch size, prefetch workers, etc.
- Optimizer and learning rate policies
- Runtime configs
  - Logs, checkpoints, visualizations
  - multi-processing / distributed training parameters
  - Random seeds

# Using Intermediate Variable in Configs

```
train_dataloader = dict(  
    batch_size=32,  
    num_workers=5,  
    dataset=dict(  
        type='ImageNet',  
        data_root='data/imagenet',  
        ann_file='meta/train.txt',  
        data_prefix='train',  
        pipeline=train_pipeline),  
    sampler=dict(type='DefaultSampler', shuffle=True),  
)
```

When written in **Python**, config files support reusing **variable** just like writing Python scripts.

- More clear file structure
- Reuse same items

```
train_pipeline = [  
    dict(type='LoadImageFromFile'),  
    dict(type='RandomResizedCrop', scale=224),  
    dict(type='RandomFlip', prob=0.5, direction='horizontal'),  
    dict(type='PackClsInputs'),  
]
```

# Inheritance of Config

Imagine training the same model using different optimizers.

The model part shares, but rewriting every item is obviously redundant.

A minimal example

```
resnet50.py:  
  
model = dict(type='ResNet', depth=50)  
optimizer = dict(type='SGD', lr=0.01)
```

```
optimizer_cfg.py  
  
_base_ = ['resnet50.py']  
optimizer = dict(type='Adam')
```

Equivalent to a merged config

Items already in `_base_` will be updated

```
optimizer_cfg.py  
  
optimizer = dict(type='Adam', lr=0.02)  
model = dict(type='ResNet', depth=50)
```

# Inheritance of Config

With inheritance, configs in OpenMMLab toolboxes are usually organized as a series of **base configs** and experiment configs inherited from these base configs.

## Base Configs

```
mmclassification/configs/_base_
├── datasets
└── models
```

## Config for specific experiment

```
mmclassification/configs/resnet/resnet50_8xb32_in1k.py
_base_ = [
    '../_base_/models/resnet50.py',
    '../_base_/datasets/imagenet_bs32.py',
    '../_base_/schedules/imagenet_bs256.py',
    '../_base_/default_runtime.py'
]
(If any) additional items
(If any) modification of base configs
```

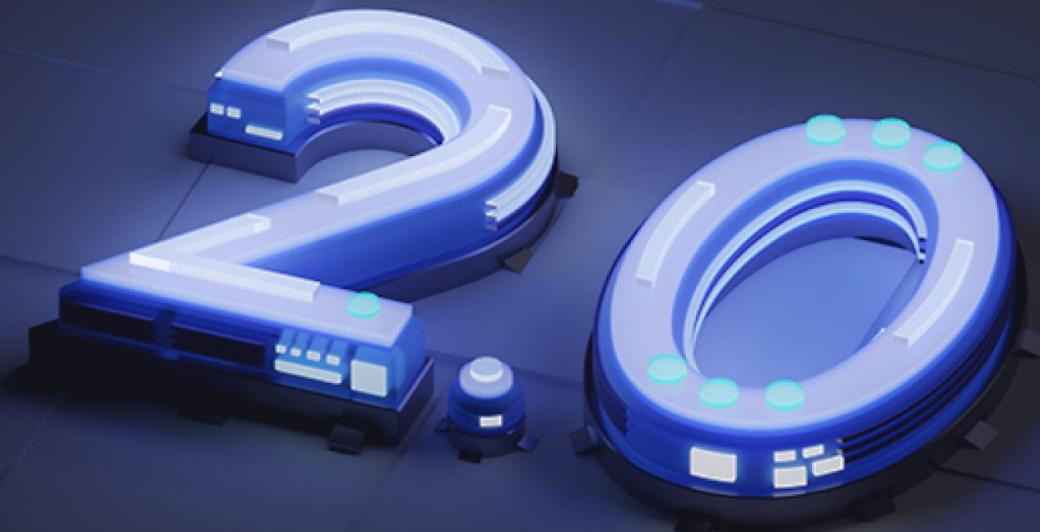
# Summary

A Config file contains all items required to define an **experiment**, including 4 major parts:

- The structure of the model
  - Data
  - Optimizer and learning rate policies
  - Runtime configs
- 
- Config files in Python support intermediate variables
  - Config files support inheritance, toolboxes organize base configs under config/\_base\_ directory

# Internal Mechanism

---



# How Config Works

## The config

```
model = dict(  
    type='ImageClassifier',  
    backbone=dict(  
        type='ResNet',  
        depth=50,  
        num_stages=4,  
        out_indices=(3, ),  
        style='pytorch'),  
    neck=dict(type='GlobalAveragePooling'),  
    head=dict(  
        type='LinearClsHead',  
        num_classes=1000,  
        in_channels=2048,  
        loss=dict(type='CrossEntropyLoss', loss_weight=1.0),  
        topk=(1, 5),  
    ))
```

from str to type

## The actual implementation in codebase

```
mmcls/models/classifiers/image.py  
  
class ImageClassifier(BaseClassifier):  
    def __init__(self,  
        backbone: dict,  
        neck: Optional[dict] = None,  
        head: Optional[dict] = None,  
        pretrained: Optional[str] = None,  
        train_cfg: Optional[dict] = None,  
        data_preprocessor: Optional[dict] = None,  
        init_cfg: Optional[dict] = None):
```

pass as arguments

Nested modules will be recursively instantiated within ImageClassifier.

# How Config Works

```
model = dict(  
    type='ImageClassifier',  
    backbone=dict(  
        type='ResNet',  
        depth=50,  
        num_stages=4,  
        out_indices=(3, ),  
        style='pytorch'),  
    neck=dict(type='GlobalAveragePooling'),  
    head=dict(  
        type='LinearClsHead',  
        num_classes=1000,  
        in_channels=2048,  
        loss=dict(type='CrossEntropyLoss', loss_weight=1.0),  
        topk=(1, 5),  
    ))
```

Instantiate recursively  
in ImageClassifier

```
from mmcls.models.resnet import ResNet
```

```
backbone = ResNet(  
    depth=50,  
    num_stages=4,  
    out_indices=(3, ),  
    style='pytorch'  
)
```

# Config and Registry

Registry is essentially a mapping from class name to the class itself.

MODEL is a specific registry containing all models. There are also other registries.

Model definition in codebase

```
mmcls/models/resnet.py

@MODELS.register_module
class ResNet(nn.Module):
    def __init__(self, depth, **kwargs)
    ...
...
```

Registered in the Registry

```
MODELS Registry: Mapping[str, type]
{
    "ResNet": mmcls.models.resnet.ResNet
    "mobilenet": ...
}
```

Fetch the class by type name  
Instantiate based on arguments

```
from mmengine.registry import MODELS

model = MODELS.build({
    "type": "ResNet"
    "depth": 50})
# This is equivalent to
model = ResNet(depth=50)
```

**Note:** To make the registry work, we need to register all classes into the registry. This is why we need to call `register_all_modules()` in inference part.

# Use Component from Other Toolboxes

Registry allows using modules from other toolboxes.

A config in MMDetection

```
model = dict(
    backbone=dict(
        _delete_=True,
        type='mmcls.ConvNeXt',
        arch='tiny',
        out_indices=[0, 1, 2, 3],
        drop_path_rate=0.4,
        layer_scale_init_value=1.0,
        gap_before_final_norm=False,
        init_cfg=dict(
            type='Pretrained', checkpoint=checkpoint_file,
            prefix='backbone.')),
    neck=dict(in_channels=[96, 192, 384, 768]))
```

This backbone actually implemented in MMClassification

# The Runner ---- The Skeleton of the Program

## A typical PyTorch program

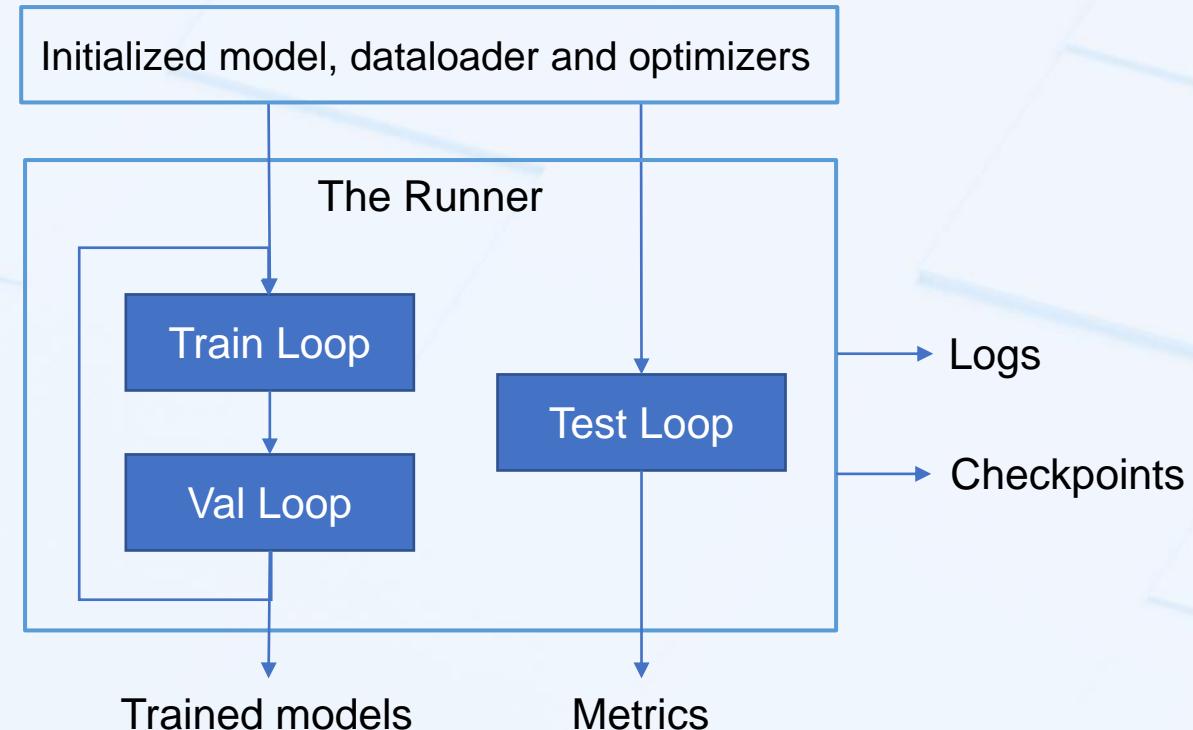
```
# First constructed model,
# dataloaders and optimizer
for _ in range(epochs):
    for data in train_loader:
        loss = model(*data)
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
    lr_scheduler.step()

    with torch.no_grad():
        for data in val_loader:
            pred = model(*data)
            metric = some_stats_of_all_preds

    with torch.no_grad():
        for data in test_loader:
            pred = model(*data)
            metric = some_stats_of_all_preds
```

Abstract

## The Runner in MMEngine



Decouple the framework and specific models and datasets:

- MMEngine implements the Runner
- Downstream toolboxes focus on models, data, etc.

More on Runner:

<https://mmengine.readthedocs.io/en/latest/design/runner.html>

<https://github.com/open-mmlab/mmengine/blob/main/mmengine/runner/runner.py>

# The Runner ---- The Skeleton of the Program

- The runner is essentially the *main* function of the program
- The config file specify the whole argument list to initialize the runner

The config file

```
class Runner:  
    def __init__(  
        self,  
        model: Union[nn.Module, Dict],  
        work_dir: str,  
        train_dataloader: Optional[Union[DataLoader, Dict]] = None,  
        val_dataloader: Optional[Union[DataLoader, Dict]] = None,  
        test_dataloader: Optional[Union[DataLoader, Dict]] = None,  
        train_cfg: Optional[Dict] = None,  
        val_cfg: Optional[Dict] = None,  
        test_cfg: Optional[Dict] = None,  
        auto_scale_lr: Optional[Dict] = None,  
        optim_wrapper: Optional[Union[OptimWrapper, Dict]] = None,  
        param_scheduler: Optional[Union[_ParamScheduler, Dict, List]] = None,  
        val_evaluator: Optional[Union[Evaluator, Dict, List]] = None,  
        test_evaluator: Optional[Union[Evaluator, Dict, List]] = None,  
        default_hooks: Optional[Dict[str, Union[Hook, Dict]]] = None,  
        custom_hooks: Optional[List[Union[Hook, Dict]]] = None,  
        data_preprocessor: Union[nn.Module, Dict, None] = None,  
        load_from: Optional[str] = None,  
        resume: bool = False,  
        launcher: str = 'none',  
        env_cfg: Dict = dict(dist_cfg=dict(backend='nccl')),  
        log_processor: Optional[Dict] = None,  
        log_level: str = 'INFO',  
        visualizer: Optional[Union[Visualizer, Dict]] = None,  
        default_scope: str = 'mmengine',  
        randomness: Dict = dict(seed=None),  
        experiment_name: Optional[str] = None,  
        cfg: Optional[ConfigType] = None,  
    ):
```

More on Runner:

<https://mmengine.readthedocs.io/en/latest/design/runner.html>

<https://github.com/open-mmlab/mmengine/blob/main/mmengine/runner/runner.py>

# Hooks

Hook = insert functions at specific locations of a program

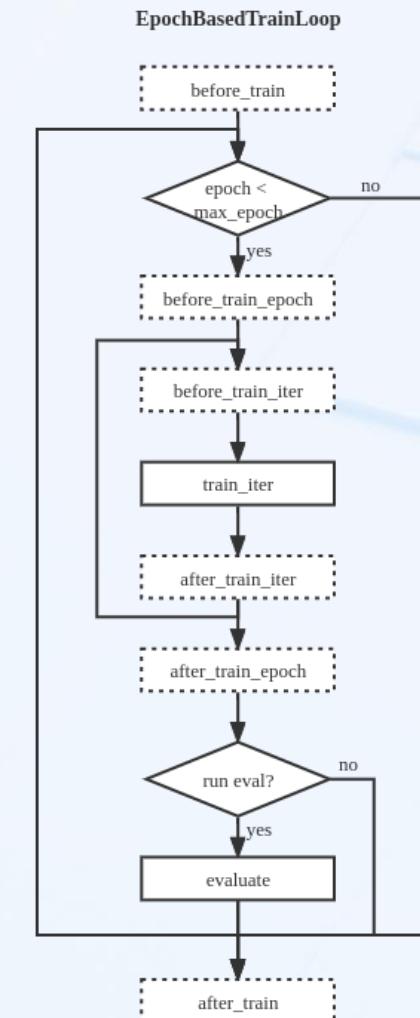
The runner support 20+ hook locations for users to customize.

Hook functions take the whole runner as argument, thus is very flexible.

MMEngine implements some default hooks, **for example**:

- CheckpointHook will be executed at after\_train\_epoch location. It fetch the model and the optimizer from the runner and save their state\_dict to disks.

User can also define their own hooks and set them into configs to make them work



Hook points at EpochBaseTrainLoop

Reference: <https://mmengine.readthedocs.io/en/latest/tutorials/hook.html>

[https://mmdetection.readthedocs.io/en/3.x/user\\_guides/useful\\_hooks.html?highlight=hook#how-to-implement-a-custom-hook](https://mmdetection.readthedocs.io/en/3.x/user_guides/useful_hooks.html?highlight=hook#how-to-implement-a-custom-hook)

# Learn More

Learn more internal design at MMEngine's documentation site:

<https://mmengine.readthedocs.io/en/latest/index.html>

## Tutorials [ - ]

- Runner
- Dataset and DataLoader
- Model
- Evaluation
- OptimWrapper
- Parameter Scheduler
- Hook

## Advanced tutorials [ - ]

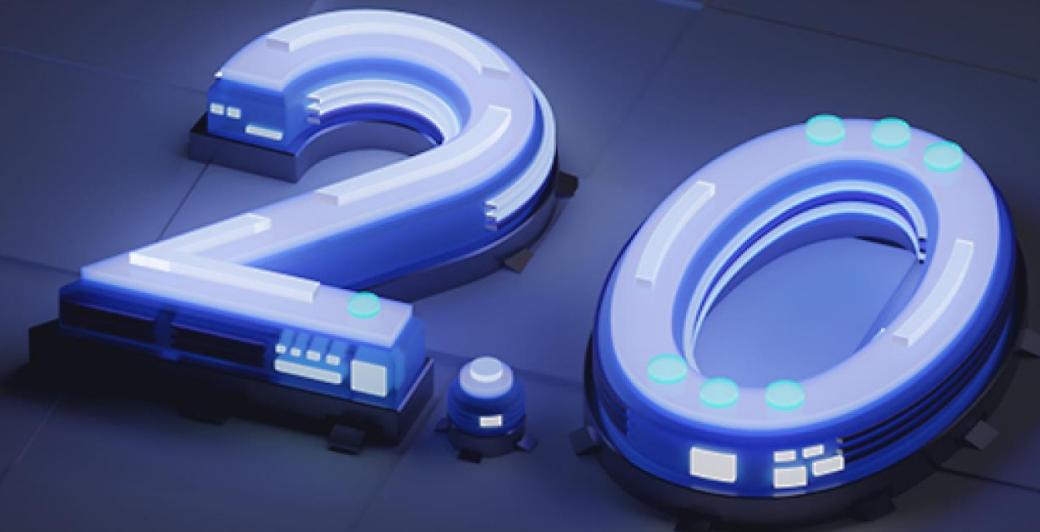
- Registry
- Config
- BaseDataset
- Data transform
- Weight initialization
- Visualization
- Abstract Data Element
- Distribution Communication
- Logging
- File IO
- Global manager (ManagerMixin)
- Use modules from other libraries
- Test time augmentation

## Design [ - ]

- Hook
- Runner
- Evaluation
- Visualization
- Logging
- Infer

# Customization

---



# General Idea

With registry, we can implement customized modules without modifying the original code base.

Existing implementation in codebase

```
mmcls/models/resnet.py

@MODELS.register_module
class ResNet(nn.Module):
    def __init__(self, depth, **kwargs)
    ...

```

The MODEL registry

```
MODELS Registry: Mapping[str, type]
{
    "ResNet": mmcls.models.resnet.ResNet
    "CustomModel": mymodule.CustomModel
}
```

The config

```
# model part of the config
model = dict(
    type='CustomModel',
    arg1=xxx,
    arg2=xxx),
```

Extensions by user

```
mymodule.py

@MODELS.register_module
class CustomModel(nn.Module):
    def __init__(self, arg1, arg2):
        pass
    def forward(self, x):
        pass
```

Remember the  
decorator

CustomModel will be found in the  
registry and be built in the runner

```
# Add this to config file
custom_imports = dict(
    imports=['mymodule'],
    allow_failed_imports=False)
```

Ensure mymodule under  
import paths, e.g. current  
working directory or  
PYTHONPATH

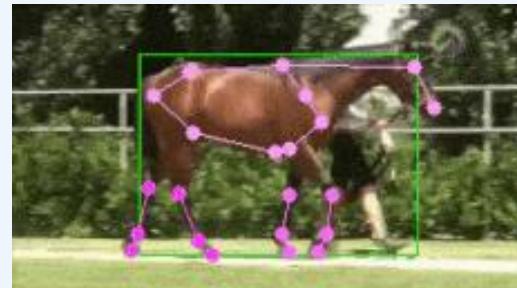
# Detailed Examples

Check our documentation site for more concrete example on customizing model, dataset, pipelines, optimizers, hooks and everything!

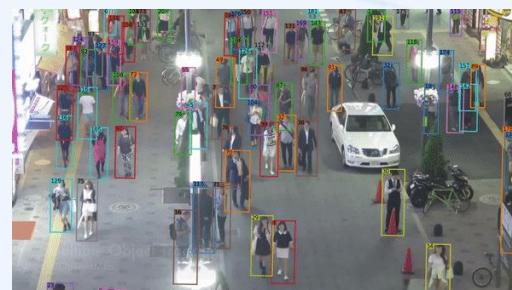
[https://mmdetection.readthedocs.io/en/3.x/advanced\\_guides/index.html#component-customization](https://mmdetection.readthedocs.io/en/3.x/advanced_guides/index.html#component-customization)

# More Examples and Tutorials

Check the demo folders of each toolbox for more examples!

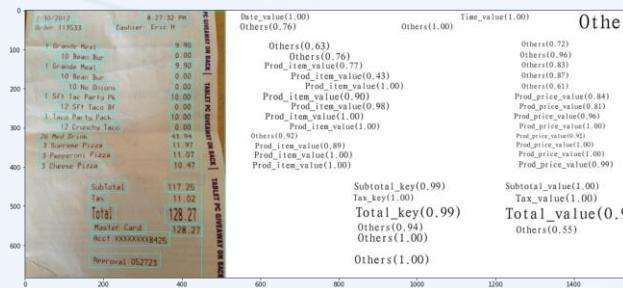


Animal pose



Tracking

Remember to checkout to the new branch



Key information extraction



Video super resolution

open-mmlab / mmpose Public

Code Issues 151 Pull requests 22 Discussions ...

1.x mmpose / demo /

This branch is 148 commits ahead, 90 commits behind master.

ly015 [Doc] fix api reference (#1792) ... ✓ on Nov 11, 2022 History

docs 2 months ago

mmdetection\_cfg 3 months ago

mmtracking\_cfg last year

resources last year

webcam\_cfg 2 months ago

MMPose\_Tutorial.ipynb 3 months ago

image\_demo.py 5 months ago

topdown\_demo\_with\_mmdet.py 3 months ago

topdown\_face\_demo.py 3 months ago

webcam\_demo.py 3 months ago

Thank you! Q&A

---

