|  |  |  |
| --- | --- | --- |
|  |  |  |
|  | Master’s thesis |  |
|  |
|  |
|  |
|  | A Monocular Visual-Inertial Navigation System based on Multi-state Constraint Kalman Filter with Comprehensive Feature Motion Measurements |  |
|  |
|  | 2  0  2  1  ․  2 |  |
|  | Hoang Viet Do |
|  |  |
|  |
|  |
|  |