

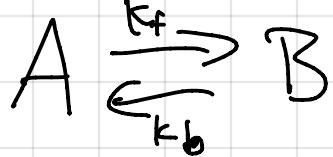
Non Equilibrium Pt 3

Other kinds of Brownian Motion

The general theory we are learning is useful for other kinds of random processes besides a particle in solution

To illustrate this, let's look @ chemical reactions

Simplest reaction is



$$\text{expect } \frac{dA}{dt} = BK_B - AK_f$$

$$\frac{dB}{dt} = AK_f - BK_B$$

In this case, we know

$$A + B = N \underbrace{\text{const}}_{\text{const \# molecules}}$$

$$@ \text{Eq still true, } A_{\text{eq}} + B_{\text{eq}} = N$$

In the spirit of our prev work, think about

$$A = A_{\text{eq}} + C, \quad A \text{ at a particular time}$$

is a deviation from eq

$$\text{This means } B = B_{\text{eq}} - C$$

C measures reaction condition from eq in

$$A (C = B_{\text{eq}}) + \text{all in } B (C = -A_{\text{eq}})$$

Lastly, we have our detailed balance condition

$$A_{\text{eq}} k_f = k_B B_{\text{eq}}$$

Combining this info, we have

$$\frac{d(A_{\text{eq}} + C)}{dt} = -k_f(A_{\text{eq}} + C) + k_B(B_{\text{eq}} - C)$$

$$\frac{d(B_{\text{eq}} - C)}{dt} = k_f(A_{\text{eq}} + C) - k_B(B_{\text{eq}} - C)$$

$$\frac{dA_{\text{eq}}}{dt} = \frac{dB_{\text{eq}}}{dt} = 0$$

$$\text{Subtract: } 2 \frac{dC}{dt} = 2k_B(B_{\text{eq}} - C) - 2k_f(A_{\text{eq}} + C)$$

$$\Rightarrow \frac{dc}{dt} = -(k_f + k_B) c$$

$$\Rightarrow c(t) = e^{-(k_f + k_B)t} \quad \leftarrow \tau_{\text{relax}} = \frac{1}{k_f + k_B}$$

Macroscopic diff from eq decays to
eq. exponentially

Ornstein-Zernike Hypothesis (1931)

Small fluctuations decay on the average c^{noneq}
@ the same way as macroscopic deviations

[not really a hypothesis, more like so
far always true theory/law]

Makes sense, how would you know whether prepared in
this state, or result of true dynamics?

$$\Rightarrow \langle c(t)c(t') \rangle = \langle c^2 \rangle_{\text{eq}} e^{-(k_1 + k_2)|t - t'|}$$

However, it can't be true that
the non eq condition goes to $c=0$, ..

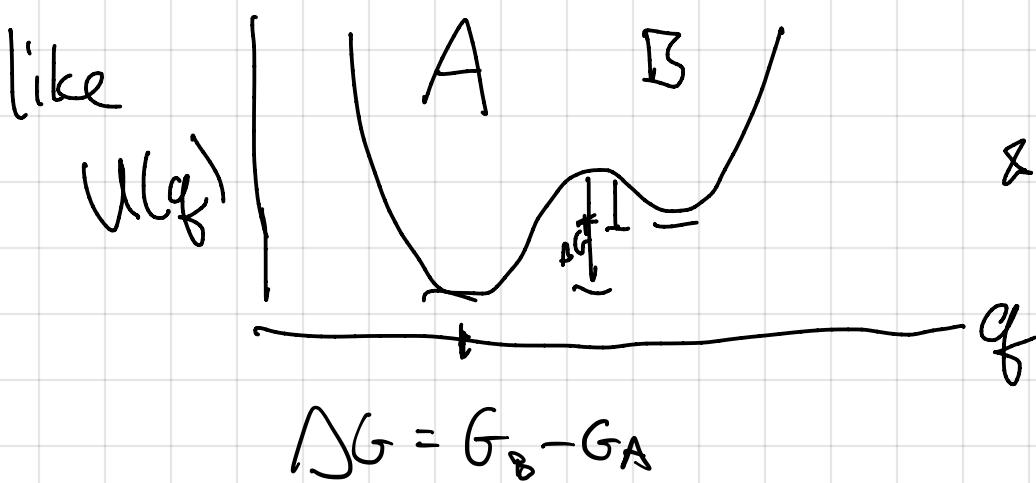
... and then the number of A & B are fixed, they have to fluctuate randomly

Have to maintain a $\langle C^2 \rangle_{eq}$ that is non-zero
this is just like Brownian motion

so, postulate $\frac{dC}{dt} = -(\kappa_1 + \kappa_2)C + S^F$

$$\xrightarrow{\text{HW}} \text{ & now } \langle S^F(t) S^F(t') \rangle = 2(\kappa_1 + \kappa_2) \langle C^2 \rangle_{eq} \delta(t-t')$$

This is a macroscopic view of chemical eq,
but where do these rate constants come
from. For this simple prob, we expect something



$$\begin{aligned} P_A/P_B &\approx e^{-\beta \Delta G} \\ &\& \& \\ &\& k_{A \rightarrow B} \propto e^{-\beta \Delta G_A} & \\ &\& k_{B \rightarrow A} \propto e^{-\beta \Delta G_B} & \end{aligned}$$

Now we have to connect this to the microscopic stat mech theory we've learned all semester. Molecularly, we still have $Q(x, p) = C \int dx \int dp e^{-\beta H(x, p)}$

Real problem example could be



Define q by a collective coordinate
transition state @ q^*
Can define a function $H_A(q) = \begin{cases} 1, & q < q^* \\ 0, & q \geq q^* \end{cases}$ (in A)

$$\langle H_A \rangle = X_A = \frac{A_{q^*}}{A_{q^*} + B_{q^*}}$$

Since H_A is 1 in A & 0 otherwise

$$\langle H_A^2 \rangle = \frac{H_A(A)^2 P(A) + H_A(B)^2 P(B)}{P(A) + P(B)} = \frac{P(A)}{P(A) + P(B)} = X_A$$

$$\Rightarrow \langle S_{H_A}^2 \rangle = \langle H_A^2 \rangle - \langle H_A \rangle^2 = X_A - X_A^2 \\ = X_A(1-X_A) = X_A X_B$$

Now, already said

$$\langle C(t)C(0) \rangle = e^{-t/\tau_{\text{exn}}} \cdot \langle C^2 \rangle$$

similarly at a microscopic level

$$\langle S_{H_A}(g(t))S_{H_A}(g(0)) \rangle = e^{-t/\tau_{\text{exn}}} \langle S_{H_A}^2 \rangle$$

$$\Rightarrow e^{-t/\tau_{\text{exn}}} = \underbrace{\langle S_{H_A}(g(t))S_{H_A}(g(0)) \rangle}_{X_A X_B}$$

(call $H_A(g(t)) = H_A(t)$ for simplicity)

since we care how the number in A is changing in time
take time deriv

$$-\frac{1}{2} \frac{1}{\tau_{\text{exn}}} e^{-t/\tau_{\text{exn}}} = \underbrace{\langle S_{H_A}(t)S_{H_A}(0) \rangle}_{X_A X_B}$$

Last time sort of discussed

$\downarrow \text{Pop } ^{\text{so}}$

$$\cancel{H_A}, \langle A(t)A(t') \rangle = \langle A(0)A(t'-t) \rangle = \langle A(t-t')A(0) \rangle \\ \Rightarrow \langle A(0)A(t) \rangle = \langle A(0)A(t) \rangle$$

For our case $\langle S H_A(0) \dot{S} H_A(t) \rangle = \langle \dot{S} H_A(0) S H_A(t) \rangle$

Important to note $\frac{d H[q]}{dt} = \dot{q} \frac{d}{dq} H_A = -\dot{q} S(q - q^*)$

Br changes from $0 \rightarrow -\infty \rightarrow 0$ instantaneously

$$S_0 - \langle S H_A(0) \dot{S} H_A(t) \rangle = \langle -\dot{q}(0) S(q(0) - q^*) S H_A(q(t)) \rangle \\ = \langle \dot{q}(0) S(q(0) - q^*) S H_B(q(t)) \rangle$$

Since $H_B = -H_A$

$$\text{and } \langle \dot{q}(0) S(q(0) - q^*) \rangle = 0$$

b/c velocity & configs are uncorrelated

Finally

$$\frac{1}{C_{rxn}} e^{-t/\tau_{rxn}} = \frac{1}{X_A X_B} \langle v^*(0) S[q(0) - q^*] H_B(q(t)) \rangle$$

v^* on surface

Right side is flux crossing surface if ends up in B

Left side is simple exponential & cont account for really short time fluxes, hence

evidence regression hypothesis is true only after coarse-graining over short time scales, so expect this to be true for $\tau_{\text{mo}} \ll f \ll \tau_{\text{rxn}}$
 (fast barrier crossing)

$$\text{If so } \frac{1}{\tau_{\text{rxn}}} = k_f + k_s = \frac{1}{x_A x_B} \langle v(0) f(g - g^*) H_3(g(t)) \rangle$$

mult by x_B & detailed balance

$$x_B(k_f + k_s) = \frac{B}{A+B} (k_f + k_s) = \frac{B/A}{1 + B/A} (k_f + k_s) = \frac{k_f}{1 + \frac{k_s}{k_f}} (k_f + k_s)$$

$$= k_f$$

$$\text{So } k_f = \frac{1}{x_A} \langle v(0) f(g - g^*) H_3(g(t)) \rangle$$

This connect microscopic behavior at the transition state to the macroscopic reaction rate

let
 $n_A(t) = H_A[q(t)]$,

where

$$\begin{aligned} H_A[z] &= 1, & z < q^* \\ &= 0, & z > q^*. \end{aligned}$$

Note

$$\langle H_A \rangle = x_A = \langle c_A \rangle / (\langle c_A \rangle + \langle c_B \rangle)$$

and

$$\langle H_A^2 \rangle = \langle H_A \rangle = x_A.$$

Hence

$$\begin{aligned} \langle (\delta H_A)^2 \rangle &= x_A(1 - x_A) \\ &\equiv x_A x_B. \end{aligned}$$

Exercise 8.5 Verify these results.

According to the fluctuation-dissipation theorem, we now have

$$\exp(-t/\tau_{xn}) = (x_A x_B)^{-1} [\langle H_A(0) H_A(t) \rangle - x_A^2].$$

To analyze the consequences of this relationship, we take a time derivative to obtain

$$\tau_{xn}^{-1} \exp(-t/\tau_{xn}) = -(x_A x_B)^{-1} \langle H_A(0) \dot{H}_A(t) \rangle,$$

where the dot denotes a time derivative. Since $\langle A(t) A(t') \rangle = \langle A(0) A(t' - t) \rangle = \langle A(t - t') A(0) \rangle$, we have

$$-\langle H_A(0) \dot{H}_A(t) \rangle = \langle \dot{H}_A(0) H_A(t) \rangle.$$

Exercise 8.6 Derive this result.

Furthermore,

$$\dot{H}_A[q] = \dot{q} \frac{d}{dq} H_A[q] = -\dot{q} \delta(q - q^*).$$

Hence

$$\begin{aligned} -\langle H_A(0) \dot{H}_A(t) \rangle &= -\langle \dot{q}(0) \delta[q(0) - q^*] H_A[q(t)] \rangle \\ &= \langle \dot{q}(0) \delta[q(0) - q^*] H_B[q(t)] \rangle, \end{aligned}$$

where the second equality is obtained from

$$\begin{aligned} H_B[z] &= 1 - H_A[z] = 1, & z > q^*, \\ &= 0, & z < q^*, \end{aligned}$$

Exercise 8.7 Show that

$$k_{BA}(0) = (1/2x_A) \langle |v| \rangle \langle \delta(q - q^*) \rangle$$

and verify that this initial rate is precisely that of the transition state theory approximation,

$$k_{BA}^{(\text{TST})} = (1/x_A) \langle v(0) \delta[q(0) - q^*] H_B^{(\text{TST})}[q(t)] \rangle,$$

where

$$\begin{aligned} H_B^{(\text{TST})}[q(t)] &= 1, & v(0) > 0, \\ &= 0, & v(0) < 0. \end{aligned}$$

and the fact that

$$\langle q(0) \delta[q(0) - q^*] \rangle = 0.$$

This last result is true because the velocity is an odd vector function and the equilibrium ensemble distribution is even and uncorrelated with configurations. Combining of velocities function where $v(0) = \dot{q}(0)$.

But this equality cannot be correct for all times. The left-hand side crossing the "surface" at $q = q^*$ given that the trajectory ends up in state B . For short times, we expect transient behavior that should not correspond to the exponential macroscopic decay. This does not mean that the regression hypothesis is wrong. Rather, the phenomenological rate laws we have adopted can only be right after coarse-graining in time. In other words, the phenomenology can only be right on a time scale that does not resolve the short time transient relaxation. On that time scale, let Δt be a small time. That is,

but at the same time

$$\Delta t \gg \tau_{xn},$$

where τ_{xn} is the time for transient behavior to relax. For such times, $\exp(-\Delta t/\tau_{xn}) \approx 1$, and we obtain

$$\tau_{xn}^{-1} = (x_A x_B)^{-1} \langle v(0) \delta[q(0) - q^*] H_B[q(\Delta t)] \rangle$$

or

$$k_{BA} = x_A^{-1} \langle v(0) \delta[q(0) - q^*] H_B[q(\Delta t)] \rangle.$$

To illustrate the transient behavior we have just described, let

$$k_{BA}(t) = x_A^{-1} \langle v(0) \delta[q(0) - q^*] H_B[q(t)] \rangle.$$

Fokker Planck Equation

General version of something like
Liouville eqn

Let $f(\vec{a}, t)$ be density like with phase space before, but \vec{a} is n properties of system rather than full phase space

$$\int d\vec{a} f(\vec{a}, t) = 1 \quad \text{required}$$

$$\text{let } \vec{v} = \frac{d\vec{a}}{dt} = \dot{\vec{a}}$$

$$\frac{\partial f(\vec{a}, t)}{\partial t} + \nabla_{\vec{a}} \cdot (\vec{v} f(\vec{a}, t)) = 0, \quad \begin{array}{l} \text{change in density} \\ \text{related to flux} \\ \text{of points} \end{array}$$

$$\text{now suppose } \dot{\vec{a}} = \vec{v} + \vec{R}(t)$$

$$\langle \vec{R}(t) \rangle = 0 \quad \& \quad \langle R_i(t) R_j(t') \rangle = 2B_{ij} \delta_{ij} \delta(t-t')$$

$$\frac{\partial f(\vec{a}, t)}{\partial t} + \nabla_{\vec{a}} \cdot (\dot{\vec{a}} f(\vec{a})) = \frac{\partial f}{\partial t} + \nabla_{\vec{a}} \cdot \left[[V(\vec{a}) + \vec{R}(t)] f(\vec{a}, t) \right] = 0$$

$$L = \nabla_a \cdot [\dot{a} -] = \{ , H \}$$

det part

for no noise

$$\frac{\partial f}{\partial t} + Lf = 0 \Rightarrow f(\vec{a}, t) = e^{-Lt} f(\vec{a}, 0)$$

here $\frac{\partial f}{\partial t} = -Lf - \nabla_a \cdot \vec{R}(t) f(\vec{a}, t)$

$$f(\vec{a}, t) = e^{-Lt} f(\vec{a}, 0) - \int_0^t ds e^{-(t-s)L} \nabla_a \cdot \vec{R}(s) f(\vec{a}, s)$$

$f(\vec{a}, t)$ only depends on noise up to time t

Sub back in & get

$$\frac{\partial f(a, t)}{\partial t} + Lf(a, t) = - \left[\nabla_a \cdot \vec{r} e^{-Lt} f(a, 0) \right. \\ \left. - \nabla_a \cdot \int_0^t ds e^{-L(t-s)} \nabla \cdot [R(s) f(\vec{a}, s)] \right]$$

avg over noise

$$\frac{\partial \langle f \rangle}{\partial t} + L\langle f \rangle = \nabla_a \int_0^t ds e^{-L(t-s)} \langle R(t) \cdot R(s) \rangle \nabla_a \langle f(a, s) \rangle$$

$$\Rightarrow \underbrace{\frac{\partial \langle f(\vec{a}, t) \rangle}{\partial t} + \nabla_a \cdot [\vec{B} \langle f(\vec{a}, t) \rangle]}_{\text{Fokker-Planck}} = \nabla_a \cdot \underline{\underline{B}} \cdot \nabla_a \langle f(\vec{a}, t) \rangle$$

Langvin eq

$$\frac{dx}{dt} = P/m \quad \frac{dp}{dt} = -\frac{du}{dx} - \{P/m + F_p(t)\}$$

$$\langle f_p(t) f_p(t') \rangle_2 \sim \{k_B T S(t-t')$$

$$\vec{a} = \begin{pmatrix} x \\ p \end{pmatrix} \quad \vec{v} = \begin{pmatrix} P/m \\ -\frac{du}{dx} - \xi P/m \end{pmatrix}$$

$$\vec{F}(t) = \begin{pmatrix} 0 \\ \vec{r}_p(t) \end{pmatrix} \quad B = \begin{pmatrix} 0 & 0 \\ 0 & \xi k_B T \end{pmatrix}$$

$$\text{Then } \frac{\partial f(u, t)}{\partial t} = -\frac{\partial}{\partial x} \left[\frac{1}{m} f(\vec{a}, t) \right] - \frac{\partial}{\partial p} \left[-u - \frac{\xi p}{m} \right] f + \{k_B T \frac{\partial^2}{\partial p^2} f(\vec{a}, t)$$

only matrix element

no noise or friction, standard Liouville eqn

$$\text{eq, } \frac{\partial f}{\partial t} = 0 \quad \text{check!}$$

$$\text{Solution is } f(\vec{a}, t) \propto e^{-\beta H(f, \vec{p})} \propto P^2 / \text{multi}$$

Shows Langvin eq give Boltz statistics

$$\text{Consider } m \frac{\partial^2 x}{\partial t^2} = -u'(x) - \left\{ \frac{dx}{dt} + F(t) \right\}$$

one limit of Brownian behavior, $\frac{d^2 x}{dt^2} \approx 0$

$$\frac{dx}{dt} = -\frac{1}{\xi} u'(x) + \frac{1}{\xi} F(t)$$

only one coordinate

$$\frac{\partial f(x)}{\partial t} = -\frac{\partial}{\partial x} \left(-\frac{1}{\xi} u'(x) f(x, t) \right) + k_B T \frac{\partial^2}{\partial x^2} f$$

$$\begin{aligned} & \left\langle F(t) \cdot F(t') \right\rangle \\ &= \frac{k_B T}{\xi} \delta(t-t') \end{aligned}$$

Smoluchowski

$$\frac{\partial f}{\partial t} = D \frac{\partial}{\partial x} e^{-\beta u} \frac{\partial}{\partial x} e^{\beta u} f(x, t) \quad D = k_B T / \xi$$

$$\begin{aligned} b/c &= D \frac{\partial}{\partial x} e^{-\beta u} \left[\beta u' e^{\beta u} f + e^{\beta u} \frac{\partial f}{\partial x} \right] \\ &= D \frac{\partial}{\partial x} \left[\beta u' f + \frac{\partial f}{\partial x} \right] \\ &= \frac{\partial}{\partial x} \frac{u'}{\xi} f + \frac{k_B T}{\xi} \frac{\partial^2 f}{\partial x^2} \end{aligned}$$

obviously stationary for $f(x, t) \propto e^{-\beta u(x)}$