

Nomor 1

```
1;
function x = backwardSub(U, b)
    % This solves  $Ux = b$ , U is unit upper triangular matrix
    [n n] = size(U); x = zeros(n, 1); x(n) = b(n);
    for i = (n - 1):-1:1
        x(i) = b(i) - U(i, i+1:n) * x(i+1:n);
    endfor
endfunction

function x = forwardSub(L, b)
    % This solves  $Lx = b$ , L is unit lower triangular matrix
    [n n] = size(L); x = zeros(n, 1); x(1) = b(1);
    for i = 2:n
        x(i) = b(i) - L(i, 1:i-1) * x(1:i-1);
    endfor
endfunction

function x = diagSub(D, b)
    % This solves  $Dx = b$ , D is a diagonal matrix
    [n n] = size(D); x = zeros(n, 1);
    for i = 1:n
        x(i) = b(i)/D(i, i);
    endfor
endfunction

function [A] = getSymmetric(n)
    % Generate a symmetric matrix with uniform distribution
    A = zeros(n, n);
    for i=1:n
        for j=1:n
            A(i, j) = rand();
            if(i > j)
                A(i, j) = A(j, i);
            endif
        endfor
    endfor
endfunction

function [L D] = LDLT(A)
    % Input: A, symmetric matrices
    % Output L and D such that  $A = L D L'$ 
    [n n] = size(A);
    L = zeros(n, n);
    D = zeros(n);
    for k=1:n
        D(k) = A(k, k) - sum(L(k, 1:k-1).^2.*D(1:k-1));
        for i=1:n
            % Cari pembagiannya
            L(i, k) = (A(i, k) - sum(L(i, 1:k-1).*L(k, 1:k-1).*D(1:k-1)))/D(k);
        endfor
    endfor
    D = D(1:n,1);
```

```
endfunction
```

```
function [L D P] = LDLTWP(A)
```

```
    % Input: A, symmetric matrices
```

```
    % Output L and D such that  $A = L D L'$ 
```

```
    [n n] = size(A);
```

```
    p = 1:n;
```

```
    L = zeros(n, n);
```

```
    D = zeros(n);
```

```
    for k=1:n
```

```
        % Extract maximum diagonal of submatrix k .. n : k .. n
```

```
        [M pos] = max(diag(A(k:n,k:n)))
```

```
        % p is the relative position
```

```
        pos += k - 1;
```

```
        % Swap pos and k
```

```
        tmp = p(pos);
```

```
        p(pos) = p(k);
```

```
        p(k) = tmp;
```

```
        % Swap Diagonal p and k
```

```
        tmp = A(pos,1:n)
```

```
        A(pos, 1:n) = A(k, 1:n);
```

```
        A(k, 1:n) = tmp;
```

```
        tmp = A(1:n, pos);
```

```
        A(1:n, pos) = A(1:n, k);
```

```
        A(1:n, k) = tmp;
```

```
        % Swap Diagonal p and k
```

```
        tmp = L(pos,1:n)
```

```
        L(pos, 1:n) = L(k, 1:n);
```

```
        L(k, 1:n) = tmp;
```

```
        tmp = L(1:n, pos);
```

```
        L(1:n, pos) = L(1:n, k);
```

```
        L(1:n, k) = tmp;
```

```
        D(k) = A(k, k) - sum(L(k,1:k-1).^2.*D(1:k-1));
```

```
        for i=1:n
```

```
            % Cari pembagiannya
```

```
            L(i, k) = (A(i, k) - sum(L(i, 1:k-1).*L(k, 1:k-1).*D(1:k-1)))/D(k);
```

```
        endfor
```

```
    endfor
```

```
    D = D(1:n,1);
```

```
    P = zeros(n, n);
```

```
    for i=1:n
```

```
        P(i, p(i)) = 1
```

```
    endfor
```

```
endfunction
```

```
function [x] = solve(A, b)
```

```
    [L D P] = LDLTWP(A);
```

```
    disp(L);
```

```
    disp(D);
```

```

disp(P);
disp(L * diag(D) * L');
disp(P * A * P');
b = P * b;
z = forwardSub(L, b);
y = diagSub(diag(D), z);
w = backwardSub(L', y);
x = P' * w;
endfunction

A = [1, 2, 3, 4; 2, 5, 6, 7; 3, 6, 8, 9; 4, 7, 9, 0];
b = [4; 1; 5; 8];

A = getSymmetric(3);
b = rand(3, 1);
disp(solve(A, b));
disp(A\b);

```

Jika kita diberikan persamaan $Ax = b$, dan diketahui dekomposisi $A = LDL^T$, maka bisa kita tuliskan $LDL^T x = b$. Pertama, kita akan menyelesaikan dari bagian terluarnya.

- Carilah z sehingga $Lz = b$. Perhatikan bahwa disini $DL^T x = z$.
- Carilah y sehingga $Dy = z$. Perhatikan bahwa disini $L^T x = y$.
- Carilah x sehingga $L^T x = y$. Perhatikan bahwa x adalah solusi yang kita inginkan.

Perhatikan bahwa L ialah matriks **unit segitiga bawah**, artinya entri pada diagonal utamanya berisi satu, kita bisa buat fungsi backward dan forward substitution untuk L dan L^T .

```

function x = backwardSub(U, b)
% This solves Ux = b, U is unit upper triangular matrix
[n n] = size(U); x = zeros(n, 1); x(n) = b(n);
for i = (n - 1):-1:1
    x(i) = b(i) - U(i, i+1:n) * x(i+1:n);
endfor
endfunction

function x = forwardSub(L, b)
% This solves Lx = b, L is unit lower triangular matrix
[n n] = size(L); x = zeros(n, 1); x(1) = b(1);
for i = 2:n
    x(i) = b(i) - L(i, 1:i) * x(1:i);
endfor
endfunction

function x = diagSub(D, b)
% This solves Dx = b, D is a diagonal matrix
[n n] = size(D); x = zeros(n, 1);
for i = 1:n
    x(i) = b(i)/D(i, i);
endfor
endfunction

```

Bagaimana kasusnya untuk $PAP^T = LDL^T$? Pertama secara intuitif bisa kita tuliskan $A = P^{-1}LDL^T(P^T)^{-1}$. Perhatikan bahwa $PP^T = I \iff P^T = P^{-1}$.

Proof

$$(PP^T)_{ij} = \begin{cases} 1 & P_{ik} \wedge P_{kj}^T \iff i = j \\ 0 & \text{otherwise} \end{cases}$$

Akan kita selesaikan persamaan sebagai berikut.

$$\begin{aligned} P^{-1}LDL^T(P^T)^{-1}x &= b \\ LDL^T(P^T)^{-1}x &= Pb \\ LDL^T(P^T)^T x &= Pb \\ LDL^T Px &= Pb \end{aligned}$$

Untuk kemudahan komputasi, lakukan $b := Pb$

- Carilah z sehingga $Lz = b$. Perhatikan bahwa disini $DL^T Px = z$.
- Carilah y sehingga $Dy = z$. Perhatikan bahwa disini $L^T Px = y$.
- Carilah w sehingga $L^T w = y$. Perhatikan bahwa disini $Px = w$.
- Carilah x sehingga $x = P^T w$.

Total Flops:

- $LDL' = \frac{n^3}{3}$ (Setengah dari LU)
- Backward substitution = Forward Substitution = $\frac{n(n-1)}{2}$.
- Diagonal = n .
- Perkalian matriks permutasi (Kasus diagonal pivoting) n^3 (?)

Nomor 2
