

## Background

- Traditional approaches for mesh learning typically rely on the computation of spectral components or spectral embeddings through eigenvalue decomposition of the Laplacian.
- HodgeFormer takes a fundamentally different approach. Instead of learning features on a fixed spectral basis, we learn the geometric operator itself — directly from data.

## Landscape of Mesh Learning

Spatial methods are fast but lack global context. Spectral methods capture global geometry but require expensive eigendecomposition.

Method	Year	EVD?	Key Idea
<i>Spatial Methods</i>			
MeshCNN[1]	2019	No	Edge conv + collapse pooling
SubdivNet[2]	2021	No	Loop subdivision regularity
MeshWalker[3]	2020	No	Random walks + RNN
<i>Spectral Methods</i>			
HodgeNet[4]	2021	Yes	Learn diagonal Hodge stars
DiffusionNet[5]	2022	Yes	Heat diffusion + HKS
Laplacian2Mesh[6]	2022	Yes	Transformer on eigenvectors
MeT[7]	2023	Yes	Laplacian PE

## The Hodge Star $\star_k$

$\star_k$  maps primal  $k$ -forms to dual  $(2-k)$ -forms via a ratio of measures — it is the **only** place shape information enters.

Primal → Dual	Entry
$\star_0$ Vertex → Voronoi cell	$A_v^*$ (area)
$\star_1$ Edge → dual edge	$\frac{\cot \alpha + \cot \beta}{2}$
$\star_2$ Face → dual vertex	$1/A_f$

Exterior Derivative  $d_k$  encodes connectivity:

$$d_0 \in \{-1, 0, 1\}^{n_e \times n_v}, \quad d_1 \in \{-1, 0, 1\}^{n_f \times n_e}$$

with  $d_1 d_0 = 0$  (curl of gradient = 0).

## Galerkin Mass Matrices

Classical diagonal  $\star_k$ : one scalar per element, **no neighbor coupling**. Assumes orthogonal primal-dual. Breaks for irregular or obtuse meshes.

The **Galerkin** approach yields a non-diagonal mass matrix:

$$M_{ij} = \int_{\Omega} \phi_i(x) \cdot \phi_j(x) dx$$

If  $M \approx \star_k^{\text{Gal}}$  and  $A \approx M$ , then **attention can learn Hodge stars**:  
 $\star_k \approx \sigma(QK^\top/\sqrt{d})$

## HodgeFormer Overview

- Fix incidence matrices  $d_0, d_1$  from mesh topology
- Learn non-diagonal Hodge stars  $\star_0, \star_1, \star_2$  via sparse attention
- Assemble Hodge Laplacians:  $L_v = \star_0^{-1} d_0^\top \star_1 d_0$  (and  $L_e, L_f$ )
- Apply operators end-to-end

## Results

### Quantitative Results:

Method	EVD	SHREC	Cube	Human	Vases	Chairs	Aliens
<i>Spectral Methods (require EVD)</i>							
HodgeNet	Yes	94.7	—	85.0	90.3	95.7	96.0
DiffusionNet	Yes	99.5	—	90.8	—	—	—
Laplacian2Mesh	Yes	100	91.5	88.6	94.6	96.6	95.0
MeT	Yes	—	—	—	99.8	98.9	99.3
<i>Spatial Methods (no EVD)</i>							
MeshCNN	No	91.0	92.2	85.4	92.4	93.0	96.3
SubdivNet	No	99.5	98.9	91.7	96.7	96.7	97.3
MeshWalker	No	97.1	98.6	—	99.6	98.7	99.1
<b>HodgeFormer</b>	No	98.7	95.3	90.3	94.3	<b>98.8</b>	98.3

### Runtime Comparison:

Mesh Size ( $n_v$ )	$2^8$	$2^{10}$	$2^{12}$	$2^{14}$
Compute Time (ms)				
HF Encoder (Train)	5.78	8.98	29.72	197.9
HF Encoder (Infer)	2.50	3.42	10.96	66.13
HF Layer (Infer)	1.08	1.91	9.42	55.25
Peak Memory Usage (GBs)				
HF Encoder (Train)	0.12	0.40	2.54	19.23
HF Encoder (Infer)	0.09	0.31	2.08	15.89
HF Layer (Infer)	0.09	0.31	2.08	15.89
Train (s/ep) GPU (ms) Mem (GB)				
MeshCNN	26.84	806.29	4.41	
Laplacian2Mesh	641.34	423.57	4.80	
<b>HodgeFormer</b>	<b>17.58</b>	<b>263.57</b>	14.21	

### Qualitative Results (Human Seg):



## Input Features

- Vertex: 3D coords, normals, Voronoi cell area
- Edge: endpoint coords, opposite vertex coords, normals, lengths
- Face: vertex coords, face normal, face area

### Embedding Layer $x_{k_{\text{in}}} \rightarrow x_k$

$$x_k = \text{MLP}(x_{k_{\text{in}}} + A_k \cdot x_{k_{\text{in}}})$$

- One-hop aggregation via  $A_k$
- MLP projects to latent dim  $d$

### Learned Hodge Star via Attention

$$\begin{aligned} Q_k &= x_k W_{Q_k}, \quad K_k = x_k W_{K_k} \quad W \in \mathbb{R}^{d \times d_k} \\ \star_k(x_k) &= \text{softmax}\left(\frac{Q_k K_k^\top}{\sqrt{d_h}}\right) \end{aligned}$$

- Non-diagonal

## HodgeFormer Layer

### Learned Hodge Laplacians:

- $L_v := \star_0^{-1}(x_v) d_0^\top \star_1(x_e) d_0$
- $L_e := d_0 \star_0^{-1}(x_v) d_0^\top \star_1(x_e) + \star_1^{-1}(x_e) d_1^\top \star_2(x_f) d_1$
- $L_f := d_1 \star_1^{-1}(x_e) d_1^\top \star_2(x_f)$

### Parametrization:

$$\star_k(x_k) = \sigma(Q_k K_k^\top / \sqrt{d_h}), \quad k \in \{v, e, f\}.$$

$$\text{Layer: } H_l(x_v, x_e, x_f) := G_l(A_{H_l}(\cdot) + (\cdot)).$$

### Multi-head:

$$x_v = L_v V_v(x_v), \quad x_e = L_e V_e(x_e), \quad x_f = L_f V_f(x_f).$$

## Contact

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