

# Lab 3: Feature Detection and Matching

## CPV301

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# Table of Contents

## 1 Algorithms

## 2 Designing Application

## Harris Detector

Algorithm:

1. Compute Gaussian derivatives at each pixel
2. Compute second moment matrix  $M$  in a Gaussian window around each pixel
3. Compute corner response function  $R$
4. Threshold  $R$
5. Find local maxima of response function (nonmaximum suppression)

Figure: Harris Corner Detection

# HOG

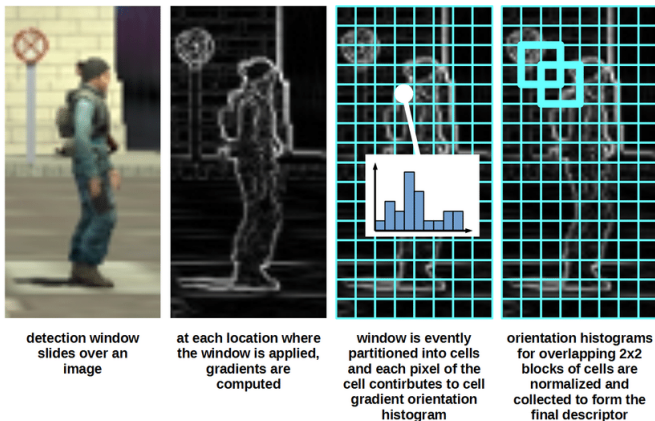


Figure: Histogram of Oriented Gradients

# Canny Operator

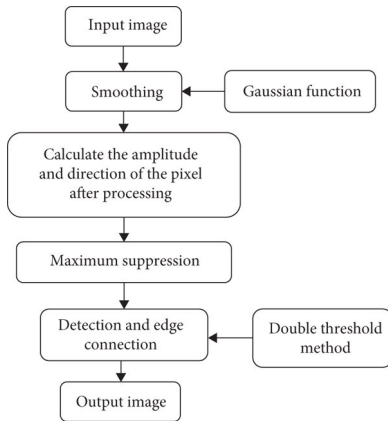


Figure: Process steps of Canny Operator

# Hough Transform

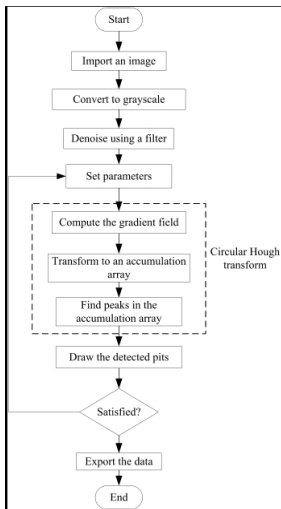


Figure: Process steps of Hough Transform

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# Dependencies

**Tkinter** is the library be chosen to design GUI for this app. It is the standard GUI library for Python. Tkinter provides a fast and easy way to create applications.





# Dependencies

[NumPy](#) is imported for mathematical calculations, matrices operations. And [OpenCV](#) and [Scikit-Image](#) are used for loading, processing and exporting images.



# Harris Corner Detection

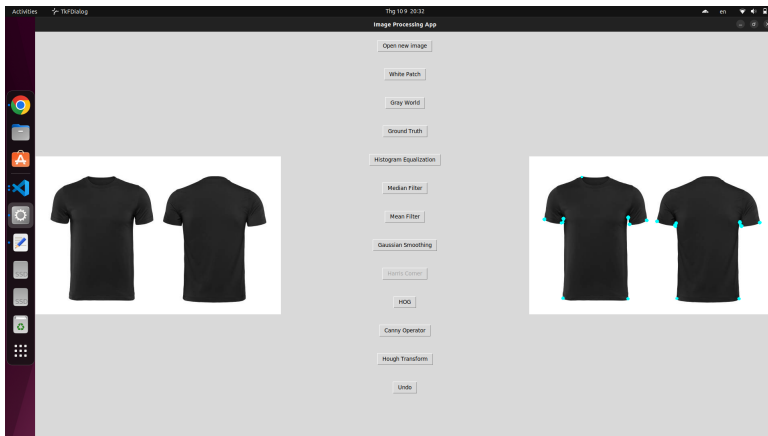


Figure: Harris Corner Detection

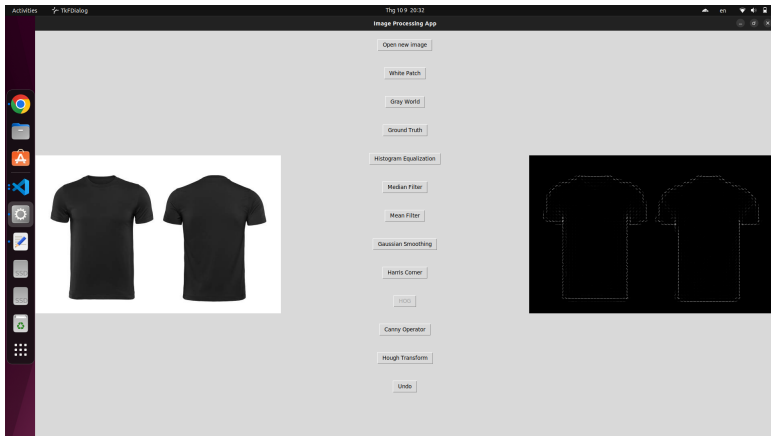


Figure: Histogram of Oriented Gradients

# Canny Operator

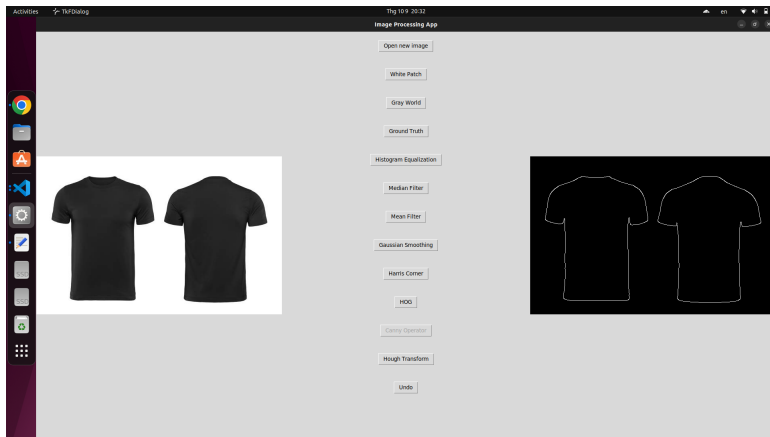


Figure: Canny Operator

# Hough Transform

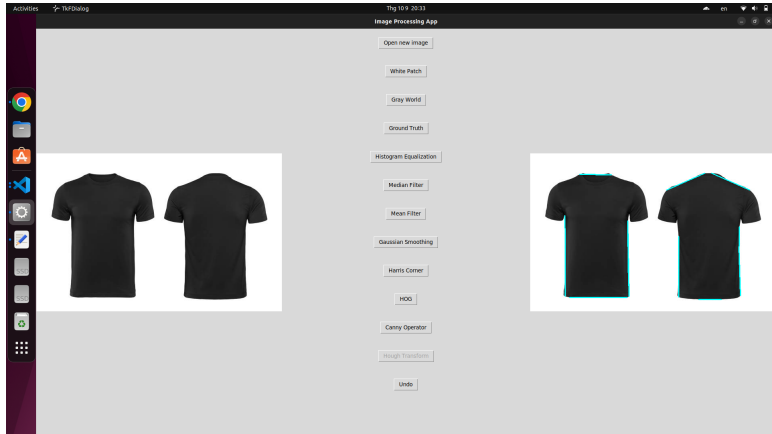


Figure: Hough Transform

After loading image, we can perform many effect on it. Each effect can only be used once, after using that button it will be disabled. We can undo the effects.

<https://github.com/hoanghai1803/CPV301/tree/main/lab3>

Thanks!

