# **English for Robotics** Tiếng Anh chuyên ngành Robot và Cơ điện tử

## Contents

Pr	eface		V
1	Rob	otics and Engineering	1
	1.1	Reading: What Is Robotics?	2
	1.2	Writing: What Can Robotics Do?	4
	1.3	Speaking: Robots Help People	5
	1.4	Listening: How Are Robots Built?	6
	1.5	My Glossary	7
2	Rob	ots and Their Applications	9
	2.1	Reading: Classification of Robots	10
	2.2	Writing: Caterogizing Robots	12
	2.3	Speaking: Robots in Your Country	13
	2.4	Listening: Will Robots Take Our Jobs?	14
	2.5	My Glossary	15

#### **Preface**

#### The book is under development. (2021-01-06)

This book is for students who majored in Robotics or Mechatronics. It aims at helping students (especially Vietnamese students) to learn both technical English and knowledge in robotics (and mechatronics).

The book is regularly updated to state-of-the-art knowledge in robotics and partially mechatronics and AI since these fields are closely connected.

There might be some mistakes in this book since I am not an English native speaker. Please let me know so I can correct them.

Hoang-Long Cao

Contact info: hoanglongcao@gmail.com<sup>1</sup>



The online version of this book is licensed under the Creative Commons Attribution-NonCommercial-ShareAlike 4.0 International License<sup>2</sup>. I currently have no plans to release a hardcopy version.

<sup>&</sup>lt;sup>1</sup>mailto:hoanglongcao@gmail.com

<sup>2</sup>http://creativecommons.org/licenses/by-nc-sa/4.0/

vi Preface

#### Resourses

This book has been created using the **Rmarkdown** (Allaire et al., 2020) and **bookdown** (Xie, 2020) packages within the RStudio (RStudio Team, 2018) environment.

English definitions are from Cambridge Dictionary<sup>3</sup>, and Dictionary.com<sup>4</sup>.

Pictures are from Freepik<sup>5</sup> and Unplash<sup>6</sup>. Icons are from Flaticon<sup>7</sup>.

#### About the author

I am Hoang-Long Cao (http://hoanglongcao.github.io). I am currently a postdoc researcher at the Vrije Universiteit Brussel, Belgium and a lecturer at Can Tho University, Vietnam. My research topics are social robotics, human-robot interaction, and human-robot collaboration.

<sup>3</sup>https://dictionary.cambridge.org

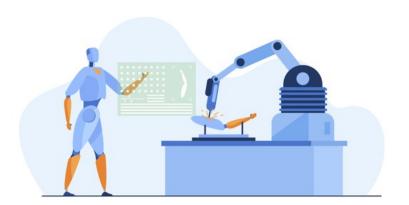
<sup>4</sup>https://dictionany.com

<sup>5</sup>http://freepik.com

<sup>6</sup>https://unsplash.com

<sup>&</sup>lt;sup>7</sup>https://www.flaticon.com

## Robotics and Engineering



i

Robotics is an interdisciplinary research area at the interface of computer science and engineering. The goal of robotics is to design intelligent machines that can help and assist humans. Robotics draws on the fields of information engineering, computer engineering, mechanical engineering, electronic engineering, artificial intelligence, and others.

Source: Adapted from the Wikipedia article "Robotics" (Wikipedia contributors, 2021), which is released under the Creative Commons Attribution-Share-Alike License 3.0.

1

#### 1.1 Reading: What Is Robotics?



Robotics develops machines that can substitute for humans and replicate human actions. Robots can be used in many situations and for many purposes, but today many are used in dangerous environments, manufacturing processes, or where humans cannot survive. Robots appear in various forms. Some are made to resemble humans in appearance. This is said to help in the acceptance of a robot in certain replicative behaviors usually performed by people. Such robots attempt to replicate walking, lifting, speech, cognition, or any other human activity. Many of today's robots are inspired by nature, contributing to the field of bio-inspired robotics.

The concept of creating robots that can operate autonomously started in the past but has only grown rapidly since the 20th century. Throughout history, it has been frequently assumed by various scholars, inventors, engineers, and technicians that robots will one day be able to mimic human behavior and manage tasks in a human-like fashion. Today, people reserch, designm and build robots for various purposes, whether domestically, commercially, or militarily. Many robots are built to do jobs that are hazardous to people, such as defusing bombs, finding survivors, and exploring mines. Robotics is also used in STEM (science, technology, engineering, and mathematics) as a teaching aid.

Robotics is a branch of engineering that involves the conception, design, manufacture, and operation of robots. This field overlaps with computer engineering, computer science (especially artificial intelligence), electronics, mechatronics, mechanical, nanotechnology and bioengineering.

*Source*: Adapted from the Wikipedia article "Robotics" (Wikipedia contributors, 2021), which is released under the Creative Commons Attribution-Share-Alike License 3.0.



## Read the text above and match the words below with their definitions.

#### Words

1.	robotics
2.	inventors
3.	engineers
4.	STEM
5.	artificial intelligence
6	mechatronics

#### **Definitions**

- a. the science of making and using robots
- the combination of mechanical engineering, computing, and electronics, as used in the design and development of new manufacturing techniques.
- c. the study of how to produce computers that have some of the qualities of the human mind, such as the ability to understand language, recognize pictures, solve problems, and learn
- someone who has invented something or whose job is to invent things
- e. science, technology, engineering, and mathematics
- f. a person specially trained to design and build machines, structures, and other things, including bridges, roads, vehicles, and buildings

#### 1.2 Writing: What Can Robotics Do?



Write a paragraph about what robotics can do for a better world. An example is shown below.

Industrial robots are mechanical devices which, to a certain degree, replicate human motions. They are used whenever there is a need to reduce the danger to a human, provide more strength or accuracy than a human, or when continuous operation is required. Most robots are stationary, but some move throughout the workplace delivering materials and supplies.

— "Industrial Robot". (encyclopedia.com, 2020)

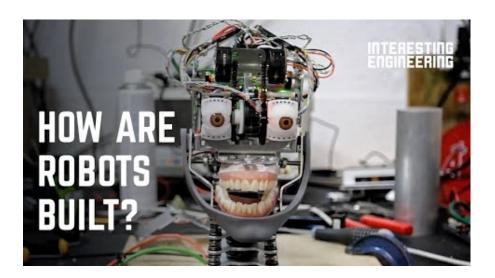

### 1.3 Speaking: Robots Help People



 $\label{lem:continuous} \textbf{Dicuss with your class mates about how robotics can help people.}$ 



#### 1.4 Listening: How Are Robots Built?





Source: "How are robots built?". Youtube. https://www.youtube.com/watch?v=oHKCwyUa2r (Interesting Engineering, 2020).

#### Listen to the video and fill in the blanks.

Robots have jumped from the screen andpages into our reality disrupting almost every modern industry.
Agriculture, space, travel, medicine, and are just a couple of places robots have begun to appear.
You could argue that they have already started to take over our world.
Just in the past few decades, robots have reached new heights.
The continual and rapid progress of paired with readily available large datasets, lower prices for

1.5 My Glossary 7

and a steady demand for efficiency has created the perfect storm for engineered ......

Yet you should not be intimidated by robots.

Though robots are certainly complicated pieces of machinery, they are also delightfully simple to understand.

In a lot of cases, robots are based on us humans.

You can even build your own simple robot at home.

Solution is in the footnote.<sup>2</sup>

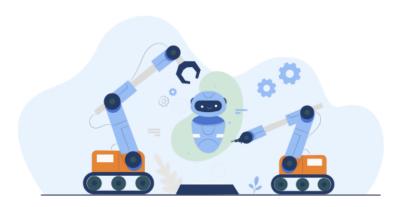
#### 1.5 My Glossary



Translate these terms into your language.										
robotics										
artificial intelligence										
mechatronics										
engineer										
manufacturing										
technology										
innovation										
electronics										
sensors										
motors										

science fiction; manufacturing; artificial intelligence; sensors and electronics; innovation.

## Robots and Their Applications



i

Robots are found everywhere in factories, homes, hospitals, and even in outer space. Several categories of robotic applications are industrial robots, autonomous mobile robots, humanoid robots and educational robots. In the past, robots mainly worked alone in isolated areas. Nowadays, people reserch and develop robots that interact with humans directly.

Source: Adapted from the chapter "Robots and their applications" (Ben-Ari and Mondada, 2018).

#### 2.1 Reading: Classification of Robots



Robots can be classified according to the environment in which they operate. The most common distinction is between fixed and mobile robots. These two types of robots have very different working environments and therefore require very different capabilities. Fixed robots are mostly industrial robotic manipulators that work in well defined environments adapted for robots. By contrast, mobile robots are expected to move around and perform tasks in large, ill-defined and uncertain environments that are not designed specifically for robots.

There are three main environments for mobile robots that require significantly different design principles because they differ in the mechanism of motion: aquatic (underwater exploration), terrestrial (cars) and aerial (drones). Robots for these three environments can be further divided into subclasses: terrestrial robots can have legs or wheels or tracks, and aerial robots can be lighter-than-air balloons or heavier-than-air aircraft.

Robots can be classified by intended application field and the tasks they perform. The first robots were industrial robots because the well-defined environment simplified their design. Service robots, on the other hand, assist humans in their tasks. These include home robots like vacuum cleaners, transportation like self-driving cars, and defense applications such as drones. Medicine, too, has seen increasing use of robots in surgery, rehabilitation and training. These are recent applications that require improved sensors and a closer interaction with the user.

Source: Adapted from the chapter "Robots and their applications" (Ben-Ari and Mondada, 2018).



#### Read the text above and complete the diagrams below.

#### Classification of robots by environment and mechanism of interaction

1.	fixed
2.	
	a)
	b) terrestrial
	i)
	ii)
	c)

Solution is in the footnote.<sup>1</sup>

#### Classification of robots by application field

1.	industrial												
	a)												
	b)												
2.													
	a) home												
	b)												
	c)												
	d)												

Solution is in the footnote.<sup>2</sup>

<sup>1.</sup> industrial; logistics; manufacturing; 2. service; home; transportation; defense; medicine 7. fixed; 2. mobile; aquatic; terrestrial; i.wheeled; ii.legged; airborne 1.

#### 2.2 Writing: Caterogizing Robots



## Describe these robots using two types of classification learned in the Reading section



This is a robot arm. It is a fixed industrial robot for logistics.



1																									
4		•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	



-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	•





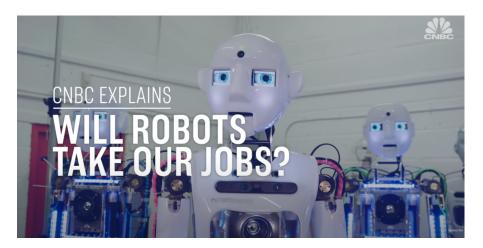
#### 2.3 Speaking: Robots in Your Country



 $\label{lem:power} \textbf{Dicuss with your class mates about robotics research and development in your country.}$ 



#### 2.4 Listening: Will Robots Take Our Jobs?





Source: "Will robots take our jobs? | CNBC Explains". Youtube. https://www.youtube.com/watch?v=oHKCwyUa2r (CNBC International, 2018).



#### Listen to the video and fill in the blanks.

This is a robot, which means it looks, it talks, and it even acts, well, like a human.											
There's no denying robots andare increasingly part of our daily lives.											
Occupations that require repetitive and predictable tasks in and administrative support were especially high-risk.											
A survey of 20,000 employers from 42 countries found that the IT, customer service and advancedindustries will add workers over the next two years as a result of automation.											

This is particularly a problem for ...... workers who aren't able to retrain for new jobs.

Solution is in the footnote.<sup>3</sup>

#### 2.5 My Glossary



Translate these terms into your language.							
application							
classification							
industrial							
logistics							
transportation							
automation							
humanoid							
drone							
mobile							
fixed							

humanoid; automation; transportation; logistics; manufacturing; low-skilled

## **Bibliography**

- Allaire, J., Xie, Y., McPherson, J., Luraschi, J., Ushey, K., Atkins, A., Wickham, H., Cheng, J., Chang, W., and Iannone, R. (2020). *rmarkdown: Dynamic Documents for R.* R package version 2.6.
- Ben-Ari, M. and Mondada, F. (2018). Robots and their applications. In *Elements of Robotics*, pages 1–20. Springer.
- CNBC International (2018). Will robots take our jobs? Youtube. [Online; accessed 05-January-2021].
- encyclopedia.com (2020). Industrial robot. [Online; accessed 05-January-2021].
- Interesting Engineering (2020). How are robots built?—Youtube. [Online; accessed 05-January-2021].
- RStudio Team (2018). RStudio: Integrated Development Environment for R. RStudio, Inc., Boston, MA.
- Wikipedia contributors (2021). Robotics Wikipedia, the free encyclopedia. [Online; accessed 05-January-2021].
- Xie, Y. (2020). bookdown: Authoring Books and Technical Documents with R Markdown. R package version 0.21.