

EDUCATION

NC State University — *M.S. Computer Science*

August 2020 - December 2022

- GPA 3.79
- Member of the [Robot Code Lab](#) under John-Paul Ore, PhD

UNC Asheville — *B.S. Computer Science, Math minor*

August 2016 - May 2022

- GPA 3.83
- Dean's List (Fall 2016 - Fall 2019)
- Chancellor's List (Spring 2019)

SKILLS

Languages — Python, C++, Bash, Java, MATLAB, JavaScript + HTML/CSS, C

Technologies — Linux, Git, Docker, Agile Development, CI/CD, ROS2, Behavior Trees, PyTest, SQL (MySQL, Oracle DBMS), RESTful APIs, SFML, LaTeX, Svelte, Node.js, Keras+TF

WORK EXPERIENCE

NCSU Computer Science — *Research Assistant*

September 2020 - October 2022

- Defined **Behavior-Tree**-specific coverage criteria for robots and then implemented them in an [open-source Coverage Tool](#) using C++ and **Python**.
- Co-authored *Canopy: Coverage Measurement for Behavior Trees*. In review by ICRA 2023.
- Developed [multiple Docker images](#) and Bash scripts for developing ROS-based Robots. Created [Docker image](#) for simulating ROS2 robots in Unity.

NCSU Computer Science — *Teaching Assistant*

August 2020 - December 2022

- Mentored students and assessed code in: undergraduate Software Engineering, Software Engineering for Robotics, and Discrete Mathematics.

UNCA Computer Science — *Research Assistant*

May 2019 - July 2020

- Developed SBML compliant **Python** code for asynchronous simulation graphing with the [GillesPy2](#) team.
- Co-Authoring *GillesPy2: a Biochemical Modeling Framework for Simulation Driven Biological Discovery*. Currently in review by *Letters in Biomathematics*
- Improved functions for graphical and statistical analysis of stochastic simulations with **Matplotlib** and **Plotly**.
- Gained experience in **test-driven development** and **Git** version control.

Appalachian Tropicals — *Greenhouse Manager*

September 2016 - August 2020

Manna Food Bank — *Warehouse Volunteer*

January 2018 - May 2019

EXAMPLE PROJECTS

A* Pathfinding and Boids — C++, Python, SFML

- Wrote multithreaded **C++ code** for simulating and animating multi-agent movement behaviors using **SFML**.
- Created [Python scripts](#) for creating large geometric graphs and procedural multi-room indoor test environments.
- Programmed [A* search algorithm with path-following](#) in C++ for indoor navigation.

Wifi-Enabled Humidistat Controller — C++, Arduino, ESP32

- Developed application in [Arduino/C++](#) for monitoring and controlling temperature and humidity using an **esp32** over LAN.
- Implemented ad hoc wifi network broadcast on device for home network authentication.
- Utilized RESTful web server for [monitoring and controlling device in-browser](#).

Canopy (Coverage for Behavior Trees) — Python, C++, ROS2, Bash, Docker

- Developed a [ROS2 application](#) for logging Behavior Tree activity and for calculating tree **coverage**.
- Utilized ROS2 node messaging to enable library/implementation agnostic monitoring and logging.
- Created ROS2 publisher nodes for out-of-the-box functionality with BehaviorTree.CPP and `py_trees_ros`.

Personal Website — Svelte, JavaScript, html+css, Node.js

- Produced a static website in Svelte and JavaScript and [deployed to github pages](#).

Genetic Algorithm for Chess Heuristic Optimization — Python

- Created a command line [chess game runner](#) in **Python** with options for custom board configurations.
- Implemented opposing AI agents utilizing [Alpha-Beta Pruning Search](#) and a board state transposition table (hash table).
- Collaborated on [genetic algorithms](#) for player agent heuristic function optimization.