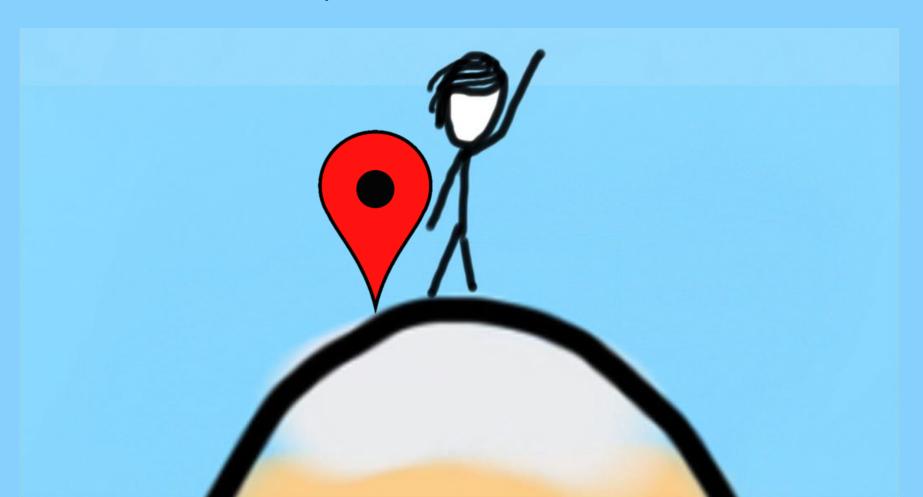


# Learning Goals

- 1. Calculate information gain
- 2. Make choices that maximize information gain
- 3. Numerically score how similar two distributions are



# **Uncertainty Theory**

Beta Distributions

Thompson Sampling

Adding Random Vars

Central Limit
Theorem

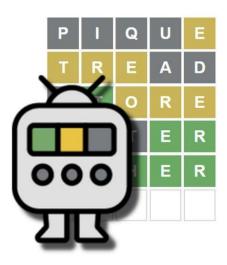
Sampling

Bootstrapping

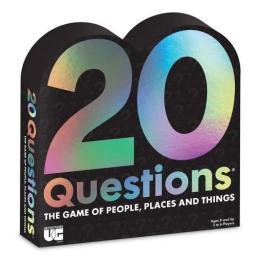
Algorithmic Analysis

Information Theory

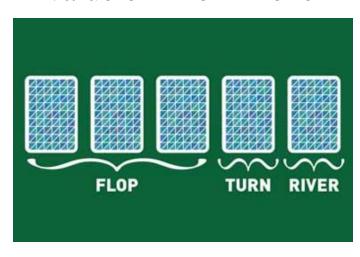
#### WorldeBot



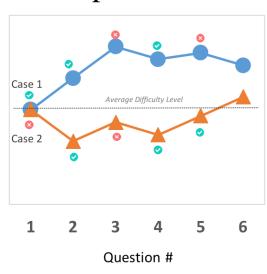
**Decision Trees** 



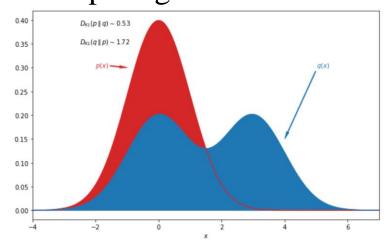
Value of Info in Poker



Adaptive Tests



**Comparing Distributions** 



Compression of Data



#### Plot Line



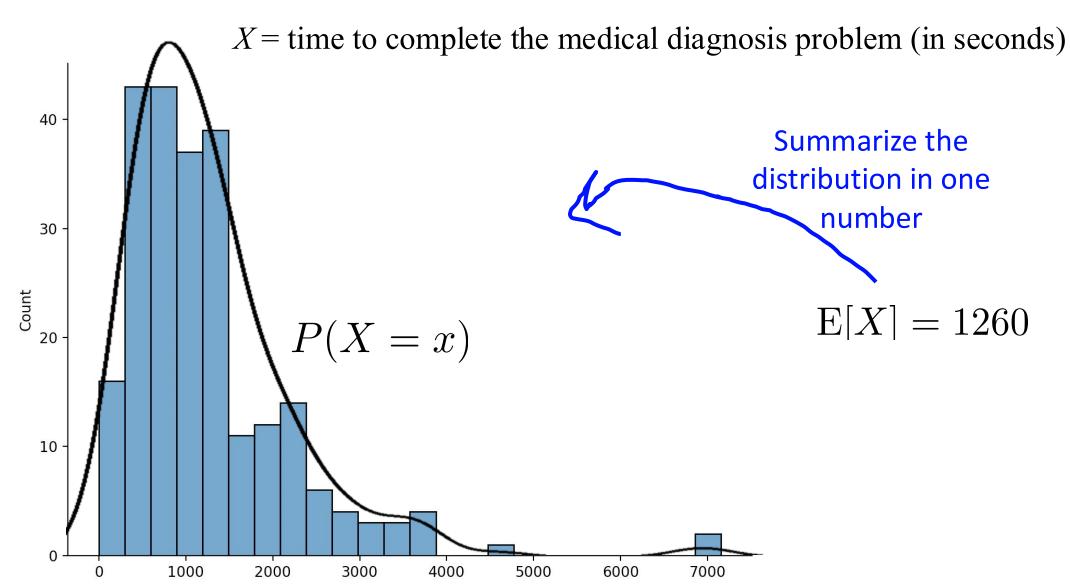
- 1. We want to chose questions in think of an animal (Let X be the animal random var)
- 2. Idea! Select the question which most reduces our "uncertainty" in X
- 3. We can measure "uncertainty" as "expected amount of surprise when we find out X"
- 4. We can measure "surprise" in an assignment as log 1/P(X=x)
- 5. This measure of uncertainty of X is super helpful for lots of problems!

# Review

#### Expectation

The probability that X takes on that value 
$$E[X] = \sum_{x} x \cdot P(X = x)$$
 All the values that X can take on

## Limitation of Expectation



#### Expectation of a Function

#### Law of unconscious statistician

$$E[g(X)] = \sum_{x} g(x) \cdot P(X = x)$$

So for example...

$$E[X^2] = \sum_{x} x^2 \cdot P(X = x)$$

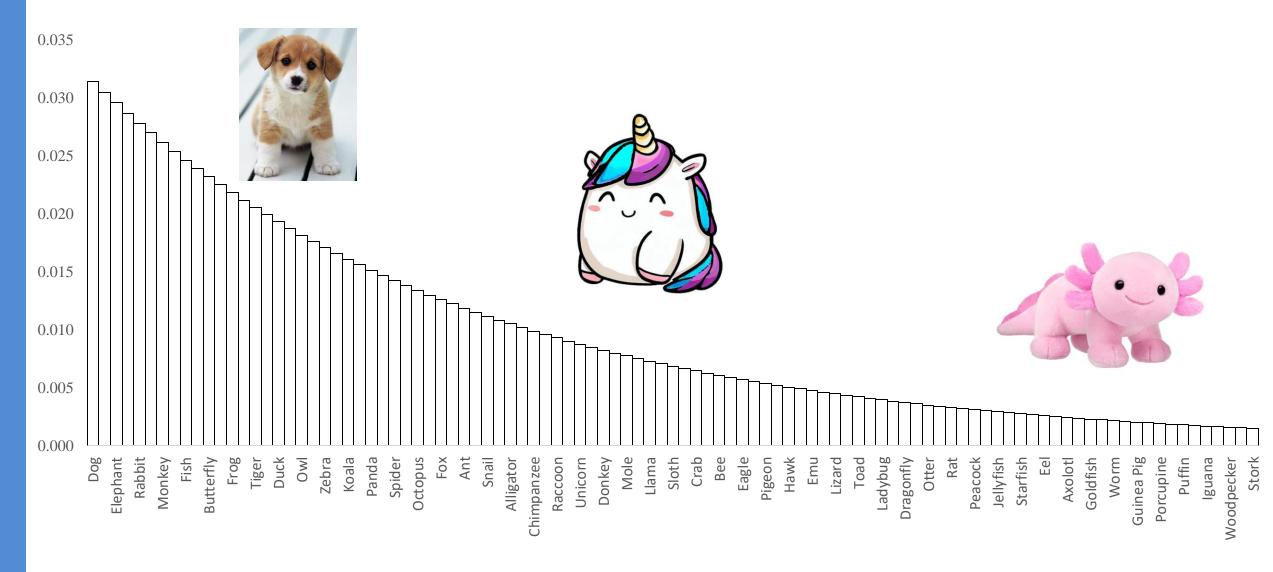
Def: Law of Total Expectation

$$E[X] = \sum_{y} E[X|Y = y]P(Y = y)$$

# **End Review**

# I am thinking of an animal...

## I am thinking of an animal



# What is the **best question** to ask?

## **Question Choosing Algorithms**

Algorithm	Average Questions	Standard Error of the Mean
Random Questions	61.34	1.41
Binary Search	6.79	0.02
Information Theory Search	5.33	0.04

5

Hey what's that?

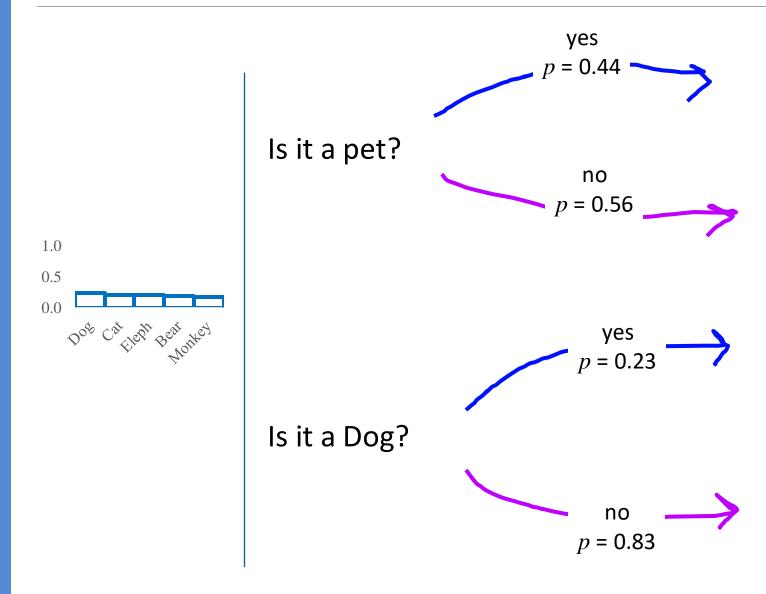
## Which Question is Better?



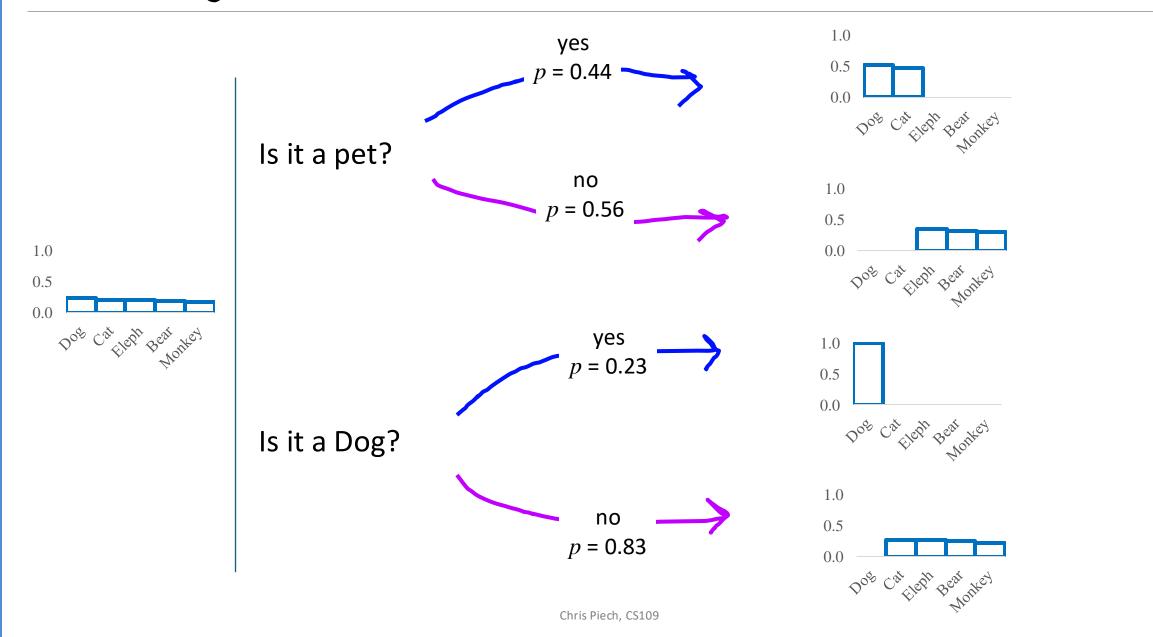
Is it a pet?

Is it a Dog?

## Which Question is Better?

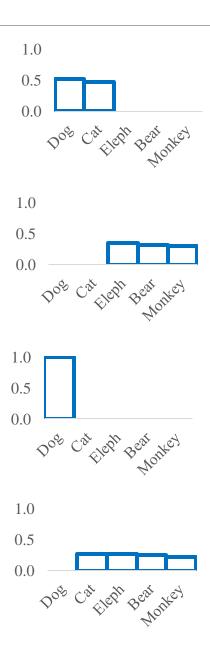


#### Which Question is Better?



## Which Question is Better

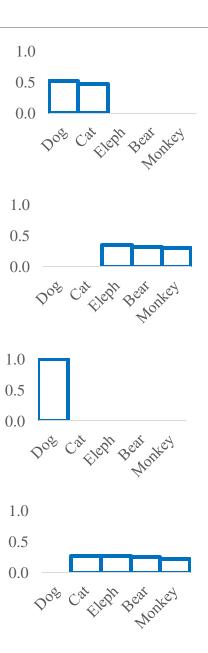
Can you "score" how bad each of these PMFs are?



#### Which Question is Better

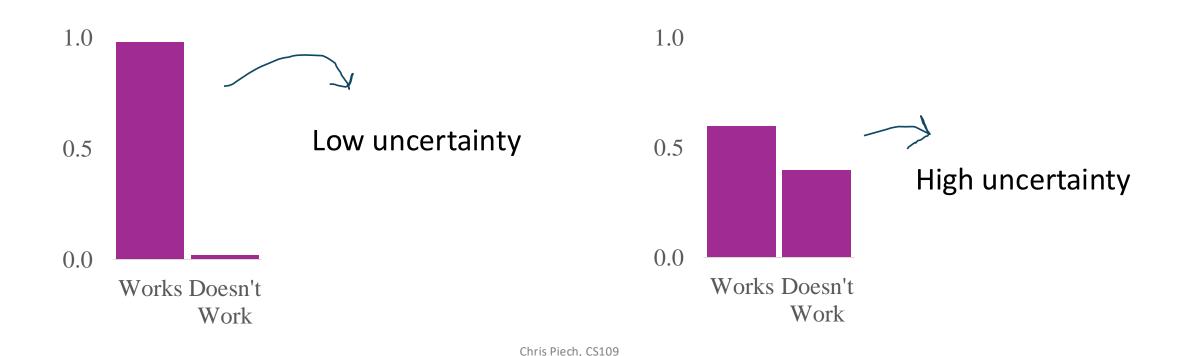
#### uncertain

Can you "score" how bad each of these PMFs are?

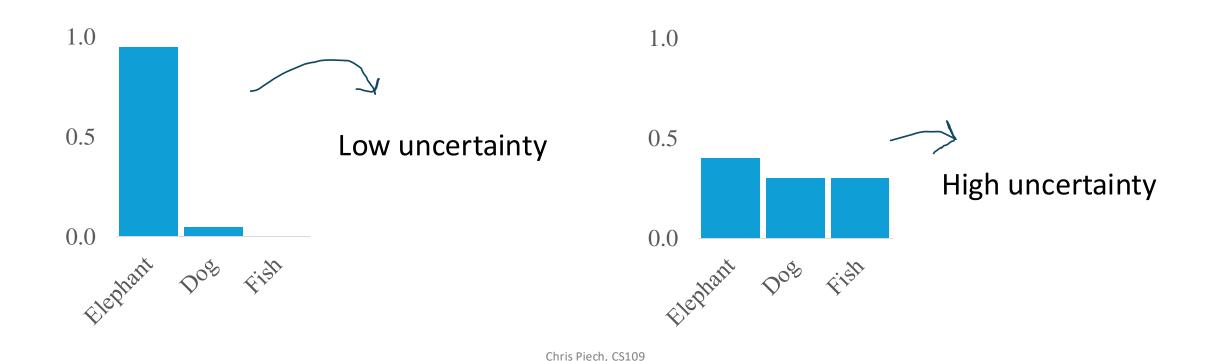


What we really need is a measure of our uncertainty in a random variable

Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X

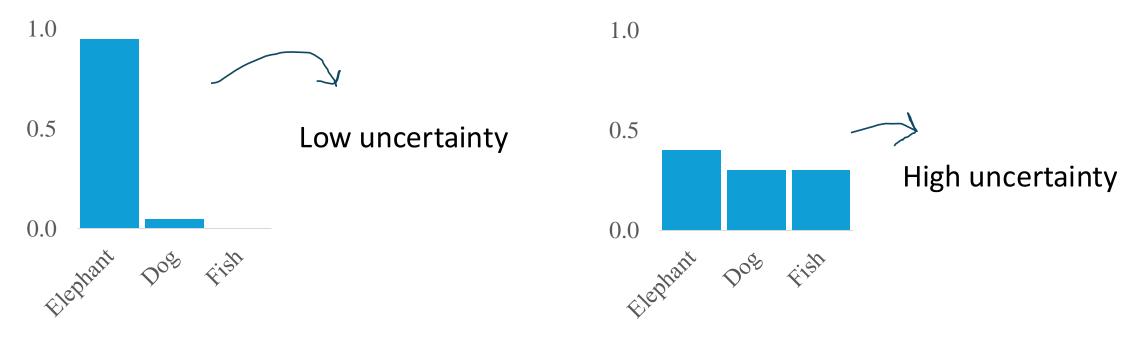


Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X



Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X

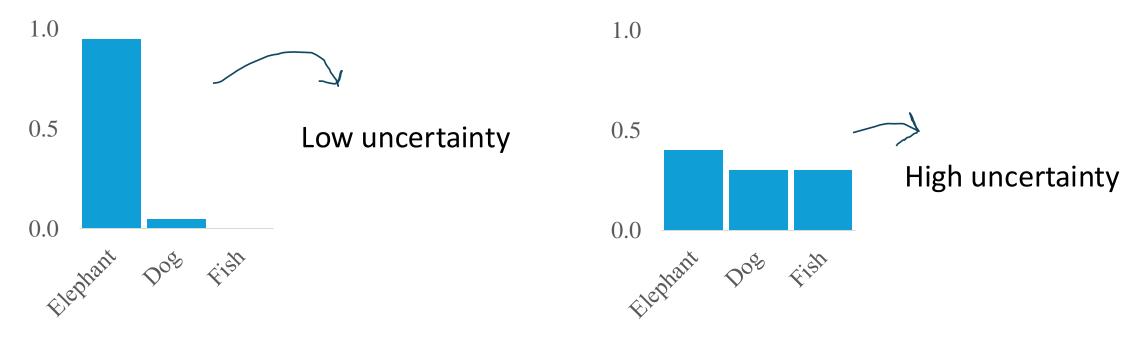
Uncertainty(X) = Expected "Surprise" when I observe X



Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X

Uncertainty
$$(X) = \sum_{x \in X} \text{Surprise}(X = x) \cdot P(X = x)$$

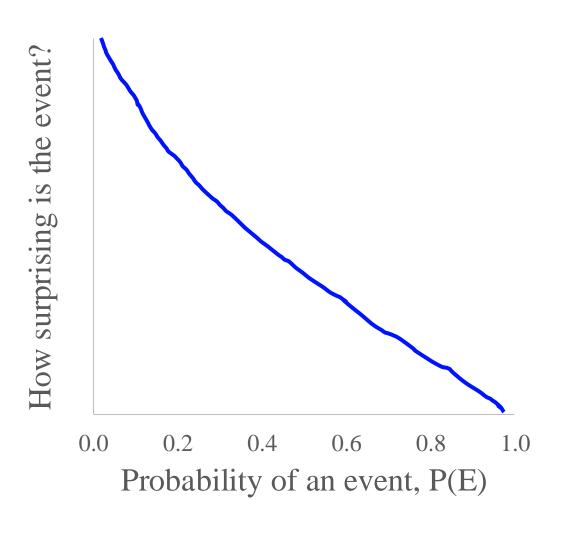
Uncertainty is expected Surprise



# Ok, but then what is our measure of **Surprise**?

#### Surprise of an Event

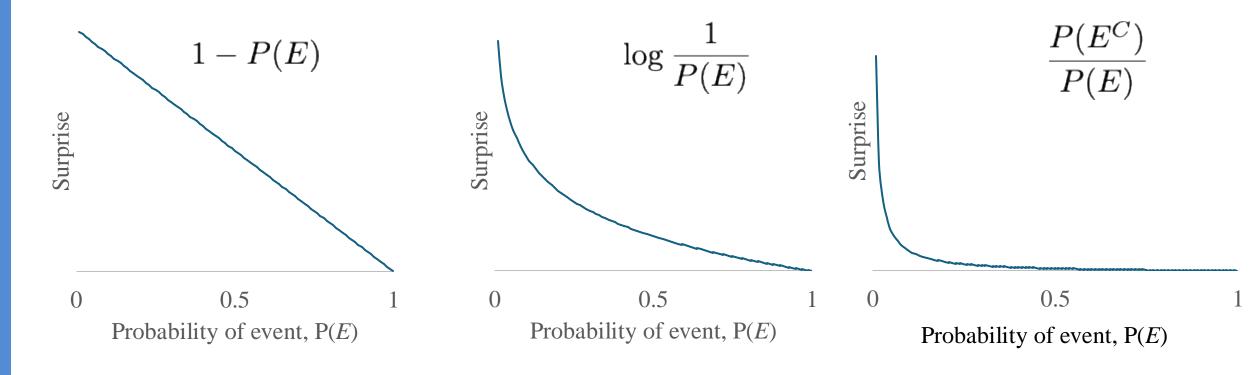
High probability events are not surprising
Low probability events are surprising
Relationship should be monotonic



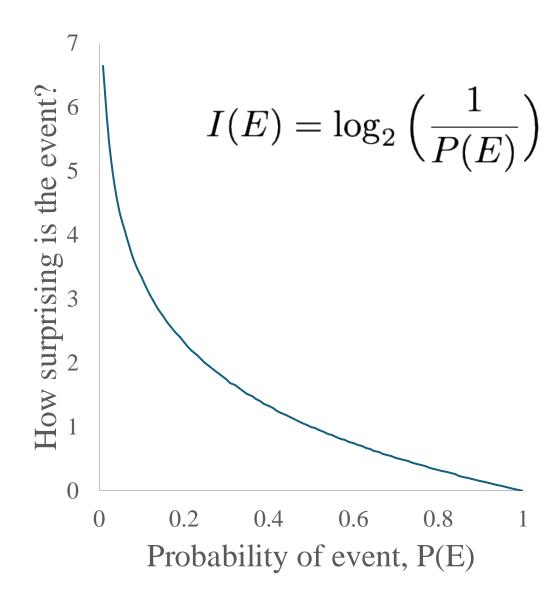
#### Surprise of an Event

High probability events are not surprising
Low probability events are surprising
Relationship should be monotonic

Here are three reasonable options



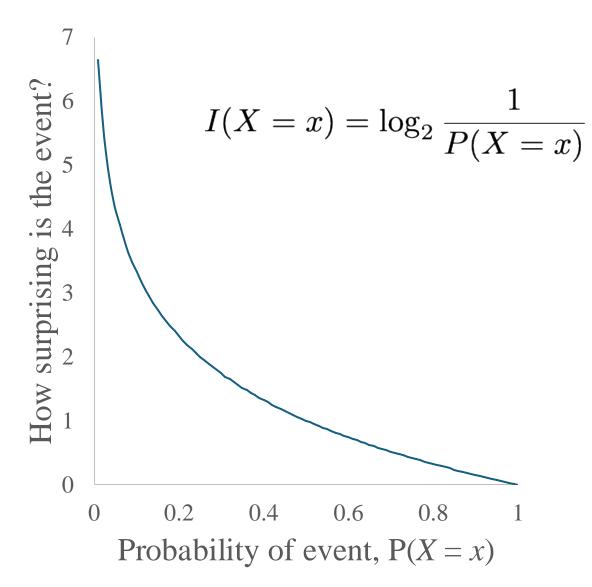
#### Surprise of an Event, I(E)



Probability of Event $P(E)$	Surprise of Event $I(E)$
1	0
1/2	1
1/4	2
1/8	3
1/16	4
1/32	5
1/64	6

I(E) stands for "Information Content" aka"Surprisal" aka"Self-Information"

#### Surprise of an Event, I(X = x)



Probability of Event $P(X = x)$	Surprise of Event $I(X = x)$
1	0
1/2	1
1/4	2
1/8	3
1/16	4
1/32	5
1/64	6

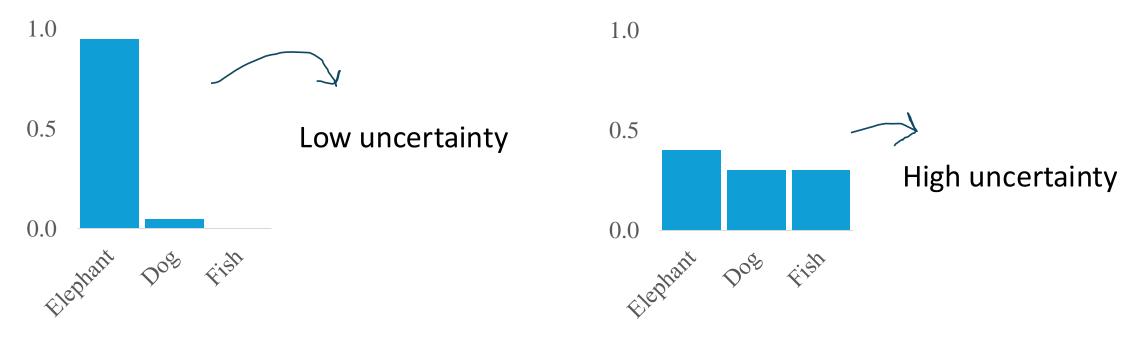
I(X = x) stands for "Information Content" aka "Surprisal" aka "Self-Information"

# Back to the measure of uncertainty in the outcome of a random variable

Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X

Uncertainty
$$(X) = \sum_{x \in X} \text{Surprise}(X = x) \cdot P(X = x)$$

Uncertainty is expected Surprise



Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X

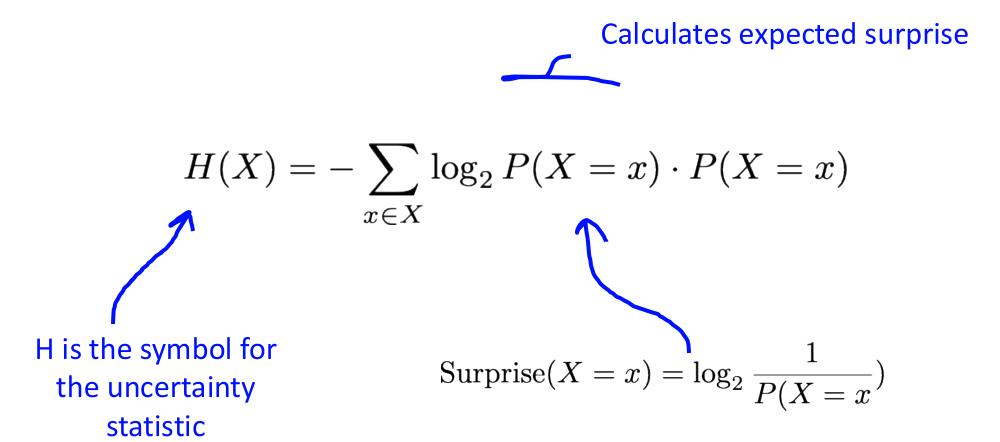
$$\operatorname{Uncertainty}(X) = \sum_{x \in X} \operatorname{Surprise}(X = x) \cdot P(X = x)$$
 Uncertainty is expected Surprise

Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X

$$\begin{aligned} &\operatorname{Uncertainty}(X) = \sum_{x \in X} \operatorname{Surprise}(X = x) \cdot P(X = x) & \operatorname{Uncertainty is expected Surprise} \\ &= \sum_{x \in X} \log_2 \frac{1}{P(X = x)} \cdot P(X = x) & \operatorname{Our favorite measure of Surprise} \\ &= \sum_{x \in X} \log_2 P(X = x)^{-1} \cdot P(X = x) & 1/\text{x is the same as } \text{x}^{-1} \\ &= \sum_{x \in X} -\log_2 P(X = x) \cdot P(X = x) & \operatorname{Log of a power (here -1)} \\ &= -\sum_{x \in X} \log_2 P(X = x) \cdot P(X = x) & \operatorname{Pull the negative out} \end{aligned}$$

#### Uncertainty of a Random Variable (Entropy)

Let X be any random variable. We can calculate a statistic, "Uncertainty" to express how much we don't know about X



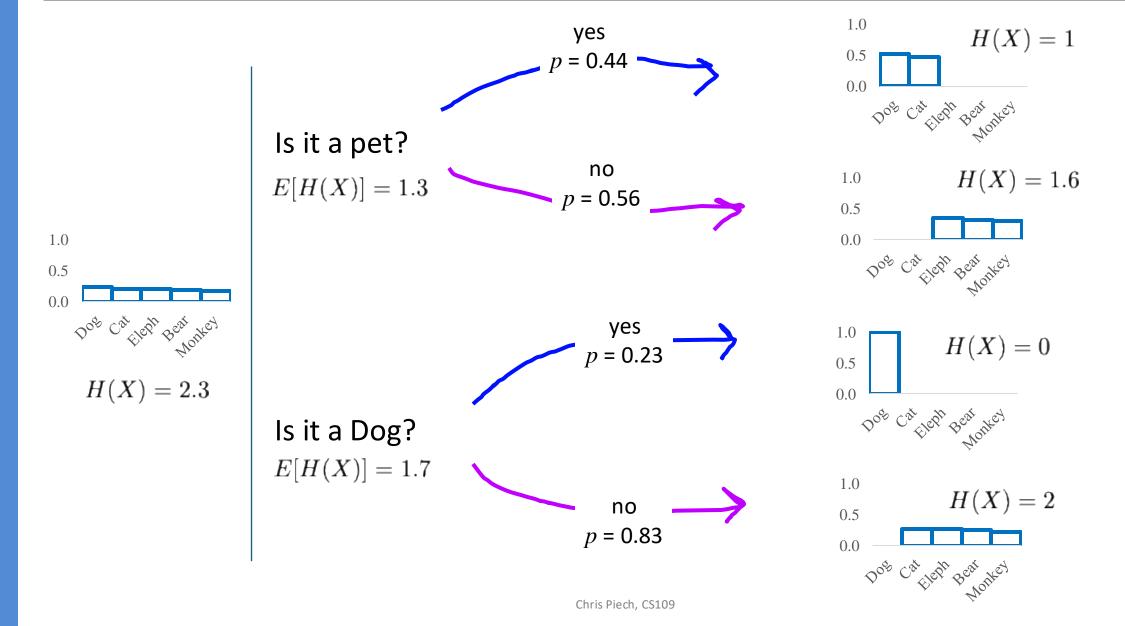
By the way...

H(X)

Is called **Shannon Entropy** to scare students and impress Physics people

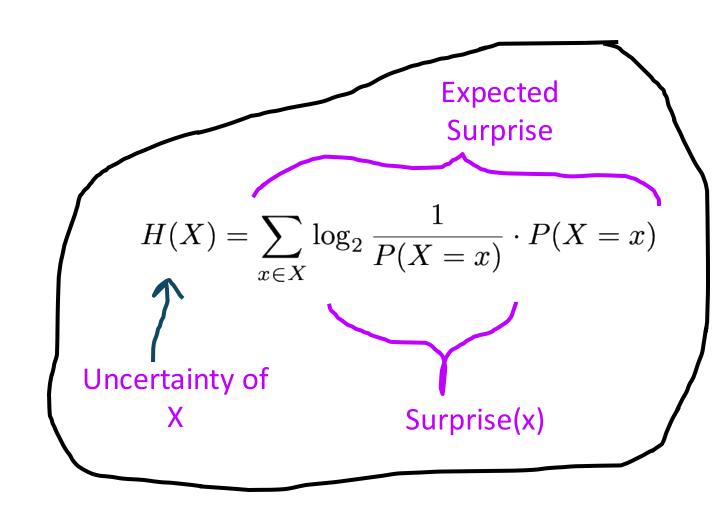
# Back to I am thinking of an animal...

# Which Question is Better?



# Uncertainty (aka Entropy) in code

```
def calc_uncertainty(pmf):
    # this calculates the entropy of the distribution
    # aka the uncertainty
    uncertainty = 0
    for x in pmf:
        p_x = pmf[x]
        # skip zero probabilities
        if p_x == 0: continue
        suprise_x = np.log2(1/p_x)
        uncertainty += suprise_x * p_x
    return uncertainty
```



Entropy in the sum of two dice.

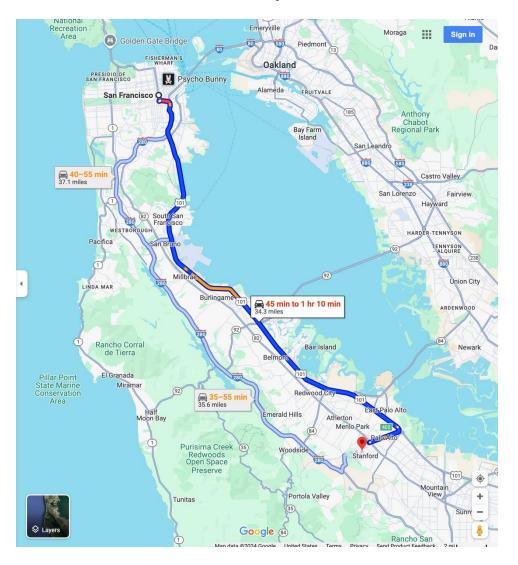
What is more informative:

I tell you that the sum is odd
I tell you the value of the first dice

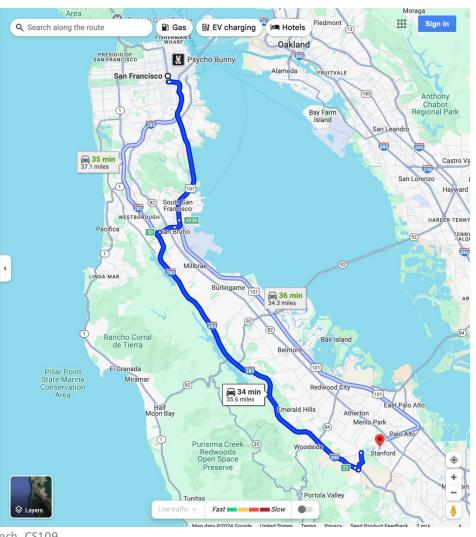
# Traffic Predictions Over Time

## Should You Wait to Plan Your Route?

#### Prediction 1 day in advance



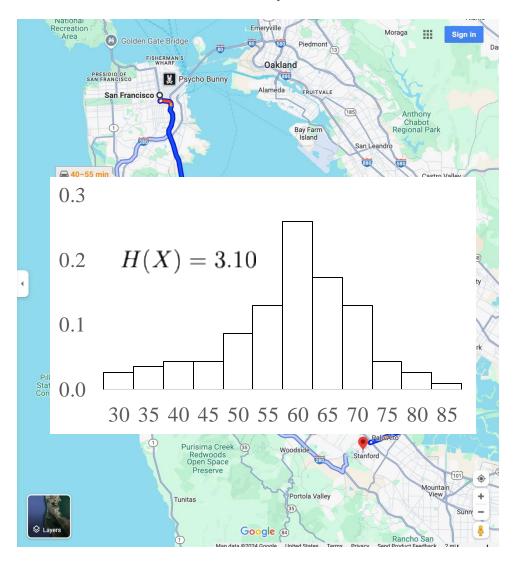
#### Prediction 30 mins in advance



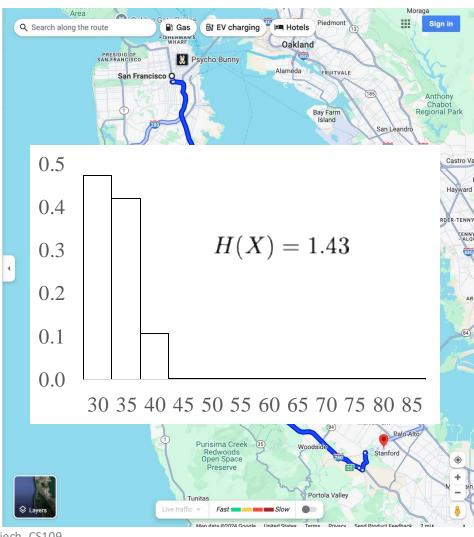
Chris Piech, CS109

## Should You Wait to Plan Your Route?

#### Prediction 1 day in advance



#### Prediction 30 mins in advance



Chris Piech, CS109

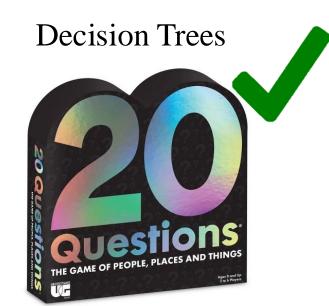
### Should You Wait to Plan Your Route?

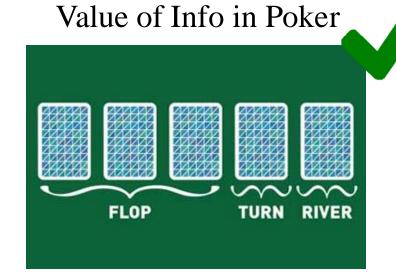
Let X be the amount of time to drive from SF to Stanford

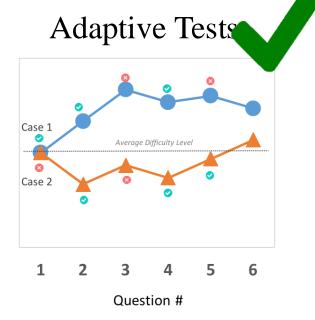


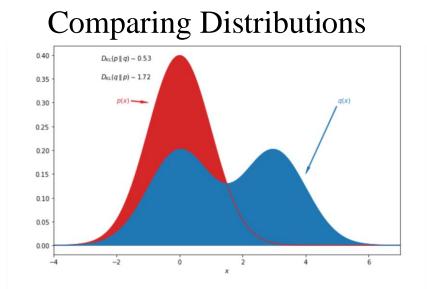
# Limitations of Entropy for Decision Making?

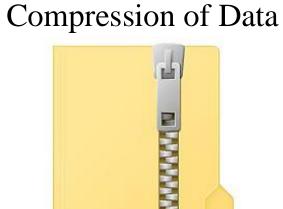
# WorldeBot PIQUE TREAD ORE ER











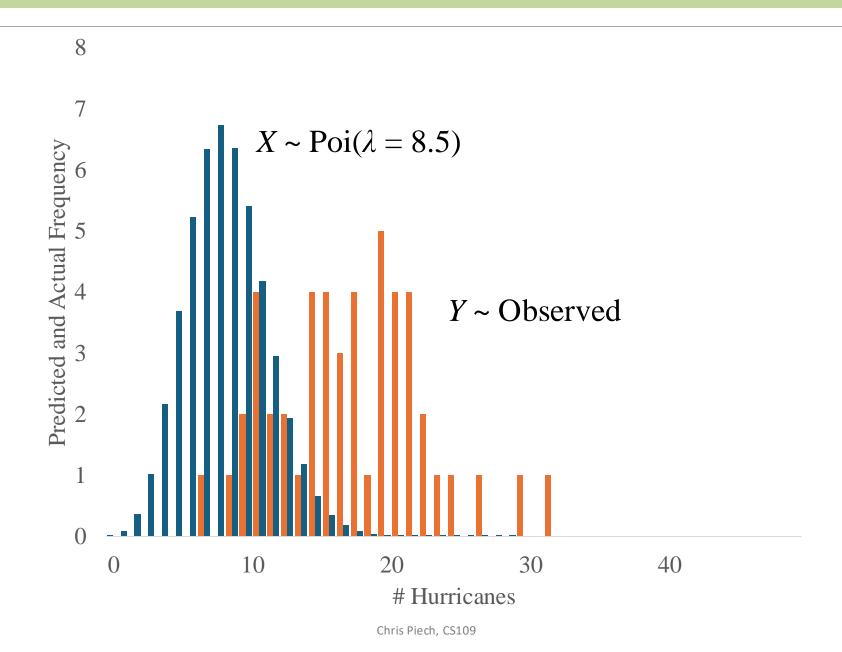




DALL-E 3

# Distance Between Two Distributions

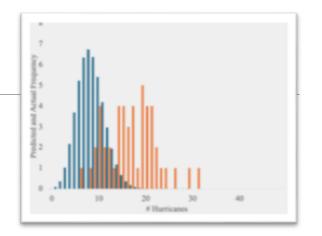
# Recall this



#### Distance Between Two Distributions

Three reasonable ideas

Let poisson prediction be XLet real data be Y



#### **Total Variation (TV)**

Loop over all possible values and calculate the **absolute difference** in probability

$$TV(X,Y) = \sum_{i} |P(X=i) - P(Y=i)|$$

#### **Earth Movers (EMD)**

Imagine one distribution is a lump of dirt. How much work would it take to make it look just like the other?

Solved using an LP Solver  $O(n^3 \log n)$ 

#### **Kullback Leibler (KL)**

Expected excess
surprise from using Y
as a model instead of X
when the actual
distribution is X.

$$KL(X,Y) =$$

$$\sum_{x} \log \frac{P(X=x)}{P(Y=x)} \cdot P(X=x)$$

# **KL Divergence Without Tears**

$$\begin{aligned} \operatorname{KL}(X,Y) &= \sum_{x \in X} \operatorname{ExcessSurprise}(x) \cdot P(X=x) & \text{How much more surprising is x} \\ &= \sum_{x \in X} \left[ \operatorname{Surprise}_Y(x) - \operatorname{Surprise}_X(x) \right] \cdot P(X=x) & \text{Surprise according to?} \\ &= \sum_{x \in X} \left[ \log_2 \frac{1}{P(Y=x)} - \log_2 \frac{1}{P(X=x)} \right] \cdot P(X=x) & \text{Surprise!} \\ &= \sum_{x \in X} - \log_2 P(Y=x) + \log_2 P(X=x) \cdot P(X=x) & 1/x = x^{-1} \\ &= \sum_{x \in X} \log_2 \frac{P(X=x)}{P(Y=x)} \cdot P(X=x) & \text{Log rules} \end{aligned}$$

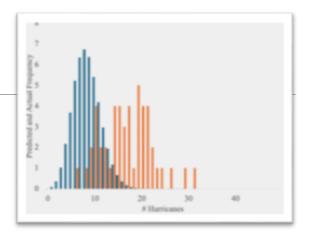
Log rules

People often use natural log

# KL Divergence in Code

from scipy import stats import math

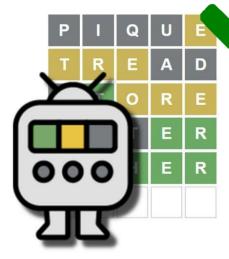
```
Let poisson prediction be X
          Let real data be Y
```



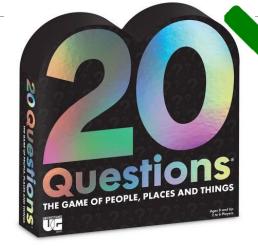
```
def kl divergence(predicted lambda, observed pmf):
 1111111
 We predicted that the number of hurricanes would be
 X ~ Poisson(predicted lambda) and observed a real world
 number of hurricanes Y ~ observed_pmf
 \Pi\Pi\Pi\Pi
 X = stats.poisson(predicted lambda)
 divergence = 0
 # loop over all the values of hurricanes
 for i in range(0, 40):
   pr X i = X.pmf(i)
   pr Y i = observed pmf[i]
   excess_surprise_i = math.log(pr_X_i / pr_Y_i)
   divergence += excess_surprise_i * pr_X_i
 return divergence
```

$$KL(X,Y) \approx 0.376$$

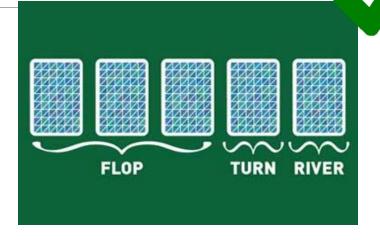
#### WorldeBot



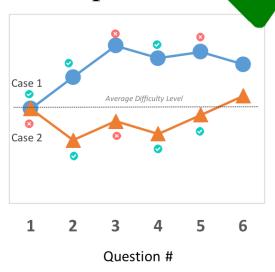
#### **Decision Trees**



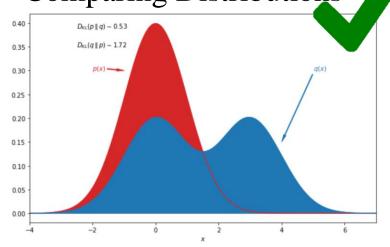
#### Value of Info in Poker



#### Adaptive Tests



#### Comparing Distributions



#### Compression of Data



# Where are we in CS109?

